

Regional and Thematic Hubs

Status update June 24-26, 2022 "[...] new connections and structures will emerge, or existing ones will be strengthened, which will bring the principle of subsidiarity into practice."

- Recommendation 4 "Ensure Equity in Decision-making"

Hubs Timeline(s) - prework











November - December 2020

January 2021

June 2021

November 2021

February -March 2021

Recommendation prioritization

Initiative specific conversations

First research grants funded

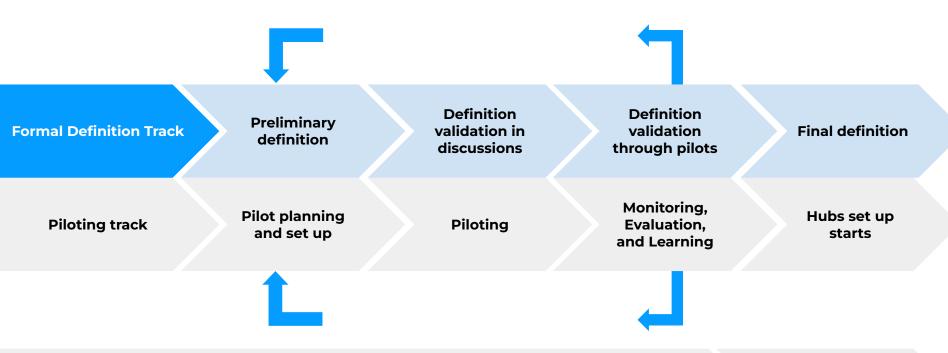
Hub workshops - mapping the work

Hubs Dialogue - agreement for next steps

Phase 0 - Initial implementation conversations

Phase 1 - Mapping, Research and Planning

Hubs Timeline - Definition <> Piloting Cycle



Phase 2 - Intertwined piloting and defining

Phase 3 - Implementation A complex system has no repeating relationships between cause and effect, is highly sensitive to small interventions and cannot be determined by outcome based targets; hence when dealing with complex systems there is the need for experimentation. 50

- Cynefin wiki "Safe to fail probes"

Minimum Piloting Criteria - Why?

Enabling constraints to ensure that

- >> We don't deviate too far from the definition work;
- >> We have visibility into piloting, creating movement level accountability;
- >> We don't stall the progress and momentum of developing movement.

Approval Process	Minimum Criteria	Planning Template
 Define if and how the approval of any pilots will happen. Key focus on alignment with the definition work, also feasibility of the plan and visibility into pilot Includes a mention of the MCDC 	 Minimum criteria to ensure sufficient level of visibility into the plans and pilot. Ensures movement level accountability. Helps to do the mapping and avoid duplications and redundancies. Not brought to a minimal level yet 	 A supporting template to help pilot planners define their working concept and work itself Supports intentionality in piloting and is a basis for monitoring, evaluation, and learning work
Decision-making	Accountability to Movement	Implementation Support



Let's discuss!