

A COMPARATIVE TEST
OF
INTEGRATING WATTMETERS

BY

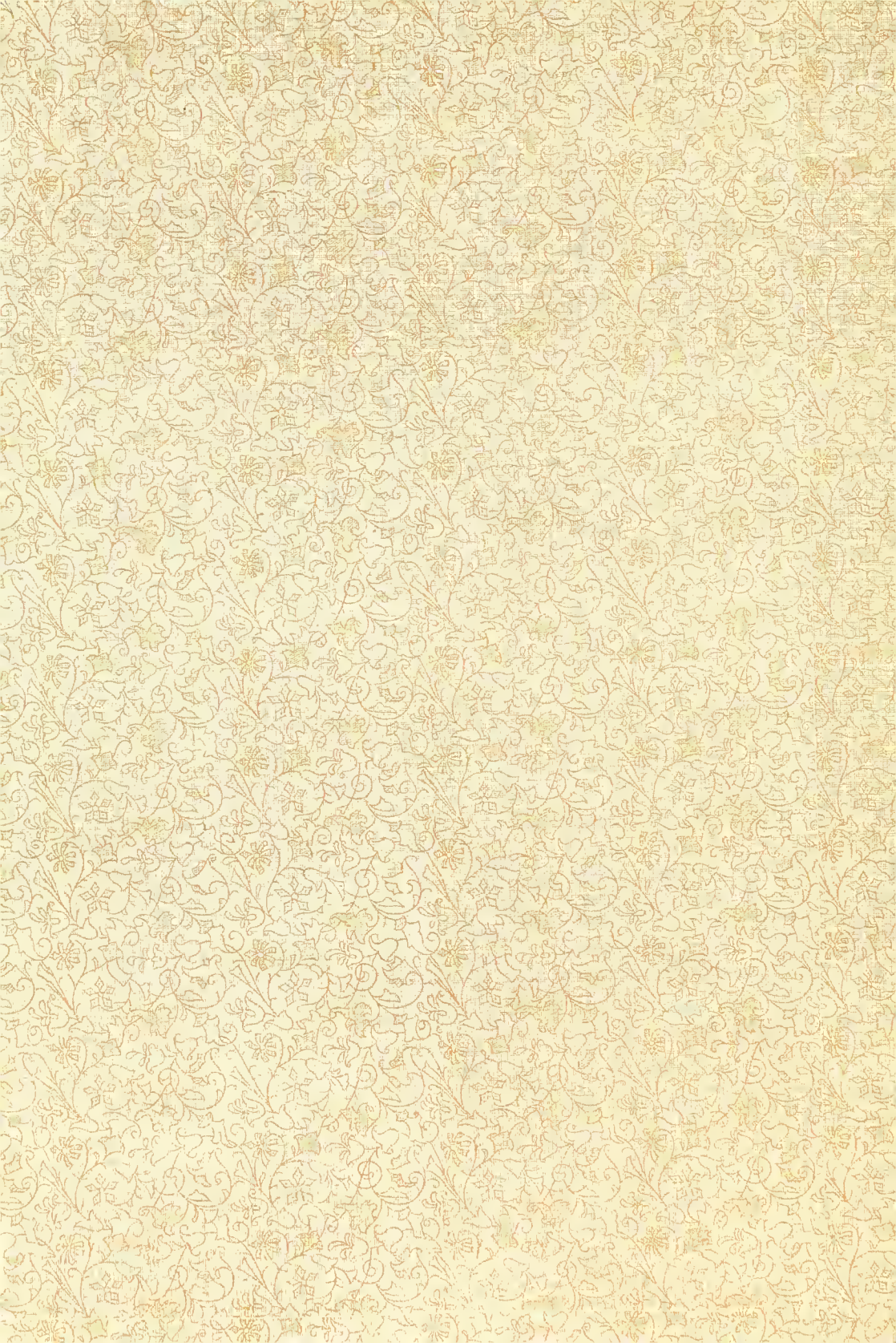
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Armour Institute of Technology

1908

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Anderson, M. J.
Comparative test of
integrating wattmeters

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A COMPARATIVE TEST
OF
INTEGRATING WATTMETERS

A THESIS

PRESENTED BY

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AND
AUGUSTUS B. CORNWELL

TO THE

PRESIDENT AND FACULTY

OF

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FOR THE DEGREE OF

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HAVING COMPLETED THE PRESCRIBED COURSE OF STUDY IN

ELECTRICAL ENGINEERING

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A Comparative Test of Integrating Wattmeters.

The object of this thesis is to determine the per cent accuracy of the meters tested when operated on loads varying from no load to 150 % load with voltages varying from 10 % below to 10 % above normal voltage, with different frequencies, and with different power factors; also to determine the phase relation of the series and pressure fluxes of each meter.

The following apparatus was used for this test;-

- 1- Weston Voltmeter. A.C. & D.C. (0-120).
- 2- Thomson Ammeters. A.C. (0-5) & (0-25).
- 1- Weston Wattmeter. (10 ampere).
- 3- Frequency Meters. (25-60-125 cycles)
- 1- Dynamometer.
- 1- Stop Watch.
- 1- Counter.
- 1- Variable Inductance.
- Lamp Bank.
- Two Phase Alternator. (60 cycles).
- Single Phase Alternators.(25-60-125 cycles)
- Storage Battery.

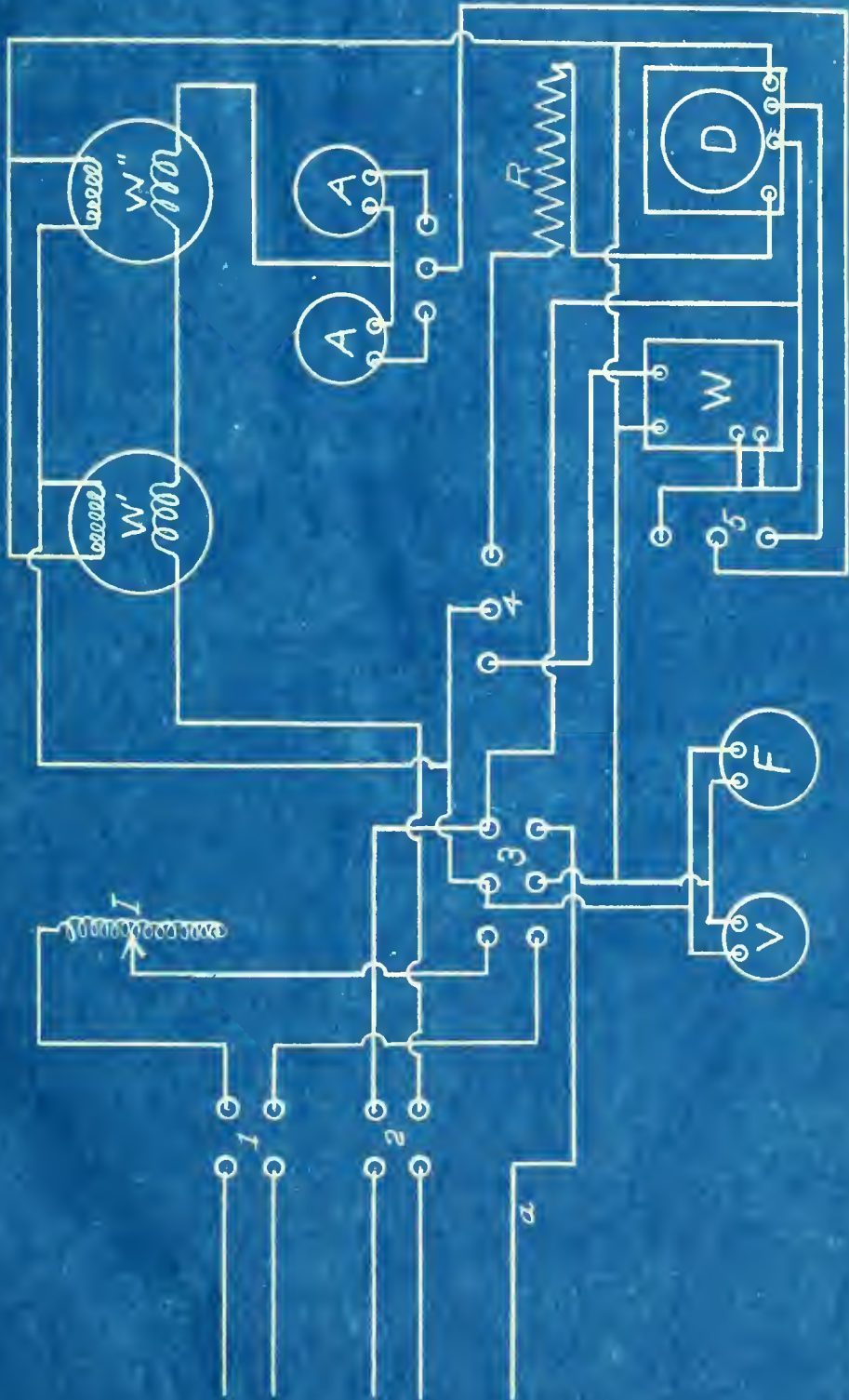
A Comparative Test of Integrities and Weibull's

The object of this test is to determine the
relative accuracy of the methods tested when applied
on loads varying from no load to 150% load with
voltage varying from 1% below to 1% above normal
voltage, with different the number, and with different
power factors; also to determine the effect of variation of
the number and pressure of the motor.

The following apparatus was used for this test:-

- 1- Weston Voltmeter. A.C. 0-150 (1-150)
- 2- Thomson Ammeter. A.C. (0-5) & (0-25)
- 1- Weston Wattmeter. (1-100)
- 2- Pressure Meters. (0-0-150 of 0-150)
- 1- Dynamometer.
- 1- Stop Valve.
- 1- Counter.
- 1- Variable Inductor.
- 1- Lamp Bank.
- Two Three-Phase Transformers. (0-0-150 of 0-150)
- Single Phase Transformer. (0-0-150 of 0-150)
- Storage Battery.

SCHEME of CONNECTIONS
for
Integrating Wattmeter Test



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On the preceding blue print is shown a scheme of the connections used. The leads from switch 1 are connected directly to one phase of a two phase alternator. The leads from switch 2 connect to the series posts of the lamp bank; the lower lead "a" connects directly to one side of the second phase and the upper lead of switch 2 connects to the other side of the second phase, thus giving the pressure of the second phase on the right hand posts of switch 3 when switch 2 is closed. V and F are the voltmeter and the frequency meter. W is the Weston wattmeter. D is the dynamometer. R is a non-inductive resistance in series with the pressure coil of the dynamometer. By means of the double throw switches 4 and 5 either the wattmeter or the dynamometer may be connected in the circuit. A and A represent the high and low reading ammeters, either of which may be connected to the line by means of the double throw switch 6. W' and W" are the watt hour meters under test. I is a variable inductance connected in series in one of the leads of the upper phase, for the purpose of adjusting the phase relation of the currents in these two phases. By throwing switch 3 to the right all pressure apparatus is connected to the lower phase, and by throwing it to the left all pressure apparatus is connected to the upper phase.

In order to obtain good results in this test it

On the preceding page it is shown how the
of the connections used. The leads from switch 1 are
connected directly to one phase of a two phase alternator.
The leads from switch 2 connect to the series posts of
the lamp bank; the lower lead connects directly to
one side of the second phase and the upper lead of
switch 2 connects to the other side of the second phase,
thus giving the pressure of the second phase on the
right hand posts of switch 2 when switch 2 is closed.
V and T are the voltmeter and the frequency meter.
W is the wattmeter. Z is the dynamometer.
R is a non-inductive resistance in series with the
pressure coil of the dynamometer. By means of the
double throw switches 4 and 5 either the wattmeter or
the dynamometer may be connected in the circuit.
The high and low reading ammeters,
either of which may be connected to the line by means
of the double throw switch 6. "A" and "B" are the watt
four meters under test. I is a variable inductance
connected in series in one of the leads of the upper
phase, for the purpose of adjusting the phase relation
of the currents in these two phases. By throwing switch
3 to the right all pressure apparatus is connected to the
lower phase, and by throwing it to the left all pressure
apparatus is connected to the upper phase.
In order to obtain good results in this test it

was necessary that the load, the voltage and the frequency be maintained constant during the run. This was accomplished by operating the motors, to which the generators were attached, from a 60 cell storage battery. The field rheostats of both motor and generator were placed by the testing table to give convenient control of the frequency and the voltage.

The method of procedure was as follows;- First all instruments to be used were calibrated by comparing their readings with those of the standard instruments of the laboratory of Armour Institute of Technology. The voltmeter used was made for A.C. and D.C. and it was calibrated by comparing its readings directly with those of the standard D.C. voltmeter. In making this comparison two readings were made in determining each point of the calibration, one with the current in one direction and the other with the current in the reverse direction, the average being taken for the true reading, thus eliminating any effect of stray magnetic fields. The dynamometer, to be used in the determination of the flux phase relation, was calibrated as a watt-meter by comparing its readings with the standard volt-amperes. For the calibration of the A.C. ammeters it was necessary to first calibrate a dynamometer as an ammeter by comparing its readings with those of the standard ammeter, direct current being used for this calibration, and then to calibrate the ammeters by

was necessary that the voltage and the frequency be maintained constant during the run. This was accomplished by operating the motor, to which the generator were attached, from a 60 cell storage battery. The field rheostats of both motor and generator were placed by the setting table to give convenient control of the frequency and the voltage.

The method of procedure was as follows: - First all instruments to be used were calibrated by comparing their readings with those of the standard instruments of the Laboratory of Bureau Institute of Technology. The voltmeter used was made for 1.0, 2.0 and 3.0 and it was calibrated by comparing its readings directly with those of the standard 2.0 voltmeter. In making this comparison two readings were made in determining each point of the calibration, one with the current in one direction and the other with the current in the reverse direction, the average being taken for the two readings, thus eliminating any effect of hysteresis. The dynamometer, to be used in the determination of the flux relation, was calibrated as a wattmeter by comparing its readings with the normal volt-ammeter. For the calibration of the wattmeter it was necessary to find a suitable standard wattmeter for comparison of readings. The standard wattmeter used in the calibration, direct current being used for this calibration, was then used in the calibration of the dynamometer.

comparing their readings with those of the dynamometer, alternating current being used in this second calibration. The Weston wattmeter was calibrated by comparing its readings with the product of those of the calibrated ammeter and voltmeter.

When an integrating meter was placed on the testing board and connections made as shown in the above scheme, the meter was first tested to ascertain if it were running at correct speed with full load current, unity power factor, normal frequency, and normal voltage. The number of revolutions made by the disc in about two minutes was counted. This number multiplied by the disc constant and divided by the time required to make this number of revolutions gives the watts recorded, which corresponds to the watts given by the Weston wattmeter if the integrating meter is running at the correct speed. In case the meter ran too fast or too slow under these normal conditions the position of the damping magnet was adjusted until the proper speed was obtained. In this manner all the meters tested were adjusted to record within 2% of the true watts when operating under normal conditions at full load.

In cases where the disc constant was not given the recording train was removed and the ratio of the revolutions of the disc to the revolutions of the first dial was determined by counting the number of revolutions

comparing their readings with those of the dynamometer, the integrating current being used in this second calibration. The action voltmeter was calibrated by comparing its readings with the product of those of the dynamometer and voltmeter.

When an integrating meter was placed on the testing board and connections made as shown in the above scheme, the meter was first tested to ascertain if it were running at correct speed with full load current, unity power factor, normal frequency, and normal voltage. The number of revolutions made by the disc in about two minutes was counted. This number multiplied by the disc constant and divided by the time required to make this number of revolutions gives the watts recorded, which corresponds to the watts given by the action voltmeter if the integrating meter is running at the correct speed. In case the meter runs too fast or too slow under these normal conditions, the position of the integrating magnet was adjusted until the proper speed was obtained. In this manner all the meters tested were adjusted to record within 2% of the true value under open circuit normal conditions at full load. In cases where the disc constant was not given the recording table was removed and the ratio of the revolutions of the disc to the revolutions of the line dial was determined by counting the number of revolutions

made by an intermediate gear, usually the one that meshed with the gear on the spindle, to one revolution of the first dial, and then determining the ratio between this gear and the one on the spindle. From these the disc constant can be determined directly.

After an accurate adjustment had been obtained a run was made with normal frequency, normal voltage and unity power factor, about seven or eight readings being taken as the load was varied from no load to 150 % load. Then like runs were made with approximately 10 % above and 10 % below normal voltage.

The meter was next tested for accuracy with different power factors. The variable inductance I was disconnected from the upper phase, as shown in the scheme, and connected in series with the load on the lower phase, being placed in the lower lead of switch 2, which is the load side of the meters. With the inductance in this particular lead we were able to vary the power factor without changing the voltage impressed upon the instruments. Readings were taken for the determination of the per cent accuracy with normal voltage, normal frequency, constant full load current and power factors varying from unity to about .500.

A test was next made to determine the phase relation of the series and pressure fluxes. The connections were as shown in the scheme, switches 1 and 2 being closed, switch 3 being thrown to the left and

made by an intermesh gear, usually the one meshed with the gear on the shaft, to one revolution of the first shaft, and then determining the ratio between this gear and the one on the shaft. This constant can be determined directly.

After an accurate adjustment has been obtained a run was made with normal frequency, normal voltage and unity power factor, load given on light resistance being taken as the load was varied from no load to full load. Then like runs were made with approximately 10% above and 10% below normal voltage.

The motor was next tested for accuracy with different power factors. The variable inductance was disconnected from the upper phase, as shown in the scheme, and connected in series with the load on the lower phase, being placed in the lower lead of switch 2, which is the 10% side of the motor. The inductance in this position is 1.5 ohms and is capable of varying the power factor without changing the voltage impressed upon the instruments. Readings were taken for the determination of the per cent efficiency with normal voltage, normal frequency, constant full load output and power factor varying from unity to about 0.5. A test was next made to determine the efficiency in relation of the series inductance. The connection was shown in the scheme, switch 1 and 2 being closed, switch 3 being thrown to the left and

switches 4 and 5 being thrown so that the Weston wattmeter was connected in the circuit. With the switches in these positions all pressure circuits are connected to one phase and all series circuits are connected to the other phase of the two phase alternator. The load was adjusted until the desired current was obtained and this current was then maintained constant thru-out this particular test. The inductance I was adjusted until the phase difference between the currents in the two circuits was approximately 90 degrees, as indicated by the very low reading of the Weston wattmeter, and by the very slow movement of the disc of the integrating meter. Switches 4 and 5 were now thrown so as to connect the dynamometer in the circuit. A reading was made on the dynamometer and the speed at which the disc was rotating was determined by noting, with a stop watch, the time required for a point on the disc to pass between two noted points on the stationary portion of the meter, as for example across the width of the damping magnet. It was not necessary to know the exact speed of the disc in revolutions per minute but simply to know the speed relative to some fixed part of the meter in order that the disc could be given the exact same speed when the flux phase relation was readjusted. Two more readings were made on the dynamometer with this same speed and direction of

rotation of the disc, the inductance I being readjusted previous to each reading, and the watts corresponding to the average of these first three readings was taken as the true watts for this phase relation of the series and pressure currents. The true watts divided by the apparent watts gives the cosine of the angle between these currents. The position of the core of the inductance was now changed until the disc was rotating in the opposite direction with a speed equal to that at which it was revolving in the first direction. Three readings were taken on the dynamometer for this direction of rotation of the disc and the watts corresponding to the average of these readings was taken as the true watts for this phase relation of the series and pressure currents. These true watts divided by the apparent watts gives the cosine of the angle between these currents for the second position of the core of the inductance coil. If it was necessary to reverse the connections of the dynamometer to get a positive reading when the inductance was adjusted so as to change the direction of rotation of the disc then one of the readings was considered positive and the other negative, indicating that one of the angles was less than 90 degrees and the other was greater than 90 degrees. In the meters of the induction type the phase angle from a quadrature relation of the series and pressure fluxes

rotation of the disc, the induction I being reversed
previous to each reading, and the water corresponding
to the average of these first runs the disc was taken
the true water for this particular relation of the series
and pressure elements. The true water divided by the
apparent water gives the cosine of the angle between
these elements. The position of the core of the
induction was now changed until the disc was rotating
in the opposite direction with a speed equal to that
at which it was revolving in the first direction.
These readings were then on the dynamometer for this
direction of rotation of the disc and the water
corresponding to the average of these readings was
taken as the true water for this particular relation of
the series and pressure elements. These true water
divided by the apparent water gives the cosine of the
angle between these elements for the second position
of the core of the induction. It is necessary
to reverse the connection of the dynamometer to get
positive reading when the induction is directed in
change the direction of rotation of the disc then one
of the readings is considered positive and the other
negative, indicating that one of the angles is
from 90 degrees and the other less than 90 degrees.
In the matter of the induction, the true water
is an average relation of the series and pressure elements.

when used with a single phase current, is equal to the average of the phase angles from quadrature as obtained from these two sets of readings. In the meters not of the induction type the phase angle between the series and pressure fluxes is equal to the average of the phase angles from quadrature obtained from these two sets of readings.

There is a small error in this method of determining the flux phase relation due to the fact that the meters are compensated for friction and this compensation aids the movement of the disc in a forward direction and resists movement in a backward direction. With high torque meters this error will be small and that it is small in this case is shown by the fact that the per cent accuracy of these meters with different power factors as calculated from this flux phase determination agrees very closely with that determined directly by the use of these different power factors as described above.

Tests were next made with frequencies of 25 and 120 cycles, the connections being first made to the 25 cycle alternator. Adjustments were made for the change of frequency if such adjustments were required and the meter was tested for correct speed with normal voltage, unity power factor and full load current and was adjusted to run at correct speed if such adjustment was required. An accuracy test was made with normal voltage and 25 cycles with loads varying from no load

When used with a single phase circuit, it is equal to the
average of the phase angles from the two sets of readings
from these two sets of readings. In the case of the
induction type the phase angle between the series and
pressure fluxes is equal to the average of the two angles
from the two sets of readings.

There is a small error in the method of determining
the true phase relation due to the fact that the motor
is compensated for friction and this compensation is
the movement of the disc in a forward direction and
resists movement in a backward direction.

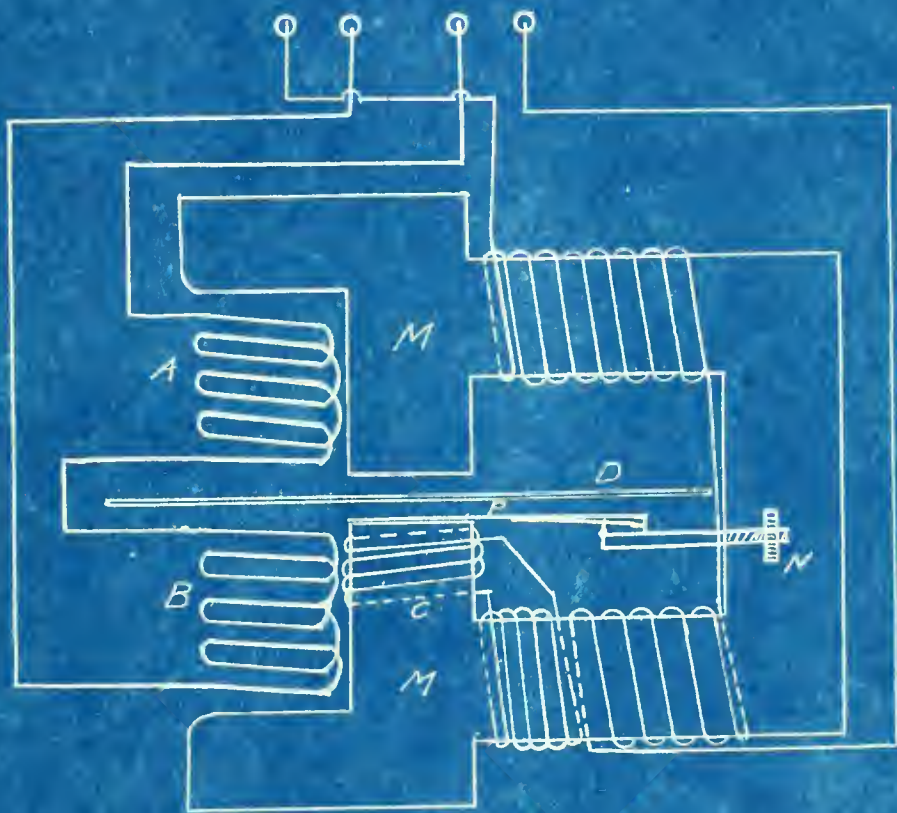
For the motor this error will be small and that it is
small in this case is shown by the fact that the per-
cent accuracy of these readings with different power
factors as calculated from this true phase determination
agrees very closely with that determined directly by the
use of these different power factors as described above.

Tests were not made with frequencies of 25 and
120 cycles, the comparison being first made to the 50
cycle alternator. Adjustments were made for the
change of frequency in such adjustments were required
and the motor was tested for constant speed with normal
voltage, unity power factor and full load current and
was adjusted to run at constant speed in each adjustment
was required. A series of tests were made with normal
voltage and 25 cycles with loads varying from no load

to 150 % load. Similarly, the apparatus was connected to a 120 cycle circuit and, after all necessary adjustments had been made, the meter was tested for accuracy with normal voltage and 120 cycles thru-out the same range of loads.

to 150 & loads. Similarly, the apparatus was connected
to 120 cycle circuit and, after if necessary adjust-
ments had been made, the motor was tested for efficiency
with normal voltage and 120 cycles thru-out the same
range of loads.

Diagram of
The Fort Wayne Integrating Wattmeter
Type W No. 252944.



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The Fort Wayne Integrating Wattmeter.

Type W. No.252944.

Volts 110. Amperes 10. Cycles 60.

The Fort Wayne watt hour meter is of the induction type. An outline of the meter with circuit diagram is given on the preceding blue print. The series circuit consists of the two coils A and B, one being just above the disc and the other just below it. The pressure circuit consists of the two coils P and P' wound on the yoke of the laminated magnet M, The moving system consists of a light shaft carrying the disc D which rotates between the poles of the laminated magnet M and between the poles of the damping magnet. Speed adjustment is obtained by changing the position of the copper bracket P by means of the knurled nut N. On one leg of the laminated magnet M is wound a small coil C, the object of which is to increase the lag of the pressure flux behind its E.M.F., thus aiding in the production of the quadrature relation between the series and pressure fluxes. The phase relation of the E.M.F. and currents of the different circuits of this meter may be best explained by reference to the following vector diagrams, the first figure being for a non-inductive load and the second one for an inductive load.

Let E represent the impressed E.M.F., and I the current in the series coil in phase with the E.M.F.

The first type integrating circuit.

Type No. 25214.

Volts 11. Amperes 10. Output 5.

The first type with four meters in the induction

type. An outline of the meter with circuit diagram

is given on the preceding page. The series

circuit consists of the two coils A and B, one being

just above the disc and the other just below it. The

pressure circuit consists of the two coils C and D

wound on the yoke of the laminated magnet M. The

moving system consists of a light shaft carrying the

disc C which rotates between the poles of the laminated

magnet E and between the poles of the damping magnet.

Speed adjustment is obtained by changing the position

of the copper bracket F by means of the screw nut N.

On one leg of the laminated magnet is wound a coil

coil G, the object of which is to increase the lag of

the pressure film behind its E.M.F., thus aiding in the

production of the pressure relation between the series

and pressure fluxes. The phase relation of the

and currents of the different circuits of this meter

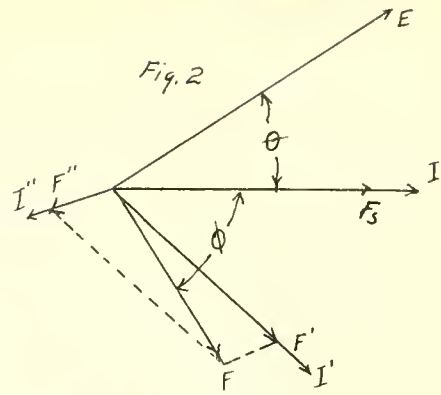
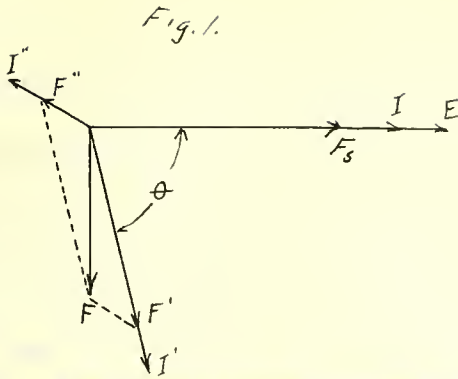
may be best explained by reference to the following

vector diagram, the first figure being for a non induc-

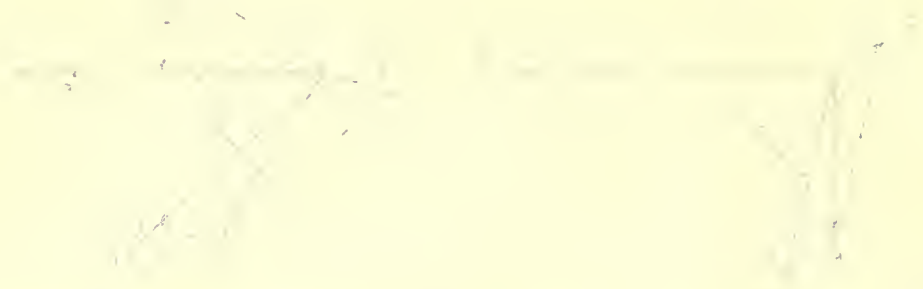
tive load and the second one for an inductive load.

Let I represent the impressed E.M.F., and E the

current in the series coil in phase with the E.M.F.



I' is the pressure current which, because of the self inductance of the pressure circuit, lags by an angle which is a little less than 90° behind the impressed E.M.F. There will be induced in the auxiliary coil C an E.M.F. which will lag 90° behind the pressure flux which produces it. This E.M.F. will cause a current to flow in the coil C which will lag slightly behind its E.M.F. because of the self inductance of the coil. The current in the coil C is represented by the vector I'' . The flux F'' due to the current I'' is in phase with I'' , and the flux F' due to the current I' is in phase with I' . By properly adjusting the resistance of the auxiliary coil C the value of the flux F'' may be made such that the resultant of F' and F'' will be practically in quadrature with the series flux. The torque upon the disc is proportional to the product of the two fluxes and the sine of the angle between them, hence it is proportional to the product of the impressed E.M.F. and the current in the series coil when the load is non-inductive. If the load is inductive and the current lags by an angle θ behind the impressed E.M.F., the



I' is the pressure current which, because of the self
 inductance of the pressure circuit, lags by an angle
 which is a little less than 90° behind the impressed
 E.M.F. There will be induced in the auxiliary coil
 an E.M.F. which will lag 90° behind the pressure flux
 which produces it. This E.M.F. will cause a current
 to flow in the coil C which will lag slightly behind
 its E.M.F. because of the self inductance of the coil.
 The current in the coil C is represented by the vector "I".
 The flux "W" due to the current "I" is in phase with "I",
 and the flux "F" due to the current "I" is in phase with
 "I". By properly adjusting the resistance of the
 auxiliary coil C the value of the flux "W" may be made
 such that the resultant of "W" and "F" will be practically
 in phase with the series flux. The torque upon
 the disc is proportional to the product of the two fluxes
 and the sine of the angle between them, hence it is
 proportional to the product of the impressed E.M.F. and
 the current in the series coil when the load is non-
 inductive. If the load is inductive and the current
 lags by an angle θ behind the impressed E.M.F., the

torque will be proportional to the product of the E.M.F. and the series current and the sine of the angle between the series and pressure fluxes, or the sine of the angle ϕ as given in the second vector diagram. The sine of the angle between these fluxes is equal to the cosine of 90° degrees minus this angle which is equal to the cosine of the angle of lag of the series current if the meter is correctly adjusted for a quadrature relation between the series and pressure fluxes with a non-inductive load. Hence the torque is proportional to the true power for all loads when the meter is properly adjusted as described above.

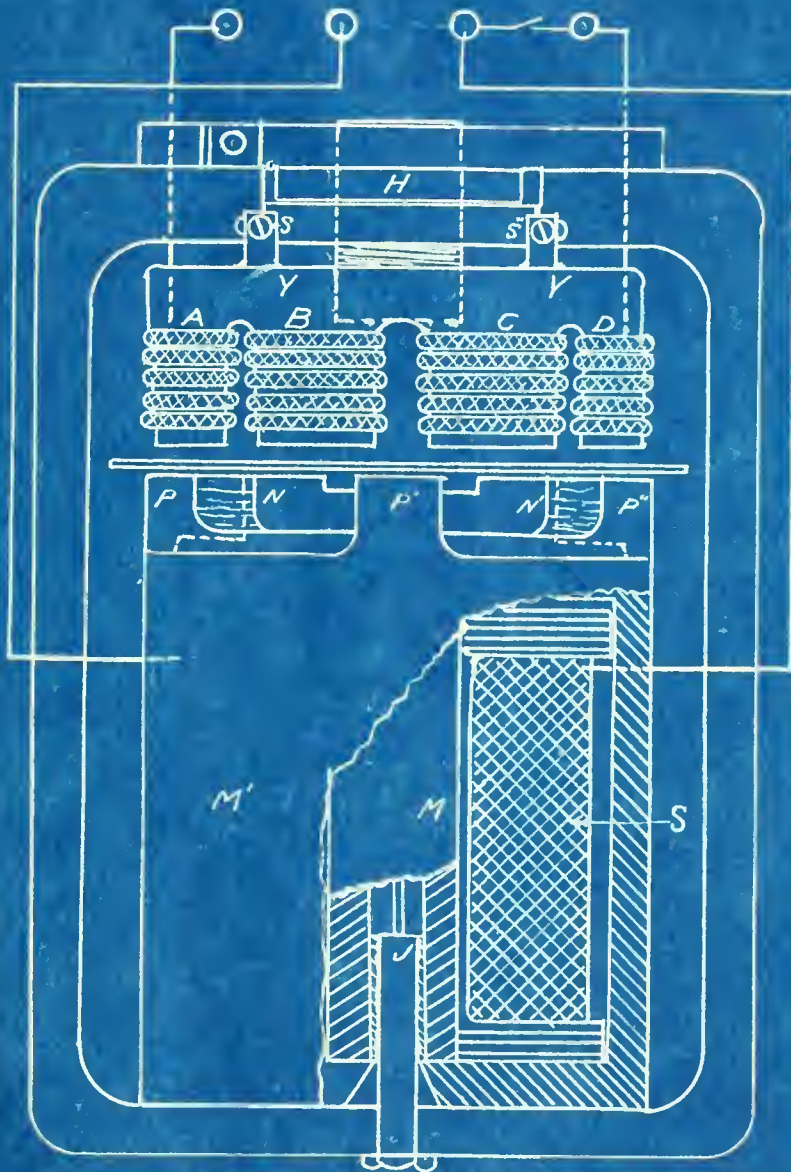
The results of the test for the determination of the flux phase relation show the angle between the series and pressure fluxes to be $91^\circ 15.25'$. This inaccurate adjustment of the meter for quadrature will make an error of 4 % with a power factor of .500, as shown by the data calculated from this flux phase determination. The error as determined experimentally with a power factor of .508 was about 4.5 %. This meter gives practically the same results with normal voltage and with 10 % high and 10 % low voltage. With a load of one ampere the meter is about 18 % slow. With loads from 5 amperes to 15 amperes this meter gave good results. The Fort Wayne meter now on the market can not be judged by these results as the type K instead of the type W is now manufactured by the Fort Wayne company.

... will be proportional to the ... of the ...
... and the series current ... the angle between
... the series and pressure lines, or the sine of the
... angle θ as given in the second vector diagram. The
... sine of the angle between these lines is equal to the
... cosine of 90° minus this angle which is a sine
... to the cosine of the angle of lag of the series current
... if the meter is correctly adjusted for a constant
... relation between the series and pressure lines with
... non-inductive load. Hence the torque is proportional
... to the true power for all loads when the meter is
... properly adjusted as described above.
... The results of the test for the determination
... of the true phase relation show the angle between the
... series and pressure lines to be $91^\circ 18.3'$. This
... in correct adjustment of the meter for standard will
... make an error of $\pm 1\%$ with a power factor of .500, as
... shown by the data calculated from this true
... determination. The error is determined experimentally
... with a power factor of .508 was about $\pm 0.5\%$. This
... meter gives practically the same results with normal
... voltage and with 10% high and 10% low voltage.
... with a load of one ampere the meter is about $\pm 0.5\%$ error.
... with loads from 5 amperes to 15 amperes this meter gives
... good results. The Fort meter now on the market
... can not be judged by these results of the type 2 meters of
... the type 2 is now manufactured by the Fort and company.

THE FERRANTI INTEGRATING WATTMETER

No. 222322

DIAGRAM OF CIRCUITS.



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The Ferranti Integrating Wattmeter.

No.222522. Volts 110. Amperes 10. Cycles 60.

The Ferranti watt hour meter is of the induction type. A general outline of this meter with circuit diagram and sectional view of the pressure coil and magnet is shown on the preceding blue print. This meter is an English make and differs considerably in appearance and construction from the American make of induction meters. It is small and very compact. The series circuit of this meter consists of four small coils, A, B, C, and D, wound on poles formed by slotting the iron yoke Y. The shunt circuit consists of a single coil, S, wound in the form of a bobbin on the tubular core M, and which is surrounded by the semi-cylindrical magnet M', an extension of the core M. The magnet M' has three inwardly projecting poles P, P', and P'', and the core M has two poles N, and N' which project radially between the poles P, P', and P'', as shown on the blue print. These projecting poles of the shunt magnet are directly under the slots between the poles of the series magnet. The revolving element consists of an aluminum disc mounted on a light vertical spindle which rests on a jewel bearing J. The disc rotates in the air gap between the poles of the pressure and series magnets, and between the poles of the permanent magnet which is mounted in the back of the meter. The reaction of the field, due to the eddy currents induced

The first interesting feature.

No. 23232. Volume 10. Chapter 10. Chapter 10.

The first interesting feature of the invention

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circuit of this meter consists of four small coils, 1, 2,

3, and 4, wound on poles formed by slotting the iron

yoke Y. The shunt circuit consists of a single coil, 5,

wound in the form of a bobbin on the tubular core 6, and

which is surrounded by the semi-cylindrical magnet 7,

an extension of the core 6. The magnet 7 has three

inwardly projecting poles 8, 9, and 10, and the core 6

has two poles 11, and 12, which project radially between

the poles 8, 9, and 10, as shown on the blue print.

These projecting poles of the shunt magnet are directly

under the slots between the poles of the series magnet.

The revolving element consists of an aluminum disc mounted

on a light vertical spindle which rests on a jewel bearing 13

the disc rotates in the air gap between the poles of the

pressure and series magnets, and between the poles of the

permanent magnet which is mounted in the back of the meter.

The reaction of the field, due to the eddy currents induced

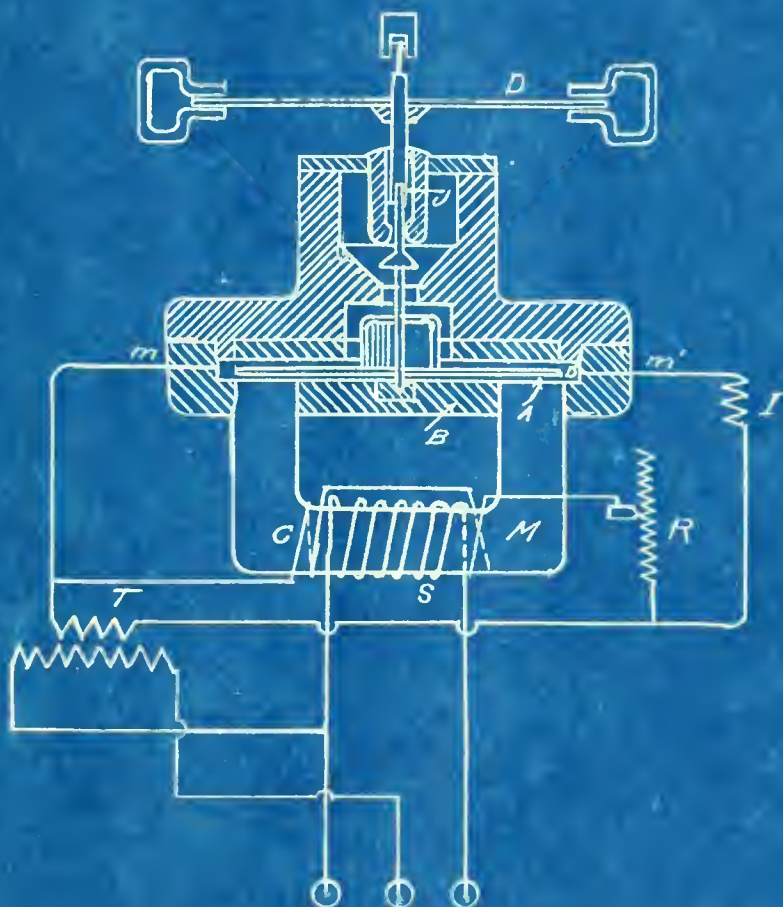
in the disc by the pressure flux, upon the series flux gives to the disc a torque which is proportional to the product of the series flux and the pressure flux, and hence to the true watts. Friction compensation on light loads is effected by turning the series coils about the axis of rotation of the disc by means of the screws S' and S". If the series magnet be displaced in one direction the disc will tend to revolve in the opposite direction and vice versa. The speed adjustment is obtained by raising or lowering the series magnets by turning the nut H. This varies the length of the air gap and hence varies the strength of the series field. When running at correct speed with full load the disc makes 40 revolutions per minute.

The results of the test for the determination of the flux phase relation show the angle between the series and pressure fluxes to be $91^{\circ} 1.5'$. This variation of $1^{\circ} 1.5'$ from quadrature will make an error of 3% when the meter is operated on a power factor of .500, as shown by the data calculated from this flux phase determination. The per cent accuracy as determined by these tests is practically the same for normal voltage and for 10% high and low voltage. With a current of one ampere the meter is 15% slow. This meter gave very good results with 25 cycles, but the per cent accuracy obtained for this run can be considered only relatively as no adjustment was made when the meter was placed on the 25 cycle circuit.

in the disc by the pressure flux, upon the series flux
 gives to the disc a torque which is proportional to the
 product of the series flux and the pressure flux, and
 hence to the time factor. Friction compensation on
 light loads is effected by turning the series coils
 about the axis of rotation of the disc by means of the
 screws 'a' and 'b'. If the series magnet be displaced
 in one direction the disc will tend to revolve in the
 opposite direction and vice versa. The speed adjustment
 is obtained by raising or lowering the series magnets
 by turning the nut H. This varies the length of the
 air gap and hence varies the strength of the series field.
 When running at correct speed with full load the disc
 makes 40 revolutions per minute.

The results of the test for the determination of
 the flux phase relation show the angle between the series
 and pressure fluxes to be $91^{\circ} 1.5'$. This variation
 of $1^{\circ} 1.5'$ from quadrature will make an error of 3% when
 the meter is operated on a power factor of 0.866, as shown
 by the data calculated from this flux phase determination.
 The per cent accuracy as determined by these tests is
 practically the same for normal voltage and for 10% high
 and low voltage. With a current of one ampere the meter
 is 15% slow. This meter gave very good results with 25
 cycles, but the per cent accuracy obtained for other
 can be considered only relatively as no adjustment was made
 when the meter was placed on the 25 cycle circuit.

Diagram of
The Sangamo Integrating Wattmeter
Type E^m No. 66151.



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The Sangamo Integrating Wattmeter.

Type E. No.66151.

Volts 110. Amperes 10. Frequency any.

This Sangamo meter is of the mercury type. On the preceding blue print is given a partial vertical section together with an outline of the meter. The moving system consists of a light shaft carrying two discs, D and D'. The upper disc, D, rotates between the poles of two permanent magnets as shown in the upper part of the diagram. The lower disc, D', is enclosed in the chamber A which is filled with mercury. The shaft and the discs are buoyed up by the mercury and the upper end of the shaft bears against a jewel bearing J. The two poles of the series magnet M project thru the casing of the mercury chamber and are close to the under side of the disc D'. The series circuit consists of the single coil S wound on the laminated magnet M. T is a small, low potential, step-down transformer, the primary of which consists of a large number of turns of fine wire and is connected directly to the pressure posts of the meter. The secondary winding consists of only a few and in this case of only two turns of heavy wire. The small inductance coil I and the mercury chamber A connected in series constitute the main circuit of the secondary of this transformer. The secondary E.M.F. of this transformer is small but the secondary current is large because the inductance and resistance

The General Integrating Wattmeter.

Type E. No. 63151.

Volts 110. Amperes 10. Frequency 60.

On this type meter is of the mercury type.

The preceding blue print is given a partial vertical section together with an outline of the meter.

Moving system consists of a light shaft carrying two discs D and D'. The upper disc D rotates between the

poles of two permanent magnets as shown in the upper part of the diagram. The lower disc is enclosed

in the chamber A which is filled with mercury. The

shaft and the discs are buoyed up by the mercury.

The upper end of the shaft is fitted with a jewel bearing.

The two poles of the series magnet M project from the

ring of the mercury chamber and are also to the under

side of the disc D'. The series circuit consists of

the coil wound on the laminated magnet M.

T is a small, low potential, step-down transformer, the

primary of which consists of a large number of turns of

fine wire and is connected directly to the pressure

points of the meter. The secondary winding consists of

only a few and in this case of only two turns of heavy

wire. The coil is inductance coil I and the mercury

chamber A connected in series constitutes the

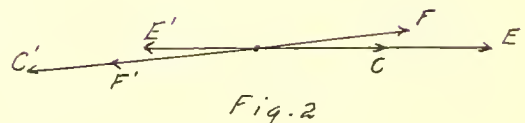
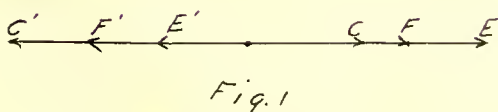
resistance of the transformer. The secondary

of this transformer is small but the secondary

current is large because the inductance and resistance

of the circuit are exceedingly small. This large secondary current enters one side of the mercury chamber A, flows across the disc D' and leaves at the opposite side of the mercury chamber. In passing across the disc this current flows past the poles of the series magnet M and the reaction between the series flux and the flux due to the secondary current produces the necessary torque. Friction compensation is obtained by means of the small coil C, which is connected thru the variable resistance R to the secondary terminals of the transformer T.

The phase relation of the various currents may be best explained by reference to the following vector diagrams. The first diagram disregards any lag of the currents or fluxes due to the effect of the coils and the iron in the circuits of the meter. The second diagram takes this into consideration. The magnetizing components of the currents in the transformer are so small that they are neglected in both cases.



Let E represent the E.M.F. impressed upon the primary of the potential transformer, and E' the secondary E.M.F. of this transformer. Let C be the current in the series

of the circuit are exceedingly small. This large secondary current enters one side of the mercury chamber A, flows across the disc, and leaves at the opposite side of the mercury chamber. In passing across the disc this current flows past the poles of the series magnet and the reaction between the series flux and the flux due to the secondary current produces the necessary torque. Friction compensation is obtained by means of the small coil C, which is connected from the variable resistance R to the secondary terminals of the transformer T.

The phase relation of the various currents may be best explained by reference to the following vector diagram. The first diagram disregards any lag of the currents or fluxes due to the effect of the coils and the iron in the circuit of the motor. The second diagram takes this into consideration. The magnetizing components of the currents in the transformer are so small that they are neglected in both cases.

Let E represent the E.M.F. impressed upon the primary of the potential transformer, and E' the secondary E.M.F. of this transformer. Let C be the current in the series

coil for a non-inductive load. Neglecting any effect due to inductance and hysteresis, the current in the series coil and the flux due to it will be in phase with the impressed E.M.F. Since the secondary circuit of the transformer is non-inductive, neglecting the effect of the inductance coil I for the first vector diagram, the secondary current C' will be in phase with its E.M.F., or 180 degrees out of phase with the series current. By making proper connections to the secondary terminals of the transformer, the pressure current vector C' may be considered to be in phase with the series current. The torque produced in the disc will, therefore, be proportional to the product of the pressure current and the series flux, which is proportional to the true watts.

The second vector diagram takes into consideration the fact that the series flux lags slightly behind the current due to the hysteretic effect of the iron core of the series magnet. In this diagram the vectors E, E', and C represent the same quantities as in the first diagram. F represents the series flux lagging slightly behind the series current due to the hysteresis in the series magnet. The small inductance coil I, see blue print, gives a slight lag to the pressure current bringing it into phase opposition with the series flux. We now have practically the same conditions

coil for a non-inductive load. Neglecting any effect due to inductance and capacitance, the current in the series coil and the flux due to it will be in phase with the impressed A.C. since the secondary circuit of the transformer is non-inductive, neglecting the effect of the induced e.m.f. in the first vector diagram, the secondary current I_2 will be in phase with its A.C. or 180 degrees out of phase with the series current. By making proper connections to the secondary terminals of the transformer, the primary current vector I_1 may be considered to be in phase with the series current. The torque produced in the disc will, therefore, be proportional to the product of the primary current and the series flux, which is proportional to the true watts.

The second vector diagram taken into consideration the fact that the series flux lags slightly behind the current due to the hysteretic effect of the iron core of the series magnet. In this diagram the vectors I_1 , I_2 , and Φ represent the same quantities as in the first diagram. I_2 represents the series flux lagging slightly behind the series current due to the hysteresis in the series magnet. The e.m.f. induced in coil 1, see blue print, gives a slight lag to the primary current bringing it into phase opposition with the series flux. We now have practically the same conditions

as in the preceding case, the pressure current being in phase with the series flux when proper connections are made. The torque will, therefore, as in the first case, be proportional to the true watts.

The results obtained in the determination of the flux phase relation show the angle between the pressure current and the series to be $53'$. This will make an error of 2.7 % with a power factor of .500. The error as determined experimentally with a power factor of .514 was between 2 % and 3 %. This meter gives nearly the same results with normal voltage and with 10 % high and 10 % low voltage, except with large overload. The per cent error with a current of 1.5 amperes is about 5 %. With 150 % load the greatest accuracy was obtained with the lowest voltage. With 10 % low voltage the meter is practically correct at 150% load, while with normal voltage there is an error about 3.5 %, and with 10 % high voltage there is an error of about 6.5 % with this same load. Taken as a whole the percent accuracy of this meter is very good. It will operate successfully with 120 cycles but will not operate on 25 cycles. The per cent accuracy on 120 cycles is not as good as on 60 cycles.

as in the preceding case, the pressure current being in phase with the series flux when proper connections are made. The torque will, therefore, as in the first case, be proportional to the time watts.

The results obtained in the determination of

the flux phase relation show the angle between the pressure current and the series to be 53°. This will make an error of 2.7% with a power factor of .800. The error as determined experimentally with a power factor of .815 was between 2% and 3%. This meter gives nearly the same results with normal voltage and with 10% high and 10% low voltage, except with large overload. The per cent error with a current of 1.5 amperes is about 2.5% with 150% load the greatest accuracy was obtained with the lowest voltage. At 10% low voltage the meter is practically correct at 150% load, while with normal voltage there is an error about 2.5% and with 10% high voltage there is an error of about 2.5% with this same load. When the voltage is the normal torque of this meter is very good. It will operate satisfactorily with 10% cycles but will not operate on 25 cycles. The per cent accuracy on 150% cycles is not as good as on 60 cycles.

The Sangamo Integrating Wattmeter.

Type F. No.76671.

Volts 110. Amperes 5. Frequency, any.

The type F Sangamo meter is very similar, in general construction, to the type E Sangamo meter but it is an improvement over the type E meter. The type F meter will be described with reference to the blue print given with the type E meter. In the type F meter the series coil S is wound in two parts, one part being on each leg of the laminated magnet M. The bottom casing of the mercury chamber is made of an alloy having a high resistance instead of the fibre used in the type E meter. The poles of the magnet M are close to the under side of this casing and hence close to the disc D'. The transformer T of the type F meter has a greater number of turns and a better magnetic circuit than that of the type E meter, hence the quadrature component of the primary current which is very small in the type E meter, as compared to the power component, is made still smaller in the type F meter. The disc D' is stamped in the form of a cart wheel giving a slightly different path to the current flowing across it than in the type E meter which has a plain disc. The vector diagram given with the type E meter applies equally well to the type F meter.

The results of the determination of the flux

The type 2 transformer is very similar, in

general construction, to the type 1 transformer but

it is an improvement over the type 1 motor. The type 2

motor will be described with reference to the disc being

given with the type 2 motor. In the type 2 motor the

series coil is wound in the stator, one part being on

each leg of the laminated magnet core. The bottom casing

of the mercury chamber is made of an alloy having

high resistance instead of the fibre used in the type 1

motor. The poles of the magnet core close to the

under side of this casing are hence close to the disc.

The transformer 2 of the type 2 motor has a greater

number of turns and a better magnetic circuit than that

of the type 1 motor, hence the magnetic component of the

primary current which is very small in the type 1 motor,

is compared to the power component, is made still smaller

in the type 2 motor. The disc 2 is placed in the

form of a cast wheel giving a slightly different path to the

current flowing across it than in the type 1 motor which

has a plain disc. The vector diagram given with the

type 2 motor applies equally well to the type 1 motor.

The results of the tabulation of the data

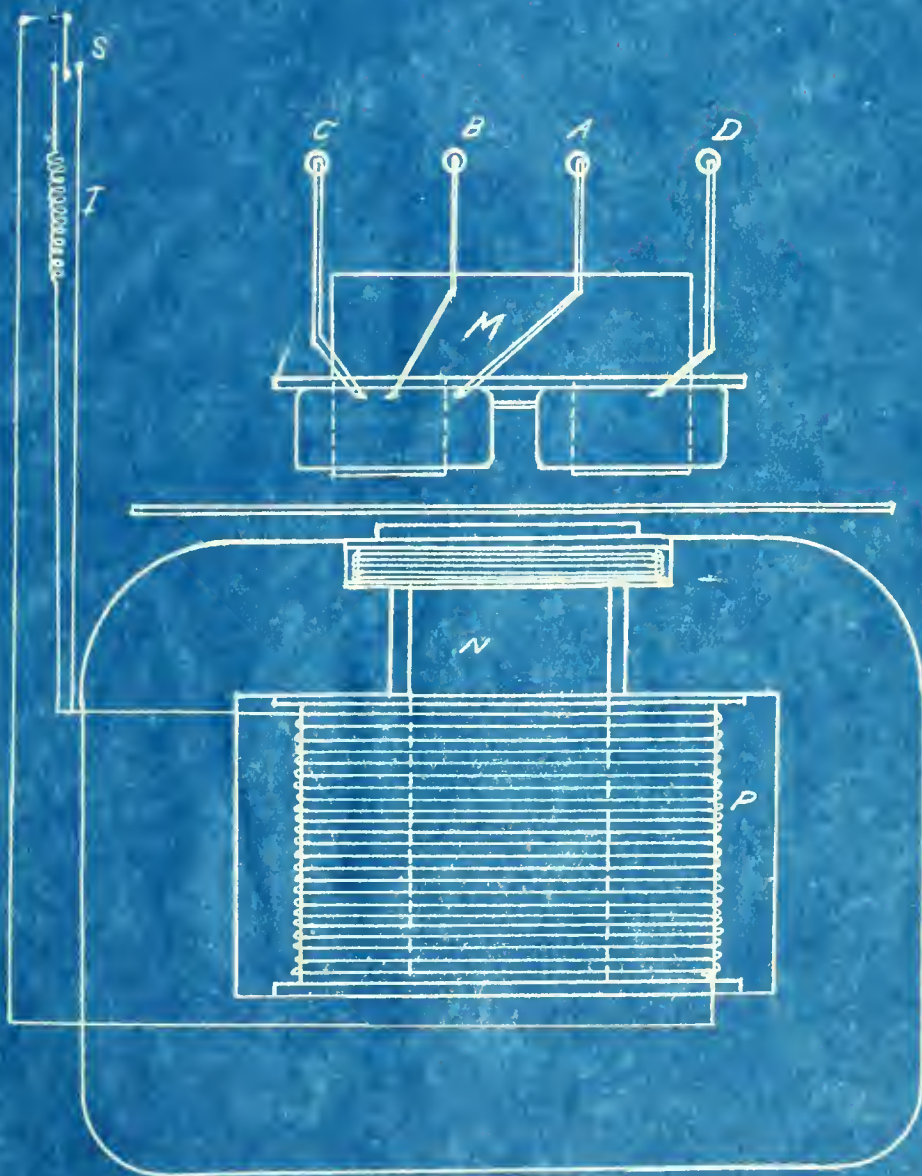
phase relation show the angle between the series flux and the pressure current to be $1^{\circ} 33'$. This phase difference will make an error of 4.5 % with a power factor of .500. The error as determined experimentally with a power factor of .570 is 3.4 %. As this error is positive the experimental error should be less than the calculated because friction tends to decrease the error. The type F meter gives practically the same results with normal voltage and with 10 % high and 10 % low voltage. With a load of 1.1 amperes the error obtained was about 9 %. As the load is increased the per cent accuracy rises quickly to approximately 100 % and remains within the allowable 2 % error up to 150 % load.

This meter is independent of the frequency. Run # 7, with normal voltage and a frequency of 120 cycles, was made immediately after run # 6, with normal voltage and a frequency of 25 cycles, no adjustment whatever being required for this change of frequency. The per cent accuracy obtained with 120 cycles is almost identical with that obtained with 25 cycles. In each case the meter was about 10 % slow with a load of 1.1 amperes and was practically correct on larger loads up to 50 % over load.

phase relation show the angle between the voltage and the pressure current to be 1.33'. This phase difference will make an error of 4.5% with a power factor of .900. The error as determined experimentally with a power factor of .700 is 3.4%. As this error is positive the experimental error should be less than the calculated because friction tends to decrease the error. The type meter gives practically the same results with normal voltage and with 10% high and 10% low voltage. With a load of 1.1 amperes the error obtained was about 0.5%. As the load is increased the per cent accuracy rises quickly to approximately 100% and remains within the allowable 2% error up to 150% load.

This meter is independent of the frequency. Run at 70% with normal voltage and a frequency of 120 cycles, was made immediately after run at 60% with normal voltage and a frequency of 25 cycles, no adjustment whatever being required for this change of frequency. The per cent accuracy obtained with 120 cycles is almost identical with that obtained with 25 cycles. In each case the meter was about 10% low with a load of 1.1 amperes and was practically correct on larger loads up to 50% over load.

Diagram of
The General Electric Integrating Wattmeter
No. 1506564.



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The General Electric Watt Hour Meter.

No. 1506564.

Volts 110. Amperes 1 - 10 - 20. Cycles 25 - 60.

This meter is known as the Thomson high torque induction test meter. An outline of the meter together with the circuit diagram is given on the preceding blue print. This meter is designed particularly for testing purposes and in order to obtain a good per cent accuracy with a wide range of load it is constructed with three separate current coils, one for 1 ampere, one for 10 amperes, and one for 20 amperes. With the use of these three coils we may reasonably get a good per cent accuracy on all loads from, say, .1 ampere to as high as 30 amperes. These coils have one common terminal D, see blue print, and three individual terminals, A, B, and C. They are wound on the two poles of the laminated magnet M. The pressure coil P is wound in the form of a bobbin on the laminated magnet N. The moving system consists of a light shaft carrying a large aluminum disc which rotates in the air gap between the poles of the series and pressure magnets and between the poles of damping magnets. The reaction between the series field and the field of the eddy currents induced in the disc by the pressure flux produces the required torque. The large diameter of the disc aids in producing the high torque. In order to make the meter suitable for both

This meter is known as the Thomson light torque induction test meter. An outline of the meter together with the circuit diagram is given on the preceding page. This meter is designed particularly for testing purposes and in order to obtain a good per cent accuracy with a wide range of load it is constructed with three separate current coils, one for 1 ampere, one for 10 amperes, and one for 20 amperes. In the use of these three coils we may reasonably get a good per cent accuracy on all loads from 1/2 ampere to a high 20 ampere. These coils have one common terminal, see first point, and three individual terminals, A, B, and C. They are wound on the two poles of the laminated magnet M. The pressure coil P is wound in the form of a bobbin on the laminated magnet M. The moving system consists of a light shaft carrying a large aluminum disc which rotates in the air gap between the poles of the series and pressure magnets. The pressure magnet is designed to produce a torque between the poles of the series magnet. The torque between the series magnet and the field of the edge currents induced in the disc by the pressure coil produces the resisting torque. The large diameter of the disc aids in producing a light torque. In order to make the meter a satisfactory test meter

60 and 25 cycles it is provided with a small inductance coil I which may be connected in series in the pressure circuit by means of the switch S, which is operated by a button at the top of the meter, when it is desired to operate the meter with 25 cycles.

The per cent accuracy of this meter was determined for the ten ampere coil only. The results of the determination of the phase relation of the series and pressure fluxes show the angle between them to be $90^{\circ} 48.5'$. This phase angle from quadrature will make an error of 2.4 % with a power factor of .5, as shown by the data giving the per cent accuracy as calculated from this flux phase determination. The error determined experimentally with a power factor of .536 was 5 %. The large error obtained experimentally is due partly to the fact that, as the error is negative, all frictional effects tend to increase it; also the load under which the experimental error was determined was 50 % of that under which the calculated error was determined. The difference in the per cent accuracy of the meter between full load and 50 % load with normal conditions is approximately 2 % which accounts largely for the difference between the calculated and experimental error with the low power factor. Practically the same results were obtained with this meter with normal voltage and with 10 % high and 10 % low voltage. From 50 % load up to 150 % load the accuracy is within

... 23 cycles it is provided with ...
... may be connected in series in the primary
... which is open to the atmosphere, which is open to the
... when it is desired to
... cycles.

The per cent accuracy of this method is determined
for the ten ampere coil only. The results of the
determination of the phase relation of the coil
... show the angle between the
... The phase angle from a distance will
... with a power factor of 0.8, the
... giving the per cent accuracy of
... from this distance determination.
... experimentally with a power factor of 0.8
... the large error obtained experimentally
is due partly to the fact that the error is negative,
... it is essential to increase it; also the
load under which the experimental error was determined
was 50% of the full load which the coil is rated for
... in the per cent accuracy
of the meter between full load and 50% load with normal
conditions is approximately 2% which accounts for the
for the difference between the calculated and experimental
error with the low power factor. Practically the
same results were obtained with this meter with normal
voltage and with 10% high and 10% low voltage.
From 50% load up to 150% load the accuracy is within

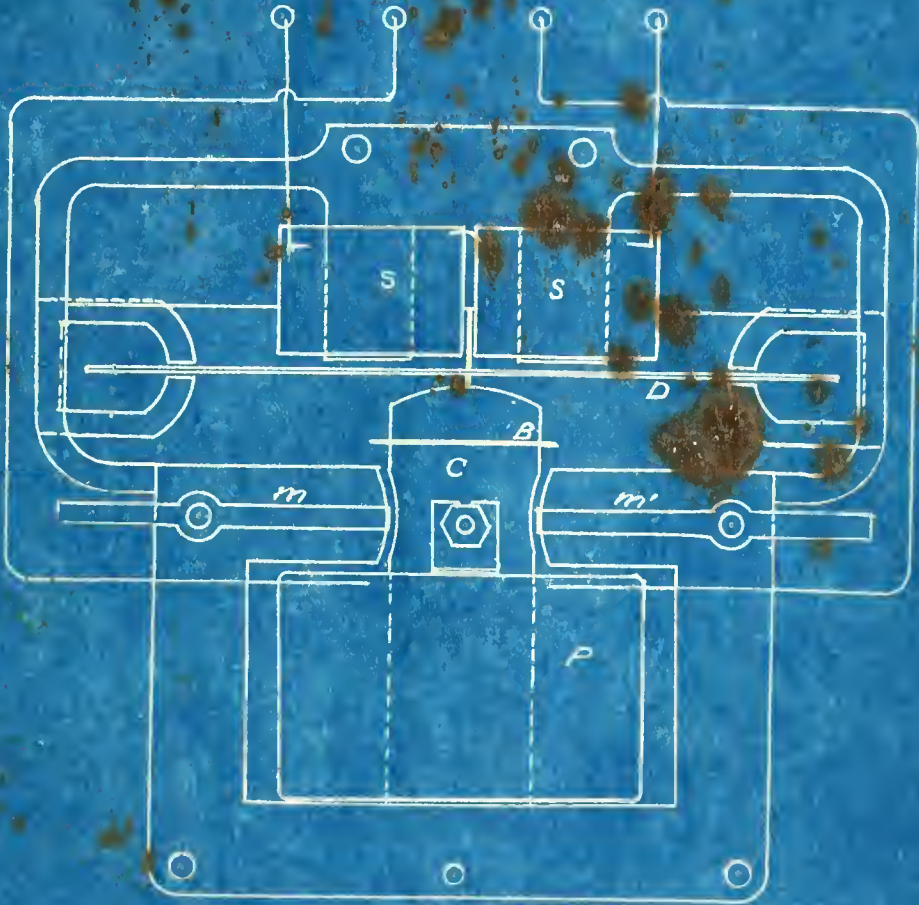
the allowable 2 % error. With a current of one ampere in the ten ampere coil the meter is approximately 15 % slow. This load, however, is within the range of the one ampere coil with which a negligible error could be obtained. The greatest low load error given with the ten ampere coil with loads beyond the range of the one ampere coil is approximately 10 %. The results obtained with 25 cycles are practically the same as the 60 cycle results.

the allowable error. With a current of one ampere
in the ten ampere coil the meter is approximately 15
slow. This load, however, is within the range of the
one ampere coil with which a negligible error could be
obtained. The greatest low load error given with the
ten ampere coil with loads beyond the range of the one
ampere coil is approximately 10%. The results
obtained with 25 cycles are practically the same as the
50 cycle results.

Diagram of

The Westinghouse Integrating Water Meter

Type C No. 681372



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The Westinghouse Watt Hour Meter.

Type C. No. 681372.

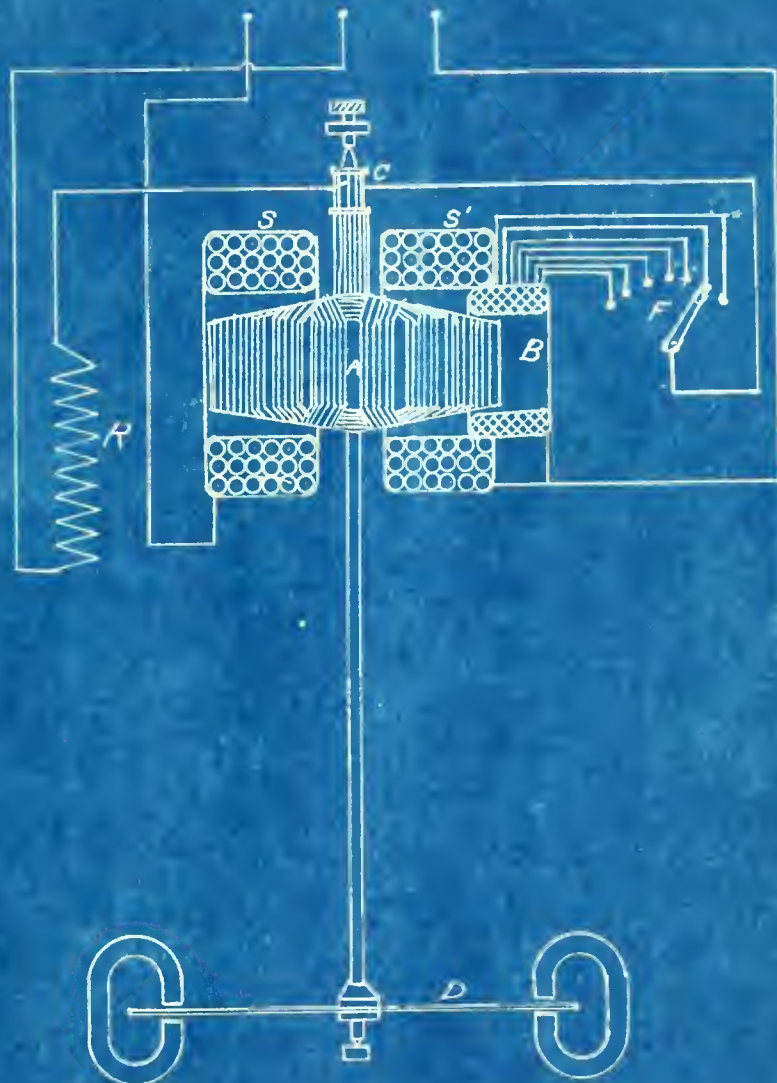
Volts 110. Amperes 15. Cycles 60.

This Westinghouse meter is of the induction type. The blue print given on the preceding sheet shows an outline of this meter with the circuit diagram. The rotating element consists of a light shaft carrying an aluminum disc which rotates between the poles of the series and pressure magnets and between the poles of the damping magnets. On the blue print D represents the disc. P is the pressure coil and S is the series coil. The copper bracket, B, surrounds the laminated pole, C, and furnishes means of adjustment for different frequencies. If the circuit of this bracket is opened the meter will be adjusted for 125 cycles, if this circuit is closed the meter will be adjusted for 60 cycles. The small brackets shown on the outer poles at m and m' provide for friction compensation. The adjustment for friction is obtained by first opening the series circuit, then raising these brackets, m and m' until the meter just starts on the pressure current only, and then lowering the brackets until the disc just stops. With this position of these brackets the torque due to the pressure current alone will not make the meter creep but is nearly sufficient to compensate for all moving friction. The moving system is supported on a highly polished steel ball between two cup-shaped jewels.

The results of the test for the determination of the phase relation of the series and pressure fluxes of this meter show that they are only $34'$ from quadrature, and that the angle between the fluxes is $90^\circ 34'$. This small angle from quadrature will make the meter run less than 2 % slow with a power factor as low as .500, as shown by the data calculated from this flux phase relation. This meter gives practically the same per cent accuracy with normal voltage and with 10 % high or 10 % low voltage, and also with normal voltage and either 25 or 120 cycles. The principal error found was the slowness of the meter on small loads. This meter is new and previous to this test had not been operated since leaving the factory. It was labeled by the manufacturers to be correct within 2 % - or - from 2 % of full load to 50 % overload. When first placed on the testing board it was found that the meter was correct within 2 % at full load and hence no adjustment was given it. The error of this meter under normal conditions with a load of one ampere, or 20 % of full load, was found to be about 25 %. The data shows that there is no decrease in the per cent accuracy of the meter up to 50 % overload, hence we would say that much better results could be obtained thru-out the entire range of the meter if the adjustments were made so that the meter would register correctly, or perhaps one or two per cent fast at about 75 % of full load.

The results of the test for the determination of the phase relation of the series and pressure lines of this meter show that the angle between the lines is 90 degrees and that the angle between the lines will make the meter run slow than 2% slow with a power factor as low as .500, as shown by the data calculated from this line phase relation. This meter gives practically the same per cent error with normal voltage and with 10% high or 10% low voltage, and also with normal voltage and either 25 or 120 cycles. The principal error found was the closeness of the meter on small loads. This meter is now in service on a factory. This test had not been operated since leaving the factory. It was labeled by the manufacturer to be correct within 2% or - from 2% of full load to 25% overload. When first placed on the testing stand it was found that the meter was correct within 2% at full load and hence no adjustment was given it. The error of this meter under normal conditions with a load of one ampere, or 20% of full load, was found to be about 25%. The data shows that there is no change in the per cent accuracy of the meter up to 50% overload, hence we would say that much better results could be obtained than with the entire range of the meter if the adjustments were made so that the meter would register correctly, or perhaps one or two per cent less at about 75% of full load.

Diagram of
The Duncan Integrating Wattmeter
No. 61666



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The Duncan Integrating Wattmeter.

No. 61666. Volts 110. Amperes 10.

This Duncan integrating wattmeter is an alternating current commutator meter. An outline of the meter with the circuit diagram is given on the preceding blue print. The moving system consists of a light shaft carrying the damping disc D, a coreless armature A, and the commutator C. The shaft is supported by a hardened steel point resting on a cup-shaped jewel. S and S' are the series coils. R is a resistance coil, containing no iron, connected in series with the armature. B is the compensating coil, the object of which is to give to the armature sufficient torque to counteract the effect of friction. By means of the small lever and contact points shown at F the number of active turns of this compensating coil can be varied. The flux due to the series coils is practically in phase with that of the armature, hence the meter should be correct on both non-inductive and inductive loads.

The results of the test for the determination of the phase relation of the series and pressure fluxes show the angle between them to be $59'$. This will make an error of about 3% with a power factor of .500, as shown by the data calculated from this flux phase determination. The error as determined experimentally with a power factor of .517 was 3.5%. This meter gives practically the same results with normal voltage

This Dunsen integrating wattmeter is an I beam type current commutator meter. An outline of the meter with the circuit diagram is given on the preceding page. The moving system consists of a light shaft carrying the damping disc D, a coil structure A, and the commutator C. The shaft is supported by a hardened steel point resting on a cup-shaped jewel. S and S' are the series coils. R is a resistance coil, containing no iron, connected in series with the structure. B is the compensating coil, the object of which is to give to the structure sufficient torque to counteract the effect of friction. By means of the small lever and contact points shown in the number of active turns of this compensating coil can be varied. The flux due to the series coils is practically in phase with that of the structure, hence the meter should be correct on both non-inductive and inductive loads. The results of the test for the determination of the phase relation of the series and pressure fluxes show the angle between them to be 52°. This will make an error of about 3% with a power factor of 0.8, as shown by the 6% calculated from this flux phase determination. The error is determined experimentally with a power factor of 0.5. This error gives practically the same results with normal voltage

and with 10 % high and 10 % low voltage. The per cent accuracy is practically the same for both 60 cycles and 25 cycles, there being no decrease in the accuracy up to 150 % load. For 120 cycles the accuracy curve reaches a maximum at about 80 % load and decreases on over load. With 10 % load the meter is about 20 % slow on all frequencies.

The Duncan Integrating Wattmeter.

No. 74520. Volts 110. Amperes 10.

This Duncan meter is a direct current meter. In appearance and construction it is practically the same as the Duncan alternating current commutator meter described above, except that all parts are heavier in the direct current meter than in the alternating current meter. The blue print given with the Duncan meter No. 61666 showing the outline and circuit diagram of that meter applies equally to the Duncan meter No. 74520. In the direct current meter the resistance coil R is enclosed in the back of the meter, being wound in several sections on a thin board. The description given with the Duncan meter No. 61666 applies to this meter also.

This meter was tested with alternating current only and the following is a brief summary of the results obtained. The results of the test for the determination of the flux phase relation show the angle between the series and pressure fluxes to be $25.5'$. This will make an error of only 1.1 % in the percent accuracy of the meter with a power factor of .500. The error as determined experimentally with a power factor of .517 was about 1 %. A large per cent error was given by this meter on light load, this being 30 % with a load of 1.55 amperes at normal voltage. There is no decrease in the per cent accuracy of the meter up to

150 % load. Since the inductance of the circuits of this meter is very small it will be practically independent of the frequency. The results obtained with 25 cycles are practically the same as those obtained with 60 cycles.

to insure that the insurance of the ... 1901, 1902.

this motor is very small it will be ...

independent of the ... The results of ...

with 25 cycles ... or ... the ...

with 50 cycles.

Calibration Data for Weston Voltmeter # 5091.

True Volts.	Voltmeter Reading.
90	89.9 ⁰
95	94.95
97.5	97.5
100	100.0
102	102.05
104	104.1
106	106.0
108	107.9
110	109.8
112	111.85
114	113.75
116	115.75
118	117.85
120	119.80

Calibration Data for Weston Voltmeter 5091.

Volts	Volmeter Reading.
90	89.90
95	94.92
97.5	97.5
100	100.0
105	105.02
107	107.1
108	108.0
109	107.9
110	109.2
115	111.32
117	115.72
118	115.72
119	117.82
120	118.80

Calibration Data for Queen & Co's. Dynamometer # 11.

Volts.	Amperes.	True Watts.	Dynamometer Reading.
50	.1	5	2
"	.2	10	5
"	.3	15	7.75
"	.4	20	10.75
"	.5	25	13.75
"	.6	30	16.75
"	.7	35	19.50
"	.8	40	22.50
"	.9	45	25.50
"	1.0	50	28.50
"	1.2	60	34.00
"	1.4	70	39.50
"	1.6	80	45.50
"	2.0	100	57.00
"	2.4	120	68.00
"	2.8	140	79.50
"	3.2	160	90.75
"	3.6	180	102.75
"	4.0	200	111.25
"	4.4	220	125.00
"	4.8	240	136.50
"	5.2	260	147.75

Calibration Data for Electro-dynamometer
 for the Calibration of Thomson A.C. Ammeter # 144085, and
 of Thomson A.C. Ammeter # 82511.

Time in seconds.	Dynamometer Reading.
1.0	2.0
1.5	2.5
2.0	2.5
2.5	2.8
3.0	11.0
4.0	20.0
5.0	21.0
6.0	44.5
7.0	61.0
8.0	79.0
9.0	99.0
10.0	122.5
11.0	148.5
12.0	178.5
13.0	208.0
14.0	239.5
15.0	274.5

Calibration Data for Thomson A.C. Ammeter # 144085.

Dynamometer Reading	True Amperes.	Ammeter Reading.
2.	1.0	.90
4.	1.65	1.54
6.	2.08	1.895
9	2.60	2.38
12.5	3.10	2.97
16.	3.55	3.45
20.5	4.03	3.91
25.	4.45	4.31
30.	4.90	4.74

Calibration data for Thomson .0.1mmeter # 144085.

mmeter Reading.	True mmbers.	Dynamometer Reading
.00	1.0	0.
1.00	1.05	4.
1.005	2.08	6.
2.08	2.60	8
2.97	3.10	12.5
3.45	3.55	16.
3.91	4.03	20.5
4.31	4.45	25.
4.74	4.90	30.

Calibration Data for Thomson A.C. Ammeter # 82511.

Dynamometer Reading.	True Amperes	Ammeter Reading.
8	2.45	2.2
12	3.1	2.8
16.5	3.6	3.3
19	3.9	3.7
24	4.4	4.2
29	4.82	4.61
36	5.35	5.1
40	5.70	5.5
45.5	6.05	5.88
60	6.95	6.78
80	8.10	8.00
98.5	9.00	8.89
138	10.60	10.50
165	11.65	11.53
189.5	12.45	12.37
214	13.30	13.20
245	14.20	14.10
286	15.35	15.25

Calibration Data for Thomson C. G. Ammeter # 82511.

Reading. Ammeter	True Amperes	Reading. Ammeter
2.2	2.45	8
2.8	3.1	12
3.2	3.6	16.5
3.7	3.9	19
4.2	4.4	24
4.61	4.85	29
5.1	5.35	35
5.5	5.75	40
5.88	6.05	45.5
6.78	6.95	50
8.00	8.10	60
8.88	8.90	68.5
10.50	10.60	108
11.50	11.65	125
12.75	12.95	139.5
13.50	13.60	144
14.10	14.20	145
15.25	15.35	155

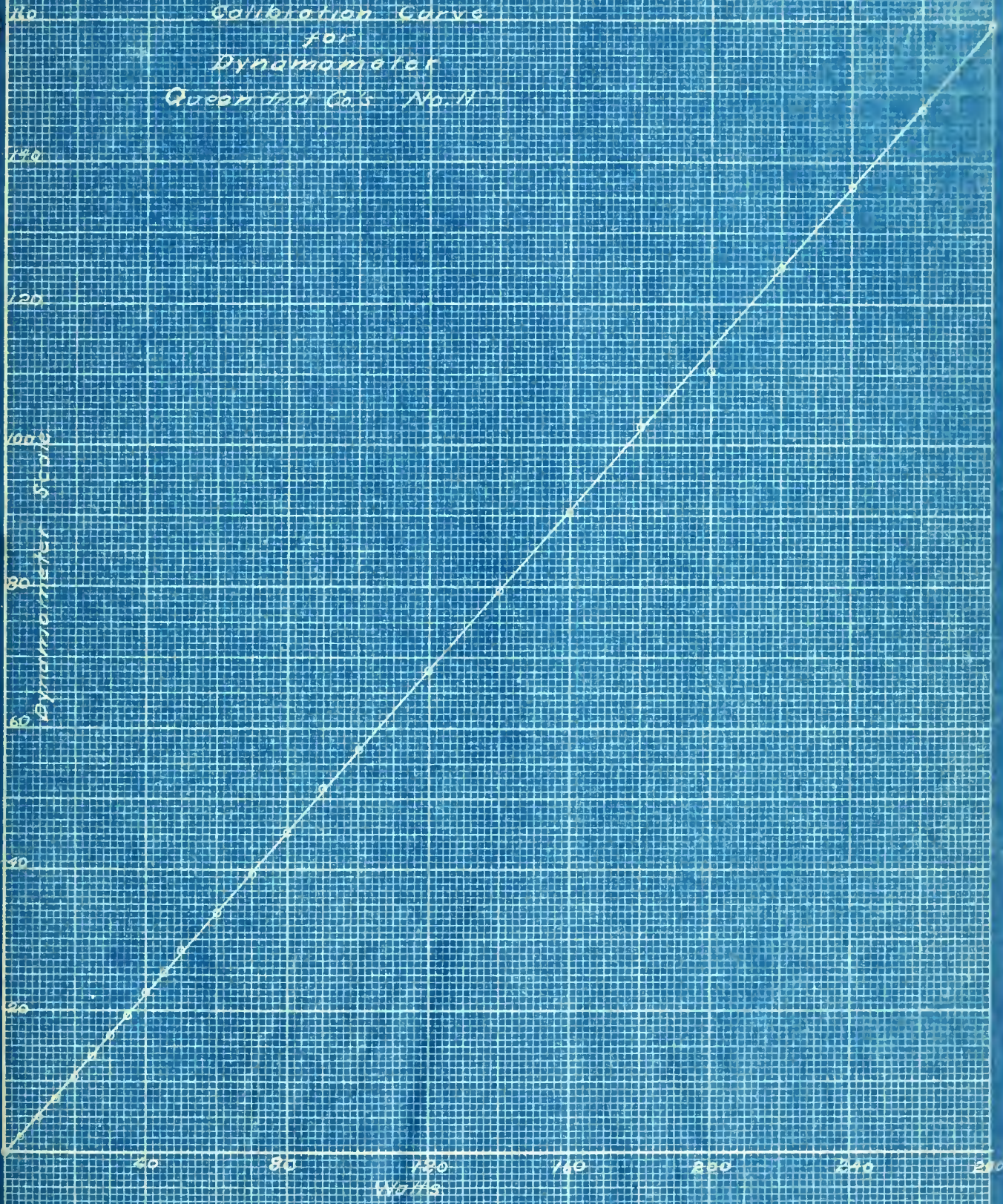
Calibration Data for Weston Wattmeter # 466.

Volts.	Amperes	True Watts	Wattmeter Reading.
100	1.23	123	103
"	1.70	170	140
"	2.23	223	200
"	2.60	260	237
"	3.42	342	315
"	3.78	378	353
"	4.28	428	408
"	4.58	458	440
"	5.60	560	546
"	6.40	640	624
"	7.20	720	710
"	8.05	805	800
"	9.03	903	897
"	9.90	990	986
"	11.42	1142	1140
"	12.22	1222	1222
"	13.20	1320	1318
"	13.95	1395	1395
"	14.75	1475	1476
"	15.60	1560	1560
"	16.15	1615	1616

Calibration Data for Weston Wattmeter # 456.

Wattmeter Reading	True Watts	Amperes	Volts
103	133	1.33	100
140	170	1.70	"
200	232	2.32	"
237	260	2.60	"
275	342	3.42	"
292	378	3.78	"
408	428	4.28	"
440	458	4.58	"
546	560	5.60	"
624	640	6.40	"
710	730	7.30	"
800	802	8.02	"
837	902	9.02	"
982	990	9.90	"
1140	1142	11.42	"
1222	1222	12.22	"
1278	1280	12.80	"
1322	1292	12.92	"
1476	1476	14.76	"
1560	1560	15.60	"
1616	1612	16.12	"

Calibration Curve
for
Dynamometer
Queen and Co's No. 11

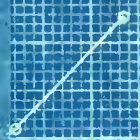


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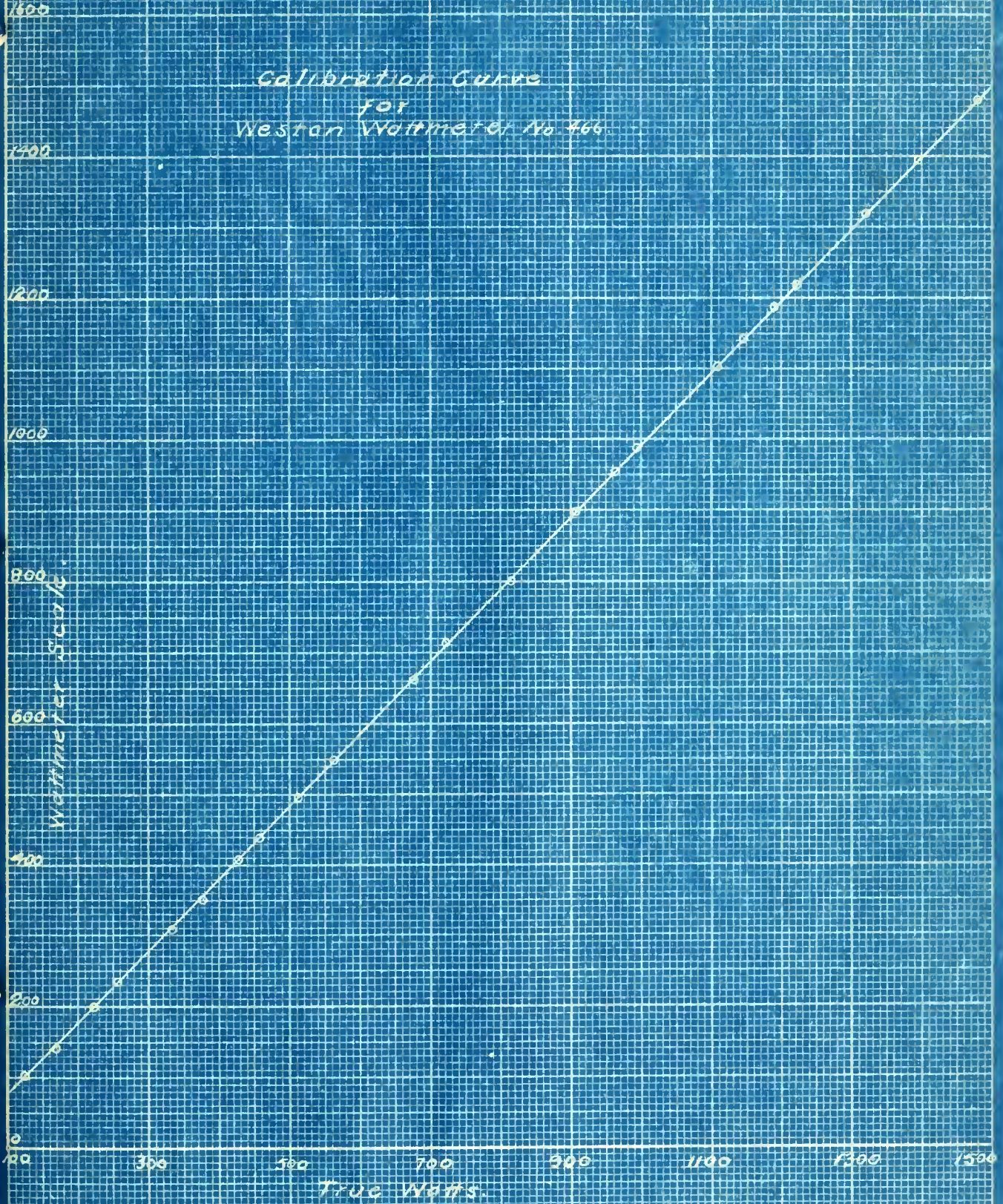
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Calibration Curve
for
Weston Voltmeter No 466



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Fort Wayne Meter # 252944.

Resistance of pressure coil 357. ohms.
 " " series "034 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 110	Amperes 10	Apparent Watts 1100		
Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .	
Forward	-7	13.5	.01228	
"	-7.5	14	.01272	
"	-6.5	13	.01180	
Backward	33	59	.05640	
"	35	62	.05640	
"	36	64	.05820	
Average cos θ for forward rotation01227	
"	θ	"	" 90° 42'
"	cos θ	" backward	"05620
"	θ	"	" 86° 47.5'
Phase angle from quadrature for forward rotation			42'	
"	"	" backward	"	3° 12.5'
Average phase angle from quadrature			1° 15.25'	
Phase angle between series and pressure fluxes .			91° 15.25'	

Fort Wayne Meter #252944.

Run # 1.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

110 volts.

60 cycles.

Temperature 76 F

Current	True Watts	R	T	Watts Recorded	% Recorded.
1.05	130	3	100	108	83.2
3.13	345	10	114.5	314	91.2
4.85	537	17	118.5	517	96.3
7.85	870	28	117.2	860	98.8
10.70	1178	38	116.8	1170	99.5
12.85	1420	46	118.0	1405	99.0
14.80	1630	52	115.5	1620	99.5

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Meter 1252944.

Run 1.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

Temperature 76 F	60 cycles.	110 volts.				
Recorded.	Recorded	Time .atts	R	T	Recorded	Recorded.
82.2	108	130	3	100	1.25	
81.2	214	245	10	114.5	2.12	
80.2	217	297	17	118.5	4.82	
83.8	280	370	28	117.2	7.82	
82.5	1170	1178	38	116.8	10770	
82.0	1405	1420	46	118.0	12.82	
82.5	1220	1220	52	115.5	14.80	

R is the no. of revolutions made by the disc in 1/2 seconds.

Fort Wayne Meter # 252944.

Run # 2.

Data showing the effect of change of load with unity power factor, normal frequency, and 91 % normal voltage.

100 volts.

60 cycles.

Temperature 76 F.

Current	True Watts	R	T	Watts Recorded	% Recorded.
1.10	110	2	86	84	76.3
3.25	325	10	120	300	92.5
5.00	500	16	120	480	96.0
7.68	770	25	117.3	768	99.8
10.30	1032	35	121	1040	100.8
12.45	1248	41	118.3	1245	100.0
15.50	1545	51	117.5	1565	101.3

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Motor # 252944.

Run # 2.

Data showing the effect of change of load with unity power factor, normal frequency, and 91 1/2 normal voltage.

100 volts. 60 cycles. Temperature 76 F.

Current	Time, sec	R	T	Watts Recorded	Temperature Recorded
1.10	110	2	88	84	76.0
2.25	225	10	120	200	82.5
5.00	500	15	120	480	86.0
7.88	770	25	117.5	758	89.8
10.80	1082	35	121	1040	100.8
12.45	1248	41	118.5	1215	100.0
15.50	1545	51	117.5	1525	101.0

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Meter # 252944.

Run # 2.3

Data showing the effect of change of load with unity power factor, normal frequency, and 109 % normal voltage.

120 volts.		60 cycles.		Temperature 78 F.	
Current	True Watts.	R	T	Watts Recorded	% Recorded.
1.28	155	3	85	127	82.
3.40	400	12	114.5	377	94.4
4.90	590	18	116.5	557	94.5
7.75	925	30	119.4	905	98.0
10.40	1244	40	118.0	1220	98.5
12.00	1440	47	116.2	1420	98.8
14.65	1760	56	116.8	1725	98.0

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Motor 332944.

Run 2.

Data showing the effect of change of load with unity power factor, normal frequency, and 100% normal voltage.

120 volts. 60 cycles. Temperature 73 F.

Recorded Watts	Recorded Watts	T	R	Time (secs)	Current
82.8	127	88	3	155	1.38
94.4	277	114.5	12	400	3.40
94.5	527	116.5	18	530	4.30
98.0	905	119.4	30	925	7.75
93.7	1220	118.0	40	1244	10.40
92.8	1220	116.2	47	1440	12.00
99.0	1725	116.8	55	1750	14.85

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Meter # 252944.

Run # 4.

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts 10 amperes 60 cycles Temperature 75 F					
Cos θ	True Watts	R	T	Watts Recorded	% Recorded
1.000	1100	20	65	1110	101
.976	1075	35	117	1075	100
.907	998	34	122	1000	100.2
.855	940	31	120	930	99.0
.810	890	30	123	880	98.8
.745	820	27	120.5	806	98.4
.700	770	25	119	755	98.0
.622	685	22	119.5	663	96.8
.508	560	18	121	535	95.5

R is the no. of revolutions made by the disc in T seconds.

Fort Wayne Meter # 252044.

Run # 4.

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts	10 amperes	60 cycles	Temperature 75 F
cos φ	True Watts	Watts	Recorded
1.000	1100	1100	101
.975	1075	1075	100
.950	998	1000	100.8
.925	940	930	99.0
.910	890	885	98.8
.875	820	830.5	98.4
.850	770	775	98.0
.825	685	715.5	96.8
.800	580	625	95.5

φ is the no. of revolutions made by the disc in 1 second.

Fort Wayne Meter # 252944.

5.

Data, calculated from the flux quadrature determination, showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts.

10 amperes.

60 cycles.

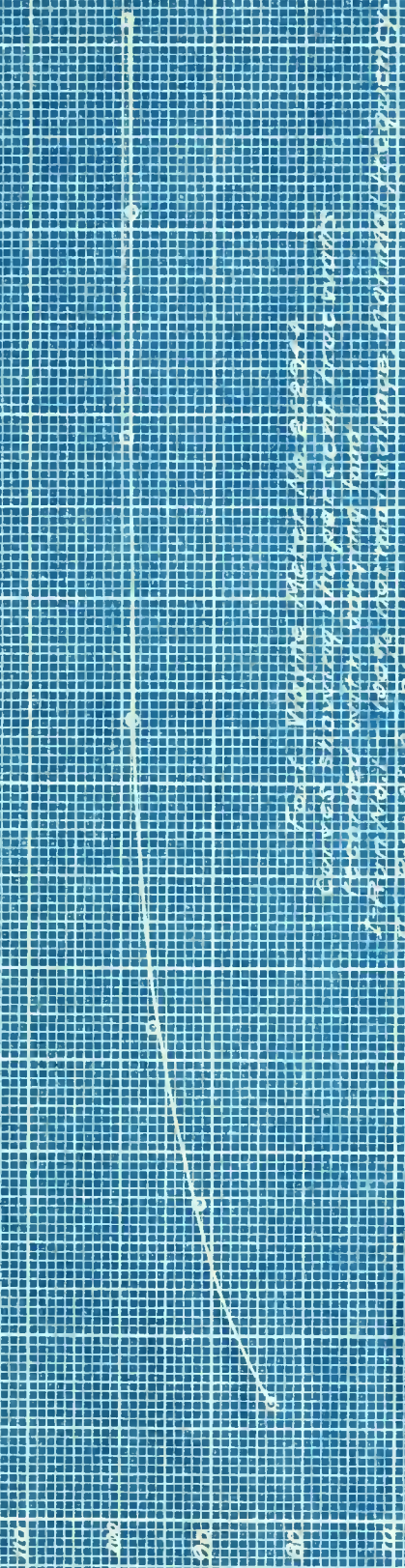
Cos θ .	True Watts.	Watts Recorded.	% Recorded.
1.0000	1100	1100	100.0
.9396	1032	1024	99.5
.8660	954	939	98.5
.7660	844	826	97.9
.6428	708	689	97.4
.5735	631	612	97.0
.5000	550	530	96.3

Port Wayne Meter # 252944.

5.

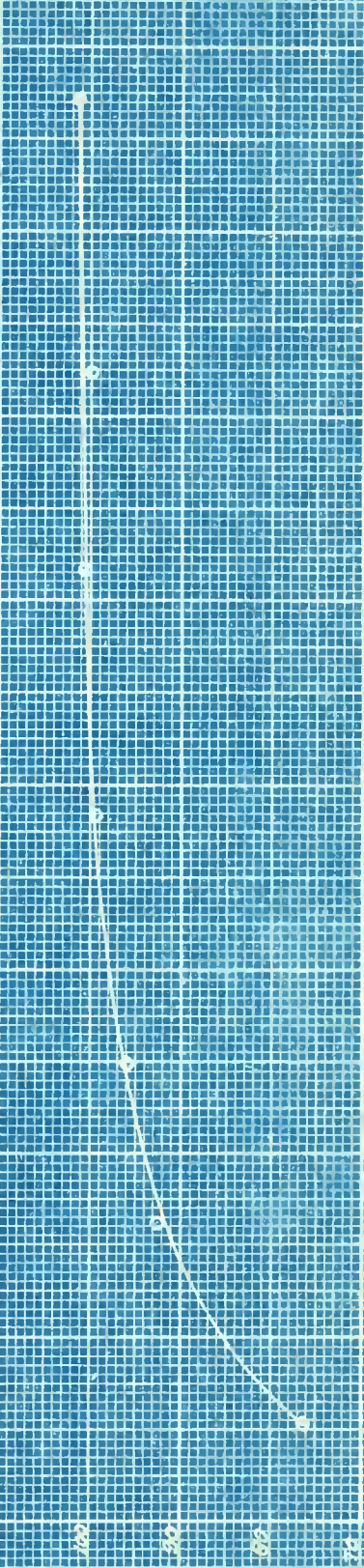
Data, calculated from the flux quadrature determination, showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

60 cycles.	10 amperes.	110 volts.	110 volts.
Watts Recorded.	Watts Recorded.	True Watts.	Cos θ .
100.0	1100	1100	1.0000
99.5	1084	1082	.9999
98.5	982	982	.9998
97.9	982	844	.9997
97.4	689	702	.9996
97.0	612	631	.9995
96.3	520	550	.9994



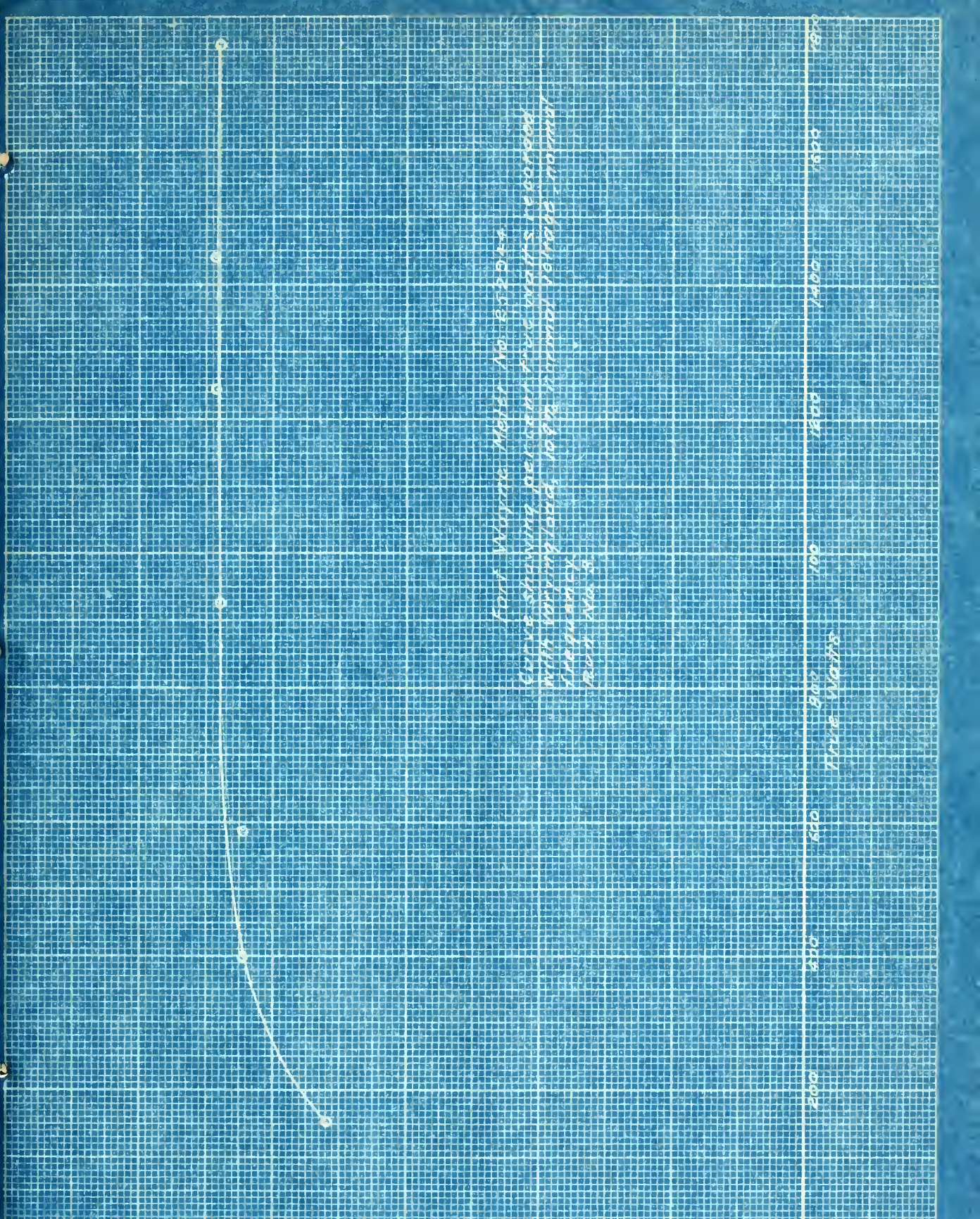
PERCENT OF MASS VERSUS TIME FOR 1000 CC SOLUTION

1000 cc solution
 Percent of mass versus time for 1000 cc solution
 The percent of mass versus time for 1000 cc solution
 The percent of mass versus time for 1000 cc solution



PERCENT OF MASS VERSUS TIME FOR 500 CC SOLUTION

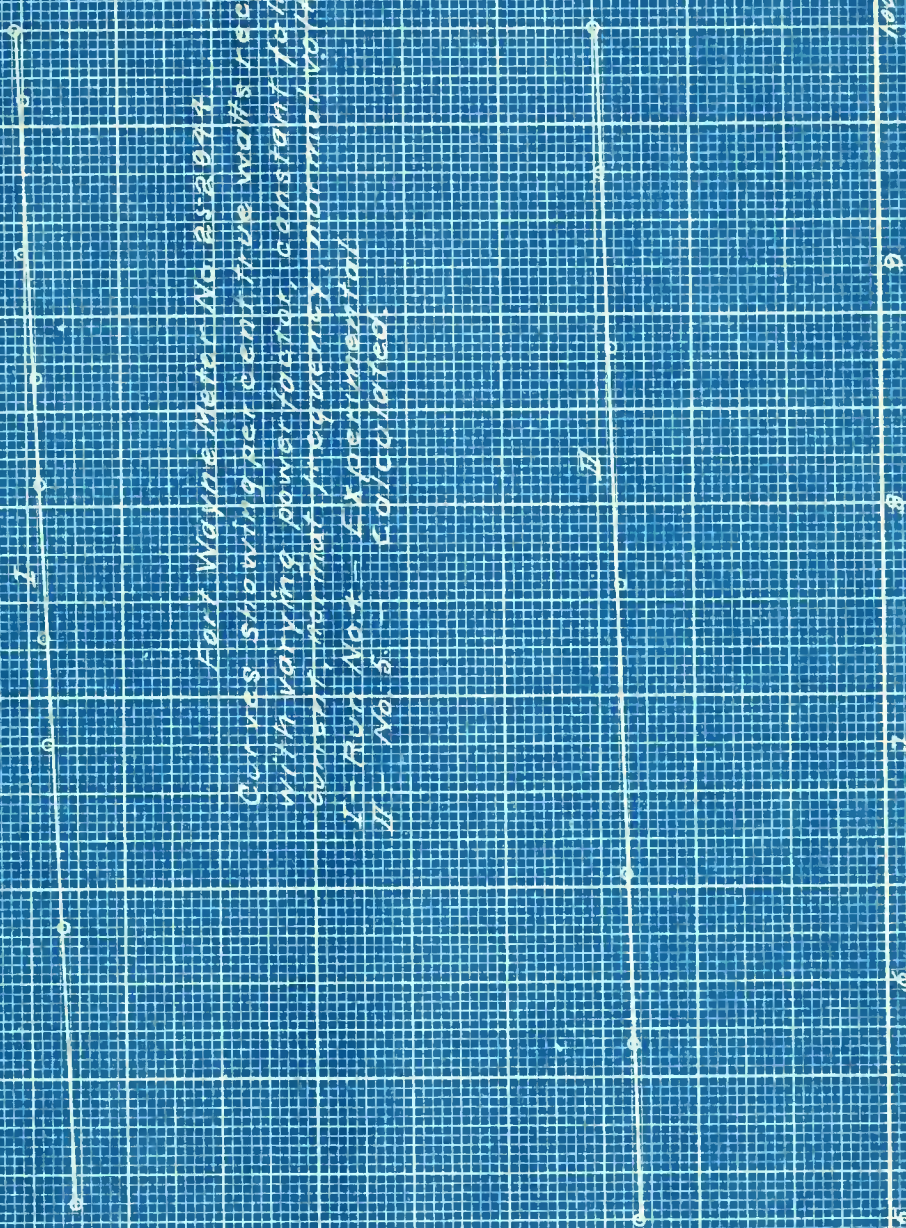
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THE HISTORY OF THE UNITED STATES OF AMERICA
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Per Cent True Watts Recorded



Fort Wayne Meter No. 2522977

Curves showing per cent true watts recorded with varying power factor, constant full load constant, normal frequency, normal voltage

I - Run, No. 1 - Experimental

II - No. 5 - Calculated

Power Factor - Cos φ

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Ferranti Meter # 222322.

Resistance of pressure coil 201.0 ohms.
 " " series "0225 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 110 Amperes 15.8 Apparent Watts 1738.

Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ
Forward	13.5	25	.0144
"	12.5	23	.0133
"	15.0	27.5	.0158
Backward	20.5	37	.0212
"	20.5	37	.0212
"	20.0	36	.0207
Average cos θ for forward rotation0145
" " " " backward "02103
" θ " forward "		89° 10'
" " " backward "		88° 47'
Phase angle from quadrature for forward rotation			50'
" " " " backward "		1° 13'
Average phase angle from quadrature			1° 1.5'
Phase angle between series and pressure fluxes ..			91° 1.5'

Ferranti Meter # 222322.

Run # 1.

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and 100 % normal voltage.

110 volts.		60 cycles.		Temperature 77 F.	
Current	True Watts	R	T	Watts Recorded	% Recorded
1.00	130	10	151	110.5	85.0
2.54	280	20	127.5	262.	93.6
3.95	435	32	127	422	97.0
5.90	650	50	128	653	100.2
8.95	985	75	126.5	990	100.5
11.40	1253	100	133	1256	100.2
13.25	¹⁴⁶⁰ 1253	120	137	1462	100.0
15.75	1740	140	137	1706	98.0

R is the no. of revolutions made by the disc in T seconds.

Wattmeter # 22222

Run # 1

Data showing the relation between the load and the
of true watts recorded with unity power factor, normal
frequency, and 100% normal voltage.

Temperature W F.	60 cycles.	110 volts.	Current	True Watts	R	P	Watts Recorded	Watts Recorded
85.0	151	130	1.00	130	10	151	110.5	85.0
85.5	137.5	280	2.54	280	20	137.5	280	85.5
87.5	137	435	3.95	435	32	137	435	87.5
100.0	133	550	5.20	550	50	133	550	100.0
100.5	126.5	685	6.95	685	75	126.5	685	100.5
100.5	133	1255	11.40	1255	100	133	1255	100.5
100.0	137	1555	12.35	1555	130	137	1465	100.0
98.0	137	1740	15.75	1740	140	137	1700	98.0

R is the no. of revolutions made by the disc in 1 second.

Ferranti Meter % 222322.

Run # 2.

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and 91 % normal voltage.

Current	True Watts	R	T	Watts Recorded	% Recorded
1.13	125	10	146	114.4	91.4
2.45	270	21	136	258	95.5
5.75	578	46	132	582	100.5
8.98	900	68	126	902	100.2
11.43	1153	90	131	1148	97.0
13.23	1325	100	126	1325	100.0
15.40	1540	120	131	1530	99.5

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter No. 222222.

Run 12.

Data showing the relation between the load and the %
of true watts recorded with unity power factor, normal
frequency, and 91 1/2 normal voltage.

Current	True Watts	T	Watts Recorded	% Recorded
1.12	122	146	114.4	93.4
2.25	270	136	258	95.5
2.75	278	132	282	100.2
3.98	300	126	302	100.2
11.42	1122	121	1148	97.0
12.22	1222	126	1222	100.0
12.40	1240	121	1222	98.2

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter # 222322.

Run # 3

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and 109 % normal voltage.

120 volts.		60 cycles.		Temperature 77 F.	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.15	140	10	135	123.8	88.5
3.34	400	28	121	387	96.6
5.85	700.8	50	118	707	100.8
9.65	1160	88	127	1157	99.8
12.50	1500	110	122.5	1500	100.0
15.60	1880	150	136	1912	101.5

R is the no. of revolutions made by the disc in T seconds.

Terranti Motor # 222222.

Run # 3

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and 100% normal voltage.

Temperature V F.	60 cycles.	120 volts.	Current	Time (watts)	R	T	Watts Recorded	% Recorded.
			1.15	140	10	125	122.8	88.5
			2.34	400	28	121	387	96.6
			2.85	700.8	50	118	707	100.8
			2.65	1160	88	127	1157	99.8
			12.50	1500	115	122.5	1500	100.0
			12.60	1880	150	126	1812	101.5

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter # 222322.

Run # 4.

Data showing the relation between the load and the % of true watts recorded with unity power factor, 100 % normal voltage, and 25 cycles, temperature 75 F.

Current.	True Watts.	R.	T.	Watts Recorded.	% Recorded.
1.10	120	7	116	101	84.3
3.45	378	25	117	368	97.3
5.25	574	39	117	558	97.5
7.45	822	56	118.4	780	96.8
9.50	1042	69	115	990	96.8
11.60	1278	85	115	1220	97.2
13.20	1455	95	114	1395	95.7
15.10	1665	109	115.3	1585	95.3

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter # 223222.

Run # 4.

Data showing the relation between the load and the % of

true watts recorded with unity power factor, 100% normal

voltage, and 35 cycles, temperature 75 F.

Current.	True watts.	R.	F.	Watts Recorded.	% Recorded.
1.10	120	7	116	101	84.2
3.45	378	25	117	368	97.3
5.25	574	39	117	558	97.5
7.45	822	56	118.4	780	96.8
9.50	1042	69	115	930	96.8
11.60	1278	85	115	1220	97.3
13.20	1452	95	114	1325	95.7
15.10	1622	109	113.3	1525	95.3

R is the no. of revolutions made by the disc in 1 second.

Ferranti Meter #222322.

Run # 5

Data showing the effect of change of load at normal voltage, unity power factor and 25 cycles.

110 volts		25 cycles		Temperature 80 F	
Current	True Watts	R	T	Watts Recorded	% Recorded
1.54	169.4	12	132	152	89.25
3.52	387.8	30	139	361	93.1
6.88	757.5	60	136.5	735	97.0
9.30	1022.0	77	128	1005	98.5
12.68	1393.0	100	124.7	1338	96.0
15.32	1686	121	125	1617	96.0

R is the no. of revolutions made by the disc in T seconds.

Terranti Meter #232222.

Run 1 2

Data showing the effect of change of load at normal voltage, unity power factor and 25 cycles.

110 volts 25 cycles Temperature 80 F

Current	True Watts	R	T	Watts Recorded	% Recorded
1.54	169.4	12	132	152	89.25
3.52	387.8	30	152	361	93.1
6.88	757.5	60	186.5	735	97.0
9.30	1022.0	77	188	1005	98.3
12.68	1328.0	100	124.7	1328	98.0
15.32	1686	121	125	1617	96.0

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter # 222322.

Run # 6

Data showing the effect of change of power factor with constant full load, normal voltage and 60 cycles.

110 volts.

10.1 amperes.

Temperature 80 F.

Cos.θ	True Watts	R	T	Watts Recorded	% Recorded
1.000	1110	40	59.5	1128	102.5
.930	1032	40	63	1060	102.5
.864	958	54	92	985	102.5
.750	832	32	63.5	843	101.5
.672	745	28	62	756	101.5
.620	688	26	62	703	101.7
.567	628	24	63	638	101.5
.516	573	22	63.5	582	101.5

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter " 222222.

Run 6

Data showing the effect of change of power factor with constant full load, normal voltage and 60 cycles.

Temperature 80 F.	110 volts.	10.1 amperes.	Temperature 80 F.
Recorded	Time watts	R	Recorded
%			Watts
Recorded			Recorded
102.5	1110	40	1128
102.5	1032	40	1060
102.5	958	34	982
101.5	882	32	842
101.5	742	28	752
101.7	688	26	702
101.5	628	24	658
101.5	572	22	582

R is the no. of revolutions made by the disc in T seconds.

Ferranti Meter # 222322.

#7

Data calculated from the flux quadrature determination showing the effect of change of power factor with constant full load, normal voltage and frequency.

110 volts.

10 amperes.

60 cycles.

Cos.θ	Watts Recorded	True Watts	% Recorded
1.0000	1099.78	1100	100
.9848	1079.76	1083.28	99.8
.9597	1026.85	1033.67	99.2
.8660	942.70	952.60	98.5
.7660	829.95	824.60	98.3
.6428	692.00	707.00	97.9
.5000	533.00	550.00	97.0

Permitt Meter 22222

Data calculated from the flux waveform determination showing the effect of change of power factor with constant full load, normal voltage and frequency.

110 volts.	10 amperes.	60 cycles.
1.0000	1092.78	1100
.9848	1072.76	1082.28
.9727	1052.85	1062.67
.9600	942.70	952.60
.7660	822.25	824.60
.6428	692.00	707.00
.5000	552.00	550.00

1000

750

500

250

0

Per Cent of Time Walks Recorded



Patient's Ankle, No Record

curves showing person's time walks recorded with varying load.

1. 1000 lbs. net & no load in the 1st 10 minutes of experiment
 2. 1000 lbs. net & 100 lbs. load in the 1st 10 minutes
 3. 1000 lbs. net & 200 lbs. load in the 1st 10 minutes
 4. 1000 lbs. net & 300 lbs. load in the 1st 10 minutes

1000

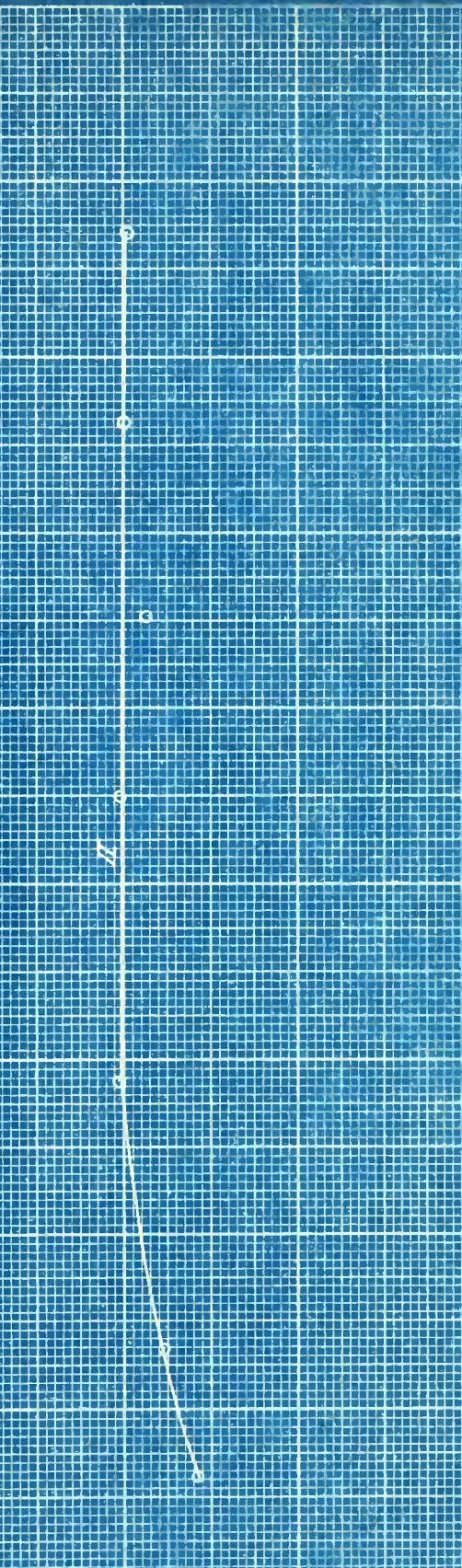
750

500

250

0

Per Cent of Time Walks Recorded



1000

750

500

250

0

1000

750

500

250

0

1000

750

500

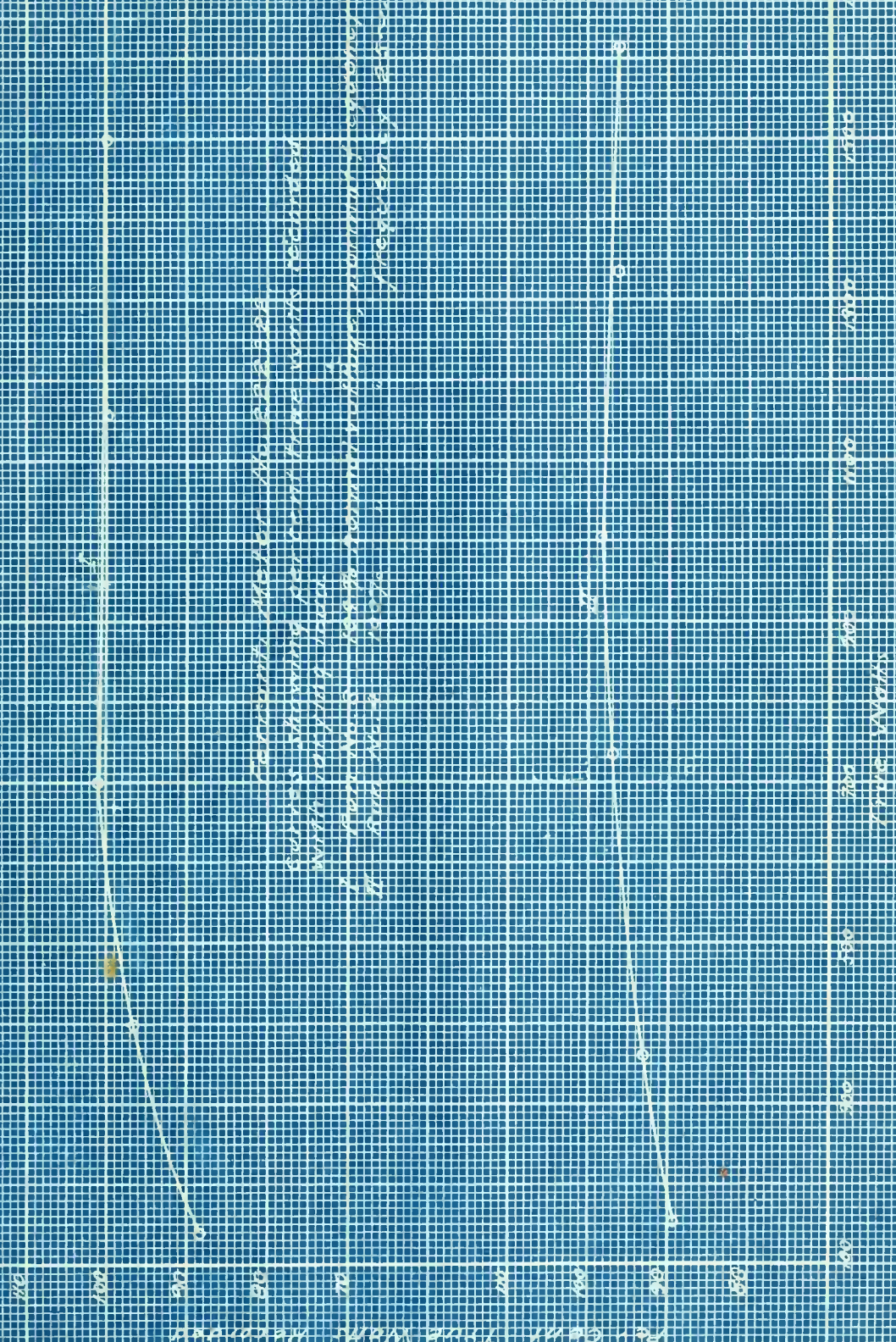
250

0

Time (min)

1000 750 500 250 0 1000 750 500 250 0 1000 750 500 250 0

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1. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 2. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 3. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 4. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 5. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 6. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 7. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 8. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 9. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*
 10. *Handwritten notes and labels on the graph, including 'T. GEHT. TONNE KRAFT. MEASUREMENT' and 'T. GEHT. TONNE KRAFT. MEASUREMENT'.*

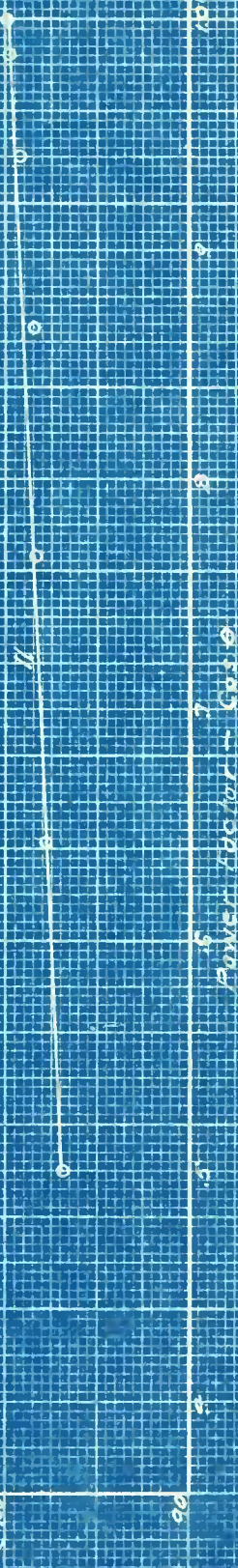
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Forward Meter No. 22899A

Curves showing percent true watts recorded with varying amount load on motor ratings, normal efficiency and large load.

- I. Run No. 5 Experimented
- II - No. 7 - Calculated



Power Factor - Cos ϕ

Per Cent True Watts Recorded

0.01
0.01

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Sangamo Meter # 66151.

Resistance of pressure coil 204.5 ohms.
 " " series "0275 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 110 Amperes 15.15 Apparent Watts 1665.

Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .	
Forward	-9	17	.0102	
"	-11	20.3	.0122	
"	-9	17	.0102	
Backward	37.5	67	.0415	
"	38.5	68.5	.0412	
"	37.5	67	.0402	
Average cos θ for forward rotation0109	
"	θ	"	" 90° 37'
"	cos θ	" backward	"0410
"	θ	"	" 87° 37'
Phase angle from quadrature for forward rotation			37'	
"	"	" backward	"	2° 23'
Average phase angle from quadrature			53'	
Phase difference between series and pressure fluxes			53'	

Sangamo Meter # 66151.

Run # 1.

Data showing the effect of change of load with normal voltage, unity power factor, and normal frequency.

	110 volts.	60 cycles.		Temperature 75 F	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.6	175	8	115	167	95.5
3.5	383	18	111.8	387	101.
5.0	553	26	111.8	558	101.
7.8	865	40	110	873	101.
10.4	1147	53	111	1146	99.5
12.8	1410	64	111.4	1380	98.
15.2	1680	75	111	1620	96.4

R is the no. of revolutions made by the disc in T seconds.

Diagram Letter 1 08151.

Run 1.

Data showing the effect of change of load with normal voltage, unity power factor, and normal frequency.

Temperature 75 F	60 cycles.	110 volts.	Current	True Watts	R	T	Watts Recorded	% Recorded.
92.5	115	8	175	175	115	115	167	92.5
101.	111.8	18	333	333	111.8	111.8	387	101.
101.	111.8	26	553	553	111.8	111.8	558	101.
101.	110	40	835	835	110	110	873	101.
99.5	111	52	1147	1147	111	111	1145	99.5
98.	111.4	64	1410	1410	111.4	111.4	1380	98.
98.4	111	75	1680	1680	111	111	1630	98.4

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 66151.

Run # 2

Data showing the effect of change of load with unity power factor, normal frequency, and 109 % voltage.

120 volts		<u>60</u> cycles		Temperature 75 F	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.35	155	7	114.3	147	94.8
3.4	378	18	113.2	381	100.8
4.9	588	28	113.5	593	100.8
7.55	910	43	111.6	925	101.6
10.00	1210	55	110.2	1200	99.4
13.20	1590	70	109.8	1530	96.2
15.20	1840	79	110.4	1720	93.4

R is the no. of revolutions made by the disc in T seconds.

Wattmeter Meter No. 65151.

Run No. 2

Data showing the effect of change of load with unity power factor, normal frequency, and 10% voltage.

Temperature 75 F	60 cycles	120 volts	Current	Time Watts	R	T	Watts Recorded	Watts Recorded.
84.8	114.3	7	155				147	84.8
100.8	113.2	18	378				381	100.8
100.8	112.5	28	588				593	100.8
101.6	111.6	43	910				925	101.6
99.4	110.2	55	1210				1200	99.4
99.2	109.8	70	1590				1550	99.2
99.4	110.4	79	1840				1780	99.4

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 66151.

Run # 3

Data showing the effect of change of load with unity power factor, normal frequency, and 91 % normal voltage.

100 volts.		60 cycles.		Temperature 75 F	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.45	150	6	103	140	96.5
3.35	335	16	114.8	335	100.0
5.50	560	27	113.3	572	102.0
7.75	780	37	112.5	790	101.3
9.90	998	47	111.5	1012	101.3
12.50	1255	57	110.0	1245	99.3
14.50	1470	66	110.0	1440	98.0

R is the no. of revolutions made the disc in T seconds.

Sangamo Meter # 66151.

Run # 4.

Data showing the effect of change of power factor with constant full load, normal voltage and 60 cycles.

110 volts.

10.1 amperes

Temperature 80 F.

Cos.θ	True Watts	R	T	Watts Recorded	% Recorded
1.000	1147	53	111	1146	99.5
.92	1020	27	63	1029	101.0
.863	958	25	62	970	101.0
.855	950	25	64	938	99.0
.783	870	22	61	866	99.7
.703	780	24	74	778	99.7
.653	725	19	63.5	718	99.6
.594	660	18	66	655	99.3
.514	588	15	62	581	98.8

R is the no. of revolutions made by the disc in T seconds.

Watts Motor # 66151.

Run # 4.

Data showing the effect of change of power factor with constant full load, normal voltage and 60 cycles.

Temperature 60 F.	10.1 amperes	110 volts.	Watts	Time	Watts	Recorded
99.5	111	1147	1146	1.000	1147	1146
101.0	83	1020	1029	.92	1020	1029
101.0	82	958	970	.862	958	970
99.0	64	920	938	.855	920	938
99.7	61	870	906	.782	870	906
99.7	47	780	778	.702	780	778
99.6	35.5	725	718	.652	725	718
99.5	66	660	655	.594	660	655
98.8	62	582	581	.514	582	581

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 66151.

5.

Data, calculated from the flux phase determination, showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

Volts 110

Amperes 10

Cycles 60.

Cos θ	Watts Recorded.	True Watts.	% Recorded.
1.000	1100	1100	100
.984	1080	1083	99.7
.940	1028	1033	99.4
.866	944	954	99.0
.766	832	843	98.7
.643	695	707	98.3
.500	535	550	97.3

Standard Meter # 66151.

15.

Data, calculated from the flux phase determination, showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

Volts 110 Amperes 10 Cycles 60.

Cos θ	Watts Recorded.	True Watts.	Watts Recorded.
1.000	1100	1100	100
.984	1080	1088	99.7
.940	1038	1032	99.4
.888	944	954	99.0
.788	882	843	98.7
.643	692	707	98.3
.500	552	550	97.3

Sangamo Meter # 66151.

Run # 6.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

110 volts.		120 cycles.		Temperature 70 F.	
Current	True Watts	R.	T.	Watts Recorded.	% Recorded.
1.20	132	5	106	113	85.7
2.55	280	12	113	255	91.0
3.85	425	19	112	408	96.0
5.10	560	30	126	572	102.0
7.20	845	39	111	844	99.9
12.20	1345	57	105	1305	97.0
15.00	1640	68	104.2	1565	95.4

R is the no. of revolutions made by the disc in T seconds.

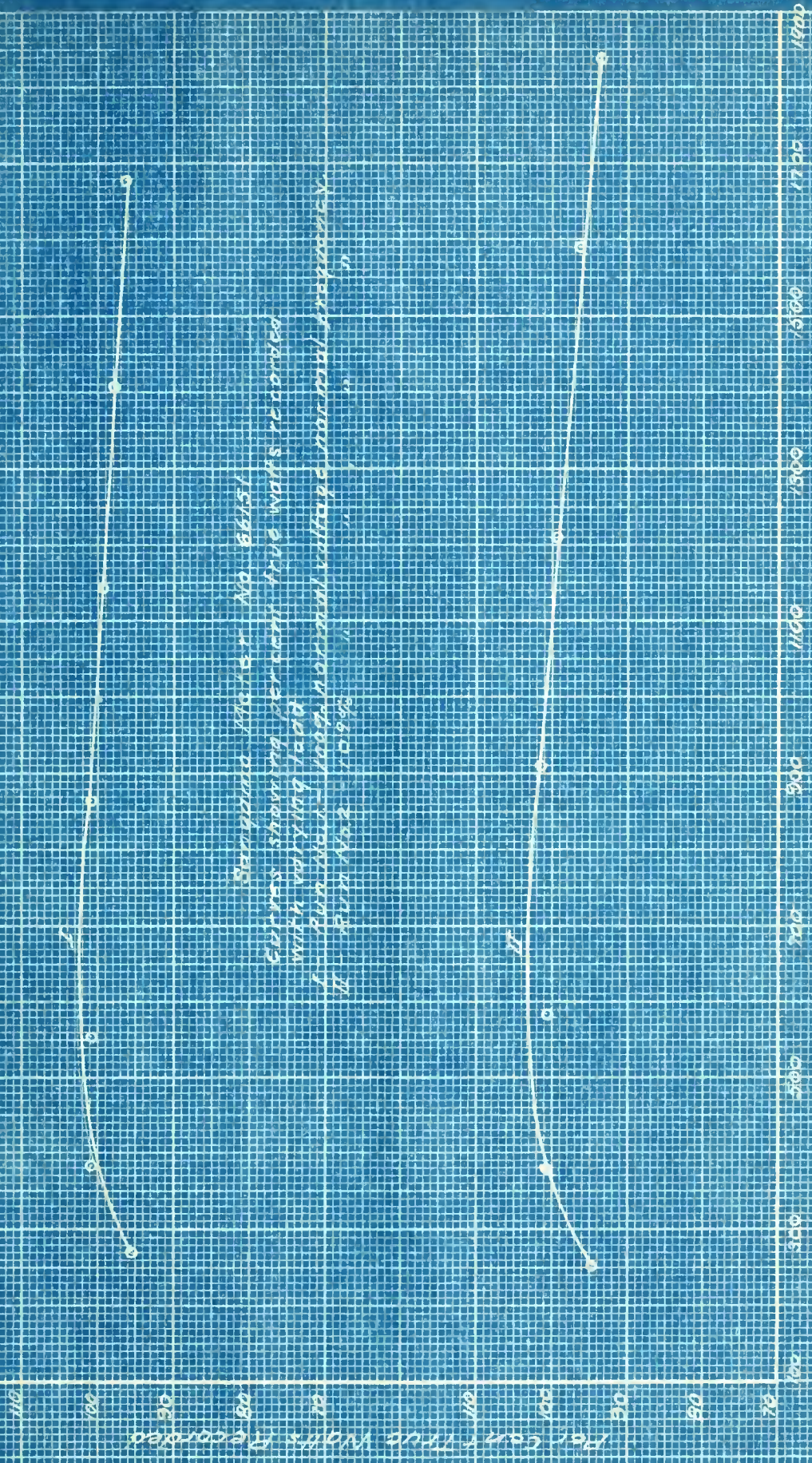
Sanjano Meter, 66151.

Run, 6.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

110 volts.	120 cycles.	Temperature W. R.
Current	Time Watts	Watts
	R.	Recorded.
1.20	132	118
2.25	280	252
3.85	425	408
5.10	560	572
7.20	845	844
12.20	1345	1302
15.00	1640	1522

R is the no. of revolutions made by the disc in T seconds.



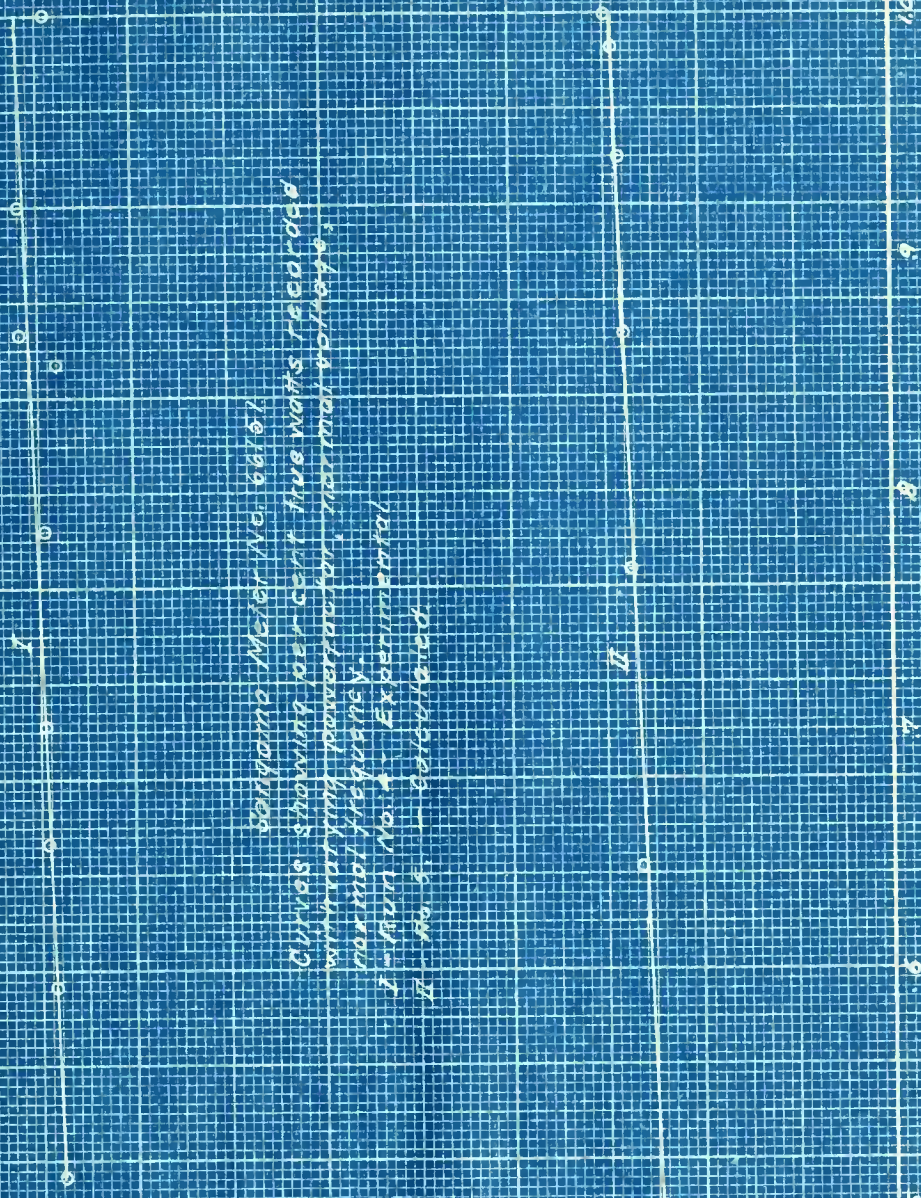
Each box showing my selected true widths recorded with varying lead
 1. 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000
 2. 2000 2000 2000 2000 2000 2000 2000 2000 2000 2000

True Widths

Per cent True Widths Recorded

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Per cent True Waits Recorded



Sanjama Meter No. 66101

Curves showing per cent true waits recorded with varying power factor, normal voltage.

Normal frequency

I - Run No. 4 - Experimental

II - No. 5 - Calculated

Power Factor - 5000

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160

180

200

250

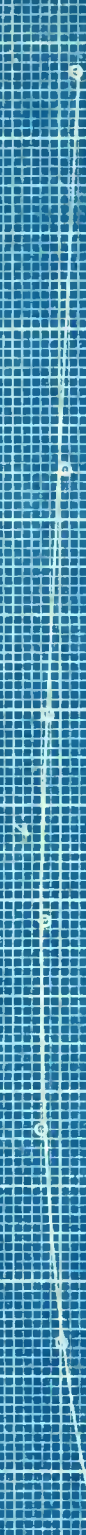
100

120

140

160

Per cent Total Water Absorbed



Sample No. 1
 curves showing the water absorbed
 with varying load

1 - Run No. 1 - at normal voltage, normal frequency
 2 - Run No. 2 - at normal voltage, normal frequency

17



200

300

400

500

600

700

800

900

Time (min)

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Sangamo Meter # 76671.

Resistance of pressure coil 317. ohms.
 " " series "04 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 110	Amperes 5	Apparent Watts 550.	
Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .
Forward	14	26	.0473
"	14	26	.0473
"	14	26	.0473
Backward	1	2.8	.0051
"	1	2.8	.0051
"	2	5.0	.0091
Average cos θ for forward rotation0473
" θ	" "	" 87° 17'
" cos θ	" backward	"0064
" θ	" "	" 89° 38'
Phase angle from quadrature for forward rotation			2° 43'
" " "	" "	" backward "	22'
Average phase angle from quadrature			1° 33'
Phase difference between series and pressure fluxes			1° 33'

Sangamo Meter # 76671.

Run # 1.

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and normal voltage.

110 volts.

60 cycles.

Temperature 76 F.

Current.	True Watts.	R	T	Watts Recorded.	% Recorded.
1.1	120	5	82.5	109	91.8
1.78	195	11	105.3	188	96.4
2.50	275	16	105.3	274	99.7
3.00	330	19	102.8	333	100.8
3.85	422	28	118.0	427.5	101.0
4.80	528	30	100.4	538	101.7
5.65	622	37	106.3	625	100.5
7.40	812	47	104.3	810	99.8

R is the no. of revolutions made by the disc in T seconds.

Sargent & Lundy Meter # 76671.

Run # 1.

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and normal voltage.

Temperature in °F.	60 cycles.	110 volts.	Current.	True Watts.	Watts Recorded.	% Recorded.
91.8	82.5	120	1.1	120	109	91.8
92.4	105.3	125	1.78	125	188	92.4
92.7	105.3	2.75	2.50	2.75	274	92.7
100.8	102.8	320	3.00	320	332	100.8
101.0	118.0	425	3.85	425	427.5	101.0
101.7	100.4	528	4.80	528	528	101.7
100.5	106.3	622	5.65	622	625	100.5
99.8	104.3	812	7.40	812	810	99.8

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 76671.

Run # 2

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal frequency, and 91% of normal voltage.

100 volts.		60 cycles.		Temperature 76 F	
Current.	True Watts	R	T	Watts Recorded	% Recorded.
1.1	115	6	105.5	102.5	89.0
2.25	225	13	111.	211	93.6
3.15	317	19	108.	316	99.7
4.15	415	25	108.	416	100.2
5.18	518	31	106.2	525	101.2
6.25	626	36	103.5	626	100.0
7.50	752	45	107.6	752	100.0

R is the no. of revolutions made by the disc in T seconds.

Sanborn Meter # 70671.

Run 2

Data showing the relation between the load and the
of true watts recorded with unity power factor, normal
frequency, and 91% of normal voltage.

Temperature $^{\circ}$ F	60 cycles	100 volts	Current	True Watts	Watts Recorded
89.0	102.5	6	1.1	115	102.5
92.6	111	13	2.25	235	111
99.7	108	19	3.15	314	108
100.2	108	27	4.15	415	108
101.2	106.5	31	5.18	518	106.5
100.0	103.5	38	6.25	625	103.5
100.0	107.5	47	7.50	752	107.5

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 76671.

Run # 3.

Data showing the relation between the load and the % of true watts recorded, unity power factor, normal frequency, and 109 % normal voltage.

120 volts.		60 cycles.		Temperature 76 F.	
Current.	True Watts	R	T	Watts Recorded	% Recorded.
1.12	135	7	102.5	125	91
2.05	247	14	107.2	235	95.2
2.85	340	20	106.2	338	99.5
3.65	433	26	107.5	435	100.5
4.52	544	32	105.2	547	100.7
5.50	660	38	104.0	658	99.75
6.40	770	45	106.0	765	99.4
7.40	888	51	105.0	875	98.5

R is the no. of revolutions made by the disc in T seconds.

Wattmeter # 76671.

Run # 3.

Data showing the relation between the load and the % of true watts recorded, unity power factor, normal frequency, and 100% normal voltage.

Temperature 70 F.	60 cycles.	120 volts.	Current.	True watts	Watts Recorded	Watts Recorded.
	7	135	1.12	135	135	91
	14	247	2.02	247	235	92.2
	20	340	2.32	340	332	97.5
	26	433	3.65	433	435	100.5
	32	544	4.52	544	547	100.7
	38	660	5.50	660	658	99.75
	45	770	6.40	770	765	99.4
	51	888	7.40	888	875	98.5

T is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 76671.

Run # 4.

Data showing the effect of change of power factor with constant full load current, normal voltage, and normal frequency.

110 volts. 60 cycles. 5 amperes. Temperature 76 F.

Cos.θ.	True Watts.	R.	T.	Watts Recorded.	% Recorded.
1.000	550	32	103.	560	101.5
.928	510	30	104.2	518	101.5
.850	468	28	105.5	478	102.2
.763	420	27	111.5	436	103.7
.695	382	25	114.	395	103.4
.570	313	23	128.	324	103.4

R is the no. of revolutions made by the disc in T seconds.

Sanborn Meter # 78671.

Run 4.

Not showing the effect of change of power factor with constant full load current, normal voltage, and normal frequency.

110 volts. 60 cycles. 5 amperes. Temperature 78 F.

Co.e.	Time	R.	T.	Watts	No. Recorded.
1.000	250	22	100.	260	101.3
.938	210	20	104.2	218	101.5
.850	488	28	102.5	478	102.2
.762	420	27	111.5	432	102.7
.692	332	25	114.	322	102.3
.570	212	23	122.	224	102.4

R is the no. of revolutions made by the disc in T seconds.

Sangamo Meter # 76671.

5.

Data, calculated from the flux phase determination, showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

Volts 110

Amperes 5.

Cycles 60.

Cos θ	True Watts	Watts Recorded	% Recorded.
1.0000	550	550	100.0
.9848	542	544	100.5
.9400	517	522	100.8
.8660	477	483	101.2
.7660	422	431	102.0
.6430	354	364.5	103.0
.5000	275	287.5	104.5

Sangamo Meter No. 75571.

5.

Data, calculated from the flux phase determination, showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

Volts 110	Amperes 5.	Cycles 30.
1.0000	250	100.0
.9848	244	100.5
.9700	238	100.8
.9550	232	101.2
.9400	226	101.5
.9250	220	102.0
.9100	214	102.5
.8950	208	103.0
.8800	202	104.5

Sangamo Meter # 76671.

Run # 6

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

110 volts.		25 cycles.		Temperature 70 F.	
Current.	True Watts.	R.	T.	Watts Recorded.	% Recorded.
1.16	128	7	110.2	114	89.2
1.55	170	10	114.0	158	93.0
2.50	275	17	113.0	271	98.5
3.50	383	26	122.0	384	100.2
4.50	495	32	116.0	497	100.3
5.80	640	41	114.5	645	100.6
7.30	805	53	119.5	800	99.4

R is the no. of revolutions made by the disc in T seconds.

Barham Meter # 76671.

Run # 6

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

Temperature 70 F.	55 cycles.	110 volts.	Current.	Time Watts.	Watts Recorded.
92.8	114.2	128	1.16	138	114
91.0	114.0	130	1.25	140	128
90.8	113.0	132	2.25	145	131
100.3	122.0	135	2.50	150	134
100.2	116.0	138	4.50	155	137
100.0	114.5	141	5.80	160	142
99.1	112.5	145	7.30	165	140

is the no. of revolutions made by the disc in 2 seconds.

Sangamo Meter # 76671.

Run # 7.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

110 volts.		120 cycles.		Temperature 70 F.	
Current	True Watts	R.	T.	Watts Recorded.	% Recorded.
1.10	120	6	100.5	107.5	89.7
1.55	170	10	114	158	93.0
2.50	277	16	106	272	98.3
3.40	375	22	106	374	99.8
4.45	490	24	87	495	101.0
4.95	545	36	119	545	100.0
7.25	795	40	91	792	99.6

R is the no. of revolutions made by the disc in T seconds.

Standard Motor Co. 75271.

Run 1 V.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

Temperature V. F.	110 volts.	120 cycles.	Temperature V. F.
Recorded.	Time	Watts	Recorded.
33.7	120	100.5	107.5
34.0	170	114	158
38.3	277	106	272
39.8	375	106	374
101.0	490	87	495
100.0	545	119	545
99.5	795	91	795

R is the no. of revolutions made by the disc in 1 second.

110

100

90

80

70

110

100

90

80

PER CENT CRACK WIDTH IN INCH



Test No. 100

can also be used to find
 curves showing percent of the total strain
 with any load. The load is the horizontal frequency
 of the curve.

110

100

90

80

110

100

90

80

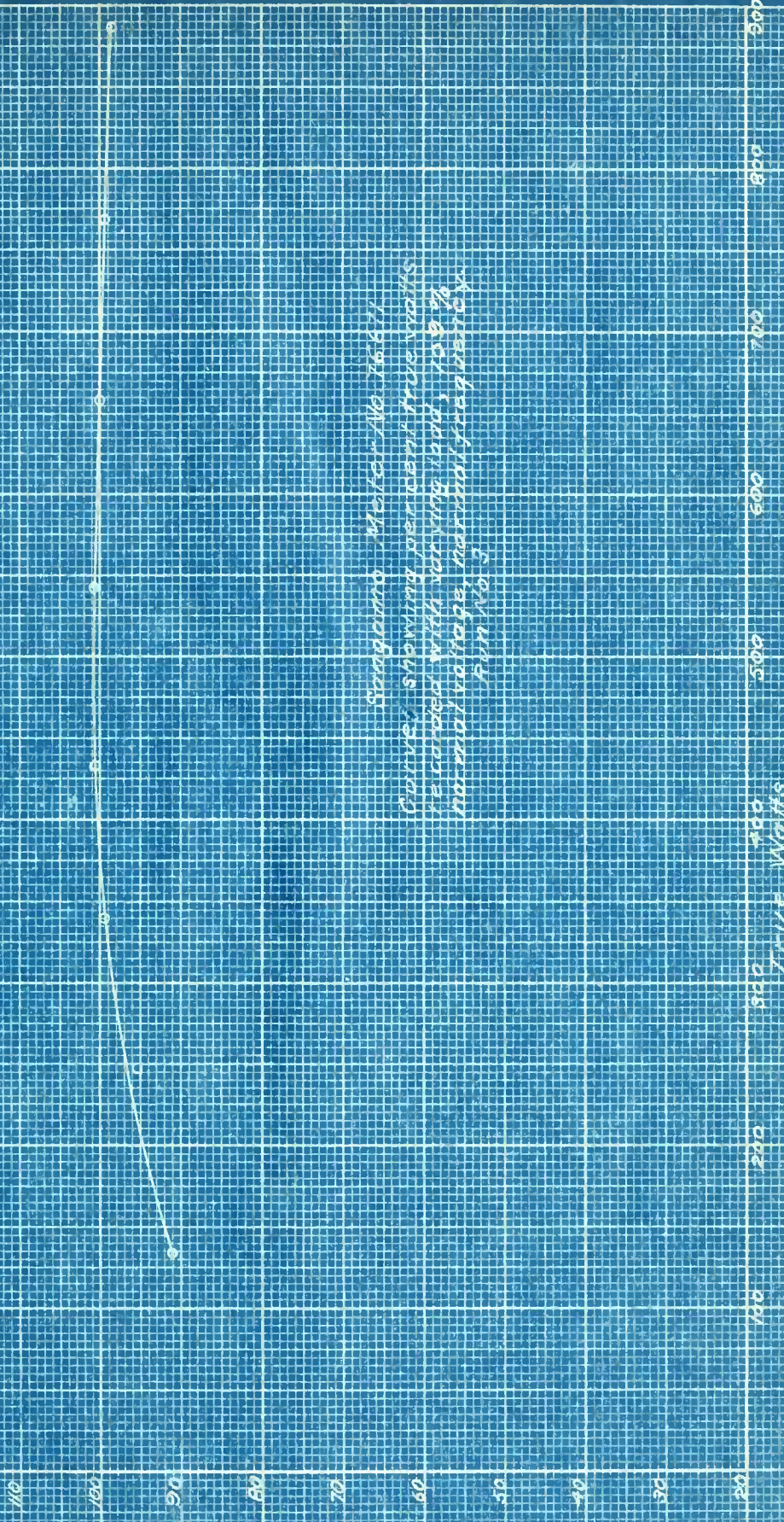
PER CENT CRACK WIDTH IN INCH



Test No. 101

can also be used to find
 curves showing percent of the total strain
 with any load. The load is the horizontal frequency
 of the curve.

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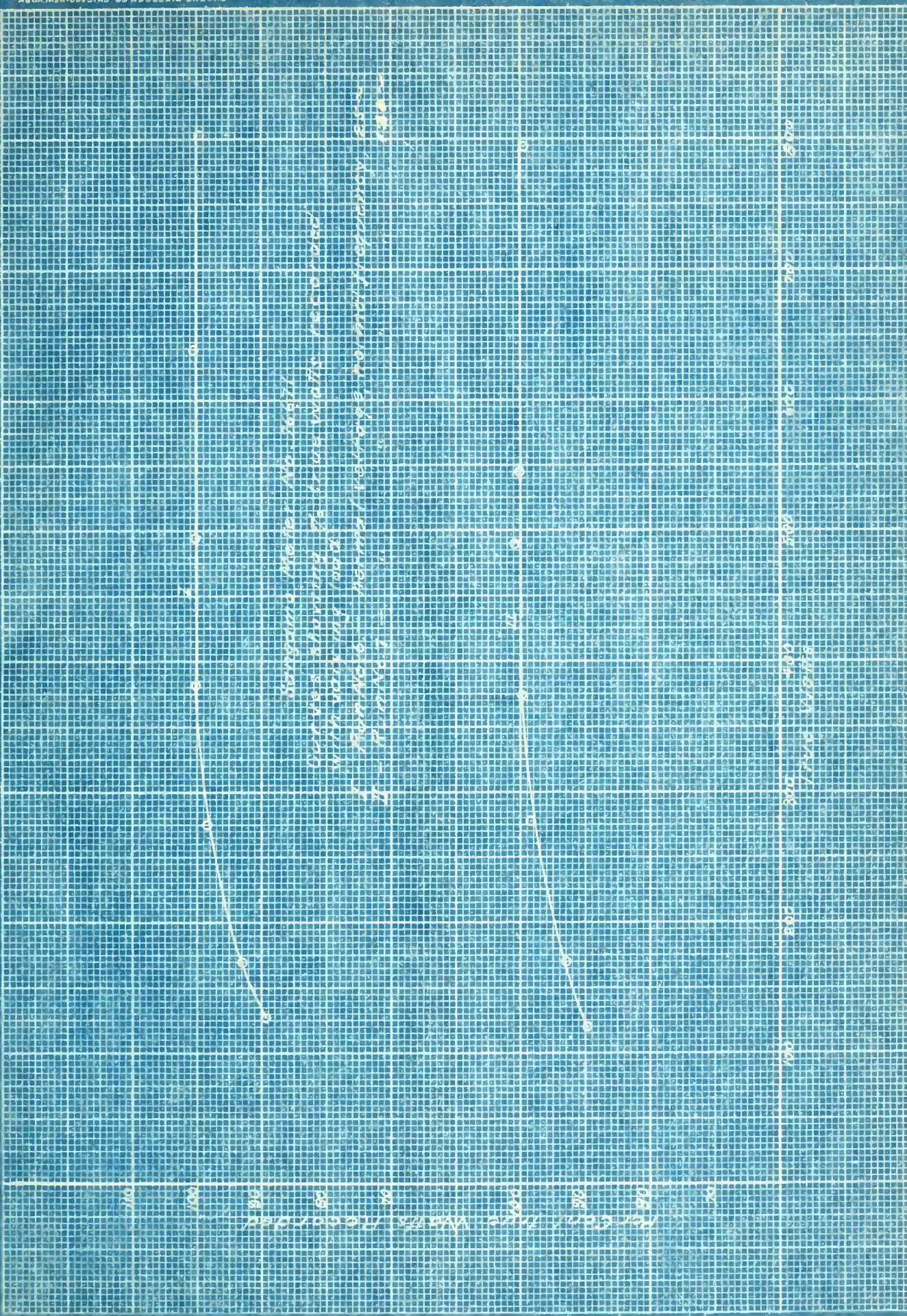


Complains Market No. 76-47
 Curve showing percent true wavels
 compared with set line 100, 200, 300
 Normal to have normal frequency
 Run No. 3

True Wavels

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General Electric Meter # 1506564.

Resistance of 60 cycle pressure coil 679.5 ohms.
 " " 25 " " " 132.5 " .
 " " 10 ampere series coil027 ohms.

Data for the determination of the phase relation of the series and pressure fluxes.

Volts 110. Amperes 10. Apparent Watts 1100.

Direction of Rotation of Disc.	Dynamometer Reading.	True Watts.	Cos θ .
Forward	-19	34	.0309
Backward	+2	4.5	.0041
Forward	-21	38	.0345
Backward	+2	4.5	.0041
Forward	-18.5	33	.0300
Backward	+2	4.5	.0041
Average cos θ for forward rotation0318
" θ " " "		88° 10'
" cos θ " backward "0041
" θ " " "		90° 13'
Phase angle from quadrature for forward rotation			13'
" " " " " backward "		1° 50'
Average phase angle from quadrature			48.5'
Phase difference between series and pressure fluxes			90° 48.5'

General Electric Meter # 1506564.

Run # 1.

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and normal frequency.

110 volts.

60 cycles.

Temperature 73 F.

Watts	Watt hours Recorded.	T	True Watt hours	% Recorded
120	3	106.5	3.54	85.
325	10	116.0	10.46	95.8
545	20	134.5	20.35	98.4
825	27	119.0	27.25	99.0
1050	35	120.0	35.00	100.0
1279	45	127.0	45.00	100.0
1440	45	114.0	45.70	98.7

T is the time in seconds.

General Electric Meter # 150254.

Run # 1.

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and normal frequency.

110 volts.	60 cycles.	Temperature 73 F.
Watt hours Recorded.	T	% Recorded
120	106.5	85.
325	116.0	95.8
545	134.5	98.4
825	119.0	99.0
1050	120.0	100.0
1275	127.0	100.0
1440	114.0	98.7

T is the time in seconds.

General Electric Meter # 1506564.

Run # 2.

Data showing the effect of change of load with unity power factor, normal frequency, and 109 % normal voltage.

120 volts.

60 cycles.

Temperature 73 F.

Watts	Watt hours Recorded.	T	True Watt hours	% Recorded.
145	4	116	4.67	85.7
333	11	123	11.40	97.0
602	19	113	18.90	100.5
885	28	114	27.7	100.2
1203	38	113.7	38.00	100.0
1523	47	112.5	47.60	99.0
1800	54	111.4	55.70	99.0

T is the duration of each run in seconds.

General Electric Meter # 150554.

Run 1.2.

Data showing the effect of change of load with unity power factor, normal frequency, and 100% normal voltage.

Watts	Watt hours Recorded.	T	True Watt hours	% Recorded.
145	4	116	4.67	85.7
333	11	123	11.40	97.0
602	19	113	18.90	100.5
885	28	114	27.7	100.2
1203	38	113.7	38.00	100.0
1523	47	112.5	47.60	99.0
1800	54	111.4	52.70	99.0

T is the duration of each run in seconds.

General Electric Meter # 1506564.

Run # 3.

Data showing the relation between the load and the % of true watt hours recorded with varying load ,normal frequency, unity power factor, and 91 % normal voltage.

100 volts.		60 cycles.		Temperature 73 F.
Watts	Watt hours Recorded	T	True Watt hours.	% Recorded.
105	3	126.5	3.69	81.4
350	10	116.0	11.3	88.5
490	16	119.0	16.2	98.8
773	26	121.0	26.0	100.0
990	32	114.3	31.4	101.8
1145	36	113.3	36.0	100.0
1370	42	111.7	42.2	99.8
1560	50	116.0	50.4	99.3

T is the time in seconds.

General Electric Meter 1503544.

Run 3.

Data showing the relation between the load and the time watt hours recorded with varying load, normal frequency, unity power factor, and 91% normal voltage.

Watts Recorded.	Time Watt hours.	W	Watt hours Recorded	100 volts.	60 cycles.	Temperature 75 F.
105	3.69	128.5	3	100	60	75
250	11.3	116.0	10	100	60	75
450	15.2	119.0	15	100	60	75
775	26.0	121.0	25	100	60	75
990	31.4	114.3	32	100	60	75
1145	36.0	113.3	35	100	60	75
1270	42.8	111.7	42	100	60	75
1560	50.4	116.0	50	100	60	75

T is the time in seconds.

General Electric Meter # 1506564.

Run # 4.

Data showing the relation between the load and the % of true watts recorded with normal frequency, unity power factor, and 100 % normal voltage.

110 volts.

25 cycles

Temperature 73 F.

Watts	Watt hours Recorded.	T	True Watt hours	% Recorded.
120	3	104.0	3.46	86.8
335	9	101.0	9.4	95.8
545	19	128.0	19.4	98.0
833	25	109.0	25.2	99.3
1050	30	104.0	30.4	98.8
1283	43	122.0	43.5	98.8
1460	47	117.5	47.8	98.4
1675	47	104.0	48.4	97.2

T is the time in seconds.

General Electric Meter 150564.

Run 4.

data showing the relation between the load and the
of true watts recorded with normal frequency, unity power
factor, and 100 % normal voltage.

Watts Recorded.	Watt hours Recorded.	T	True Watt hours	Temperature 73 F.
120	3	104.0	3.46	86.8
225	9	101.0	9.4	87.8
245	12	128.0	12.4	88.0
333	25	122.0	25.2	89.5
1050	30	104.0	30.4	92.8
1285	43	122.0	43.5	93.8
1460	47	117.5	47.8	98.4
1575	47	104.0	48.4	97.5

T is the time in seconds.

General Electric Meter # 1506564.

Run # 5

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts. 10 amperes. 60 cycles Temperature 75 F.

Cos θ	Watt hours Recorded.	T	True Watt hours	% Recorded.
1.000	35	114.5	35	100
.981	37	124	37.2	99.5
.855	35	136	35.5	98.6
.781	30	127	30.4	98.5
.691	25	120	25.4	98.4
.622	24	129.5	24.62	97.3
.536	20	129	21.1	95.0

T is the duration of each run in seconds.

General Electric Meter # 1506264

Run # 5

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

cos θ	Watt hours Recorded.	T	Watt hours Recorded.	Temperature 75 F.
1.000	35	114.5	35	100
.981	37	124	37.2	99.5
.855	35	131	35.5	98.6
.781	30	127	30.4	98.5
.691	25	120	25.4	98.4
.622	24	122.5	24.62	97.3
.552	20	122	21.1	95.0

T is the duration of each run in seconds.

General Electric Meter #1506564.

#6.

Data, calculated from the flux quadrature determination, showing the effect of change of power factor with constant full load current, normal frequency and normal voltage.

110 volts.

10 amperes.

60 cycles.

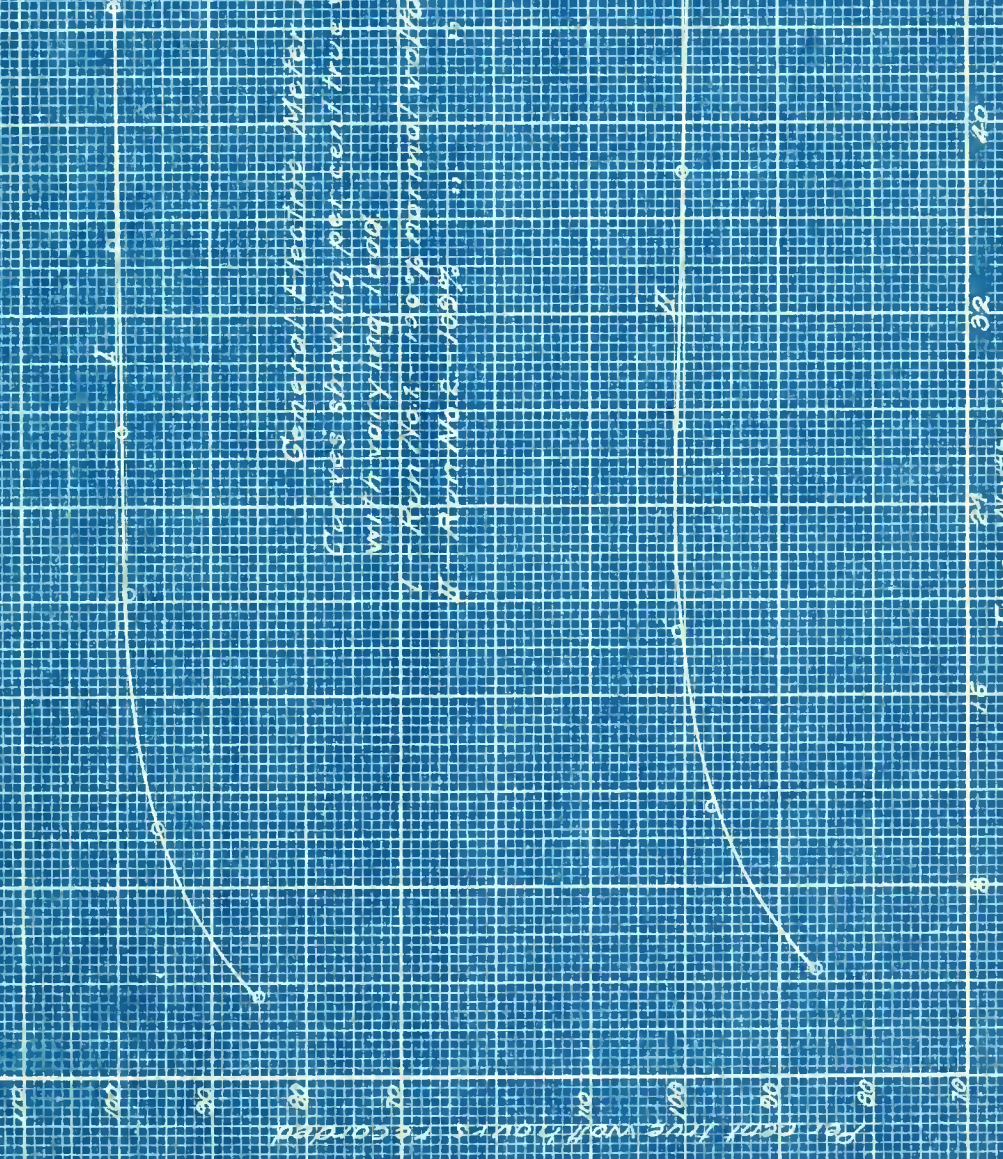
Cos θ .	True Watts.	Watts Recorded.	% Recorded.
1.0000	1100	1100	100.0
.9396	1032	1028	99.6
.8660	954	946	99.3
.7660	844	834	98.7
.6428	707	695	98.3
.5735	631	618	98.0
.5000	550	538	97.6

General Electric Meter 1150554.

16.

Data, calculated from the flux structure determination, showing the effect of change of power factor with constant full load current, normal frequency and normal voltage.

60 cycles.	10 amperes.	110 volts.	cos φ.
100.0	1100	1100	1.0000
99.8	1038	1032	.9998
99.3	946	954	.9980
98.7	834	844	.9960
98.3	692	707	.9938
98.0	618	631	.9925
97.8	528	550	.9900

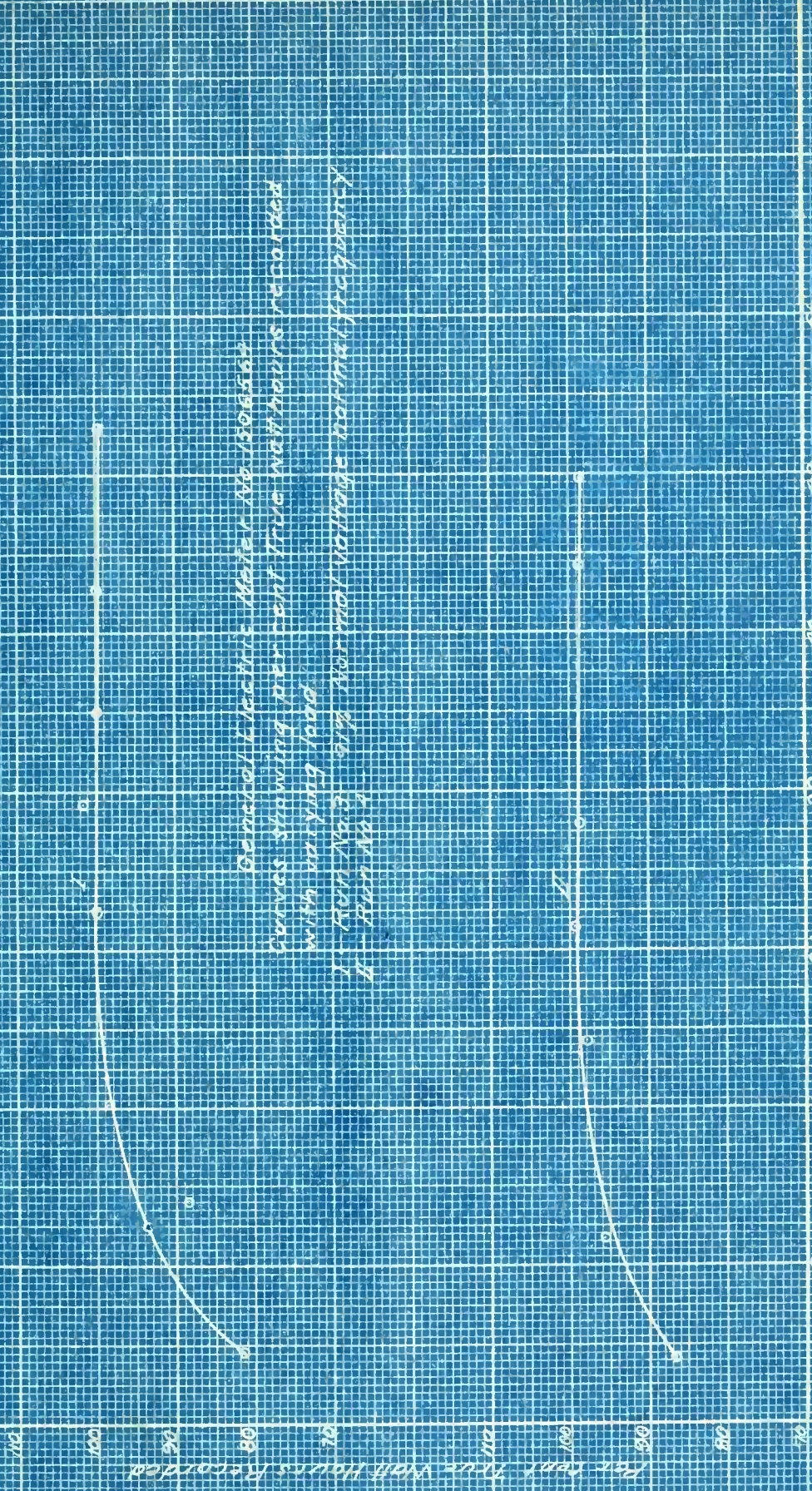


General Electric Meter No. 1006544
 Curves showing per cent true watt-hours recorded
 with varying load.
 I - Well No. 1, 130 sp normal voltage, normal frequency
 II - Run No. 2, 100% " " " "

True Watt-hours

Per cent True watt-hours recorded

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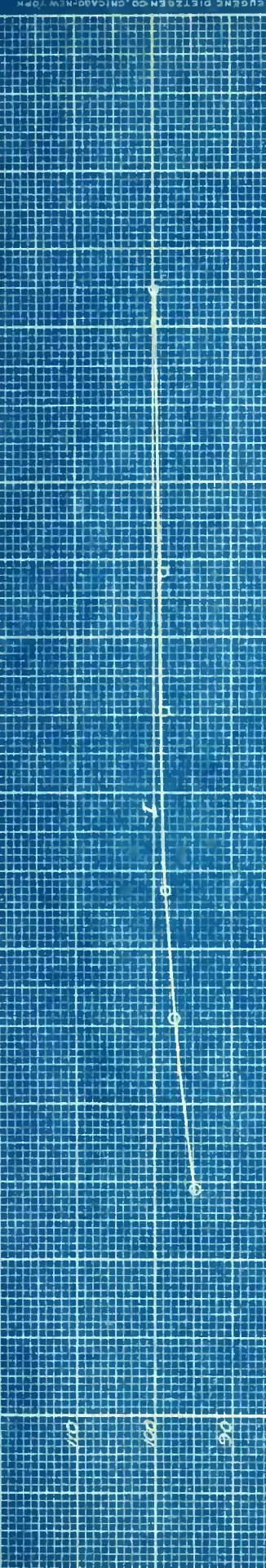


Geminali Machine Meter No. 1506562
 Canvas showing present true watt hours recorded
 with varying load

Run No. 3 and normal voltage normal frequency
 Run No. 1

True Watt Hours

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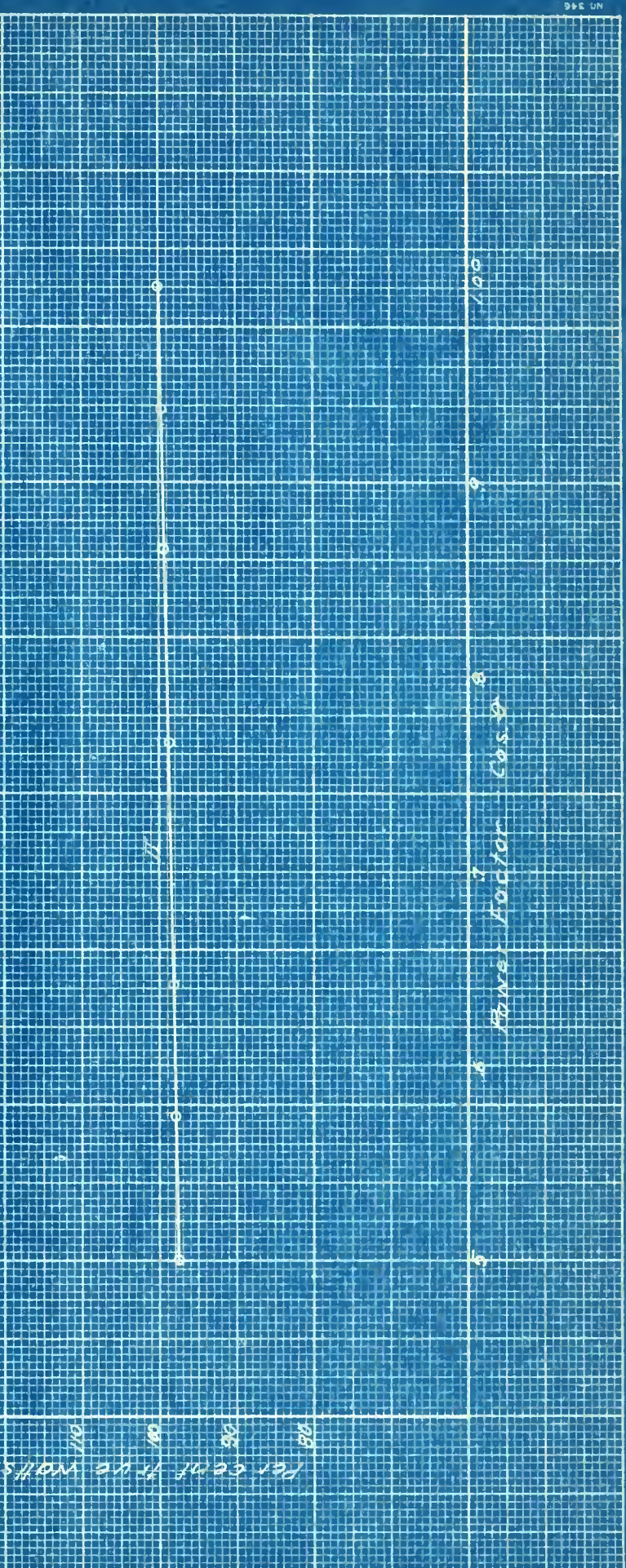


General Electric Meter No. 405554

Curves showing percent True Watts recorded with varying power factor, constant full load current, normal frequency, normal voltage.

f - Run No. 3 Experimental

H - No. 6 - Calculated



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Westinghouse Meter # 681372.

Resistance of pressure coil 427 ohms.
 " " series "0775 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 100	Amperes 5	Apparent Watts 500.		
Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .	
Forward	4	8	.016	
"	5	10	.020	
"	4.5	9	.018	
Backward	0	1	.0002	
"	0	1	.0002	
"	1	2.5	.0050	
Average cos θ for forward rotation018	
"	θ	"	" 88° 58'
"	cos θ	" backward	"0018
"	θ	"	" 89° 54'
Phase angle from quadrature for forward rotation			1° 2'	
"	"	" backward	"	6'
Average phase angle from quadrature			34'	
Phase angle between series and pressure fluxes ..			90° 34'	

Westinghouse Meter # 681372

Run # 1.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

100 volts.		60 cycles.		Temperature 82 F	
Current	True Watts	R	T	Watts Recorded	% Recorded
1.00	100	6	98.3	73.3	73.3
1.45	140	11	111.	119.	85.0
1.88	210	18	111.	195.	92.8
3.12	314	29	114.	306.	97.4
4.15	415	36	105.	412	99.4
5.00	480 ⁵⁰⁰	48	114	505	101.0
6.20	620	61	119	616	99.5
7.50	735	71	116	735	100.0

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 681373

Run # 1.

Data showing the effect of change of load with unity power factor, normal voltage, and normal frequency.

Temperature 82 F		60 cycles.		100 volts.	
Recorded	Watts Recorded	T	R	True Watts	Current
73.3	73.3	98.3	6	100	1.00
82.4	113.	111.	11	140	1.45
92.8	155.	111.	18	210	1.88
97.4	206.	114.	29	314	2.12
99.4	412	105.	36	415	4.15
101.0	505	114	43	480	5.00
99.5	616	113	61	620	6.20
100.0	712	112	71	725	7.20

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 681372

Run # 2

Data showing the effect of change of load with unity power factor, 110% voltage, and normal frequency.

110 volts		60 cycles		Temperature 82 F	
Current	True Watts	R	T	Watts Recorded	% Recorded
.90	100	7	99.2	77.8	77.8
1.20	130	10	115.3	114.5	88.0
2.25	240	22	113.2	233.0	94
3.05	335	30	109.6	328	97.7
4.05	444	40	109.3	440	99.2
5.00	550	53	115	554	100.5
6.40	700	67	115.3	697	99.5
7.40	800	79	116.7	814	100

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter 4 681373

Run 2

Data showing the effect of change of load with unity power factor, 110v voltage, and normal frequency.

Temperature 82 F		60 cycles		110 volts	
Watts Recorded	T	Time	Watts R	Current	
77.8	99.2	100	7	.90	
88.0	112.3	130	10	1.20	
94	118.2	240	22	2.25	
97.7	122.2	325	30	3.05	
99.2	128.2	444	40	4.05	
100.5	115	550	52	5.00	
99.2	115.3	700	67	6.40	
100	115.7	800	72	7.40	

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter #681372.

Run # 3

Data showing the effect of change of load with unity power factor, 90% normal voltage, and normal frequency.

90 volts		60 cycles		Temperature 82 F	
Current	True Watts	R	T	Watts Recorded	% Recorded
1.00	90	7	119	70.5	78.4
1.35	125	12	119	121.0	84.0
2.30	210	19	116	196	93.5
3.45	315	28	110.5	302	96.5
4.30	395	36	110.3	372	99.3
5.50	500	48	114	506	101.0
6.50	595	50	105.4	570	99.3
7.60	690	65	114	685	99.2

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 601373.

Run # 3

Data showing the effect of change of load with unity power factor, 90% normal voltage, and normal frequency.

90 volts	60 cycles	Temperature	Watts	Current	Time	Watts	Recorded
90	7	119	70.5	1.00	90	70.5	78.4
125	12	119	121.0	1.37	125	121.0	84.0
210	12	116	126	2.30	210	126	90.3
315	28	110.5	202	3.45	315	202	96.7
395	36	110.5	275	4.30	395	275	99.2
500	48	114	506	5.50	500	506	101.0
595	50	105.4	570	6.60	595	570	99.2
600	65	114	685	7.60	600	685	99.2

T is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 681372.

Run # 4

Data showing the effect of change of load with unity power factor, normal voltage, and 25 cycles.

100 volts		25 cycles.		Temperature 82 F.	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.10	115	7	86	97.7	85.
2.25	227	18	104.5	203.8	94.8
3.17	315	27	104.5	310.0	98.4
4.10	410	35	103.	407.0	99.2
5.20	520	44	101.5	520.0	100.0
6.40	646	55	102.5	645.0	100.0
7.60	760	70	110.5	760.0	100.0

R is the no. of revolutions made by the disc in T seconds.

Weatherhouse Meter # 681372.

Table 4

Data showing the effect of change of load with unity power factor, normal voltage, and 25 cycles.

Temperature 25 F.	25 cycles.	100 volts	Current	Time (secs)	Watts	Recorded
85.5	97.7	88	7	115	1.10	Recorded.
84.8	803.8	104.5	18	227	2.25	
83.4	310.0	104.5	27	315	3.17	
82.2	407.0	103.	35	410	4.10	
100.0	520.0	101.5	44	520	5.20	
100.0	645.0	102.5	55	645	6.40	
100.0	760.0	110.5	70	760	7.60	

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 681372.

Run # 5

Data showing the effect of change of power factor
with normal voltage, normal frequency, and 100 % load.

100 volts. 5 amperes. 60 cycles. Temperature 74 F

Cos θ	True Watts	R	T	Watts Recorded	% Recorded.
.94	470	46	116.2	475	101.
.84	420	38	108.0	422	100.3
.76	380	38	100.5	382	100.5
.67	335	30	109.0	330	98.5
.58	290	25	107.0	281.5	97.0

R is the no. of revolutions made by the disc in Tnseconds.

Westinghouse Meter No. 681372.

Run 5

Data showing the effect of change of power factor with normal voltage, normal frequency, and 100% load.

100 volts. 5 amperes. 60 cycles. Temperature 74° F

cos φ	True watts	R	T	watts Recorded	watts Recorded
.94	470	46	118.2	475	101.
.84	430	38	108.0	422	100.5
.76	380	32	100.5	382	100.5
.67	325	30	102.0	330	98.1
.58	290	25	107.0	281.5	97.0

R is the no. of revolutions made by the disc in T seconds.

Westinghouse Meter # 681372.

6

Data, calculated from the flux quadrature determination, showing the effect of change of power factor with constant full load, normal voltage, and normal frequency.

	100 volts.	5amperes.	60 cycles.	Temperature
Cos θ	True Watts	Watts Recorded	% Recorded	
1.0000	500	500	100.	
.9397	470	468	99.6	
.8660	433	431	99.4	
.7660	383	380	99.3	
.6428	322	318	99.0	
.5000	250	245.8	98.3	

Westinghouse Meter No. 681372.

7 6

Data calculated from the flux linkage determination, showing the effect of change of power factor with constant full load, normal voltage, and normal frequency.

100 volts.	Temperature.	60 cycles.	Temperature
1.0000	500	100.	% Recorded
.9997	498	99.5	
.9990	496	99.4	
.9983	494	99.3	
.9976	492	99.0	
.9969	490	98.5	

Westinghouse Meter # 681372.

Run # 7.

Data showing the relation between the load and the % of true watts recorded with unity power factor, normal voltage, and a frequency of 120 cycles.

110 volts.		120 cycles.		Temperature 70 F.	
Current	True Watts	R.	T.	Watts Recorded.	% Recorded.
1.15	125	10	105	114.2	91.5
2.14	235	20	108	220	94.5
3.45	380	28	89	378	99.4
5.00	550	36	120.6	558	101.4
6.50	715	57	95	720	102.0

R is the no. of revolutions made by the disc in T seconds.

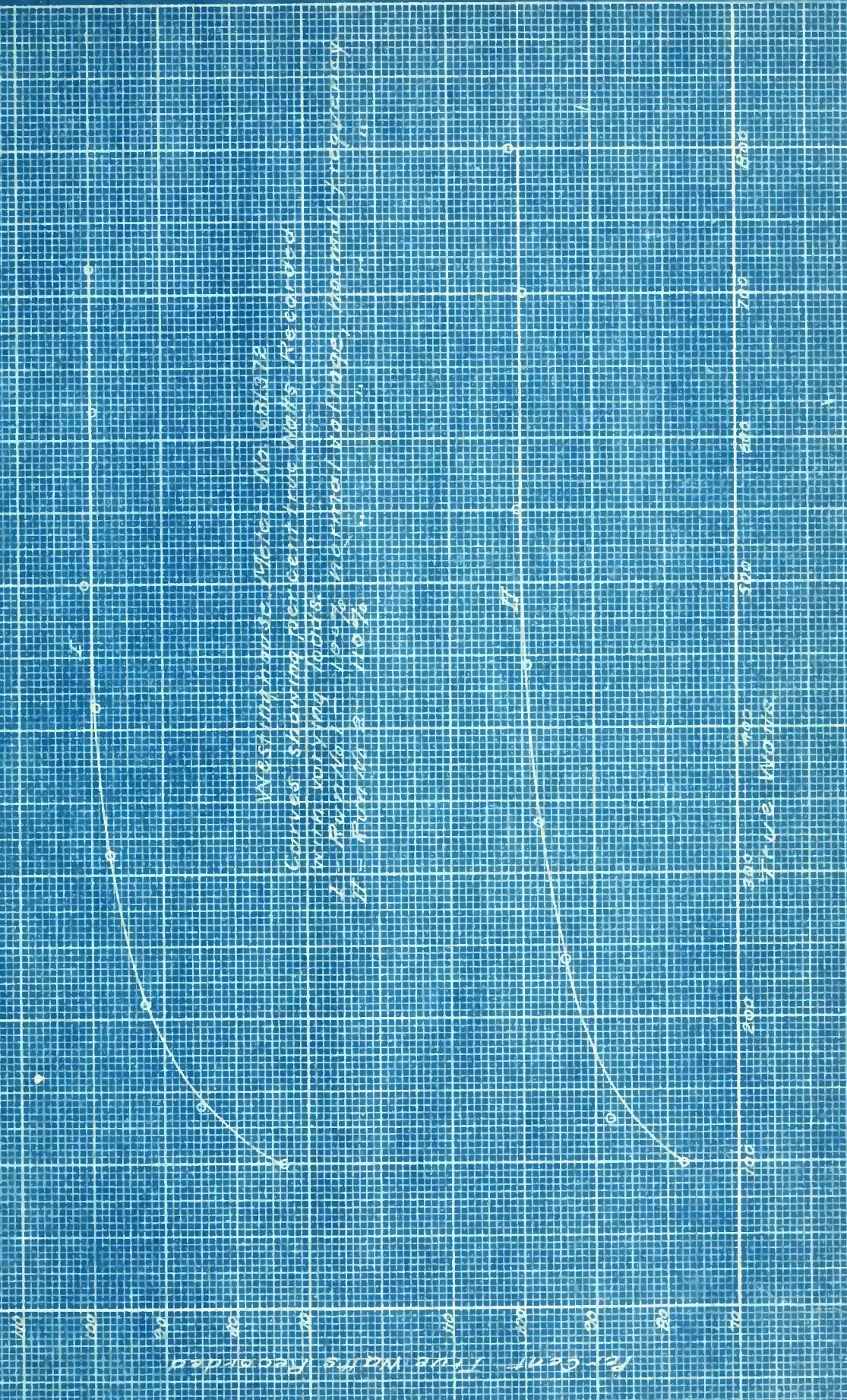
Wattmeter No. 681273.

Run # 7.

Data showing the relation between the load and the
of true watts recorded with unity power factor, normal
voltage, and a frequency of 150 cycles.

Temperature 70 F.	150 cycles.	110 volts.	Current	True Watts	Watts Recorded.	% Error
103.0	25	715	1.15	125	114.5	91.5
103.0	30	825	2.14	325	320	94.5
103.0	35	930	3.45	500	378	99.4
103.0	40	1050	5.00	650	550	101.4
103.0	45	1175	6.50	800	730	103.0

R is the no. of revolutions made by the disc in 1 second.



Weathering note: No marks
 Curves showing percent tide marks recorded
 with varying tides
 A - 100% tide marks
 B - 10% tide marks

Time in Minutes

Percent Tide Marks Recorded

Percent Tide Marks

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1/10

100

20

30

40

50

60

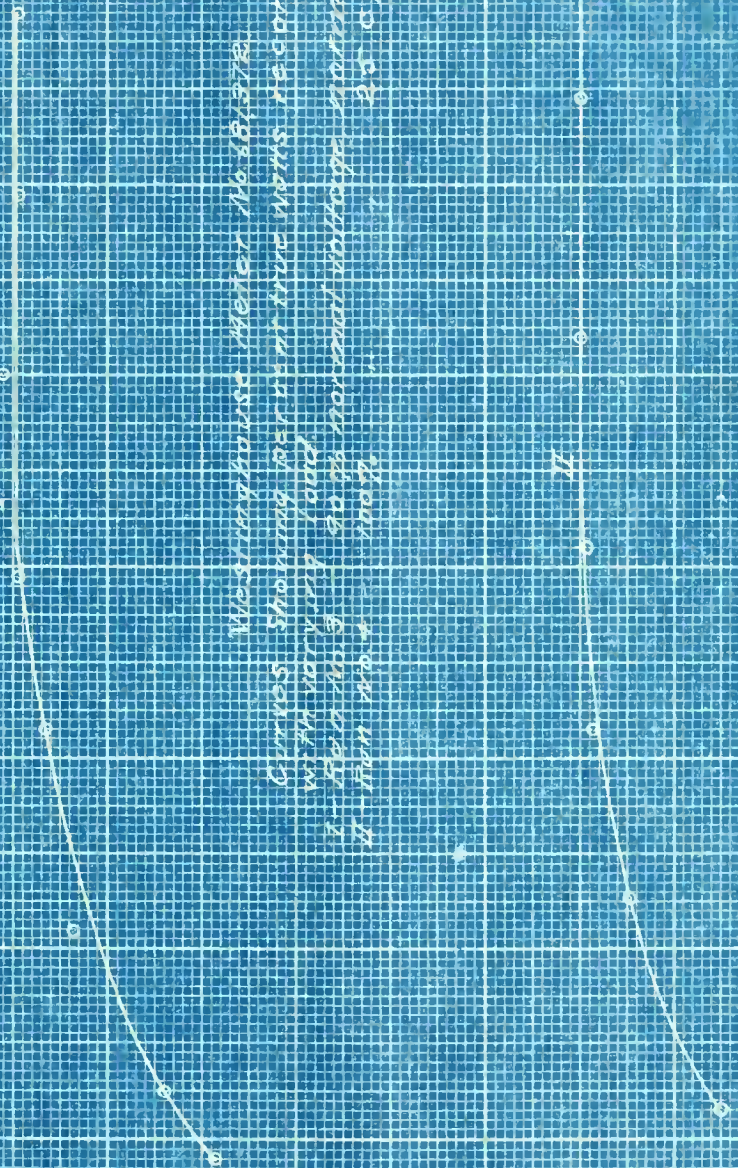
70

80

90

100

Temperature, degrees Celsius



Washington Meter No. 161578

Cross section of a pipe with a diameter of 1.5 inches.

Temperature of the pipe at the center is 100 degrees Celsius.

Temperature of the pipe at the surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature of the pipe at the outer surface is 10 degrees Celsius.

Temperature of the pipe at the inner surface is 10 degrees Celsius.

Temperature, degrees Celsius

100

20

30

40

50

60

70

80

90

100

Temperature, degrees Celsius

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Masterhouse Meter No. 64122

Curves starting at about 100% works recorded with varying power factor, normal voltage surges

- Power factor, normal
- Meter No. 5 - Experimental
- This has - cancelled



Per Cent True Works Recorded - Case 3

PER CENT TRUE WORKS RECORDED

0 50 100

0 50 100

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Percent Insect Work Recorded

140

120

98

80

100

95

90

85

80

75

70

65

60

55

50

45

40

35

30

25

20

15

10

5

0

100

200

300

400

500

600

700

800

2000 Yards

Washington Meter No. 66522

0.1% Insect Work Recorded with
no more than 1/2 hr. recording (1/2 hr. per
1000 Yards)

1000 Yards

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Duncan Meter # 61666.

Resistance of pressure coil 2780. ohms.
 " " series "0575 ohms.

Data for the determination of the phase relation of the series and pressure fluxes.

Volts 110	Amperes 10	Apparent Watts 1100.		
Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .	
Forward	-24	42	.0382	
"	-22	40	.0364	
"	-26	44	.0400	
Backward	+ 2	4	.00364	
"	+ 2	4	.00364	
"	+ 2	4	.00364	
Average cos θ for forward rotation0382	
"	θ	"	" 87° 49'
"	cos θ	" backward	"00364
"	θ	"	" 90° 13'
Phase angle from quadrature for forward rotation			2° 11'	
"	"	" backward	"	13'
Average phase angle from quadrature			59'	
Phase difference between series and pressure fluxes			59'.	

Duncan Meter # 61666.

Run # 1.

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and normal frequency.

110 volts.		60 cycles.		Temperature 84 F.	
Current	True Watts.	R	T	Watts Recorded	% Recorded.
1.05	115	6	121	89.5	88.0
3.50	385	24	124.5	345.	90.0
5.05	555	35	117.	505.	91.0
8.50	935	60	116.	932.	99.7
11.50	1262	84	120.	1260	99.9
13.25	1465	100	121.	1490	101.8
15.30	1690	115	120.5	1720	102.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter, 11666.

Jan 1.

Data showing the effect of change of load with unity power factor, 100% normal voltage, and normal frequency.

Current	Time Watts.	R	T	Watts Recorded	Temperature 84 F.
1.75	115	6	121	89.5	78.0
3.50	385	24	124.5	245.	80.0
5.05	555	32	117.	505.	81.0
8.50	935	60	115.	955.	82.7
11.50	1255	84	120.	1250	83.9
13.25	1465	100	121.	1490	101.8
15.50	1590	115	120.5	1720	102.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter #61666.

Run # 2.

Data showing the effect of change of load with unity power factor, 91 % normal voltage, and normal frequency.

100 volts.		60 cycles.		Temperature 84 F.	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.54	155	8	120	120	77.5
3.15	316	20	120	300	95.0
4.90	490	30	113	478	97.5
7.50	750	50	119	757	101.0
9.70	973	70	127	992	102.0
13.50	1345	93	122.5	1366	101.5
15.60	1565	108	122	1595	101.8

R is the no. of revolutions made by the disc in T seconds.

Wattmeter 61000.

Run 2.

Data showing the effect of change of load with unity power factor, 91 normal voltage, and normal frequency.

Temperature 84 F.	60 cycles.	100 volts.	Current	Time Watts	R	T	Watts Recorded	% Recorded.
			1.54	155	8	120	120	77.5
			3.15	318	20	120	300	95.0
			4.30	430	30	113	478	97.5
			7.50	750	50	110	757	101.0
			9.70	973	70	127	982	103.0
			13.50	1345	93	132.5	1366	101.5
			15.60	1565	108	133	1535	101.8

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 61666.

Run # 3.

Data showing the effect of change of load with unity power factor, 109 % normal voltage, and normal frequency.

120 volts.		60 cycles.		Temperature 84 F	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.20	145	7	110	115	79.0
3.20	385	23	115	360	93.6
5.00	600	36	112	578	96.3
7.60	910	57	113	910	100.0
9.40	1125	71	115	1111	99.0
11.30	1366	95	124.5	1372	100.4
13.60	1630	105	117	1615	99.2
15.50	1880	123	119	1860	99.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter 61666.

Run 3.

Data showing the effect of change of load with unity power factor, 109% normal voltage, and normal frequency.

Temperature 84 F	60 cycles.	120 volts.	Current	Time Watts	R	T	Watts Recorded	% Recorded.
			1.20	145	7	110	115	79.0
			2.30	385	22	115	360	92.6
			3.00	600	36	115	573	92.3
			4.60	910	57	113	910	100.0
			6.40	1125	71	115	1111	99.0
			11.30	1366	95	124.5	1372	100.4
			13.60	1620	106	117	1615	99.3
			15.50	1880	123	119	1860	99.3

R is the no. of revolutions made by the disc in 1 second.

Duncan Meter # 61666.

Run # 4

Data showing the effect of change of power factor with constant full load, 100 % normal voltage, and normal frequency.

110 volts. 10.1 amperes. 60 cycles Temperature 84 F

Cos.θ.	True Watts.	R	T	Watts Recorded	% Recorded.
.965	1065	38	65	1052	99.0
.914	1005	35	63	1000	99.0
.838	932	33	64	928	99.6
.770	854	30	64	845	99.0
.657	730	25	63.5	710	97.3
.517	574	21	69	548	96.5

R is the no. of revolutions made by the disc in T seconds.

Johnson Meter 6166.

Run 4

Plot showing the effect of change of power factor with constant full load, 100% normal voltage, and normal frequency.

110 volts. 10.1 amperes. 60 cycles Temperature 24

Power Factor	Watts Recorded	T	F	Time Watts	Cost
0.99	1082	62	38	1082	.265
0.99	1000	62	38	1000	.244
0.99	928	64	36	928	.238
0.99	848	64	36	848	.210
0.97	710	67.5	32	750	.237
0.95	548	69	31	574	.217

T is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 61666.

Run # 5

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and 25 cycles.

110 volts.

25 cycles.

Temperature 80 F.

Current.	True Watts.	R	T	Watts Recorded	% Recorded.
1.1	120	4	71	101.2	84.5
3.45	382	12	60	360.	94.3
5.20	570	19	61.6	556.	97.2
7.55	832	27	60	811.	97.7
10.22	1115	37	59.7	1115.	100.0
12.70	1400	47	60	1410.	100.7
14.95	1650	55	60.3	1640	99.5

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter, 6166.

Run # 2

Data showing the effect of change of load with unity

power factor, 100% normal voltage, and 25 cycles.

110 volts. 25 cycles. Temperature 80 F.

Current.	True Watts.	R	T	Watts Recorded	Watts Recorded
1.1	120	4	71	101.2	84.2
2.45	382	12	60	260.	94.2
5.20	570	19	61.6	556.	97.2
7.55	832	27	60	811.	97.7
10.22	1115	37	59.7	1112.	100.0
12.70	1400	47	60	1410.	100.7
14.95	1650	55	60.2	1640	99.5

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 61666.

Run # 6.

Data showing the effect of change of load with unity power factor, normal voltage, and 120 cycles.

110 volts.		120 cycles.		Temperature 77 F.	
Current	True Watts	R	T	Watts Recorded.	% Recorded.
1.1	120	6	114.5	94.5	78.6
2.1	228	12	108.	200.	87.8
3.75	422	24	107.	404.	95.8
5.2	574	35	113.	558	97.3
7.0	788	50	116.	777	98.6
10.2	1125	71	117	1100.	97.0
12.3	1350	86	118	1312.	97.2
14.9	1640	101	116	1565.	95.5

R is the no. of revolutions made by the disc in T seconds.

Dynamometer Meter No. 01666.

Run No. 6.

Data showing the effect of change of load with unity power factor, normal voltage, and 120 cycles.

Temperature V T.	120 cycles.	110 volts.	Current	True Watts	R	T	Watts Recorded.	Temperature V T. Recorded.
78.6	114.5	1.1	120	6	114.5	24.5	78.6	
87.8	108.	2.1	228	12	108.	200.	87.8	
95.8	107.	3.75	422	24	107.	404.	95.8	
97.3	112.	5.2	574	32	112.	558	97.3	
98.6	116.	7.8	788	50	116.	777	98.6	
97.0	117	10.2	1125	71	117	1100.	97.0	
97.2	118	12.3	1250	82	118	1212.	97.2	
95.5	112	14.2	1640	101	112	1525.	95.5	

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 61666.

7.

Data calculated from the flux phase determination showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

Volts 110

Amperes 10

Cycles 60.

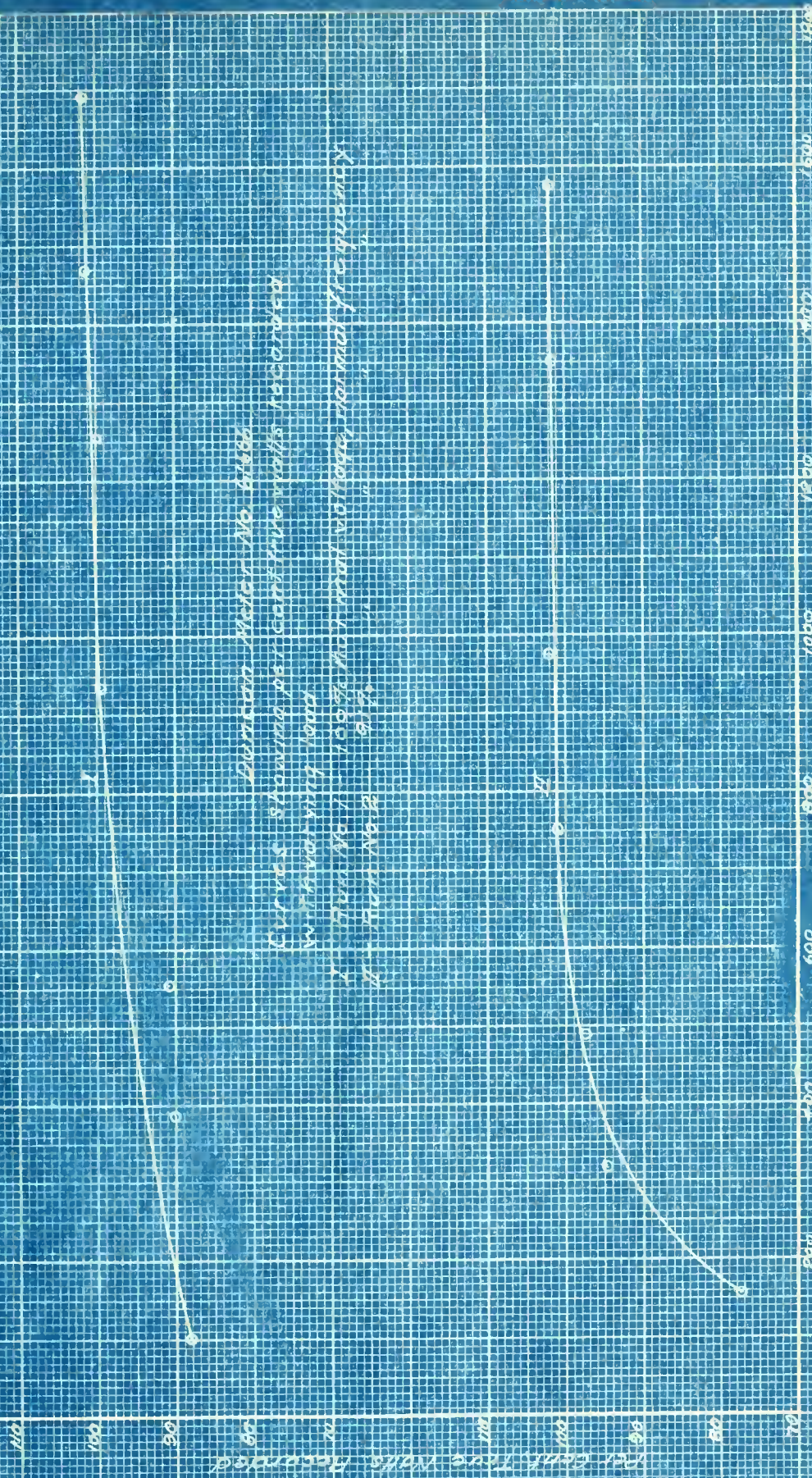
Cos θ	True Watts	Watts Recorded	% Recorded.
1.000	1100	1100	100.0
.966	1061	1057	99.6
.866	953	944	99.1
.766	844	831	98.5
.656	723	708	98.0
.500	550	534	97.2

Duncan Meter # 6166.

7.

Data calculated from the flux phase determination showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

Volts 110	Amperes 10	Cycles 60.	Gas @	Time Watts	Watts Recorded	% Recorded.
1.000	1100	100.0				
.999	1081	99.9				
.998	983	99.1				
.997	844	98.5				
.996	723	98.0				
.995	554	97.3				



Duration Motor No 6100
 Curves showing per cent free wells recorded
 W. P. W. No. 11 1000

A. Motor No. 150% M.V. and voltage, normal frequency
 W. P. W. No. 3 875

1500 1400 1300 1200 1100 1000 900 800 700 600 500 400 300 200 100 0

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REL. CONCENTRATION IN THE TEST INDEX

100%

75%

50%

25%

0%

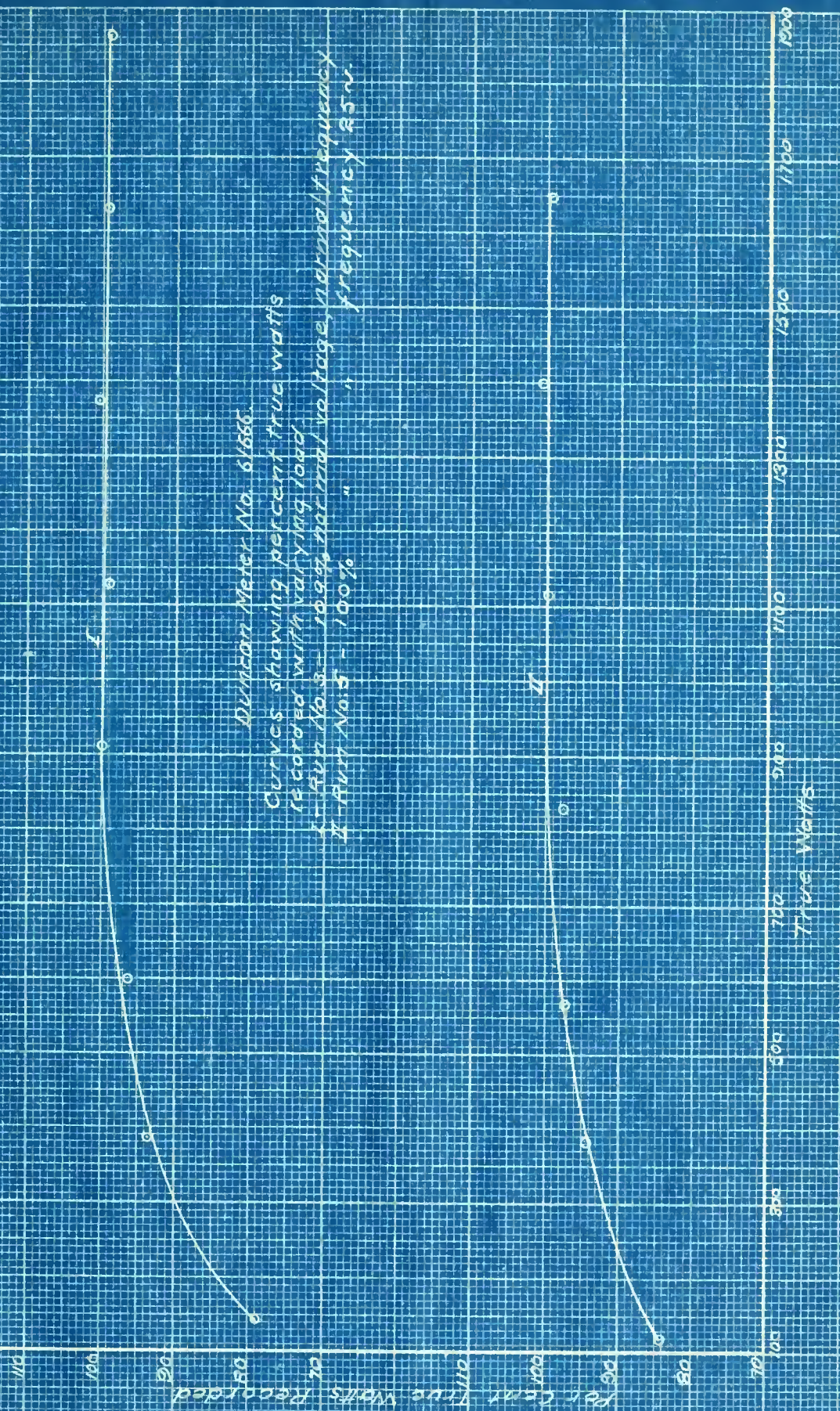


PHOSPHORIC ANHYDRIDE
Curve showing the results recorded
in Table 1, Figure 1, 1000 cc. of water

0 100 200 300 400 500 600 700 800 900 1000 1100 1200 1300 1400 1500 1600 1700 1800

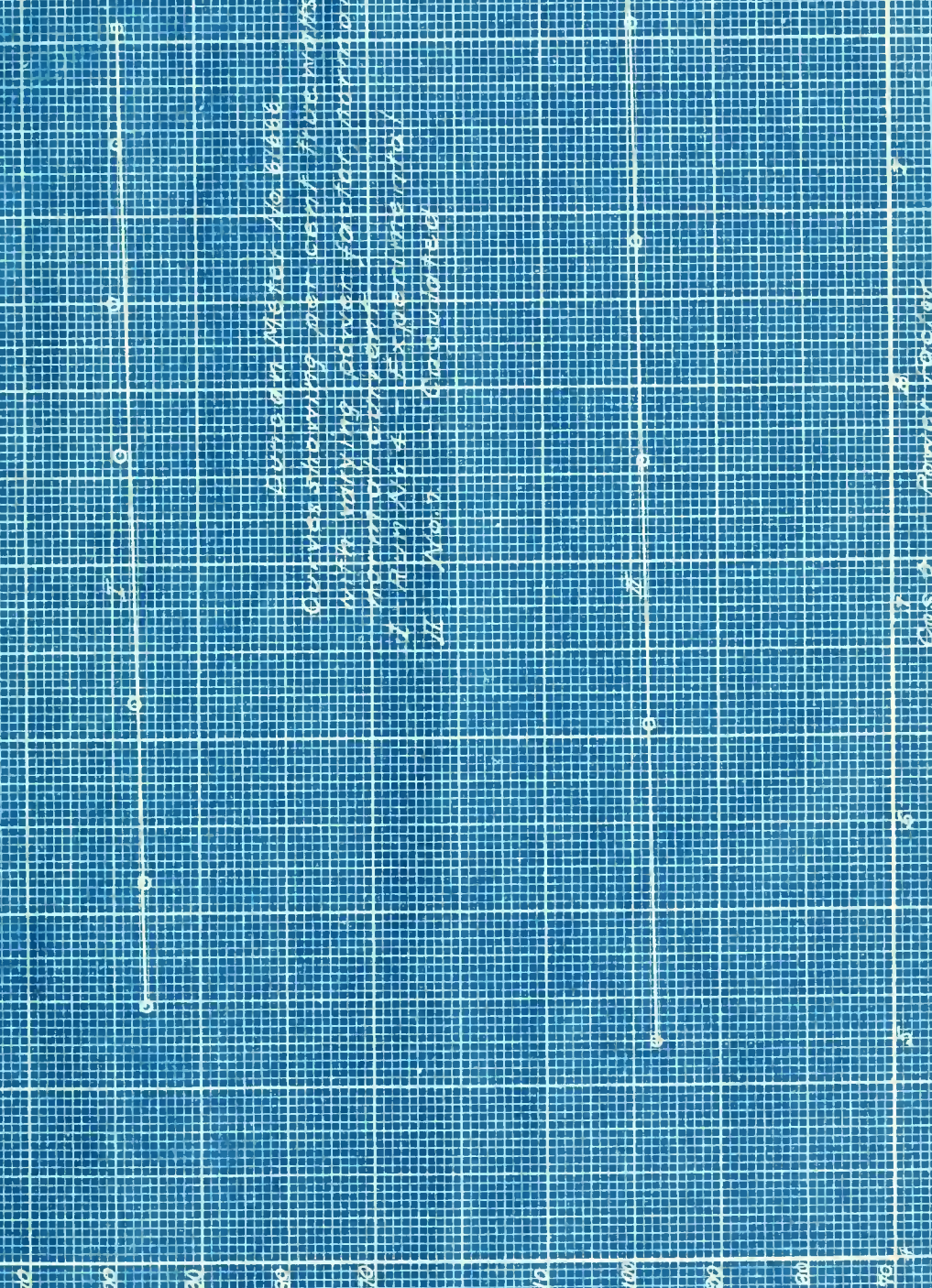
TIME IN MINUTES

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LANSING,

PER CENT TIME WASTES RECORDED



Standard Meter No. 61888
 Curves showing per cent time wastes recorded
 with varying number of air meters for economy
 of air meter use. Experiment No. 1
 at Mount Airy, N.C.

Series A Standard Meter

100

MEMORANDUM
INSTITUTE OF TECHNOLOGY
MAY 1951

Duncan Meter # 74520.

Resistance of pressure coil 2295. ohms.
 " " series "0875 ohms.

Data for the determination of the phase relation of
 the series and pressure fluxes.

Volts 110. Amperes 10. Apparent Watts 1100.

Direction of Rotation of Disc.	Dynamometer Reading.	True Watts	Cos θ .	
Forward	- 13	24	.0218	
"	- 12	22	.0200	
"	-12.5	23	.0209	
Backward	+4	8	.00726	
"	+4	8	.00726	
"	+4	8	.00726	
Average cos θ for forward rotation0209	
"	θ	"	" 88° 48'
"	cos θ	" backward	"00726
"	θ	"	" 90° 25'
Phase angle from quadrature for forward rotation			1° 12'	
"	"	" backward	"	25'
Average phase angle from quadrature			23.5'	
Phase angle between series and pressure fluxes .			23.5'	

Duncan Meter # 74520

Run # 1

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and normal frequency.

110 volts.		60 cycles.		Temperature 73 F.	
Current.	True Watts	R.	T	Watts Recorded	% Recorded.
1.55	173	8	118.7	122	70.5
3.00	328	20	128.	281	85.8
5.20	573	35	118.	534	92.0
7.95	875	57	121.2	848	96.8
10.85	1195	79	121.5	1170	98.0
13.25	1455	97	121.5	1435	98.5
15.50	1700	113	120.8	1685	99.0

R is the no. of revolutions made by the disc in T seconds.

Johnson Meter # 74220

Run # 1

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and normal frequency.

110 volts. 60 cycles. Temperature 73 F.

Current.	Time	Watts	T	Watts	Recorded.
1.25	172	172	118.7	122	70.5
2.00	228	228	122	221	82.8
2.50	278	278	118	234	92.0
3.25	342	342	121.2	243	96.8
4.00	402	402	121.5	1170	98.0
4.75	452	452	121.5	1422	98.5
5.50	502	502	120.8	1682	99.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

Run # 2.

Data showing the effect of change of load with unity power factor, 109 % normal voltage, and normal frequency.

120 volts.		60 cycles.		Temperature 73 F	
Current	True Watts	R	T	Watts Recorded	% Recorded.
1.10	130	7	128.5	98.5	77.0
3.25	388	22	122.7	323.0	83.2
4.85	585	36	122.	531.	90.5
8.10	970	62	121.6	918.	94.7
10.50	1258	81	119.	1225	97.4
13.10	1570	100	116.	1550	98.8
15.50	1850	122	120	1830	99.0

R is the no. of revolutions made by the disc in T seconds.

Dynamometer Meter # 74530.

Run # 2.

Data showing the effect of change of load with unity power factor, 100% normal voltage, and normal frequency.

Temperature 73 F	60 cycles.	120 volts.		
Recorded	Recorded	Recorded	Recorded	Recorded
Watts	Watts	Watts	Watts	Watts
Recorded	Recorded	Recorded	Recorded	Recorded
77.0	188.5	130	7	1.10
83.3	223.0	133.7	22	3.25
90.5	231.	133.	36	4.85
94.7	218.	131.5	52	8.10
97.4	1325	119.	81	10.50
98.8	1550	116.	100	13.10
99.0	1820	120	122	15.50

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

Run # 3.

Data showing the effect of change of load with unity power factor, 91% normal voltage, and normal frequency.

100 volts.

60 cycles.

Temperature 73 F.

Current	True Watts	R	T	Watts Recorded	% Recorded.
1.35	140	6	123.7	87.3	62.3
3.15	315	17	113.	271.	86.0
4.93	495	28	111.2	453.	91.5
9.40	940	57	112.	916.	97.5
11.50	1140	69	112.	1110	97.5
13.00	1298	78	109.2	1286	99.0
15.00	1510	90	108.5	1495	99.1

R is the no. of revolutions made by the disc in T seconds.

Dynamometer Meter # 74520.

Run # 2.

Data showing the effect of change of load with unity power factor, 91 normal voltage, and normal frequency.

Temperature 73 F.	100 volts.	60 cycles.	Current	Time watts	Watts Recorded	Watts Recorded
82.8	140	6	1.35	183.7	87.2	82.8
82.0	315	14	3.15	113.	271.	82.0
81.5	495	28	4.95	111.2	453.	81.5
87.5	640	54	6.40	112.	316.	87.5
87.5	1140	69	11.50	112.	1110	87.5
89.0	1328	78	13.00	102.2	1381	89.0
89.1	1510	90	15.00	108.5	1425	89.1

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

Run #4.

Data showing the effect of change of load with unity power factor, 100 % normal voltage, and 25 cycles.

110 volts.

25 cycles.

Temperature 80.F.

Current.	True Watts.	R	T	Watts Recorded	% Recorded.
1.1	120	3	59	91.5	76.1
3.15	345	11	62.8	315.	91.4
5.75	628	20	60	600	97.0
7.75	848	28	61.2	826	97.5
10.15	1115	38	62.	1105	99.5
12.90	1420	47	60.3	1405	99.0
15.00	1650	55	60.5	1635	99.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

Run #4.

Data showing the effect of change of load with unity

power factor, 100 % nominal voltage, and 25 cycles.

110 volts. 25 cycles. Temperature 80.5.

Current.	Time Watts.	R	T	Watts Recorded	Recorded.
1.1	180	3	59	21.5	26.1
3.15	345	11	62.8	315.	31.4
5.75	628	20	60	600	37.0
7.75	848	28	61.3	825	37.5
10.15	1115	38	62.	1105	39.3
12.30	1420	47	60.3	1405	39.0
15.00	1650	55	60.5	1625	39.0

R is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

Run # 5.

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts. 10 amperes. 60 cycles. Temperature 75 F.

Cos θ .	True Watts	R	T	Watts Recorded	% Recorded.
1.000	1110	38	61.8	1125	100.5
.945	1040	58	100.0	1045	100.5
.880	970	65	120.5	970	100.0
.764	840	48	102.0	846	100.7
.710	780	46	104.0	790	101.0
.595	655	41	111.5	660	100.8
.517	570	32	100.0	576	101.0

R is the no. of revolutions made by the disc in T seconds.

Dunham Meter # 74280.

Run # 5.

Data showing the effect of change of power factor with constant full load current, normal frequency, and normal voltage.

110 volts. 10 amperes. 60 cycles. Temperature 75 F.

cos φ	Time	Watts	Watts	φ	Watts
Recorded	Recorded	Recorded	Recorded	Recorded	Recorded
1.000	1110	38	61.8	1115	100.5
.945	1040	58	100.0	1045	100.5
.880	970	65	120.5	970	100.5
.764	840	48	102.0	845	100.7
.710	780	46	104.0	780	101.0
.595	655	41	111.5	655	100.8
.517	570	32	100.0	570	101.0

φ is the no. of revolutions made by the disc in T seconds.

Duncan Meter # 74520.

6

Data calculated from the flux phase determination showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

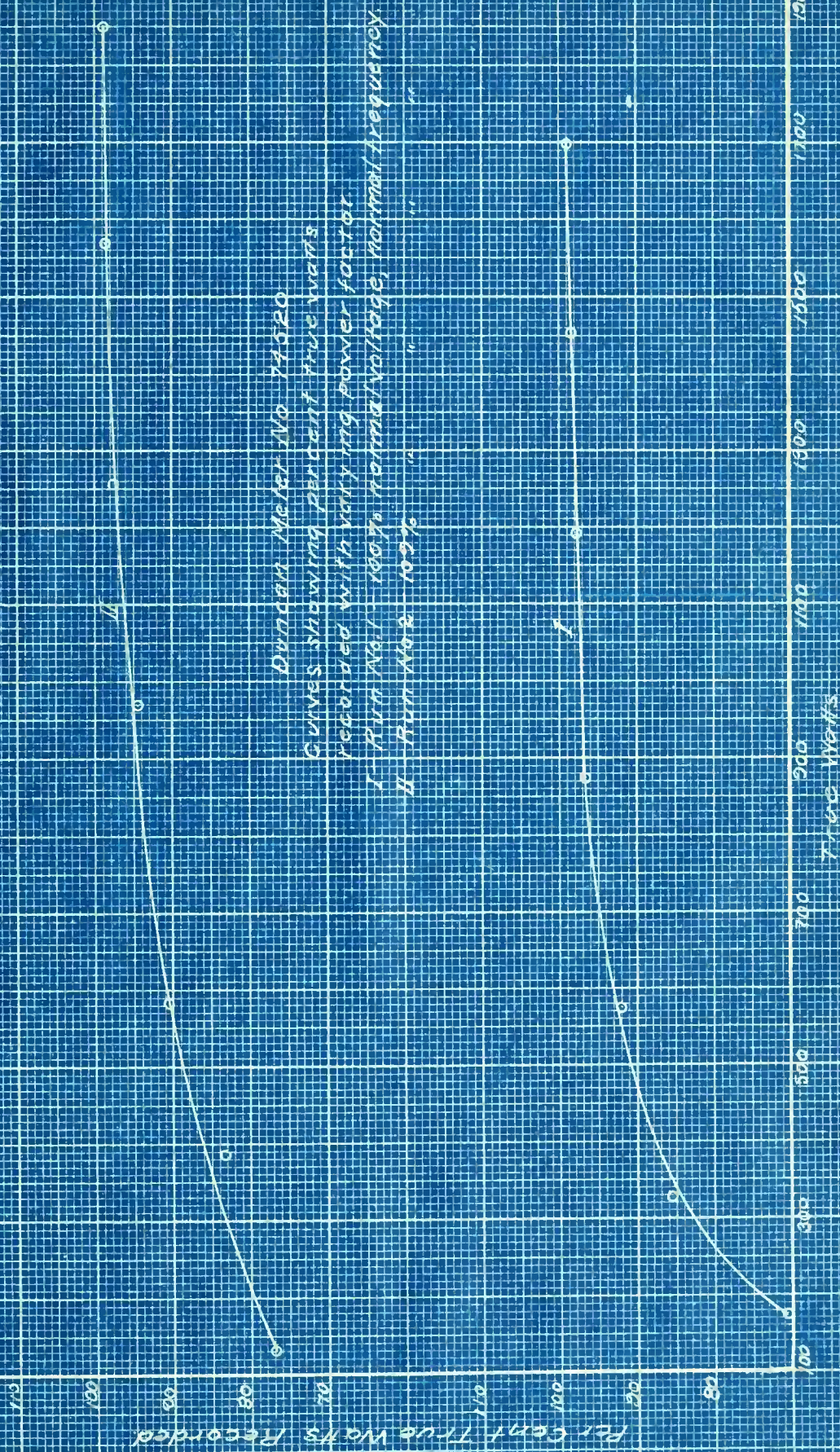
Volts 110	Amperes 10	Cycles 60	
Cos θ .	True Watts	Watts Recorded.	% Recorded
1.000	1100	1100	100
.966	1061	1062	100.1
.866	954	957	100.3
.766	844	848	100.5
.642	707	714	100.8
.500	550	557	101.1

Duncan Meter # 74520.

6

Data calculated from the flux phase determination showing the effect of change of power factor with normal frequency, normal voltage, and constant full load current.

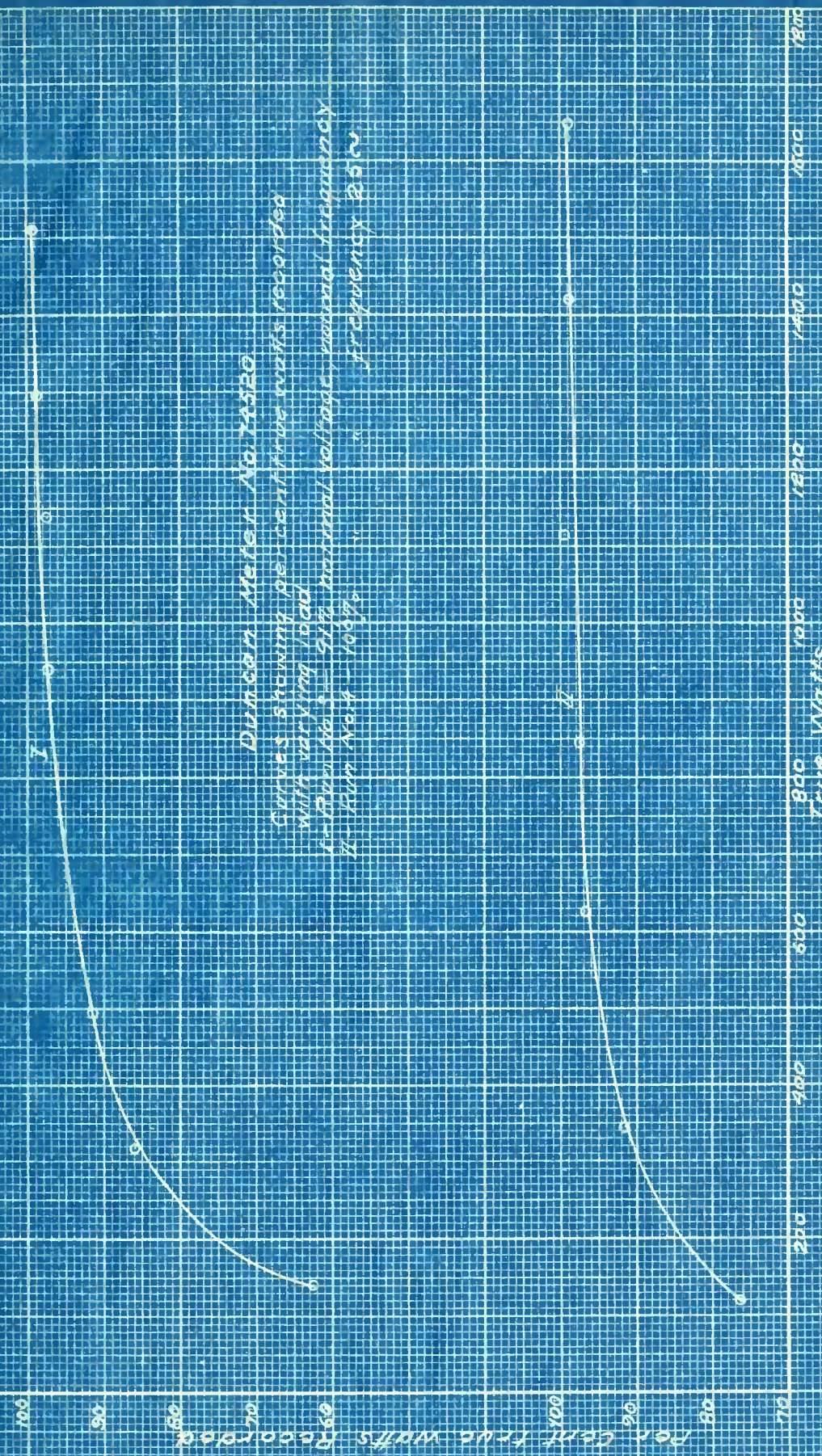
Volts 110	Amperes 10	Cycles 60
1.000	1100	100
.988	1082	100.1
.986	957	100.3
.982	848	100.5
.978	714	100.8
.970	557	101.1



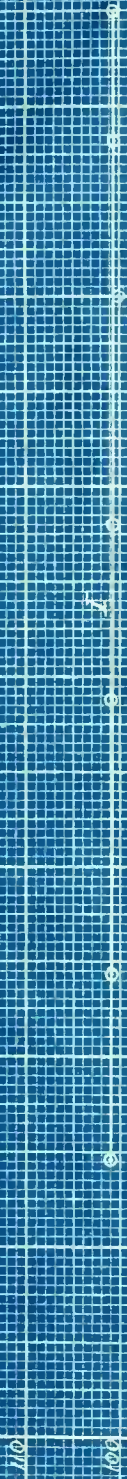
True Watts

Per Cent True Watts Recorded

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ALBANY, N. Y.

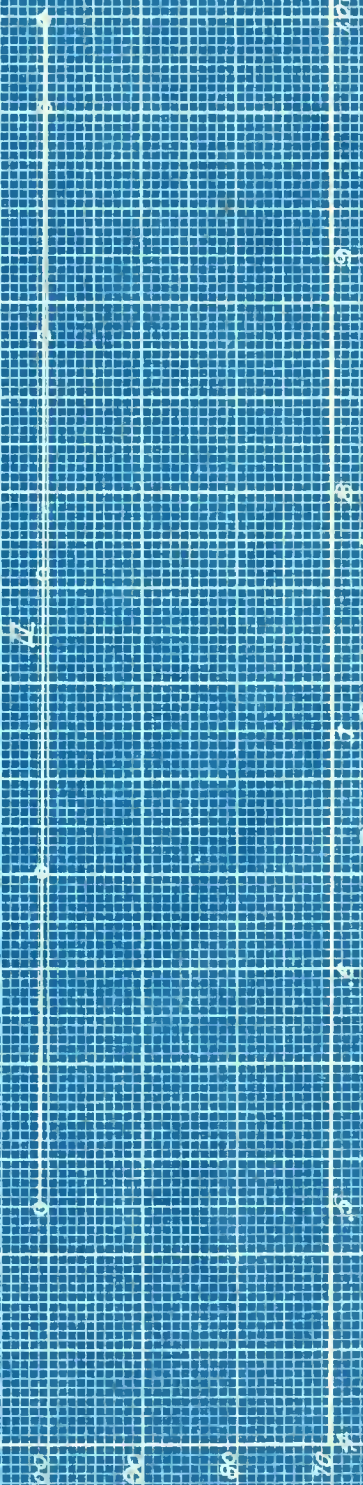


PER CENT TRUE WATTS RECORDED

Standard Meter No. 11310

Curves showing percent true watts recorded with varying power factor, normal voltage, normal frequency, full load current.

1 - Radio's Experimental
 2 - No. 6 - Calculated



Power Factor - cos φ

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