

An Executive System for Modeling with Rational B-Splines

by

Glenn Roy Hottel, SR

B.S. and M.S., Nuclear Engineering, Purdue University (1978)

Submitted to the Department of

OCEAN ENGINEERING

In partial fulfillment of the requirements for the Degree of

NAVAL ENGINEER

and

MASTER OF SCIENCE IN MECHANICAL ENGINEERING

at the

MASSACHUSETTS INSTITUTE of TECHNOLOGY

MAY , 1989

© Glenn Roy Hottel, SR, 1989. All rights reserved.

The author hereby grants to M.I.T. and to the U.S. Government permission to reproduce and distribute copies of this thesis document, in whole or in part.

Certified By :

Professor N. M. Patrikalakis
Department of Ocean Engineering
Thesis Supervisor

Department of Ocean Engineering
Author, May, 1989

Professor P. E. Sullivan
Department of Ocean Engineering
Thesis Supervisor

Accepted By :

A. Douglas Carmichael, Chairman
Department Graduate Committee
Department of Ocean Engineering

Professor D. C. Gossard
Mechanical Engineering Department
Thesis Reader

Ain A. Sonin, Chairman
Committee on Graduate Studies,
Mechanical Engineering Department

An Executive System for Modeling

With Rational B-Splines

by

Glenn Roy Hottel, SR

Submitted to the Department of Ocean Engineering and
Department of Mechanical Engineering on May 6, 1989,
in partial fulfillment of the requirements for
the Degree of Naval Engineer and Degree
of Master of Science in
Mechanical Engineering

ABSTRACT

An editor for use in the modeling of surfaces and curves with non-uniform rational B-splines (NURBS) was developed. A comprehensive menu structure has been generated and a method for interfacing future modules into this structure was developed and discussed with examples.

Surface modules interfaced include: Gaussian, mean, normal and principal curvature presentations; shading with light source and color editing; presentation editing with full positioning and rotation capabilities; and, isophote line calculation.

Curve modules interfaced include entering and editing points in the parametric space of a B-spline surface; generation of a B-spline curve interpolating these points while staying on the surface; and, fairing of the curve to get a smoother shape for a curve on a surface.

Implementation of the editor uses a DEC VAX Station II with the NAG Mark 11 library. The display graphics are performed on a Silicon Graphics IRIS 3030 Workstation networked with the VAX station.

Thesis Supervisor : N. M. Patrikalakis, Ph.D.
Title : Assistant Professor of Ocean Engineering

Thesis Supervisor : P. E. Sullivan
Title : Associate Professor of Ocean Engineering

ACKNOWLEDGMENTS

The United States Navy provided tuition and salary during my stay at M.I.T and for this I am truly appreciative. Without this assistance I would not have been able to have this valuable educational experience.

The MIT Ocean Engineering Design Laboratory research in the area of this thesis is supported by the Naval Sea Systems Command of the U.S. Navy and the MIT Sea Grant College Program under contract number NA86AA-D-SG089.

Special thanks go to Mr. Mike Drooker who gave me hours of assistance in many different areas, all of which were crucial to my work. The majority of the routines interfaced into the editor are the work of Mr. Panagiotis Alourdas. His assistance in helping me understand their inner workings is greatly appreciated.

A number of the members of the Design Laboratory unselfishly answered questions and gave assistance to me on the many occasions when I became lost with the various operations of the laboratory. To Mr. George Kriezis, Mr. Bradley Moran and Mr. Seamus Tuohy, again, thank you for your help.

DEDICATION

To my wife Janet and four children, Kelly, Chris, Emily and Glenn Roy, JR, whose love and support made this possible and without whom it would all be meaningless.

TABLE OF CONTENTS

CHAPTER 1 - INTRODUCTION AND OUTLINE	21
CHAPTER 2 - DATA AND FILE STRUCTURES	23
2.1 General	23
2.2 B-Spline Curves	24
2.3 B-Spline Surfaces	28
2.4 Existing Structures	30
2.4.1 egeom	30
2.4.2 fgeom	31
2.5 Developed Structures	32
2.5.1 Mouse_Words	33
2.5.2 Menu_Entry	35
2.5.3 Stats	37
2.5.4 Message	38
2.5.5 Choice_List	39
2.5.6 FulCurv	39
2.5.7 FulSurf	42
2.6 File Naming Conventions	46
CHAPTER 3 - HELP FILE	49
3.1 Input Help File	49
3.2 Help File Processing Program	51
3.3 Generated Files	53
3.3.1 Message Files	53
3.3.2 Pointer Files	53
3.3.3 Include File	54
3.3.3.1 Define Lines	54
3.3.3.2 Extern Lines	54
3.3.3.3 Array Set Ups	55
CHAPTER 4 - MENU FILES	57
4.1 Menu Data Structure	57
4.2 Menu Tree Structure	58
4.3 Menu Interaction	62
CHAPTER 5 - EDITOR PROGRAMS AND LAYOUT	65
5.1 CHANGING A VIEW POINT	67
5.2 MAIN MENU	68
5.2.1 INPUT ROUTINES	68
5.2.1.1 CURVE (3-D)	68
5.2.1.1.1 ENTER FORM KEYBOARD	68
5.2.1.1.2 RECALL FRO LOCAL FILE	68
5.2.1.1.3 RECALL IGES FILE	68
5.2.1.1.4 INTERACTIVE INPUT	68
5.2.1.2 SURFACE	68
5.2.1.2.1 ENTER FROM KEYBOARD	68
5.2.1.2.2 RECALL FROM LOCAL FILE	68
5.2.1.2.3 RECALL IGES FILE	69
5.2.1.2.4 INTERACTIVE INPUT	69

5.2.1.3	CURVE ON SURFACE	70
5.2.1.3.1	ENTER FROM KEYBOARD	70
5.2.1.3.2	RECALL FROM LOCAL FILE	70
5.2.1.3.3	RECALL IGES FILE	70
5.2.1.4	ALGEBRAIC SURFACE	70
5.2.1.4.1	ENTER FROM KEYBOARD	70
5.2.1.4.2	RECALL FROM LOCAL FILE	70
5.2.1.5	GRID OF POINTS	70
5.2.1.5.1	ENTER FROM KEYBOARD	70
5.2.1.5.2	RECALL FROM LOCAL FILE	70
5.2.1.6	FUNCTION ON CURVE	70
5.2.1.6.1	ENTER FROM KEYBOARD	70
5.2.1.6.2	RECALL FROM LOCAL FILE	70
5.2.1.7	LIST OF POINTS	70
5.2.1.7.1	ENTER FROM KEYBOARD	70
5.2.1.7.2	RECALL FROM LOCAL FILE	70
5.2.1.7.3	INTERACTIVE INPUT	70
5.2.1.8	LIST OF LISTS	70
5.2.1.8.1	RECALL FROM LOCAL FILE	70
5.2.1.8.2	INTERACTIVE INPUT	70
5.2.1.9	LIST OF POINTS (3-D)	70
5.2.1.9.1	ENTER FROM KEYBOARD	70
5.2.1.9.2	RECALL FROM LOCAL FILE	70
5.2.1.9.3	INTERACTIVE INPUT	71
5.2.2	GEOMETRY GENERATION	71
5.2.2.1	CURVES	71
5.2.2.1.1	FIT POINTS IN 3-D	71
5.2.2.1.2	APPROXIMATE WITH NURBS	71
5.2.2.1.3	OFFSET OF A PLANAR CURVE	71
5.2.2.1.4	OFFSET NORMAL TO PATCH	71
5.2.2.2	SURFACES	71
5.2.2.2.1	OFFSET OF ANOTHER SURFACE	71
5.2.2.2.2	RULED SURFACE	71
5.2.2.2.3	FIT/APPROXIMATE n ISOPARAMETER LINES	71
5.2.2.2.4	FIT/APPROXIMATE GRID OF POINTS	71
5.2.2.2.5	CONVERT ALGEBRAIC TO NURBS	71
5.2.2.3	CURVES ON SURFACE	71
5.2.2.3.1	FIT/APPROXIMATE LIST OF POINTS --> calls submenu (see Chapter 5.3)	71
5.2.2.3.2	FIT/APPROXIMATE LIST OF LISTS	71
5.2.2.3.3	VARIABLE OFFSET OF ANOTHER CURVE ON SURFACE	71
5.2.2.4	BLEND	71
5.2.2.4.1	BOUNDARY CONDITIONS	71
5.2.2.4.1.1	POSITION	71
5.2.2.4.1.2	NORMAL	71
5.2.2.4.1.3	CURVATURE	72
5.2.2.4.2	DEFINE SURFACE	72
5.2.2.4.3	DEFINE CURVES	72
5.2.2.4.4	EXECUTE BLEND	72

5.2.3	GEOMETRY INTERROGATION	72
5.2.3.1	CURVES	72
5.2.3.1.1	VISUALIZATION	72
5.2.3.1.1.1	RESOLUTION	72
5.2.3.1.1.2	COLOR	72
5.2.3.1.1.3	VIEWPOINT	72
5.2.3.1.2	CURVATURE VALUES	72
5.2.3.1.2.1	RESOLUTION	72
5.2.3.1.2.2	SHOW CURVATURE MAP	72
5.2.3.1.3	STATUS	72
5.2.3.1.3.1	ON	72
5.2.3.1.3.2	OF	72
5.2.3.2	CURVES ON SURFACE	72
5.2.3.2.1	VISUALIZATION	72
5.2.3.2.1.1	RESOLUTION	72
5.2.3.2.1.2	LINETYPE	72
5.2.3.2.1.3	VIEWPOINT	72
5.2.3.2.2	CURVATURE MAP	72
5.2.3.2.2.1	RESOLUTION	72
5.2.3.2.2.2	SHOW	72
5.2.3.2.3	STATUS	73
5.2.3.2.3.1	ON	73
5.2.3.2.3.2	OFF	73
5.2.3.3	SURFACE	73
5.2.3.3.1	VISUALIZATION	73
5.2.3.3.1.1	RESOLUTION	73
5.2.3.3.1.2	COLOR	73
5.2.3.3.1.3	VIEWPOINT	73
5.2.3.3.2	PLANE CONTOURS	74
5.2.3.3.2.1	SET # PLANES	74
5.2.3.3.2.2	SET START PLANE	74
5.2.3.3.2.3	SET PLANE DISTANCE	74
5.2.3.3.2.4	INTERSECTION ACCURACY	74
5.2.3.3.2.4.1	2-D	74
5.2.3.3.2.4.2	3-D	74
5.2.3.3.3	CYLINDER CONTOURS	74
5.2.3.3.3.1	SET # CYLINDERS	74
5.2.3.3.3.2	SET START CYLINDER	74
5.2.3.3.3.3	CYLINDER DISTANCE	74
5.2.3.3.3.4	INTERSECTION ACCURACY	74
5.2.3.3.3.4.1	2-D	74
5.2.3.3.3.4.2	3-D	74
5.2.3.3.4	SHADED IMAGE	74
5.2.3.3.4.1	READ IMAGE	74
5.2.3.3.4.2	CALCULATE IMAGE	74
5.2.3.3.4.3	COLOR	75
5.2.3.3.4.4	SET LIGHT SOURCE	77
5.2.3.3.4.5	SET VIEWPOINT	77
5.2.3.3.5	RAY TRACE	78
5.2.3.3.5.1	READ TRACE	78
5.2.3.3.5.2	CALCULATE TRACE	78
5.2.3.3.5.3	SET COLOR	78

5.2.3.3.6	CURVATURE	78
5.2.3.3.6.1	READ CURVATURE	78
5.2.3.3.6.2	CHANGE VIEW	78
5.2.3.3.6.3	ALL CURVATURES	78
5.2.3.3.6.4	GAUSSIAN	79
5.2.3.3.6.5	MEAN	80
5.2.3.3.6.6	ABSOLUTE	80
5.2.3.3.6.7	MAXIMUM PRINCIPAL	80
5.2.3.3.6.8	MINIMUM PRINCIPAL	80
5.2.3.3.6.9	NORMAL U	80
5.2.3.3.6.10	NORMAL V	81
5.2.3.3.7	ISOPHOTES	81
5.2.3.3.7.1	SET NUMBER	81
5.2.3.3.7.2	READ ISOPHOTE	81
5.2.3.3.7.3	CALCULATE ISOPHOTES	81
5.2.3.3.7.4	SHOW ISOPHOTES	81
5.2.3.3.8	REFLECTION LINES	82
5.2.3.3.8.1	SET NUMBER	82
5.2.3.3.8.2	READ IN LINES	82
5.2.3.3.8.3	CALCULATE LINES	82
5.2.3.3.8.4	SHOW LINES	82
5.2.3.3.9	GEODESICS	82
5.2.3.3.9.1	READ IN	82
5.2.3.3.9.2	CALCULATE	82
5.2.3.3.9.3	SHOW	82
5.2.3.3.10	SURFACE ON/OFF	82
5.2.4	GEOMETRY PROCESSING	82
5.2.4.1	CURVES	82
5.2.4.1.1	APPROXIMATE NURBS	82
5.2.4.1.1.1	SET ORDER	82
5.2.4.1.1.2	SET ACCURACIES	82
5.2.4.1.1.3	RUN	82
5.2.4.1.2	FAIRING	82
5.2.4.1.2.1	KNOT	82
5.2.4.1.2.2	AUTOMATED	82
5.2.4.1.2.3	RUN	82
5.2.4.1.3	CONTROL POINT EDIT	82
5.2.4.1.4	CHOOSE EXACT DEGREE	82
5.2.4.1.5	SUBDIVIDE	82
5.2.4.1.6	SPLIT CURVE	82
5.2.4.2	CURVE ON SURFACE	83
5.2.4.2.1	CONVERT COS TO NURBS	83
5.2.4.2.1.1	SET ACCURACIES	83
5.2.4.2.1.1.1	POSITION	83
5.2.4.2.1.1.2	CURVATURE	83
5.2.4.2.1.1.3	SLOPE	83
5.2.4.2.1.2	RUN CONVERT	83
5.2.4.2.2	FAIRING --> calls submenu (see	
Chapter 5.4)		83
5.2.4.2.3	EDITING	83
5.2.4.2.4	SUBDIVIDE IN UV	83
5.2.4.2.5	SPLIT IN UV	83

5.2.4.3	SURFACE	83
5.2.4.3.1	APPROXIMATE NURBS	83
5.2.4.3.1.1	SET ORDER	83
5.2.4.3.1.2	SET ACCURACIES	83
5.2.4.3.1.2.1	POSITION	83
5.2.4.3.1.2.2	CURVATURE	83
5.2.4.3.1.2.3	SLOPE	83
5.2.4.3.1.3	RUN	83
5.2.4.3.2	FAIRING	83
5.2.4.3.2.1	KNOT	83
5.2.4.3.2.2	AUTOMATED	83
5.2.4.3.2.3	RUN FAIRING	83
5.2.4.3.3	EDITING	84
5.2.4.3.4	DEGREE ELEVATION	84
5.2.4.3.5	SUBDIVIDE	84
5.2.4.3.6	SPLIT	84
5.2.4.4	INTERSECTIONS	84
5.2.4.4.1	LISTS 2-D	84
5.2.4.4.2	LISTS 3-D	84
5.2.5	QUIT	84
5.3	UV MENU	84
5.3.1	INPUT U-V POINTS	84
5.3.2	OUTPUT U-V POINTS	85
5.3.3	SHOW U-V POINTS	85
5.3.4	ADD U-V POINTS	86
5.3.5	INSERT U-V POINTS	87
5.3.6	DELETE U-V POINTS	88
5.3.7	MOVE U-V POINTS	89
5.3.8	SELECT WINDOW	90
5.3.9	FIT POINTS	91
5.3.10	MAKE SYSTEM CURVE	92
5.3.11	SET STEPS	93
5.3.12	START AGAIN	94
5.3.13	QUIT	94
5.4	COSFAIR MENU	94
5.4.1	FAIR CHILD - SINGLE	94
5.4.2	FAIR CHILD - AUTO	95
5.4.3	SET SCALE	96
5.4.4	SET STEPS	96
5.4.5	REDRAW CURVES	96
5.4.6	CHANGE VIEW, USE PARENT	96
5.4.7	CHANGE VIEW, USE CHILD	96
5.4.8	KEEP CHILD	97
5.4.9	SHOW WIRE FRAME/CURVE	97
5.4.10	SHOW SURFACE/CURVE	97
5.4.11	SET VIEW OF COS	98
5.4.12	QUIT FAIRING	98
5.5	WORLD MENU	98
5.5.1	SET BACKGROUND COLOR	98
5.5.2	SELECT CURRENT SURFACE	99
5.5.3	SELECT CURRENT CURVE	100

5.5.4	STATUS ROUTINES	100
5.5.4.1	LIST JOBS	100
5.5.4.2	SUSPEND JOBS	100
5.5.4.3	ACTIVATE JOBS	100
5.5.4.4	KILL JOBS	100
5.5.5	SET PERSPECTIVE	100
5.5.6	TOGGLE BELL	101

CHAPTER 6 - NEW MODULES - EDITOR EXPANSION 103

6.1	Help File Additions	103
6.2	Menu File Additions	105
6.2.1	Menu Entry Formats	106
6.2.2	Menu Addition Examples	107
6.2.3	Menu Replacement Examples	107
6.3	Interface Examples	109
6.3.1	Add Call To Existing Routine	109
6.3.2	Add New Simple Entry	109
6.3.3	Add New Compound Entry	111
6.3.4	Consolidation Of Routines	114
6.3.5	Multiple Related Routines Requiring Identical Setup	115
6.3.6	Add Routine To Run External Job	120

CHAPTER 7 - DEMONSTRATION OF EDITOR 127

7.1	Screen Layout	127
7.2	Starting A Design - Input Data	130
7.3	Surface Operations	130
7.3.1	View Changing	132
7.3.2	All Curvatures	134
7.3.3	Segmentation Selection	134
7.3.4	Shaded Image	137
7.3.5	System Level Routines	140
7.3.6	External Jobs	144
7.3.7	Further Development In Surface Area	144
7.4	Curve Operations - Entering and Editing	146
7.4.1	Input Of Data Points From File	146
7.4.2	Windowing	148
7.4.3	Adding New Points	148
7.4.4	Help Screens	151
7.4.5	Insert New Points	151
7.4.6	Data Point Corrections	154
7.4.6.1	Move A Point	154
7.4.6.2	Delete A Point	154
7.4.7	Fit Of Points and Step Size	157
7.4.8	Making a System Curve and Quitting	157
7.5	Curve Operations - Fairing	159
7.5.1	Actual Fairing	159
7.5.2	Setting the Scale	159
7.5.3	Porcupine View	161
7.5.4	Curve on Wire Frame	161
7.6	Open Parametric Curve	164

CHAPTER 2 DATA AND FILE STRUCTURES

2.1 General

For ease and clarity in programming, large blocks of related data should be grouped into a single data structure. This makes it much easier to manipulate the related data in all aspects of the program. A considerable effort must be expended at the beginning of any programming project to ensure that the data structures developed are both adequate for the task at hand and have sufficient growth capability to allow small adjustments for unplanned changes.

The system that is used for development of a computer program will usually have a major influence upon the layout of the program and the data structures used in the program and this was the case with this editor. The computer set up for this development was a Silicon Graphics IRIS 3030 Workstation used for the display of the graphical output and a DEC VAX Station II for computations. In addition to the remote IRIS Graphics Library installed on the DEC VAX station, many of the routines developed use functions of the NAG Mark 11 Fortran library. The editor primarily employs the C programming language with occasional calls to the ULTRIX operating system.

As important as data structures are the file structures used for data storage and the system of naming these storage files. A suggested system for file naming developed for this editor is discussed at the end of this section.

To support this editor it was necessary to develop many new structures. Previously developed structures were utilized whenever possible to aid in compatibility across application boundaries. Because they are essentially a subset of the new, larger structures, the preexisting structures used in the editor are briefly discussed first.

The central idea of this editor is the use of non-uniform rational B-spline curves and surfaces for modeling of free-form (sculptured) shapes. The most basic data structures that hold the information needed to define these curves and surfaces are **egeom** and **fgeom** respectively. These data structures are listed in detail after a brief review of the terms needed to understand the definition of B-splines. The discussion here comes mainly from [1].

2.2 B-Spline Curves

If $T = (t_0, t_1, \dots, t_k)$ is a set of real numbers such that $t_i \leq t_{i+1}$, then a real valued function $f(t)$ defined in the domain $[t_0, t_k]$ is called a **spline** of order M , or degree $M-1$, if $f(t)$ is a polynomial of degree $M-1$ on each sub interval $[t_i, t_{i+1}]$ and its first $M-2$ derivatives are continuous in the entire interval $[t_0, t_k]$. More

important, the higher derivatives of a spline function are continuous everywhere except at $t_i, 0 \leq i \leq k$. The values t_0, t_1, \dots, t_k are the knots of the B-spline function and T is the knot vector.

A basis for the vector space spanned by spline functions was found by Curry and Schoenberg [2] and an expression of this basis best suited for numerical evaluation has been provided by De Boor [3] and Cox [4]. The definition of this basis function is recursive and is listed below:

$$N_{i,1}(t) = \begin{cases} 1 & \text{if } t_i \leq t < t_{i+1} \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

$$N_{i,M}(t) = \frac{t - t_i}{t_{i+M-1} - t_i} N_{i,M-1}(t) + \frac{t_{i+M} - t}{t_{i+M} - t_{i+1}} N_{i+1,M-1}(t) \quad \text{if } M > 1 \quad (2)$$

The functions defined through (1) and (2) are called B-spline basis functions over T . In evaluating (2) the convention $0/0 = 0$ is used whenever such a ratio appears. $N_{i,M}(t)$ is a weighted average of the B-spline functions associated with knots i and $i+1$. Each weight is the ratio of the distance between the parameter and the corresponding end of the support, t_i or t_{i+M} , to the length of $M-1$ spans starting from t_i, t_{i+1} , respectively. Thus, $N_{i,M}(t)$ extends over M spans of the knot vector covered by the interval $[t_i, t_{M+i}]$. $N_{i,M}(t)$ is zero in the remainder of $[t_0, t_k]$.

Non-uniform knot vectors offer certain advantages. Local manipulation of the curve shape is better achieved by a finer knot mesh in areas where accurate shape control is desirable. In applications where interpolation of unevenly spaced points

is required using the B-spline basis, a better parameterization results with a non-uniform knot vector. Curve and surface subdivision (refinement) for enhanced control also necessitates use of a non-uniform knot vector.

These concepts can be extended to vector-valued functions, i.e. spline functions $\mathbf{f}(t) : [t_0, t_k] \rightarrow \mathbf{R}^3$. In this case, $\mathbf{f}(t)$ is a vector, $\mathbf{f}(t) = (x(t) \ y(t) \ z(t))$, where $x(t)$, $y(t)$ and $z(t)$ are scalar spline functions over the same knot vector $T = (t_0, t_1, \dots, t_k)$. The basis functions are the same as those given by equations (1) and (2). The parametric representation of curves with vector-valued spline functions offers certain advantages with respect to explicit methods such as independence of coordinate systems, easy mathematical formulation of multiple-valued shapes and representation of derivative singularity within the same formulation.

A class of spline functions with the so called open knot vector

$$T = [\tau_0, \tau_0, \dots, \tau_0, \tau_1, \tau_2, \dots, \tau_{n-M}, \tau_{n-M+1}, \tau_{n-M+1}, \dots, \tau_{n-M+1}] = (t_0, t_1, \dots, t_{n+M-1}) \quad (3)$$

where τ_0 and τ_{n-M+1} each repeat M times

is of particular interest for design applications. This curve representation can be expressed as

$$\mathbf{R}_M(t) = \sum_{i=0}^{n-1} \mathbf{P}_i N_{i,M}(t) \quad (4)$$

where \mathbf{P}_i are the n vertices of the associated control polygon (P) described in terms of their (x, y, z) coordinates in a Cartesian system.

One point on a B-spline curve for the parameter value t can be computed recursively through the Cox-De Boor's algorithm. Let $T = (t_0, t_1, \dots, t_{n+M-1})$ be the knot vector and i an index such that $t_i \leq t < t_{i+1}$. Then

$$\mathbf{R}_M(t) = \mathbf{P}_i^{[M-1]}(t) \quad (5)$$

where
$$\mathbf{P}_i^{[k]}(t) = \begin{cases} \mathbf{P}_i & \text{if } k=0 \\ \lambda \mathbf{P}_i^{[k-1]}(t) + (1-\lambda) \mathbf{P}_{i-1}^{[k-1]}(t) & \text{if } k > 0 \end{cases} \quad (6)$$

and
$$\lambda = \frac{t - t_i}{t_{i-k+M} - t_i} \quad (7)$$

One vertex of the control polygon of a general B-spline curve according to (4) affects M consecutive intervals $[t_i, t_{i+1}], \dots, [t_{i+M-1}, t_{i+M}]$ and one interval is affected by M consecutive vertices. Hence, local control of the B-spline curve is possible by shifting only a limited number of vertices.

Rational B-spline curves [5] provide a generalization of integral or polynomial B-spline curves. They permit the representation of a wider class of free-form curves as well as classical algebraic curves such as conics, in particular circular arc segments as a special case. A rational B-spline curve of order M over the control polygon P with n vertices and knot vector T is defined as

$$\mathbf{R}_M(t) = \frac{\sum_{i=0}^{n-1} h_i \mathbf{P}_i N_{i,M}(t)}{\sum_{i=0}^{n-1} h_i N_{i,M}(t)} \quad (8)$$

where the h_i are positive real numbers (weights). The integral B-spline curve is a special case of the rational. It is obtained by setting h_i equal to 1 and observing

$$\sum_{i=0}^{n-1} N_{i,M}(t) = 1 \quad , \quad t_0 \leq t \leq t_{n+M-1}$$

Rational B-splines have all the properties of integral B-splines. In addition, they are closed under bilinear transformations, i.e. transformations of the form $t = (at' + b)/(ct' + d)$ with a, b, c, d all real.

2.3 B-Spline Surfaces

The B-spline patch is the surface analogue of the B-spline curve and is a tensor product surface defined by a topologically rectangular set of control points $\mathbf{P}_{i,j}$, $0 \leq i \leq m-1$, $0 \leq j \leq n-1$, which are the vertices of the control polyhedron, P , and two knot vectors, T and S , associated with each parameter, u , v .

Let

$$T = (t_0, t_1, \dots, t_{m+M-1}) \quad (9)$$

$$S = (s_0, s_1, \dots, s_{n+N-1}) \quad (10)$$

be the knot vectors, where M and N are the orders in u and v respectively. The corresponding integral B-spline patch is given by

$$\mathbf{S}_{M,N}(u, v) = \sum_{i=0}^{m-1} \sum_{j=0}^{n-1} \mathbf{P}_{i,j} N_{i,M}(u) N_{j,N}(v) \quad (11)$$

where $N_{i,M}(u)$ and $N_{j,N}(v)$ are obtained from (1) and (2) by replacing the parameter t with u and v respectively.

Isoparametric or, simply, parametric lines on a B-spline patch are obtained by letting $u = \text{constant}$ or $v = \text{constant}$. A parametric line with $u = u_0$ is a B-spline curve in v with S as its knot vector and vertices $\mathbf{Q}_j, 0 \leq j \leq n-1$ given by

$$\mathbf{Q}_j = \sum_{i=0}^{m-1} \mathbf{P}_{i,j} N_{i,M}(u_0) \quad (12)$$

Some of the properties of B-spline curves can be easily extended to patches. The support of the basis functions extends over a rectangular area of $M \times N$ adjacent intervals of the parametric space. Surface discontinuities can also be represented by using multiple internal knots in either knot vector.

Rational B-spline surfaces are generalizations of integral B-spline patches. Given a control polyhedron P with m, n vertices in each parametric direction and the knot vectors T and S , the corresponding rational B-spline patch of orders M, N in u, v is

$$\mathbf{R}_{M,N}(u, v) = \frac{\sum_{i=0}^{m-1} \sum_{j=0}^{n-1} h_{i,j} \mathbf{P}_{i,j} N_{i,M}(u) N_{j,N}(v)}{\sum_{i=0}^{m-1} \sum_{j=0}^{n-1} h_{i,j} N_{i,M}(u) N_{j,N}(v)} \quad (13)$$

where $h_{i,j}$ are positive real numbers. By taking $h_{i,j}=1$ in (13) the rational B-spline patch is reduced to an integral tensor product patch. The properties of integral B-spline patches are easily extended to rational patches [5]. Rational B-spline patches can be employed to represent a wider class of free-form surfaces in comparison to integral B-spline patches. In addition, they allow representation of classical algebraic surfaces such as quadrics, torii and surfaces of revolution with planar rational B-spline profiles.

2.4 Existing Structures

The existing structures used in this editor are the core of the interaction between all of the Design Laboratory programs developed for B-spline curves and surfaces. The names of the structures are **egeom** and **fgeom** for edge (curve) geometry and face (surface) geometry respectively. These structures are given in Chapters 2.4.1 and 2.4.2 and are defined in the include file **gen.h**.

2.4.1 egeom

This structure is used to hold the information needed for three-dimensional non-uniform rational B-spline curves. There are many variables in the editor with the type definition **ParCurv**. This type definition is a short hand notation for the **egeom** structure.

Table 2.1 - Structure : egeom

int type	Currently used to <u>code</u> the type of egeom the data has been generated for. For example, 261326 would be a periodic parametric curve.
short order	The order of the B-spline curve.
short ncontpts	The number of control points for the curve.
short kmem	The assigned size of the knots array \geq (order + ncontpts)
short pmem	The assigned size of the control points array \geq ncontpts
double2 *knots	Pointer to array of knots ordered from the smallest parametric value to the largest.
vector **contpts	Pointer to array of control points for the curve.

2.4.2 fgeom

This structure is used to hold the basic information needed for a three-dimensional non-uniform rational B-spline surface. The variables in the editor with the type definition ParSurf are this type of structure.

Table 2.2 - Structure : fgeom

int type	Currently used to <u>code</u> the specific kind of fgeom the data has been generated for. For example, the code for a parametric surface, periodic in u, is 262931.
short uorder	The order of the B-spline surface in the u direction.
short vorder	Same as uorder but for the v direction.
short ucontpts	The number of control points in the u direction.
short vcontpts	Same as ucontpts but for the v direction.
short ukmem	The assigned size of uknots array $\geq (uorder + ucontpts)$.
short vkmem	Same as ukmem but for the v direction.
short upmem	The assigned size of contpts array $\geq ucontpts$.
short vpmem	Same as upmem but for the v direction.
double2 *uknots	Pointer to the knot vector in the u direction ordered from the smallest parametric value to the largest parametric value.
double2 *vknots	Same as uknots but for the v direction.
vector ***contpts	Pointer to the vector array holding the values for the control points for the surface.

2.5 Developed Structures

The structures developed specifically for the editor include:

1. Mouse_Words - Used for setting the mouse icon wording.
2. Menu_Entry - Used to build the linked menu structure.
3. Stats - Keeps track of external jobs.
4. Message - Used to send messages between external processes and the main program of the editor.
5. Choice_List - Used to implement a popup menu structure.
6. FulCurv - Incorporates the egeom structure discussed in Chapter 2.4.1 into a full system curve.
7. FulSurf - Incorporates the fgeom structure discussed in Chapter 2.4.2 into a full system surface.

Each new structure is discussed separately below.

2.5.1 Mouse_Words

This structure is used anytime the routine for labeling the mouse icon is called. The following items are included in the structure:

Table 2.3 - Structure : Mouse_Words

int press	1/0 : there is/is not a valid press operation for some mouse button
int release	1/0 : there is/is not a valid release operation for some mouse button
char *text[8]	The left and right mouse buttons have four lines of text associated with their operation, two each for press and release. Each line can be up to eleven characters long. Since the different operations are color coded, it is important to use the correct lines.
char *middle[2]	Serves the same purpose for the middle mouse button as 'text' serves for the other two mouse buttons. Only one entry (vice two) is needed for the middle mouse button operations because these lines can be much longer, 24 characters.

A typical use of this variable is shown in the following code (assumes mousew has been declared of type Mouse_Words). This would tell the user that some sort of action will be taken as a result of the press or subsequent release of the left mouse button.

```

/* press operation */
mousew.text[0] = strdup("SELECT");
mousew.text[1] = strdup(" POINT");
press = 1;

/* release operation */
mousew.text[2] = strdup("ACCEPT");
mousew.text[3] = strdup(" POINT");
release = 1;

mousewords (&mousew, 1);

```

The routine **strdup()** allocates memory for a copy of the argument string. The routine **mousewords()** actually labels the mouse icon and if called with a **1** releases the memory allocated by the **strdup** call. Calling with a **0** will stop the freeing of this memory.

2.5.2 Menu_Entry

This structure is used to build the menu tree structure used throughout the program. Any number of these variables can be made and interfaced in adding future modules. Currently four such menus are used. This structure contains pointers to occurrences of itself so it is essentially a recursive definition. To facilitate this, the original definition is in terms of **menu_entry** (no caps) and the definition used throughout the program is **Menu_Entry**.

Table 2.4 - Structure : Menu_Entry

char entry_name[25]	The text printed when this item is part of a menu.
char menu_title[25]	The text printed when this item is the head of a menu.
int num_subs	The number of menu selections directly available in the menu that this entry is the head of. Can range from 1, if this entry has no submenu items, to an upper limit of 14, based upon screen layout limitations.
char help[5]	The help file index abbreviation for this selection.
struct menu_entry *from	Points to the menu entry that directly called this entry.
struct menu_entry *first_sub	Points to the first member of any subentries.
struct menu_entry *next	If this is a subentry, points to the next entry if it exists.
struct menu_entry *head	Points to the calling menu item of the submenu that this item is a part of.

Shown next is a sample menu structure. For this structure the various values of the Menu_Entry CIRCLE are listed.

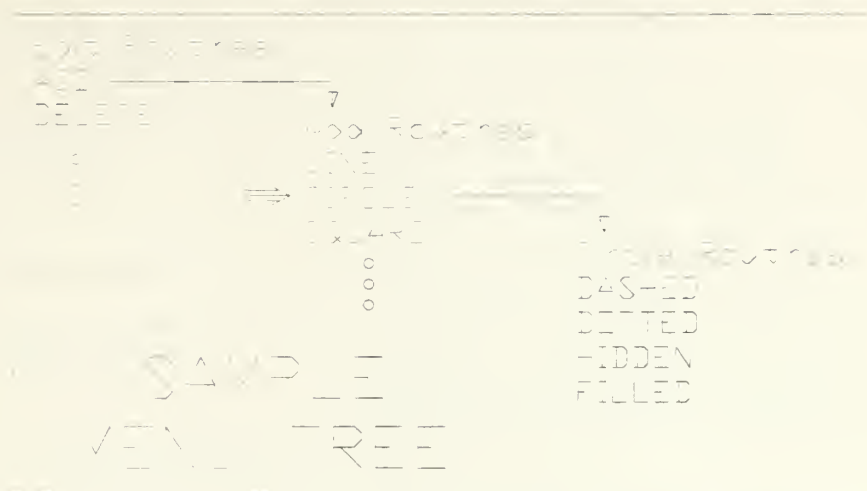


Figure 2.1 - Sample Menu Structure

```

entry_name : CIRCLE
menu_title : Circle Routines
  num_subs : 4
    from : points to LINE entry
    next : points to SQUARE entry
    head : points to Edit Routines entry

```

The storage requirements of a menu are dynamically allocated when the program is called. This allows the menu arrangement to be changed external to the program. For a more in depth discussion of the menu structure used in the program see Chapter 4.

2.5.3 Stats

This structure is used to keep track of the status of external jobs started by this program. It consists of the following elements:

Table 2.5 - Structure : Stats

int colors	The color of a specific entry, where colors are used to code progress of jobs.
char *file_name	Pointer to the name of the externally running program.
char *path_name	Pointer to a string containing the full path of the externally running program.

This data structure will need to be expanded as the routines that check and manage external jobs are completed and added to the editor.

2.5.4 Message

This structure is used to read and write system messages. This is the method used for communication between processes in the editor. With these messages it is possible for the main calling program to keep track of the progress of the externally running programs.

Table 2.6 - Structure : Message

long type	The numerical type identifier of the message.
char text[1024]	The actual message text.

As with the Stats data structure, as the message handling characteristics of the editor are extended this structure will be expanded.

Table 2.9 - Structure : FulSurf

ParSurf *fgeom	Pointer to surface data structure.
struct surfaces *copy_of	Pointer to surface this is a copy of.
struct surfaces *offset_of	Pointer to surface this is an offset of.
char *show_it	Points to a string of 1's and 0's that signify which parts of the structure are to be shown in the various sections of the editor.
char *has_parts	String of 1's and 0's that signify which parts above have been generated.
char *parts_saved	String of 1's and 0's that signify which parts have been saved. The following are the positions in the has_parts and parts_saved strings: 0 : surface (fgeom) 1 : surface (auxiliary data) 2 : curvature values 3 : shaded image 4 : ray traced image 5 : wire frame 6 : open 7 : open 8 : open
char *copy_name	Pointer to the file name where the surface this is a copy of is stored.
char *offset_name	Pointer to the file name where the surface this is an offset of is stored.
char *scurvature	These are all pointers to file names where the given data has been stored.
char *sshaded;	same as above
char *sray_trace;	same as above

char *sgrowth_1;	same as above but for future growth
char *sgrowth_2;	for future growth
char *sgrowth_3;	for future growth
char *sgrowth_4;	for future growth
char *sgrowth_5;	for future growth
char *saved_as;	Pointer to file name where this surface has been saved
char *desc	Pointer to description of this surface.
double2 box[6]	Array of minimum and maximum x, y and z values of the surface control points.
double2 light[3]	Array of light vectors used for making shaded image.
float seelight[3]	Source intensity, azimuthal angle and incident angle of light source. Used in setting light source position routine. After the routine, the values are transformed into light[] values.
int nsegu	The number of segments to be used in the u direction when producing shaded and curvature surfaces.
int nsegv	Same as nsegu but for the v direction.
int npointsu	The number of segments to be used in the u direction when making the wire frame model.
int npointsv	Same as npointsu but for the v direction.
int sys_number	The location of this surface in the system surface array.
float ssee[4]	Perspective values to be used when viewing shaded image alone.

float csee[4]	Perspective values to be used when viewing curvature images.
float ctrans[4]	Translation values to be used when viewing curvature images.
float strans[4]	Translation values to be used when viewing shaded image alone.
int port[4]	Viewport values used to view images.
int color	Color to be used when producing shaded image and wire frame.
Object obj[9]	Array for objects generated during the various portions of the editor.
Object key[9]	Color keys for the objects generated.
char *have_obj	String of 1's and 0's that signifies which objects above have been generated. The following positions are used in the obj and key arrays and in the have_obj string: <ul style="list-style-type: none"> 0 : wire frame 1 : shaded image 2 : Gaussian curvature 3 : mean curvature 4 : absolute curvature 5 : maximum principal curvature 6 : minimum principal curvature 7 : normal U curvature 8 : normal V curvature
double2 ***curv	Curvature values along the u and v directions. Curvatures K1, K2, normal U and normal V are stored for later use.
double2 ***pt	Three dimensional array of calculated points lying on the actual surface.

double2 ***norms	Normals at the points on the surface stored in pt array.
int **intensity	Intensity values at points on the surface. Each intensity value translates into a specific color for the shaded image.

2.6 File Naming Conventions

Because many external programs will be used with the editor and the primary method of passing information between these programs will be through data files, a file naming convention must be adopted so that the history of a file can be somewhat extracted from the name. This will help users go from one session of the editor to the next.

If a curve or surface is started from scratch, the user will be prompted for the file name without any extension, for example **surface_1**. The program will append the extension 'base' to the name entered, making the complete file name **surface_1.base**. This basic name will be used throughout all operations on this surface or curve.

As operations are performed on this curve or surface, the program will append additional extensions onto the file name as needed. For instance, if the surface is shaded, the shaded surface file will be named **surface_1.shade** and if the surface has the curvature mapping done, the name of the map will be **surface_1.map**.

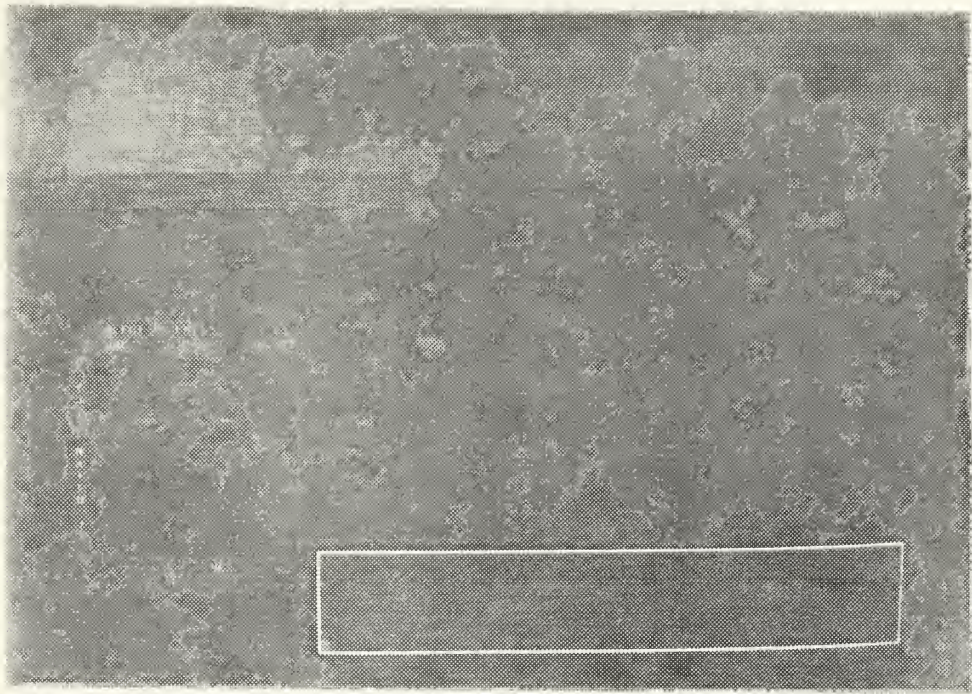


Figure 7.32 - Move : After Move

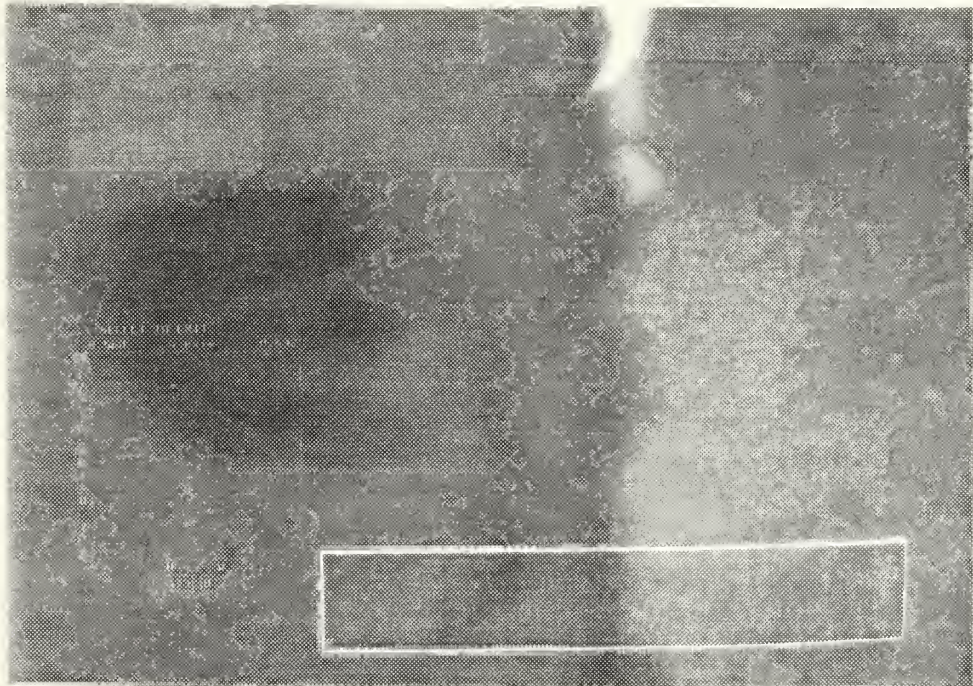


Figure 7.33 - Delete : After Selection, Before Deletion

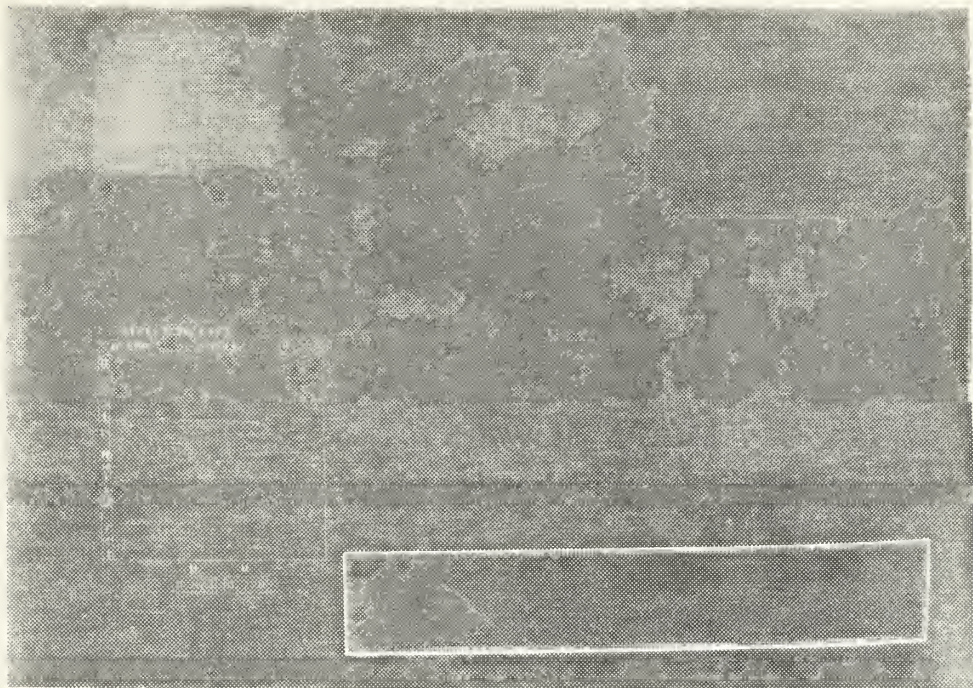


Figure 7.34 - Delete : After Deletion

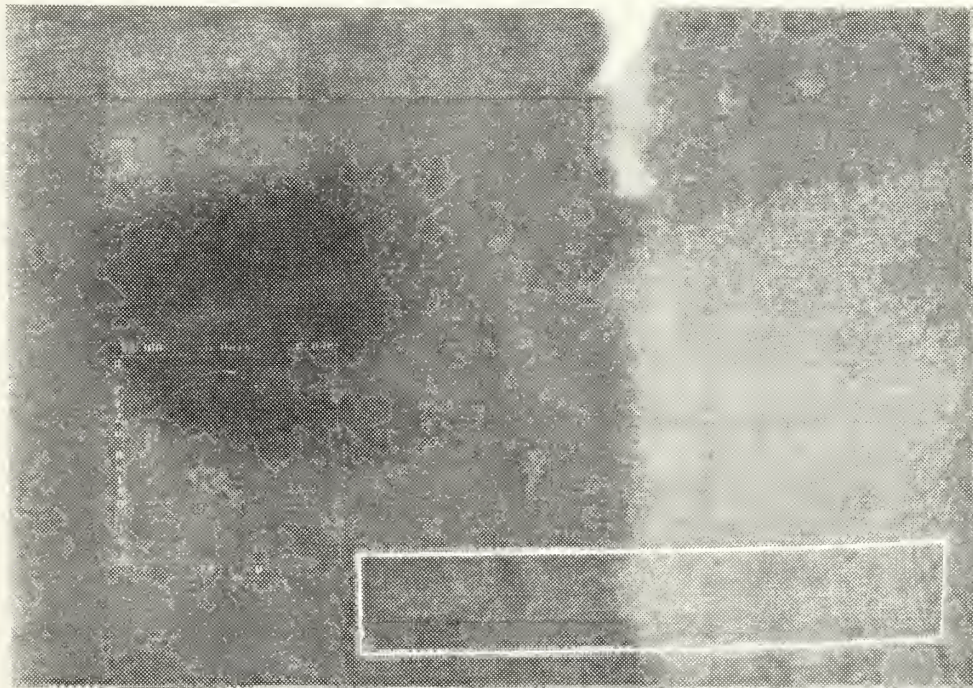


Figure 7.35 - Curve Fit Drawn With 25 Steps

7.4.7 Fit Of Points and Step Size

Once all points have been entered and edited as desired, the user can fit a fourth order B-spline curve through the points. This curve interpolates all the data points. If this does not appear to be the case it is because the number of steps chosen to display the curve is too small. Setting the number of steps to a larger value will fix this visualization problem. Figures 7.35 and 7.36 show the same curve using 25 and 100 steps.

7.4.8 Making a System Curve and Quitting

When the fit operation is complete, the user could make a system curve and then quit the menu. Care has been taken to ensure data entered into the system is not lost accidentally. If the quit routine is chosen before saving the current data set, the user is prompted as shown in Figure 7.37 and positive action must be taken to continue on in the editor.

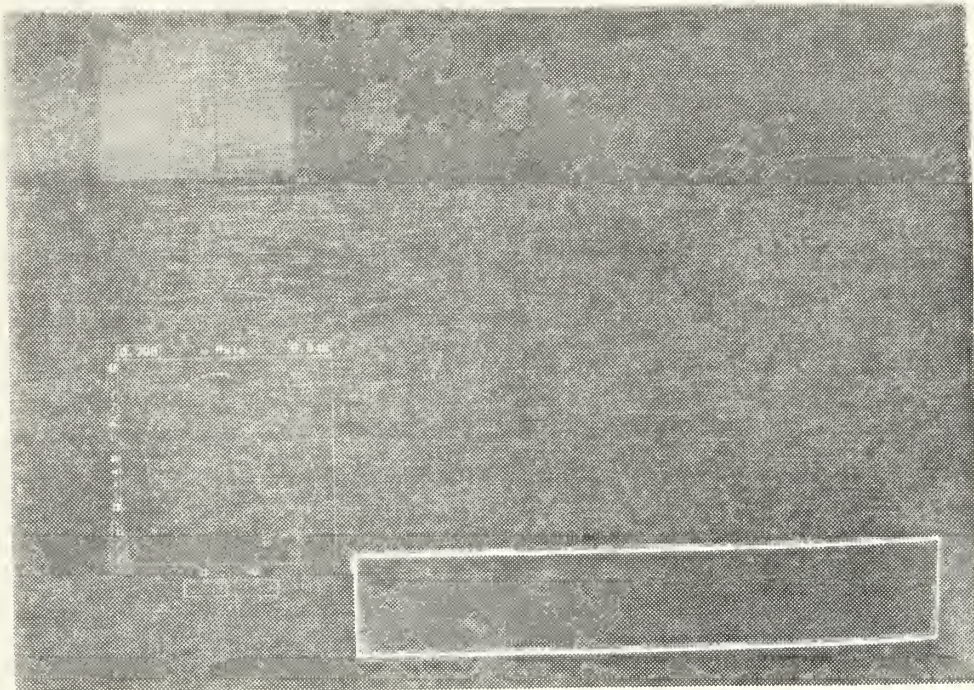


Figure 7.36 - Curve Fit Draw with 100 Steps

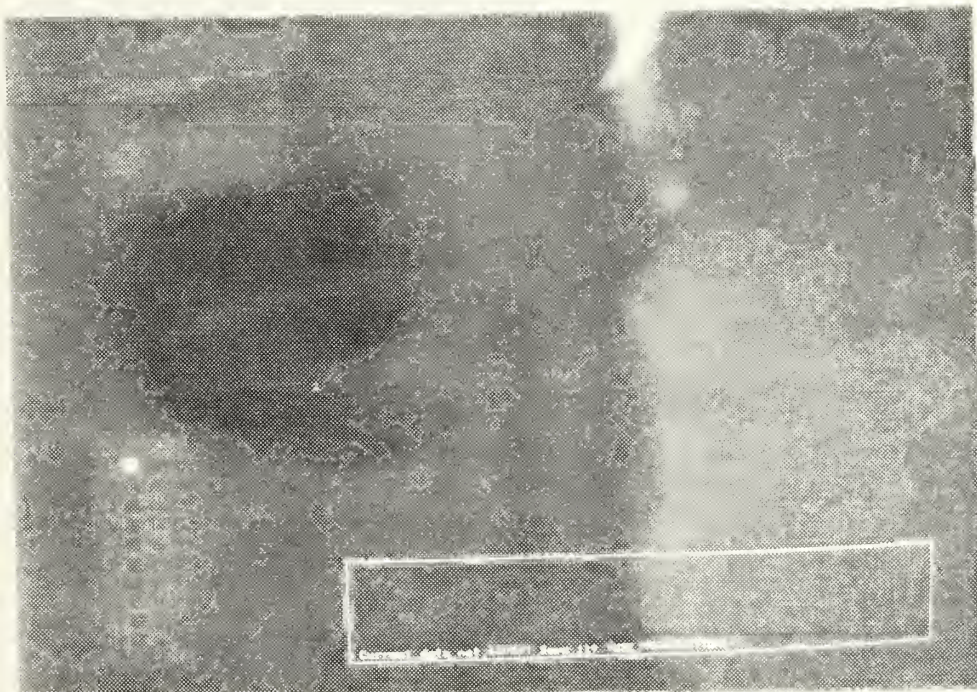


Figure 7.37 - Data Saving Prompt

7.5 Curve Operations - Fairing

Once the designer is satisfied with the points entered for the curve, the , , routine would be called to ensure the curve is sufficiently smooth for use. The various options in the area are discussed below.

7.5.1 Actual Fairing

When the fairing routine is first entered a copy is made of the curve and a curvature map of both curves is given on a split screen presentation. These maps are called porcupines for obvious reasons. The designer can fair the curve on the lower screen. Fairing can be done manually or automatically.

7.5.2 Setting the Scale

The scale of the porcupines can be set to bring all curvatures into view. Figure 7.38 shows the screen upon first entering the fairing routine and Figure 7.39 shows the same presentation but with a scale of 0.1 .

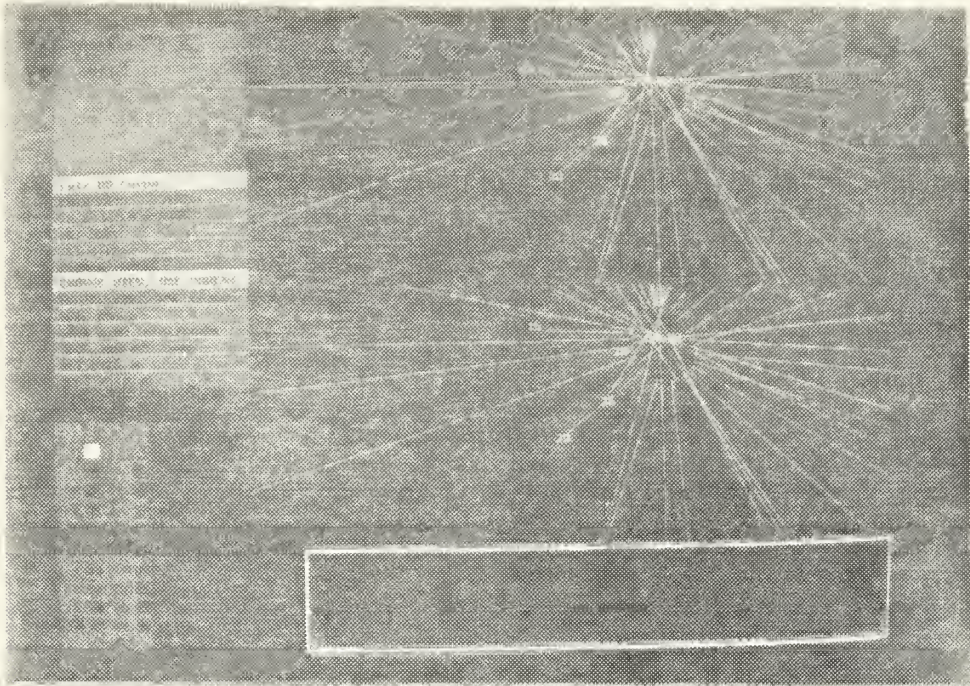


Figure 7.38 - Initial Fairing Screen Presentation

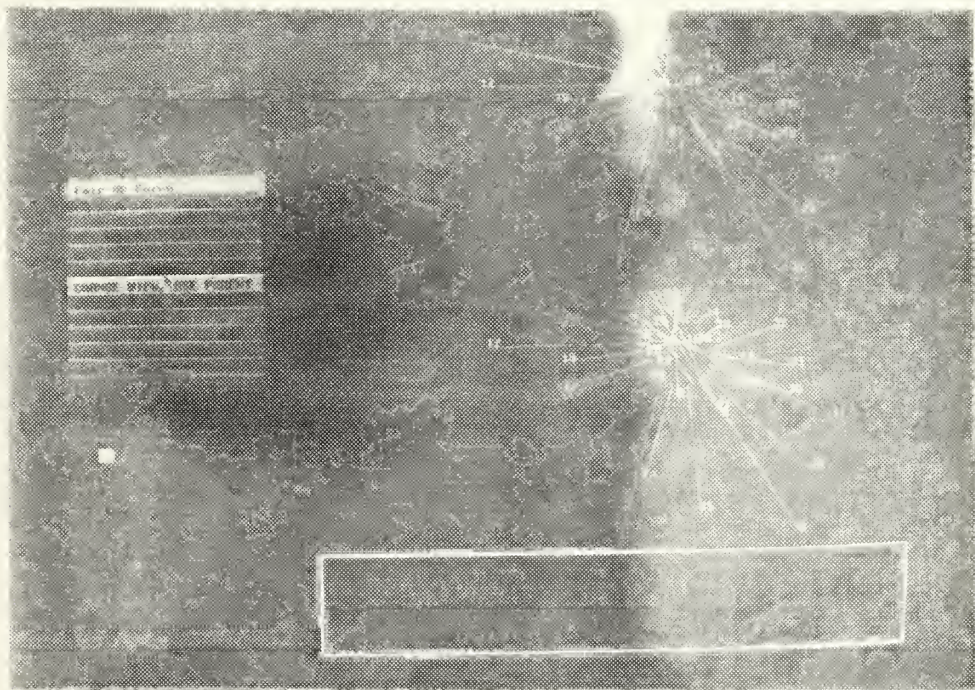


Figure 7.39 - Fairing Screen With Scale of 0.1

7.5.3 Porcupine View

As the designer fairs the lower curve, the curvature values will change causing the porcupine to change. After fairing has progressed the user may see the changed presentation of Figure 7.40. To get a better idea of the porcupine details, the view of the parent and child porcupines can be changed as desired. The routine for changing the view works as previously discussed in Chapter 7.3.1. Figure 7.41 shows the screen after changing the view.

7.5.4 Curve on Wire Frame

Once the curve is sufficiently fair, the designer can have a wire frame of the surface of interest and the curve displayed at the same time. This is shown in Figure 7.42. As with other presentations, the wire frame and curve viewing position can be changed to suit the designer and Figure 7.43 shows the curve and surface in Figure 7.42 after such a view change.

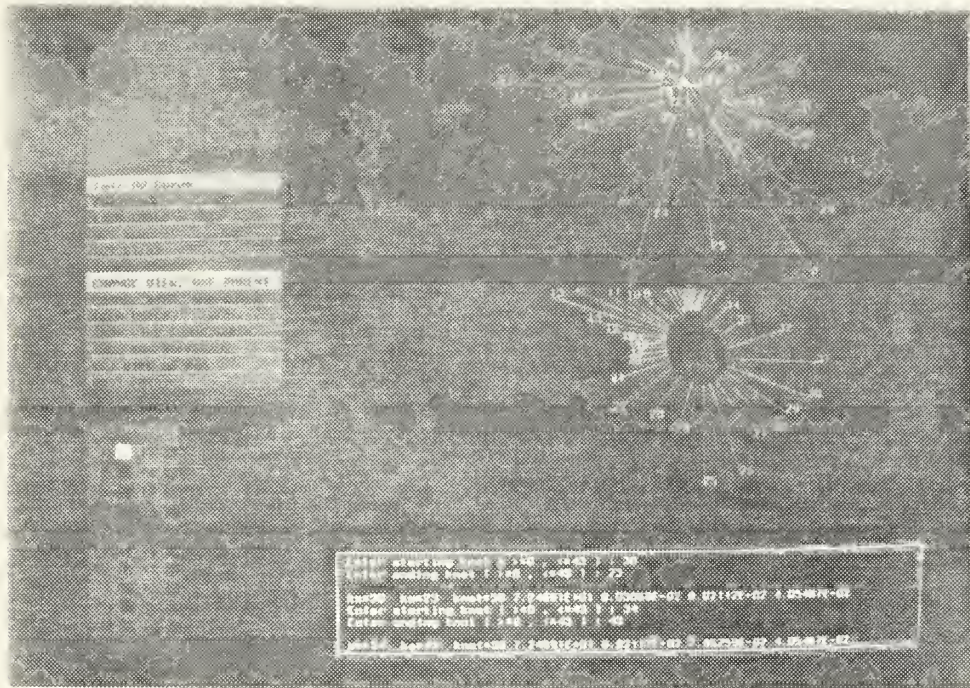


Figure 7.40 - Parent and Child Curves : After Firing

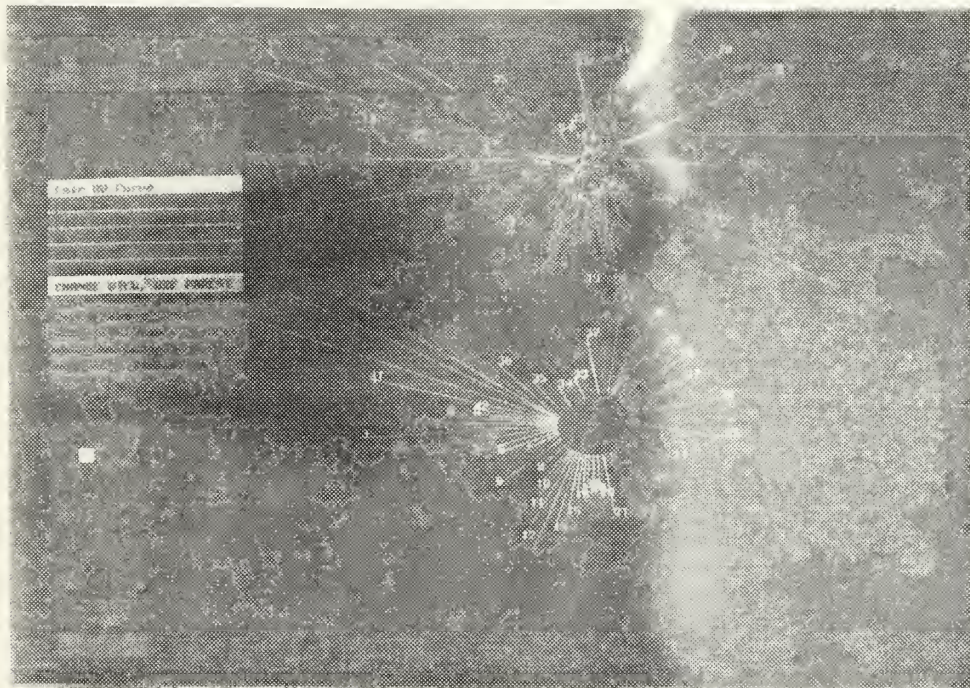


Figure 7.41 - View Change of Burstable Curves

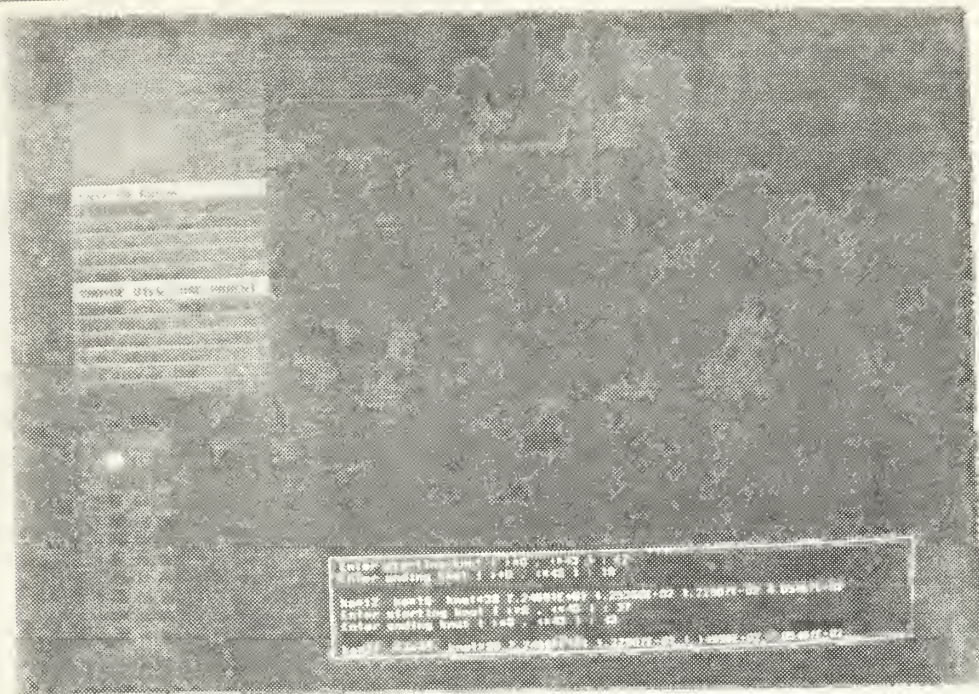


Figure 7.42 - Faired Curve in Surface Wire Frame

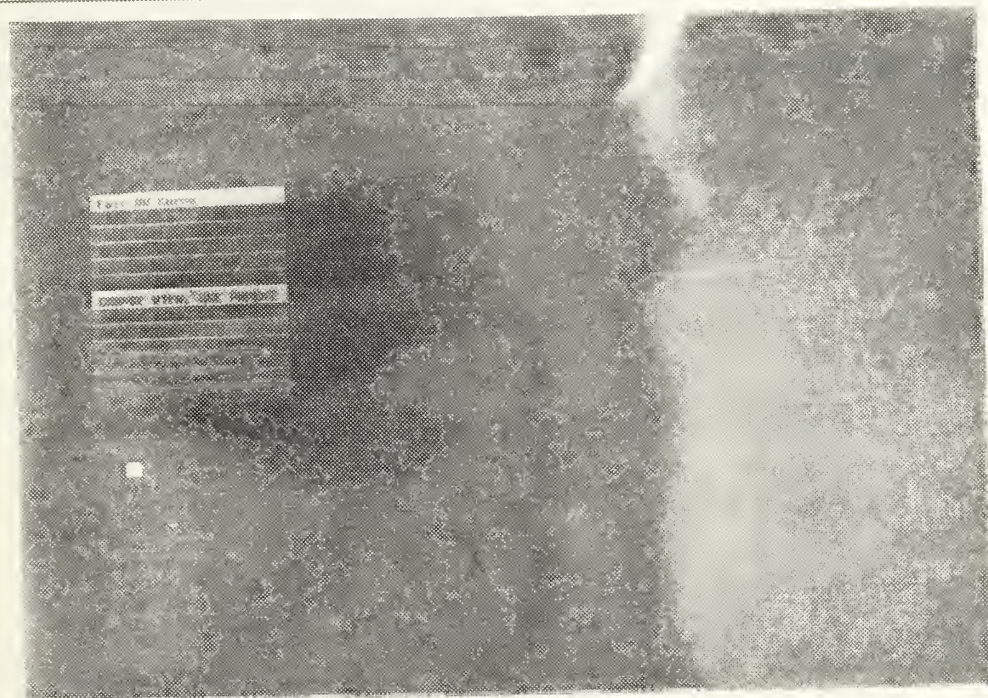


Figure 7.43 - Curve and Wire Frame : Transformed View

If the curve can not be faired to suit the designer, the fairing routine can be exited and the points in the U-V space changed as necessary. This type of movement through the editor is to be expected during the design process. Once the curve is sufficiently smooth and the presentation of the curve on the surface is acceptable, the child curve can be saved and the editor session can continue with another problem.

7.6 Open Parametric Curve

The example given above for curve fairing used a periodic curve. The editor will also accept open curves. Figure 7.44 shows an example of an open curve in the parametric space. Figures 7.45 and 7.46 show this curve before and after fairing. Figure 7.47 shows this curve with the same surface and viewport as used in Figure 7.43.

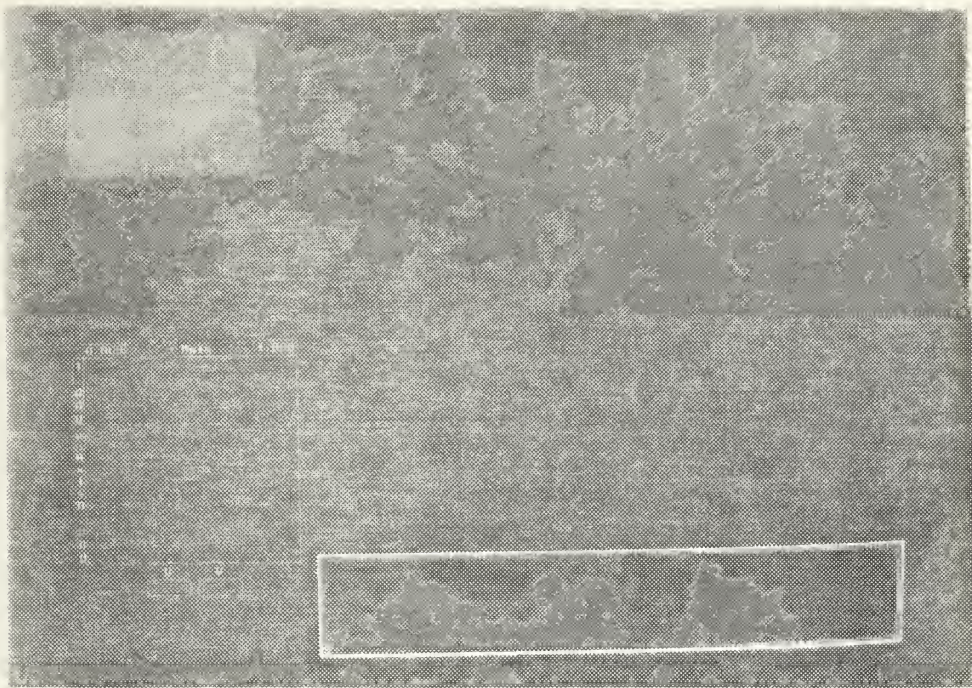


Figure 7.44 - Open Curve in Parametric Space

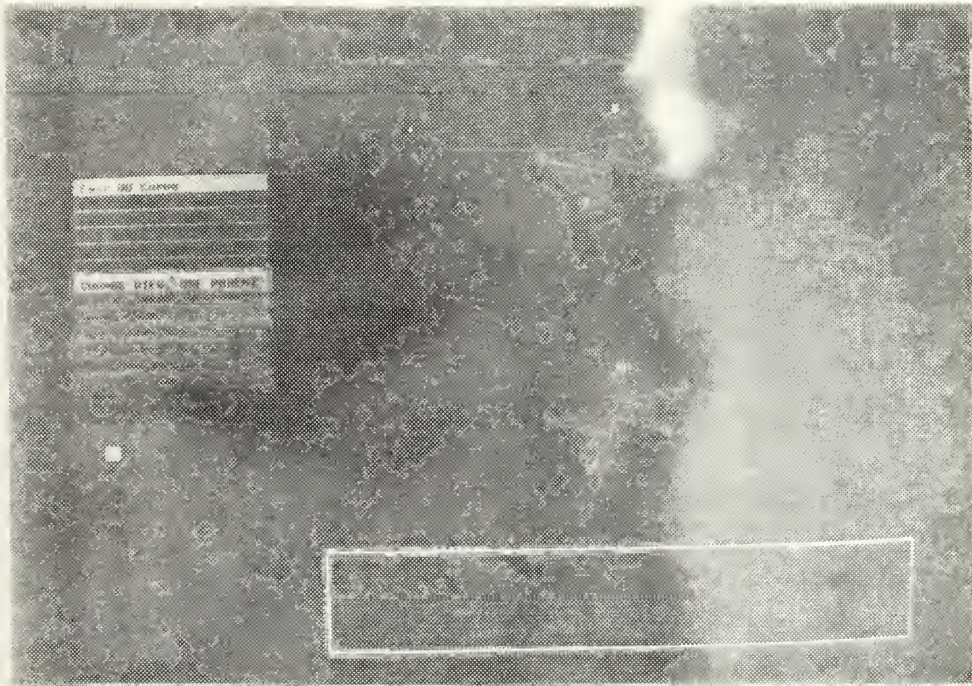


Figure 7.45 - Open Curve : before the End

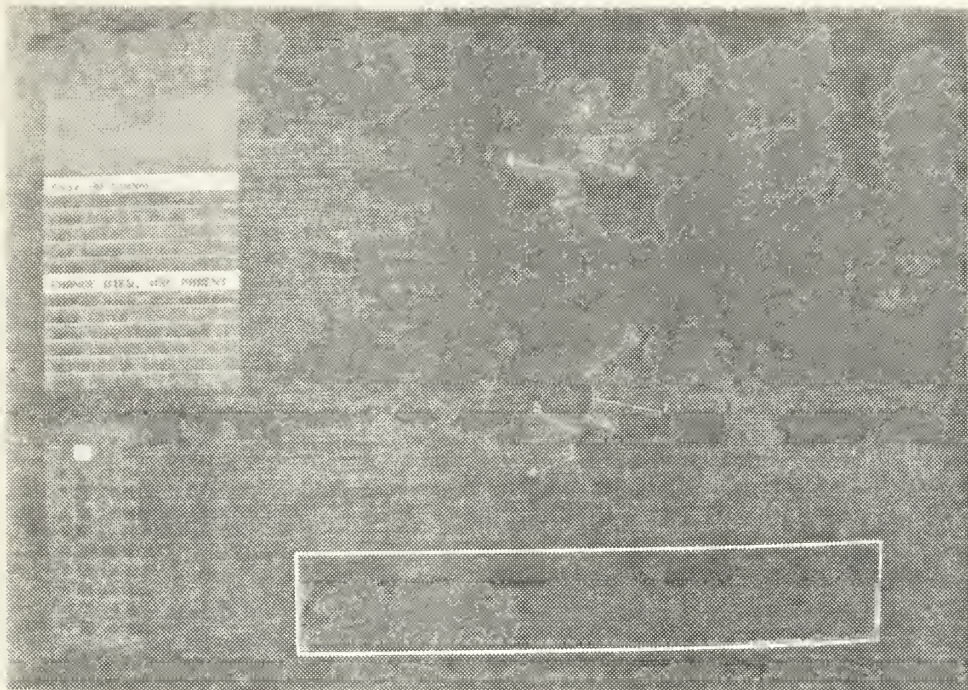


Figure 7.46 - Open Curve : After Fairing

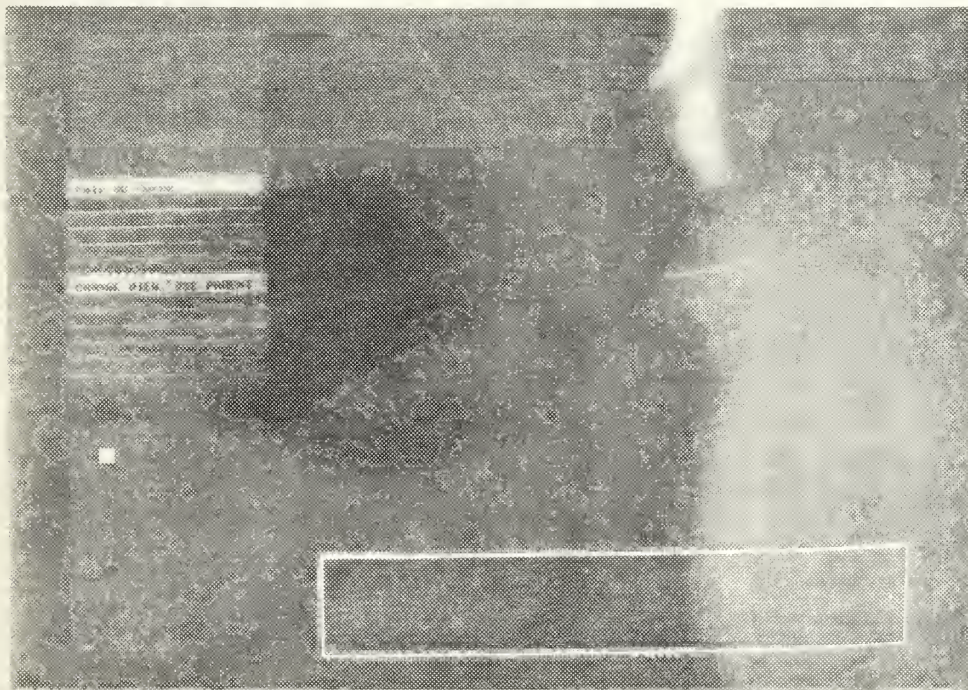


Figure 7.47 - Open Curve on Surface With Frame

CHAPTER 8 SUMMARY

The previous chapters have discussed the general idea behind the development of the editor, including the need for such an editor and the structure of both the data files and menu arrangements. Examples were given on how to expand the editor to include all the functions listed in the menus. Finally, a pictorial example of the use of the current editor was given.

Future development on the editor should address the continued interfacing of new modules. In addition to this expansion, there are a few enhancements to the modules already interfaced from which the user would benefit. The following are some of these enhancements:

1. Allow the user to enter specific segmentation values greater than 32.
2. Add a call to segmentation routine from within the shading and curvature menus.
3. Allow the step size in the translation and distance portion of the view setting routine to be user selectable and variable.
4. Allow the user to set the color of the background to values other than black and white.
5. Increase the size of the parameter space data input to the larger, 3-D portion of the screen.

6. List applicable data files and allow user to select from the list with the mouse or enter name manually if desired.

These are but some of the enhancements that can be implemented to make the editor even more user friendly. As the editor is used by more designers there will be many more additions and enhancements that need to be made. This is the nature of any program - the more it is used, the more the user will want. It is because of this that the editor was designed for easy additions and changes.

CHAPTER 9 REFERENCES

- [1] Patrikalakis, N. M., Bardis, L. and Kriezis, G. A.
Approximate Conversion Of Rational B-Spline Curves and
Surfaces Patches. Design Laboratory Memorandum No.
88-5, July, 1988.
- [2] Curry, H. B., and Schoenberg, I. J.
On the Polya Frequency Functions IV: The Fundamental
Spline Functions and their Limits. *Journal d'Analyse
Mathematique*, 17:71-107, 1966.
- [3] De Boor, C.
On Calculating with B-Splines. *Journal of Approxima-
tion Theory*, 6:50-62, 1972.
- [4] Cox, M. G.
The Numerical Evaluation of B-Splines. *Journal of the
Institute for Mathematics Applications*, 10:134-149,
1972.
- [5] Tiller, W.
Rational B-Splines for Curve and Surface Representa-
tion. *IEEE Computer Graphics and Applications*,
3(6):61-69, September, 1983.
- [6] IRIS User's Guide, Volume 1, Programming Guide, Ver-
sion 4.0, Document Number 007-1101-040, Silicon Graph-
ics, Inc., Mountain View, CA, 1987.

- [7] Alourdas, P. G.
Shape Creation, Interrogation and Fairing Using B-Splines. Naval Engineer's Thesis, Massachusetts Institute of Technology, Cambridge, Massachusetts, May, 1989.
- [8] Thomas, R., Rogers, L. R., and Yates, J. L.
Advanced Programmer's Guide To UNIX System V. Osborne McGraw-Hill, Berkeley, CA, 1986.
- [9] Kernighan, B. W., and Ritchie, D. M.
The C Programming Language, 2nd Edition. Prentice-Hall, Englewood Cliffs, NJ, 1988.

CHAPTER 10 APPENDICES

10.1 MAIN MENU DATA FILE

The following file is used to set up the main menu of the editor. Additions and changes discussed in Chapter 6 are indicated by bullets, . As discussed previously the indentation scheme is not required but it is suggested that it be used to add clarity in the presentation of long data files. Also, for a clearer presentation the data file has larger spacing between the different menu items that would be the actual case in the data file. THERE CAN BE NO BLANK LINES IN THE DATA FILE.

```
5 _____(F)
MAIN MENU
Main Menu Routines
N50
_____ (E)
  9
  INPUT ROUTINES
  Input Menu Routines
  N9
    4
    CURVE (3-D)
    3-D Curve Input Routines
    N0
      1
      ENTER FROM KEYBOARD
      V0
      1
      RECALL FROM LOCAL FILE
      V1
      1
      RECALL IGES FILE
      V2
      1
      INTERACTIVE INPUT
      V3
```


4
SURFACE
Surface Input Routines
N1

1
ENTER FROM KEYBOARD
V4

1
RECALL FROM LOCAL FILE
V5

1
RECALL IGES FILE
V6

1
INTERACTIVE INPUT
V7

3
CURVE ON SURFACE
Curve On A Surface Data
N2

1
ENTER FROM KEYBOARD
V8

1
RECALL FROM LOCAL FILE
V9

1
RECALL IGES FILE
V10

2
ALGEBRAIC SURFACE
Algebraic Surface Inputs
N3

1
ENTER FROM KEYBOARD
V11

1
RECALL FROM LOCAL FILE
V12

2
ID OF POINTS
Grid Of Points Input
N4

1
ENTER FROM KEYBOARD
V13

1
RECALL FROM LOCAL FILE
V14

2
FUNCTION ON CURVE
Function On A Curve Menu
N5

1
ENTER FROM KEYBOARD
V15

1
RECALL FROM LOCAL FILE
V16

3
LIST OF POINTS
List Of Points Input Menu
N6

1
ENTER FROM KEYBOARD
V17

1
RECALL FROM LOCAL FILE
V18

1
INTERACTIVE INPUT
V19

2
LIST OF LISTS
List Of Lists Input Menu
N7

1
RECALL FROM LOCAL FILE
V20

1
INTERACTIVE INPUT
V21

3
LIST OF POINTS (3-D)
List Of Points (3-D)
N8

1
ENTER FROM KEYBOARD
V22

1
RECALL FROM LOCAL FILE
V23

1
INTERACTIVE INPUT
V24

4 _____ (K)
GEOMETRY GENERATION
GEO Generation Routines
N15

_____ (J)
4
CURVES
Curve Generation Menu
N10

1
FIT POINTS IN 3-D
V25

1
APPROXIMATE WITH NURBS
V26

1
OFFSET OF A PLANAR CURVE
V27

1
OFFSET NORMAL TO PATCH
V28

5
SURFACES
SUR Generation Routines
N11

1
OFFSET OF ANOTHER SURFACE
V29

1
RULED SURFACE
V30

1
FIT/APPROX n ISOPARAMETER
V31


```
1
FIT/APPROX GRID OF POINTS
V32

1
CONVERT ALG TO NURBS
V33

3
CURVE ON SURFACE
COS Generation
N12

1
FIT/APPROX LIST OF POINTS
V34

1
FIT/APPROX LIST OF LISTS
V35

1
VAR OFFSET OF ANOTHER
V36

4
BLEND
Blend Generation
N14

3
BOUNDARY CONDITIONS
Blend Boundary Conditions
N13

1
POSITION
V37

1
NORMAL
V38

1
CURVATURE
V39

1
DEFINE SURFACE
V40

1
DEFINE CURVES
V41
```


1
EXECUTE BLEND
V42

3
GEOMETRY INTERROGATION
Geometry Interrogation
N36

3
CURVES
Curve Interrogation
N19

3
VISUALIZATION
Curve Visualization
N16

1
RESOLUTION
V43

1
COLOR
V44

1
VIEWPOINT
V45

2
CURVATURE VALUES
Curvature Map Values
N17

1
RESOLUTION
V46

1
SHOW CURVATURE MAP
V47

2
STATUS
Curve Status
N18

1
ON
V48

1
OFF
49

3
VISUALIZATION
Visualization Routines
N24

1
RESOLUTION
V57

1
COLOR
V58

1
VIEWPOINT
V59

4
PLANE CONTOURS
Plane Contours Menu
N25

1
SET # PLANES
V60

1
SET START PLANE
V61

1
SET PLANE DISTANCE
V62

2
INTERSECTION ACCURACY
Intersection Accuracy
N26

1
2_D
V63

1
3_D
V64

4
CYLINDER CONTOURS
Cylinder Contours
N27

1
SET # CYLINDERS
V65

1
SET START CYLINDER
V66

1
CYLINDER DISTANCE
V67

2
INTERSECTION ACCURACY
Intersection Accuracy
N28

1
2_D
V68

1
3_D
V69

5 _____ B
SHADED IMAGE
Shaded Image Routines
N29

1
READ IMAGE
V70

1
CALCULATE IMAGE
V71

1
COLOR
V72

1
SET LIGHT SOURCE
V73

_____ A
1
VIEW
V74

3
RAY TRACE
Ray Trace Routines
N30

1
READ TRACE
V75

1
CALCULATE TRACE
V76

1
SET COLOR
V77

10 ————— H
CURVATURE
Curvature Routines
N31

1
READ CURVATURE
V78

1
CHANGE VIEW
V87

————— G
1
ALL CURVATURES
V79
1
GAUSSIAN
V80
1
MEAN
V81
1
ABSOLUTE
V82
1
MAXIMUM PRINCIPLE
V83
1
MINIMUM PRINCIPLE
V84
1
NORMAL U
V85
1
NORMAL V
V86

I

4
ISOPHOTES
Isophote Routines
N32

1
SET NUMBER
V88

1
READ ISOPHOTE
V89

1
CALCULATE ISOPHOTE
V90

1
SHOW ISOPHOTE
V91

4
REFLECTION LINES
Reflection Lines
N33

1
SET NUMBER
V92

1
READ IN LINES
V93

1
CALCULATE LINES
V94

1
SHOW LINES
V95

3
GEODESICS
Geodesics Routines
N34

1
READ IN
V96

1
CALCULATE
V97

1
SHOW
V98

1
SURFACE ON/OFF
V99

4
GEOMETRY PROCESSING
Geometry Processing
N49

6
CURVES
Curves Processing
N39

3
APPROXIMATE NURBS
Approximate NURBS
N37

1
SET ORDER
V100

1
SET ACCURACIES
V101

1
RUN
V102

3
FAIRING
Fair Curve
N39

1
KNOT
V103

1
AUTOMATED
V104

1
RUN
V105

1
CTRL PT EDIT
V106

1
EXACT DEGREE
V107

1
SUBDIVIDE
V108

1
SPLIT CURVE
V109

5
COS PROCESSING
Curve On Surface
N43

2
CONVERT COS TO NURBS
Convert Curve On Surface
N41

3
SET ACCURACIES
Accuracy Setting
N40

1
POSITION
V110

1
CURVATURE
V111

1
SLOPE
V112

1
RUN CONVERT
V113

1
FAIRING
V114

1
EDITING
V117

1
SUBDIVIDE IN UV
V118

1
SPLIT IN UV
V119

6
SURFACE PROCESSING
Surface Processing
N47

2
APPROXIMATE NURBS
Approximate With NURBS
N45

1
SET ORDER
V120

3
SET ACCURACIES
Set Accuracies
N44

1
POSITION
V121

1
CURVATURE
V122

1
SLOPE
V123

3
FAIRING
Surface Fairing
N46

1
KNOT
V124

1
AUTOMATED
V125

1
RUN FAIRING
V126

1
EDITING
V127

1
DEGREE ELEVATION
V128

1
SUBDIVIDE
V129

1
SPLIT
V130

2
INTERSECTIONS
Intersections
N48

1
LISTS 2_D
V131

1
LISTS 3_D
V132

1
QUIT
V133

0
END MENU

10.2 UV_MENU.DAT DATA FILE

13

FIT/APPROX LIST OF POINTS

COS - Fit UV Pts w/ NURBS

N53

1

INPUT UV POINTS

V141

1

OUTPUT UV POINTS

V142

1

SHOW UV POINTS

V150

1

ADD UV POINTS

V143

1

INSERT UV POINTS

V144

1

DELETE UV POINTS

V145

1

MOVE UV POINTS

V146

1

SELECT WINDOW

V147

1

FIT POINTS

V148

1

MAKE SYSTEM CURVE

V151

1

SET STEPS

V158

1

START AGAIN

V161

1
QUIT
V149

0
END MENU


```
LIB1 = rgl2  
LIB2 = oegl50
```

```
OBJECTS = main.o $(OBJECTS1) $(OBJECTS2) $(OBJECTS3)
```

```
menu: Makefile $(OBJECTS)
```

```
    f77 -g -o mainmenu $(OBJECTS) $(LIB) -l$(LIB1) -lm -lnag
```

```
$(OBJECTS1): $(ROOT)/thesis1/struct.h
```

```
$(OBJECTS1): $(ROOT)/thesis1/hottel.h
```

```
$(OBJECTS2): $(ROOT)/thesis1/struct.h
```

```
$(OBJECTS): $(ROOT)/thesis1/defines.h
```

```
$(MESSAGES): $(ROOT)thesis1/msg.h
```

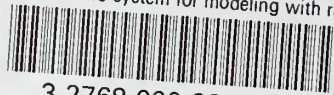

Thesis
H8142 Hottel
c.1 An executive for
modeling with rational
B-splines.

Thesis
H8142 Hottel
c.1 An executive for
modeling with rational
B-splines.



thesH8142

An executive system for modeling with ra



3 2768 000 82194 6

DUDLEY KNOX LIBRARY