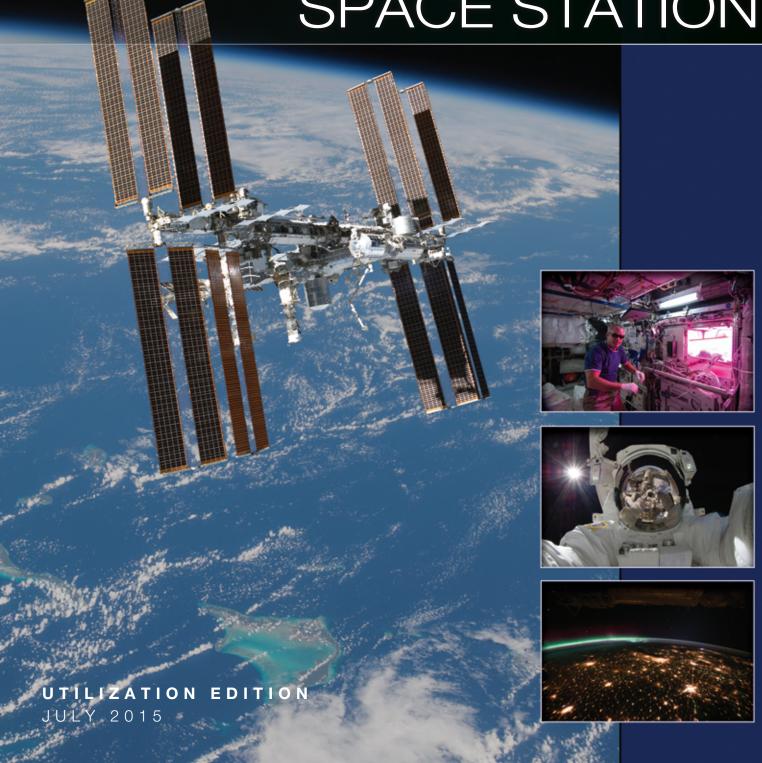


REFERENCE GUIDE TO THE INTERNATIONAL SPACE STATION



INTERNATIONAL SPACE STATION

UTILIZATION EDITION

JULY 2015

FRONT COVER: Images from top to bottom: 1. NASA astronaut Steve Swanson is photographed near the Veggie facility in ExPRESS (Expedite the Processing of Experiments to Space Station) Rack 3 (ER3) during Veg-01 experiment initialization.

2. Japan Aerospace Exploration Agency astronaut Aki Hoshide snaps a selfie, while in the midst of completing repairs on the ISS. In his visor you can see the robotic arm and the reflection of earth, while the sun shines behind him. 3. View of the Midwestern United States city lights at night with Aurora Borealis.

MESSAGE FROM THE PROGRAM MANAGER BACKGROUND:

The night lights of cities in North and South America glow in this image captured by the Suomi NPP satellite and mapped over existing imagery of Earth. The Suomi NPP satellite has a Visible Infrared Imaging Radiometer Suite which allows it to detect light in a range of wavelengths from green to near-infrared and uses filtering techniques to observe dim signals such as city lights, gas flares, auroras, wildfires and reflected moonlight. This image provides new meaning to the Earth being a spaceship traveling through the darkness and overwhelming expanse of space.

Reference guide to the International Space Station. – Utilization Edition. NP-2015-05-022-JSC

A World-Class Laboratory in Space

I am pleased to provide this 2015 International Space Station (ISS) Reference Guide, Utilization Edition. The unique environment of space and the full capabilities of the ISS are available for innovative commercial use, including academic and government research. In this edition, we provide an overview of the ISS, describe its research facilities and accommodations, and provide key information to conduct your experiments on this unique orbiting laboratory.



As of this writing, NASA and the space agencies of Russia, Japan, Europe and Canada have hosted investigators from 83 nations to conduct over 1700 investigations in the long-term micro-gravity environment on-board the ISS. Many investigators have published their findings and others are incorporating findings into follow-on investigations on the ground and onboard. Their research in the areas of earth and space science, biology, human physiology, physical sciences, and technology demonstration will bring yet to be discovered benefits to humankind and prepare us for our journey beyond low Earth orbit.

While ISS has proven its value as a platform for a broad waterfront of research disciplines and technology development for exploration, NASA and the Center for the Advancement of Science in Space (CASIS), are providing an ideal opportunity to test new business relationships. One that allows a shift from a paradigm of government-funded, contractor-provided goods and services to a commercially provided, government-as-a-customer approach. From commercial firms spending some of their research and development funds to conduct applied research on the ISS, to commercial service providers selling unique services to users of the orbiting lab, the beginnings of a new economy in LEO are starting to emerge.

Please enjoy this latest iteration of the ISS Reference Guide and its focus on conducting pioneering science in micro-gravity. Herein we cover current capabilities, but the ISS is an extremely flexible platform. I invite you to use the additional resources listed in the back of this guide to learn more and I hope to work with you to conduct your experiment onboard the ISS soon. Please let us know if you have other needs to support your use of this amazing platform.

Sincerely,

MICHAEL T. SUFFREDINI ISS Program Manager

Research/Research Accomodations	8
The Lab is Open - Unique Features of the ISS Research Environment	9
Destiny Racks	10
Kibo Racks	11
Columbus Racks	12
Internal Research Accommodations	13
External Research Accommodations	14
Biological Sciences and Biotechnology	15
Human Research	18
Physical Sciences	19
Earth and Space Science	21
Technology Demonstrations	23
Commercial Development	24
Education	25
Elements and Support Systems	26
U.S. Laboratory Module Destiny	27
European Research Laboratory Columbus	28
Japanese Experiment Module Kibo (Hope)	29
Nodes Nade 1 Heits	30
Node 1 Unity	31 32
Node 2 Harmony Node 3 Tranquility	33
Joint Airlock Quest	34
Cupola	35
Permanent Multipurpose Module (PMM)	36
Functional Cargo Block (FCB) Zarya (Sunrise)	37
Docking Compartment (DC) Pirs (Pier)	38
Mini-Research Module 2 (MRM2) Poisk (Explore)	39
Mini-Research Module 1 (MRM1) Rassvet (Dawn)	40
Service Module (SM) Zvezda (Star)	41
Pressurized Mating Adapters (PMAs)	42
Habitation	43
Environmental Control and Life Support System (ECLSS)	44
Crew Health Care System (CHeCS)	45
Computers and Data Management	46
Extravehicular Mobility Unit (EMU)	47
Orlan Spacesuit	48
Mobile Servicing System (MSS)	49
Electrical Power System (EPS)	50
Guidance, Navigation and Control (GN&C)	51
Thermal Control System	52
Integrated Truss Assembly	53
Propulsion	54
Communications	55
Micrometeoroid and Orbital Debris (MMOD) Protection	56

Contents

International Partnership	57
ISS Operations and Management	58
Canada	60
Europe	61
Japan	62
Russia	63
United States of America	64
Soyuz	66
Progress	67
JAXA H-II Transfer Vehicle (HTV)	68
Space Shuttle Orbiter/Columbia, Discovery, Atlantis, Endeavour	69
Automated Transfer Vehicle (ATV)	70
Commercialization	71
Requirements and Benefits	72
Antares and Cygnus	73
Falcon 9 and Dragon	74
Assembly	75
ISS Expanded View	76
Principal Stages in Construction	78
Missions	88
ISS Expeditions and Crews	89
STS Missions and Crews	95
Soyuz ISS Missions	101
Unmanned ISS Missions	106
Reference	109
To Learn More	110
Acronym List	111
Definitions	114



The International Space Station (ISS) is a unique scientific platform that enables researchers from all over the world to put their talents to work on innovative experiments that could not be done anywhere else. Although each space station partner has distinct agency goals for station research, each partner shares a unified goal to extend the resulting knowledge for the betterment of humanity. Through advancing the state of scientific knowledge of our planet, looking after our health, developing advanced technologies and providing a space platform that inspires and educates the science and technology leaders of tomorrow, the benefits of the ISS will drive the legacy of the space station as its research strengthens economies and enhances the quality of life here on Earth for all people.

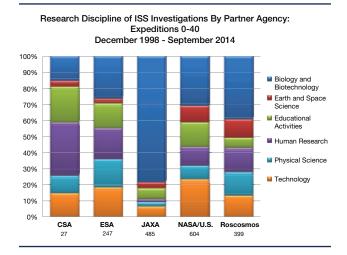
The Lab Is Open

Unique Features of the ISS Research Environment

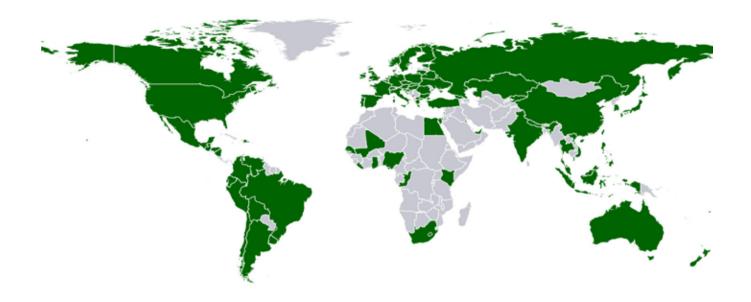
Microgravity, or weightlessness, alters many observable phenomena within the physical and life sciences. Systems and processes affected by microgravity include surface wetting and interfacial tension, multiphase flow and heat transfer, multiphase system dynamics, solidification, and fire phenomena and combustion. Microgravity induces a vast array of changes in organisms ranging from bacteria to humans, including global alterations in gene expression and 3-D aggregation of cells into tissue-like architecture.

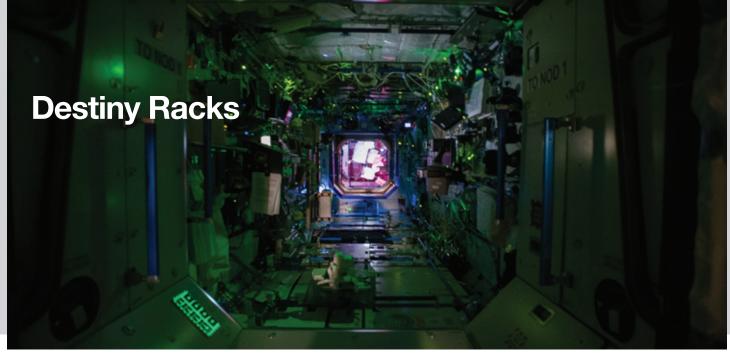
Extreme conditions in the ISS space environment include exposure to extreme heat and cold cycling, ultra-vacuum, atomic oxygen, and high energy radiation. Testing and qualification of materials exposed to these extreme conditions have provided data to enable the manufacturing of long-life reliable components used on Earth as well as in the world's most sophisticated satellite and spacecraft components.

Low-Earth orbit at 51 degrees inclination and at a 90-minute orbit affords ISS a unique vantage point with an altitude of approximately 240 miles (400 kilometers) and an orbital path over 90 percent of the Earth's population. This can provide improved spatial resolution and variable lighting conditions compared to the sun-synchronous orbits of typical Earth remotesensing satellites.



Through Expedition 40, 83 countries and areas (highlighted in green) have been involved in ISS Research and Educational activities





This view in the International Space Station is looking into the Destiny Laboratory from Node 1 (Unity) with Node 2 (Harmony) in the background.

EXPRESS Rack 1



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

EXPRESS Rack 2



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

EXPRESS Rack 6



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

EXPRESS Rack 7



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

Combustion **Integrated Rack** (CIR)



Used to perform sustained, systematic combustion experiments in microgravity.

Fluids Integrated Rack (FIR)



A complementary fluid physics research facility designed to accommodate a wide variety of microgravity experiments.

Materials Science Research Rack-1 (MSRR-1)



Accommodates studies of many different types of materials.

Microgravity **Science Glovebox** (MSG)



A dedicated science facility that provides a sealed environment to perform many different types of small "glovebox" sized experiments.

Window Observational Minus Eighty-Degree **Research Facility** (WORF)



Provides a facility for Earth science research using the Destiny science window on the ISS.

Laboratory Freezer for ISS (MELFI-3)



A refrigerator/freezer for biological and life science samples.



NASA astronaut Reid Wiseman conducts a session with the Binary Colloidal Alloy Test (BCAT) experiment in the Kibo laboratory of the International Space Station.

Minus Eighty-Degree Laboratory Freezer for ISS (MELFI-1)



A refrigerator/freezer for biological and life science samples.

Minus Eighty-Degree Laboratory Freezer for ISS (MELFI-2)



A refrigerator/freezer for biological and life science samples.

Multipurpose Small Payload Rack 1 (MSPR-1)



Multipurpose rack accommodating small experiments from various science disciplines.

EXPRESS Rack 4



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

EXPRESS Rack 5



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

Ryutai Experiment Rack



A multipurpose payload rack system that supports various fluid physics experiments.

Saibo Experiment Rack

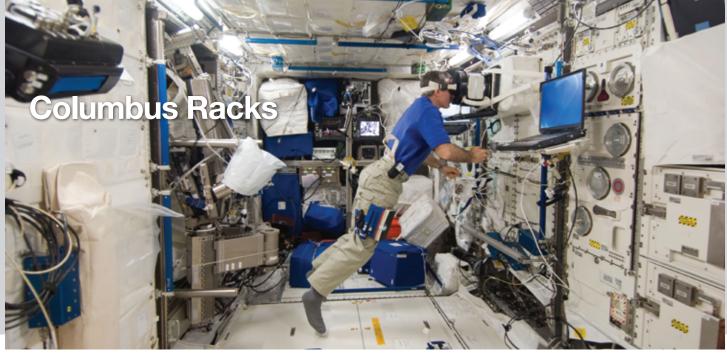


A multipurpose payload rack system that sustains life science experiment units inside and supplies resources to them.

KOBAIRO



Science experiment rack accommodating a gradient heating furnace for material studies.



NASA astronaut Dan Burbank uses Neurospat hardware to perform a science session with the PASSAGES experiment in the Columbus laboratory.

EXPRESS Rack 3



Sub-rack-sized experiments with standard utilities such as power, data, cooling, and gases.

Multipurpose Small Payload Rack 1 (MSPR-1)



Multipurpose rack accommodating small experiments from various science disciplines.

II Muscle Atrophy Research and Exercise System (MARES)



Used for research on musculoskeletal, biomechanical, and neuromuscular human physiology.

Human Research Facility (HRF-1)



Enable researchers to study and evaluate the physiological, behavioral, and chemical changes induced by long-duration space flight.

Human Research Facility (HRF-2)



Enable researchers to study and evaluate the physiological, behavioral, and chemical changes induced by long-duration space flight.

Biological Experiment Laboratory (BioLab)



Used to perform space biology experiments on microorganisms, cells, tissue cultures, small plants, and small invertebrates.

European Drawer Rack (EDR)



Provides sub-rack-sized experiments with standard utilities such as power, data, and cooling.

European Physiology Module (EPM)



Investigates the effects of shortand long-duration space flight on the human body.

Fluid Science Laboratory (FSL)



A multi-user facility for conducting fluid physics research in microgravity conditions.

KOBAIRO



Science experiment rack accommodating a gradient heating furnace for material studies.

Internal Research Accommodations

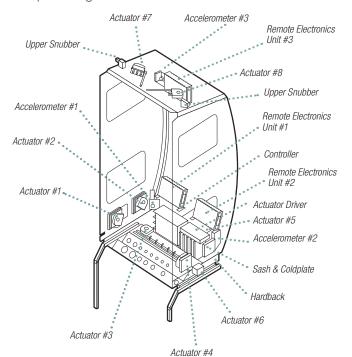
Several research facilities are in place aboard the ISS to support microgravity science investigations, including those in biology, biotechnology, human physiology, material science, physical sciences, and technology development.

Standard Payload Racks

Research payload within the U.S., European, and Japanese laboratories typically are housed in a standard rack, such as the International Standard Payload Rack (ISPR). Smaller payloads may fit in ISS lockers carried in a rack framework.

Active Rack Isolation System (ARIS)

The ARIS is designed to isolate payload racks from vibration. The ARIS is an active electromechanical damping system attached to a standard rack that senses the vibratory environment with accelerometers and then damps it by introducing a compensating force.



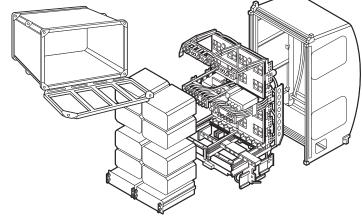
Power		
3, 6, or 12 kW, 114.5 to 126 voltage, direct current (VDC)		
Data		
Low rate	MIL-STD-1553 bus 1 Mbps	
High rate	100 Mbps	
Ethernet	10 Mbps	
Video	NTSC	
Gases		
Nitrogen flow	0.1 kg/min minimum 517 to 827 kPa, nominal 1,379 kPa, maximum	
Argon, carbon dioxide, helium	517 to 768 kPa, nominal 1,379 kPa, maximum	
Cooling Loops		
Moderate temperature	16.1 to 18.3 °C	
Flow rate	0 to 45.36 kg/h	
Low temperature	3.3 to 5.6 °C	
Flow rate	233 kg/h	
Vacuum		
Venting	10 ⁻³ torr in less than 2 h for single payload of 100 L	
Vacuum resource	10 ⁻³ torr	

Research Rack Locations

International Pressurized Sites	Total by Module	U.S. Shared
U.S. Destiny Laboratory	13	13
Japanese Kibo Laboratory	11	5
European Columbus Laboratory	10	5
Total	34	23







External Research Accommodations

External Earth and Space Science hardware platforms are located at various places along the outside of the ISS. Locations include the Columbus External Payload Facility (CEPF), Russian Service Module, Japanese Experiment Module Exposed Facility (JEM-EF), four EXPRESS Logistics Carriers (ELC), and the Alpha Magnetic Spectrometer (AMS). External facility investigations include those related to astronomy; Earth observation; and exposure to vacuum, radiation, extreme temperature, and orbital debris.

External Payload Accommodations

External payloads may be accommodated at several locations on the U.S. S3 and P3 Truss segments. External payloads are accommodated on an Expedite the Processing of Experiments to the Space Station racks (EXPRESS) Logistics Carrier (ELC). Mounting spaces are provided, and interfaces for power and data are standardized to provide quick and straightforward payload integration. Payloads can be mounted using the Special Purpose Dexterous Manipulator (SPDM), Dextre, on the ISS's robotic arm.



Japanese Experiment Module Exposed Facility (JEM-EF).



The European Columbus Research Laboratory has four exterior mounting platforms that can accommodate external payloads.



Small Satellite Orbital Deployer (SSOD) providing a novel, safe, small satellite launching capability.



Exterior nadir view of the ExPRESS Logistics Carrier 1 (ELC1) mounted to the P3 truss segment.

Express Logist	ics Carrier (ELC) Resources		
Mass capacity	227 kg (8 sites across 4 ELCs; not including adaptor plate)		
Volume	1.2 m³		
Power	750 W, 113 to 126 VDC 500 W at 28 VDC per adapter		
Thermal	Active heating, passive cooling		
Low-rate data	1 Mbps (MIL-STD-1553)		
Medium- rate data	6 Mbps (shared)		
Kibo Exposed F	Kibo Exposed Facility Resources		
Mass capacity	 500 kg Standard Site (10 Standard Sites, mass includes PIU adaptor) 2500 kg Heavy Site (3 Heavy Sites, mass includes PIU adaptor) 		
Volume	1.5 m³		
Power	3 kW max, 113-126 VDC		
Thermal	3–6 kW cooling		
Low-rate data	1 Mbps (MIL-STD-1553)		
High-rate data	43 Mbps (shared) Ethernet: 100 Base-TX		
Columbus Exter	rnal Payload Facility (CEPF) Resources		
Mass capacity	230 kg per site (4 sites; uses Columbus External Payload Adapter (CEPA)		
Volume	1.2 m³		
Power	1250 W, 120 VDC		
Thermal	Passive		
Low-rate data	1 Mbps (MIL-STD-1553)		
Medium- rate data	2 Mbps (shared) Ethernet: 100 Base-TX		

External Research Locations		
External Unpressurized Attachment Sites	Stationwide	U.S. Shared
U.S. Truss	8	8
Japanese Exposed Facility	10	5
European Columbus Research Laboratory	4	2
Total	22	15

Biological Sciences and Biotechnology



European Space Agency astronaut Alexander Gerst working on the T-Cell Activation investigation.



View of Russian cosmonaut Elena Serova as she performs the RJR Augmented Microbial Sampling investigation by taking air samples with Microbial Air Sampler.



NASA astronaut Karen Nyberg harvests plants from JAXA's Resist Tubule investigation.

The ISS has scientific capabilities to provide a unique laboratory to investigate biological or life sciences without the constraint of gravity. Biological researchers are investigating a multitude of questions that include the role of gravity and genomic diversity in biological processes. They are also contributing to finding solutions for biomedical problems that occur both on Earth and in space, in addition to the biological responses to multiple stressors.

Cells, microbes, animals and plants have evolved and developed in gravity, and the role of this environment on the regulation of biological processes is beginning to be understood. Genetic diversity in some systems is obscured in the Earth environment; use of a microgravity environment is providing unique insights into such regulation. Previous microgravity studies observed increased virulence in microbes, pluripotency of stem cells, and tissue morphogenesis patterns.

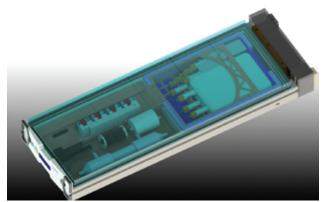
Results obtained from ISS research have implications for understanding basic biological processes, understanding stress response, developing drugs and therapeutics that can combat diseases, improving food supplies on Earth, and enhancing life-support capabilities for the exploration of space. In addition, better understanding of some of these biological processes (such as microbial virulence and the behavior of planktonic vs. biofilm forms of bacteria) could also have implications for astronaut health and also for improving life here on Earth.

Cellular and Molecular Biology

Cellular Biology includes cell culture, tissue culture and related microbial (single-cell organism) experiments. These cell-based studies in microgravity support many areas of basic and applied research for space exploration and Earth applications. The environment of space offers a unique opportunity for novel

discoveries of cellular and tissue adaptation. These novel discoveries have applications in understanding changes to human health during long-duration spaceflight and to Earth-based medicine in such areas of biomedical research as tissue engineering, host-pathogen interactions, vaccine development and drug discovery. Using gravity as a variable enables two broad classes of space cell biology research:

(a) understanding fundamental mechanisms of life's responses to changes in gravity and (b) using gravity as a tool to advance biological applications in the field of tissue engineering.

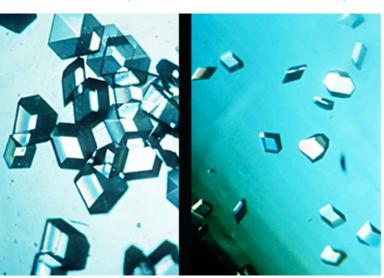


Top view of enclosed Bioculture System cassette. Image courtesy of Tissue Genesis. Inc.



Hand-Held High Density Protein Crystal Growth (HDPCG).

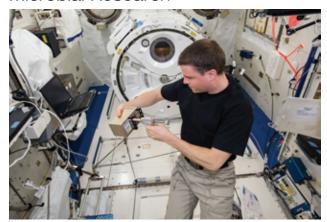
In the area of molecular biology, protein crystallization is at the forefront of this discipline. Proteins are biological macromolecules that function in an aqueous environment. Biotechnology and pharmaceutical researchers carry out the process of protein crystallization in order to grow large, well-ordered crystals for use in X-ray and neutron diffraction studies. However, on Earth, the protein crystallization process is hindered by forces of sedimentation and convection since the molecules in the crystal solution are not of uniform size and weight. This leads to many crystals of irregular shape and small size that are unusable for diffraction. Diffraction is a complex process and the quality of data obtained about the three-dimensional structure of a protein is directly dependent on the degree of perfection of the crystals. Thus, the structures of many important proteins remain a mystery simply because researchers are unable to obtain crystals of high quality or large size. Consequently, the growth of high quality macromolecular crystals for diffraction analysis has been of primary importance for protein engineers, biochemists, and pharmacologists.



Hand-Held High Density Protein Crystal Growth (HDPCG).

Fortunately, the microgravity environment aboard the ISS is relatively free from the effects of sedimentation and convection and provides an exceptional environment for crystal growth. Crystals grown in microgravity could help scientists gain detailed knowledge of the atomic, three-dimensional structure of many important protein molecules used in pharmaceutical research for cancer treatments, stroke prevention and other diseases. The knowledge gained could be instrumental in the design and testing of new drugs.

Microbial Research



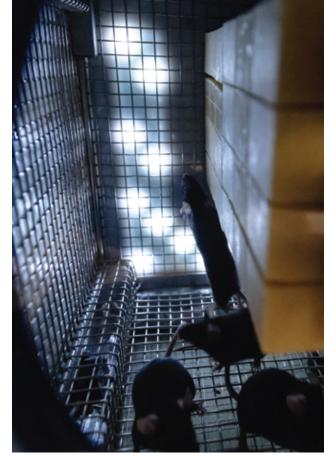
NASA astronaut Reid Wiseman activates the BRIC-19 investigation.

A human is both an individual organism and an entire ecosystem, including microorganisms in, on, and around them in which the human cells are greatly outnumbered by the microbial cells. The microbial inhabitants in and on the person outnumber the human cells 10 to 1. For the most part, these microorganisms are beneficial to their human host or otherwise innocuous. Given the right opportunity, either a shift in the environment of the host or the invasion to a new location within the host, can cause the microorganisms to become pathogenic.

Significant strides have been made to define and mitigate the source of microbial contamination aboard spacecraft and to document the responses of numerous microorganisms to the spaceflight environment. Both experience and research data has helped in the identification of critical gaps in scientist's understanding of how this environment impacts microbial ecology, the microbial genotypic and phenotypic characteristics, and their interactions with plant and animal hosts. As we look toward human interplanetary exploration, the importance of this knowledge has been recognized. With the increases in both the occupancy and duration of humans aboard the ISS, these knowledge gaps are becoming better defined. With the laboratory platform aboard ISS, many of these gaps for future spaceflight can be understood.

Animal Biology

The International Space Station provides a unique environment in which to study the effects of microgravity and the space environment on various organisms. Rodents (rats and mice) are the animal models most commonly used to study fundamental biological processes in space: predominately rats, followed by mice. Given that human astronauts and



Interior view of the rodents found within the rodent habitat.



Japan Aerospace Exploration Agency astronaut Aki Hoshide works on the Multipurpose Small Payload Rack (MSPR) in preparation for the arrival of the JAXA Medaka Osteoclast experiment.

cosmonauts routinely spend 180 days or longer on the ISS, that amount of time represents a significant portion of the lifespan of a rodent. Studies with rodents in space have been useful and important for extrapolating the implications for humans living in space and more work remains to be done (National Research Council [U.S.], 2011).

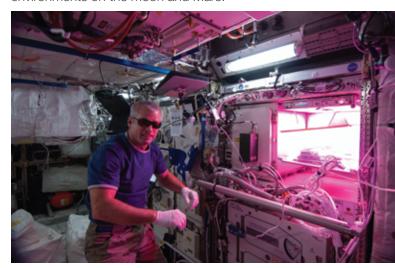
One example is the leveraging of current technology such as using genetically engineered mice in flight experiments to investigate the molecular mechanisms of bone loss that occurs during exposure to microgravity for possible pharmacological intervention. NASA is particularly interested in studies that enable a better understanding of how mechanisms

governing homeostasis at the genetic, molecular and cellular levels are integrated to regulate adaptation to spaceflight at the physiological system or wholeanimal level.

Plant Biology

The progress in plant space biology over the past quarter century has greatly increased our understanding of how plants: respond to gravity; informed the design of advanced plant growth facilities; achieved the completed life cycle; and demonstrated that physiological processes necessary for biological life support are sustainable. In the process, the horticulture of plants in the unique environment of microgravity was being developed, and plant/microbe interactions were explored. The advances made during the decades of spaceflight experimentation have also identified critical gaps in our understanding of the role of gravity and the spaceflight environment on plant biology at the cellular, tissue, whole plant, and community levels.

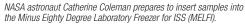
In this context, the International Space Station is a unique platform where reduced gravity can be used to probe and dissect biological mechanisms in plants for understanding how terrestrial biology responds to gravity. This knowledge is important for supporting safe and long-term human habitation in space using bio-regenerative life support, utilizing plants and microbial communities, and for reducing exploration risks to crews by designing countermeasures to problems associated with living in space. In addition, by using the facilities with centrifuges, scientists can investigate how plants respond to the reduced gravity environments on the moon and Mars.



NASA astronaut Steve Swanson is photographed near the Veggie facility in ExPRESS (Expedite the Processing of Experiments to Space Station).

Human Research







NASA astronaut Terry Virts must maintain a well balanced diet while in microgravity to help avoid additional bone and muscle loss.



NASA astronaut Sunita Williams as she underwent a blood draw to support Human Research

NASA's history has proven that humans are able to live safely and work in space. The ISS serves as a platform to extend and sustain human activities in preparation for long-duration, exploration-class missions. It provides opportunities to address critical medical questions about astronaut health through multidisciplinary research operations to advance our understanding and capabilities for space exploration.

The multi-disciplinary biomedical research currently underway on the ISS include studies addressing behavioral health and performance, bone and muscle physiology, exercise countermeasures, cardiovascular physiology, nutrition, and immunology. These life sciences research studies aim to provide a thorough understanding of the many physiologic changes that occur in a microgravity environment. Among the many physiological changes that occur in the human body include susceptibility to fainting after landing, vision changes potentially because of the harmful effects of microgravity on the eye and optic nerve, changes in blood volume, reduction in heart size and capacity, alterations in posture and locomotion, decreases in



NASA astronaut Michael Hopkins performs ultrasound eye imaging while European Space Agency astronaut Luca Parmitano assists.

aerobic capacity and muscle tone, difficulty sleeping, increased risk for renal stone formation, and weakened bones.

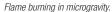
The research focuses on astronaut health and performance and the development of countermeasures that will protect crew members from the space environment during long-duration voyages, evaluate new technologies to meet the needs of future exploration missions and develop and validate operational procedures for long-duration space missions.

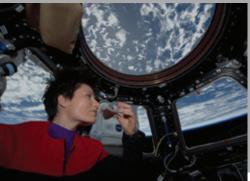


European Space Agency astronaut Samantha Cristoforetti exercises on the Advanced Resistive Exercise Device (ARED).

Physical Sciences







European Space Agency astronaut Samantha Cristoforetti using the Capillary Beverage Cup in the Cupola.



A close-up view of the Capillary Flow Experiments-2.

The ISS provides a long-duration spaceflight environment for conducting microgravity physical science research. The microgravity environment greatly reduces buoyancy driven convection, pressure head, and sedimentation in fluids. By eliminating gravity or using gravity as a factor in experimental design, the ISS allows physical scientists to better understand fluid physics; the dynamics of interfaces, such as the line of contact between a liquid and a gas; the physical behavior of systems made up wholly or partially of particles; combustion processes in the absence of buoyant convection and the properties of materials.

Fluid Physics

A fluid is any material that flows in response to an applied force; thus, both liquids and gases are fluids. Nearly all of the life support, environmental and biological, processes take place in the fluid phase. Fluid motion accounts for most transport and mixing in both natural and man-made processes as well as within all living organisms. Fluid physics is the study of the motions of liquids and gases and the associated transport of mass, momentum and energy. The need for a better understanding of fluid behavior has created a vigorous, multidisciplinary research community whose ongoing vitality is marked by the continuous emergence of new fields in both basic and applied science. In particular, the low-gravity environment offers a unique opportunity for the study of fluid physics and transport phenomena. The nearly weightless conditions allow researchers to observe and control fluid phenomena in ways that are not possible on Earth.

Experiments conducted in space have yielded rich results. Some were unexpected and most could not be observed in Earth-based labs. These results provided valuable insights into fundamental fluid behavior that

apply to both terrestrial and space environments. In addition, research on fluid management and heat transfer for both propulsion and life-support systems, have contributed greatly to U.S. leadership in space exploration.



NASA astronaut Reid Wiseman conducts a session with the Binary Colloidal Alloy Test.

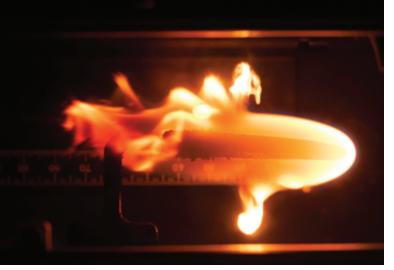


Image taken during a BASS-II (Burning and Suppression of Solids - II) experiment flame test.

Combustion

Combustion occurs when fuel and oxygen react to produce carbon dioxide, water and heat. For the foreseeable future the overwhelming majority of delivered energy in terrestrial applications will be from combustion or other chemically reacting systems. These energy uses cover the range from electric power and transportation to processes directly tied to the delivered material (e.g., glass and steel manufacture). These processes produce some of the most important environmental hazards currently facing humanity (global climate change, acid gas pollution, mercury contamination from coal, and wild-land fires).

Despite being the subject of active research for over 80 years, combustion processes remain one of the most poorly controlled phenomena that have a significant impact on human health, comfort and safety. This is because the simplest combustor (e.g., kitchen stove) remains beyond our detailed numerical modeling capabilities. The combustion process typically involves a large number of chemical species (hundreds) and reactions (even thousands). It is these species and reactions that determine flammability limits (combustor operating ranges) and pollutant emissions. Much of combustion research involves developing a comprehensive and predictive quantitative understanding of this complex process.

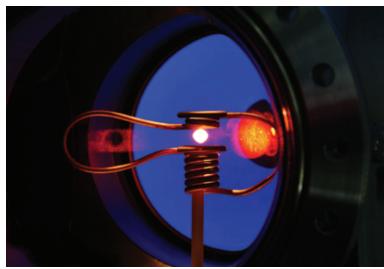
The ISS allows for the variance or elimination of the effects of gravity. By doing this, we can extract fundamental data that is important for understanding combustion systems. This approach has been implemented to some extent in existing terrestrial reduced-gravity platforms, but the experimental time scales and sizes have been limited. Long-duration experiments using realistic sizes are essential for a comprehensive understanding of the combustion phenomena and are possible only in the microgravity environments offered by space facilities.

Materials Science

Most materials are formed from a partially or totally fluid sample and the transport of heat and mass inherently influences the formation of the material and its resultant properties. The reduction in gravity related sources of heat and mass transport may be used to determine how the material processes are affected by gravitational driven and gravitationally independent sources of heat and mass transfer.

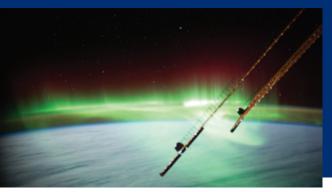


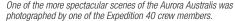
Images of the Materials Science Research Rack (MSRR).



Interior view of the EML experiment. Image credit: European Space Agency (ESA)

Earth and Space Science







The expedition 41 crew took pictures of the Atlantic Hurricane



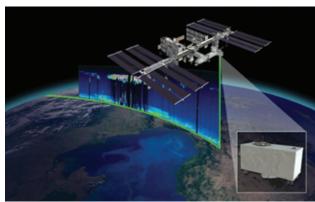
Image taken for the Hyperspectral Imager for the Coastal Ocean (HICO) investigation.

The presence of the space station in low-Earth orbit provides a vantage point for collecting Earth and space data. From an altitude of about 400 km, details in such features as Glaciers, agricultural fields, cities, and coral reefs taken from the ISS can be layered with other sources of data, such as orbiting satellites, to compile the most comprehensive information available.

Earth Observation

While NASA and other space agencies have had remote-sensing systems orbiting Earth and collecting publically available data since the early 1970s, these sensors have been primarily carried aboard free-flying, unmanned satellites. These satellites have typically been placed into sun-synchronous polar orbits that allow for repeat imaging of the entire surface of the Earth with approximately the same sun illumination (typically local solar noon) over specific areas, with set revisit times—this allows for uniform data to be taken over long time periods and enables straightforward analysis of change over time.

The ISS is a unique remote sensing platform from several perspectives—unlike automated remote-

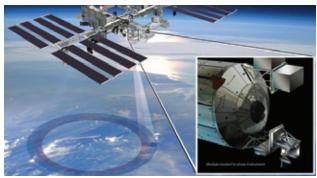


Artistic representation of the Cloud-Aerosol Transport System (CATS) that is being used to measure clouds and aerosols in the Earth's atmosphere.

sensing platforms—it has a human crew, a low-orbit altitude, and orbital parameters that provide variable views and lighting. The presence of a crew provides options not available to robotic sensors and platforms, such as the ability to collect unscheduled data of an unfolding event using handheld digital cameras as part of the Crew Earth Observations facility and real-time assessment of whether environmental conditions (like cloud cover) are favorable for data collection. The crew can also swap out internal sensor systems and payloads installed in the Window Observational Research Facility (WORF) on an as-needed basis.

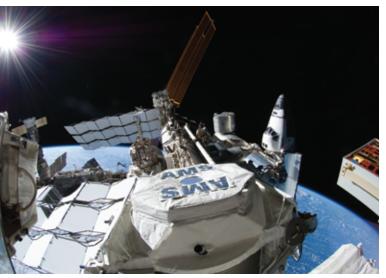


Japan Aerospace Exploration Agency astronaut Koichi Wakata works with the Window Observational Research Facility (WORF) rack.



Artistic representation of the ISS RapidScat payload that is being used to measure wind speeds and directions over the oceans. Image credit: NASA/JPL.

Fundamental Physics

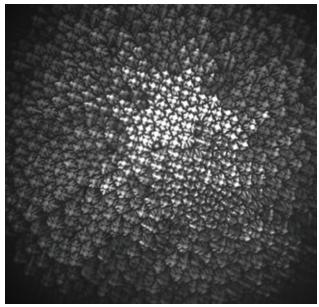


Exterior view of the International Space Station (ISS) taken during an Extravehicular Activity (EVA) with the Alpha Magnetic Spectrometer - 02 (AMS-02) visible in the foreground.

Studies in fundamental physics address space, time, energy, and the building blocks of matter. The primary theories of modern physics are based upon Einstein's theory of relativity and the standard model of particle physics. However, as scientists, we know that the picture painted by these theories remains incomplete. Einstein's theory of gravitation remains unproved to be consistent with the theories that define other forces of nature in all length scales. Furthermore, recent astronomical observation and cosmological models strongly suggest that dark matter and dark energy, which are entities not directly observed and not at all understood, dominate these interactions at the largest scales. All these unexplained observations and inconsistencies point to the potential for discovery of new theories. The ISS provides a modern and well-



View of DEvice for the study of Critical LIquids and Crystallization (DECLIC) Experiment Locker.



Dendritic pattern of the Succinonitrile-Camphor alloy grown in microgravity, seen from the top. Image courtesy of Nathalie Bergeon.

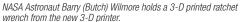
equipped orbiting laboratory for long-term micro-gravity environment research. Routine and continued access to this environment allows for fundamental physics research to be performed from a completely different vantage point.

The International Space Station provides a unique space laboratory for a set of fundamental physics experiments with regimes and precision not achievable on the ground. Some of the advantages of the space environment for experiments include:

- Long-duration exposure to the orbital free-fall environment
- Ease of measurement of changes of gravitational potential and relative motions
- Study of very small accelerations on celestial bodies
- Reduced atmospheric interference on the propagation of optical and radio signals
- Ability to track and fit to theory very long time segments of body orbital motion

Technology Demonstrations



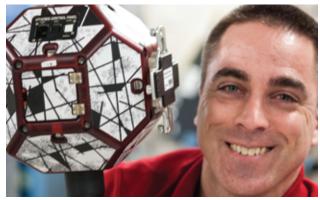






Cyclops enables the space-based launch of a new class of satellites, which are larger than cubesats but not large enough to require their own Earth-based launch vehicles.

The ISS provides an infrastructure capable of demonstrating prototypes and systems that may advance spaceflight technology readiness. The space station, the in-orbit crew, the launch and return vehicles, and the operation control centers are all supporting the demonstration of advanced systems and operational concepts that will be needed for future exploration missions.



NASA astronaut Chris Cassidy poses for a photo while conducting a session with a pair of bowling-ball-sized free-flying satellites known as Synchronized Position Hold, Engage, Reorient. Experimental Satellites. or SPHERES.

The ISS is the only long-duration platform available in the relevant space environment with an integrated space systems architecture that can be used to demonstrate advanced technologies and operations concepts. Working in close cooperation with the exploration community, the ISS Program is enabling technology and systems investigations in support of future exploration endeavors. NASA has identified 11 exploration technology areas of interest that ISS is capable of supporting.

- In-Space Propulsion
- Space Power and Energy

- Robotics, Tele-Robotics and Autonomous Systems
- Communication and Navigation
- Life Support and habitation Systems
- Exploration Destination Systems
- Science Instruments
- Entry, Descent and landing Systems
- Materials Structures and Manufacturing
- Thermal Management Systems
- Operational Processes and Procedures



NASA astronaut Steve Swanson takes a picture with Robonaut after installation of the Robonaut legs.

Commercial Development





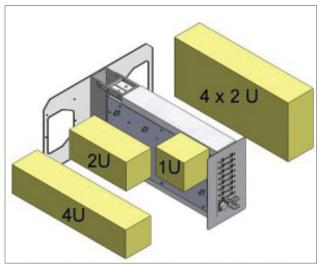


The Bigelow Expandable Activity Module. Image Courtesy of Bigelow.

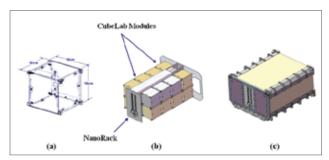
While the International Space Station (ISS) has proven its value as a platform for a broad waterfront of research disciplines as well as technology development, it also provides an ideal opportunity to test new business relationships. This allows an opportunity to shift from a paradigm of government-funded, contractor-provided goods and services to a commercially provided, government-as-a-customer approach.

This interest in promoting a more commercially oriented market in low-Earth orbit (LEO) is driven by several goals. First, it can stimulate entirely new markets not achievable in the past. Second, it creates new stakeholders in spaceflight and represents great economic opportunity. Third, it ensures strong industrial capability not only for future spaceflight but also for the many related industries. Finally, and perhaps most importantly, it allows cross-pollination of ideas, processes, and best practices, between partners of equal standing.

From commercial firms spending some of their research and development funds to conduct research on the space station, to commercial service providers selling unique services to users of the orbiting lab, the beginnings of a new economy in LEO is starting to emerge.



Various sizes of Cubelab modules are available. Image courtesy of NanoRacks.



Cubelabs fit within SubeLab Modules that will in turn fit into an EXPRESS Rack on the ISS. Image courtesy of NanoRacks.

Education







Japan Aerospace Exploration Agency astronaut Koichi Wakata reads a book to students in the cupola.



Students learning about different STEM opportunities at NASA.

The International Space Station has a unique ability to capture the interests of both students and teachers worldwide. The presence of humans onboard ISS has provided a foundation for numerous educational activities aimed at capturing that interest and motivating study in the sciences, technology, engineering and mathematics (STEM). Over 43 million students from 64 countries around the world have participated in ISS-related educational activities. Having the opportunity to connect with crewmembers realtime, either through"live" downlinks or simply speaking via a ham radio, ignites the imagination of students about space exploration and its application to the STEM fields. Projects such as Earth Knowledge-based Acquired by Middle Schools (EarthKAM) have allowed for global student, teacher and public access to space through student image acquisition. This serves to support inquiry-based learning which is an approach to science education that allows students to ask questions, develop hypothesis-derived experiments, obtain supporting evidence, analyze data, and identify solutions or explanations.

Through the life of ISS operations, these projects and their accompanying educational materials will



A Canadian student from Good Shepherd School in Peace River, Alberta, studies orbital paths of the International Space Station.

continue to be made available to more students and more countries. Through expanded international cooperation, the next generation of scientists, engineers and explorers from our global community will have the capability to learn more about and be involved in space exploration.



NASA Astronaut Scott Kelly poses with 600 000 tomato seeds for the Tomatosphere TM educational project.



After completing its pupa stage, a Monarch butterfly emerges on the International Space Station on Nov. 30, 2009 during the latest in a series of educational experiments designed to accompany in-class experiments for teachers and students. Credit: NASA/BioServe, University of Colorado



The International Space Station modules serve as a habitat for its crew and provide ports for docking and berthing of visiting vehicles. The station functions as a microgravity and life sciences laboratory, test bed for new technologies, and platform for Earth and celestial observations.

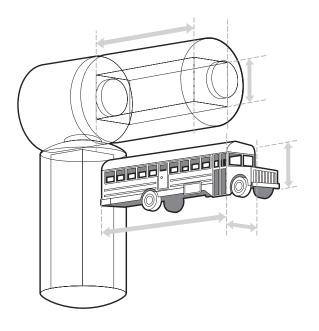
U.S. Laboratory Module Destiny

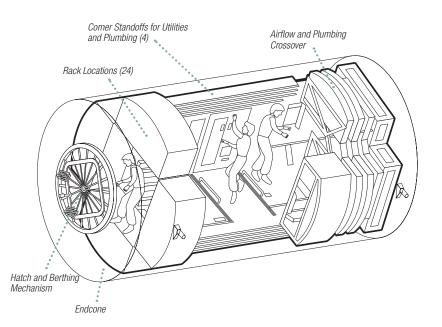
NASA/Boeing

The U.S. Laboratory Module, called Destiny, is the primary research laboratory for U.S. payloads, supporting a wide range of experiments and studies contributing to health, safety, and quality of life for people all over the world.

Science conducted on the ISS offers researchers an unparalleled opportunity to test physical processes in the absence of gravity. The results of these experiments will allow scientists to better understand our world and ourselves and prepare us for future missions. Destiny provides internal interfaces to accommodate 24 equipment racks for accommodation and control of ISS systems and scientific research.

Length	8.5 m (28 ft)
Length with attached Common Berthing Mechanism (CBM)	9.2 m (30.2 ft)
Width	4.3 m diameter (14 ft)
Launch Mass	14,515 kg (32,000 lb)
Exterior	Aluminum, 3 cylindrical sections, 2 endcones
Number of racks	24 (13 scientific and 11 system)
Windows	1, with a diameter of 50.9 cm (20 in)
Launch date	February 7, 2001 STS-98 5A







Visible are the Pressurized Mating Adapter 2 (PMA2), Destiny laboratory module, and Node 1



NASA astronaut Doug Wheelock as he retrieves 2D Nano Template sample bags from the Minus Eighty Laboratory Freezer for ISS (MELFI) in U.S. Laboratory Destiny.



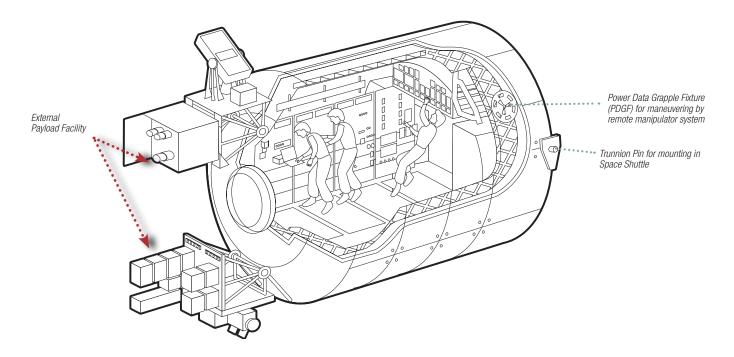
NASA astronaut Reid Wiseman is pictured in the Harmony node looking through the Destiny laboratory.

European Research Laboratory Columbus

European Space Agency (ESA)/European Aeronautic Defence and Space Co. (EADS) Space Transportation

The Columbus Research Laboratory is Europe's largest contribution to the construction of the ISS. It supports scientific and technological research in a microgravity environment. Columbus is a multifunctional pressurized laboratory permanently attached to Node 2 of the ISS. Astronauts carry out experiments in materials science, fluid physics, life science, and technology.

Length	6.9 m (22.6 ft)
Diameter	4.5 m (14.7 ft)
Launch Mass	10,300 kg (22,700 lb)
Launch date	February 7, 2008 STS-122 1E
Racks	10 International Standard Payload Racks (ISPRs)





An interior view of the Columbus laboratory of the International Space Station.



European Space Agency astronaut Luca Parmitano works with the Biolab in the Columbus laboratory of the International Space Station. Biolab is used to perform space biology experiments on microorganisms, cells, tissue cultures, plants and small invertebrates.



Columbus attached to the ISS.

Japanese Experiment Module Kibo (Hope)

Japan Aerospace Exploration Agency (JAXA)/ Mitsubishi Heavy Industries, Ltd.

The Japanese Experiment Module (JEM), known as "Kibo" (pronounced keybow), which means "hope" in Japanese, is Japan's first human-rated space facility and the Japan Aerospace Exploration Agency's (JAXA's) first contribution to the ISS program.

Kibo was designed and developed with a view to conducting scientific research activities on orbit. In Kibo astronauts perform experimental research activities. Currently, educational, cultural, and commercial uses of Kibo are also planned. Thus, as a part of the ISS, Kibo will provide extensive opportunities for utilization of the space environment. Resources necessary for Kibo's on-orbit operation, such as air, power, data, and cooling fluid, are provided from the U.S. segment of the ISS.

Fine Arm Stage

Experiments

Interorbit Communications

System (ICS)

RMS Console

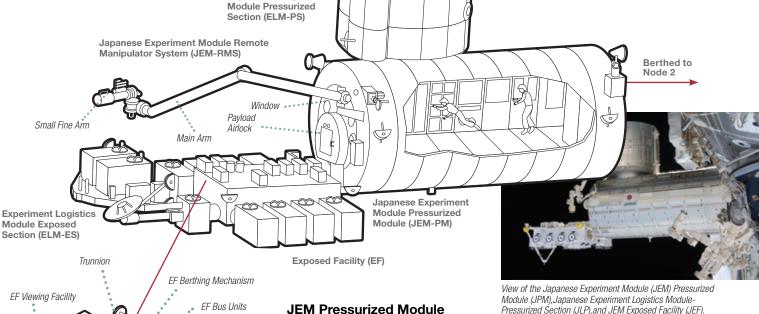
Experimen

Communication Rack

Common Berthing Mechanism

GPS Antennas **Experiment Logistics**

ELM-PS 4.4 m (14.4 ft) 4.4 m (14.4 ft) 11.2 m (36.7 ft) 4.2 m (13.9ft) Length 15,900 kg (35,050 lb) 4,200 kg (9,260 lb) **Launch Mass** March 11, 2008 May 31, 2008 Launch date STS-124 STS-123 1J/A ΕĒ **Dimensions** $5.6 \times 5 \times 4$ m (18.4 × 16.4 × 13.1 ft) 4,100 kg (9,038 lb) **Launch Mass** July 15, 2009 STS-127 Launch date 2.I/A JEM Remote Manipulator System Main Arm length 10 m (32.9 ft) Small Fine Arm length 2.2 m (7.3 ft)



JEM Remote Manipulator

Payload

Mating Mechanism

Workstation

Stowage Rack

Power System Rack

System (JEM-RMS)

Pressurized Section (JLP), and JEM Exposed Facility (JEF).



NASA astronauts Scott Kelly (left) and Terry Virts (right) work on a Carbon Dioxide Removal Assembly (CDRA) inside the station's Japanese Experiment Module.

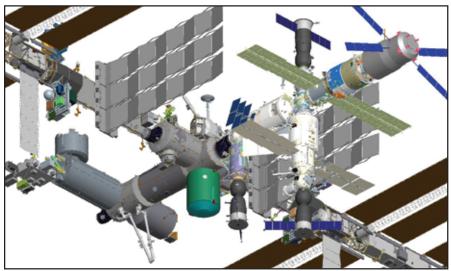
Nodes

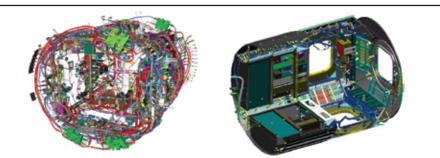
Nodes are U.S. modules that connect the elements of the ISS. Node 1, called Unity, was the first U.S.-built element that was launched, and it connects the U.S. and Russian segments.

Node 2 (Harmony) and Node 3 (Tranquility) are European-built elements and are each one rack bay longer than Node 1. Node 2 connects the U.S., European, and Japanese laboratories, as well as providing a nadir berthing port and a forward PMA-2 docking port. Node 3 is attached to the port side of Node 1 and provides accommodation for life-support and exercise equipment.

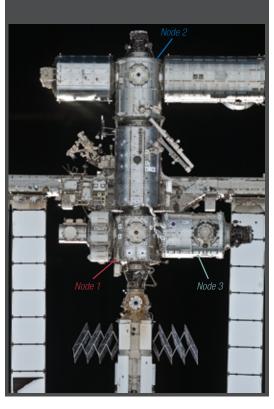


Astronaut Reid Wiseman is photographed at work in the Node 2 module. He is joined by Astronaut Steve Swanson (left).





Mechanical assemblies—including berthing mechanisms and hatches, cable harnesses for electrical and data systems routing, and fluid lines for thermal control—add to the complexity of the node modules.





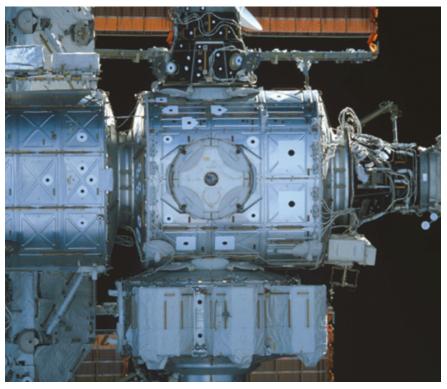




Node 1 Unity

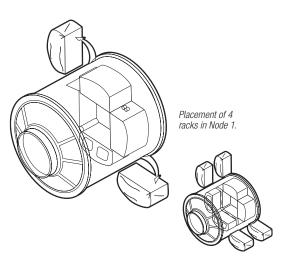
NASA/Boeing

Node 1's six ports provide berthing connections to the Z1 Truss, U.S. Laboratory Module, Airlock, and Node 3. In the summer of 2015, the Node 1 nadir port will be available as a second berthing port for visiting cargo vehicles.



Node 1 is shown with the Russian segment FGB to the right (aft), the U.S. Laboratory to the left (fore), the U.S. Airlock at the bottom (starboard), and PMA-3 at the top (port).

Length	5.5 m (18 ft)
Width (diameter)	4.3 m (14 ft)
Mass	11,895 kg (26,225 lb)
Exterior	Aluminum cylindrical sections, 2 endcones
Number of racks	4
Launch date	December 4, 1998 STS-88 2A





NASA astronaut Karen Nyberg is pictured near fresh fruit floating freely in the Unity Node 1 module.



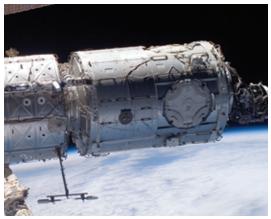
The moments are far and few between when crewmembers have an opportunity to gather together. Pictured here in Node 1 are Chris Hadfield of the Canadian Space Agency at the right. Clockwise from his position are the five flight engineers -- NASA astronauts Tom Marshbum and Chris Cassidy, and Russian cosmonauts Alexander Misurkin, Roman Romanenko and Pavel Vinogradov.

Node 2 Harmony

ESA/Thales Alenia Space Italy (TAS-I)

Node 2 was built in Europe by Thales Alenia Space Italy (TAS-I) under contract of the European Space Agency. It incorporates six berthing ports: two in the longitudinal axis and four on the radial perpendicular axes. Node 2 is attached to the forward end of the U.S. laboratory and connects Columbus, the European laboratory, on the starboard side; Kibo, the Japanese laboratory, on the port side; the Pressurized Mating Adaptor 2 (PMA-2) on the forward side, which provides a docking location for visiting vehicles; on the nadir (Earth-facing) side, Node 2 provides a berthing port for the H-II Transfer Vehicle (HTV), a Japanese cargo vehicle as well as commercial cargo vehicles,. In the summer of 2015, the PMA3 (currently on Node 3) will be relocated to provide a second US docking port on the zenith port of Node 2. In addition, Node 2 provides Crew Quarters for 4 crew members as well as vital functional resources for the operation of the connected elements, namely the conversion and distribution of the electrical power, heating, cooling resources from the ISS Integrated Truss, and support of the data and video exchange with the ground and the rest of the ISS.

Length	6.7 m (22 ft)
Width (diameter)	4.3 m (14 ft)
Mass	14,787 kg (32,599 lb)
Exterior	Aluminum cylindrical sections, 2 endcones
Number of racks	8
Launch date	October 23, 2007 STS-120 10A



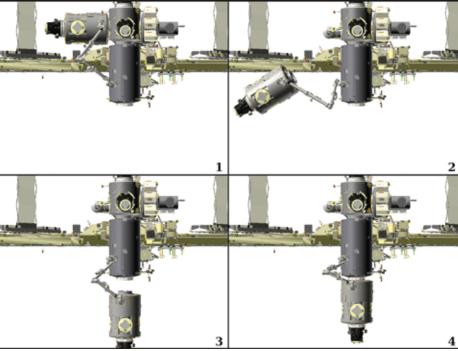
Exterior view of Node 2.



ESA astronaut Samantha Cristoforetti works on the Maintenance Work Area (MWA) which provides a rigid surface on which to perform maintenance tasks



European Space Agency astronaut Alexander Gerst conducts a session with the Capillary Flow Experiment (CFE-2) in the Harmony Node 2.



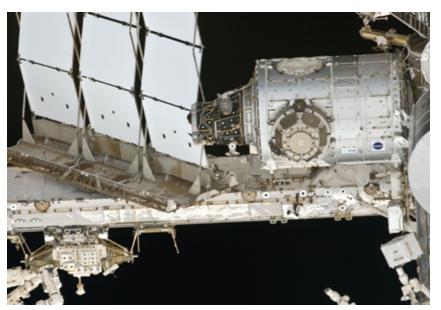
Initially Node 2 was berthed on the starboard port of Node 1. The ISS's remote manipulator moved Node 2 to the forward port of the U.S. Lab. PMA2 is berthed to the front port of Node 2.

Node 3 Tranquility

ESA/Thales Alenia Space Italy (TAS-I)

Node 3 was built in Europe by Thales Alenia Space Italy (TAS-I) under contract of the European Space Agency. Node 3 is attached to the port side of Node 1, and the Cupola is berthed on its nadir (Earth facing) port. The PMA-3 is currently attached to the Node 3 port. The zenith port has been inhibited and modified to become the parking location of the ISS: Special Purpose Dexterous Manipulator (SPDM). In the summer of 2015, the PMM will be relocated from the Node 1 nadir port to the Node 3 forward port and the PMA-3 will be relocated to Node 2 zenith port. The port and aft ports are then available for further ISS additions.

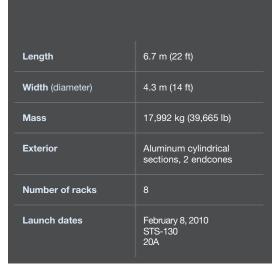
Node 3 accommodates ISS air revitalization, oxygen generation, carbon dioxide removal and water recovery systems. It also accommodates the bathroom for the crew hygiene and exercising equipment such as a treadmill and a weight-lifting device.



Exterior view the P1 truss segment, and the Node 3/Tranquility and Cupola.



NASA astronaut Chris Cassidy enters data in a computer in the Tranquility node.





Interior view of the Node 3/Tranquility.

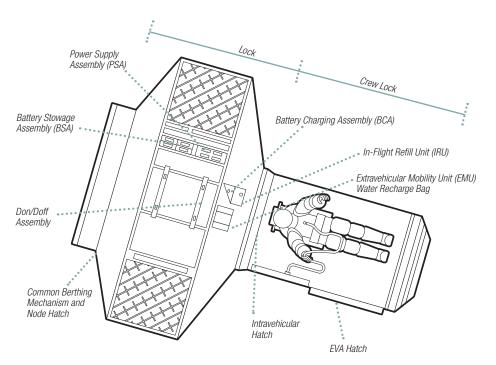


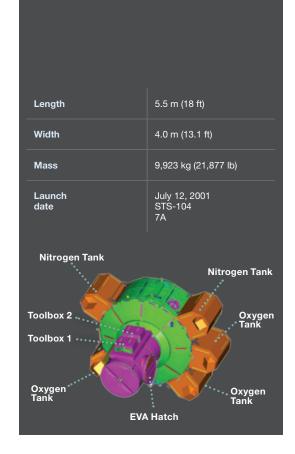
View of the Waste Management Compartment (WMC) in the Node 3 module.

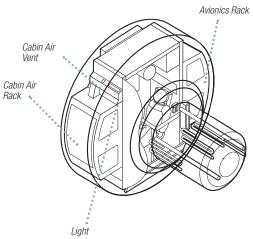
Joint Airlock Quest

NASA/Boeing

The Quest Airlock is a pressurized space station module consisting of two compartments attached end-to-end by a connecting bulkhead and hatch. The two compartments consist of: the Equipment Lock, which provides the systems and volume for suit maintenance and refurbishment, and the Crew Lock, which provides the actual exit for performing EVAs. The airlock is the primary path for International Space Station spacewalk entry and departure for U.S. spacesuits, which are known as Extravehicular Mobility Units, or EMUs. Quest can also support the Russian Orlan spacesuit for spacewalks.

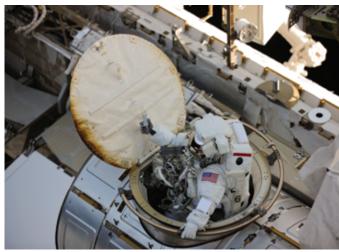








View of NASA astronaut Chris Cassidy (left) and European Space Agency astronaut Luca Parmitano (right) preparing for a dry run in the International Space Stations Quest airlock in preparation for the first of two sessions of extravehicular (EVA). Both are wearing a liquid cooling and ventilation garment and preparing to don their EMUs. Astronaut Karen Nyberg, is visible in the foreground.



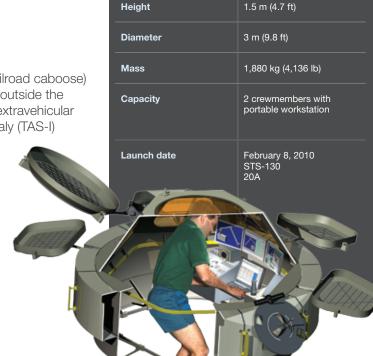
NASA astronaut Doug Wheelock enters the Quest airlock as the session of extravehicular activity (EVA) draws to a close.

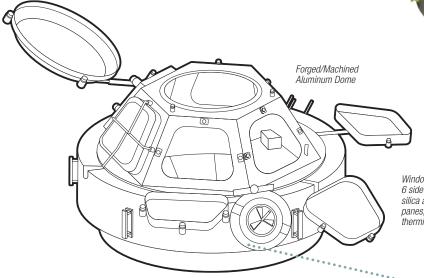
Cupola

ESA/Thales Alenia Space Italy (TAS-I)

The Cupola (named after the raised observation deck on a railroad caboose) is a small module designed for the observation of operations outside the ISS such as robotic activities, the approach of vehicles, and extravehicular activity (EVA). It was built in Europe by Thales Alenia Space Italy (TAS-I)

under contract of the European Space Agency. It provides spectacular views of Earth and celestial objects. The Cupola has six side windows and a direct nadir viewing window, all of which are equipped with shutters to protect them from contamination and collisions with orbital debris or micrometeorites. The Cupola is designed to house the robotic workstation that controls the ISS's remote manipulator arm. It can accommodate two crewmembers simultaneously and is berthed to the Earth facing side of Node-3 using a Common Berthing Mechanism (CBM).





Window Assembly (1 top and 6 side windows with fused silica and borosilicate glass panes, window heaters, and thermistors)

> Payload Data Grapple Fixture (PDGF)



At the robotics workstation in the Cupola, NASA astronaut Karen Nyberg participates in onboard training activity in preparation for the grapple and berthing of a visiting vehicle.



Exterior view of the Cupola and the Node 3/Tranquility taken by a crew member during a Extravehicular Activity (EVA). Crew members onboard are partially visible in the Cupola windows.



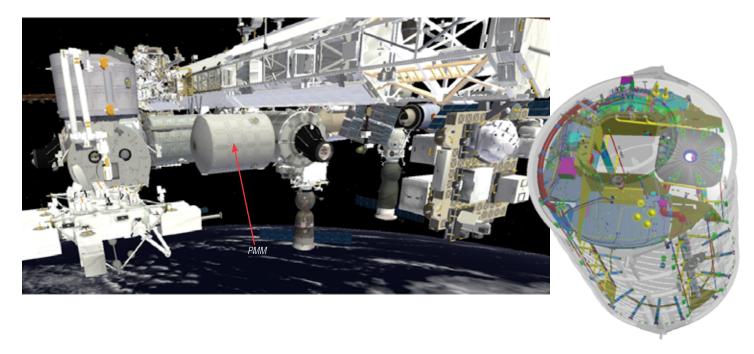
European Space Agency astronaut Alexander Gerst enjoys the view of Earth from the windows in the Cupola of the International Space Station.

Permanent Multipurpose Module (PMM)

NASA/ASI (Italian Space Agency)

Derived from the Leonardo Multi-purpose Logistics Module (MPLM), the Italian-built Permanent Multi-Purpose Module (PMM) is currently berthed to the nadir port of Node 1. In the summer of 2015, the PMM will be relocated to the Node 3 forward port. The PMM can host up to 16 racks containing equipment, experiments, and supplies, and it has additional storage space for bags in the aft endcone.

Length	6.67 m (21.7 ft)
Diameter Exterior Interior	4.5 m (14.76 ft) 4.21 m (13.81 ft)
Mass	4,428 kg (9,784 lb)
Pressurized volume	76.7 m³ (2708.6 ft³)
Cargo capability	9,000 kg (20,000 lb)
Pressurized habitable volume	31 m ³ (1,095 ft ³)





NASA astronauts Chris Cassidy and Karen Nyberg along with European Space Agency astronaut Luca Parmitano are shown amongst cargo bags in the PMM.

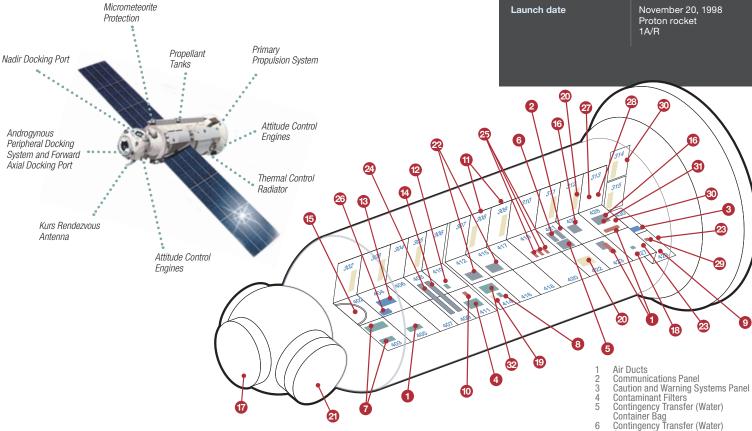


View of Permanent Multipurpose Module (PMM) and Soyuz spacecraft.

Functional Cargo Block (FGB) Zarya (Sunrise)

NASA/Boeing/Khrunichev State Research and **Production Space Center**

The FGB was the first launched element of the ISS, built in Russia under a U.S. contract. During the early stages of ISS assembly, the FGB was selfcontained, providing power, communications, and attitude control functions. Now, the FGB module is used primarily for storage and propulsion. The FGB was based on the modules of Mir.





Russian cosmonaut Maxim Suraev using the communications system in the FGB.



View of the FGB on orbit flanked by the Service Module and PMA-1.

Contingency Transfer (Water)
Container Bag
Container Connections
Dust Collectors
Electrical Container **Electrical Outlet** Flex Airduct Container 10 Fuse 11 12 Fuse Panels (behind close-outs) Gas Analyzer Gas Mask 14 15 Handrail Hatch Protection Instrument Containers Docking Port to PMA Laptop Outlets Lighting Panel 17 18 19 20 21 22 23 24 25 26 27 28 29 30 Lights Nadir Docking Port Onboard Documentation Onboard Network Receptacle Outlets Pole and Hook

12,990 m (42.6 ft)

24,968 kg (55,045 lb)

71.5 m³ (2,525 ft³)

24.4 m (80 ft)

28 m² (301 ft²)

3,800 kg (8,377 lb)

3 kW

4.1 m (13.5 ft)

Length

Mass

Maximum diameter

Pressurized volume

Solar array span

Array surface area

Power supply (avg.)

Propellant mass

TV Outlet

Portable Fans

Removable Fire Extinguisher Power Outlet Pressurized Valve Unit Caution and Warning Panel Smoke Detector

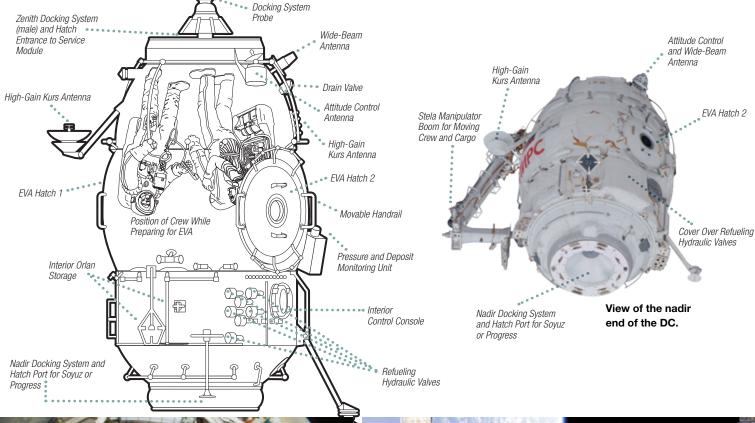
Wipes/Filters

Docking Compartment (DC) Pirs (Pier)

Russian Federal Space Agency (Roscosmos)/ S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

Pirs serves as a docking port for the Russian Segment. Pirs also provides the capability for extravehicular activity (EVA) using Russian Orlan spacesuits. Additionally, Pirs provides systems for servicing and refurbishing the Orlan spacesuits. The nadir Docking System on Pirs provides a port for the docking of Soyuz and Progress vehicles. When the final Russian Multi-Purpose Logistic Module arrives, Pirs will be deorbited.

Length	4.9 m (16 ft)
Maximum diameter	2.55 m (8.4 ft)
Mass	3,838 kg (8,461 lb)
Volume	13 m³ (459 ft³)
Launch date	September 15, 2001 Progress M 4R





Cosmonaut Oleg Kononenko with two Russian Orlan spacesuits in the Pirs Docking Compartment.

Progress supply vehicle docked to the Pirs DC-1.

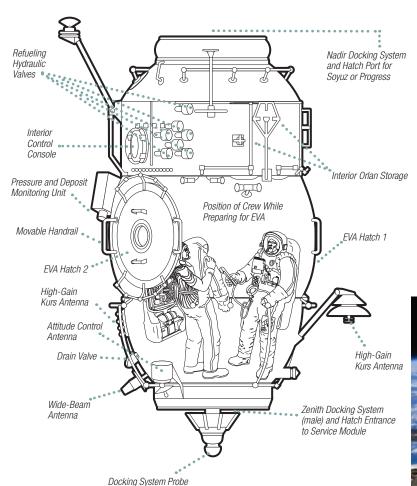
Mini-Research Module 2 (MRM2) Poisk (Explore)

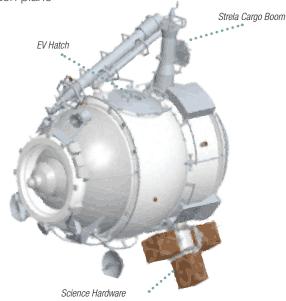
Russian Federal Space Agency (Roscosmos)/ S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

Poisk, also known as the MRM2, is almost identical to the Pirs Docking Compartment. Poisk provides the capability for extravehicular activity (EVA) using Russian Orlan spacesuits. Additionally, Poisk provides systems for servicing and refurbishing the Orlan spacesuits.

The zenith docking system on Poisk provides a port for the docking of Soyuz and Progress logistics vehicles. Poisk also provides extra space for scientific experiments, including power supply outlets and data transmission interfaces for five external workstations (one three-port active and four passive) to accommodate science payloads for observation of the upper hemisphere and for exposure. The module is also equipped with three temporary internal workstations near the module's side windows to observe a local horizon plane and to accommodate payloads equipped with vacuum interfaces.

Length	4.9 m (16 ft)
Maximum diameter	2.55 m (8.4 ft)
Mass	3,795 kg (8,367 lb)
Volume	14.8 m³ (523 ft³)
Launch date	November 10, 2009 Progress M 5R





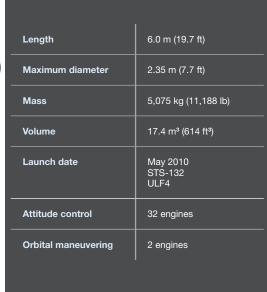


Exterior view of the Mini Research Module 2 (MRM2)/Poisk.

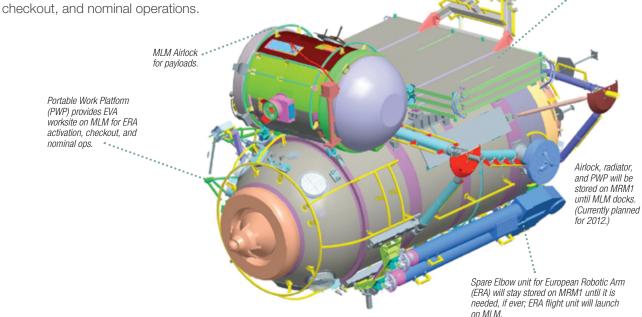
Mini-Research Module 1 (MRM1) Rassvet (Dawn)

Russian Federal Space Agency (Roscosmos)/ S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

Rassvet, also known as the MRM1, is primarily used for cargo storage; being equipped with eight internal workstations, it serves as a mini-research laboratory for biological and biotechnological investigations, as well as for experiments in material sciences and fluid physics. The nadir docking system on Rassvet provides the fourth docking port on the Russian segment for the docking of Soyuz and Progress logistics vehicles. It was built from the pressurized hull of the Science Power Platform (SPP) dynamic test article. Moreover, the exterior of Rassvet carries a spare elbow joint for the European Robotic Arm and outfitting equipment for the Russian Multi-Purpose Laboratory Module (MLM), including a radiator, an airlock for payloads, and a Portable Work Post (PWP) that provides an EVA worksite for ERA activation,



MLM Radiator





View of the Rassvet Mini-Research Module 1 (MRM1) as it is mated with the Zarya Functional Cargo Block (FGB) nadir docking port.



Russian cosmonaut Oleg Skripochka uses the Russian Tekh-38 VETEROK ("Breeze") science hardware to take aero-ionic concentration measurements in the Rassvet Mini-Research Module 1 (MRM1).

Service Module (SM) Zvezda (Star)

Fuses

Night-Lights Power Distribution Panel Recessed Cavity & Valve Panel

Toru Seat

Smoke Detector

Vela Ergometer Ventilation Screen Vozdukh Control Panel Waste Management Compartment Zenith Docking Port Soyuz and Progress Docking Port

Galley Table
Integrated Control Panel
Lighting Control Panels
Maintenance Box
Maintenance Post

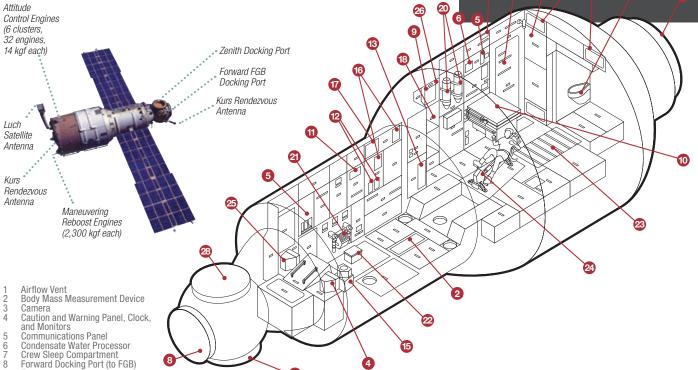
Nadir Docking Port Navigation Sighting Station

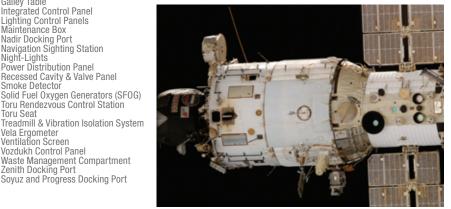
Solid Fuel Oxygen Generators (SFOG)
Toru Rendezvous Control Station

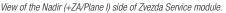
Roscosmos/S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

The Service Module was the first fully Russian contribution, providing early living quarters, life-support system, electrical power distribution, data processing system, flight control system, and propulsion system. Its communications system still enables remote command capabilities from ground flight controllers. Although some of these systems were subsequently supplemented by U.S. systems, the Service Module remains the structural and functional center of the Russian segment of the ISS. The Service Module was intended primarily to support crew habitation but became the first multipurpose research laboratory on the ISS.

13.1 m (43 ft) Length Diameter 4.2 m (13.5 ft) Wingspan 29.7 m (97.5 ft) Weight 24,604 kg (54,242 lb) Launch date July 12, 2000 Proton Attitude control 32 engines **Orbital maneuvering** 2 engines 27 29









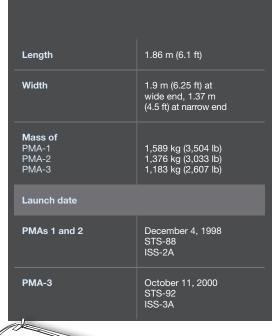
View of Cosmonaut Alexander Samokutyaev during Remote Teleoperator Control Mode Training, in the Service Module (SM).

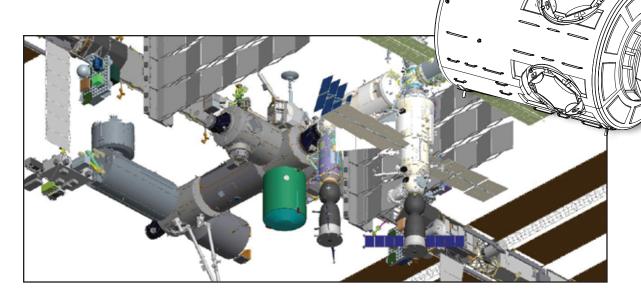
Pressurized Mating Adapters (PMAs)

NASA/Boeing

Three conical docking adapters, called Pressurized Mating Adapters, attach to the Nodes' berthing mechanisms. The other sides of the adapters allow for docking vehicles. PMA-1 connects the U.S. and Russian segments while PMA-2 and PMA-3 serve as docking ports for future commercial crew vehicles. PMA-2 is located on the Node 2 forward port and PMA-3 is currently located on Node 3 port. In the summer of 2015 PMA-3 will be relocated to the Node 2 zenith port. The ISS at that point will have two permanent docking ports.

PMA-1, 2 and 3 structures are identical. The PMA structure is a truncated conical shell with a 28 inch axial offset in the diameters between the end rings.







View of Node 2, Pressurized Mating Adapter 2 (PMA-2) taken during Extravehicular Activity (EVA).



European Space Agency astronaut Paolo Nespoli and NASA astronaut Ron Garan pause for a photo during preparations to open the Pressurized Mating Adapter 2 (PMA-2) hatch.

Habitation

The habitable elements of the ISS are mainly a series of cylindrical modules. Accommodations—including the waste management compartment and toilet, the galley, individual crew sleep compartments, and some of the exercise facilities are located in the Service Module (SM), Node 1, Node 2, Node 3, and the U.S. Laboratory.



NASA astronaut Sunita Williams vacuuming out crew quarters in the Node 2/Harmony.



Russian cosmonaut Mikhail Tyurin trims the hair of Japan Aerospace Exploration Agency astronaut Koichi Wakata inside the Unity node.



Russian cosmonaut Alexander Skvortsov pictured in his crew



NASA astronaut Chris Cassidy gets a workout on the advanced Resistive Exercise Device (aRED) in Node 3.



Dinner in Node 1 with Russian cosmonaut Oleg Kotov, NASA astronaut Mike Hopkins and Japan Aerospace Exploration Agency astronaut Koichi Wakata.



European Space Agency astronaut Luca Parmitano exercises on the Combined Operational Load Bearing External Resistance Treadmill (COLBERT).



European Space Agency astronaut Samantha Cristoforetti exercises on the Cycle Ergometer with Vibration Isolation and Stabilization (CEVIS) in the Destiny Laboratory.

Progress

Service Module

FGB

Node 1

Quest Airlock

NASA Astronauts Rick Mastracchio and Mike Hopkins in the airlock (A/L). Extravehicular Mobility Units (EMUs) are visible.

Node 3

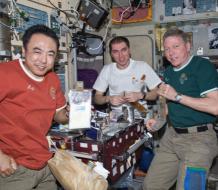
Destiny

Node 2

JEM



Toilet Compartment in the Service Module (SM)



Japan Aerospace Exploration Agency astronaut Satoshi Furukaw, NASA astronaut Mike Fossum and Russian cosmonaut Sergei Volkov prepare for a meal in the Service Module galley.



Stowed food trays in FGB.



Interior view of the Node 1 module



Waste and Hygiene Compartment (WHC) in the Node 3.



NASA astronaut Susan J. Helms looks out the U.S. Lab

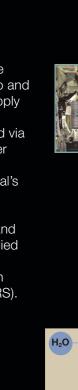


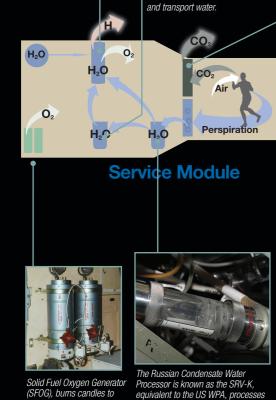
NASA astronaut Karen Nyberg is photographed in her Crew Quarters during her off-duty

Environmental Control and Life Support System (ECLSS)

Earth's natural life support system provides the air we breathe, the water we drink, and other conditions that support life. For people to live in space, however, these functions must be performed by artificial means. The ECLSS includes compact and powerful systems that provide the crew with a comfortable environment in which to live and work.

The on-orbit ECLSS is supplemented by an assortment of resupply vehicles provided by the international partnership and U.S. Commercial Resupply System (CRS) vehicles. Water can be resupplied via lodine Compatible Water Containers (ICWCS) on SpaceX's Dragon, Orbital's Cygnus, or JAXA's H-II Transfer Vehicle (HTV). High pressure oxygen and nitrogen can be resupplied by these same vehicles via the Nitrogen/Oxygen Recharge System (NORS). The Russian Progress also delvers water and atmospheric gas.



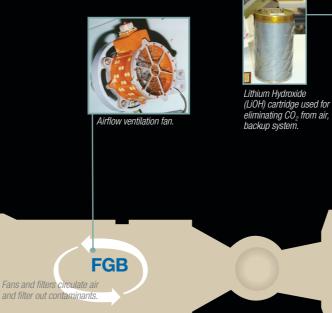


produce oxygen as a backup the condensate that is reclaimed by

Russian EDVs used to store

Regenerative environmental control life support in the U.S. seament of the ISS.

U.S. Regenerative Environmental Control and Life Support System (ECLSS) Water Recovery
System Rack 1 (WRS-1) System Rack 2 (WRS-2) 16 Power Supply Product Water 18



Urine

Gallev

Node '

Quest Airlock



carbon dioxide from crew.



Astronauts share a meal at a galley.

Destiny

Node 2

Columbus

JEM

ECLSS on the ISS provides the following functions:

- Recycles wastewater (including urine) to produce drinking (potable) water and technical water (for flush and oxygen generation)
- · Stores and distributes potable water

Vozdukh absorbs carbon dioxide

- Uses recycled water to produce oxygen for the
- Removes carbon dioxide from the cabin air
- Filters the cabin air for particulates and microorganisms
- Removes volatile organic trace gases from the
- Monitors and controls cabin air partial pressures of nitrogen, oxygen, carbon dioxide, methane, hydrogen, and water vapor

- Maintains total cabin pressure • Detects and suppresses fire
- · Maintains cabin temperature and humidity levels
- · Distributes cabin air between ISS modules (ventilation)

The U.S. Regenerative Environmental Control and Life Support System takes steps toward closing the water cycle; it takes humidity condensate from the cabin air and urine from the crew and converts these into drinking water, oxygen for breathing, and hydrogen which combines with CO, scrubbed from the cabin air to make more water.



Waste Hygiene Compartment (WHC) collects urine and waste for processing



Common Cabin Air Assembly (CCAA) condenses water

Water Processor Assembly Urine Processor Assembly

Oxygen Generation Assembly.

Crew Health Care System (CHeCS)

The Crew Health Care System (CHeCS) is a suite of hardware on the ISS that provides the medical and environmental monitoring capabilities necessary to ensure the health and safety of crewmembers during long-duration missions. CHeCS is divided into four subsystems:

Countermeasures System (CMS)—The CMS provides the equipment and protocols for the performance of daily exercise to mitigate the deconditioning effects of living in a microgravity environment. The CMS hardware provides aerobic conditioning, interval and resistive training, and also works to preserve aerobic and anaerobic capacity, and muscular strength and endurance.

Environmental Health

System (EHS)—The EHS monitors the atmosphere for gaseous contaminants (i.e., from nonmetallic materials offgassing, combustion products, and propellants), and microbial contamination levels from crewmembers and station activities. The EHS also monitors water quality and acoustics.

Health Maintenance System (HMS)—The HMS provides inflight life support and resuscitation. medical care to respond to crew

illness and injury, preventative health care, and crew health monitoring capabilities.

The Radiation System -

The Radiation System characterizes the complex, multicomponent radiation environment to which the crew is exposed, and records the crewmembers' cumulative exposures. The ionizing radiation environment encountered by ISS consists of a mixture of primary and secondary radiation types:

- Primary radiation varies as a function of ISS altitude and consists mostly of trapped protons, electrons, galactic cosmic radiation and solar flux.
- Secondary radiation products are produced by collisions of primary radiation with the ISS and its hardware inside, as well as inside the crewmembers' bodies.



Russian cosmonaut Oleg Kotov exercises on water samples. Dorozhka which is a



European Space Agency astronaut Frank De Winne taking



NASA astronaut Reid Wiseman exercises on the Combined Operational Load Bearing External Resistance



Japan Aerospace Exploration Agency astronaut Koichi

FGB



Russian cosmonaut lena Serova RS 41FE with Microbial Air

Sampler (MAS) for the Microbial Sampling investigation.

with TOCA for water

Close-up view of a Surface Sample

Kit (SSK) surface



NASA astronaut Karen

Nyberg performs ar

Russian cosmonaut Roman Romanenko and NASA astronaut Michael Barratt perform a

detailed checkout and inspection of the HMS CMRS (Health Maintenance System/Crew

Medical Restraint System) in the U.S. Lab. The boardlike CMRS allows strapping down a

patient on the board with a harness for medical attention by the CMO who is also provided

NASA astronaut eter with Vibration (CEVIS).



astronaut Luca Parmitano with Colorimetric Water Quality Monitoring Kit (CWQMK).

JEM

Automated External Defibrillator (AFD)

Service Module





Ergometer Bike.



IV- Tissue Equivalent Proportional



European Space Agency astronaut Andre Kuipers



NASA astronaut Steve Swanson with Sound Level Meter (SLM) to take noise level measurements.



Node 3

Node 1



Canadian astronaut Robert Kit (SSK) to collect and incubate microbiology samples

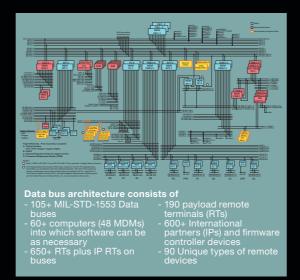
Destiny

Node 2

Columbus

Computers and Data Management

The system for storing and transferring information essential to operating the ISS has been functioning at all stages of assembly and provides control from various segments of the ISS. The Enhanced Processor and Integrated Communications upgrade in some of the Multiplexer/Demultiplexers (MDMs) has vastly improved the processing and memory margins; in addition to adding a new Ethernet interface. The Portable Computer System laptops provide the crew interface for commanding and monitoring the ISS Core Systems hardware and associated software.







Multiplexer/Demultiplexer with Solid State Mass Memory Unit (SSMMU) and Processor cards in US lab.







Crew uses Progress Remote Control workstation in SM.



Multiplexer/Demultiplexer (computer).

Progress

Service Module

FGB

Node 1

Node 3

Destiny

Node 2

Columbus

JEM

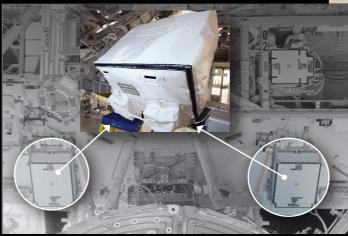


Laptop and TVIS Control (located near galley).





ORU Remote Progress Docking Workstation



Multiplexer/Demultiplexers (mounted externally on the truss).

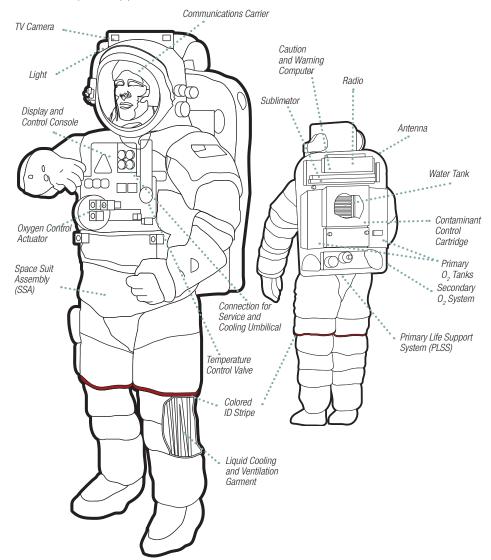




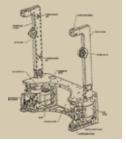
Extravehicular Mobility Unit (EMU)

NASA/Hamilton Sundstrand/ILC Dover

The EMU provides a crewmember with life support and an enclosure that enables an EVA (Extravehicular Activity). The unit consists of two major subsystems: the Primary Life Support Subsystem (PLSS) and the Space Suit Assembly (SSA). The EMU provides atmospheric containment, thermal insulation, cooling, solar radiation protection, and micrometeoroid/orbital debris (MMOD) protection.



The Simplified Aid For EVA Rescue (SAFER) provides a compressed nitrogen-powered backpack that permits a crewmember to maneuver independently of the ISS. Its principal use is that it allows a crewmember to maneuver back to the station if he or she becomes detached from the ISS.



Suit's nominal pressure	0.3 atm (4.3 psi)
Atmosphere	100% oxygen
Primary oxygen tank pressure	900 psi
Secondary oxygen tank pressure	6,000 psi (30-min backup supply)
Maximum EVA duration	8 h
Mass of entire EMU	143 kg (315 lb)
Suit life	25 EVA's or 6 years prior to returning to Earth



- Thermal Micrometeoroid Garment (TMG).
 Cover: Ortho/KEVLAR® reinforced with GORE-TEX®.
- 2. TMG Insulation. Five to seven layers of aluminized Mylar® (more layers on arms and legs).
- 3. TMG liner. Neoprene-coated nylon ripstop.
- 4. Pressure garment cover. Restraint: Dacron®.
- 5. Pressure garment bladder. Urethane-coated nylon oxford fabric.
- 6. Liquid cooling garment. Neoprene tubing.



NASA astronaut Chris Cassidy participates in a session of extravehicular activity (EVA). During the six-hour, seven-minute spacewalk, Cassidy was preparing the space station for a new Russian module and performed additional installations on the station's backbone.

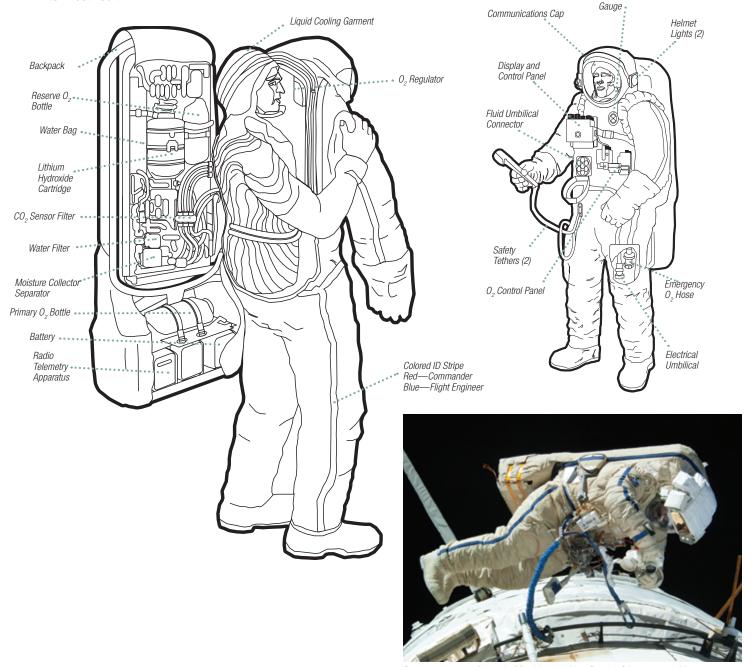
Orlan Spacesuit

Russian Federal Space Agency (Roscosmos)/ Science Production Enterprise Zvezda

The Orlan-MK spacesuit is designed to protect an EVA (Extravehicular Activity) crewmember from the vacuum of space, ionizing radiation, solar energy, and micrometeoroids. The main body and helmet of the suit are integrated and are constructed of aluminum alloy. Arms and legs are made of a flexible fabric material. Crewmembers enter from the rear via the backpack door, which allows rapid entry and exit without assistance. The Orlan-MK spacesuit is a "one-size-fits-most" suit.

Suit's nominal pressure	0.4 atm (5.8 psi)
Atmosphere	100% oxygen
Maximum EVA duration	7 h
Mass of entire EMU	108 kg (238 lb)
Suit life	15 EVAs or 4 years without return to Earth

Suit Pressure



Russian cosmonaut Alexander Misurkin, attired in a Russian Orlan spacesuit (blue stripes),participates in a session of extravehicular activity (EVA) to continue outfitting the International Space Station.

Mobile Servicing System (MSS)

Space Station Remote Manipulator System (SSRMS/Canadarm2)

Special Purpose Dexterous Manipulator (SPDM/Dextre) Mobile Base System (MBS)

Canadian Space Agency (CSA)

Three components of MSS

berth them to the ISS.

The Mobile Servicing System (MSS) is a sophisticated robotics suite that plays a critical role in the assembly, maintenance, and resupply of the ISS. The MSS Operations Complex in Saint Hubert, Quebec, is the ground base for the MSS, which is composed of three robots that can work together or independently. The MSS was built for the CSA by MacDonald, Dettwiler and Associates Ltd. (MDA).

The Space Station Remote Manipulator System (SSRMS), known as Canadarm2, is a 56-foot- long robotic arm that assembled the ISS module by module in space.

It is regularly used to move supplies, equipment, and

even astronauts, and captures free-flying spacecraft to

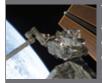
	SSRMS	MBS	SPDM
Length/ height	17.6 m (57 ft)		3.5 m (11.4 ft)
Maximum diameter	.36 m (1.2 ft)		.88 m (2.9 ft)
Dimensions		5.7 × 4.5 × 2.9 m	
		(18.5 × 14.6 × 9.4 ft)	
Mass	1,497 kg (3,300 lb)	1,450 kg (3,196 lb)	1,662 kg (3,664 lb)
Degrees of freedom	7		

Roll Joint Yaw Joint Latching End Effector B Pitch Joint Video Distribution

Camera, Light, and Pan and Tilt Unit *• Arm Control Unit (ACU)



The Special Purpose Dexterous Manipulator (SPDM), also known as Dextre, performs routine maintenance on the ISS. Equipped with lights, video equipment, a tool platform, and four tool holders, Dextre's dual-arm design and precise handling capabilities reduces the need for spacewalks.



The Mobile Base System (MBS) provides a movable work platform and storage facility for astronauts during spacewalks. With four grapple fixtures, it can serve as a base for both the Canadarm2 and the Special Purpose Dexterous Manipulator (SPDM) simultaneously.



Backdropped by Earth's horizon and the blackness of space, the Canadian-built Dextre, also known as the Special Purpose Dextrous Manipulator (SPDM), is featured in this image.

MBS Capture Latch

Power Data Grapple Fixture (PDGF)

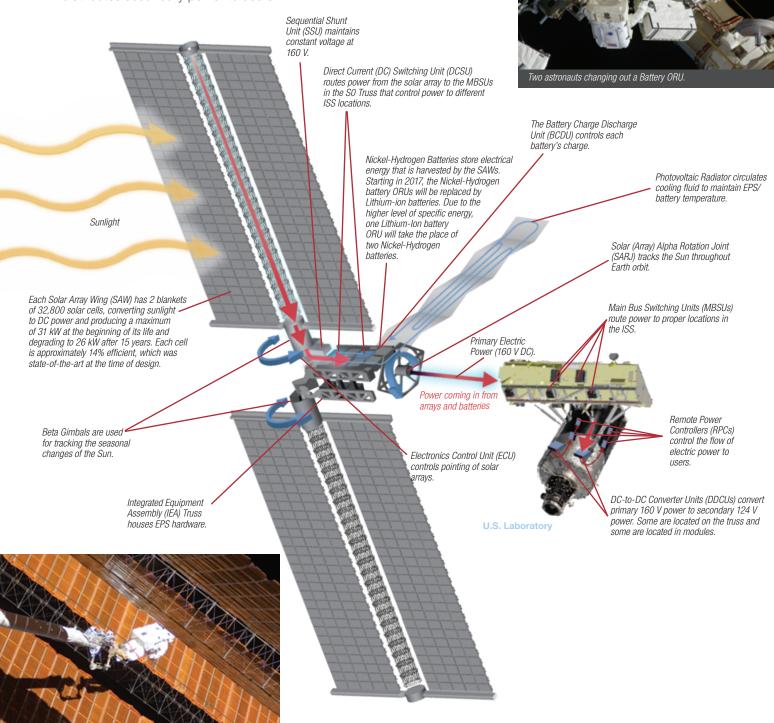
Camera and Light Assembly

Payload and Orbital Replacement Unit (ORU) Accommodation

... Pitch Joint

Electrical Power System (EPS)

The EPS generates, stores, and distributes power and converts and distributes secondary power to users.



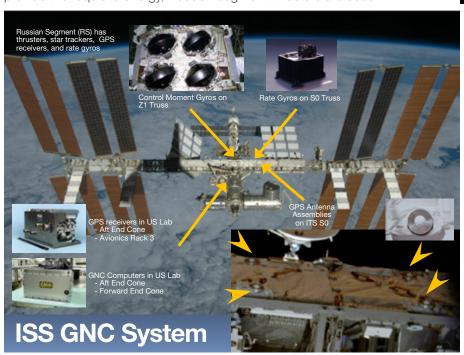
NASA astronaut Scott Parazynski, anchored to the Articulating Portable Foot Restraint (APFR) on the Orbiter Boom Sensor System (OBSS), assesses repair work on the P6 4B Solar Array Wing (SAW) as the array is deployed during an extravehicular activity (EVA).

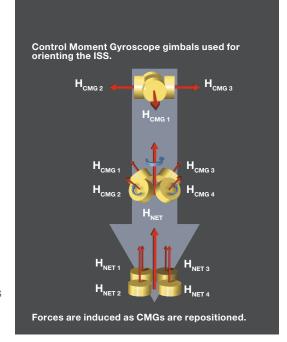
Guidance, Navigation, and Control (GN&C)

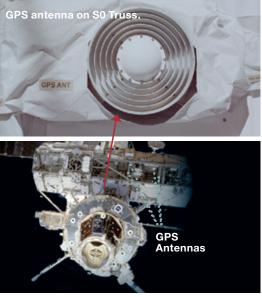
The ISS is a large, free-flying vehicle. The attitude or orientation of the ISS with respect to Earth and the Sun must be controlled; this is important for maintaining thermal, power, and microgravity levels, as well as for communications.

The ISS GN&C hardware consists of GPS receivers and antennas, rate gyro sensors, control moment gyros on the U.S. segment, and thrusters, star trackers, GPS receivers, and rate gyros on the Russian segment. The GPS receivers provide information about the location of the ISS, and the rate gyros provide information about the change in orientation of the ISS. Both U.S. and Russian segment GN&C systems have extensive software to be able to determine and control the ISS orientation. The GN&C system tracks the Sun, communications and navigation satellites, and ground stations. Solar arrays, thermal radiators, and communications antennas aboard the ISS are pointed using information from the GN&C system.

The preferred method of attitude control is the use of Control Moment Gyroscopes (CMGs), sometimes called gyrodynes in other programs, mounted on the Z1 Truss segment. Each CMG has 98-kilogram (220-pound) flywheel that spins at 6,600 revolutions per minute (rpm). The high-rotational velocity and large mass of the flywheel allow a considerable amount of angular momentum to be stored. Each CMG has gimbals such that the flywheels can be repositioned. As the flywheel is repositioned, the resulting force orients the ISS. Using multiple CMGs permits the ISS to be moved to new attitudes or permits the attitude to be held constant. The advantages of this system are that it relies on electrical power generated by the solar arrays and that it provides smooth, continuously variable attitude control. CMGs are; however, limited in the amount of angular momentum they can provide and the rate at which they can move the station. When CMGs can no longer provide the requisite energy, Russian segment thrusters are used.





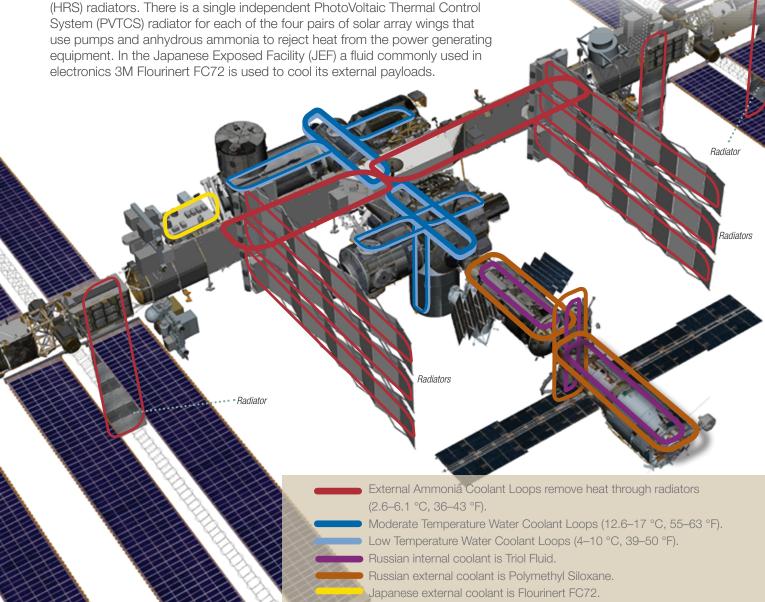


Thermal Control System (TCS)

The TCS maintains ISS temperatures within defined limits. The four components used in the Passive Thermal Control System (PTCS) are insulation, surface coatings, heaters, and heat pipes.

The Active Thermal Control System services point source heat loads such as electrical equipment on cold plates as well as providing heat rejection for the crew cabin using pumps to move heat rejection fluids through the vehicle. The water-based internal cooling loops are used in controlling humidity and removing heat loads generated by the crew and electronic equipment. This heat is transferred to interface heat exchangers located on the exterior of the vehicle. The interface heat exchangers flow water on one side, and transfer the heat to anhydrous ammonia flowing on the other side. The warmed ammonia rejects heat to space from the six large Heat Rejection Subsystem (HRS) radiators. There is a single independent PhotoVoltaic Thermal Control System (PVTCS) radiator for each of the four pairs of solar array wings that





Integrated Truss Assembly The truss assemblies provide attachment points for the solar arrays, thermal control radiators, and external payloads. Truss assemblies also contain electrical and cooling utility lines, as well as the mobile transporter rails. The Integrated Truss Structure (ITS) is made up of 11 segments plus a separate component called Z1. These segments, which are shown in the figure, will be installed on the station so that they extend symmetrically from the center of the ISS.

At full assembly, the truss reaches 108.5 meters (356 feet) in length across the extended solar arrays. ITS segments are labeled in accordance with their location. P stands for "port," S stands for "starboard," and Z stands for "Zenith."

- Solar Array Alpha Rotary Joint
- Ammonia Tank Assembly
- Assembly Contingency **Baseband Signal Processor**
- **Battery Charge Discharge Unit**
- Beta Gimbal Assemblies
- Cable Trays
- **Charged Particle Directional Spectrometer**
- 9 Direct Current Switching Unit (DCSU)
- 10 DC-to-DC Converter Unit (DDCU)
- 11 Deployed Thermal System Radiator
- 12 Grapple Fixture

Flyaround view of the forward (FWD) and standown (STBD) sides of the International Space Station (ISS), taken aboard Atlantis after undeckning on STS 136 Flight Day 12 (FD12)

- 13 Inboard Lower Camera
- 14 Main Bus Switching Units
- 15 Mast Storage Canister
- 16 Mobile Transporter Rails
- 17 Multiplexer/De-Multiplexers
- 18 Nitrogen Tank Assembly (interior to truss) 19 Outboard Lower Camera
- 20 Photovoltaic Radiator
- 21 Pump Flow Control Assembly
- 22 Pump Flow Control Subassembly

- 23 Pump Module
- 24 PVR Controller Unit 25 PVR Grapple Fixture Bar
- 26 Radiator Beam Valve Module
- 27 Remote Power Control Modules
- 28 Rotary Joint Motor Controller
- 29 S-Band Antenna
- 30 Solar Array Alpha Rotary Joint Drive Lock Assembly
- 31 Solar Array Wing
- 32 Stowed Photovoltaic Radiator
- 33 Struts
- 34 Thermal Control System Radiator Beam
- 35 Thermal Radiator Rotary Joint with Flex Hose **Rotary Coupler**
- 36 Transponder

- 39 Umbilical Mechanism Assemblies
- 41 Unpressurized Cargo Carrier Attachment
- 42 Wireless Video System Antenna

Propulsion











- Progress Cargo Module Progress Propulsion System
- Attitude Control Engines (32)
- 6. Propellant Tanks (4)

- Correction and Docking Engines (2) Correction and Docking Engines (2)
- Accurate Stabilization Engines (16)
- Propellant Tanks (16)







Service Module Rocket Engines

Main Engines: 2,300 kgf (661 lbf); one or both main engines can be fired at a time; they are fed from the Service Module's propellant storage system

Attitude Control Engines: 32 multidirectional, 13.3 kgf (29.3 lbf); attitude control engines can accept propellant fed from the Service Module, the attached Progress, or the FGB propellant tanks

Service Module Propellant Storage

Two pairs of 200-L (52.8-gal) propellant tanks (two nitrogen tetroxide N_cO_c and two unsymmetrical dimethyl hydrazine [UDMH]) provide a total of 860 kg (1,896 lb) of usable propellant. The propulsion system rocket engines use the hypergolic reaction of UDMH and N₂O₄. The Module employs a pressurization system using N₂ to manage the flow of propellants to the engines.

FGB Rocket Engines

FGB engines are deactivated once the Service Module is in use.

FGB

Correction and Docking Engines: 2 axis, 417 kgf (919 lbf)

Docking and Stabilization Engines:

24 multidirectional, 40 kgf (88 lbf)

Accurate Stabilization Engines:

16 multidirectional, 1.3 kgf (2.86 lbf)

FGB Propellant Storage

There are two types of propellant tanks in the Russian propulsion system: bellows tanks (SM, FGB), able both to receive and to deliver propellant, and diaphragm tanks (Progress), able only to deliver fuel.

Sixteen tanks provide 5,760 kg (12,698 lb) of N₂O₄ and UDMH storage: eight long tanks, each holding 400 L (105.6 gal), and eight short tanks, each holding 330 L (87.17 gal).

Node 3

Node 1

Quest **Airlock** Columbus

Node 2

JEM

The ISS orbits Earth at an altitude ranging from 370 to 460 kilometers (230 to 286 miles) and at a speed of 28,000 kilometers per hour (17,500 miles per hour). Due to atmospheric drag, the ISS is constantly slowed and must be re-boosted periodically to maintain its altitude. The ISS must be maneuvered to assist in rendezvous and docking of visiting vehicles and to avoid debris.

Destiny

Thrusters located on the Service Module, as well as on the docked vehicles are used to perform these maneuvers.

The Service Module provides thirty-two 13.3-kilograms force (29.3-pounds force) attitude control engines. The engines are combined into two groups of 16 engines each, taking care of pitch, yaw, and roll control. Each Progress provides 24 engines similar to those on the Service Module. When a Progress is docked at the aft Service Module port, these engines can be used for pitch and yaw control. When the Progress is docked at the Russian Docking Module, the Progress engines can be used for roll control.

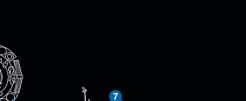
Besides being a resupply vehicle, the Progress provides a primary method for reboosting the ISS. Eight 13.3-kilograms force (29.3-pounds force) Progress engines can be used for reboosting. The Service Module engines can also be used for reboosting. The Progress can also be used to resupply propellants stored in the FGB that are used in the Service Module engines.

Progress Rocket Engines

Progress is used for propellant resupply and for performing reboosts. For the latter, Progress is preferred over the Service Module. Progress uses four or eight attitude control engines, all firing in the direction for reboost.

Orbital Correction Engine: 1 axis, 300 kgf (661 lbf)

Attitude Control Engines: 28 multidirectional, 13.3 kgf (29.3 lbf)

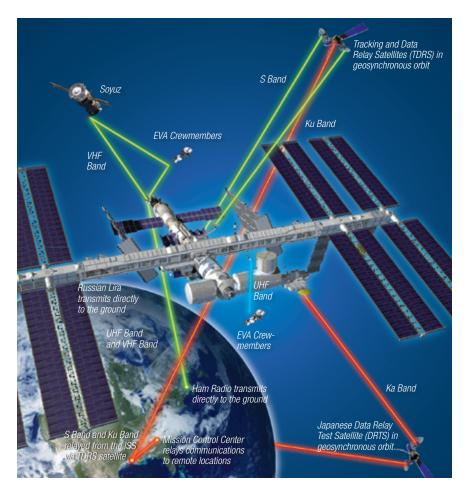


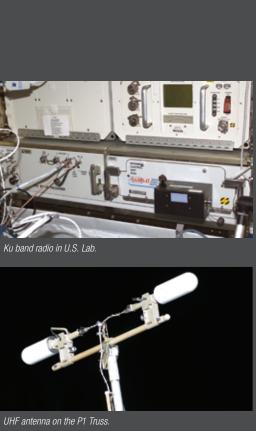
Communications

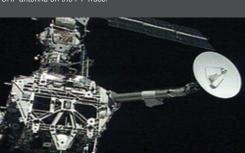
The Communications & Tracking (C&T) System provides Radio Frequency (RF) links between ISS and the Mission Control Center-Houston (MCC-H), other ground control centers, and Payload Operations Centers (POCs) around the world via the Tracking & Data Relay Satellite System provided by NASA's Space Network. These links support all ISS mission operations via real-time exchange of digital audio, video, and systems and payload data. It also enables the flight control team and POCs on the ground to control, operate and monitor performance of ISS systems and payloads.

The C&T System provides the following:

- Two-way audio between crew aboard the ISS and with Control Centers, including exchange of audio and receipt of video from Extravehicular Activity (EVA) crew.
- Downlink of high-rate payload science data to MCC-H and the Payload Operations & Integration Center (POIC) for distribution to payload scientists.
- Two-way crew support (email, daily planning products, family & medical teleconferencing, IP Phone, public affairs broadcasts).
- Transmission of multiple video channels to the ground.
- Communications with Visiting Vehicles including the new Common Communications for Visiting Vehicles (C2V2) system currently in development for use by future Commercial Crew and Commercial Cargo/ Resupply vehicles.







Ku band radio on exterior of ISS.





Micrometeoroid and Orbital **Debris (MMOD) Protection**

Spacecraft in low-Earth orbit are continually impacted by meteoroids and orbital debris. Most of the meteoroids and debris are small and cause little damage. A small fraction of the meteoroid and debris populations, however, are larger and can cause severe damage in a collision with a spacecraft.

The International Space Station (ISS) is the largest spacecraft ever built. With the completion of assembly more than 11,000m² (118,400 ft²) of surface area is exposed to the space environment. Due to its large surface area, its long planned lifetime, and the potential for a catastrophic outcome of a collision, protecting the ISS from meteoroids and debris poses a unique challenge.

Many ISS elements are shielded from impacts. The primary shielding configurations are:

- Whipple shield is a two layer shield consisting of an outer bumper, usually aluminum, spaced some distance from the module pressure shell wall; the bumper plate is intended to break up, melt, or vaporize a particle on impact. This type of shield is used where few MMOD impacts are expected (aft, nadir and zenith areas of ISS.)
- Stuffed Whipple shield consists of an outer bumper, an underlying blanket of Nextel ceramic cloth, and Kevlar fabric to further disrupt and disperse the impactor spaced a distance from the module pressure shell. Because these shields have a higher capability than Whipple shields, they are used where more MMOD impacts are expected to occur (front and starboard/port sides of ISS).

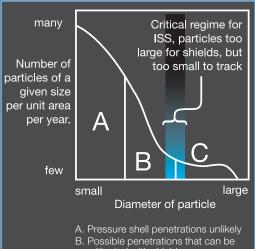
Windows are generally multi-pane with separate and redundant pressure panes, as well as an outer debris pane and/or shutter to provide protection from MMOD. Other critical areas, such as electrical, data, and fluid lines on the truss and radiator panels, are toughened with additional protective layers to prevent loss from MMOD impacts.



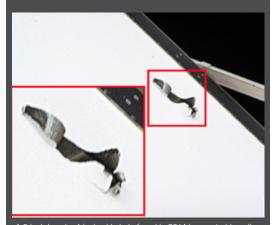
Exterior view of the Cupola Module and Japan Aerospace Exploration agency astronaut Koichi Wakata inside, looking out through one of the windows.



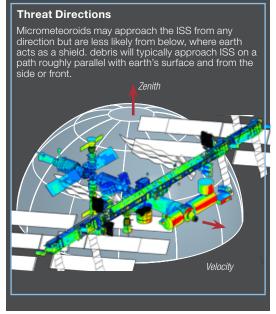
U.S. Lab in orbit, above, NASA astronaut Ken Bowersox uses camera at window with partially deployed shutter, to right, window shutter fully deployed; outer debris shields are visible.



- mitigated with shields
- C. Larger debris is tracked and ISS is maneuvered out of impact path



A 5 inch long by 4 inch wide hole found in 2014 in a port-side radiator for the solar array power system. No coolant leak occurred due to this impact damage





Launched in 1998 and involving the U.S., Russia, Canada, Japan, and the participating countries of the European Space Agency the International Space Station is one of the most ambitious international collaborations ever attempted. It has been visited by astronauts from 14 countries.

Operating the space station is even more complicated than other space flight endeavors because it is an international program. The station requires the support of facilities on the Earth managed by all of the international partner agencies, countries and commercial entities involved in the program.

ISS Operations and Management

CSA Headquarters

Mobile Servicing System Control and Training Saint-Hubert, Quebec, Canada

European Astronaut Centre Cologne, Germany

Telescience Support Center

Glenn Research Center Cleveland, Ohio, U.S.

Telescience Support Center

Ames Research Center Moffett Field, California, U.S.

ISS Training

Program Management Mission Control Johnson Space Center Houston, Texas, U.S.

NASA Headquarters *Washington D.C., U.S.*

Launch Control

Kennedy Space Center Florida, U.S.

Payload Operations Center

Marshall Space Flight Center HUntsville, Alabama, U.S.







ESA European Space Research and Technology Centre (ESTEC)

Noordwijk, Netherlands

ISS Mission Control Korolev, Russia

Roscosmos Headquarters Moscow, Russia

Russian Launch Control
Baikonur Cosmodrome
Baikonur, Kazakhstan

Gagarin Cosmonaut Training Center (GCTC) Star City, Russia

> H-II Launch Control Tanegashima , Japan

JEM HTV Control Center and Crew Training Tsukuba, Japan

> JAXA Headquarters Tokyo, Japan

Columbus Control Center Oberpfaffenhofen, Germany

ESA Headquarters *Paris, France*





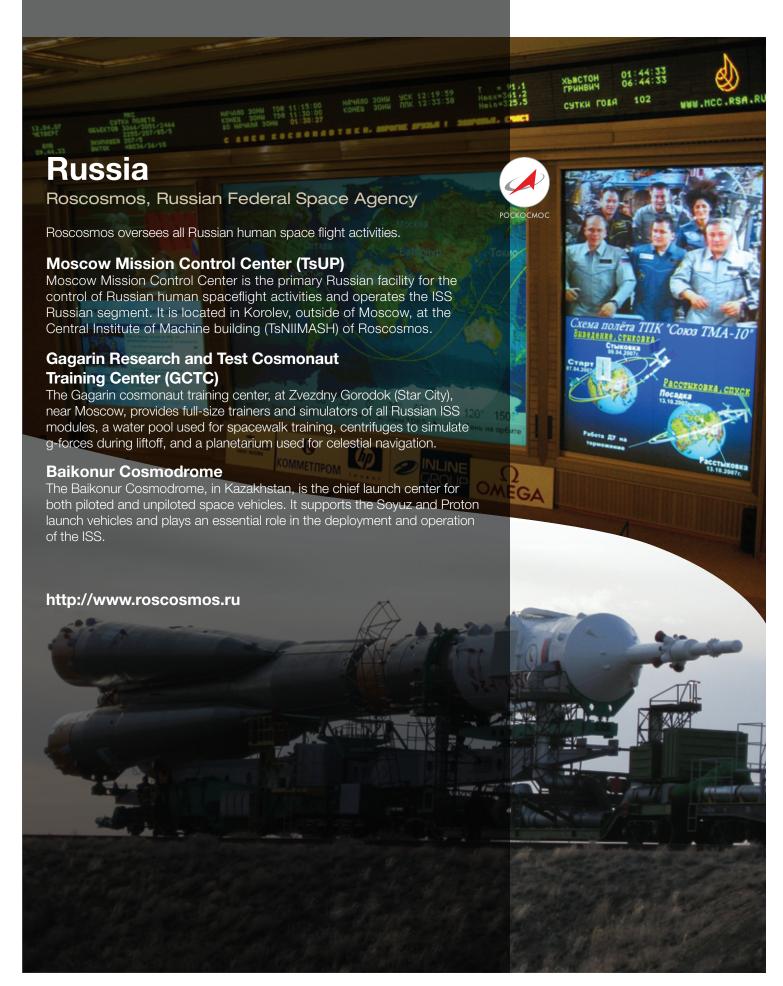


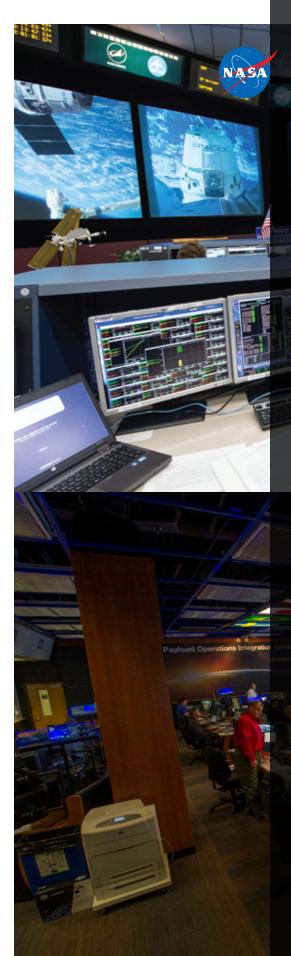












United States of America

National Aeronautics and Space Administration (NASA)

NASA Headquarters (HQ)

NASA Headquarters in Washington, DC, exercises management over the NASA Field Centers, establishes management policies, and analyzes all phases of the ISS program.

Johnson Space Center (JSC)

Johnson Space Center in Houston, TX, directs the ISS program. Mission control operates the U.S. On-orbit Segment (USOS) and manages activities across the ISS in close coordination with the international partner control centers. JSC is the primary center for spacecraft design, development, and mission integration. JSC is also the primary location for crew training. Commercial Resupply Services contracts with OrbitalATK and SpaceX U.S. commercial companies are managed by JSC to provide reliable commercial cargo transportation that is critical for the continued support of the ISS research community. NASA's contract strategy enabled the contractor's responsibility to provide an end to end service while meeting milestone payment and mission success criteria. NASA's key focus is managing the research, cargo and safety aspects for each mission to the ISS. A follow-on contract for ISS services will expand the vehicle research capability and promote further U.S. space industry competition.

Kennedy Space Center (KSC)

Kennedy Space Center in Cape Canaveral, FL, prepared the ISS modules and Space Shuttle orbiters for each mission, coordinated each countdown, and managed Space Shuttle launch and post-landing operations. The goal of NASA's Commercial Crew Program (CCP) Commercial Crew Transportation Capability will enable NASA to ensure crew transportation system is safe, reliable and cost-effective. The certification process will assess progress throughout the production and testing of one or more integrated space transportation systems, which include rockets, spacecraft, missions and ground operations. Requirements also include at least one crewed flight test to the space station before NASA certification of a U. S. spacecraft can be granted. CCP missions will then provide ISS crew rotation and double the amount of critical science research being performed on-orbit.

Marshall Space Flight Center (MSFC)

Marshall Space Flight Center's Payload Operations and Integration Center (POIC) controls the operation of U.S. experiments and coordinates partner experiments aboard the ISS. MSFC oversaw development of most U.S. modules and the ISS ECLSS system.

Telescience Support Centers (TSCs)

Telescience Support Centers around the country are equipped to conduct science operations on board the ISS. These TSCs are located at Marshall Space Flight Center in Huntsville, AL; Ames Research Center (ARC) in Moffett Field, CA; Glenn Research Center (GRC) in Cleveland, OH; and Johnson Space Center in Houston, TX.

http://www.nasa.gov









Roscosmos

Russia

JAXA

Japan

Ariane 2008-2015 ESA

Europe

Shuttle 1998-2011

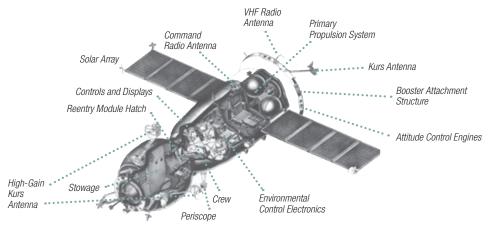
NASA United States

Russia Japan Europe U.S.			U.S.		
	Soyuz SL-4	Proton SL-12	H-IIB	Ariane 5	Space Shuttle
First launch to ISS	2000	1998	2009	2008	1998
Launch site(s)	Baikonur Cosmodrome	Baikonur Cosmodrome	Tanegashima Space Center	Guiana Space Center	Kennedy Space Center
Launch performance payload capacity	7,150 kg (15,750 lb)	20,000 kg (44,000 lb)	16,500 kg (36,400 lb)	18,000 kg (39,700 lb)	18,600 kg (41,000 lb) 105,000 kg (230,000 lb), orbiter only
Return performance payload capacity	N/A	N/A	N/A	N/A	18,600 kg (41,000 lb) 105,000 kg (230,000 lb), orbiter only
Number of stages	2 + 4 strap-ons	4 + 6 strap-ons	2 + 4 strap-ons	2 + 2 strap-ons	1.5 + 2 strap-ons
Length	49.5 m (162 ft)	57 m (187 ft)	57 m (187 ft)	51 m (167 ft)	56.14 m (18.2 ft) 37.24 m (122.17 ft), orbiter only
Mass	310,000 kg (683,400 lb)	690,000 kg (1,521,200 lb)	531,000 kg (1,170,700 lb)	746,000 kg (1,644,600 lb)	2,040,000 kg (4,497,400 lb)
Launch thrust	6,000 kN (1,348,800 lbf)	9,000 kN (2,023,200 lbf)	5,600 kN (1,258,900 lbf)	11,400 kN (2,562,820 lbf)	34,677 kN (7,795,700 lbf)
Payload examples	Soyuz Progress Pirs	Service Module Functional Cargo Block (FGB) Multipurpose Lab Module (MLM)	H-II Transfer Vehicle (HTV)	Ariane Automated Transfer Vehicle (ATV)	Shuttle Orbiter, Nodes 1–3, U.S. Lab, JEM, Truss elements, Airlock, SSRMS

Soyuz

Russian Federal Space Agency (Roscosmos)/ S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

Soyuz spacecraft have been in use since the mid-1960s and have been upgraded periodically. Soyuz can support independently three suited crewmembers for up to 5.2 days and be docked to the ISS up to 200 days. The vehicle has an automatic docking system and may be piloted automatically or by a crewmember. The Soyuz provides transportation of Crewmembers and cargo to/from the ISS. The Soyuz is comprised of 3 modules, the Descent module is the only one which returns to Earth.







Soyuz spacecraft approaching the International Space Station

Mission Sequence

Cosmonaut Anton Shkaplerov reviews procedures in the descent module of a docked Soyuz TMA-1 spacecraft.

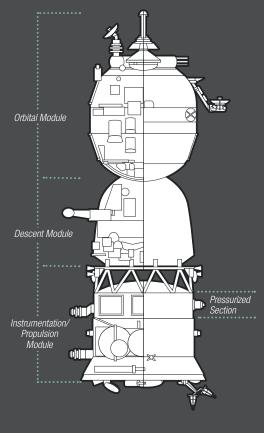
Launch and Aborts

- 1 Launch
- Abort using escape rocket
- 2 Escape rocket jettison, nose shroud separation (160 seconds in full)
- 3 Staging (186 seconds)
- Abort by separation of Soyuz
- 4 Orbital velocity (526 seconds)

Return

- Soyuz retrofire, orbital module separation, reentry module separation
- 6 Pilot parachute deploys
- Drogue parachute deploys
- Main parachute reefed
- 8 Main parachute fully deployed9 Reentry heatshield jettison
- Landing, retro rocket firing

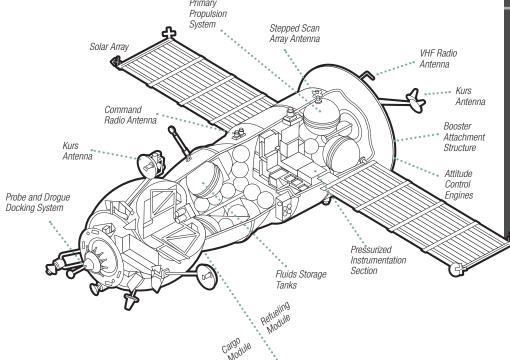
Launch mass	7,190 kg (15,851 lb)
Descent module	2,900 kg (6,393 lb)
Orbital module	1,300 kg (2,866 lb)
Instrumentation/ propulsion module	2,600 kg (5,732 lb)
Delivered payload with two crewmembers with three crewmembers	230 kg (507 lb) 170 kg (375 lb)
Returned payload	50 kg (110 lb)
Length	7 m (22.9 ft)
Maximum diameter	2.7 m (8.9 ft)
Diameter of habitable modules	2.2 m (7.2 ft)
Solar array span	10.6 m (34.8 ft)
Volume of orbital module	6.5 m³ (229.5 ft³)
Volume of descent module	4 m³ (141.3 ft³)
Descent g-loads	4–5 g
Final landing speed	2 m/s (6.6 ft/s)
Orbital Module	



Progress

Russian Federal Space Agency (Roscosmos)/ S.P. Korolev Rocket and Space Corporation Energia (RSC Energia)

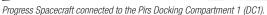
Progress is a resupply vehicle used for dry cargo, propellant, water, and gas deliveries to the ISS. Once docked to the ISS, Progress engines can boost the ISS to higher altitudes and control the orientation of the ISS in space. Typically, four Progress vehicles bring supplies to the ISS each year. Progress is based upon the Soyuz design, and it can either work autonomously or can be flown remotely by crewmembers aboard the ISS. After a Progress vehicle is filled with trash from the ISS, and after undocking and deorbit, it is incinerated in Earth's atmosphere at the end of its mission. During its autonomous flight (up to 30 days), Progress can serve as a remote free-flying research laboratory for conducting space experiments.

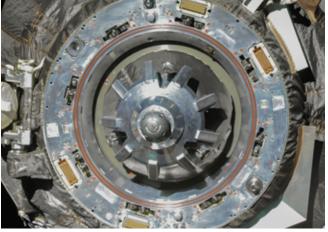


Length	7.4 m (24.3 ft)	
Maximum diameter	2.7 m (8.9 ft)	
Span with solar arrays	10.7 m (35.1 ft)	
Launch mass	7,440 kg (16,402 lb)	
Cargo upload capacity	2,250 kg (4,960 lb)	
Pressurized habitable volume	7.0 m³ (247.2 ft³)	
Engine thrust	2,942 N (661 lbf)	
Orbital life	6 mo	
Dry cargo max	1,700 kg (3,748 lb)	
Refueling propellant	870 kg (1,918 lb)	

Cargo Load		
	Maximum	Typical*
Dry cargo such as bags	1,800 kg (3,968 lb)	1,070 kg (2,360 lb)
Water	420 kg (925 lb)	300 kg (660 lb)
Air	50 kg (110 lb)	47 kg (103 lb)
Refueling propellant	1,700 kg (3,748 lb)	870 kg (1,918 lb)
Reboost propellant	250 kg (550 lb)	250 kg (550 lb)
Waste capacity	2,140 kg (4,718 lb)	2,000 kg (4,409 lb)







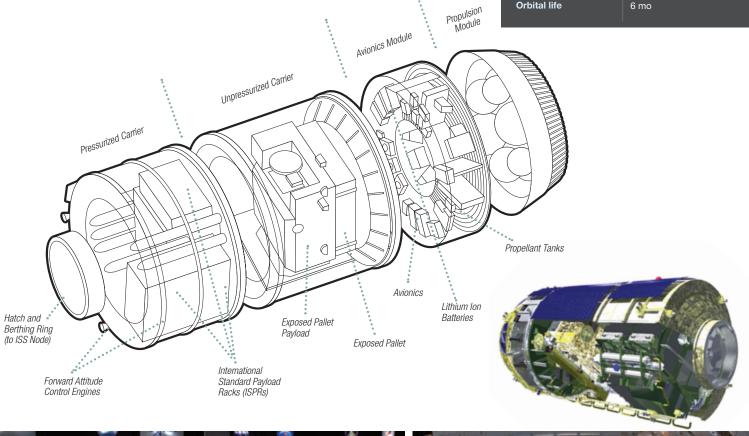
This close-up view shows the docking mechanism of the unpiloted Russian ISS Progress resupply ship as it undocks from the International Space Station's Pirs Docking Compartment.

JAXA H-II Transfer Vehicle (HTV)

Japan Aerospace Exploration Agency (JAXA)/ Mitsubishi Heavy Industries, Ltd.

The H-II Transfer Vehicle is an autonomous logistical resupply vehicle designed to berth to the ISS using the Space Station Remote Manipulation System (SSRMS). HTV offers the capability to carry logistics materials in both its internal pressurized carrier and in an unpressurized carrier for exterior placement. It is launched on the H-II unmanned launch vehicle and can carry dry cargo, gas and water. After fresh cargo is unloaded at the ISS, the HTV is loaded with trash and waste products; after unberthing and deorbit, it is incinerated during reentry.

Length	9.2 m (30 ft)
Maximum diameter	4.4 m (14.4 ft)
Launch mass	16,500 kg (36,375 lb)
Cargo upload capacity	5,500 kg (12,125 lb)
Pressurized habitable volume	14 m³ (495 ft³)
Unpressurized volume	16 m³ (565 ft³)
Orbital life	6 mo









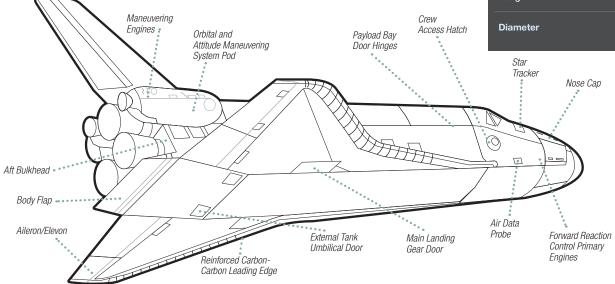
View of H-II Transfer Vehicle (HTV) docked to Node 2.

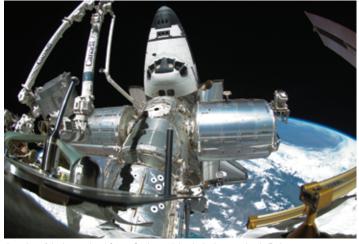
Space Shuttle Orbiter/ Discovery, Atlantis, Endeavour

NASA/Boeing 1981-2011

Between the first assembly launch using the Space Shuttle on December 4, 1998, and the final landing on July 21, 2011, NASA's space shuttle fleet – Discovery, Atlantis and Endeavour – helped construct the largest structure in space, the International Space Station. The Space Shuttle was used to deliver most of the ISS modules and major components. It also provided crew rotation (beginning in November, 2001), science and maintenance cargo delivery, and is the only vehicle that provided the capability to return significant payloads.

Length	37.2 m (122.2 ft)
Height	17.3 m (56.7 ft)
Wingspan	23.8 m (78 ft)
Typical mass	104,000 kg (230,000 lb)
Cargo capacity	16,000 kg (35,000 lb) (typical launch and return to ISS)
Pressurized habitable volume	74 m³ (2,625 ft³)
Mission length	7-16 days, typical
Number of crew	7, typical
Atmosphere	oxygen-nitrogen
Cargo Bay	
Length	18.3 m (60 ft)
Diameter	4.6 m (15 ft)





 $\label{lem:approx} \textit{A portion of the International Space Station and the docked space shuttle Endeavour.}$



Space shuttle Atlantis launches from Launch Pad 39A at Kennedy Space Center on the STS-135 mission, the final flight of the Space Shuttle Program (SSP).

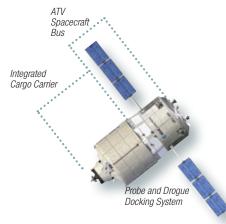
Automated Transfer Vehicle (ATV)

European Space Agency (ESA)/European Aeronautic Defence and Space Co. (EADS) 2008-2015

The European Space Agency Automated Transfer Vehicle was an autonomous logistical resupply vehicle that provided the crew with dry cargo, atmospheric gas, water, and propellant. After the cargo was unloaded, the ATV was reloaded with trash and waste products, undocked, and was incinerated during reentry. Five ATVs, Jules Verne, Johannes Kepler, Edoardo Amaldi, Albert Einstein, and Georges Lemaître were launched, with the first in March 2008. The last ATV was undocked from ISS in February 2015, ending

the ATV programme. Attitude Control Spacecraft Bus Engines (20) Integrated Cargo Carrier Primary based on MPLM design Maneuverina Engines (4) /SS Service Module Titanium Tanks for carrying water, propellant, and oxygen. Cargo : Environmental Compartment Control System ISPRs (8) Solar

Length	10.3 m (33.8 ft)
Maximum diameter	4.5 m (14.8 ft)
Span across solar arrays	22.3 m (73.2 ft)
Launch mass	20,750 kg (45,746 lb)
Cargo upload capacity	7,667 kg (16,903 lb)
Engine thrust	1,960 N (441 lbf)
Orbital life	6 mo
Cargo Load	
Dry cargo such as bags	5,500 kg (12,125 lb)
Water	840 kg (1,852 lb)
Air (O ₂ , N ₂)	100 kg (220 lb)
Refueling propellant	860 kg (1,896 lb)
Reboost propellant	4,700 kg (10,360 lb)
Waste capacity	6,500 kg (14,330 lb)





ESA astronaut André Kuipers floats into the ATV.



View of European Space Agency (ESA) Edoardo Amaldi Automated Transfer Vehicle-3 (ATV-3) approaching the International Space Station (ISS).



these systems onboard ISS in such a way that they will support market driven commercial research. NASA is also fostering new commercial markets in LEO through its innovative cargo resupply services and crew transportation contracts.

Requirements and Benefits

Commercial Crew Requirements for International Space Station Missions

- Transport 4 NASA or NASA-sponsored crew members
- Transport 220.5 pounds of pressurized cargo
- Stay on orbit docked to the station for up to 210 days
- Serve as a safe haven and act as a lifeboat in case of an emergency
- Able to quickly return to Earth for time-sensitive cargo

Commercial Crew Benefits

- Cost-Effective: Developing safe, reliable and costeffective crew transportation to the International Space Station that reduces reliance on foreign systems.
- American Ingenuity: Lowering the cost of access to space and enhancing the U.S. industrial base.
 - NASA's Commercial Crew Program partner companies, and their providers and suppliers, are leading a truly national effort.
 - More than 150 companies across 37 states are applying their most efficient and innovative approaches to get astronauts back into space on American-led spacecraft and rockets.
 - American companies have the flexibility to determine the design details and development approach for state-of-the-art U.S.-based transportation systems to and from the International Space Station and to develop other space markets in low-Earth orbit.
- Journey to Mars: Using limited resources wisely to enable deep space capabilities.
 - NASA is on a dual path for human exploration.
 By turning over low-Earth orbit flights to the commercial aerospace industry, NASA can pursue the challenges of deep space exploration and our journey to Mars.
- Focus on Science: Two times more research.
 - The International Space Station crew spends about 35 hours each week conducting research in Earth, space, physical and biological sciences to advance scientific knowledge for the benefit of people living on Earth.
 - NASA requires these spacecraft to carry a crew of four, enabling the station crew to expand from six to seven astronauts and cosmonauts.
 - It only takes six crew members to maintain the station, so an extra person translates to 40 additional hours of crew time for research.







Antares and Cygnus

Orbital ATK

The Cygnus missions are launched on an Antares from the NASA Wallops Flight Facility on Wallops Island, Virginia. The first stage is powered by two RD-181 engines, and the second stage is a Castor 30XL. The spacecraft that launches on the Antares is called the Cygnus. The Cygnus spacecraft is an automated logistical resupply vehicle designed to rendezvous with the ISS and is grappled and berthed using the Space Station Remote Manipulator System (SSRMS). The Cygnus has a Pressurized Cargo Module (PCM) that brings cargo (logistics and utilization) to the ISS. The other section of the spacecraft is the Service Module (SM), which houses the avionics, electrical, propulsion, and guidance systems. After cargo is transferred to the ISS, Cygnus is then loaded with trash for disposal. Once the mission is complete, the Cygnus unberths from the ISS and is destroyed (incinerated) upon re-entry into the Earth's atmosphere.









Antares	
Height	40.1 m
Diameter	3.9 m
Mass at launch	290,000 - 310,000 kg
First stage thrust	4.17 MN
Second stage thrust	533 kN
Cygnus	
PCM Length	5.1 m
Diameter	3.05 m
Maximum Upmass Pressurized	3200 -3500 kg
Maximum Downmass Pressurized	3500 kg
Maximum Upmass Unpressurized	0
Maximum Downmass Unpressurized	0
Payload volume Pressurized	26 m³



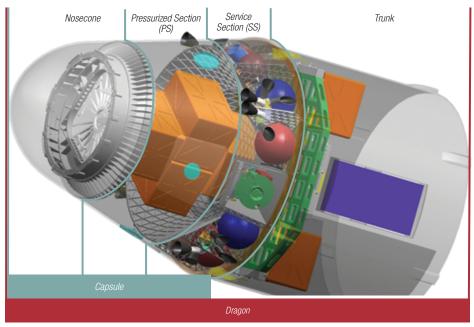
Falcon 9 and Dragon

Space Exploration Technologies (SpaceX)

The SpaceX missions are launched on a Falcon 9 from Launch Complex 40 at Cape Canaveral Air Force Station, Florida. The first stage is powered by nine SpaceX Merlin engines, and the second stage is also a single SpaceX Merlin engine. The spacecraft that launches on the Falcon 9 is called the Dragon.

The Dragon spacecraft is an automated logistical resupply vehicle designed to rendezvous with the ISS and is grappled and berthed using the Space Station Remote Manipulator System (SSRMS).

The Dragon has a capsule section for delivering pressurized cargo, and another section called the "trunk" is used to deliver unpressurized cargo to the ISS. Once the mission is complete, the Dragon unberths from the ISS. The trunk is jettisoned and destroyed during reentry into the atmosphere, whereas the Dragon capsule, with its valuable pressurized return cargo, reenters the Earth's atmosphere and lands in the ocean with the use of parachutes. The Dragon capsule is recovered by SpaceX and is transported back to their facility for return cargo processing.





SpaceX's Dragon cargo capsule is seen here docked to the Earth facing port of the Harmony module.

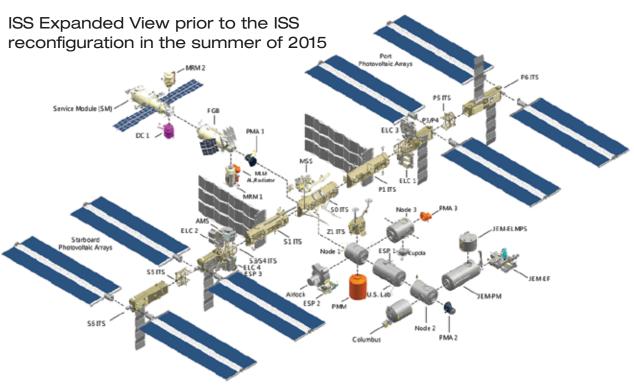
Falcon 9	
Height	48.1 m (157.80 ft)
Diameter	3.66 m (12 ft)
Mass at launch	313,000 kg (690,047 lb)
First stage thrust	3.80 MN (854,000 lb)
Second stage thrust	414 kN (93,000 lb)
Dragon	
Height	5.1 m (16.73 ft)
Diameter	3.66 m (12 ft)
Maximum Pressurized Cargo Up mass/volume	3,310 kg (7,297 lb) 6.8 m³ (240 ft³)
Down mass/volume	2,500 kg (5,512 lb) 6.8 m³ (240 ft³)
Maximum Unpressurized Cargo Up mass/volume Down mass/volume	3,310 kg (7,297 lb) 14 m³ (494 ft³) 2,600 kg (5,732 lb)
Parked advisor	14 m³ Disposed (494 ft³)
Payload volume Pressurized	10 m³ (245 ft³)
Unpressurized	14 m³ (490 ft³)



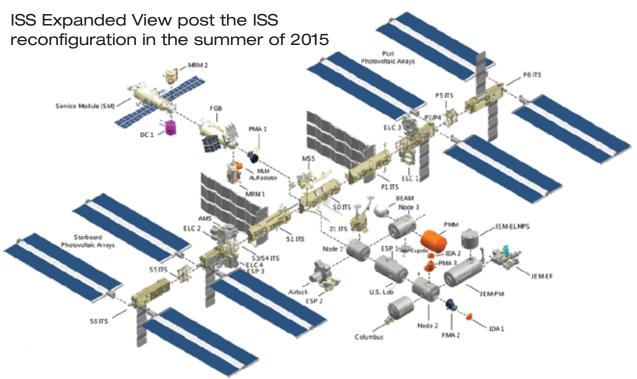


ISS Expanded View









Principal Stages in Construction

The ISS is the largest human made object ever to orbit the Earth. The ISS has a mass of 410,501 kg (905,000 lbs) and a pressurized volume of approximately 916 m3 (32,333 ft3). The ISS can generate up to 80 kilowatts of electrical power per orbit from solar arrays which cover an approximate area of 2,997 m2 (32,264 ft2). The ISS structure measures 95 m (311 ft) from the P6 to S6 trusses and 59 m (193 ft) from PMA2 to the Progress docked on the aft of the Russian Service Module. The ISS orbital altitude can range from 278-460 km (150-248 nautical miles) and is in an orbital inclination of 51.6 degrees. The ISS currently houses 6 crew members.

Building the ISS required 36 Space Shuttle assembly flights and 5 Russian launches. Currently, logistics and resupply are provided through a number of vehicles including the Russian Progress and Soyuz, Japanese H-II Transfer Vehicle (HTV), and commercial cargo vehicles (Dragon and Cygnus). Previous vehicles that have been retired include the Space Shuttle and the European Automated Transfer Vehicle (ATV).

ISS stage number/letter conventions:

A=U.S. Assembly

E=European Assembly

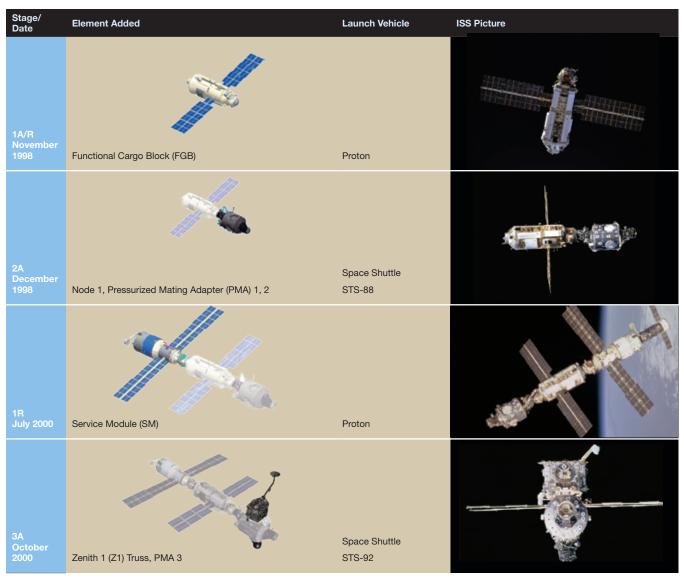
J=Japanese Assembly

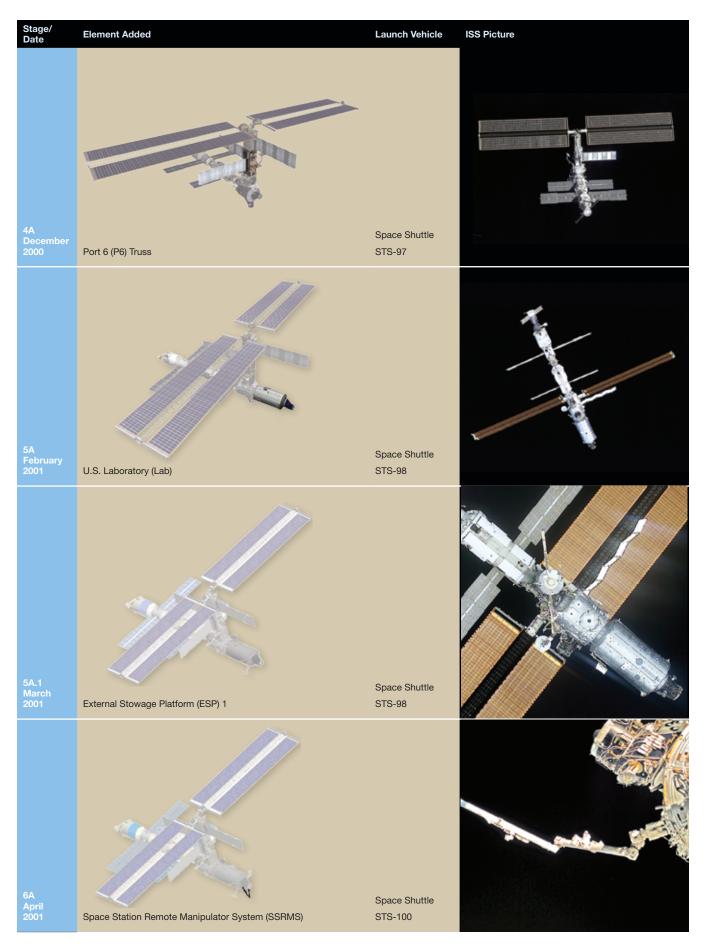
LF=Logistics

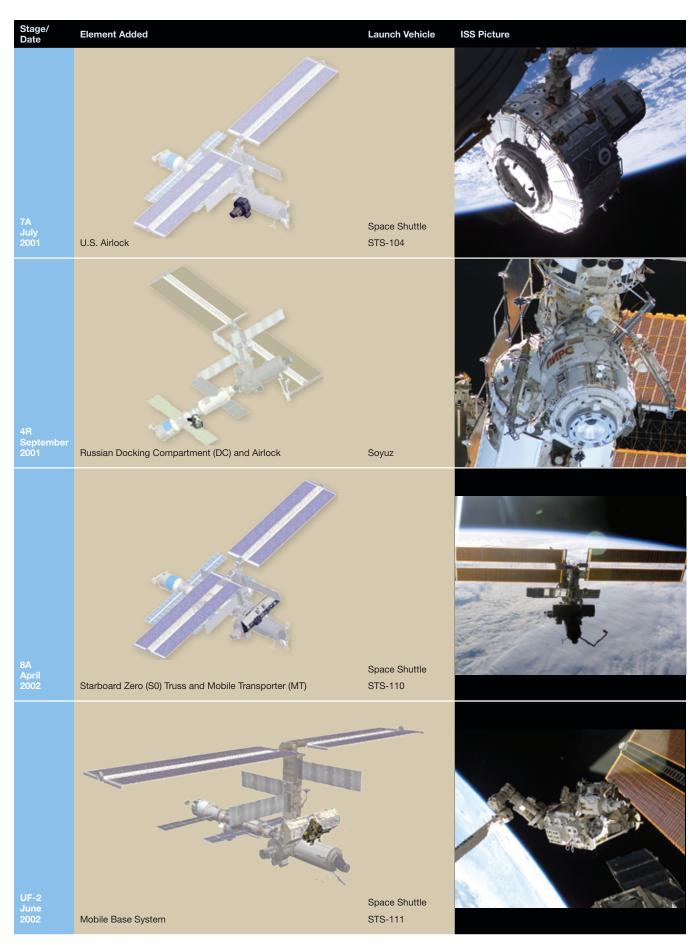
R=Russian Assembly

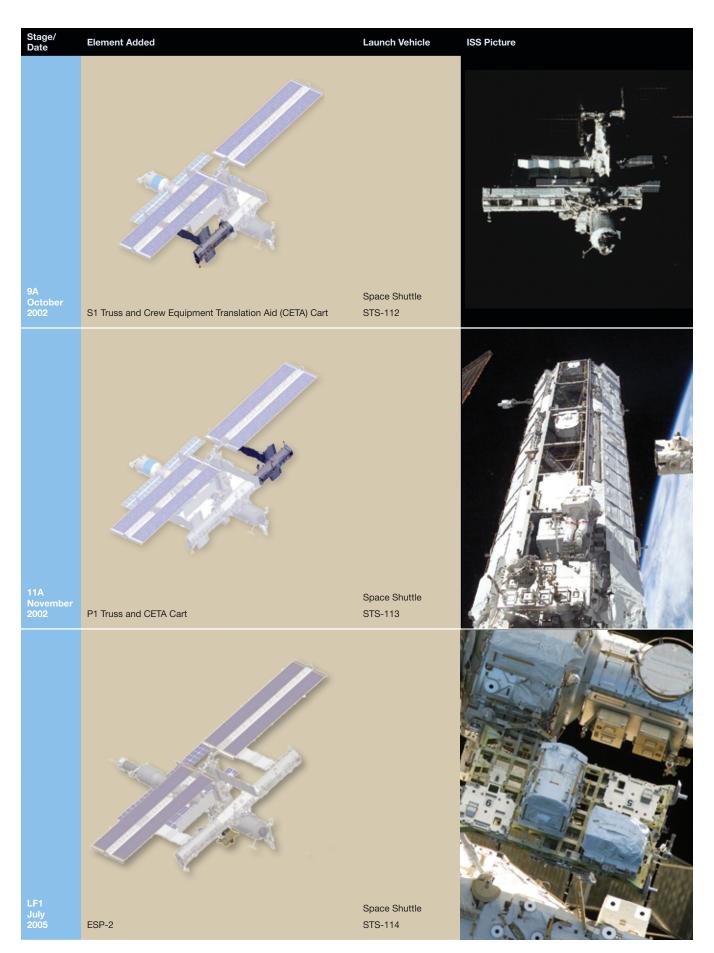
JF=Utilization

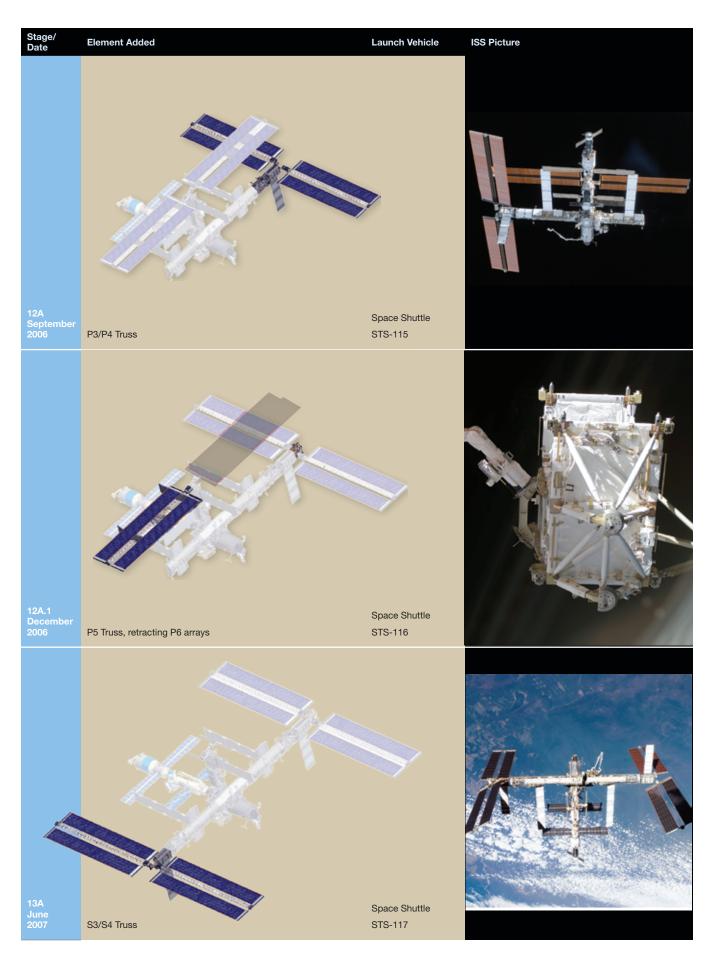
ULF=Utilization/Logistics

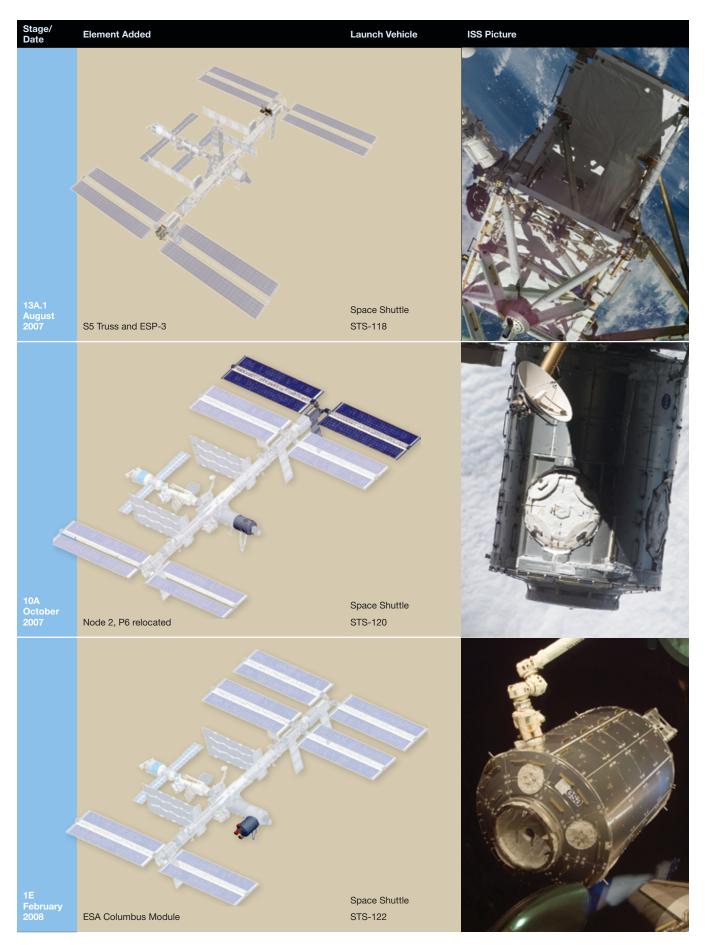




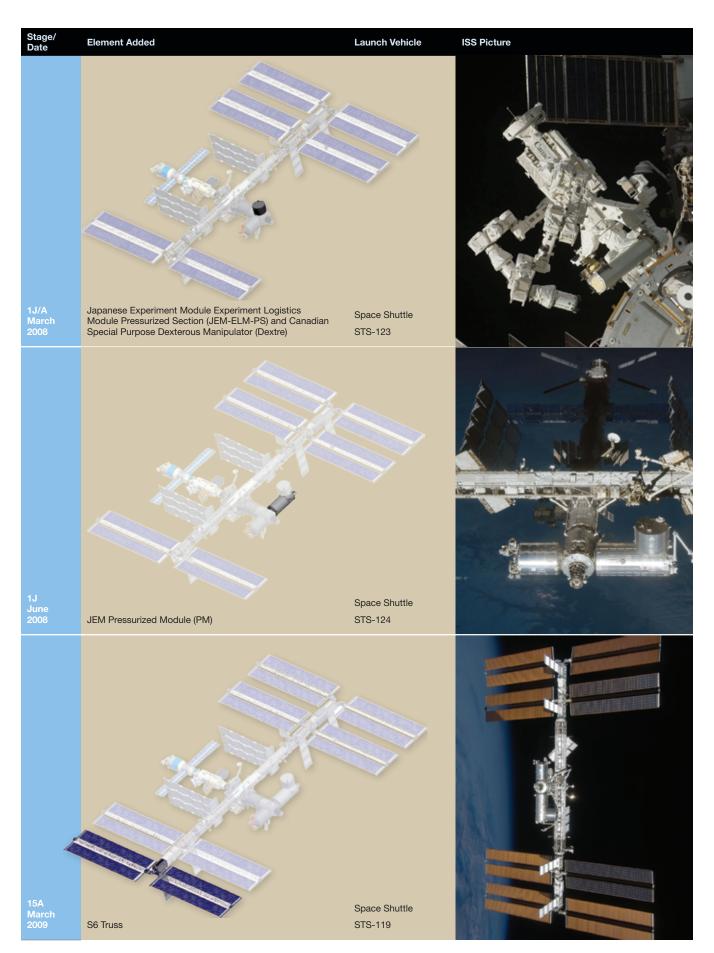


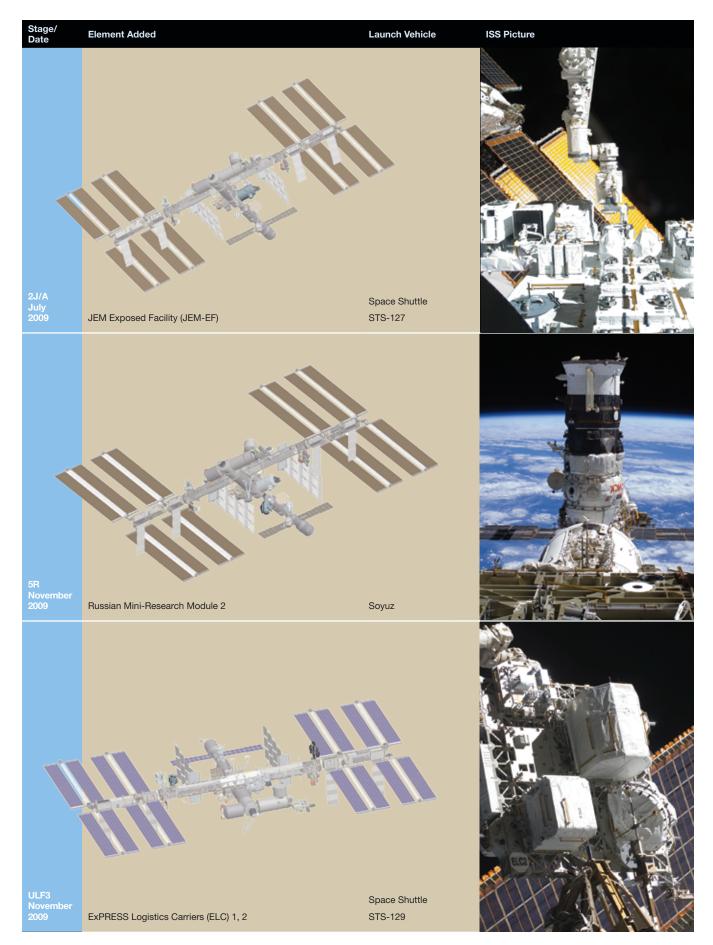


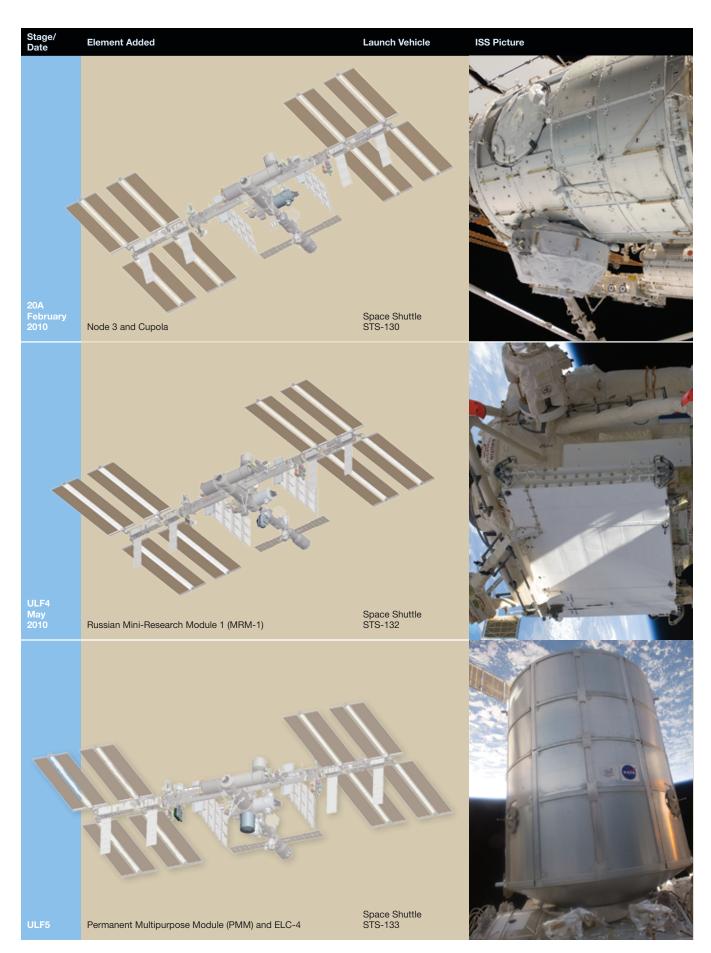


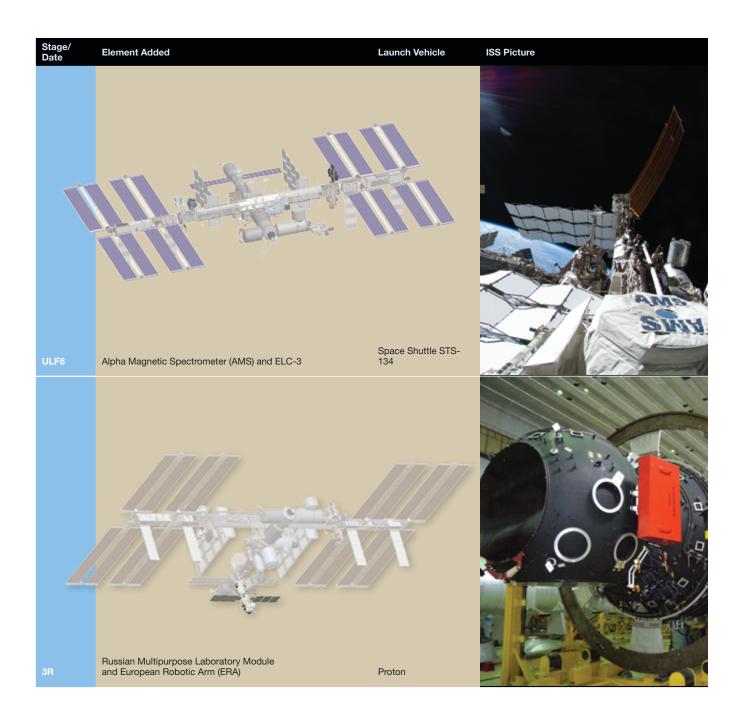


83











High-performing personnel are key to International Space Station (ISS) mission success. International crewmembers and ground controllers who support assembly, logistics, and long-duration missions have highly specialized skills and training. They also utilize procedures and tools developed especially for the ISS.

The experience gained from the ISS program has improved the interaction between the flight crews and ground-team members and has made missions safer and more effective. Moreover, working with teams from many countries and cultures on the ground and in space has provided (and continues to provide) innovative solutions to critical operational challenges.

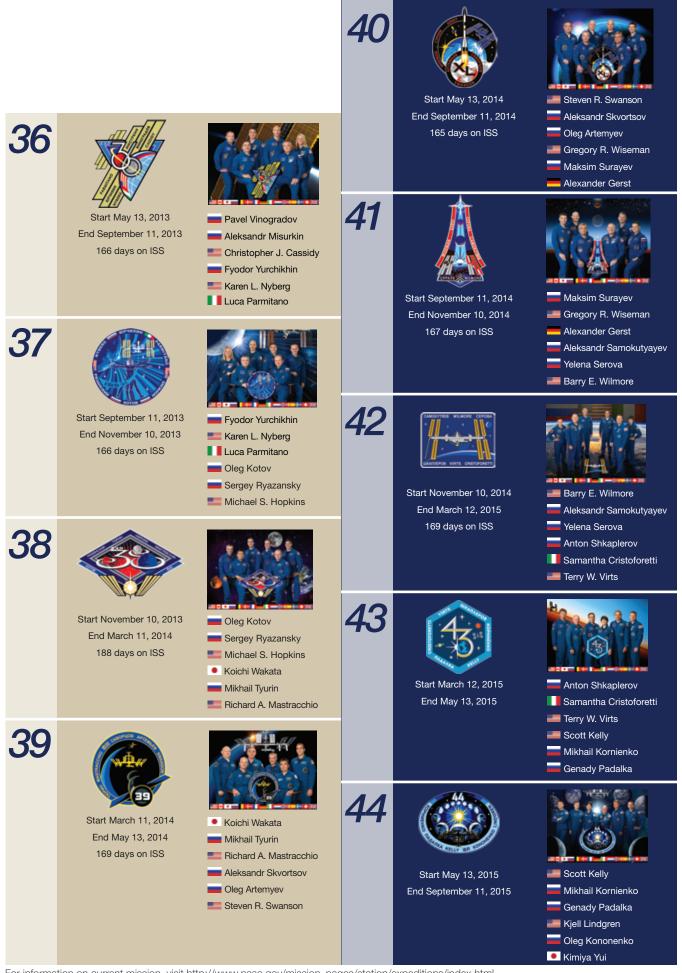
ISS Expeditions and Crews







28 32 Gennady Padalka Start July 1, 2012 Start May 23, 2011 Andrei Borisenko End September 17, 2012 Sergei Revin Aleksandr Samokutyayev End September 16, 2011 126 days on ISS Joseph M. Acaba Ronald J. Garan 167 days on ISS Michael E. Fossum Sunita L. Williams Sergey Volkov Yuri Malenchenko Satoshi Furukawa Akihiko Hoshide 33 Start September 17, 2012 Sunita L. Williams Start September 16, 2011 Michael E. Fossum End November 18, 2012 Yuri Malenchenko End November 16, 2011 Sergey Volkov 143 days on ISS Akihiko Hoshide Satoshi Furukawa 165 days on ISS Daniel C. Burbank Kevin A. Ford Anton Shkaplerov Oleg Novitskiy Anatoli Ivanishin Evgeny Tarelkin 34 *30* Kevin A. Ford Start November 18, 2012 Start November 16, 2011 Daniel C. Burbank End March 15, 2013 Oleg Novitskiy End April 27, 2012 Anton Shkaplerov 145 days on ISS Evgeny Tarelkin Anatoli Ivanishin 192 days on ISS Oleg Kononenko Chris Hadfield Donald R. Pettit Roman Romanenko André Kuipers Thomas H. Marshburn 31 35 Start April 27, 2012 Oleg Kononenko Start March 15, 2013 Chris Hadfield Donald R. Pettit End May 13, 2013 Roman Romanenko End July 1, 2012 166 days on ISS André Kuipers Thomas H. Marshburn 124 days on ISS Gennady Padalka Pavel Vinogradov Sergei Revin Aleksandr Misurkin Joseph M. Acaba Christopher J. Cassidy



For information on current mission, visit http://www.nasa.gov/mission_pages/station/expeditions/index.html



STS Missions and Crews

Space Shuttle Missions to the ISS



STS-88 Endeavour



Launched December 4, 1998

Landed December 15, 1998

12 days



Robert D. Cabana

- Frederick W. Sturckow
- Nancy J. Currie Jerry L. Ross
- James H. Newman
- Sergei Krikalev



October 11, 2000

Landed October 24, 2000



- Brian Duffy
- Pamela A. Melroy
- Leroy Chiao
- William S. McArthur
- Peter J. K. Wisoff
- Michael E. Lopez-Alegria
- Koichi Wakata

ISS Flight 2A.1

STS-96 Discovery



Launched May 27, 1999

Landed June 6, 1999 10 days



Kent V. Rominger

- Rick D. Husband
- Tamara E. Jernigan
- Ellen L. Ochoa Daniel T. Barry
- Julie Payette
- Valery Tokarev

ISS Flight 4A

ISS Flight

3A

STS-92

Discovery

STS-97

Endeavour



Landed 11 days



- Michael J. Bloomfield
- Joseph R. Tanner
- Carlos I. Noriega
- Marc Garneau

ISS Flight 2A.2a

STS-101 Atlantis



Launched May 19, 2000

Landed May 29, 2000

10 days



- James D. Halsell
- Scott J. Horowitz
- Mary E. Weber
- Jeffrey N. Williams
- James S. Voss Susan J. Helms
- Yury Usachev

ISS Flight

5A STS-98 Atlantis



February 7, 2001

February 20, 2001

13 days



- Mark L. Polansky
- Robert L. Curbeam
- Marsha S. Ivins
- Thomas D. Jones

ISS Flight 2A.2b STS-106

Atlantis



Launched September 8, 2000

Landed September 20, 2000

12 days



- Terrence W. Wilcutt Scott D. Altman
- Edward T. Lu
- Richard A. Mastracchio
- Daniel C. Burbank Yuri Malenchenko
- Boris Morukov

ISS Flight 5A.1





Launched March 8, 2001

Landed 12 days





- James D. Wetherbee
- James M. Kelly
- Paul W. Richards
- Andrew S. W. Thomas
- Yury Usachev
- James S. Voss
- Susan J. Helms

ISS Flight 6A STS-100 Endeavour



Launched April 19, 2001 Landed

May 1, 2001 12 days

Kent V. Rominger Jeffrey S. Ashby John L. Phillips Scott E. Parazynski Chris A. Hadfield Umberto Guidoni

Yuri Lonchakov

ISS Flight 8A

STS-110 Atlantis



Launched April 8, 2002

Landed April 19, 2002



Stephen N. Frick

Jerry L. Ross

Steven L. Smith

Ellen L. Ochoa

Lee M. E. Morin

Rex J. Walheim

ISS Flight **7A**

STS-104 Atlantis



Launched July 12, 2001 Landed

July 24, 2001 13 days



Steven W. Lindsey

Charles O. Hobaugh

Michael L. Gernhardt Janet L. Kavandi

James F. Reilly

ISS Flight UF-2

STS-111 Endeavour



June 5, 2002

Landed 11 days



Paul S. Lockhart

Franklin R. Chang-Diaz

Philippe Perrin

Valery Korzun

Sergei Treshchev

Peggy A. Whitson

ISS Flight 7A.1

STS-105 Discovery



Launched August 10, 2001

Landed August 22, 2001

10 days



Scott J. Horowitz

Frederick W. Sturckow

Daniel T. Barry

Patrick G. Forrester

Frank L. Culbertson

Mikhail Tyurin Vladimir Dezhurov ISS Flight

9A

STS-112 Atlantis



Launched October 7, 2002

Landed October 18, 2002



Jeffrey S. Ashby

Pamela A. Melroy

David A. Wolf

Sandra H. Magnus

Piers J. Sellers

Fyodor Yurchikhin

ISS Flight UF-1

STS-108 Endeavour



Launched December 5, 2001

Landed December 17, 2001

12 days



Dominic L. Pudwill Gorie

Mark E. Kelly

Linda M. Godwin

Daniel M. Tani Yuri Onufrienko

Carl E. Walz Daniel W. Bursch

ISS Flight **11A** STS-113 Endeavour



Launched November 23, 2002

14 days



James D. Wetherbee

Paul S. Lockhart

Michael E. Lopez-Alegria

John B. Herrington

Kenneth D. Bowersox

Donald R. Pettit

Nikolai Budarin

LF1
STS-114
Discovery



Launched July 26, 2005

Landed August 9, 2005

14 days



Eileen M. Collins
James M. Kellv

Stephen K. Robinson

Andrew S. W. Thomas

Wendy B. LawrenceCharles J. Camarda

Soichi Noguchi

STUNCKOW, ARCHAMIAULT PROBASTER SWANSON OLIVAS RELLEV TILLY

Launched June 8, 2007

Landed June 22, 200

13 days



Frederick W. Sturcko

Lee J. Archambault

Patrick G. Forrester

Steven R. Swanson

John D. Olivas

James F. Reilly

Clayton C. Anderson

ISS Flight
ULF1.1

STS-121 Discovery



Launched July 4, 2006

Landed July 17, 2006 13 days



Steven W. Lindsey

Mark E. Kelly

Michael E. Fossum

Lisa M. Nowak

Stephanie D. Wilson

Piers J. Sellers
Thomas Reiter

ISS Flight 13A.1

ISS Flight

13A

STS-117

Atlantis

STS-118 Endeavour



Launched August 8, 2007

Landed August 21, 2007 13 days



Scott J. Kelly

Charles O. Hobaugh

Tracy E. Caldwell Dyson

Richard A. Mastracchio

Barbara R. Morgan

Benjamin A. Drew

Dafydd R. Williams

ISS Flight 12A

STS-115 Atlantis



Launched September 9, 2006

Landed September 21, 2006

12 days



Brent W. Jett

Christopher J. Ferguson

Daniel C. Burbank

Heidemarie M. Stefanyshyn-Piper

Joseph R. Tanner

■ Steven G. MacLean

ISS Flight

STS-120 Discovery



Launched October 23, 2007

Landed Novemeber 7, 2007

15 days



Pamela A. Melroy

George D. Zamka

Scott E. Parazynski

Stephanie D. Wilson

Douglas H. Wheelock
Paolo Nespoli

Daniel M. Tani

ISS Flight 12A.1

STS-116 Discovery



Launched December 9, 2009

Landed December 22, 2009

13 days



Mark L. Polansky

William A. Oefelein

Nicholas J. M. Patrick

Robert L. Curbeam
Joan E. Higginbotham

Christer Fuglesang
Sunita L. Williams

ISS Flight

1E

STS-122 Atlantis



February 7, 2008

Landed ebruary 20, 2008 13 days Stephen N. Frick
Alan G. Poindexter
Leland D. Melvin

Rex J. Walheim

Stanley G. Love

Hans Schlegel

Léopold Eyharts

ISS Flight 1J/A STS-123 Endeavour



Launched March 11, 2008

Landed March 26, 2008

15 days



Dominic L. Pudwill Gorie

Gregory H. Johnson Robert L. Behnken

Michael J. Foreman

Richard M. Linnehan

Takao Doi

Garrett E. Reisman



Launched July 15, 2009

Landed

16 days



Douglas G. Hurley

Christopher J. Cassidy

Thomas H. Marshburn

David A. Wolf

Julie Payette

Timothy L. Kopra

ISS Flight 1J

STS-124 Discovery



Launched May 31, 2008 Landed

June 14, 2008 14 days



Mark E. Kelly

Kenneth T. Ham

Karen L. Nyberg

Ronald J. Garan Michael E. Fossum

Akihiko Hoshide

Gregory E. Chamitoff

ISS Flight 17A

ISS Flight

2J/A STS-127

Endeavour

STS-128 Discovery



Launched August 28, 2009

Landed

14 days



Kevin A. Ford

Patrick G. Forrester

Jose M. Hernández

John D. Olivas

Christer Fuglesang

Nicole P. Stott

ISS Flight ULF2 STS-126 Endeavour



Launched November 14, 2008

Landed Novemeber 30, 2008

16 days



Christopher J. Ferguson

Eric A. Boe

Donald R. Pettit

Stephen G. Bowen

Heidemarie M. Stefanyshyn-Piper

Robert S. Kimbrough

Sandra H. Magnus

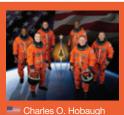
ISS Flight ULF3

STS-129 Atlantis



Launched November 16, 2009

Landed November 27, 2009



Barry E. Wilmore

Michael J. Foreman

Randolph J. Bresnik Leland D. Melvin

Robert L. Satcher

ISS Flight 15A

STS-119 Discovery



Launched

Landed March 28, 2009 13 days

March 15, 2009

Lee J. Archambault Dominic A. Antonelli

Joseph M. Acaba Steven R. Swanson

Richard R. Arnold John L. Phillips

Koichi Wakata

ISS Flight 20A

STS-130 Endeavour



February 8, 2010

13 days



George D. Zamka

Terry W. Virts

Kathryn P. Hire

Stephen K. Robinson

Nicholas J. M. Patrick

Robert L. Behnken

ISS Flight 19A STS-131 Discovery



Launched April 5, 2010

Landed April 20, 2010 15 days

Alan G. Poindexter James P. Dutton

Richard A. Mastracchio Clayton C. Anderson

Dorothy M. Metcalf-Lindenburger

Stephanie D. Wilson

Naoko Yamazaki

ISS Flight ULF7 STS-135 Atlantis



Launched July 8, 2011 **Landed** July 21, 2011



Christopher J. Ferguson

Douglas G. Hurley

Sandra H. Magnus

Rex J. Walheim

ISS Flight ULF4 STS-132 Atlantis



Launched May 14, 2010

Landed May 26, 2010

11 days



Kenneth T. Ham

Dominic A. Antonelli

Stephen G. Bowen

Michael T. Good

Piers J. Sellers

Garrett E. Reisman

ISS Flight ULF5 STS-133 Discovery



Launched February 24, 2011

Landed March 9, 2011

13 days



Steven W. Lindsey

Eric A. Boe

Benjamin A. Drew

Michael R. Barratt

Stephen G. Bowen

Nicole P. Stott

ISS Flight ULF6 STS-134 Endeavour



Launched May 16, 2011

Landed June 1, 2011

16 days



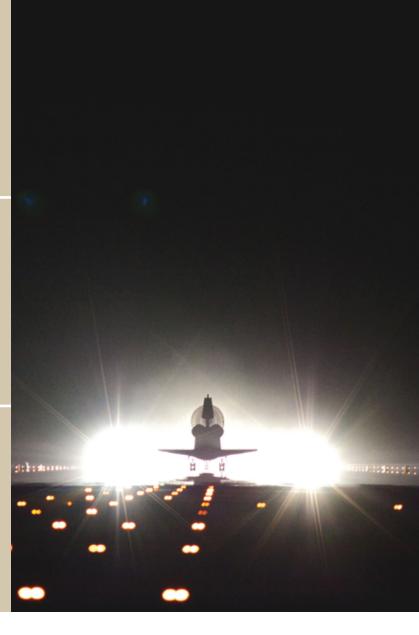
Mark E. Kelly

Gregory H. Johnson

Michael Fincke

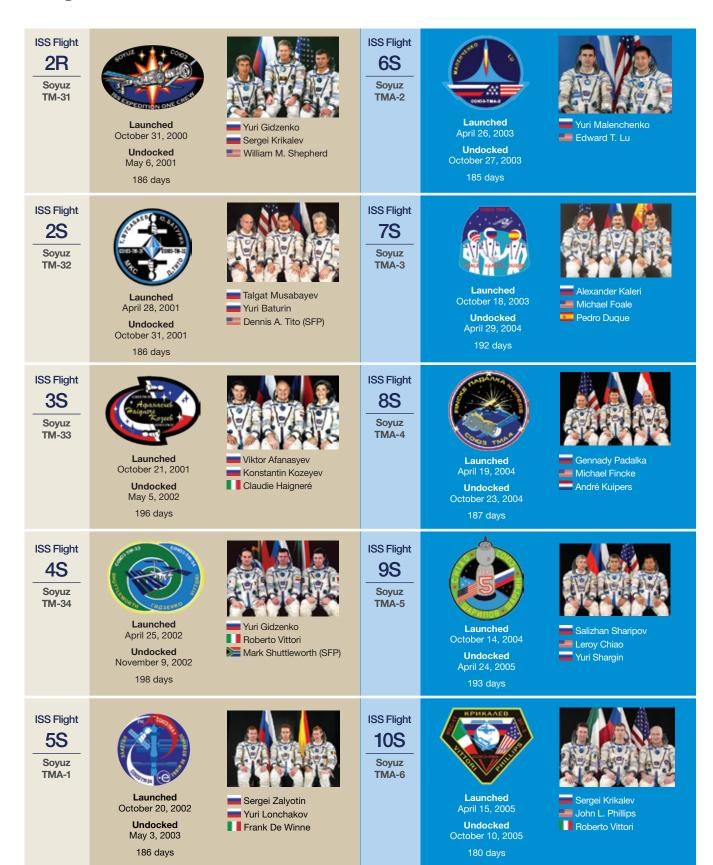
Gregory E. Chamitoff Andrew J. Feustel

Roberto Vittori





Soyuz ISS Missions



ISS Flight **11S** Soyuz TMA-7

> Launched October 1, 2005 **Undocked** April 8, 2006

> > 190 days

Valery Tokarev William S. McArthur Gregory H. Olsen (SFP) ISS Flight **16S**

> Soyuz TMA-12

April 8, 2008 Undocked October 24, 2008 199 days



Sergei Volkov Oleg Kononenko Yi So Yeon (SFP)

ISS Flight **12S**

Soyuz TMA-8



Launched March 30, 2006

Undocked September 28, 2006 182 days



Pavel Vinogradov Jeffrey N. Williams

Marcos Pontes (SFP)

ISS Flight **17S**

Soyuz TMA-13



Launched October 12, 2008

> Undocked April 8, 2009 178 days



Michael Fincke

Richard A. Garriott (SFP)

ISS Flight 13S

> Soyuz TMA-9



Launched September 18, 2006

Undocked April 21, 2007 215 days



1ikhail Tyurin

Michael E. Lopez-Alegria === / === Anousheh Ansari (SFP) ISS Flight **18S**

Soyuz TMA-14



Launched March 26, 2009

Undocked 199 days



Gennady Padalka

Michael R. Barratt / Charles Simonyi (SFP)

ISS Flight 14S

> Soyuz **TMA-10**



Launched April 7, 2007

Undocked October 21, 2007 196 days



Oleg Kotov Fyodor Yurchikhin

Charles Simonyi (SFP)

ISS Flight **19S**

> Soyuz TMA-15



Launched May 27, 2009

Undocked 188 days



Frank de Winne

Robert B. Thirsk

ISS Flight **15S**

> Soyuz TMA-11



Launched October 11, 2007

> Undocked April 19, 2008 191 days

Yuri Malenchenko Peggy A. Whitson

Sheikh Muszaphar Shukor

ISS Flight **20S** Soyuz TMA-16



Launched September 30, 2009

> Undocked March 18, 2010 169 days



Maksim Surayev Jeffrey N. Williams

■ Guy Laliberté (SFP)

ISS Flight
21S
Soyuz
TMA-17



Launched December 20, 2009 Undocked June 2, 2010

164 days



Oleg Kotov
Timothy J. Creamer

Soichi Noguchi

50

April 4, 2011

Undocked
September 16, 2011



Aleksandr SamokutyayevAndrei Borisenko

Ronald J. Garan

ISS Flight 22S

Soyuz TMA-18



Launched April 2, 2010 Undocked

Undocked September 25, 2010 176 days



Aleksandr Skvortsov

Mikhail Korniyenko
Tracy E. Caldwell Dyson

ISS Flight 27S

ISS Flight

26S

Soyuz TMA-21

Soyuz TMA-02M



Launched October 12, 2008

Undocked April 8, 2009 166 Days



Sergey Volkov

Michael E. Fossum

Satoshi Furukawa

ISS Flight 23S

Soyuz TMA-19



Launched June 15, 2010 Undocked

Novemeber 26, 2010 163 days

Fyodor Yurchikhin
Douglas H. Wheelock

Douglas H. Wheeloo

ISS Flight 28S

Soyuz TMA-22



Launched November 14, 2011

Undocked April 27, 2012 165 Days



Anton Shkaplerov
Anatoli Ivanishin

Daniel C. Burbank

ISS Flight 24S

Soyuz TMA-01M



Launched October 7, 2010

Undocked March 16, 2011 159 Days



Alexander Kaleri
Oleg Skripochka

Scott J. Kelly

ISS Flight

Soyuz TMA-03M



Launched December 21, 2011

Undocked July 1, 2012 192 Days



Oleg Kononenko
Donald R. Pettit

André Kuipers

ISS Flight 25S

Soyuz TMA-20



Launched December 15, 2010

Undocked May 23, 2011 159 Days



Dimitri KondratyevCatherine G. Coleman

Paolo Nespoli

ISS Flight

Soyuz TMA-04M



Launched May 15, 2012

Undocked September 17, 2012

124 Days



Gennady Padalka
Sergei Revin

Joseph M. Acaba

ISS Flight **31S** Soyuz

TMA-05M



Launched July 15, 2012 Undocked November 18, 2012 126 Days



Sunita L. Williams Akihiko Hoshide

ISS Flight **36S** Soyuz TMA-10M

Launched

September 25, 2013 Undocked March 11, 2014 166 Days



Oleg Kotov Sergey Ryazansky Michael S. Hopkins

ISS Flight **32S**

Soyuz TMA-06M



Launched October 23, 2012

Undocked March 15, 2013

Oleg Novitskiy Evgeny Tarelkin Kevin A. Ford

ISS Flight **37S** Soyuz

TMA-11M

Launched Undocked

May 13, 2014 187 Days

Mikhail Tyurin Richard A. Mastracchio

Koichi Wakata

ISS Flight **33S**

Soyuz TMA-07M

143 Days

Launched December 19, 2012 Undocked May 13, 2013

145 Days

Roman Romanenko Thomas H. Marshburn Chris A. Hadfield

ISS Flight **38S**

Soyuz TMA-12M



Launched March 25, 2014 Undocked September 11, 2014 169 Days



Aleksandr Skvortsov Oleg Artemyev Steven R. Swanson

ISS Flight **34S**

Soyuz TMA-08M



March 28, 2013 Undocked September 11, 2013

166 Days

Pavel Vinogradov Aleksandr Misurkin Christopher J. Cassidy ISS Flight **39S**

Soyuz TMA-13M



Launched May 28, 2014 Undocked November 10, 2014 165 Days



Maksim Surayev Gregory R. Wiseman Alexander Gerst

ISS Flight **35S**

Soyuz TMA-09M



Launched May 28, 2013 Undocked November 10, 2013

166 Days



Fyodor Yurchikhin Karen L. Nyberg Luca Parmitano

ISS Flight **40S** Soyuz

TMA-14M



Launched September 25, 2014

Undocked May 12, 2015 167 Days



Aleksandr Samokutyayev
Yelena Serova

Barry E. Wilmore

ISS Flight **41S** Soyuz TMA-15M



November 23, 2014 Undocked TBD



Samantha Cristoforetti Terry W. Virts

ISS Flight **42S** Soyuz TMA-16M



Undocked TBD



Mikhail Korniyenko
Scott J. Kelly







Unmanned ISS Missions

Spacecraft	Launch date	ISS Flight Number	Deorbit	
Progress M1-3	6 August 2000	ISS-1P	1 November 2000	
Progress M1-4	16 November 2000	ISS-2P	8 February 2000	
Progress M-44	26 February 2001	ISS-3P	16 April 2001	
Progress M1-6	20 May 2001	ISS-4P	22 August 2001	
Progress M-45	21 August 2001	ISS-5P	22 November 2001	
Progress M-S01	14 September 2001	ISS-4R	26 September 2001	
Progress M1-7	26 November 2001	ISS-6P	20 March 2001	
Progress M1-8	21 March 2002	ISS-7P	25 June 2002	
Progress M-46	26 June 2002	ISS-8P	14 October 2002	
Progress M1-9	25 September 2002	ISS-9P	1 February 2002	
Progress M-47	2 February 2003	ISS-10P	28 August 2003	
Progress M1-10	8 June 2003	ISS-11P	3 October 2003	
Progress M-48	29 August 2003	ISS-12P	28 January 2004	
Progress M1-11	29 January 2004	ISS-13P	3 June 2004	
Progress M-49	25 May 2004	ISS-14P	30 July 2004	
Progress M-50	11 August 2004	ISS_15P	22 December 2004	
Progress M-51	23 December 2004	ISS-16P	9 March 2005	
Progress M-52	28 February 2005	ISS-17P	16 June 2005	
Progress M-53	16 June 2005	ISS-18P	7 September 2005	
Progress M-54	8 September 2005	ISS-19P	3 March 2006	
Progress M-55	21 December 2005	ISS-20P	19 June 2006	
Progress M-56	24 April 2006	ISS-21P	19 September 2006	
Progress M-57	24 June 2006	ISS-22P	17 January 2007	
Progress M-58	23 October 2006	ISS-23P	27 March 2007	
Progress M-59	18 January 2007	ISS-24P	1 August 2007	
Progress M-60	12 May 2007	ISS-25P	25 September 2007	
Progress M-61	2 August 2007	ISS-26P	22 January 2008	
Progress M-62	23 December 2007	ISS-27P	15 February 2008	
Progress M-63	5 February 2008	ISS-28P	7 April 2008	
ATV	9 March 2008	ISS-ATV1	5 September 2008	
Progress M-64	14 May 2008	ISS-29P	8 September 2008	
Progress M-65	10 September 2008	ISS-30P	8 December 2008	
Progress M-01M	26 November 2008	ISS-31P	8 February 2009	
Progress M-66	10 February 2009	ISS-32P	18 May 2009	
Progress M-02M	7 May 2009	ISS-33P	13 July 2009	
Progress M-67	24 July 2009	ISS-34P	27 September 2009	
HTV	10 September 2009	ISS-HTV1	30 October 2009	
Progress M-03M	15 October 2009	ISS-35P	27 April 2010	
Progress M-MIM2	10 November 2009	ISS-5R	8 December 2009	

Spacecraft	Launch date	ISS Flight Number	Deorbit	
Progress M-04M	3 February 2010	ISS-36P	1 July 2010	
Progress M-05M	28 April 2010	ISS-37P	15 November 2010	
Progress M-06M	30 June 2010	ISS-38P	6 September 2010	
Progress M-07M	10 September 2010	ISS-39P	20 February 2011	
Progress M-08M	27 October 2010	ISS-40P	24 January 2011	
HTV	22 January 2011	ISS-HTV2	28 March 2011	
Progress M-09M	28 January 2011	ISS-41P	26 April 2011	
ATV	16 February 2011	ISS-ATV2	20 June 2011	
Progress M-10M	27 April 2011	ISS-42P	29 October 2011	
Progress M-11M	21 June 2011	ISS-43P	1 September 2011	
Progress M-12M	24 August 2011	ISS-44P	ISS-44P. Failed to orbit; premature third stage cutoff, impacted in the Choisk Region of Russia's Altai Republic.	
Progress M-13M	30 October 2011	ISS-45P	25 January 2012	
Progress M-14M	25 January 2012	ISS-46P	28 April 2012	
ATV	23 march 2012	ISS-ATV3	28 September 2012	
Progress M-15M	20 April 2012	ISS-47P	20 August 2012	
SpaceX	22 May 2012	ISS-SpX-D	31 may 2012	
HTV	21 July 2012	ISS-HTV3	12 September 2012	
Progress M-16M	1 August 2012	ISS-48P	9 February 2013	
SpaceX	8 October 2012	ISS-SpX-1	28 October 2012	
Progress M-17M	31 October 2012	ISS-49P	21 April 2013	
Progress M-18M	11 February 2013	ISS-50P	26 July 2013	
SpaceX	1 March 2012	ISS-SpX-2	26 March 2013	
Progress M-19M	24 April 2013	ISS-51P	19 June 2013	
ATV	5 June 2013	ISS-ATV4	28 October 2012	
Progress M-20M	27 July 2013	ISS-52P	11 February 2014	
HTV	3 August 2013	ISS-HTV4	4 September 2013	
Orbital	18 September 2013	ISS-Orb-D1	22 October 2013	
Progress M-21M	25 November 2013	ISS-53P	9 June 2014	
Orbital	9 January 2014	ISS-0rb-1	18 February 2014	
Progress M-22M	5 February 2014	ISS-54P	18 April 2014	
Progress M-23M	9 April 2014	ISS-55P	31 July 2014	
SpaceX	18 April 2014	ISS-SpX-3	15 May 2014	
Orbital December 14 0414	13 July 2014	ISS-Orb-2	15 August 2014	
Progress M-24M	23 July 2014	ISS-56P	19 November 2014	
ATV	29 July 2014	ISS-SpX-4	25 October 2014	
Orbital	28 October 2014	ISS-0rb-3	Lost on Ascent	
Progress M-25M	29 October 2014	ISS-57P	25 April 2015	

Spacecraft	Launch date	ISS Flight Number	Deorbit
SpaceX	10 January 2015	ISS-SpX-5	10 February 2015
Progress M-26M	17 February 2015	ISS-58P	Planned: 26 August 2015
SpaceX	13 April 2015	ISS-SpX-6	21 May 2015
Progress M-27M	28 April 2015	ISS-59P	Failed to Orbit











Reference

To Learn More

ONLINE:

International Space Station www.nasa.gov/station

Station Science www.nasa.gov/iss-science

Canadian Space Agency (CSA) http://www.asc-csa.gc.ca/eng/iss/

European Space Agency (ESA) http://www.esa.int/esaHS/iss.html

Japan Aerospace Exploration Agency (JAXA) http://iss.jaxa.jp/en/

Russian Federal Space Agency (Roscosmos) http://knts.rsa.ru/ http://www.energia.ru/english/index.html

SOCIAL MEDIA:



@Space_Station
@ISS Research



International Space Station



@iss



NASA Johnson Space Center



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Acronym List

Α		DECLIC	Device for the study of Critical Liquids and
	Arm Control Unit	DECLIC	Device for the study of Critical Liquids and Crystallization
ACU AED	Automated External defibrillator	DRTS	Data Relay Test Satellite
A/L	Airlock	DRIS	Data Relay Test Satellite
AMS	Alpha Magnetic Spectrometer	E	
APFR	Articulating Portable Foot Restraint	EAC	European Astronaut Centre
ARC	Ames Research Center	EADS	European Aeronautic Defence and Space
ARED	Advanced Resistive Exercise Device	EADS	Company
ARIS	Active Rack Isolation System	Earthkam	
ASI	Italian Space Agency	LAKITIKAWI	Schools
ATM	Atmosphere	ECLSS	Environmental Control and Life Support System
ATV	Automated Transfer Vehicle	ECU	Electronics Control Unit
111 4	Tutomated Tunorer venicle	EDR	European Drawer Rack
В		EF	Exposed Facility
BASS-II	Burning and Suppression of Solids - II	EHS	Environmental Health System
BCA	Battery Charging Assembly	ELC	EXPRESS Logistics Carriers
BCDU	Battery Charge Discharge Unit	ELITE-S2	ELaboratore Immagini Televisive-Space 2
BIOLAB	Biological Laboratory	ELM-ES	Experiment Logistics Module Exposed Section
BRIC	Biological Research in Canisters	ELM-PS	Experiment Logistics Module-Pressurized Section
BSA	Battery Stowage Assembly	EML	Electromagnetic Levitator
2011	Duttery otominger Esternoly	EMU	Extravehicular Mobility Unit
С		EPM	European Physiology Module
C&T	Communications & Tracking	EPS	Electrical Power System
C2V2	Common Communications for Visiting Vehicles	ESA	European Space Agency
С	Celsius	ESTEC	European Space Research and Technology Centre
CATS	Cloud-Aerosol Transport System	EVA	Extravehicular Activity
CBM	Common Berthing Mechanism	EXPRESS	Expedite the Processing of Experiments to the
CDRA	Carbon Dioxide Removal Assembly		Space Station
CEPF	Columbus External Payload Facility		1
CEVIS	Cycle Ergometer with Vibration Isolation System	F	
CFE	Capillary Flow Experiment	F	Farenheit
CHECS	Crew Health Care System	FGB	Functional Cargo Block
CIR	Combustion Integrated Rack	FIR	Fluids Integrated Rack
CM	centimeter	FSL	Fluid Science Laboratory
CMG	Control Moment Gyroscope	FT	foot
CMO	Crew Medical Officer	FT^3	Cubic feet
CMTF	Canadian MSS Training Facility		
CO_2	carbon dioxide	G	
COLBERT	Combined Operational Load Bearing External	GATOR	Grappling Adaptor to On-Orbit Railing
	Resistive Exercise Treadmill	GCTC	Gagarin Cosmonaut Training Center
COL-CC	Columbus Control Center	GN&C	Guidance, Navigation, and Control
CRPCM	Canadian Remote Power Controller Module	GPS	Global Positioning System
CRS	Commercial Resupply System	GRC	Glenn Research Center
CSA	Canadian Space Agency	GSC	Guiana Space Centre
CWC	Contingency Water Container		
CWQMK	Colorimetric Water Quality Monitoring Kit	Н	
		H_2	hydrogen
D		H ₂ O	water
DC	Docking Compartment	HDPCG	Hand-Held High Density Protein Crystal
DC	Direct Current		Growth
DCSU	Direct Current Switching Unit	HICO	Hyperspectral Imager for the Coastal Ocean
DDCU	DC-to-DC Converter Unit	HMS	Health Maintenance System

******	Hadd Maintaga Carray Carray Madical	1.00	Mining Control Control
HMS CMRS	Health Maintenance System/Crew Medical	MCC	Mission Control Center
***	Restraint System	MCC-H	Mission Control Center-Houston
HQ	Headquarters	MELFI	Minus Eighty-Degree Laboratory Freezer for ISS
HR	hour	MERLIN	Microgravity Experiment Research Locker/
HRF	Human Research Facility		Incubator
HRS	Heat Rejection Subsystem	MIL-STD	Military Standard
HTV	H-II Transfer Vehicle	MLM	Multi-Purpose Laboratory Module
		MMOD	Micrometeoroid and Orbital Debris
ı		MN	Meganewton
ICWS	Iodine Compatible Water Containers	MOC	MSS Operations Complex
IEA	Integrated Equipment Assembly	MOTS	MSS Operations and Training System
IN	inch	MPLM	Multi-Purpose Logistics Module
IPS	International Partners	MRM	Mini-Research Module
IRU	In-Flight Refill Unit	MSFC	Marshall Space Flight Center
ISPR	International Standard Payload Rack	MSG	Microgravity Sciences Glovebox
ISS	International Space Station	MSPR	Multipurpose Small Payload Rack
ITS	Integrated Truss Structure	MSRR	Materials Science Research Rack
IV-TEPC-IV	Tissue Equivalent Proportional Counter	MSS	Mobile Servicing System
J		N	
JAXA	Japan Aerospace Exploration Agency	N_2	nitrogen
JEF - JEM	Exposed Facility	N ₂ O ₄	nitrogen tetroxide
JEM	Japanese Experiment Module	NASA	National Aeronautics and Space Administration
JEM-RMS	Japanese Experiment Module Remote	NORS	Nitrogen/Oxygen Resupply System
,	Manipulator System		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
JLP	Japanese Experiment Logistics Module-	0	
	Pressurized Section	02	oxygen
JPL	Jet Propulsion Laboratory	OBSS	Orbiter Boom Sensor System
JPM	Japanese Pressurized Module	OEC	Operations Engineering Centre
JSC	Johnson Space Center	OGS	Oxygen Generation System
		ORU	Orbital Replacement Unit
K	17.1 •	В	
K	Kelvin	Р	
KG	kilogram	PASSAGES	Scaling Body-Related Actions in the Absence of
KM	kilometer		Gravity
KN	Kilonewton	PCM	Pressurized Cargo Module
KSC	Kennedy Space Center	PDGF	Power Data Grapple Fixture
KW	kilowatt	PLSS	Primary Life Support Subsystem
		PMA	Pressurized Mating Adaptor
L	1.	PMM	Permanent Multipurpose Module
L	liters	POCS	Payload Operations Centers
LB	pound	POIC	Payload Operations and Integration Center
LBF	pound-force	PS	Pressurized Section
LED	Light Emitting Diode	PSA	Power Supply Assembly
LEO	Low-Earth orbit	PSI	pounds per square inch
LIOH	Lithium Hydroxide	PTCS	Passive Thermal Control System
		PTOC	Payload Telescience Science Operations Center
М		PVTCS	Photovoltaic Thermal Control System
M	meter	PWP	Portable Work Post
\mathbf{M}^3	cubic meter	_	
MARES	Muscle Atrophy Research Exercise System	R	
MAS	Microbial Air Sampler	RAM	Radiation Area Monitor
MBPS	Megabits Per Second	RMPSR	Remote Multipurpose Support Room
MBS	Mobile Base System	RMS	Remote Manipulator System
MBSU	Main Bus Switching Unit	RPM	revolutions per minute

RS Russian Segment

RSC ENERGIA S.P. Korolev Rocket and Space Corporation

Energia

RTS Remote Terminals

S

SPP

SAFER Simplified Aid For EVA Rescue SARJ Solar (Array) Alpha Rotation Joint

SAW Solar Array Wing

SFOG Solid Fuel Oxygen Generator
SFP Space Flight Participant
SLM Sound Level Meter
SM Service Module

SPDM Special Purpose Dexterous Manipulator SPHERES Synchronized Position Hold, Engage, Reorient,

> Experimental Satellites Science Power Platform Service Section

SSA Service Section
SSA Space Suit Assembly
SSK Service Sample Kit
SSP Space Shuttle Program

SSRMS Space Station Remote Manipulator System

SSU Sequential Shunt Unit

Sciences, Technology, Engineering and

Mathematics

STS Shuttle Transport System

Т

TAS-I Thales Alenia Space Italy
TCS Thermal Control System

Tracking and Data Relay Satellites

TKSC Tsukuba Space Center
TNSC Tanegashima Space Center
TOCA Total organic carbon analyzer
TSCS Telescience Support Centers
TSUP Moscow Mission Control Center
TVIS Treadmill Vibration Isolation System

U

U.S. United States

UDMH unsymmetrical dimethyl hydrazine

UHF Ultra High Frequency

Usoc User Support and Operation Centers

usos U.S. On-orbit Segment

V

VDC voltage, direct current
VDU Video Distribution Unit
VHF very high frequency

W

WHC Waste Hygiene Compartment

WORF Window Observational Research Facility

WPA Water Processing Assembly
WRS Water Recovery System

Definitions

BERTHING

Mating or linking operations of two spacecraft, modules, or elements where an inactive module/ vehicle is placed into the mating interface using a Remote Manipulator System

DOCKING

Mating or linking operations of two spacecraft, modules, or elements where an active vehicle flies into the mating interface under its own power

ELEMENT

A structural component such as a module or truss segment

EXPEDITION

A long-duration crew during a stay on the space station

INCREMENT

Period of time from launch of a vehicle rotating International Space Station crewmembers to the undocking of the return vehicle for that crew

MISSION

Flight of a "visiting" Soyuz, or other vehicle not permanently attached to the International Space Station

MODULE

An internally pressurized element intended for habitation

NADIR

Direction directly below (opposite zenith)

PORT

Direction to the left side (opposite starboard)

RENDEZVOUS

Movement of two spacecraft toward one another

SPACE FLIGHT PARTICIPANT

Nonprofessional astronaut

STARBOARD

Direction to the right side (opposite port)

ZENITH

Directly above, opposite nadir





United States of America www.nasa.gov



Canada www.space.gc.ca/asc/eng/default.asp





Japan www.jaxa.jp/index_e.html



Russian Federation www.roscosmos.ru



European Space Agency www.esa.int

