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LIFT ENHANCEMENT
USING A CLOSE-COUPLED
OSCILLATING CANARD

by

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Lieutenant, United States Navy
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Submitted in partial fulfillment
of the requirements for the degree of

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ABSTRACT

A wind-tunnel study to investigate the effects of dynamic stall of a close-coupled canard on the canard/wing vortex interaction for increased lift enhancement was conducted. Two angles of attack of the model were studied: one at the first stall condition of the wing and one in the post-stall regime where a strong leading-edge vortex was formed. Baseline force and moment parameters were measured at mean canard deflections based on those determined to be optimum for the static case, as were mean values ± 3 degrees about the optimum. The amplitude of oscillation considered was ± 5 degrees about each mean; reduced frequencies tested were from 0.046 to 0.232. For most cases, lift was enhanced beyond the static-canard case at mean deflections equal to those at or greater than the static optimum value. The effective lift was decreased for mean deflections less than those previously determined to be optimum. Lift enhancements were generally 2 to 6 percent higher than the values determined with the static canard. The increased lift was generally independent of reduced frequency and peaked between k values of 0.1 to 0.2.

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I. INTRODUCTION

A. BACKGROUND

1. Agility

The design of fighter aircraft which exhibit a high level of agility continues to be of great importance even in today's environment of relaxed Superpower tensions. The definition of the term "agility" depends upon one's philosophical point of view. It can often be related to the terms, quick and nimble. McAtee states that "Agility is the capability to point the aircraft quickly and get the first shot; continue maximum maneuvering for self-defense and multiple kills; and accelerate quickly to leave the fight at will." [Ref.1] From a systems point of view, agility is "the ability of the entire weapon system to minimize the time delays between target acquisition and target destruction." [Ref.2] In simpler terms, aircraft agility can be described as "the time rate of change of the aircraft velocity vector." [Ref. 3] It can be seen that maneuverability and controllability are characteristics which are common to each of these views. Maneuverability may be described as the sum of forces acting on an aircraft which result in changes in airspeed and flight path, and controllability is essentially the ease with which the pilot changes flight path. [Ref. 1]

Historically, the importance of agility in war-fighting machines can be

traced as far back as the year 1588 when Sir Frances Drake's nimble fleet of warships defeated the once invincible Spanish Armada, thus changing the course of European history and enabling the emergence of England as a colonial world power. Drake's ships carried no soldiers and were vastly out-gunned by the Spanish but they were able to out maneuver and wreak havoc on the Armada. [Ref. 4] An analogous process has been used in the design and utilization of fighter aircraft during the 20th century. Successful examples of such highly maneuverable aircraft from World Wars I & II and Korea include the Sopwith Camel, Supermarine Spitfire, ME-109, P-51 Mustang, and the F-86 Sabre. Each of these aircraft was able to take advantage of its inherent agility characteristics to achieve victory in aerial combat.

The advent of high agility aircraft such as the F-16, F-18, ATF, MIG-29 and SU-27 has meant that the maintenance of air superiority increasingly depends upon the ability of the fighter to rapidly point-and-shoot and to sustain increasingly high turn rates in air-to-air combat. This means that the modern fighter must be able to maneuver in the high angle-of-attack or even post-stall regime while at the same time, the aircraft must remain fully controllable. Accordingly, agility continues to be a predominant factor in evaluating the survivability and combat effectiveness of fighter aircraft. As aircraft engine and structural design engineers approach the limits of current technology, it becomes evident that they must seek new methods for squeezing increased performance from their designs.

2. Dynamic Stall

The dynamic stall phenomenon can be described as the unsteady motion of an airfoil or wing such as oscillations or a transient pitching motion which introduces significant vorticity in the flowfield that eventually coalesces into a dynamic stall vortex. Characteristically, dynamic stall occurs at angles of attack which greatly exceed those observed during static stall of the airfoil. As the airfoil is rapidly pitched upward, flow disturbances begin near the surface at the trailing edge and progress forward towards the leading edge. Then, at an angle of attack that depends on many parameters, a strong vortical flow develops near the leading edge of the airfoil. The vortex enlarges and moves down the airfoil inducing large excursions in lift and pitching moment. The additional lift generated due to unsteady motion is sustained as long as the vortex remains on the surface. As the angle of attack decreases (i.e. the airfoil is pitched downwards), the vortex moves into the wake and flow over the surface separates. [Ref. 5]

3. Supermaneuverability

Supermaneuverability is term which combines post-stall (PST) and direct force (DFM) capabilities. PST represents the ability of an aircraft to perform controlled maneuvers beyond maximum-lift angle of attack. DFM represents the ability of the aircraft to yaw and pitch independent of the flight path or to maneuver in roll and yaw at a constant fuselage attitude. PST may be used in aerial combat to trade energy for positional advantage. An aircraft which can execute a pitch-up

maneuver to angles of attack as high as 90 degrees can complete a reversal of flight direction in approximately one-half the horizontal distance required for an aircraft limited to 20 degrees angle of attack. The supermaneuverable aircraft also completes this reversal in significantly less time than its adversary and thus has time to accelerate back to a high energy level. [Ref. 3]

4. Canard/Wing Interaction

Close-coupled canard/wing configurations have been in use for almost three decades. Properly spaced canard/wing planforms offer higher lift capabilities, enhanced maneuverability, and superior lift-to-drag ratios when compared to non-canard planforms. It is believed that constructive interference of the canard/wing vortex systems increases the maximum lift coefficient, and thus angle of attack, achievable by a close-coupled canard-configured aircraft. [Refs. 6 & 7]

5. Oscillating Canard Studies

Numerous studies of dynamic stall have been conducted using oscillating airfoils. Carr [Ref. 3] et al., provides a comprehensive review of the subject. However, little has been accomplished in the three-dimensional analysis. Several studies of three-dimensional oscillating wings have been conducted at the U.S. Air Force Academy. Using hot-wire anemometry, these experiments determined that the canard tip vortex had the greatest effect on the flow over a tandem wing and thus dominated the flowfield. No quantitative force-and-moment

data were measured. Accordingly, conclusive evidence of positive effects on the wing was not achieved. [Refs. 8, 9 &10]

B. STATEMENT OF PURPOSE

Advancements in the field of high angle-of-attack maneuverability and controllability have the potential to create a lasting effect on the next generation of fighter aircraft. The purpose of this experiment was to investigate the phenomenon of dynamic stall as it applies to three-dimensional flow over an oscillating close-coupled canard and its interaction with the swept-wing vortex for a fighter configuration. It was desired to determine if the dynamic-stall vortex shed from the canard could provide an increased enhancement in the vortex coupling process. If the events which lead up to and follow the occurrence of dynamic stall can be fully understood and controlled, a superior fighter aircraft can be designed such that it can take full advantage of what is called "supermaneuverability". An initial step in understanding dynamic stall is being able to quantify its effects. In investigating the forces on a model undergoing canard oscillations, this experiment attempted to quantify the lift enhancement, or degradation, observed as the canard and swept-wing vortices interacted. Further, its purpose was to lay the ground work for further studies in this area based upon the experiment's successes or failures.

II. OBJECTIVES

A. BASELINE

The first goal of this experiment was to select two canard/wing model test conditions used by Kersh and verify his results. [Ref. 11] The data points which indicated the most improvement in lift qualities over a non-canard configuration were chosen. The first was a case with the model placed at 22 degrees angle of attack and the canard at +7 degrees deflection, for which a 34-percent increase in maximum lift coefficient was observed. For this case, the canard vortex served to reattach the wing flow at the first stall condition. A second baseline configuration was selected with the model placed at 34 degrees angle of attack and the canard deflected -7 degrees. An improvement of 9.4-percent in lift coefficient was seen for this configuration, which was the regime where a strong leading-edge vortex had formed. It was determined that fixed-canard lift and drag measurements would be made at these configurations and that the canard deflection would be varied ± 3 degrees (i.e. Alpha = 22 deg. with Deltac = +4, +7, +10 deg. and Alpha = 34 deg. with Deltac = -4, -7, -10 deg.) to provide a range of mean values around which to oscillate the canard.

B. EFFECTS OF CANARD OSCILLATION

The canard section was fitted with an electric motor and oscillation mechanism which was connected to the canard pivot point located at 40 percent of its exposed root chord. Once the fixed-canard lift and drag characteristics were obtained, the canard was configured for oscillation. The objective was to oscillate the canard about the above mean deflection angles at frequencies ranging from 5 to 25 hertz. Data was to be presented in the non-dimensional coefficients, C_L and k . C_L represents the lift coefficient and k represents reduced frequency. The following equation was used for the calculation of reduced frequency:

$$k = \frac{(\omega * (MAC/2))}{V} \quad (1)$$

Where:

ω - Frequency (radians/second)

MAC - Canard mean aerodynamic chord (5.38 inches)

V - Freestream velocity (ft/sec)

Lift and Drag data was to be obtained at oscillation amplitudes of ± 5 degrees and ± 10 degrees. It was desired to ascertain the effects of varied oscillation frequencies and amplitudes on the resultant enhanced lift.

III. EXPERIMENTAL APPARATUS

A. WIND TUNNEL

The Naval Postgraduate School (NPS) horizontal low-speed wind tunnel was used for the experiment. Figure 1 shows a diagram of the NPS low-speed wind tunnel. The tunnel is powered by a 100 HP electric motor connected to a standard four-speed truck transmission which turns a three-blade variable-pitch fan. The tunnel is of the single-return type. Airflow is straightened by a set of stator blades immediately aft of the fan. Ambient turbulence intensity in the tunnel test section is about 0.2%. The tunnel's contraction ratio (ratio of cross-section areas between the settling section and test section) of 10:1 combined with fine wire mesh screens at the entrance to the settling chamber contribute to the reasonable value of the test-section turbulence level. The tunnel test section measures 45 inches wide by 32 inches high. Lighting and a reflection plane in the test section reduce the tunnel height to 28 inches and the corresponding effective cross-sectional area to 9.88 square feet. The tunnel is equipped with an external flush-mounted cylindrical strain-gage reflection-plane (wall) balance which is attached to a remotely-controlled turntable. Four four-arm strain-gage bridges separated by 26.5 inches were used to measure axial and normal forces. A more complete

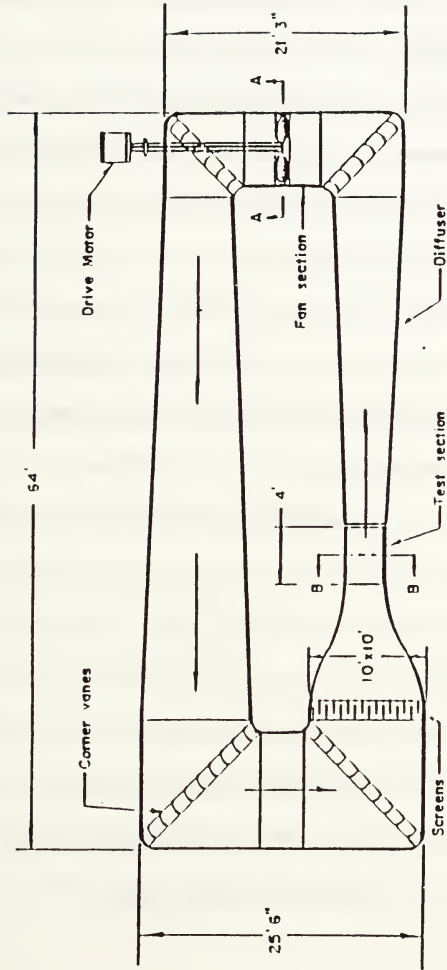


Figure 1: NPS Low-Speed Wind Tunnel

discussion of the balance is given in Section C. The turntable allowed for a variation of the model angle of attack. The temperature of the tunnel air was measured with a dial thermometer mounted on the tunnel wall extending into the settling chamber.

Test section dynamic pressure, q , was determined by measuring the pressure difference, ΔP , between the test section and the settling chamber static pressures using a water manometer. The settling chamber and the test section each have four wall-mounted static pressure taps that are connected to the manometer via a common manifold. The pressure difference measured by the manometer, in centimeters of water, was converted to the test section dynamic pressure and test section reference velocity using a previous tunnel calibration. Equations (2) and (3) show these relationships.

$$q = 2.047 * (-0.026749 + 1.1149 * \Delta P) \quad (2)$$

$$V = \sqrt{\frac{q}{\frac{1}{2} * \rho}} \quad (3)$$

- Where:
- ρ - Density of air (slugs/ft³)
 - ΔP - Manometer reading in cm of H₂O
 - q - Test section dynamic pressure (lbf/ft²)
 - V - Reference velocity (ft/sec)

The wind tunnel calibration factor, 1.1149, and tunnel calibration intercept, - 0.0267649, corrected the manometer reading, ΔP , to the test section dynamic pressure. The calibration factor was found by plotting the actual dynamic pressure measured by a pitot static tube mounted in the test section versus the measured pressure difference. The relationship was found to be linear, with the slope of the curve being the tunnel calibration factor. The slope did not pass through the origin, which resulted in there being a tunnel calibration intercept with the y-axis. [Refs. 11 &12]

B. CANARD/ WING MODEL

The canard/wing model was a half-body model fabricated from mahogany. It was designed to be compatible with the existing reflection-plane balance installed in the wind tunnel. The model was a generic fighter fuselage with a low-aspect-ratio close-coupled canard and wing. The canard and wing surfaces were wood reinforced with aluminum cores. The model consisted of three main sections: an ogive nose, a mid-section with canard, and an aft section with the wing mounted. The ogive nose section was permanently attached to the aluminum base. The removable canard section housed an electric motor and a sending unit used for measuring the canard oscillation frequency. The removable aft section provided support for the mid-section and a path for power and sensor cables to

follow within the model. The model angle of attack was varied using the tunnel turntable. Figure 2 is a sketch of the model. Appendix A contains a detailed description of the model and the design process. [Ref. 11]

C. BALANCE AND TURNTABLE

The external strain-gage balance and turntable, Figure 3, mounted in the horizontal low-speed wind tunnel, was originally built by NPS personnel in 1974. It was designed to measure normal and axial forces and pitching moment in the wind tunnel. The balance itself was capable of measuring forces of up to 150 lbf. Each of the four external strain-gage bridge circuits had four active legs for automatic temperature compensation. The normal and axial moments were measured by two orthogonal strain-gage bridges cemented on balance column flexure links at two axial stations separated by a vertical distance of 26.5 inches. With the wind tunnel in operation, the force on the model created different moments on the upper and lower strain-gage bridges. The voltage signals from the four bridge circuits were converted to axial and normal forces using the results of a balance calibration, described in Appendix B. The balance column was rigidly mounted on an electrically-controlled turntable capable of rotating from -18 to +200 degrees relative to the tunnel centerline. The model was mounted on top of an aluminum turntable disk which was flush with the reflection plane. A one-eighth

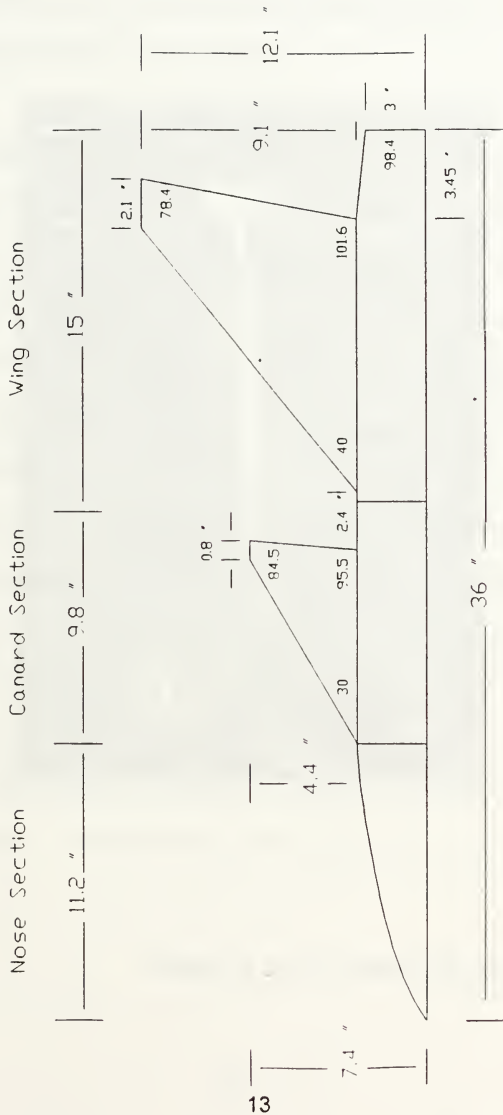


Figure 2. Canard/Wing Half-Body Model

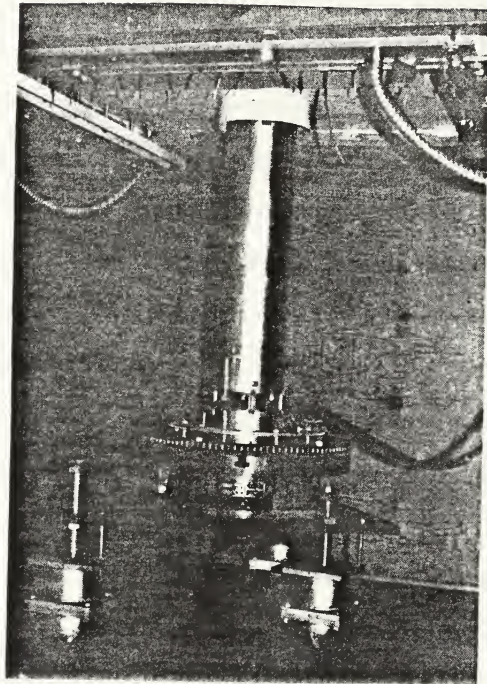


Figure 3. Strain-gage Balance and Turntable

inch gap existed between the turntable disk and the reflection plane. This gap isolated the model and wall balance from the reflection plane in order to preserve integrity of the wall balance load readings.

D. DATA ACQUISITION HARDWARE AND SOFTWARE

Each strain-gage bridge had an individual signal conditioning assembly that supplied the excitation voltage. The signal conditioning assemblies allowed their associated strain-gage bridges to be zeroed and calibrated. The signal from each conditioner was passed through a Pacific® 8255/6 low-noise amplifier with the gain set at 1000. Signals were processed by a National Instruments® MC-MIO-16L-9 12-bit multi-function board as inputs to an IBM PS/2® computer. The MC-MIO-16L-9 has an Analog-to-Digital (A/D) converter with a 9 μ sec. conversion time and is capable of data acquisition rates of up to 100 Kbytes/sec. The board's digitation span was 4096 bits (i.e. 2^{12} bits), giving a resolution of the analog-to-digital conversion of 4.88 mvolts. [Ref. 19] A Microsoft QuickBasic 4.5® program which implemented MC-MIO-16-9 board commands for data acquisition was compiled. The program was written with the help of National Instruments LabWindows® interactive software. A complete listing of the code can be found in Appendix D.

IV. EXPERIMENTAL PROCEDURES

A. CALIBRATION

1. Signal Conditioning

Figure 4 illustrates the calibration rig. The rig was mounted directly to the tunnel reflection plane. Axial line up was accomplished visually. The turntable vernier was then adjusted to zero so that all direct angle readings would be accurate. The height of the cable attachment was adjusted to either 10.5625 inches or 7.75 inches above the floor of the reflection plane, depending upon which calibration run was being conducted. A bubble level was used to adjust the pulley height so that the loading cable was horizontal. Load application to the wall balance using the calibration frame resulted in voltages being processed by the amplifiers. Prior to taking voltage readings, the amplifiers were adjusted for gain and zero offsets. While the inputs to the Pacific® 8255/6 operational amplifiers were shorted and the gain was set to 1, the output set screw was adjusted to produce a reading of 0 ± 100 μ volts. The gain was then set to 1000 and the input set screw was adjusted to obtain a reading of 0 ± 500 μ volts. The amplifier shorts were then removed and the signal conditioners were set to a bridge span of 10 ± 0.05 volts and zeroed to 0 ± 0.05 volts. As zeroing the signal conditioners

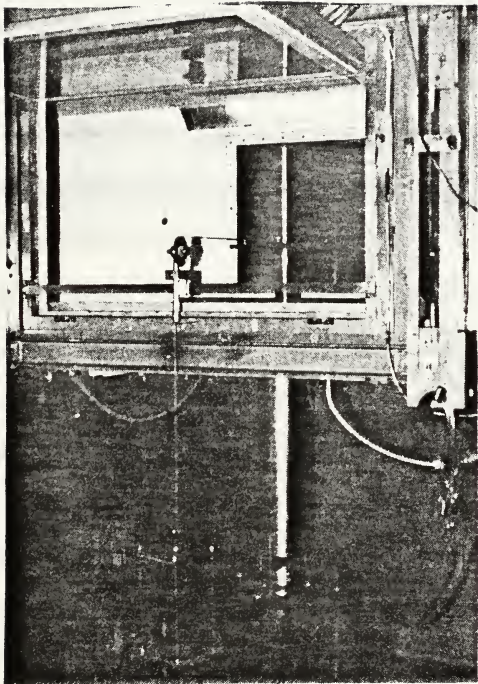


Figure 4. Calibration Rig

exactly was difficult, it was determined that the data acquisition program would be written so as to note voltage offsets or tare readings and automatically adjust for them during data reduction.

2. Equipment Failure

Initial calibration efforts using the Hewlett-Packard® Panels program indicated numerous problems in accuracy and repeatability. As with any strain-gage installation, it was expected that difficulties would generally fall into one of three categories: (1) wire connections, (2) thermal expansion, (3) and moisture absorption. [Ref. 13] The latter two problems were deemed to be negligible as there was little temperature variation during the calibration and virtually no moisture in the tunnel area. Thus, all cannon plugs and wire connections from the cylindrical wall balance through the signal conditioners and operational amplifiers were inspected, cleaned and tightened where necessary. Finally, inspection of the strain-gage bridges themselves led to the source of the inaccuracies. It was determined that the strain gage at position J of Figure B3 (Appendix B) had separated from the cylinder wall thus making all readings erroneous. Further, it was noted that the balance flexures on the cylinder, where the strain-gages were mounted, had buckled in several places. This was apparently due to misuse of the balance over a long period of time. With some difficulty (see Acknowledgements), the strain-gage was replaced and calibration was again commenced. Unfortunately, the Hewlett Packard® Digital Multi-Meter data acquisition system

failed at this time. With no replacement and an unspecified time required for repair, a new method of data acquisition was necessary. With this in mind, the IBM PS/2® computer and National Instruments® MC-MIO-16L-9 multi-function board system in the NPS vertical low-speed wind tunnel was considered for use. The board, along with its LabWindows® interactive software, was functionally tested in the vertical wind tunnel area, then moved to the horizontal low-speed wind tunnel for data acquisition. Electrical noise became a problem as several Pacific® 8255/6 operational amplifiers were tested before satisfactory results were achieved. Appendix B illustrates the calibration process.

3. Data Acquisition

Approximately 100 data points were taken for each height and direction. Each data point was the mean of 1000 voltage readings taken over the span of 2.25 seconds. The corresponding data acquisition rate was 444.44 hertz. The resulting maximum on-axis standard error of regression was less than 0.3 percent. Deflection of the horizontal bar which supported the pulley limited the calibration loading to 35.2 lbf when the cable height was 10.5625 inches and to 55.2 lbf. when the height was 7.75 inches. The maximum loads expected during tunnel operation were approximately 50 lbf. The calibration data indicated that strain-gage response was linear throughout the range of loading. The strain-gage response was assumed to be linear within the structural limits of the balance. The calibration data is included in Appendix B.

B. BASELINE VALIDATION

The experiment was initiated as a follow-on to previous NPS wind tunnel work which studied lift enhancement using close-coupled canard/wing vortex interaction with a static canard. [Ref. 11] As a result, a test objective was to keep the following parameters constant:

1. Test Section $\Delta P = 17 \text{ cm H}_2\text{O}$
2. Test Section Velocity = 172 ft/sec.
3. Reynolds Number = 9.5×10^5 , Ref. to wing MAC

In the study by Kersh, the most profound positive effects of canard/wing vortex interaction were found to occur at angles of attack where major flow separation existed. In this regime, the enhanced lift was thought to be the result of constructive interference of the canard and wing vortical flowfields.

Nineteen wind-tunnel runs were made to validate the procedures and the baseline data. A checklist of procedures was created to ensure that test conditions remained constant. The steps for each tunnel run were as follows:

1. Tunnel Temperature and pressure was recorded.
2. H_2O manometer was zeroed.
3. Model angle of attack zeroed, then set to desired angle.
4. Canard incidence set, oscillation amplitude set (if required).
5. Operational Amplifiers zeroed.
6. Signal Conditioners zeroed and span set.

7. Tare voltage readings taken and checked constant within 0.01 lbf.
8. Mark time.
9. Turn tunnel on and set to $\Delta P = 17 \text{ cm. H}_2\text{O}$.
10. Supply power to canard, set oscillation frequency (if required).
11. Record five readings of voltage for each test condition, check manometer and oscillation frequency between each set.
12. Secure tunnel.
13. Check for voltage drift when tunnel fully stopped.
14. Mark time.

Analysis of initial test runs indicated that the balance calibration procedure was correct and the load values previously obtained were repeatable if the unloaded signal drift was subtracted from all readings. As in the calibration process, each data point was the average of 1000 voltage readings taken over the span of 2.25 seconds. In an effort to determine the source of the drift, the signal variance from the balance signal was checked with the model removed and the tunnel at zero airspeed over a period of one hour. The signal was then checked with the model removed and the tunnel operating at the desired airspeed over a period of fifteen minutes. In both cases, the signal drift was negligible. Test runs were subsequently made with the model at 22 degrees angle of attack and the canard fixed at +4, +7, and +10 degrees deflection. The model was then configured for canard oscillation. Numerous wind tunnel runs indicated that the

electric motor was unable to overcome the dynamic pressure on the canard at $\Delta P = 17$ cm. The canard was designed to pivot about its 40 percent exposed root chord position which was physically located 3.2 inches aft of the leading edge at the root. This position corresponded to 7 percent of the mean aerodynamic chord. The canard's 25 percent mean aerodynamic chord position was located 4.15 inches aft of the leading edge. This aerodynamic loading was assumed to be the primary cause of the motor's failure to oscillate the canard.

Experimental runs were then conducted to determine a manometer setting which would allow canard oscillation. A value of $\Delta P = 12$ cm. was chosen and was held constant for the remainder of the experiment.

C. DATA COLLECTION

The new test objective was to keep the following parameters constant:

1. Test Section $\Delta P = 12$ cm. H_2O
2. Test Section Velocity = 150 ft/sec.
3. Reynolds Number = 7.7×10^5 , Ref. to wing MAC

The baseline procedures stated above were repeated for each tunnel run. The model was initially placed at 22 degrees angle of attack. Lift and drag measurements were obtained with the canard fixed at +4, +7, and +10 degrees deflection. The test were repeated with the model at 34 degrees angle of attack and the canard fixed at -4, -7, and -10 degrees deflection. The canard section of

the model was then removed and the internal mechanism was adjusted to achieve an oscillation amplitude of ± 5 degrees. The model was then reinstalled and tests were conducted under the above conditions with the canard oscillating. Once the tunnel was stabilized at 12 cm H₂O, the DC power supply was energized and adjusted to achieve the desired frequency of oscillation. A sending unit mounted inside the canard section counted the teeth of a sprocket attached to the motor's shaft as it rotated. The instantaneous count per second was displayed on a Fluke® 7250A universal counter/timer. Frequency was calculated by dividing the displayed count by the number of teeth on the sprocket. During each run, frequency was varied from 5 to 25 hertz in increments of 5 hertz. This corresponded to reduced frequencies ranging from 0.046 to 0.232. Five readings were taken at each point. The tunnel was secured and the entire process was repeated two more times to ensure that the results could be duplicated. The canard was then adjusted for a ± 10 -degree amplitude of oscillation. Tests were then attempted at the above model settings. It was found that the frequency could not be controlled below 10 hertz and that the power supply could not provide enough voltage to stabilize the frequency at 25 hertz. Further, it became obvious that the set screws which secured the canard to the shaft of the motor were loosening during each run. Finally, the pin which secured the canard at the pivot point sheared during a tunnel run. The pin was repaired but the canard remained loose at the pivot point and the shaft connection continued to loosen during test

runs. Due to time constraints, the test was terminated at this point. The experimental data is enclosed in Appendix E. A summary of the results and discussion is included in Chapter V.

V. RESULTS AND DISCUSSION

The following section presents the results of 52 wind tunnel runs and a total of 259 minutes of testing. Baseline values of lift and drag were obtained with the tunnel set at $\Delta P = 17 \text{ cm H}_2\text{O}$ and canard incidence fixed at several positions. The model was first placed at 22 degrees angle of attack and tunnel runs were made with the canard fixed at +4, +7, and +10 degrees deflection relative to the model's centerline. This angle of attack and the canard deflection angles were chosen for comparison with previous work which showed a 34-percent lift improvement over a non-canard configured model at 22 degrees angle of attack with +7 degrees canard deflection. [Ref. 11] The gear mechanism attached to the electric motor inside the canard section of the model was then adjusted to create a canard deflection amplitude of ± 5 degrees during oscillation. The canard was then oscillated at frequencies varying from 5 to 25 hertz and corresponding reduced frequencies from 0.046 to 0.232. For comparison to fixed-canard data, the canard was set at mean deflection angles of +4, +7, and +10 degrees. It was found that electric motor which was oscillating the canard could not provide enough power to overcome the aerodynamic forces encountered at this dynamic pressure setting. A new baseline at $\Delta P = 12 \text{ cm H}_2\text{O}$ was chosen so that fixed-canard and oscillating-canard data could be directly compared. The data for the

fixed-canard configurations at $\Delta P = 17$ cm H₂O were kept for comparison with previous work and are enclosed in Appendix F. The above procedures for the model at 22 degrees angle of attack were repeated at the new manometer setting. The model was then set to 34 degrees angle of attack and tunnel runs were made with the canard deflection fixed at -4, -7, and -10 degrees. Previous work had indicated that a 9.4-percent lift improvement over a non-canard configuration occurred at this angle of attack and -7 degrees canard deflection. [Ref. 11] The tunnel tests were then repeated with the canard oscillating about mean deflection values of -4, -7, and -10 degrees. C_L and C_D represent the lift and drag coefficients and were obtained from at least ten recordings. The following equations were used for their calculation:

$$C_L = \frac{Lift}{(q * S)} \quad (4)$$

$$C_D = \frac{Drag}{(q * S)} \quad (5)$$

Where:

- | | | |
|------------|---|--|
| Lift, Drag | - | Force (lbf) |
| q | - | Dynamic Pressure (lbf/ft ²) |
| S | - | Reference Area of exposed canard and wing (0.815 ft ²) |

A. ALPHA = 22 DEGREES

At this angle of attack, Kersh found that the lift coefficient increased as the fixed canard deflection angle was varied from 0 to +7 degrees. In this regime, the canard/wing vortex interaction had a positive effect on the flowfield as flow separation, and thus stall, was delayed. Above +7 degrees canard deflection, flow separation on the upper surface of the wing overcame the positive effects of the canard's shed vortex. Lift coefficient then began to taper off. The canard deflection angles of +4, +7, and +10 degrees were chosen for this experiment in order to verify these results and determine the effect of oscillations at and near the optimum fixed-canard deflection angle. Frequencies of 5 to 25 hertz ($k = 0.046$ to 0.232) were selected in an effort to quantify their effects. Canard amplitude variations of ± 5 degrees and ± 10 degrees were selected for comparison purposes. However, the model was unable to function properly at the ± 10 degree amplitude. Data was only obtained in the ± 5 degree configuration. Figure 5 shows the variation of mean C_L with reduced frequency at this angle of attack and canard mean deflection angles of +4, +7, and +10 degrees. The error bars represent the root-mean-squared (R.M.S.) error of the data. The largest scatter in the data was observed at the reduced frequency of 0.046. It is assumed that this was due to the difficulties encountered in stabilizing the power supply's voltage and thus, the canard's frequency at this low setting.

1. Canard Deflection = +4 Degrees

The canard's mean angle of attack was 26 degrees. Figure 5 shows that the maximum lift coefficient in this configuration was achieved when the canard was fixed. At $k = 0.232$, the lift coefficient was 6.8 percent less than the fixed-canard value. Although the fixed canard was at a deflection angle below that for the maximum-lift angle of attack, the introduction of unsteady flow resulted in a loss of lift. The vortex shed from the canard surface during the dynamic stall occurrence negated the previous improvements seen with a fixed canard. Table 1 lists the frequency, mean lift coefficient and mean drag coefficient for this configuration.

TABLE 1: ALPHA = 22, DELTAC = +4

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.139 | 0.186 | 0.232 |
| Mean CL | 1.2240 | 1.1657 | 1.1685 | 1.1657 | 1.1547 | 1.1406 |
| Mean CD | 0.4603 | 0.4519 | 0.4495 | 0.4449 | 0.4433 | 0.4380 |

2. Canard Deflection = +7 Degrees

The figure shows that the maximum lift coefficient during this portion of the experiment was achieved at the reduced frequency of 0.139. This increase was a 2.6 percent gain over that of the fixed-canard configuration. The canard was at a mean value of 29 degrees angle of attack during this phase, the value

representing the peak of the lift curve slope when the canard was fixed. The positive effects of oscillation began to taper off as frequency was further increased. Table 2 shows the data for the model at 22 degrees angle of attack and canard at +7 degrees deflection.

TABLE 2: ALPHA = 22, DELTAC = +7

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.139 | 0.090 | 0.232 |
| Mean CL | 1.2720 | 1.2902 | 1.3028 | 1.3052 | 1.3042 | 1.2928 |
| Mean CD | 0.4808 | 0.4840 | 0.4850 | 0.4839 | 0.4805 | 0.4776 |

3. Canard Deflection = +10 Degrees

The positive effects of the canard/wing vortex interaction in the fixed-canard configuration diminished as deflection was increased beyond +7 degrees. At +10 degrees deflection, the canard was at 32 degrees mean angle of attack. Figure 5 shows that the introduction of unsteady flow to this flowfield resulted in a 6 percent increase in lift coefficient for all frequencies tested. This increase was significantly greater than that observed when the mean canard deflection was +7 degrees. It is thought that the stronger vortex shed from the canard at this angle of attack resulted in the greater lift enhancement. Table 3 shows the reduced data for this configuration.

TABLE 3: ALPHA = 22, DELTAC = +10

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.093 | 0.186 | 0.232 |
| Mean CL | 1.1654 | 1.2072 | 1.2317 | 1.2316 | 1.2389 | 1.2345 |
| Mean CD | 0.4728 | 0.4833 | 0.4869 | 0.4852 | 0.4853 | 0.4822 |

B. ALPHA = 34 DEGREES

Kersh's work indicated that the lift coefficient increased as the fixed-canard deflection angle was varied from 0 to -7 degrees, at this angle of attack. In this regime, the canard/wing vortex interaction had a positive effect on the flowfield as flow separation, and thus stall, was delayed. At canard deflection angles less than -10 degrees (i.e. more negative), the canard vortex was less effective in providing a positive interaction with the flow over the wing. As a follow-on, canard deflection angles of -4, -7, and -10 were selected for comparison purposes at and near the fixed-canard peak lift angle of attack. The frequencies and amplitude stated above were also used. Oscillating the canard with the model at 34 degrees angle of attack produced effects which differed from those seen at 22 degrees angle of attack. Flow separation along the wing's upper surface was stronger at the higher angle of attack. This flow characteristic apparently delayed the onset of lift enhancement until the canard mean angle of attack was greater than that for

maximum fixed-canard lift enhancement. Figure 6 illustrates the variation of mean C_L with reduced frequency at 34 degrees angle of attack. The maximum R.M.S. error observed was less than 1 percent.

1. Canard Deflection = -4 Degrees

The mean canard angle of attack was 30 degrees during these runs. When the canard was fixed, the model was experiencing the onset of stall and a diminishing of maximum available lift. The introduction of oscillations positively effected the vortical flow over the wing surface. As can be seen in Figure 6, a 3-percent increase in lift was seen at all frequencies. Maximum lift coefficient was achieved at the reduced frequency of 0.154. Table 4 summarizes the lift and drag data for this deflection angle.

TABLE 4: ALPHA = 34, DELTAC = -4

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.139 | 0.185 | 0.232 |
| Mean CL | 1.4785 | 1.5260 | 1.5289 | 1.5289 | 1.5222 | 1.5258 |
| Mean CD | 0.9052 | 0.9261 | 0.9256 | 0.9245 | 0.9211 | 0.9236 |

2. Canard Deflection = -7 Degrees

This deflection produced a canard angle of attack of 27 degrees. Figure 6 shows that the maximum lift coefficient attained was in the fixed-canard configuration. The introduction of unsteady flow over the wing surface reduced the

model's lift by 1.7 percent. At this model angle of attack, the upper surface of the wing was experiencing severe flow separation. The strength of the vortex shed from the canard during oscillation was insufficient to reattach the flow. The positive effects obtained during steady flow were no longer achievable. Table 5 shows the reduced data for this configuration.

TABLE 5: ALPHA = 34, DELTAC = -7

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.139 | 0.186 | 0.232 |
| Mean CL | 1.5124 | 1.4868 | 1.4908 | 1.4869 | 1.4907 | 1.4897 |
| Mean CD | 0.9130 | 0.8993 | 0.8987 | 0.8957 | 0.8975 | 0.8998 |

3. Canard Deflection = -10 Degrees

The canard angle of attack was 24 degrees. A relatively weak vortex was shed from the canard's leading edge during oscillations. The flowfield was dominated by separation along the wing's upper surface. This produced a negative effect on the model's lift capability, as depicted in Figure 6, as lift coefficient was reduced by 7.2 percent. Table 6 shows the reduced data for this configuration.

TABLE 6: ALPHA = 34, DELTAC = -10

| Hertz | 0 | 5 | 10 | 15 | 20 | 25 |
|---------|--------|--------|--------|--------|--------|--------|
| k | 0.000 | 0.046 | 0.093 | 0.139 | 0.186 | 0.232 |
| Mean CL | 1.5012 | 1.4161 | 1.4088 | 1.3995 | 1.3935 | 1.4176 |
| Mean CD | 0.8887 | 0.8266 | 0.8218 | 0.8159 | 0.8125 | 0.8323 |

C. SUMMARY OF RESULTS

Figures 7 and 8 compare the fixed-canard lift characteristics with those of the canard oscillating at $k = 0.139$. These plots illustrate several of the effects of inducing dynamic stall on the canard. It can be seen that the introduction of unsteady flow over the canard at a deflection less than that for maximum lift enhancement had a negative effect. In the regime which was very close to and beyond canard deflection for maximum lift enhancement, canard oscillation had a positive effect. In this area, maximum lift coefficient was increased and the corresponding angle of attack was greater than that of the fixed canard.

Lift enhancement began at different canard angles of attack relative to the fixed-canard angle of attack for maximum lift enhancement. The positive effects began one degree prior to the canard deflection for maximum lift enhancement for the model at 22 degrees. These effects were delayed until one degree after this angle when the model was at 34 degrees. This is thought to be a result of the

relative strength of the flow separation along the upper surface of the wing. It is evident that the dynamic stall phenomenon increased the available stall angle of attack and the maximum lift coefficient.

Lift Coefficient vs. Reduced Frequency
 $\alpha = 22$

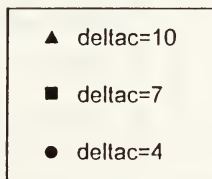
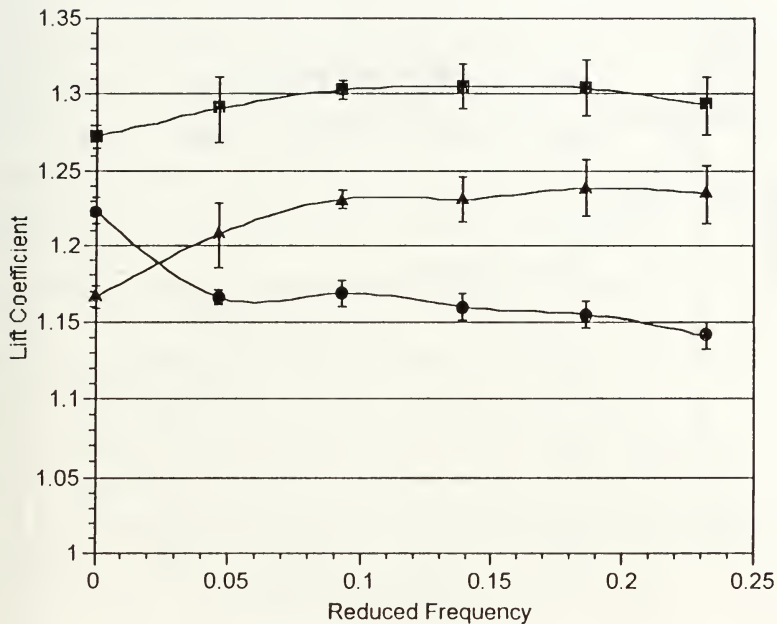


Figure 5. $\alpha = 22$, $\text{Deltac} = +4, +7, +10$

Lift Coefficient vs. Reduced Frequency
 $\alpha = 34$

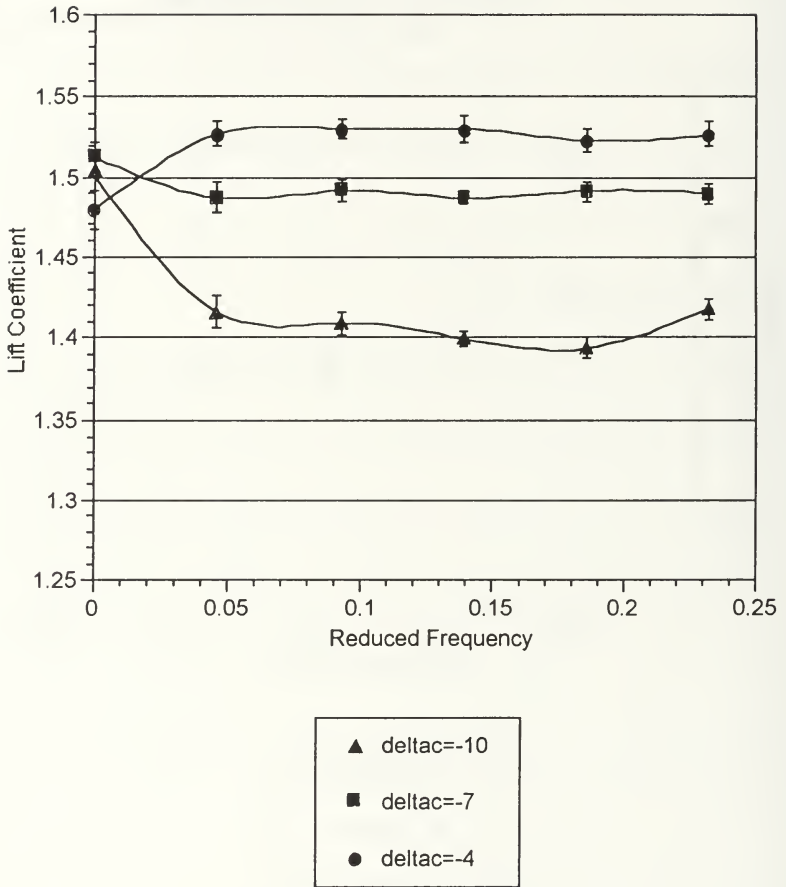


Figure 6. $\alpha = 34$, $\Delta c = -4, -7, -10$

Lift Coefficient vs Canard AOA
Model AOA = 22 degrees
k = 0.139

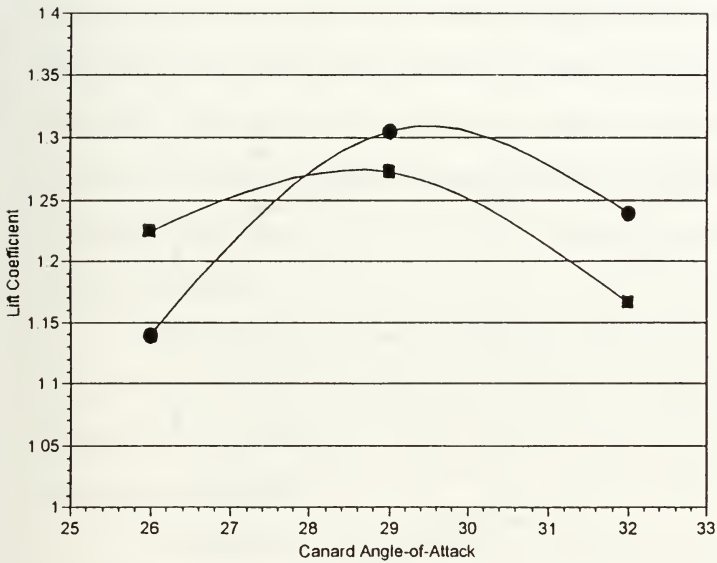


Figure 7. Summary, Alpha = 22

Lift Coefficient vs. Canard AOA
Model AOA = 34 degrees
k = 0.139

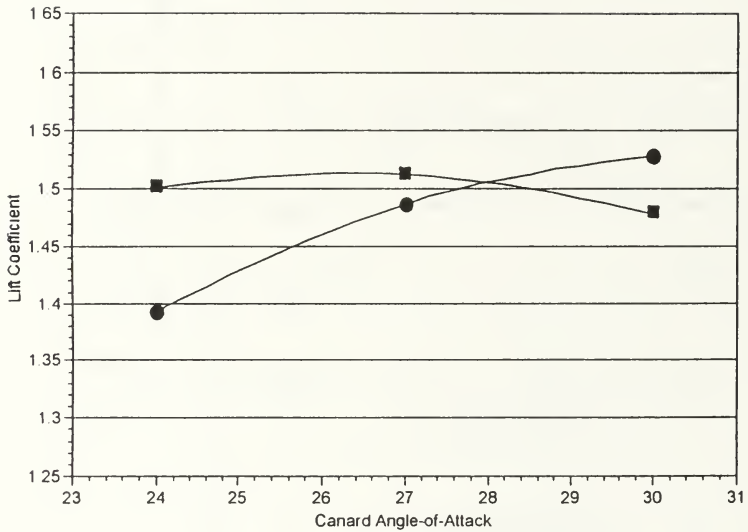


Figure 8. Summary, Alpha = 34

VI. CONCLUSIONS

Dynamic stall of a close-coupled canard was used to determine the effect on the canard/wing vortex interaction for increased lift enhancement. Two angles of attack of the model were studied: one at the first stall condition of the wing and one in the post-stall regime where a strong leading-edge vortex was formed. Mean canard deflections based on those determined to be optimum for the static case were used, as were mean values ± 3 degrees about the optimum. The amplitude of oscillation considered was ± 5 degrees about each mean; reduced frequencies tested were from 0.046 to 0.232. The following conclusions were made from the test.

- For most cases, lift was enhanced beyond the static-canard case at mean deflections equal to those at or greater than the static optimum value. The effective lift was decreased for mean deflections less than those previously determined to be optimum.

- Lift enhancements were generally 2 to 6 percent higher than the values determined with the static canard. The increased lift was generally independent of reduced frequency and peaked between k values of 0.1 to 0.2.

VII. RECOMMENDATIONS

The successes and failures encountered during this exercise result in several recommendations for further work and study. First, the strain-gage balance apparatus is in dire need of replacement. The entire cylinder should be replaced. The repair work completed was a temporary fix at best. The balance's flexure links have buckled due to overloading and misuse and its sensitivity has been reduced significantly. The rest of the strain-gage bridges will become suspect as the tunnel is continually utilized.

The oscillating mechanism within the model canard section needs several design fixes. As it now works, the arm which moves the canard is connected to the motor's shaft by set screws. These screws came loose on several test runs. An improved design would have an enlarged circular cylinder rigidly mounted to the shaft with a shear pin. The cylinder should have small indentations on its outer rim to facilitate the alteration of mean canard deflection angle. Pointed set screws which fit into these indentations would provide a more secure fitting.

The shear pin mounted on the pivot shaft of the canard failed during testing. The shaft was quickly repaired but two problems remain. The pin was replaced with a sturdier screw; however, the canard remained loose. Secondly, there is now a quarter-inch gap between the canard root chord and the model's

fuselage. A larger pin will be necessary to alleviate the looseness but care must be taken to provide a streamlined canard surface. The shaft may need replacing altogether if the gap cannot be reduced.

In the study of dynamic stall of the oscillating canard, two areas require further study. Amplitude effects were not observed due to material failures. Increasing the amplitude of the oscillations may have the same effect as increasing the frequency. [Ref. 5] This remains to be verified for the three-dimensional case. Further, the range of mean canard deflections should be extended in the post-static-stall regime for these configurations and for other model angles of attack. This would quantify the effects of the model's angle of angle and the maximum lift achievable.

In designing the model, Kersh selected the 40-percent exposed root chord of the canard for the pivot point based upon Lacey's work. [Ref. 17] This position was physically located at 7-percent of the mean aerodynamic chord. No direction is given for the placement of a pivot point on a three-dimensional wing. Most two-dimensional studies [Ref. 5 & 20] utilized the airfoil quarter-chord position for oscillation. This is very near the aerodynamic center of the airfoil and thus, minimizes aerodynamic pitching-moment changes. It is recommended that the pivot point be moved to the 25-percent mean aerodynamic chord to reduce the loading on the canard and enable a broader range of wind tunnel velocities for testing.

Finally, flow visualization could be used to yield a better understanding of the dynamic-stall phenomenon. The introduction of buoyant particles into the flowfield along with the use of high-speed photography would enable particle tracing methods to be conducted. Surface flow visualization using oil could be used to qualitatively view the changes for the oscillating and static-canard cases for the flow along the wing's upper surface.

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APPENDIX A: MODEL DESIGN

The design parameters of the canard/wing model were established by Kersh in his study of close-coupled canard/wing vortex interaction. Aspect ratios of 2 for the canard and 3 for the wing were used, based upon the earlier work of Behrbohm. [Ref. 16] A leading-edge sweep of 60 degrees for the canard and 50 degrees for the main wing were selected to ensure strong leading edge vortices for lift enhancement. The canard and wing were straight-tapered and taper ratios of 0.1 and 0.15 respectively were chosen based upon existing aircraft designs. Equations (A1), (A2), and (A3) were used to derive the planform dimensions. [Ref. 22]

$$AR=2 \frac{b}{C_x(1+\lambda)} \quad (A1)$$

$$AR=\frac{b^2}{S} \quad (A2)$$

$$MAC=\frac{2}{3} (C_x+C_t - \frac{C_x C_t}{C_x+C_t}) \quad (A3)$$

Where:

- AR - Aspect Ratio
- b - Wing span
- C_r - Length of root chord
- C_t - Length of tip chord
- λ - Taper ratio C_t/C_r
- S - Area of wing
- MAC - Wing mean aerodynamic chord

The NACA 64A008 airfoil section was chosen for both the wing and the canard based upon Lacey's previous work.[Ref. 17] A rounded leading edge for the wing and canard was used in this design to more closely model what is found on a number of existing aircraft. No attempt was made to trip the boundary layer. The Reynolds number based upon the wing mean aerodynamic chord was 7.7×10^5 . Figure A1 gives the geometric characteristics of the canard and wing. The 40-percent exposed root chord of the canard and the quarter-chord of the MAC of the wing with respect to the centerline of the fuselage were the reference points used for the longitudinal separation of the canard and wing. The ratio of the longitudinal separation of the canard 40-percent exposed root chord point from the 25-percent wing mean aerodynamic chord point, relative to the wing mean aerodynamic chord, x/MAC , was 1.2. This resulted in a 2.33-inch separation

between the exposed trailing edge of the canard and the exposed leading edge of the wing. Vertically, the canard was positioned so that the non-dimensional distance of the canard above the wing, z/MAC , equaled 0.2. This resulted in a 1.9-inch vertical separation between the canard and wing planes. The pivot point of the canard was 40 percent of the exposed root chord. The pivot point of the balance was 17.18 inches from the tip of the model. The model's length of 36 inches, width of 4.5 inches, height of 3 inches, and semi-span, measured from the reflection plane to the wing tip, of 12.1 inches ensured that the balance would be loaded by large forces while the tunnel was in operation. Figure A2 depicts the wing/canard/body model. Although the model was initially tested with a fixed canard, adequate space for a canard positioning motor was included in the design. A rotary-arm mechanism with electric motor was then designed and built by lab personnel to positively control the canard at all tunnel ΔP 's. The electric cabling for the model was led through a hole in the model tail to a controller outside of the tunnel. The canard was oscillated using the controller and a variable DC power supply. Lines drawn on the body at the trailing edge of the canard depicted degrees of canard deflection from the body centerline. Figures A3 and A4 show the model and canard positioning motor. [Ref. 11]

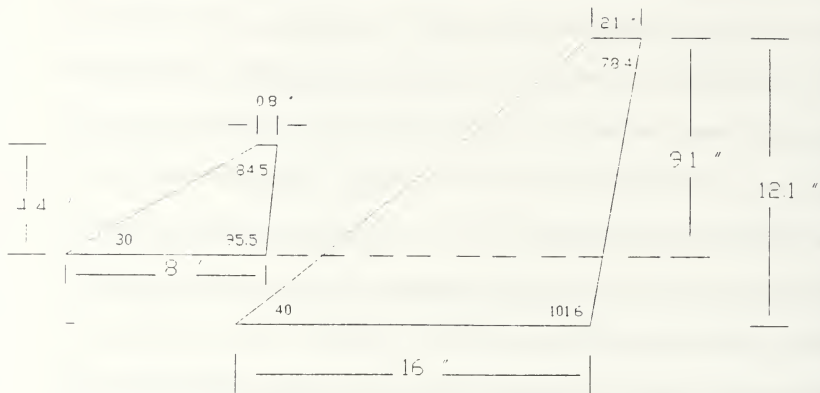


Figure A1. Canard and Wing Sketch

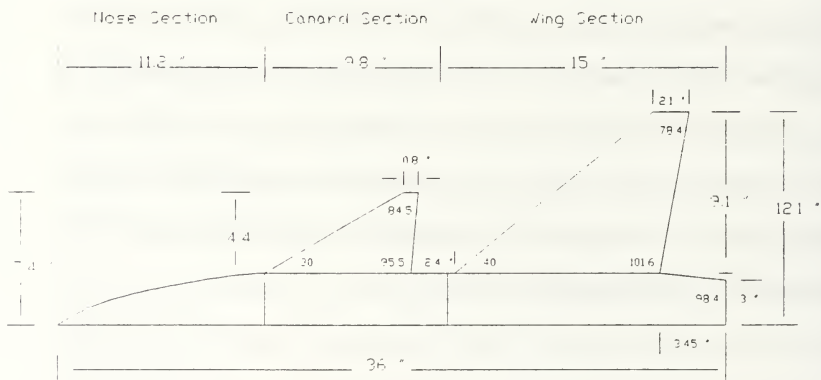


Figure A2. Canard/Wing Model Sketch



Figure A3. Canard/Wing Model

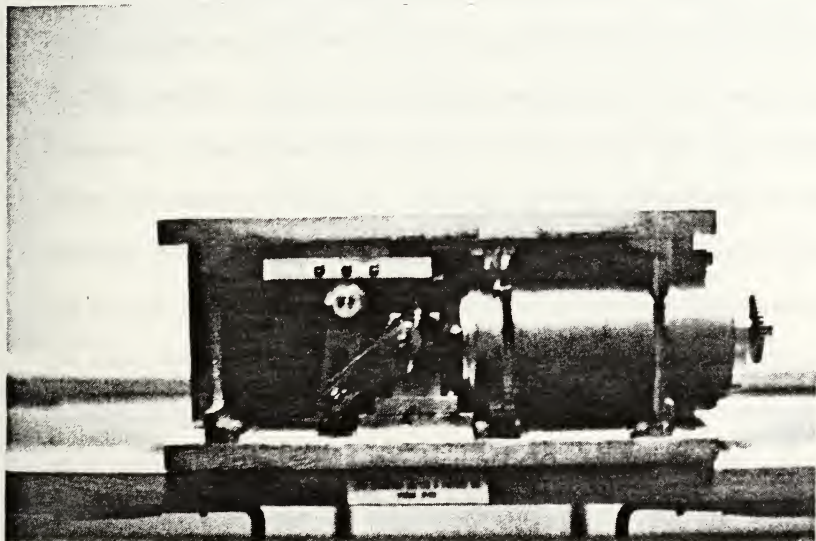


Figure A4. Canard Positioning Motor

APPENDIX B: BALANCE CALIBRATION

The externally-mounted cylindrical strain-gage balance used was built to measure axial and normal forces and pitching moment in the NPS low-speed wind tunnel. Each external strain-gage bridge had four active legs for automatic temperature compensation. The normal and axial moments were measured by two orthogonal strain-gage bridges cemented to the flexure links on the balance column at positions A and B separated by a vertical distance of 26.5 inches, as shown in Figure B1. With the wind tunnel in operation, the forces on the model created a different moment on the upper, bridge B, and the lower, bridge A, strain-gage bridges. With the operational amplifiers set to a gain of 1000 and the 12-bit MC-MIO-16-9 board set for a gain of 1, the system was capable of analog-to-digital conversion with a 4.88-mvolt resolution. An R.M.S. voltmeter was used to verify that electrical noise in the system was less than 1.5 mvolts. The calibration procedure consisted of rotating the balance turntable to either 0 or 90 degrees and suspending weights from the rig at two different heights. A horizontal beam with a pulley mechanism was designed by NPS laboratory personnel to support the calibration weights. The beam was bolted horizontally to the side opening of the wind tunnel test section. The pulley was mounted vertically at the center of the

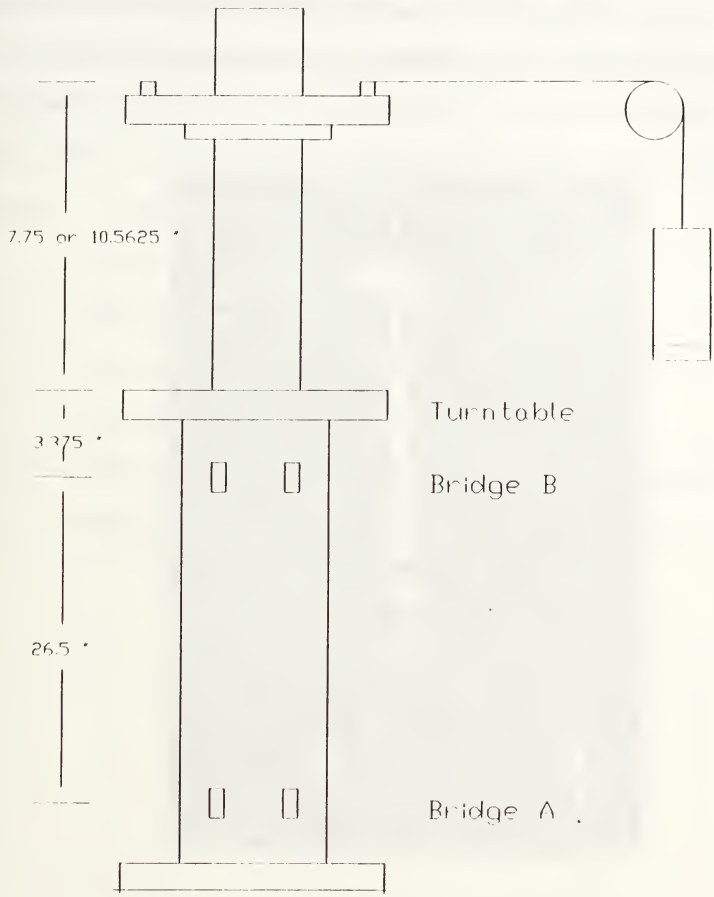


Figure B1. Strain-gage Balance Diagram

beam. Its height was adjustable so that the cable could remain horizontal. Figure B2 shows a photograph of the balance used to measure the forces and the rotating turntable used to position the model at various angles of attack.

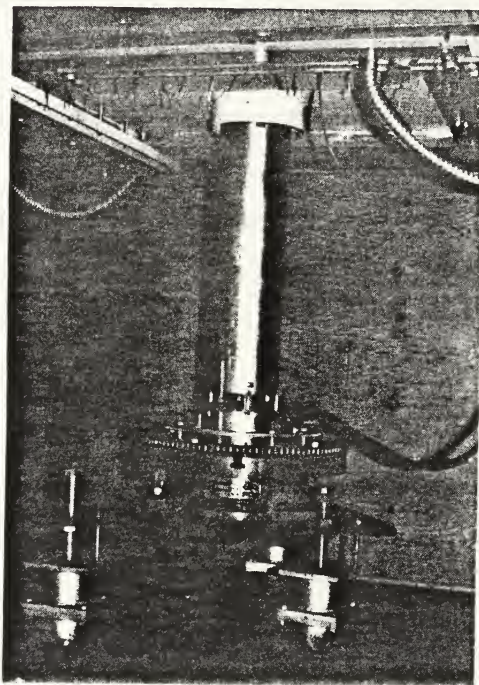


Figure B2. Balance and Turntable

Figure B3 shows the wiring diagram of the strain-gage bridges. Axial forces were measured parallel to the tunnel walls. Normal forces were perpendicular to the walls. Figure B4 illustrates the sign convention used. Note that the balance was rotated 90 degrees when the wing/canard/body model was mounted. This was to account for the turntable rotational limits of -18 to +200 degrees of revolution. Balance nomenclature is as follows:

Ean -Voltage at the lower normal force bridge

Eaa -Voltage at the lower axial force bridge

Ebn -Voltage at the upper normal force bridge

Eba -Voltage at the upper axial force bridge

(a - b) -Height above turntable of first cable attachment point (10.5625 in.)

(a' - b) -Height above turntable of second cable attachment (7.75 in.)

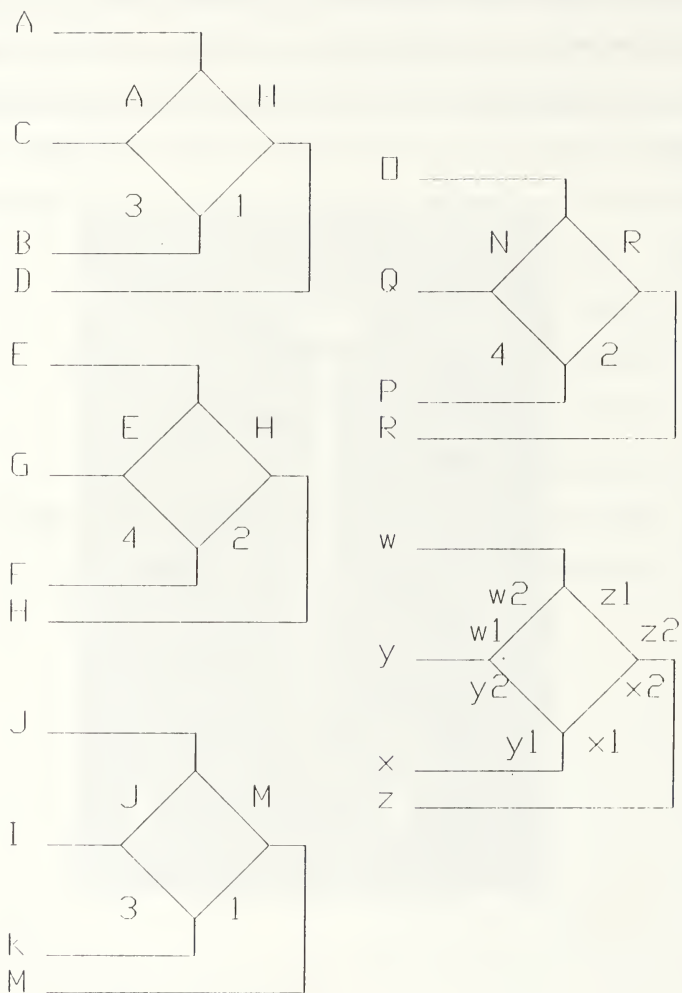


Figure B3. Strain-gage Wiring Diagram

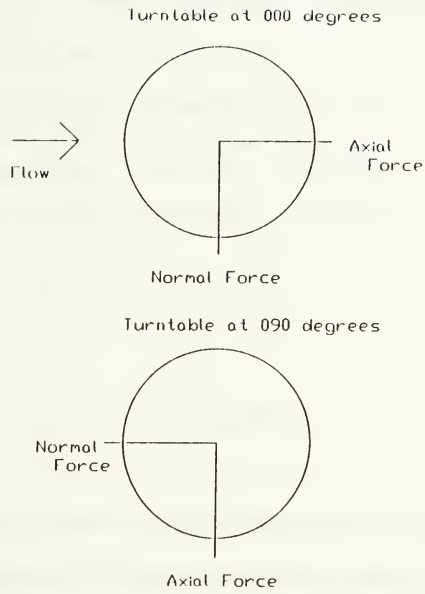


Figure B4. Sign Convention

Equation (B1) was the basic equation used in determining the axial and normal forces and moments.

$$[K] \begin{bmatrix} \frac{d\Delta E}{dLOAD} \end{bmatrix} = \begin{bmatrix} \frac{FORCES}{FORCES} & 0 \\ \frac{FORCES}{MOMENTS} & 0 \\ 0 & \frac{FORCES}{FORCES} \\ 0 & \frac{FORCES}{MOMENTS} \end{bmatrix} \tag{B1}$$

Expanding equation (B1) into 4 X 4 matrices yields:

$$\begin{bmatrix} K_{11} & K_{12} & K_{13} & K_{14} \\ K_{21} & K_{22} & K_{23} & K_{24} \\ K_{31} & K_{32} & K_{33} & K_{34} \\ K_{41} & K_{42} & K_{43} & K_{44} \end{bmatrix} \begin{bmatrix} d\Delta Eaa/dA & d\Delta E'aa/dA & d\Delta Eaa/dN & d\Delta E'aa/dN \\ d\Delta Eba/dA & d\Delta E'ba/dA & d\Delta Eba/dN & d\Delta E'ba/dN \\ d\Delta Ean/dA & d\Delta E'an/dA & d\Delta Ean/dN & d\Delta E'an/dN \\ d\Delta Ebn/dA & d\Delta E'bn/dA & d\Delta Ebn/dN & d\Delta E'bn/dN \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ (a-b) & (a'-b) & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & (a-b) & (a'-b) \end{bmatrix} \quad (B2)$$

The right hand side of equation (B2) was known. The calibration process served to determine the voltage slopes as the balance was loaded and the [K] matrix was found by inverting the $d\Delta E/d\text{Load}$ matrix. Prior to loading the rig, the operational amplifier inputs and outputs were zeroed. The span voltages were then set to 10 volts and the signal zeroes were adjusted to 0 ± 0.05 volts. Weights measured to three-digit accuracy were then suspended from the rig and increased in increments of 5 and 10 lbf. in the normal and axial directions. Two different values for the height of the cable, $(a - b) = 10.5625$ in. and $(a' - b) = 7.75$ in., were used to resolve the moments. Corresponding voltages at each strain-gage were recorded and assembled in data files. The slopes of the voltage variations were determined using the linear regression function of Microsoft Excel®.

To illustrate; $d\Delta E_{aa}/dA$ represents the slope of the voltage E_{aa} versus weight as the rig is loaded axially at the 10.5625-inch height.

The normal and axial forces and moments on the model could then be found using equation (B3).

$$\begin{bmatrix} A \\ n \\ N \\ l \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} [K] \begin{bmatrix} E_{aa} \\ E_{ba} \\ E_{an} \\ E_{bn} \end{bmatrix} \quad (B3)$$

Where: A, N - Axial and Normal Forces (lbf)

n, l - Yaw and Roll Moments (ft lbf)

The non-dimensional coefficients, C_N and C_A , were found using equations similar to (4) and (5). C_L and C_D were found using equations (B4) and (B5).

$$C_L = C_N * \cos(\alpha) - C_A * \sin(\alpha) \quad (B4)$$

$$C_D = C_N * \sin(\alpha) + C_A * \cos(\alpha) \quad (B5)$$

Figures B9 through B12 graphically depict the voltage variations as the calibration rig was loaded in both the axial and normal directions. The calibration data is enclosed in Tables B1 through B4. Linear regression summaries along with error analyses are included at the bottom of each table.

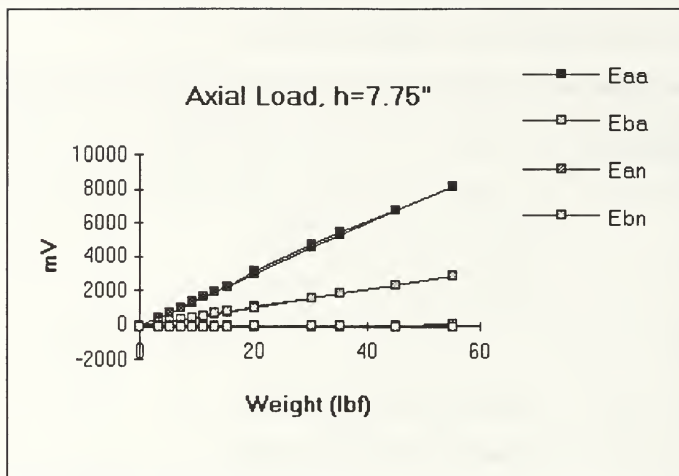


Figure B9: Calibration loading

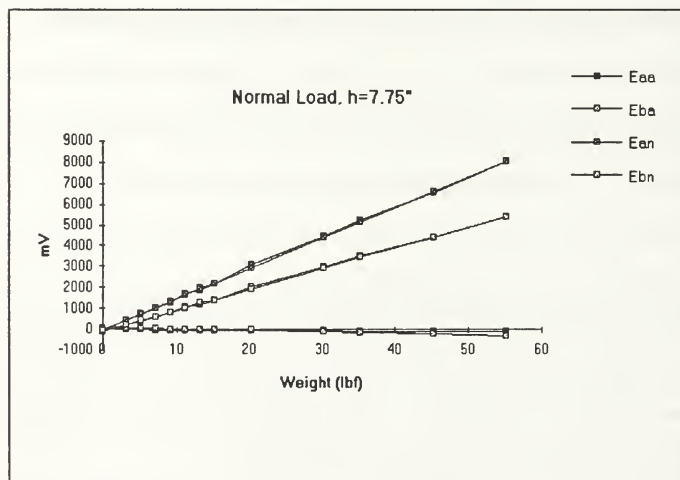


Figure B10: Calibration Loading

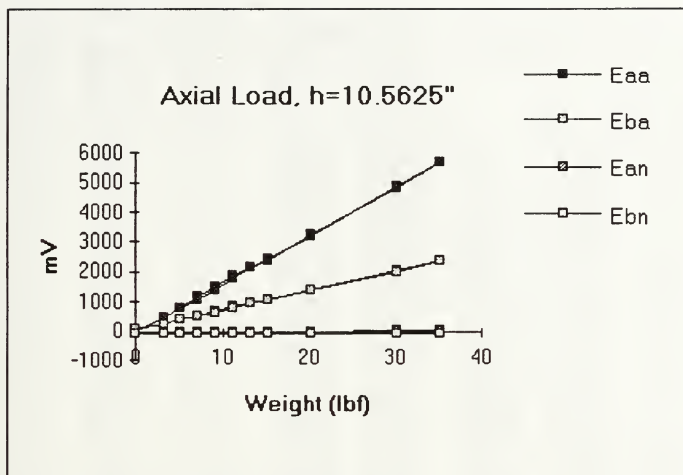


Figure B11: Calibration Loading

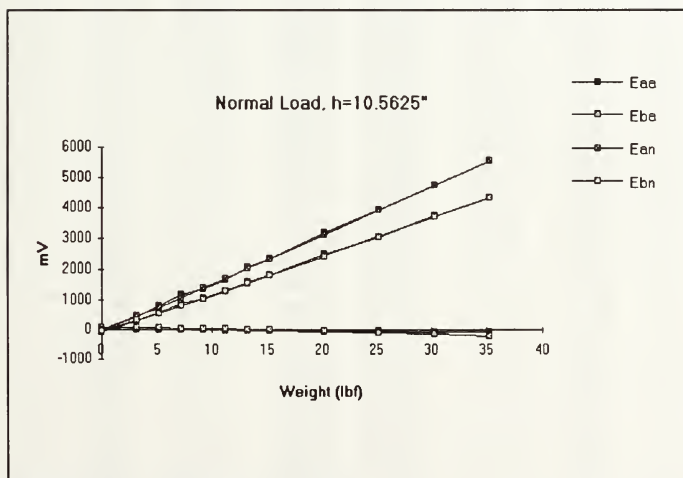


Figure B12: Calibration Loading

TABLE B1: AXIAL LOADING, H=7.75"

| Axial Load | h=7.75" | | | |
|------------|----------|----------|----------|----------|
| Weight | Eaa | Eba | Ean | Ebn |
| 0 | -0.02441 | -3.33008 | -30.0732 | -65.3564 |
| 0 | -0.0293 | -3.21777 | -29.9316 | -65.4688 |
| 0 | -0.01953 | -3.03711 | -30.083 | -65.5518 |
| 0 | -0.00488 | -3.14453 | -29.9658 | -64.9512 |
| 3.204 | 476.1914 | 158.423 | -24.4775 | -63.4521 |
| 3.204 | 475.4248 | 157.998 | -24.5703 | -63.7842 |
| 3.204 | 475.1807 | 157.954 | -24.4775 | -63.6719 |
| 3.204 | 474.2969 | 157.744 | -24.4482 | -64.0918 |
| 5.2 | 717.7783 | 241.646 | -24.3066 | -62.9883 |
| 5.2 | 716.8311 | 240.928 | -24.3604 | -63.0957 |
| 5.2 | 715.752 | 240.767 | -24.3359 | -63.0811 |
| 5.2 | 715.3271 | 240.205 | -24.2627 | -63.2373 |
| 7.207 | 1007.881 | 339.995 | -19.5166 | -62.8613 |
| 7.207 | 1006.968 | 339.522 | -19.5166 | -62.9541 |
| 7.207 | 1005.361 | 339.165 | -19.5117 | -62.9639 |
| 7.207 | 1004.805 | 339.102 | -19.5117 | -63.0518 |
| 9.21 | 1319.497 | 444.805 | -15.6738 | -62.7441 |
| 9.21 | 1318.32 | 444.004 | -16.9482 | -62.5781 |
| 9.21 | 1317.212 | 443.804 | -16.1279 | -62.1924 |
| 9.21 | 1316.177 | 443.706 | -15.542 | -62.4756 |
| 9.21 | 1315.742 | 443.325 | -15.0195 | -62.4414 |
| 11.214 | 1684.038 | 565.776 | -13.4863 | -61.2354 |
| 11.214 | 1683.921 | 565.405 | -13.2861 | -60.9277 |
| 11.214 | 1683.452 | 565.435 | -13.3936 | -61.5137 |
| 11.214 | 1682.954 | 565.103 | -13.1836 | -62.0898 |
| 13.219 | 1936.948 | 654.502 | -9.75586 | -61.4795 |
| 13.219 | 1935.352 | 653.696 | -9.76074 | -61.3623 |
| 13.219 | 1933.779 | 653.267 | -9.75586 | -61.6504 |
| 13.219 | 1932.935 | 652.822 | -9.75586 | -61.9727 |
| 15.223 | 2257.744 | 766.875 | -7.86133 | -60.7568 |
| 15.223 | 2256.147 | 766.494 | -7.55859 | -61.0986 |
| 15.223 | 2254.849 | 765.718 | -7.05566 | -60.8838 |
| 15.223 | 2253.955 | 765.996 | -6.35742 | -60.9619 |
| 20.233 | 3125.903 | 1071.95 | 0.498047 | -59.4629 |
| 20.233 | 3124.395 | 1070.74 | 0.527344 | -59.3408 |
| 20.233 | 3122.754 | 1070.74 | 0.493164 | -58.9063 |
| 20.233 | 3120.894 | 1069.97 | 0.678711 | -58.6963 |
| 30.236 | 4691.333 | 1607.08 | 14.31641 | -58.0615 |
| 30.236 | 4688.755 | 1606.11 | 14.25293 | -58.2813 |
| 30.236 | 4686.528 | 1605.02 | 14.27246 | -58.2715 |
| 30.236 | 4684.966 | 1604.61 | 14.21387 | -58.5205 |
| 35.242 | 5447.676 | 1869.58 | 19.28711 | -58.2617 |

| | | | | | | |
|--------|----------|---------|----------|----------|--|--|
| 35.242 | 5442.495 | 1867.72 | 19.5459 | -58.1836 | | |
| 45.244 | 6741.177 | 2316.51 | 28.70606 | -58.2715 | | |
| 45.244 | 6736.66 | 2315.27 | 28.76953 | -58.2422 | | |
| 45.244 | 6733.574 | 2314.44 | 28.7207 | -58.0566 | | |
| 45.244 | 6729.819 | 2312.88 | 28.75977 | -57.959 | | |
| 55.248 | 8191.704 | 2825.47 | 37.12891 | -60.2979 | | |
| 55.248 | 8182.231 | 2822.47 | 37.03613 | -60.3906 | | |
| 55.248 | 8177.139 | 2821.01 | 36.85547 | -60.7178 | | |
| 55.248 | 8174.16 | 2820.3 | 36.97754 | -60.6104 | | |
| 45.244 | 6738.53 | 2328.48 | 30.21973 | -56.5576 | | |
| 45.244 | 6736.006 | 2327.62 | 30.1709 | -56.8213 | | |
| 45.244 | 6733.516 | 2326.89 | 30.20996 | -56.2256 | | |
| 45.244 | 6731.792 | 2325.83 | 30.24902 | -57.1924 | | |
| 35.242 | 5253.608 | 1830.83 | 21.12793 | -54.917 | | |
| 35.242 | 5252.813 | 1830.3 | 20.28809 | -54.7559 | | |
| 35.242 | 5249.463 | 1829.15 | 20.27832 | -54.7949 | | |
| 35.242 | 5247.573 | 1828.66 | 20.22949 | -55.4639 | | |
| 30.236 | 4520.259 | 1576.64 | 15.3125 | -54.7314 | | |
| 30.236 | 4519.741 | 1576.31 | 15.19043 | -54.3457 | | |
| 30.236 | 4519.199 | 1576.72 | 15.15137 | -54.0186 | | |
| 30.236 | 4518.662 | 1576.3 | 15.30273 | -54.3457 | | |
| 20.233 | 2989.595 | 1053.71 | 1.010742 | -56.665 | | |
| 20.233 | 2988.486 | 1053.72 | 0.722656 | -57.0605 | | |
| 20.233 | 2987.896 | 1053.03 | 0.795898 | -57.0459 | | |
| 20.233 | 2987.422 | 1052.87 | 1.230469 | -56.6895 | | |
| 15.223 | 2262.227 | 800.181 | -4.94629 | -58.0518 | | |
| 15.223 | 2261.729 | 799.722 | -4.96582 | -58.0811 | | |
| 15.223 | 2261.563 | 799.634 | -4.94629 | -57.4023 | | |
| 15.223 | 2261.699 | 799.443 | -4.94629 | -57.2461 | | |
| 15.223 | 2261.309 | 799.78 | -4.90234 | -57.3193 | | |
| 13.219 | 1947.998 | 690.962 | -9.71191 | -58.4863 | | |
| 13.219 | 1947.583 | 690.947 | -9.73145 | -58.3447 | | |
| 13.219 | 1947.173 | 690.518 | -9.70703 | -58.5205 | | |
| 13.219 | 1947.134 | 690.542 | -9.72656 | -58.4131 | | |
| 13.219 | 1946.821 | 690.898 | -9.69727 | -58.3008 | | |
| 11.214 | 1636.221 | 583.189 | -11.9873 | -59.1602 | | |
| 11.214 | 1636.602 | 582.817 | -12.6416 | -58.8672 | | |
| 11.214 | 1636.719 | 582.93 | -13.0957 | -58.9648 | | |
| 11.214 | 1636.729 | 583.149 | -12.6074 | -58.8086 | | |
| 9.21 | 1360.371 | 489.219 | -14.6338 | -59.8828 | | |
| 9.21 | 1360.952 | 489.048 | -14.6338 | -59.7363 | | |
| 9.21 | 1360.767 | 489.116 | -14.6338 | -59.2236 | | |
| 9.21 | 1359.243 | 488.926 | -14.6338 | -59.5654 | | |
| 7.207 | 1038.735 | 382.324 | -19.5117 | -60.1758 | | |
| 7.207 | 1038.647 | 382.036 | -19.5117 | -59.8242 | | |
| 7.207 | 1038.208 | 381.88 | -19.5117 | -60.9717 | | |
| 7.207 | 1038.052 | 381.846 | -19.5117 | -61.1572 | | |
| 5.2 | 733.2666 | 278.96 | -24.0039 | -61.499 | | |

| | | | | | | | |
|-----------|--------------|----------------|----------|-----------|--------------|----------------|--|
| 5.2 | 731.6699 | 278.057 | -24.0576 | -61.123 | | | |
| 5.2 | 731.7432 | 277.959 | -24.0723 | -60.9619 | | | |
| 5.2 | 733.3789 | 278.711 | -24.0723 | -60.8936 | | | |
| 3.204 | 447.832 | 180.132 | -24.873 | -61.7432 | | | |
| 3.204 | 444.3359 | 179.17 | -26.2061 | -62.5879 | | | |
| 3.204 | 444.1064 | 178.677 | -26.1475 | -62.749 | | | |
| 3.204 | 444.1846 | 179.004 | -25.6543 | -62.2461 | | | |
| 3.204 | 443.6377 | 178.535 | -25.1758 | -62.4072 | | | |
| 0 | 0.9375 | 24.7266 | -31.9531 | -62.9688 | | | |
| 0 | 0.981445 | 24.6143 | -32.2021 | -63.2764 | | | |
| 0 | 1.142578 | 24.5068 | -32.3486 | -63.2178 | | | |
| 0 | 1.040039 | 24.4678 | -32.1045 | -63.1738 | | | |
| | | | | | | | |
| | Coefficients | Standard Error | | | Coefficients | Standard Error | |
| Eaa | | | | Ean | | | |
| Intercept | -24.7759 | 9.244163 | | Intercept | -28.1355 | 0.381975 | |
| x1 | 150.3653 | 0.401024 | | x1 | 1.307424 | 0.016571 | |
| | | | | | | | |
| Eba | | | | Ebn | | | |
| Intercept | 0.370737 | 3.415721 | | Intercept | -62.1463 | 0.313433 | |
| x1 | 51.67094 | 0.148178 | | x1 | 0.120979 | 0.013597 | |

TABLE B2: NORMAL LOADING, H=7.75"

| Normal Load | h=7.75" | | | |
|-------------|-----------|----------|----------|----------|
| Weight | Eaa | Eba | Ean | Ebn |
| 0 | -9.887695 | 23.1299 | -5.44922 | -82.7881 |
| 0 | -9.863281 | 23.0225 | -5.29297 | -82.4805 |
| 0 | -9.907227 | 23.0371 | -5.25391 | -82.3389 |
| 0 | -9.858398 | 23.0127 | -5.16113 | -82.2314 |
| 3.204 | -19.51172 | 16.3867 | 446.8359 | 213.442 |
| 3.204 | -19.51172 | 16.3086 | 447.0313 | 212.881 |
| 3.204 | -19.51172 | 16.333 | 447.0752 | 213.081 |
| 3.204 | -19.51172 | 16.1426 | 447.3486 | 213.521 |
| 5.2 | -24.38477 | 12.7393 | 712.2363 | 391.465 |
| 5.2 | -24.375 | 12.6123 | 711.2842 | 391.299 |
| 5.2 | -24.36035 | 12.583 | 710.9863 | 390.918 |
| 5.2 | -24.37988 | 12.6416 | 710.7129 | 390.117 |
| 5.2 | -24.37988 | 12.5928 | 710.542 | 389.443 |
| 7.207 | -29.10156 | 8.45703 | 1001.929 | 582.432 |
| 7.207 | -29.16016 | 8.46191 | 1000.41 | 581.157 |
| 7.207 | -29.15527 | 8.34961 | 999.6338 | 580.747 |
| 7.207 | -29.0625 | 8.25195 | 999.0869 | 580.151 |
| 9.21 | -33.37402 | 3.76953 | 1292.456 | 781.113 |
| 9.21 | -33.39356 | 3.63281 | 1291.797 | 780.566 |
| 9.21 | -33.50586 | 3.68652 | 1291.714 | 780.005 |
| 9.21 | -33.33496 | 3.56445 | 1291.157 | 779.775 |
| 9.21 | -33.36914 | 3.51074 | 1290.991 | 779.199 |
| 11.214 | -38.95996 | -2.91504 | 1687.554 | 1052.75 |
| 11.214 | -38.97949 | -3.14941 | 1686.504 | 1051.83 |
| 11.214 | -38.96973 | -3.25684 | 1685.537 | 1050.71 |
| 11.214 | -38.98926 | -3.29102 | 1684.541 | 1050.59 |
| 13.219 | -42.80762 | -6.21094 | 1873.511 | 1180.03 |
| 13.219 | -42.83203 | -6.2207 | 1872.358 | 1178.9 |
| 13.219 | -42.86621 | -6.31836 | 1871.323 | 1178.5 |
| 13.219 | -42.5293 | -6.17676 | 1871.357 | 1178.12 |
| 15.223 | -47.68555 | -11.6602 | 2184.409 | 1393.91 |
| 15.223 | -47.69531 | -11.7529 | 2183.408 | 1393.46 |
| 15.223 | -47.59277 | -11.9043 | 2182.754 | 1392.47 |
| 15.223 | -47.72949 | -11.9043 | 2182.354 | 1391.5 |
| 20.233 | -61.18652 | -30.4541 | 3059.663 | 1992.79 |
| 20.233 | -61.26953 | -30.8203 | 3058.389 | 1991.84 |
| 20.233 | -61.02051 | -31.25 | 3056.548 | 1990.6 |
| 20.233 | -60.99121 | -31.2305 | 3055.288 | 1989.81 |
| 20.233 | -60.9668 | -31.3037 | 3054.707 | 1989.43 |
| 30.236 | -80.96191 | -87.9834 | 4468.882 | 2952.54 |
| 30.236 | -81.29883 | -88.999 | 4464.873 | 2949.37 |
| 30.236 | -81.16211 | -89.3506 | 4462.866 | 2947.69 |

| | | | | | | | |
|--------|-----------|----------|----------|---------|--|--|--|
| 35.242 | -92.92481 | -134.644 | 5262.129 | 3492.31 | | | |
| 35.242 | -92.80762 | -134.917 | 5259.277 | 3490.47 | | | |
| 35.242 | -93.05664 | -135.015 | 5257.119 | 3489.03 | | | |
| 45.244 | -112.4902 | -222.236 | 6580.293 | 4390.35 | | | |
| 45.244 | -112.3926 | -222.715 | 6576.294 | 4387.05 | | | |
| 45.244 | -112.3096 | -223.247 | 6572.744 | 4384.69 | | | |
| 45.244 | -112.2461 | -223.335 | 6569.414 | 4382.77 | | | |
| 55.248 | -134.1895 | -335.586 | 8051.323 | 5391.52 | | | |
| 55.248 | -134.1748 | -336.353 | 8044.38 | 5385.72 | | | |
| 55.248 | -133.9551 | -336.729 | 8035.649 | 5379.47 | | | |
| 55.248 | -133.6963 | -336.782 | 8031.606 | 5376.33 | | | |
| 55.248 | -133.8916 | -336.807 | 8028.687 | 5374 | | | |
| 45.244 | -109.7705 | -230.244 | 6613.623 | 4411.33 | | | |
| 45.244 | -109.8682 | -230.439 | 6611.909 | 4409.58 | | | |
| 45.244 | -109.7412 | -230.459 | 6611.655 | 4409.5 | | | |
| 45.244 | -109.7803 | -230.698 | 6612.168 | 4410.24 | | | |
| 35.242 | -88.19336 | -146.572 | 5157.119 | 3418.93 | | | |
| 35.242 | -88.20313 | -146.782 | 5156.885 | 3418.54 | | | |
| 35.242 | -88.11035 | -146.528 | 5156.88 | 3417.92 | | | |
| 35.242 | -88.30078 | -146.577 | 5155.439 | 3416.88 | | | |
| 30.236 | -77.68066 | -100.928 | 4419.492 | 2915.8 | | | |
| 30.236 | -77.77344 | -101.187 | 4419.038 | 2914.84 | | | |
| 30.236 | -77.77832 | -101.099 | 4418.73 | 2914.07 | | | |
| 30.236 | -77.61231 | -101.25 | 4418.755 | 2914.04 | | | |
| 20.233 | -55.88379 | -24.7852 | 2934.404 | 1906.03 | | | |
| 20.233 | -55.9668 | -24.9219 | 2933.999 | 1905.46 | | | |
| 20.233 | -55.81543 | -25.166 | 2933.823 | 1904.87 | | | |
| 20.233 | -55.93262 | -25.0537 | 2933.55 | 1904.59 | | | |
| 20.233 | -55.96191 | -24.9365 | 2933.618 | 1904.51 | | | |
| 15.223 | -44.58496 | -6.18164 | 2194.624 | 1399.08 | | | |
| 15.223 | -44.58496 | -6.29395 | 2194.258 | 1397.9 | | | |
| 15.223 | -44.61426 | -6.04492 | 2194.868 | 1398.75 | | | |
| 15.223 | -44.75098 | -5.96191 | 2194.175 | 1398.23 | | | |
| 15.223 | -44.7168 | -6.10352 | 2194.272 | 1398.13 | | | |
| 13.219 | -41.99707 | -0.04883 | 1970.278 | 1246.15 | | | |
| 13.219 | -42.05078 | -0.13184 | 1971.064 | 1246.45 | | | |
| 13.219 | -42.00684 | -0.13672 | 1971.641 | 1247.19 | | | |
| 13.219 | -41.97266 | -0.15137 | 1971.982 | 1246.8 | | | |
| 11.214 | -37.19238 | 12.9004 | 1617.314 | 1003.29 | | | |
| 11.214 | -37.22168 | 12.9053 | 1617.173 | 1003.3 | | | |
| 11.214 | -37.24121 | 12.959 | 1616.646 | 1002.82 | | | |
| 11.214 | -36.96289 | 12.7881 | 1617.207 | 1003.16 | | | |
| 11.214 | -36.86035 | 12.7832 | 1616.748 | 1002.18 | | | |
| 9.21 | -32.76856 | 22.1484 | 1318.184 | 799.189 | | | |
| 9.21 | -32.89063 | 21.9238 | 1318.296 | 798.94 | | | |
| 9.21 | -33.04688 | 21.9531 | 1318.301 | 799.111 | | | |
| 9.21 | -32.92481 | 21.9189 | 1317.813 | 799.102 | | | |
| 7.207 | -29.12109 | 31.2598 | 1028.291 | 601.938 | | | |

| | | | | | | |
|-----------|--------------|----------------|-----------|--------------|----------------|--|
| 7.207 | -29.10156 | 31.3379 | 1027.817 | 601.934 | | |
| 7.207 | -29.08691 | 31.1768 | 1027.715 | 601.035 | | |
| 7.207 | -29.10156 | 31.3232 | 1027.432 | 601.25 | | |
| 5.2 | -24.37012 | 40.9033 | 726.3965 | 401.743 | | |
| 5.2 | -24.37988 | 41.1084 | 726.3525 | 401.758 | | |
| 5.2 | -24.375 | 41.0498 | 726.5088 | 401.963 | | |
| 5.2 | -24.375 | 41.0645 | 726.4111 | 402.529 | | |
| 3.204 | -19.51172 | 50.2783 | 437.9785 | 208.779 | | |
| 3.204 | -19.50684 | 50.1855 | 437.5635 | 209.111 | | |
| 3.204 | -19.5166 | 50.1807 | 437.8906 | 207.656 | | |
| 3.204 | -19.5166 | 50.2148 | 437.8467 | 207.168 | | |
| 0 | -13.36914 | 62.9492 | -1.875 | -76.9141 | | |
| 0 | -13.4375 | 63.0078 | -2.04102 | -76.0254 | | |
| 0 | -13.30566 | 62.9102 | -1.78223 | -76.4502 | | |
| 0 | -13.50098 | 62.8906 | -1.8457 | -75.6152 | | |
| | | | | | | |
| | Coefficients | Standard Error | | Coefficients | Standard Error | |
| Eaa | | | Ean | | | |
| Intercept | -12.944276 | 0.230756 | Intercept | -20.499395 | 6.552537 | |
| x1 | -2.193082 | 0.009819 | x1 | 146.805075 | 0.278807 | |
| Eba | | | Ebn | | | |
| Intercept | 71.654185 | 3.483731 | Intercept | -106.57796 | 4.745903 | |
| x1 | -6.391158 | 0.148231 | x1 | 99.945325 | 0.201936 | |

TABLE B3: AXIAL LOADING, H=10.5625"

| Axial Load | | h=10.5625" | | | |
|------------|----------|------------|----------|----------|--|
| Weight | Eaa | Eba | Ean | Ebn | |
| 0 | -0.07813 | 86.5186 | -29.2725 | -67.5146 | |
| 0 | -0.0293 | 86.3916 | -29.2627 | -67.5488 | |
| 0 | -0.01465 | 86.4746 | -29.2578 | -67.6514 | |
| 0 | -0.04883 | 86.4209 | -29.2627 | -67.832 | |
| 3.204 | 492.4072 | 291.836 | -22.6953 | -63.1396 | |
| 3.204 | 492.7393 | 291.841 | -23.4424 | -63.75 | |
| 3.204 | 493.042 | 291.704 | -22.9248 | -63.4668 | |
| 3.204 | 493.2471 | 291.953 | -22.4365 | -63.4863 | |
| 5.2 | 810.7666 | 418.897 | -18.8525 | -62.2656 | |
| 5.2 | 810.2246 | 418.398 | -19.292 | -61.8701 | |
| 5.2 | 809.4189 | 418.106 | -19.2139 | -61.7676 | |
| 5.2 | 808.9063 | 417.817 | -18.916 | -61.8896 | |
| 7.207 | 1164.453 | 558.008 | -12.2021 | -59.541 | |
| 7.207 | 1163.56 | 557.139 | -12.876 | -59.9414 | |
| 7.207 | 1162.734 | 556.523 | -12.5391 | -59.6484 | |
| 7.207 | 1162.095 | 556.577 | -11.7383 | -58.9502 | |
| 9.21 | 1531.597 | 705.273 | -7.10938 | -57.627 | |
| 9.21 | 1530.981 | 705.19 | -7.24121 | -57.6025 | |
| 9.21 | 1530.142 | 704.727 | -7.02637 | -57.7051 | |
| 9.21 | 1529.707 | 704.487 | -7.11914 | -57.5684 | |
| 9.21 | 1529.043 | 704.028 | -6.63574 | -57.4121 | |
| 11.214 | 1903.477 | 855.85 | -0.72754 | -54.1943 | |
| 11.214 | 1903.032 | 855.332 | -0.93262 | -53.9746 | |
| 11.214 | 1902.632 | 854.858 | -0.85938 | -54.0771 | |
| 11.214 | 1902.129 | 854.697 | -0.73731 | -54.4922 | |
| 13.219 | 2154.517 | 957.944 | 0.541992 | -53.1934 | |
| 13.219 | 2152.964 | 957.642 | 0.395508 | -53.1104 | |
| 13.219 | 2151.558 | 957.114 | 0.527344 | -53.2715 | |
| 13.219 | 2151.089 | 957.344 | 0.825195 | -53.418 | |
| 15.223 | 2415.957 | 1065.36 | 4.760742 | -52.583 | |
| 15.223 | 2415.273 | 1064.95 | 4.697266 | -52.5146 | |
| 15.223 | 2414.473 | 1064.28 | 4.6875 | -51.8945 | |
| 15.223 | 2413.462 | 1063.92 | 4.780273 | -51.6455 | |
| 20.233 | 3204.951 | 1385.51 | 14.54102 | -48.2275 | |
| 20.233 | 3201.807 | 1384.71 | 14.54102 | -48.3154 | |
| 20.233 | 3200.02 | 1383.73 | 14.58008 | -48.4961 | |
| 20.233 | 3199.512 | 1383.46 | 14.64356 | -48.4277 | |
| 20.233 | 3198.984 | 1383.14 | 14.70703 | -48.54 | |
| 30.236 | 4852.729 | 2037.64 | 33.78418 | -41.3965 | |
| 30.236 | 4849.116 | 2036.02 | 33.73535 | -42.4316 | |
| 30.236 | 4846.831 | 2035.13 | 33.7793 | -42.6367 | |

| | | | | | | | |
|--------|----------|---------|----------|----------|--|--|--|
| 35.242 | 5684.717 | 2363.11 | 43.08106 | -39.5166 | | | |
| 35.242 | 5682.041 | 2362.3 | 42.97363 | -39.5801 | | | |
| 35.242 | 5678.594 | 2360.63 | 43.02734 | -39.3359 | | | |
| 35.242 | 5677.29 | 2360.36 | 43.16895 | -39.5264 | | | |
| 30.236 | 4836.128 | 2024.18 | 31.71875 | -43.6719 | | | |
| 30.236 | 4834.648 | 2023.92 | 31.58691 | -43.5107 | | | |
| 30.236 | 4833.682 | 2023.13 | 31.72852 | -43.3252 | | | |
| 30.236 | 4832.661 | 2022.67 | 31.76758 | -43.3594 | | | |
| 20.233 | 3241.875 | 1401.53 | 14.32617 | -48.1738 | | | |
| 20.233 | 3241.191 | 1401.24 | 14.41895 | -48.0029 | | | |
| 20.233 | 3240.63 | 1401.06 | 14.45801 | -47.8906 | | | |
| 20.233 | 3240.815 | 1400.97 | 14.45801 | -47.8369 | | | |
| 20.233 | 3240.449 | 1400.69 | 14.37988 | -47.9395 | | | |
| 15.223 | 2403.325 | 1061.02 | 4.526367 | -52.2754 | | | |
| 15.223 | 2403.325 | 1060.92 | 4.550781 | -52.3096 | | | |
| 15.223 | 2402.822 | 1060.89 | 4.614258 | -52.4316 | | | |
| 15.223 | 2402.451 | 1061.21 | 4.619141 | -52.4951 | | | |
| 15.223 | 2402.559 | 1060.9 | 4.604492 | -51.9971 | | | |
| 13.219 | 2153.34 | 958.569 | 0.170898 | -52.8857 | | | |
| 13.219 | 2152.559 | 958.418 | 0.151367 | -53.1494 | | | |
| 13.219 | 2152.139 | 958.145 | 0.161133 | -53.1787 | | | |
| 13.219 | 2151.636 | 958.56 | 0.170898 | -53.3838 | | | |
| 11.214 | 1781.68 | 808.779 | -4.86328 | -55.2197 | | | |
| 11.214 | 1781.797 | 808.198 | -4.83887 | -55.4492 | | | |
| 11.214 | 1781.372 | 808.232 | -4.86816 | -55.1465 | | | |
| 11.214 | 1781.387 | 807.881 | -4.84863 | -55.2441 | | | |
| 9.21 | 1417.783 | 660.776 | -9.76074 | -58.0664 | | | |
| 9.21 | 1417.612 | 660.786 | -9.75586 | -58.1006 | | | |
| 9.21 | 1417.598 | 661.035 | -9.76074 | -57.8076 | | | |
| 9.21 | 1417.222 | 660.923 | -9.75586 | -57.915 | | | |
| 9.21 | 1417.71 | 661.079 | -9.75586 | -57.7539 | | | |
| 7.207 | 1104.609 | 535.303 | -14.6338 | -58.6523 | | | |
| 7.207 | 1104.224 | 535.19 | -14.6289 | -59.0332 | | | |
| 7.207 | 1104.575 | 535.156 | -14.6338 | -58.9844 | | | |
| 7.207 | 1104.814 | 535.049 | -14.6338 | -59.1357 | | | |
| 7.207 | 1104.546 | 534.907 | -14.6338 | -58.9063 | | | |
| 5.2 | 789.707 | 412.212 | -19.5117 | -61.9824 | | | |
| 5.2 | 789.0137 | 412.261 | -19.5068 | -61.2646 | | | |
| 5.2 | 789.1992 | 411.939 | -19.502 | -60.8398 | | | |
| 5.2 | 788.7402 | 411.856 | -19.5117 | -60.957 | | | |
| 5.2 | 788.9209 | 411.89 | -19.5117 | -61.0938 | | | |
| 3.204 | 467.3535 | 284.063 | -24.2969 | -63.4375 | | | |
| 3.204 | 467.5195 | 284.082 | -24.3457 | -63.6035 | | | |
| 3.204 | 467.7539 | 283.97 | -24.3506 | -63.8281 | | | |
| 3.204 | 467.5244 | 283.96 | -24.3066 | -63.7402 | | | |
| 3.204 | 467.6611 | 284.053 | -24.3262 | -63.4717 | | | |
| 0 | 0.239258 | 89.3701 | -29.502 | -66.958 | | | |
| 0 | 0.249023 | 89.3701 | -29.5166 | -66.7383 | | | |

| | | | | | | | |
|-----------|--------------|----------------|----------|-----------|--------------|----------------|--|
| 0 | 0.297852 | 89.2773 | -29.4629 | -66.7188 | | | |
| 0 | 0.288086 | 89.0283 | -29.4775 | -66.6553 | | | |
| | | | | | | | |
| | Coefficients | Standard Error | | | Coefficients | Standard Error | |
| Eaa | | | | Ean | | | |
| Intercept | -16.1475 | 6.721237 | | Intercept | -28.4967 | 0.297724 | |
| x1 | 160.9926 | 0.423445 | | x1 | 2.081286 | 0.018757 | |
| Eba | | | | Ebn | | | |
| Intercept | 87.55774 | 2.567009 | | Intercept | -65.1267 | 0.224842 | |
| x1 | 64.49639 | 0.161724 | | x1 | 0.782588 | 0.014165 | |

TABLE B4: NORMAL LOADING, H=10.5625"

| Normal Load | h=10.5625" | | | |
|-------------|------------|----------|----------|----------|
| Weight | Eaa | Eba | Ean | Ebn |
| 0 | 3.989258 | 15.6396 | -20.3516 | -60.7324 |
| 0 | 3.999023 | 15.7959 | -20.1074 | -60.8789 |
| 0 | 4.013672 | 15.6885 | -20.0537 | -60.9912 |
| 0 | 4.047852 | 15.7861 | -20.4053 | -60.874 |
| 3.204 | -4.838867 | 8.84277 | 449.2139 | 304.448 |
| 3.204 | -4.84375 | 8.76465 | 448.6865 | 304.058 |
| 3.204 | -4.824219 | 8.92578 | 448.584 | 303.252 |
| 3.204 | -4.775391 | 9.0332 | 448.2031 | 303.657 |
| 5.2 | -9.746094 | 2.12891 | 821.2402 | 595.298 |
| 5.2 | -9.755859 | 2.02637 | 820.5811 | 594.102 |
| 5.2 | -9.750977 | 1.95801 | 819.6973 | 592.852 |
| 5.2 | -9.755859 | 1.91406 | 820.0244 | 592.48 |
| 7.207 | -14.63867 | -5.01465 | 1171.353 | 872.725 |
| 7.207 | -14.63379 | -5.04395 | 1170.376 | 872.964 |
| 7.207 | -14.63379 | -5.01953 | 1170.449 | 872.173 |
| 7.207 | -14.62891 | -4.99512 | 1170.103 | 872.427 |
| 9.21 | -17.41699 | -9.75098 | 1374.307 | 1034.95 |
| 9.21 | -17.36328 | -9.76074 | 1372.822 | 1034.11 |
| 9.21 | -17.05078 | -9.76563 | 1372.085 | 1032.98 |
| 9.21 | -16.98242 | -9.75586 | 1371.602 | 1032.34 |
| 11.214 | -20.34668 | -17.9932 | 1681.011 | 1279.93 |
| 11.214 | -20.5957 | -18.2324 | 1679.419 | 1278.71 |
| 11.214 | -20.10742 | -18.5986 | 1678.301 | 1277.64 |
| 11.214 | -20.17578 | -18.2666 | 1677.588 | 1277.45 |
| 13.219 | -26.00098 | -29.1797 | 2065.234 | 1586.89 |
| 13.219 | -26.05469 | -29.1504 | 2063.335 | 1585.41 |
| 13.219 | -25.80078 | -29.1797 | 2062.051 | 1583.7 |
| 13.219 | -25.80078 | -29.2041 | 2061.504 | 1582.7 |
| 15.223 | -29.3457 | -38.7305 | 2348.95 | 1812.68 |
| 15.223 | -29.30176 | -38.75 | 2346.792 | 1809.56 |
| 15.223 | -29.32129 | -38.7646 | 2345.41 | 1808.79 |
| 15.223 | -29.28711 | -38.6621 | 2344.268 | 1807.29 |
| 20.233 | -41.21094 | -68.1592 | 3180.684 | 2473.45 |
| 20.233 | -41.2793 | -68.0713 | 3177.988 | 2472.06 |
| 20.233 | -41.17676 | -67.9053 | 3176.665 | 2470.24 |
| 20.233 | -40.93262 | -67.8125 | 3175.371 | 2468.45 |
| 25.239 | -51.43555 | -104.067 | 3910.342 | 3048.33 |
| 25.239 | -51.40137 | -103.989 | 3908.721 | 3046.62 |
| 25.239 | -51.3916 | -104.048 | 3907.48 | 3045.91 |
| 25.239 | -51.31348 | -103.613 | 3906.055 | 3045.21 |
| 30.236 | -62.54395 | -160.654 | 4756.338 | 3719.79 |

| | | | | | | |
|--------|-----------|----------|----------|---------|--|--|
| 30.236 | -62.41699 | -160.156 | 4750.869 | 3715.83 | | |
| 35.242 | -72.7002 | -217.705 | 5545.967 | 4345.74 | | |
| 35.242 | -72.47559 | -217.539 | 5542.134 | 4342.15 | | |
| 35.242 | -72.55371 | -217.363 | 5539.98 | 4340.64 | | |
| 35.242 | -72.55859 | -217.148 | 5537.798 | 4338.61 | | |
| 30.236 | -63.44238 | -149.243 | 4726.23 | 3696.58 | | |
| 30.236 | -63.26172 | -149.106 | 4725.132 | 3695.79 | | |
| 30.236 | -63.37402 | -148.984 | 4724.385 | 3694.03 | | |
| 30.236 | -63.51074 | -149.058 | 4723.95 | 3693.08 | | |
| 20.233 | -41.7334 | -35.835 | 3115.352 | 2423.75 | | |
| 20.233 | -41.8457 | -35.7861 | 3115.063 | 2423.43 | | |
| 20.233 | -41.66504 | -36.0449 | 3114.966 | 2423.02 | | |
| 20.233 | -41.7334 | -35.9326 | 3114.673 | 2422.66 | | |
| 15.223 | -29.39941 | 0.35156 | 2331.982 | 1800.67 | | |
| 15.223 | -29.38477 | 0.42481 | 2331.67 | 1800.88 | | |
| 15.223 | -29.29688 | 0.34668 | 2331.753 | 1800.75 | | |
| 15.223 | -29.33106 | 0.37598 | 2331.514 | 1800.19 | | |
| 15.223 | -29.32617 | 0.41992 | 2331.108 | 1800.43 | | |
| 13.219 | -25.3418 | 12.6709 | 2026.416 | 1558.69 | | |
| 13.219 | -25.27344 | 12.6367 | 2025.869 | 1558.02 | | |
| 13.219 | -25.1709 | 12.5146 | 2025.884 | 1557.72 | | |
| 13.219 | -25.23926 | 12.6172 | 2025.742 | 1557.58 | | |
| 11.214 | -22.26563 | 24.0039 | 1708.247 | 1304.63 | | |
| 11.214 | -21.95801 | 23.8281 | 1708.125 | 1304.39 | | |
| 11.214 | -22.12891 | 23.999 | 1708.237 | 1304.16 | | |
| 11.214 | -22.59766 | 23.9844 | 1708.081 | 1303.62 | | |
| 11.214 | -22.37305 | 24.0479 | 1707.988 | 1304.06 | | |
| 9.21 | -18.22266 | 34.8828 | 1390.962 | 1052.37 | | |
| 9.21 | -18.51074 | 34.7217 | 1390.2 | 1052.24 | | |
| 9.21 | -18.29102 | 34.8633 | 1389.932 | 1052.29 | | |
| 9.21 | -18.03711 | 34.8096 | 1390.2 | 1052.22 | | |
| 9.21 | -18.39844 | 34.624 | 1389.961 | 1051.39 | | |
| 7.207 | -13.29102 | 45.5078 | 1070.371 | 797.769 | | |
| 7.207 | -12.97363 | 45.2734 | 1070.215 | 797.666 | | |
| 7.207 | -12.81738 | 45.4639 | 1069.868 | 797.334 | | |
| 7.207 | -13.35449 | 45.5469 | 1069.663 | 796.685 | | |
| 7.207 | -13.31055 | 45.5811 | 1069.478 | 797.026 | | |
| 5.2 | -9.370117 | 55.5615 | 742.8223 | 537.91 | | |
| 5.2 | -9.345703 | 55.5127 | 742.4316 | 537.144 | | |

| | | | | | | | |
|-----------|--------------|----------|----------------|-----------|--------------|----------|----------------|
| | Coefficients | | Standard Error | | Coefficients | | Standard Error |
| Eaa | | | | Ean | | | |
| Intercept | 2.564045 | 0.161644 | | Intercept | -45.7403 | 5.413727 | |
| x1 | -2.15315 | 0.009956 | | x1 | 157.7453 | 0.333457 | |
| Eba | | | | Ebn | | | |
| Intercept | 72.54808 | 4.799721 | | Intercept | -85.4048 | 4.320142 | |
| x1 | -7.1007 | 0.295637 | | x1 | 124.9899 | 0.266098 | |

APPENDIX C: EXPERIMENTAL CORRECTIONS

Wind tunnel boundary corrections to the dynamic pressure and velocity were made for "solid blockage" only. Solid blockage affects the flowfield velocity through the test section. It is a function of model thickness and size. The model's cross-sectional area effectively reduces the area in the test section through the flow must pass. [Refs 14 & 15] The equations used were :

$$q = q_m (1 + 2*\epsilon)$$

$$U = U (1+ \epsilon)$$

$$\epsilon = (\text{Model cross-section/Tunnel cross-section})*\text{SIN}(\alpha) + (\text{Canard cross-section/Tunnel cross-section})*\text{SIN}(\alpha + \delta_{\text{canard}})$$

Where:

- q - Dynamic Pressure (lbf/ft²)
- q_m - Measured Dynamic Pressure (lbf/ft²)
- U - Velocity (ft/sec)
- U_m - Measured Velocity (ft/sec)
- ε - Blockage Factor
- α - Model Angle-of-Attack
- δ_{canard} - Canard Deflection Angle

Signal drift was measured after each tunnel run. The wind-tunnel was secured and the airspeed allowed to decay to zero. Voltage readings were taken and the corresponding zero-load lift and drag values were then subtracted from all readings taken during the run. As described in Chapter IV, the system signal drift was assumed to be a hysteresis effect of loading the strain-gage balance. All data readings were corrected for this drift.

Though wall effects may be significant for this model at high-lift conditions, absolute values for a complete trimmed aircraft configuration were not being sought. A comparison of the static-canard with the oscillating-canard effects was the desired goal. No wall corrections were made for this test.

APPENDIX D: DATA ACQUISITION CODE

' This program was written and compiled using LabWindows and QuickBasic
' 4.5. (used "bc /o multi" to compile) Its purpose was to read and convert
' voltages from four channels connected to the strain gauges on the Academic
' wind tunnel. The voltages are converted to normal and axial forces and moments
' with respect to the balance. It was written and modified by LT Tom D. Stuart and
' LT Dean C. Schmidt, 20 June 92.

' Variables explained

' eaa = Strain gauge voltage at point A in Axial direction.
' eba = Strain gauge voltage at point B in Axial direction.
' ean = Strain gauge voltage at point A in Normal direction.
' ebn = Strain gauge voltage at point B in Normal direction.

' AX = Axial force
' Max = Axial moment
' NORM = Normal force
' Mnorm = Normal moment

' alpha = Angle of Attack of the model
' LIFT = Lift force
' DRAG = Drag force

.....
REM \$INCLUDE: 'C:\LWINCLUDE\LWSYSTEM.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\GPIB.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\FORMATIO.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\GRAPHICS.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\ANALYSIS.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\DATAACQ.INC'
REM \$INCLUDE: 'C:\LWINCLUDE\RS232.INC'

DIM K\$(4,4)
DIM ean.array\$(1000),eaa.array\$(1000),ebn.array\$(1000),eba.array\$(1000)
COMMON SHARED ean.array#(),eaa.array#(),ebn.array#(),eba.array#()

```
DECLARE SUB volt (ean#, eaa#, ebn#, eba#, alpha#)
DECLARE SUB aero (AX#, NORM#, LIFT#, DRAG#, alpha#)
DECLARE SUB forces
(K#(), eaa#, eba#, ean#, ebn#, AX#, Max#, NORM#, Mnorm#, alpha#)
```

```
SCREEN 9, 0
COLOR 15, 1
```

```
 eaa0# = 0
 eaa0# = 0
 ean0# = 0
 ebn0# = 0
```

```
*****
```

```
' CALIBRATION MATRIX INPUT (See thesis for explanation)
```

```
DATA 0.009198, -0.006908, 0.000171, -0.000300
DATA -0.035913, 0.259331, 0.002494, 0.007624
DATA -0.000418, 0.000835, 0.010422, -0.005071
DATA -0.001896, 0.004440, -0.022291, 0.116806
```

```
FOR L% = 1 TO 4: FOR M% = 1 TO 4
READ K%(L%,M%) : NEXT M%
NEXT L%
```

```
*****
```

```
LOCATE 10, 20: INPUT "Type the name of the voltage file"; VOL$
VOL$ = "C:\LWINSTR\" + VOL$ + ".DAT"
OPEN VOL$ FOR APPEND AS #1
```

```
CLS: LOCATE 10, 20: INPUT "Type the name of the FORCE / MOMENT file";
FM$
FM$ = "C:\LWINSTR\" + FM$ + ".DAT"
OPEN FM$ FOR APPEND AS #2
```

```
CLS: LOCATE 10, 20: INPUT "Type the name of the Lift / Drag file"; LD$
LD$ = "C:\LWINSTR\" + LD$ + ".DAT"
OPEN LD$ FOR APPEND AS #3
```

CLS: LOCATE 10, 20: INPUT "Input the Test AOA (deg.)"; alpha#

500

CLS: LOCATE 5, 20: INPUT "Is this a tare (zero load) reading? (Y/N)"; A\$

IF A\$ = "Y" THEN CALL tare (ean0#, eaa0#, ebn0#, eba0#, alpha#)

LOCATE 23, 15: INPUT "Ready to take readings? (Y/N)"; B\$

IF B\$ = "Y" THEN CALL volt (ean#, eaa#, ebn#, eba#, alpha#)

IF B\$ <> "Y" THEN GOTO 5000

' Correcting for zero load values.

eaa# = eaa# - eaa0#

eba# = eba# - eba0#

ean# = ean# - ean0#

ebn# = ebn# - ebn0#

CALL forces (K#(), eaa#, eba#, ean#, ebn#, AX#, Max#, NORM#, Mnorm#, alpha#)

CALL aero (AX#, NORM#, LIFT#, DRAG#, alpha#)

PRINT " "

PRINT " AOA EAA (mV) EBA (mV) EAN (mV) EBN
(mV)"

PRINT " ***** ***** ***** ***** *****"

PRINT USING " ####.#####"; alpha#, eaa#, eba#, ean#, ebn#

PRINT #1, USING "#####.#####"; alpha#, eaa#, eba#, ean#, ebn#

PRINT " "

PRINT " AXIAL (lb) MOMax (ft-lb) NORMAL (lb) MOMnorm(ft-lb)"

PRINT " ***** ***** ***** *****"

PRINT USING " ####.#####"; AX#, Max#, NORM#, Mnorm#

PRINT #2, USING "#####.#####"; AX#, Max#, NORM#, Mnorm#

PRINT " "

PRINT " Lift (lb) Drag (lb)"

PRINT " ***** *****"

```
PRINT USING "   ####.#####"; LIFT#; DRAG#
PRINT #3, USING "#####.#####"; LIFT#; DRAG#
```

```
LOCATE 23, 15: INPUT "Do you want another reading? (Y/N)"; ANS$
IF ANS$ = "Y" THEN GOTO 500
```

```
5000 CLOSE #1
CLOSE #2
CLOSE #3
```

```
END
```

```
*****
```

```
*****
```

```
SUB volt (ean#, eaa#, ebn#, eba#, alpha#)
```

```
*****
```

```
,
```

```
' S/R to read Channel 0,2,4,6 on MIO-16L-9 for Analog Voltage
```

```
,
```

```
*****
```

```
' Setting Board code for MIO-16L-9
```

```
board.code%=0
```

```
*****
```

```
err1.num% = Init.DA.Brds(1, board.code%)
```

```
err2.num% = AI.Setup(1, 0, 1)
```

```
err3.num% = AI.Setup(1, 2, 1)
```

```
err4.num% = AI.Setup(1, 4, 1)
```

```
err5.num% = AI.Setup(1, 6, 1)
```

```
' Configure and set clock to 1MHZ
```

```
err6.num% = CTR.Clock (1, 1, 1, 1)
```

```
err7.num% = CTR.Config (1, 1, 0, 0, 0, 0)
```

```
LWtotal! = 0
```



```

FOR i% = 1 TO 1000

err8.num% = CTR.EvCount (1, 1, 1, 0)

' CH 0 = Eaa
  err9.num% = Al.Read(1, 0, 1, value0%)
  err10.num% = Al.Scale(1, 1, value0%, eaa.array#(i%))

' CH 2 = Eba
  er11.num% = Al.Read(1, 2, 1, value2%)
  er12.num% = Al.Scale(1, 1, value2%, eba.array#(i%))

' CH 4 = Ean
  er13.num% = Al.Read(1, 4, 1, value4%)
  er14.num% = Al.Scale(1, 1, value4%, ean.array#(i%))

' CH 6 = Ebn
  er15.num% = Al.Read(1, 6, 1, value6%)
  er16.num% = Al.Scale(1, 1, value6%, ebn.array#(i%))

er17.num% = CTR.EvRead (1, 1, overflo%, tcount%)

LWtotal! = LWtotal! + tcount%

NEXT i%

CLS:LOCATE 5,15:PRINT "Total Time is " LWtotal!*1E-6" seconds."

CALL Mean (eaa.array#(), 1000, eaa#)
CALL Mean (eba.array#(), 1000, eba#)
CALL Mean (ean.array#(), 1000, ean#)
CALL Mean (ebn.array#(), 1000, ebn#)

```

.....

' This multiplication (*1000) will make the voltages in mV

```

eaa#=eaa#*1000
eba#=eba#*1000
ean#=ean#*1000

```

ebn#=ebn#*1000

END SUB

SUB forces (K#(),eaa#,eba#,ean#,ebn#,AX#,Max#,NORM#,Mnorm#,alpha#)

' FORCES AND MOMENTS CALCULATIONS (See thesis for explanation)

AX# = K#(1,1)*eaa# + K#(1,2)*eba# + K#(1,3)*ean# + K#(1,4)*ebn#
Max# = K#(2,1)*eaa# + K#(2,2)*eba# + K#(2,3)*ean# + K#(2,4)*ebn#
NORM# = K#(3,1)*eaa# + K#(3,2)*eba# + K#(3,3)*ean# + K#(3,4)*ebn#
Mnorm# = K#(4,1)*eaa# + K#(4,2)*eba# + K#(4,3)*ean# + K#(4,4)*ebn#

END SUB

SUB aero (AX#,NORM#,LIFT#,DRAG#,alpha#)

PI# = 3.141593

LIFT# = NORM# * COS(PI#/180*alpha#) - AX# * SIN(PI#/180*alpha#)

DRAG# = NORM# * SIN(PI#/180*alpha#) + AX# * COS(PI#/180*alpha#)

END SUB

SUB tare (ean#,eaa#,ebn#,eba#,alpha#)

' S/R to read Channel 0,2,4,6 on MC-MIO-16L-9 for Analog Voltage

```

'
*****

' Setting Board code for MC-MIO-16L-9

board.code%=0

*****

CLS: LOCATE 5, 20: INPUT "Ready to take tare readings? (Y/N)"; T$
IF T$ <> "Y" THEN RETURN

err1.num% = Init.DA.Brds(1, board.code%)

err2.num% = AI.Setup(1, 0, 1)
err3.num% = AI.Setup(1, 2, 1)
err4.num% = AI.Setup(1, 4, 1)
err5.num% = AI.Setup(1, 6, 1)

' Configure and set clock to 1MHZ

err6.num% = CTR.Clock (1, 1, 1, 1)
err7.num% = CTR.Config (1, 1, 0, 0, 0, 0)

LWtotal! = 0

FOR i% = 1 TO 1000

err8.num% = CTR.EvCount (1, 1, 1, 0)

' CH 0 = Eaa
err9.num% = AI.Read(1, 0, 1, value0%)
err10.num% = AI.Scale(1, 1, value0%, eaa.array#(i%))

' CH 2 = Eba
err11.num% = AI.Read(1, 2, 1, value2%)
err12.num% = AI.Scale(1, 1, value2%, eba.array#(i%))

' CH 4 = Ean
err13.num% = AI.Read(1, 4, 1, value4%)

```

```

er14.num% = Al.Scale(1, 1, value4%, ean.array#(i%))

' CH 6 = Ebn
  er15.num% = Al.Read(1, 6, 1, value6%)
  er16.num% = Al.Scale(1, 1, value6%, ebn.array#(i%))

er17.num% = CTR.EvRead (1, 1, overflo%, tcount%)

LWtotal! = LWtotal! + tcount%

NEXT i%

CLS:LOCATE 5,15:PRINT "Total Time is " LWtotal!*1E-6" seconds."

CALL Mean (eaa.array#(), 1000, eaa#)
CALL Mean (eba.array#(), 1000, eba#)
CALL Mean (ean.array#(), 1000, ean#)
CALL Mean (ebn.array#(), 1000, ebn#)

*****

' This multiplication (*1000) will make the voltages in mV

eaa#=eaa#*1000
eba#=eba#*1000
ean#=ean#*1000
ebn#=ebn#*1000

PRINT " "
PRINT "      AOA      EAA (mV)      EBA (mV)      EAN (mV)      EBN
(mV)"
PRINT "      *****      *****      *****      *****      *****"

PRINT USING "   ###.#####"; alpha#, eaa#, eba#, ean#, ebn#
PRINT #1, USING "#####.#####"; alpha#, eaa#, eba#, ean#, ebn#

END SUB

```

APPENDIX E: WIND TUNNEL DATA

| | | | | | | |
|--------------------------|------------|------------|------------|------------|------------|------------|
| Alpha= | 22 | | | | | |
| deltac= | 4 | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01116328 | | | | | |
| Epsilon body+canard= | 0.01284224 | | | | | |
| q (lb/ft ²)= | 27.3316484 | | | | | |
| S (ft ²) | 0.815 | | | | | |
| V (ft/s)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04645424 | 0.09290848 | 0.13936272 | 0.18581695 | 0.23227119 |
| | | | | | | |
| LIFT | | | | | | |
| Mean | 27.9649726 | 26.634203 | 26.696337 | 26.488675 | 26.382005 | 26.060466 |
| Std. Dev. | 0.20225274 | 0.12263605 | 0.19785138 | 0.19474272 | 0.20292163 | 0.20150568 |
| 1.96*Std. Dev. | 0.39641537 | 0.24036666 | 0.3877887 | 0.38169574 | 0.3977264 | 0.39495114 |
| High 95% | 28.361388 | 26.8745697 | 27.0841257 | 26.8703707 | 26.7797314 | 26.4554171 |
| Low 95% | 27.5685573 | 26.3938363 | 26.3085483 | 26.1069793 | 25.9842786 | 25.6655149 |
| Mean CL | 1.22398806 | 1.16574212 | 1.16846164 | 1.15937256 | 1.15470377 | 1.14063045 |
| 1.96*CL Std. Dev. | 0.00885232 | 0.00536761 | 0.00865968 | 0.00852362 | 0.0088816 | 0.00881962 |
| | | | | | | |
| | | | | | | |
| DRAG | | | | | | |
| Mean | 10.5168105 | 10.324636 | 10.269471 | 10.164157 | 10.128822 | 10.006858 |
| Standard Deviation | 0.06405469 | 0.03671978 | 0.09930364 | 0.09534789 | 0.12415457 | 0.0273695 |
| 1.96*Std. Dev. | 0.12554719 | 0.07197077 | 0.19463514 | 0.18688186 | 0.24334296 | 0.002575 |
| High 95% | 10.6423577 | 10.3966068 | 10.4641061 | 10.3510389 | 10.372165 | 0.08654996 |
| Low 95% | 10.3912633 | 10.2526652 | 10.0748359 | 9.97727514 | 9.88547904 | 0.16963791 |
| Mean CD | 0.46030621 | 0.451895 | 0.4494805 | 0.44487105 | 0.44332449 | 0.43798629 |
| 1.96*CD Std. Dev. | 0.00280358 | 0.00160717 | 0.00434638 | 0.00417324 | 0.00543407 | 0.00119793 |

| | | | | | | |
|----------------------|------------|------------|-------------|------------|------------|------------|
| Alpha= | 22 | | | | | |
| dellac= | 7 | | | | | |
| | | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01116328 | | | | | |
| Epsilon body+canard= | 0.0130201 | | | | | |
| q (lb/ft^2)= | 27.3316484 | | | | | |
| S (ft^2) | 0.815 | | | | | |
| V (ft/s)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04645424 | 0.092908477 | 0.13936272 | 0.18581695 | 0.23227119 |
| | | | | | | |
| | | | | | | |
| LIFT | | | | | | |
| Mean Lift | 29.072835 | 29.4887185 | 29.7760765 | 29.83038 | 29.8068965 | 29.5474925 |
| Standard Deviation | 0.17436905 | 0.48544586 | 0.138682505 | 0.34246597 | 0.42561418 | 0.44659816 |
| 1.96 Std. Dev. | 0.34176334 | 0.95147388 | 0.271817709 | 0.6712333 | 0.8342038 | 0.8753324 |
| High 95% | 29.4145983 | 30.4401924 | 30.04789421 | 30.5016133 | 30.6411003 | 30.4228249 |
| Low 95% | 28.7310717 | 28.5372446 | 29.50425879 | 29.1591467 | 28.9726927 | 28.6721601 |
| Mean CL | 1.27203651 | 1.29023284 | 1.30280574 | 1.3051817 | 1.30415422 | 1.2928044 |
| 1.96*CL Std. Dev. | 0.00762925 | 0.02123993 | 0.006067836 | 0.01498406 | 0.01862208 | 0.01954021 |
| | | | | | | |
| DRAG | | | | | | |
| Mean Drag | 10.989402 | 11.061629 | 11.083714 | 11.059518 | 10.982303 | 10.916209 |
| Standard Deviation | 0.04131704 | 0.46697042 | 0.555855698 | 0.49225668 | 0.52967295 | 0.48248211 |
| 1.96* Std. Dev. | 0.08098139 | 0.91526202 | 1.089477169 | 0.96482309 | 1.03815899 | 0.94566493 |
| High 95% | 11.0703834 | 11.976891 | 12.17319117 | 12.0243411 | 12.020462 | 11.8618739 |
| Low 95% | 10.9084206 | 10.146367 | 9.994236831 | 10.0946949 | 9.94414401 | 9.97054407 |
| Mean CD | 0.48082413 | 0.48398431 | 0.484950602 | 0.48389194 | 0.48051352 | 0.47762168 |
| 1.96*CD Std. Dev. | 0.00180776 | 0.02043156 | 0.024320598 | 0.02153792 | 0.02317501 | 0.02111025 |

| | | | | | | |
|----------------------|------------|------------|------------|------------|------------|------------|
| Alpha= | 22 | | | | | |
| Deltac= | 10 | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01116328 | | | | | |
| Epsilon body+canard= | 0.01319287 | | | | | |
| q (lb/ft^2)= | 27.3316484 | | | | | |
| S (ft^2) | 0.815 | | | | | |
| V (ft/s^2)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04643853 | 0.09287706 | 0.13931559 | 0.18575411 | 0.23219264 |
| | | | | | | |
| LIFT | | | | | | |
| Mean Lift | 26.6439583 | 27.600294 | 28.1596091 | 28.1582487 | 28.3246653 | 28.2241233 |
| Standard Deviation | 0.17054131 | 0.38256539 | 0.21255614 | 0.16470014 | 0.30089305 | 0.21897795 |
| 1.96* Std. Dev. | 0.33426097 | 0.74982817 | 0.41661004 | 0.32281228 | 0.58975037 | 0.42919679 |
| High 95% | 26.9782193 | 28.3501222 | 28.5762191 | 28.4810609 | 28.9144157 | 28.6533201 |
| Low 95% | 26.3096974 | 26.8504658 | 27.7429999 | 27.8354364 | 27.734915 | 27.7949265 |
| Mean CL | 1.16537234 | 1.20720122 | 1.23166494 | 1.23160544 | 1.23888429 | 1.23448671 |
| 1.96*CL Std. Dev. | 0.01462014 | 0.03279652 | 0.01822199 | 0.01411939 | 0.02579492 | 0.01877251 |
| | | | | | | |
| DRAG | | | | | | |
| Mean Drag | 10.809935 | 11.050196 | 11.1340316 | 11.0934887 | 11.0961793 | 11.023988 |
| Standard Deviation | 0.04123263 | 0.18159774 | 0.22376169 | 0.23089359 | 0.2491573 | 0.21904721 |
| 1.96*Std. Dev. | 0.08081595 | 0.35593158 | 0.43857291 | 0.45255143 | 0.48834832 | 0.42933254 |
| High 95% | 10.8907509 | 11.4061276 | 11.5726045 | 11.5460401 | 11.5845277 | 11.4533205 |
| Low 95% | 10.7291191 | 10.6942644 | 10.6954587 | 10.6409372 | 10.607831 | 10.5946555 |
| Mean CD | 0.4728126 | 0.48332131 | 0.48698816 | 0.48521487 | 0.48533256 | 0.482175 |
| 1.96*CD Std. Dev. | 0.00353479 | 0.01556799 | 0.01918261 | 0.01979402 | 0.02135972 | 0.01877845 |

| | | | | | | |
|----------------------|------------|------------|------------|------------|------------|------------|
| Alpha= | 34 | | | | | |
| Dellac= | -4 | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01666395 | | | | | |
| Epsilon body+canard= | 0.01857895 | | | | | |
| q (lb/ft^2)= | 27.3316484 | | | | | |
| S (ft^2) | 0.815 | | | | | |
| V (ft/s2)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04645424 | 0.09290848 | 0.13936272 | 0.18581695 | 0.23227119 |
| | | | | | | |
| LIFT | | | | | | |
| Mean Lift | 34.1584067 | 35.255284 | 35.323959 | 35.321435 | 35.166783 | 35.25195 |
| Standard Deviation | 0.27649726 | 0.16722914 | 0.13661708 | 0.18493793 | 0.16266148 | 0.17581846 |
| 1.96*Std. Dev. | 0.54193462 | 0.32776911 | 0.26776947 | 0.36247834 | 0.31881651 | 0.34460418 |
| High 95% | 34.7003413 | 35.5830531 | 35.5917285 | 35.6839133 | 35.4855995 | 35.5965542 |
| Low 95% | 33.616472 | 34.9275149 | 35.0561895 | 34.9589567 | 34.8479665 | 34.9073458 |
| Mean CL | 1.47852711 | 1.52600482 | 1.52897738 | 1.52886813 | 1.5221741 | 1.52586051 |
| 1.96*CL Std. Dev. | 0.02345733 | 0.0141873 | 0.01159025 | 0.01568967 | 0.01379979 | 0.01491599 |
| | | | | | | |
| DRAG | | | | | | |
| Mean Drag | 20.9137483 | 21.3962375 | 21.3841785 | 21.3600625 | 21.2802595 | 21.3368925 |
| Standard Deviation | 0.16485173 | 0.07953415 | 0.05839094 | 0.08142902 | 0.07376121 | 0.06714689 |
| 1.96*Std. Dev. | 0.32310939 | 0.15588694 | 0.11444625 | 0.15960088 | 0.14457197 | 0.1316079 |
| High 95% | 21.2368577 | 21.5521244 | 21.4986247 | 21.5196634 | 21.4248315 | 21.4685004 |
| Low 95% | 20.5906389 | 21.2403506 | 21.2697323 | 21.2004616 | 21.1356875 | 21.2052846 |
| Mean CD | 0.90523964 | 0.92612391 | 0.92560195 | 0.9245581 | 0.92110387 | 0.9235552 |
| 1.96*CD Std. Dev. | 0.01398561 | 0.00674748 | 0.00495374 | 0.00690823 | 0.00625771 | 0.00569657 |

| | | | | | | |
|----------------------|------------|------------|------------|------------|------------|------------|
| Alpha= | 34 | | | | | |
| Deltac= | -7 | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01666395 | | | | | |
| Epsilon body+canard= | 0.01840273 | | | | | |
| q (lbf/ft^2)= | 27.3316484 | | | | | |
| S (ft^2) | 0.815 | | | | | |
| V (ft/s^2)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04645424 | 0.09290848 | 0.13936272 | 0.18581695 | 0.23227119 |
| | | | | | | |
| LIFT | | | | | | |
| Mean Lift | 34.9281845 | 34.3392823 | 34.4310765 | 34.3410235 | 34.4285855 | 34.4058575 |
| Standard Deviation | 0.21436019 | 0.22029783 | 0.16158673 | 0.10686481 | 0.14593063 | 0.14986457 |
| 1.96*Std. Dev. | 0.42014597 | 0.43178374 | 0.31670999 | 0.20945503 | 0.28602404 | 0.29373456 |
| High 95% | 35.3483305 | 34.7710666 | 34.7477865 | 34.5504785 | 34.7146095 | 34.6995921 |
| Low 95% | 34.5080385 | 33.9074986 | 34.1143665 | 34.1315685 | 34.1425615 | 34.1121229 |
| Mean CL | 1.51236041 | 1.48686145 | 1.49083606 | 1.48693685 | 1.49072821 | 1.4897441 |
| 1.96*CL Std. Dev. | 0.01819196 | 0.01869587 | 0.01371327 | 0.00906922 | 0.0123846 | 0.01271845 |
| | | | | | | |
| DRAG | | | | | | |
| Mean Drag | 21.0848035 | 20.7696615 | 20.7546585 | 20.6869115 | 20.7280485 | 20.7817165 |
| Standard Deviation | 0.11526178 | 0.12368821 | 0.10170331 | 0.05490734 | 0.06544965 | 0.06620331 |
| 1.96*Std. Dev. | 0.22591309 | 0.24242889 | 0.19933848 | 0.1076184 | 0.12828131 | 0.12975849 |
| High 95% | 21.3107166 | 21.0120904 | 20.953997 | 20.7945299 | 20.8563298 | 20.911475 |
| Low 95% | 20.8588905 | 20.5272327 | 20.55532 | 20.5792931 | 20.5997672 | 20.651958 |
| Mean CD | 0.9129539 | 0.89930852 | 0.8986589 | 0.89572551 | 0.89750671 | 0.89983049 |
| 1.96*CD Std. Dev. | 0.00978184 | 0.01049696 | 0.00863119 | 0.00465978 | 0.00555447 | 0.00561843 |

| | | | | | | |
|----------------------|------------|------------|------------|------------|------------|------------|
| Alpha= | 34 | | | | | |
| Deltac= | -10 | | | | | |
| DeltaP (cm H2O)= | 12 | | | | | |
| Epsilon body= | 0.01666395 | | | | | |
| Epsilon body+canard= | 0.01822175 | | | | | |
| q (lb/ft^2)= | 27.3316484 | | | | | |
| S (ft^2) | 0.815 | | | | | |
| V (ft/s^2)= | 151.650014 | | | | | |
| Re= | 7.69E+05 | | | | | |
| | | | | | | |
| | | | | | | |
| Hz | 0 | 5 | 10 | 15 | 20 | 25 |
| k= | 0 | 0.04645424 | 0.09290848 | 0.13936272 | 0.18581695 | 0.23227119 |
| | | | | | | |
| LIFT | | | | | | |
| Mean Lift | 34.657363 | 32.6935073 | 32.5251765 | 32.3101165 | 32.1713068 | 32.7273225 |
| Standard Deviation | 0.18474608 | 0.29195573 | 0.13795774 | 0.16674074 | 0.11750209 | 0.51619205 |
| 1.96*Std. Dev. | 0.36210232 | 0.57223323 | 0.27039717 | 0.32681185 | 0.23030409 | 1.01173642 |
| High 95% | 35.0194653 | 33.2657405 | 32.7955737 | 32.6369284 | 32.4016109 | 33.7390589 |
| Low 95% | 34.2952607 | 32.121274 | 32.2547793 | 31.9833046 | 31.9410027 | 31.7155861 |
| Mean CL | 1.50115815 | 1.41609519 | 1.40880406 | 1.3994889 | 1.39347646 | 1.41755987 |
| 1.96*CL Std. Dev. | 0.0156842 | 0.02478586 | 0.01171205 | 0.01415561 | 0.00997545 | 0.04382262 |
| | | | | | | |
| DRAG | | | | | | |
| Mean Drag | 20.5163945 | 19.0849359 | 18.97399 | 18.83677 | 18.7576423 | 19.216226 |
| Standard Deviation | 0.10018967 | 0.15470655 | 0.06094193 | 0.08007228 | 0.06362604 | 0.41955322 |
| 1.96*Std. Dev. | 0.19637175 | 0.30322485 | 0.11944618 | 0.15694167 | 0.12470703 | 0.82232432 |
| High 95% | 20.7127662 | 19.3881608 | 19.0934362 | 18.9937117 | 18.8823493 | 20.0385503 |
| Low 95% | 20.3200228 | 18.7817111 | 18.8545438 | 18.6798283 | 18.6329352 | 18.3939017 |
| Mean CD | 0.88865252 | 0.82664994 | 0.8218444 | 0.81590082 | 0.81247346 | 0.83233668 |
| 1.96*CD Std. Dev. | 0.0085057 | 0.01313396 | 0.00517372 | 0.00679781 | 0.00540159 | 0.03561837 |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|---------|---------|----------|----------|
| 18_7a | | | | | | | | | | |
| 22 | 4 | 0 | -0 0004 | -0 00266 | -0 00137 | 0 00232 | 2 12714 | 0 65282 | | |
| 22 | 4 | 5 | 30 8934 | 0 57129 | 28 85788 | 11 04318 | | | 26 73074 | 10 39036 |
| 22 | 4 | 5 | 30 72504 | 0 5729 | 28 70238 | 10 97862 | | | 26 57524 | 10 3258 |
| 22 | 4 | 5 | 30 6268 | 0 5581 | 28 60575 | 10 95554 | | | 26 47861 | 10 30272 |
| 22 | 4 | 5 | 30 6751 | 0 55772 | 28 65038 | 10 97399 | | | 26 52324 | 10 32117 |
| 22 | 4 | 5 | 30 6912 | 0 58026 | 28 67375 | 10 95911 | | | 26 54661 | 10 30629 |
| 22 | 4 | 10 | 31 11129 | 0 64319 | 29 08683 | 11 05814 | | | 26 95969 | 10 40532 |
| 22 | 4 | 10 | 30 82153 | 0 63944 | 28 81676 | 10 95307 | | | 26 68962 | 10 30025 |
| 22 | 4 | 10 | 31 07847 | 0 66481 | 29 0645 | 11 0258 | | | 26 93736 | 10 37298 |
| 22 | 4 | 10 | 30 89822 | 0 63316 | 28 88552 | 10 98762 | | | 26 75838 | 10 3348 |
| 22 | 4 | 10 | 31 08931 | 0 66161 | 29 07335 | 11 03283 | | | 26 94621 | 10 38001 |
| 22 | 4 | 15 | 30 81608 | 0 67392 | 28 82463 | 10 91906 | | | 26 69749 | 10 26624 |
| 22 | 4 | 15 | 30 82892 | 0 68327 | 28 84004 | 10 9152 | | | 26 7129 | 10 26238 |
| 22 | 4 | 15 | 30 70886 | 0 66342 | 28 72128 | 10 88863 | | | 26 59414 | 10 23581 |
| 22 | 4 | 15 | 30 66375 | 0 65564 | 28 67654 | 10 87894 | | | 26 5494 | 10 22612 |
| 22 | 4 | 15 | 30 74675 | 0 65825 | 28 75448 | 10 90762 | | | 26 62734 | 10 2548 |
| 22 | 4 | 20 | 30 77101 | 0 64179 | 28 7708 | 10 93197 | | | 26 64366 | 10 27915 |
| 22 | 4 | 20 | 30 67964 | 0 64899 | 28 68878 | 10 89106 | | | 26 56164 | 10 23824 |
| 22 | 4 | 20 | 30 79199 | 0 66727 | 28 7998 | 10 9162 | | | 26 67266 | 10 26338 |
| 22 | 4 | 20 | 30 50452 | 0 61326 | 28 51303 | 10 85859 | | | 26 38589 | 10 20577 |
| 22 | 4 | 20 | 30 61783 | 0 62731 | 28 62335 | 10 88801 | | | 26 49621 | 10 23519 |
| 22 | 4 | 25 | 30 45834 | 0 69268 | 28 49996 | 10 76765 | | | 26 37282 | 10 11483 |
| 22 | 4 | 25 | 30 4239 | 0 66037 | 28 45593 | 10 78471 | | | 26 32879 | 10 13189 |
| 22 | 4 | 25 | 30 27619 | 0 67288 | 28 32366 | 10 71778 | | | 26 19652 | 10 06496 |
| 22 | 4 | 25 | 30 24848 | 0 66854 | 28 29635 | 10 71142 | | | 26 16921 | 10 0586 |
| 22 | 4 | 25 | 30 1811 | 0 64727 | 28 2259 | 10 7059 | | | 26 09876 | 10 05308 |
| 22 | 4 | 0 | 2 24596 | 0 2116 | 2 16168 | 0 64516 | | | | |
| 22 | 4 | 0 | 2 18764 | 0 17151 | 2 0926 | 0 66048 | | | | |
| 18_7b | | | | | | | | | | |
| 22 | 4 | 0 | 0 00356 | 0 00895 | 0 00665 | -0 00696 | 1 75124 | 0 20049 | | |
| 22 | 4 | 5 | 31 60487 | 1 07245 | 29 70527 | 10 84503 | | | 27 95403 | 10 64454 |
| 22 | 4 | 5 | 31 57332 | 1 05455 | 29 66931 | 10 84981 | | | 27 91807 | 10 64932 |
| 22 | 4 | 5 | 31 44743 | 1 03871 | 29 54666 | 10 81734 | | | 27 79542 | 10 61685 |
| 22 | 4 | 5 | 31 66408 | 1 06643 | 29 57592 | 10 87279 | | | 28 00668 | 10 6723 |
| 22 | 4 | 5 | 31 59037 | 1 06055 | 29 68737 | 10 85063 | | | 27 93613 | 10 65014 |
| 22 | 4 | 10 | 31 10655 | 1 11469 | 29 25907 | 10 61919 | | | 27 50783 | 10 4187 |
| 22 | 4 | 10 | 31 14534 | 1 12131 | 29 2975 | 10 62759 | | | 27 54626 | 10 4271 |
| 22 | 4 | 10 | 31 26848 | 1 12196 | 29 41192 | 10 67312 | | | 27 66068 | 10 47263 |
| 22 | 4 | 10 | 31 20717 | 1 11853 | 29 35379 | 10 65333 | | | 27 60255 | 10 45284 |
| 22 | 4 | 10 | 31 12222 | 1 12039 | 29 27572 | 10 61978 | | | 27 52448 | 10 41929 |
| 22 | 4 | 15 | 30 93429 | 1 14065 | 29 10907 | 10 53059 | | | 27 35783 | 10 3301 |
| 22 | 4 | 15 | 30 86193 | 1 14563 | 29 04384 | 10 49887 | | | 27 2926 | 10 29838 |

| | | | | | | | | | | |
|-------|---|----|----------|---------|----------|----------|---------|---------|----------|----------|
| 22 | 4 | 20 | 30 73065 | 1.13913 | 28 91969 | 10 45572 | | | 27.16845 | 10 25523 |
| 22 | 4 | 20 | 30 89981 | 1.17741 | 29 09087 | 10 48359 | | | 27.33963 | 10 2831 |
| 22 | 4 | 20 | 30 75962 | 1.15808 | 28 95365 | 10 449 | | | 27.20241 | 10 24851 |
| 22 | 4 | 20 | 30 84409 | 1.16079 | 29 03298 | 10 47813 | | | 27.28174 | 10 27764 |
| 22 | 4 | 25 | 30 61381 | 1.14735 | 28 81444 | 10 40434 | | | 27.0632 | 10 20385 |
| 22 | 4 | 25 | 30 57054 | 1.1489 | 28 77489 | 10 38669 | | | 27.02365 | 10 1862 |
| 22 | 4 | 25 | 30 60389 | 1.14837 | 28 80562 | 10 39967 | | | 27.05438 | 10 19918 |
| 22 | 4 | 25 | 30 39866 | 1.11887 | 28 60428 | 10 35014 | | | 26 85304 | 10 14965 |
| 22 | 4 | 25 | 30 37517 | 1.14022 | 28 5905 | 10 32155 | | | 26 83926 | 10 12106 |
| 22 | 4 | 0 | 1.70479 | 0.47325 | 1.75794 | 0.19984 | | | | |
| 22 | 4 | 0 | 1.69286 | 0.46702 | 1.74454 | 0.20114 | | | | |
| 18_7c | | | | | | | | | | |
| 22 | 4 | 0 | -0.00731 | 0.00333 | -0.00553 | -0.00582 | 0.98391 | 0.31256 | | |
| 22 | 4 | 5 | 29 82355 | 0.52032 | 27 84683 | 10 68966 | | | 26 86292 | 10 3771 |
| 22 | 4 | 5 | 29 5677 | 0.52008 | 27 60952 | 10 59405 | | | 26 62561 | 10 28149 |
| 22 | 4 | 5 | 29 54302 | 0.49852 | 27 57856 | 10 60479 | | | 26 59465 | 10 29223 |
| 22 | 4 | 5 | 29 74525 | 0.51759 | 27 7732 | 10 66286 | | | 26 78929 | 10 3503 |
| 22 | 4 | 5 | 29 56449 | 0.5 | 27 59903 | 10 61146 | | | 26 61512 | 10 2989 |
| 22 | 4 | 10 | 29 34064 | 0.57582 | 27 41988 | 10 45731 | | | 26 43597 | 10 14475 |
| 22 | 4 | 10 | 29 49516 | 0.58851 | 27.56789 | 10.50343 | | | 26 58398 | 10 19087 |
| 22 | 4 | 10 | 29 37618 | 0.55989 | 27.44686 | 10.48539 | | | 26 46295 | 10 17283 |
| 22 | 4 | 10 | 29 54804 | 0.5884 | 27 61689 | 10 52334 | | | 26 63298 | 10 21078 |
| 22 | 4 | 10 | 29 46615 | 0.58622 | 27 54014 | 10 49468 | | | 26 55623 | 10 18212 |
| 22 | 4 | 15 | 29 2585 | 0.58675 | 27 3478 | 10 4164 | | | 26 36389 | 10 10384 |
| 22 | 4 | 15 | 28 99486 | 0.58473 | 27 10261 | 10 31951 | | | 26 1187 | 10 00695 |
| 22 | 4 | 15 | 29 33384 | 0.62467 | 27 43187 | 10 40947 | | | 26 44796 | 10 09691 |
| 22 | 4 | 15 | 29 41751 | 0.62794 | 27 51067 | 10 43778 | | | 26 52676 | 10 12522 |
| 22 | 4 | 15 | 29 13602 | 0.58098 | 27 23208 | 10 37586 | | | 26 24817 | 10 0633 |
| 22 | 4 | 20 | 29 15985 | 0.6179 | 27 26802 | 10 35057 | | | 26 28411 | 10 03801 |
| 22 | 4 | 20 | 29 09196 | 0.61412 | 27 20365 | 10 32864 | | | 26 21974 | 10 01608 |
| 22 | 4 | 20 | 29 15347 | 0.62679 | 27 26542 | 10 33993 | | | 26 28151 | 10 02737 |
| 22 | 4 | 20 | 29 06519 | 0.61331 | 27 17852 | 10 31936 | | | 26 19461 | 10 0068 |
| 22 | 4 | 20 | 28 94823 | 0.59687 | 27 06393 | 10 29079 | | | 26 08002 | 9 97823 |
| 22 | 4 | 25 | 28 75715 | 0.574 | 26 87819 | 10 24041 | | | 25 89428 | 9 92785 |
| 22 | 4 | 25 | 28 6414 | 0.56119 | 26 76607 | 10 20893 | | | 25 78216 | 9 89637 |
| 22 | 4 | 25 | 28 77493 | 0.57566 | 26 89529 | 10 24553 | | | 25 91138 | 9 93297 |
| 22 | 4 | 25 | 28 77813 | 0.57374 | 26 89755 | 10 24852 | | | 25 91364 | 9 93596 |
| 22 | 4 | 25 | 28 80592 | 0.56759 | 26 92101 | 10 26463 | | | 25 9371 | 9 95207 |
| 22 | 4 | 0 | 1.02482 | 0.06758 | 0.97552 | 0.32124 | | | | |
| 22 | 4 | 0 | 1.03388 | 0.08997 | 0.9923 | 0.30388 | | | | |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|---------|----------|----------|----------|----------|-----------|-----------|
| f8_5a | | | | | | | | | | |
| 22 | 7 | 0 | -0 00109 | 0 00395 | 0 00047 | -0 00408 | 0 285755 | 0 079915 | | |
| 22 | 7 | 5 | 31 49671 | 0 2453 | 29 29513 | 11 57143 | | | 29 009375 | 11 491515 |
| 22 | 7 | 5 | 31 44597 | 0 21917 | 29 2383 | 11 57665 | | | 28 952545 | 11 496735 |
| 22 | 7 | 5 | 31 49265 | 0 23083 | 29 28594 | 11 58333 | | | 29 000185 | 11 503415 |
| 22 | 7 | 5 | 31 58435 | 0 24435 | 29 37603 | 11 60515 | | | 29 090275 | 11 525235 |
| 22 | 7 | 5 | 31 60648 | 0 27864 | 29 4094 | 11 58165 | | | 29 123645 | 11 501735 |
| 22 | 7 | 10 | 32 22642 | 0 38896 | 30 02552 | 11 71159 | | | 29 739765 | 11 631675 |
| 22 | 7 | 10 | 32 04333 | 0 38932 | 29 85591 | 11 64267 | | | 29 570155 | 11 562755 |
| 22 | 7 | 10 | 32 22018 | 0 38172 | 30 01702 | 11 71597 | | | 29 731265 | 11 636055 |
| 22 | 7 | 10 | 32 05315 | 0 36128 | 29 8545 | 11 67234 | | | 29 568745 | 11 592425 |
| 22 | 7 | 10 | 32 19703 | 0 37958 | 29 99476 | 11 70928 | | | 29 709005 | 11 629365 |
| 22 | 7 | 15 | 31 88008 | 0 38615 | 29 70335 | 11 58445 | | | 29 417595 | 11 504535 |
| 22 | 7 | 15 | 32 08673 | 0 41135 | 29 90439 | 11 6385 | | | 29 618635 | 11 558585 |
| 22 | 7 | 15 | 32 0063 | 0 4236 | 29 83441 | 11 59701 | | | 29 548655 | 11 517095 |
| 22 | 7 | 15 | 31 94974 | 0 401 | 29 7735 | 11 59679 | | | 29 487745 | 11 516875 |
| 22 | 7 | 15 | 32 00196 | 0 4087 | 29 82481 | 11 60921 | | | 29 539055 | 11 529295 |
| 22 | 7 | 20 | 31 89557 | 0 40604 | 29 72516 | 11 57182 | | | 29 439405 | 11 491905 |
| 22 | 7 | 20 | 31 88365 | 0 39022 | 29 70819 | 11 58202 | | | 29 422435 | 11 502105 |
| 22 | 7 | 20 | 31 84485 | 0 40663 | 29 67836 | 11 55227 | | | 29 392605 | 11 472355 |
| 22 | 7 | 20 | 31 98668 | 0 41637 | 29 81351 | 11 59637 | | | 29 527755 | 11 516455 |
| 22 | 7 | 20 | 31 70842 | 0 38722 | 29 54459 | 11 51916 | | | 29 258835 | 11 439245 |
| 22 | 7 | 25 | 31 72226 | 0 42376 | 29 57111 | 11 49046 | | | 29 285355 | 11 410545 |
| 22 | 7 | 25 | 31 48607 | 0 38885 | 29 33904 | 11 43436 | | | 29 053285 | 11 354445 |
| 22 | 7 | 25 | 31 62611 | 0 38939 | 29 46908 | 11 48631 | | | 29 183325 | 11 406395 |
| 22 | 7 | 25 | 31 66855 | 0 42063 | 29 52014 | 11 47325 | | | 29 234385 | 11 393335 |
| 22 | 7 | 25 | 31 34769 | 0 39356 | 29 2125 | 11 37815 | | | 28 926745 | 11 298235 |
| 22 | 7 | 0 | 0 29848 | 0 02706 | 0 28689 | 0 08672 | | | | |
| 22 | 7 | 0 | 0 29128 | 0 03883 | 0 28462 | 0 07311 | | | | |
| f8_5b | | | | | | | | | | |
| 22 | 7 | 0 | -0 00289 | 0 00092 | -0 00233 | -0 00193 | -0 31153 | 0 422625 | | |
| 22 | 7 | 5 | 31 62239 | 0 85403 | 29 6397 | 11 05411 | | | 29 95123 | 10 631485 |
| 22 | 7 | 5 | 31 74301 | 0 84543 | 29 74831 | 11 10727 | | | 30 05984 | 10 684645 |
| 22 | 7 | 5 | 31 45243 | 0 85142 | 29 48113 | 10 99286 | | | 29 79266 | 10 570235 |
| 22 | 7 | 5 | 31 55979 | 0 8463 | 29 57876 | 11 03783 | | | 29 89029 | 10 615205 |
| 22 | 7 | 5 | 31 67024 | 0 91155 | 29 70561 | 11 01871 | | | 30 01714 | 10 596085 |
| 22 | 7 | 10 | 31 57287 | 0 91538 | 29 61676 | 10 97867 | | | 29 92829 | 10 556045 |
| 22 | 7 | 10 | 31 61056 | 0 89143 | 29 64274 | 11 01501 | | | 29 95427 | 10 592385 |
| 22 | 7 | 10 | 31 50778 | 0 9 | 29 55065 | 10 96856 | | | 29 86218 | 10 545935 |
| 22 | 7 | 10 | 31 43392 | 0 88801 | 29 47768 | 10 952 | | | 29 78921 | 10 529375 |
| 22 | 7 | 10 | 31 55584 | 0 90303 | 29 59635 | 10 98375 | | | 29 90788 | 10 561125 |
| 22 | 7 | 15 | 31 97054 | 0 99114 | 30 01386 | 11 0574 | | | 30 32539 | 10 634775 |
| 22 | 7 | 15 | 31 78404 | 0 94672 | 29 82429 | 11 02873 | | | 30 13582 | 10 606105 |

| | | | | | | | | | | |
|-------|---|----|----------|----------|----------|----------|----------|----------|-----------|-----------|
| 22 | 7 | 20 | 31 81819 | 1 08922 | 29 90934 | 10 90939 | | | 30 22087 | 10 486765 |
| 22 | 7 | 20 | 31 79633 | 1 0915 | 29 88992 | 10 89909 | | | 30 20145 | 10 476465 |
| 22 | 7 | 20 | 31 8382 | 1 09485 | 29 93001 | 10 91168 | | | 30 24154 | 10 489055 |
| 22 | 7 | 20 | 31 76851 | 1 088 | 29 86282 | 10 89192 | | | 30 17435 | 10 469295 |
| 22 | 7 | 25 | 31 61882 | 1 02409 | 29 70009 | 10 89509 | | | 30.01162 | 10 472465 |
| 22 | 7 | 25 | 31 54746 | 1 02353 | 29 63372 | 10 86889 | | | 29 94525 | 10 446265 |
| 22 | 7 | 25 | 31 55105 | 1 00346 | 29 62952 | 10 88884 | | | 29 94105 | 10 466215 |
| 22 | 7 | 25 | 31 65665 | 1 0143 | 29 73149 | 10 91835 | | | 30 04302 | 10 495725 |
| 22 | 7 | 25 | 31 44956 | 1 01396 | 29 53936 | 10 84109 | | | 29 85089 | 10 418465 |
| 22 | 7 | 0 | -0.13181 | -0.5148 | -0.31506 | 0 42793 | | | | |
| 22 | 7 | 0 | -0.12924 | -0.50231 | -0.308 | 0 41732 | | | | |
| fb_5c | | | | | | | | | | |
| 22 | 7 | 0 | -0.00091 | 0.00372 | 0 00055 | -0 00379 | 1 020925 | 0 284715 | | |
| 22 | 7 | 5 | 31 43877 | 0 29864 | 29 26139 | 11 50027 | | | 28 240465 | 11 215555 |
| 22 | 7 | 5 | 31 42313 | 0 3203 | 29 25501 | 11 47434 | | | 28 234085 | 11.189625 |
| 22 | 7 | 5 | 31 37038 | 0 3144 | 29 20388 | 11 46004 | | | 28 182955 | 11 175325 |
| 22 | 7 | 5 | 31 21911 | 0 30442 | 29 05989 | 11 41263 | | | 28 038965 | 11.127915 |
| 22 | 7 | 5 | 31 29848 | 0 33332 | 29 1443 | 11 41557 | | | 28 123375 | 11.130855 |
| 22 | 7 | 10 | 31 27879 | 0 42183 | 29 15921 | 11 32613 | | | 28 138285 | 11 041415 |
| 22 | 7 | 10 | 31 43151 | 0 43474 | 29 30565 | 11 37137 | | | 28 284725 | 11 086655 |
| 22 | 7 | 10 | 31 53156 | 0 46197 | 29 40861 | 11 3836 | | | 28 387685 | 11 098885 |
| 22 | 7 | 10 | 31 4618 | 0 44955 | 29 33928 | 11 36898 | | | 28 318355 | 11 084265 |
| 22 | 7 | 10 | 31 24836 | 0 44212 | 29 1386 | 11 29591 | | | 28 117675 | 11 011195 |
| 22 | 7 | 15 | 31 45977 | 0 50134 | 29 3568 | 11 3202 | | | 28 335875 | 11 035485 |
| 22 | 7 | 15 | 31 26735 | 0 50539 | 29 1799 | 11 24437 | | | 28 158975 | 10 959655 |
| 22 | 7 | 15 | 31 20401 | 0 49701 | 29 11804 | 11 22841 | | | 28 097115 | 10 943695 |
| 22 | 7 | 15 | 31 25766 | 0 50328 | 29 17012 | 11 24269 | | | 28 149195 | 10 957975 |
| 22 | 7 | 15 | 31 40891 | 0 52316 | 29 31781 | 11 28092 | | | 28 296885 | 10 996205 |
| 22 | 7 | 20 | 31 40136 | 0 66362 | 29 36343 | 11 14786 | | | 28 342505 | 10 863145 |
| 22 | 7 | 20 | 31 12683 | 0 6466 | 29 10252 | 11 0608 | | | 28 081595 | 10 776085 |
| 22 | 7 | 20 | 31 27 | 0 6752 | 29 24597 | 11 08791 | | | 28 225045 | 10 803195 |
| 22 | 7 | 20 | 31 2123 | 0 6466 | 29 18176 | 11 09281 | | | 28 160835 | 10 808095 |
| 22 | 7 | 20 | 31 24629 | 0 65725 | 29 21727 | 11 09568 | | | 28 196345 | 10 810965 |
| 22 | 7 | 25 | 31 02023 | 0 6419 | 29 00191 | 11 02522 | | | 27 980985 | 10 740505 |
| 22 | 7 | 25 | 31 17411 | 0 66387 | 29 15282 | 11 0625 | | | 28 131895 | 10 777785 |
| 22 | 7 | 25 | 30 97539 | 0 65137 | 28 96389 | 10 99965 | | | 27 942965 | 10 714935 |
| 22 | 7 | 25 | 30 99137 | 0 666 | 28 98419 | 10 99207 | | | 27 963265 | 10 707355 |
| 22 | 7 | 25 | 31 14076 | 0 67923 | 29 12765 | 11 03576 | | | 28 106725 | 10 751045 |
| 22 | 7 | 0 | 1.05283 | 0 127 | 1 01876 | 0 29447 | | | | |
| 22 | 7 | 0 | 1.0516 | 0 12832 | 1 02309 | 0 27496 | | | | |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|----------|-----------|-----------|-----------|
| f8_6a | | | | | | | | | | |
| 22 | 10 | 0 | 0 00092 | -0 00089 | 0 00052 | 0 00117 | 0 96182 | 0 06688 | | |
| 22 | 10 | 5 | 30 86767 | 0 11394 | 28 66269 | 11 45759 | | | 27 70087 | 11 39071 |
| 22 | 10 | 5 | 30 63252 | 0 09817 | 28 43876 | 11 38412 | | | 27 47694 | 11 31724 |
| 22 | 10 | 5 | 30 50693 | 0 09715 | 28 32193 | 11 33802 | | | 27 36011 | 11 27114 |
| 22 | 10 | 5 | 30 48161 | 0 11834 | 28 30639 | 11 30889 | | | 27 34457 | 11 24201 |
| 22 | 10 | 5 | 30 37664 | 0 08794 | 28 19768 | 11 29775 | | | 27 23586 | 11 23087 |
| 22 | 10 | 10 | 31 30138 | 0 23129 | 29 10878 | 11 51126 | | | 28 14696 | 11 44438 |
| 22 | 10 | 10 | 31 54859 | 0 25406 | 29 34652 | 11 58275 | | | 28 3847 | 11 51587 |
| 22 | 10 | 10 | 31 38128 | 0 23789 | 29 18534 | 11 53506 | | | 28 22352 | 11 46818 |
| 22 | 10 | 10 | 31 19252 | 0 22273 | 29 00464 | 11 47842 | | | 28 04282 | 11 41154 |
| 22 | 10 | 10 | 31 17298 | 0 21939 | 28 98527 | 11 47419 | | | 28 02345 | 11 40731 |
| 22 | 10 | 15 | 31 41448 | 0 32106 | 29 24757 | 11 47051 | | | 28 28575 | 11 40363 |
| 22 | 10 | 15 | 31 46266 | 0 31298 | 29 28892 | 11 49593 | | | 28 3271 | 11 42905 |
| 22 | 10 | 15 | 31 33074 | 0 29623 | 29 16032 | 11 46204 | | | 28 1985 | 11 39516 |
| 22 | 10 | 15 | 31 31987 | 0 29637 | 29 15029 | 11 45784 | | | 28 18847 | 11 39096 |
| 22 | 10 | 15 | 31 35292 | 0 30816 | 29 18535 | 11 45929 | | | 28 22353 | 11 39241 |
| 22 | 10 | 20 | 31 729 | 0 45731 | 29 58993 | 11 46188 | | | 28 62811 | 11 395 |
| 22 | 10 | 20 | 31 82264 | 0 47484 | 29 68332 | 11 4807 | | | 28 7215 | 11 41382 |
| 22 | 10 | 20 | 31 75818 | 0 46664 | 29 62047 | 11 46416 | | | 28 65865 | 11 39728 |
| 22 | 10 | 20 | 31 82038 | 0 45586 | 29 67411 | 11 49746 | | | 28 71229 | 11 43058 |
| 22 | 10 | 20 | 32 00811 | 0 46846 | 29 85289 | 11 55609 | | | 28 89107 | 11 48921 |
| 22 | 10 | 25 | 31 50517 | 0 46242 | 29 38431 | 11 3733 | | | 28 42249 | 11 30642 |
| 22 | 10 | 25 | 31 4367 | 0 47578 | 29 32584 | 11 33526 | | | 28 36402 | 11 26838 |
| 22 | 10 | 25 | 31 71917 | 0 47458 | 29 58728 | 11 44219 | | | 28 62546 | 11 37531 |
| 22 | 10 | 25 | 31 58094 | 0 47486 | 29 45922 | 11 39014 | | | 28 4974 | 11 32326 |
| 22 | 10 | 25 | 31 60903 | 0 48572 | 29 48933 | 11 3906 | | | 28 52751 | 11 32372 |
| 22 | 10 | 0 | 0 92687 | 0 29923 | 0 97147 | 0 06977 | | | | |
| 22 | 10 | 0 | 0 9068 | 0 29736 | 0 95217 | 0 06399 | | | | |
| f8_6b | | | | | | | | | | |
| 22 | 10 | 0 | -0 0023 | 0 00032 | -0 00201 | -0 00115 | 2 067945 | -0 752845 | | |
| 22 | 10 | 5 | 30 90938 | 1 55065 | 29 23956 | 10 14112 | | | 27 171615 | 10 893965 |
| 22 | 10 | 5 | 31 01703 | 1 56117 | 29 34332 | 10 17169 | | | 27 275375 | 10 924535 |
| 22 | 10 | 5 | 31 16244 | 1 55934 | 29 47745 | 10 22786 | | | 27 409505 | 10 980705 |
| 22 | 10 | 5 | 30 9101 | 1 58684 | 29 25379 | 10 10783 | | | 27 185845 | 10 860675 |
| 22 | 10 | 5 | 31 13463 | 1 59155 | 29 46373 | 10 18758 | | | 27 395785 | 10 940425 |
| 22 | 10 | 10 | 31 57863 | 1 69579 | 29 91445 | 10 25725 | | | 27 846505 | 11 010095 |
| 22 | 10 | 10 | 31 77246 | 1 72015 | 30 10329 | 10 30728 | | | 28 035345 | 11 060125 |
| 22 | 10 | 10 | 31 5619 | 1 69705 | 29 89941 | 10 24981 | | | 27 831465 | 11 002655 |
| 22 | 10 | 10 | 31 73422 | 1 70115 | 30 06072 | 10 31057 | | | 27 992775 | 11 063415 |
| 22 | 10 | 10 | 31 61208 | 1 71672 | 29 9533 | 10 25038 | | | 27 885355 | 11 003225 |
| 22 | 10 | 15 | 31 58487 | 1 76589 | 29 94649 | 10 19459 | | | 27 878545 | 10 947435 |
| 22 | 10 | 15 | 31 70871 | 1 76631 | 30 06148 | 10 2406 | | | 27 993535 | 10 993445 |

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|-------|----|----|----------|----------|----------|----------|----------|----------|-----------|-----------|
| 22 | 10 | 20 | 31.77684 | 1.79489 | 30.13535 | 10.23962 | | | 28.067405 | 10.992465 |
| 22 | 10 | 20 | 31.86339 | 1.80167 | 30.21814 | 10.26576 | | | 28.150195 | 11.018605 |
| 22 | 10 | 20 | 31.92102 | 1.82439 | 30.28008 | 10.26628 | | | 28.212135 | 11.019125 |
| 22 | 10 | 20 | 31.86617 | 1.81451 | 30.22553 | 10.25489 | | | 28.157585 | 11.007735 |
| 22 | 10 | 25 | 31.93175 | 1.94208 | 30.33412 | 10.16118 | | | 28.266175 | 10.914025 |
| 22 | 10 | 25 | 31.89215 | 1.92275 | 30.29016 | 10.16427 | | | 28.222215 | 10.917115 |
| 22 | 10 | 25 | 31.78953 | 1.94755 | 30.2043 | 10.10283 | | | 28.136355 | 10.855675 |
| 22 | 10 | 25 | 31.82513 | 1.94615 | 30.23679 | 10.11746 | | | 28.168845 | 10.870305 |
| 22 | 10 | 25 | 31.63435 | 1.93053 | 30.05405 | 10.06048 | | | 27.986105 | 10.813325 |
| 22 | 10 | 0 | 1.63729 | 1.46975 | 2.06864 | -0.74939 | | | | |
| 22 | 10 | 0 | 1.63341 | 1.47563 | 2.06725 | -0.7563 | | | | |
| | | | | | | | | | | |
| 18_6c | | | | | | | | | | |
| 22 | 10 | 0 | -0.00406 | -0.00248 | -0.0047 | 0.00078 | 0.421025 | 0.005755 | | |
| 22 | 10 | 5 | 30.53257 | 0.53828 | 28.51095 | 10.93861 | | | 28.089925 | 10.932855 |
| 22 | 10 | 5 | 30.4149 | 0.51225 | 28.3921 | 10.91867 | | | 27.971075 | 10.912915 |
| 22 | 10 | 5 | 30.48286 | 0.52808 | 28.46103 | 10.92945 | | | 28.040005 | 10.923695 |
| 22 | 10 | 5 | 30.59938 | 0.54198 | 28.57427 | 10.96022 | | | 28.153245 | 10.954465 |
| 22 | 10 | 5 | 30.64521 | 0.53647 | 28.61471 | 10.98249 | | | 28.193685 | 10.976735 |
| 22 | 10 | 10 | 30.68783 | 0.58671 | 28.67304 | 10.95187 | | | 28.252015 | 10.946115 |
| 22 | 10 | 10 | 30.88982 | 0.61241 | 28.86996 | 11.00371 | | | 28.448935 | 10.997955 |
| 22 | 10 | 10 | 30.70482 | 0.61004 | 28.69754 | 10.93661 | | | 28.276515 | 10.930855 |
| 22 | 10 | 10 | 30.8647 | 0.62823 | 28.85259 | 10.97964 | | | 28.431565 | 10.973885 |
| 22 | 10 | 10 | 30.76877 | 0.61945 | 28.76035 | 10.95184 | | | 28.339325 | 10.946085 |
| 22 | 10 | 10 | 30.82433 | 0.62385 | 28.81352 | 10.96857 | | | 28.392495 | 10.962815 |
| 22 | 10 | 15 | 30.79338 | 0.6305 | 28.78731 | 10.95082 | | | 28.366285 | 10.945065 |
| 22 | 10 | 15 | 30.54967 | 0.63665 | 28.56366 | 10.85382 | | | 28.142635 | 10.848065 |
| 22 | 10 | 15 | 30.60519 | 0.64456 | 28.6181 | 10.86728 | | | 28.197075 | 10.861525 |
| 22 | 10 | 15 | 30.77795 | 0.65075 | 28.78059 | 10.92626 | | | 28.359565 | 10.920505 |
| 22 | 10 | 15 | 30.68406 | 0.63866 | 28.68901 | 10.9023 | | | 28.267985 | 10.896545 |
| 22 | 10 | 20 | 30.53849 | 0.61724 | 28.54601 | 10.86763 | | | 28.124985 | 10.861875 |
| 22 | 10 | 20 | 30.57602 | 0.62464 | 28.58359 | 10.87483 | | | 28.162565 | 10.869075 |
| 22 | 10 | 20 | 30.43116 | 0.61426 | 28.44538 | 10.83018 | | | 28.024355 | 10.824425 |
| 22 | 10 | 20 | 30.57068 | 0.62202 | 28.57765 | 10.87525 | | | 28.156625 | 10.869495 |
| 22 | 10 | 20 | 30.60457 | 0.61163 | 28.60518 | 10.89758 | | | 28.184155 | 10.891825 |
| 22 | 10 | 25 | 30.53968 | 0.57287 | 28.5305 | 10.90921 | | | 28.109475 | 10.903455 |
| 22 | 10 | 25 | 30.39812 | 0.55792 | 28.39364 | 10.87005 | | | 27.972615 | 10.864295 |
| 22 | 10 | 25 | 30.54762 | 0.56399 | 28.53453 | 10.92041 | | | 28.113505 | 10.914655 |
| 22 | 10 | 25 | 30.435 | 0.56692 | 28.43121 | 10.87552 | | | 28.010185 | 10.869765 |
| 22 | 10 | 25 | 30.35835 | 0.56793 | 28.36052 | 10.84587 | | | 27.939495 | 10.840115 |
| 22 | 10 | 0 | 0.39574 | 0.14839 | 0.42251 | 0.01066 | | | | |
| 22 | 10 | 0 | 0.38931 | 0.15638 | 0.41954 | 0.00085 | | | | |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|--------|--------|-----|----------|----------|----------|----------|-----------|-----------|-----------|-----------|
| fb_13a | | | | | | | | | | |
| 34 | -4 | 0 | -0 00899 | -0 00201 | -0 00858 | -0 00336 | -0 187825 | -0 053385 | | |
| 34 | -4 | 5 | 40 80264 | 1 85606 | 34 86482 | 21 2778 | | | 35 052645 | 21 331185 |
| 34 | -4 | 5 | 40 80081 | 1 88238 | 34 87802 | 21 25496 | | | 35 065845 | 21 308345 |
| 34 | -4 | 5 | 40 98173 | 1 89972 | 35 0377 | 21 34175 | | | 35 225525 | 21 395135 |
| 34 | -4 | 5 | 40 76993 | 1 889 | 34 85612 | 21 2322 | | | 35 043945 | 21 285585 |
| 34 | -4 | 5 | 41 03707 | 1 90037 | 35 08395 | 21 37217 | | | 35 271775 | 21 425555 |
| 34 | -4 | 10 | 41 12875 | 1 9251 | 35 17378 | 21 40292 | | | 35 361605 | 21 456305 |
| 34 | -4 | 10 | 40 99873 | 1 93915 | 35 07385 | 21 31857 | | | 35 261675 | 21 371955 |
| 34 | -4 | 10 | 40 99357 | 1 94513 | 35 07292 | 21 31073 | | | 35 260745 | 21 364115 |
| 34 | -4 | 10 | 40 96896 | 1 93696 | 35 04794 | 21 30374 | | | 35 235765 | 21 357125 |
| 34 | -4 | 10 | 40 76398 | 1 90366 | 34 85939 | 21 21673 | | | 35 047215 | 21 270115 |
| 34 | -4 | 15 | 40 93724 | 1 95555 | 35 03204 | 21 27059 | | | 35 219865 | 21 323975 |
| 34 | -4 | 15 | 40 79001 | 1 92914 | 34 89521 | 21 21015 | | | 35 083035 | 21 263535 |
| 34 | -4 | 15 | 40 97183 | 1 95359 | 35 05962 | 21 29156 | | | 35 247445 | 21 344945 |
| 34 | -4 | 15 | 40 87551 | 1 92919 | 34 96612 | 21 25792 | | | 35 153945 | 21 311305 |
| 34 | -4 | 15 | 40 8577 | 1 95336 | 34 96487 | 21 22793 | | | 35 152695 | 21 281315 |
| 34 | -4 | 20 | 40 65379 | 1 90642 | 34 76957 | 21 15282 | | | 34 957395 | 21 206205 |
| 34 | -4 | 20 | 40 89142 | 1 92519 | 34 97708 | 21 27014 | | | 35 164905 | 21 323525 |
| 34 | -4 | 20 | 40 96117 | 1 96 | 35 05436 | 21 28028 | | | 35 242185 | 21 333665 |
| 34 | -4 | 20 | 40 63801 | 1 91652 | 34 76214 | 21 13562 | | | 34 949965 | 21 189005 |
| 34 | -4 | 20 | 40 65289 | 1 93853 | 34 78679 | 21 12569 | | | 34 974615 | 21 179075 |
| 34 | -4 | 25 | 40 91932 | 1 92256 | 34 99873 | 21 28792 | | | 35 186555 | 21 341305 |
| 34 | -4 | 25 | 40 79645 | 1 92539 | 34 89845 | 21 21687 | | | 35 086275 | 21 270255 |
| 34 | -4 | 25 | 40 93164 | 1 93887 | 35 01806 | 21 28129 | | | 35 205885 | 21 334675 |
| 34 | -4 | 25 | 40 8146 | 1 9302 | 34 91619 | 21 22303 | | | 35 104015 | 21 276415 |
| 34 | -4 | 25 | 40 67603 | 1 89387 | 34 78099 | 21 17566 | | | 34 968815 | 21 229045 |
| 34 | -4 | 0 | -0 18181 | -0 06296 | -0 18594 | -0 04947 | | | | |
| 34 | -4 | 0 | -0 18932 | -0 05858 | -0 18971 | -0 0573 | | | | |
| fb_13b | | | | | | | | | | |
| 34 | -4 | 0 | -0 00662 | -0 00198 | -0 0066 | -0 00206 | -0 260935 | 0 06422 | | |
| 34 | -4 | 5 | 41 30925 | 1 8033 | 35 25531 | 21 60483 | | | 35 516245 | 21 54061 |
| 34 | -4 | 5 | 40 94254 | 1 79521 | 34 94677 | 21 40648 | | | 35 207705 | 21 34226 |
| 34 | -4 | 5 | 41 14993 | 1 8244 | 35 13503 | 21 49826 | | | 35 395965 | 21 43404 |
| 34 | -4 | 5 | 41 20146 | 1 81396 | 35 17191 | 21 53572 | | | 35 432845 | 21 4715 |
| 34 | -4 | 5 | 41 10053 | 1 79817 | 35 07941 | 21 49238 | | | 35 340345 | 21 42816 |
| 34 | -4 | 10 | 41 27489 | 1 87305 | 35 26583 | 21 52779 | | | 35 526765 | 21 46357 |
| 34 | -4 | 10 | 41 16147 | 1 86452 | 35 16703 | 21 47144 | | | 35 427965 | 21 40722 |
| 34 | -4 | 10 | 41 13973 | 1 86265 | 35 14797 | 21 46084 | | | 35 408905 | 21 39662 |
| 34 | -4 | 10 | 40 99092 | 1 84015 | 35 01201 | 21 39628 | | | 35 272945 | 21 33206 |
| 34 | -4 | 10 | 41 17679 | 1 85619 | 35 17507 | 21 48692 | | | 35 436005 | 21 42227 |
| 34 | -4 | 15 | 41 21833 | 1 87807 | 35 22175 | 21 49201 | | | 35 482685 | 21 42779 |
| 34 | -4 | 15 | 41 38276 | 1 89331 | 35 36659 | 21 57132 | | | 35 627525 | 21 5071 |
| 34 | -4 | 15 | 40 97503 | 1 87433 | 35 01795 | 21 35906 | | | 35 278885 | 21 29484 |

| | | | | | | | | | | |
|----|----|----|----------|----------|----------|----------|--|--|-----------|----------|
| 34 | -4 | 20 | 41 00938 | 1 84881 | 35 03216 | 21 39942 | | | 35 293095 | 21 3352 |
| 34 | -4 | 20 | 40 91813 | 1 85923 | 34 96234 | 21 33976 | | | 35 223275 | 21 27554 |
| 34 | -4 | 20 | 40 83805 | 1 84293 | 34 88683 | 21 30849 | | | 35 147765 | 21 24427 |
| 34 | -4 | 25 | 41 08215 | 1 84303 | 35 08926 | 21 4449 | | | 35 350195 | 21 38068 |
| 34 | -4 | 25 | 41 15739 | 1 87217 | 35 16792 | 21 46282 | | | 35 428855 | 21 3986 |
| 34 | -4 | 25 | 41 11944 | 1 86556 | 35 13276 | 21 44708 | | | 35 393695 | 21 38286 |
| 34 | -4 | 25 | 40 96526 | 1 8519 | 34 99731 | 21 37219 | | | 35 258245 | 21 30797 |
| 34 | -4 | 25 | 41 27414 | 1 8924 | 35 27603 | 21 51134 | | | 35 536965 | 21 44712 |
| 34 | -4 | 0 | -0 16201 | -0 19554 | -0 24365 | 0 07151 | | | | |
| 34 | -4 | 0 | -0 19882 | -0 20278 | -0 27822 | 0 05693 | | | | |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|--------|--------|-----|----------|----------|----------|----------|----------|----------|-----------|-----------|
| fb_13c | | | | | | | | | | |
| 34 | -7 | 0 | 0 0033 | 0 00047 | 0 003 | 0 00145 | 0 022575 | 0 258705 | | |
| 34 | -7 | 5 | 40 13722 | 1 73437 | 34 24511 | 21 00659 | | | 34 222535 | 20 747885 |
| 34 | -7 | 5 | 40 04594 | 1 75497 | 34 18096 | 20 93847 | | | 34 158385 | 20 679765 |
| 34 | -7 | 5 | 39 61469 | 1 71998 | 33 80387 | 20 72633 | | | 33 781295 | 20 467625 |
| 34 | -7 | 5 | 40 40661 | 1 78067 | 34 49433 | 21 11885 | | | 34 471755 | 20 860145 |
| 34 | -7 | 5 | 40 38094 | 1 78951 | 34 478 | 21 09717 | | | 34 455425 | 20 838465 |
| 34 | -7 | 5 | 40 62715 | 1 79716 | 34 68639 | 21 2285 | | | 34 663815 | 20 969795 |
| 34 | -7 | 5 | 40 25383 | 1 76932 | 34 36133 | 21 04283 | | | 34 338755 | 20 784125 |
| 34 | -7 | 5 | 40 5343 | 1 80588 | 34 61429 | 21 16935 | | | 34 591715 | 20 910645 |
| 34 | -7 | 10 | 40 47728 | 1 83386 | 34 58267 | 21 11427 | | | 34 560095 | 20 855565 |
| 34 | -7 | 10 | 40 55576 | 1 84371 | 34 65323 | 21 14999 | | | 34 630655 | 20 891285 |
| 34 | -7 | 10 | 40 36536 | 1 82057 | 34 48245 | 21 0627 | | | 34 459875 | 20 803995 |
| 34 | -7 | 10 | 39 98679 | 1 80309 | 34 15883 | 20 8655 | | | 34 136255 | 20 606795 |
| 34 | -7 | 10 | 40 57502 | 1 86013 | 34 67838 | 21 14715 | | | 34 655805 | 20 888445 |
| 34 | -7 | 15 | 40 15373 | 1 84636 | 34 32142 | 20 92297 | | | 34 298845 | 20 664265 |
| 34 | -7 | 15 | 40 08999 | 1 81172 | 34 24921 | 20 91606 | | | 34 226635 | 20 657355 |
| 34 | -7 | 15 | 40 25393 | 1 84093 | 34 40145 | 20 98351 | | | 34 378875 | 20 724805 |
| 34 | -7 | 15 | 40 18506 | 1 83675 | 34 34202 | 20 94847 | | | 34 319445 | 20 689765 |
| 34 | -7 | 15 | 40 03943 | 1 83451 | 34 22004 | 20 86888 | | | 34 197465 | 20 610175 |
| 34 | -7 | 20 | 40 03208 | 1 8262 | 34 2093 | 20 87167 | | | 34 186725 | 20 612965 |
| 34 | -7 | 20 | 40 19731 | 1 84069 | 34 35438 | 20 95205 | | | 34 331805 | 20 693345 |
| 34 | -7 | 20 | 40 18157 | 1 82281 | 34 33133 | 20 95808 | | | 34 308755 | 20 699375 |
| 34 | -7 | 20 | 40 26053 | 1 85674 | 34 41577 | 20 97409 | | | 34 393195 | 20 715385 |
| 34 | -7 | 20 | 40 30517 | 1 85801 | 34 45349 | 20 998 | | | 34 430915 | 20 739295 |
| 34 | -7 | 25 | 40 19321 | 1 77491 | 34 3142 | 21 00429 | | | 34 291625 | 20 745585 |
| 34 | -7 | 25 | 40 22968 | 1 77445 | 34 34417 | 21 02507 | | | 34 321595 | 20 766365 |
| 34 | -7 | 25 | 40 10017 | 1 76281 | 34 2303 | 20 96229 | | | 34 207725 | 20 703585 |
| 34 | -7 | 25 | 40 16322 | 1 77982 | 34 29208 | 20 98345 | | | 34 269505 | 20 724745 |
| 34 | -7 | 25 | 40 38527 | 1 80649 | 34 49108 | 21 0855 | | | 34 468505 | 20 826795 |
| 34 | -7 | 0 | 0 17704 | -0 20209 | 0 03376 | 0 26654 | | | | |
| 34 | -7 | 0 | 0 14972 | -0 20161 | 0 01139 | 0 25087 | | | | |
| fb_13d | | | | | | | | | | |
| 34 | -7 | 0 | -0 00682 | -0 00029 | -0 00582 | -0 00358 | 0 03724 | 0 01127 | | |
| 34 | -7 | 5 | 40 04246 | 2 00198 | 34 3162 | 20 73174 | | | 34 27896 | 20 72047 |
| 34 | -7 | 5 | 40 05971 | 2 01063 | 34 33533 | 20 73422 | | | 34 29809 | 20 72295 |
| 34 | -7 | 5 | 40 25179 | 2 02152 | 34 50067 | 20 8326 | | | 34 46343 | 20 82133 |
| 34 | -7 | 5 | 40 05417 | 2 02158 | 34 33686 | 20 72204 | | | 34 29962 | 20 71077 |
| 34 | -7 | 5 | 40 16055 | 2 01993 | 34 42413 | 20 7829 | | | 34 38689 | 20 77163 |
| 34 | -7 | 10 | 40 09504 | 2 06568 | 34 39541 | 20 70834 | | | 34 35817 | 20 69707 |
| 34 | -7 | 10 | 40 06343 | 2 06786 | 34 37042 | 20 68885 | | | 34 33318 | 20 67758 |
| 34 | -7 | 10 | 40 18907 | 2 0779 | 34 48019 | 20 75079 | | | 34 44295 | 20 73952 |
| 34 | -7 | 10 | 39 99574 | 2 0637 | 34 31198 | 20 65445 | | | 34 27474 | 20 64318 |

| | | | | | | | | | |
|----|----|----|----------|---------|----------|----------|--|----------|----------|
| 34 | -7 | 15 | 39 93206 | 2 06197 | 34 25822 | 20 62027 | | 34 22098 | 20 609 |
| 34 | -7 | 15 | 40 16436 | 2 08077 | 34 46132 | 20 73459 | | 34 42408 | 20 72332 |
| 34 | -7 | 20 | 40 28706 | 2 09595 | 34 57153 | 20 79062 | | 34 53429 | 20 77935 |
| 34 | -7 | 20 | 40 41792 | 2 1196 | 34 69324 | 20 84419 | | 34 656 | 20 83292 |
| 34 | -7 | 20 | 40 37185 | 2 1219 | 34 65633 | 20 81652 | | 34 61909 | 20 80525 |
| 34 | -7 | 20 | 40 07092 | 2 0822 | 34 38465 | 20 68115 | | 34 34741 | 20 66988 |
| 34 | -7 | 20 | 40 21405 | 2 10294 | 34 51491 | 20 74399 | | 34 47767 | 20 73272 |
| 34 | -7 | 25 | 40 22057 | 2 03984 | 34 48503 | 20 79995 | | 34 44779 | 20 78868 |
| 34 | -7 | 25 | 40 26361 | 2 05194 | 34 52747 | 20 81399 | | 34 49023 | 20 80272 |
| 34 | -7 | 25 | 40 29631 | 2 03867 | 34 54716 | 20 84328 | | 34 50992 | 20 83201 |
| 34 | -7 | 25 | 40 0841 | 2 04312 | 34 37372 | 20 72092 | | 34 33648 | 20 70965 |
| 34 | -7 | 25 | 40 51404 | 2 08297 | 34 75244 | 20 9283 | | 34 7152 | 20 91703 |
| 34 | -7 | 0 | 0 05365 | 0 02044 | 0 05591 | 0 01306 | | | |
| 34 | -7 | 0 | 0 03754 | 0 00435 | 0 03355 | 0 01738 | | | |
| 34 | -7 | 0 | 0 02034 | 0 00965 | 0 02226 | 0 00337 | | | |

| Alpha | deltac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|-----------|-----------|-----------|-----------|
| 19_2b | | | | | | | | | | |
| 34 | -10 | 0 | 0 00295 | 0 00648 | 0 00607 | -0 00372 | -0.17234 | -0 047205 | | |
| 34 | -10 | 5 | 37 32882 | 2 35437 | 32 26354 | 18 92215 | | | 32 43588 | 18 969355 |
| 34 | -10 | 5 | 37 50764 | 2 39561 | 32 43485 | 18 98795 | | | 32 60719 | 19 035155 |
| 34 | -10 | 5 | 37 44065 | 2 39327 | 32 37801 | 18 95243 | | | 32 55035 | 18 999635 |
| 34 | -10 | 5 | 37 09549 | 2 36349 | 32 0752 | 18 78411 | | | 32 24754 | 18 831315 |
| 34 | -10 | 5 | 37 29397 | 2 37092 | 32 2439 | 18 88894 | | | 32 41624 | 18 936145 |
| 34 | -10 | 10 | 37 34981 | 2 3858 | 32 29852 | 18 90783 | | | 32 47086 | 18 955035 |
| 34 | -10 | 10 | 37 20786 | 2 36796 | 32 17086 | 18 84325 | | | 32 3432 | 18 890455 |
| 34 | -10 | 10 | 37 18365 | 2 3606 | 32 14668 | 18 83581 | | | 32 31902 | 18 883015 |
| 34 | -10 | 10 | 37 3324 | 2 38317 | 32 28261 | 18 90027 | | | 32 45495 | 18 947475 |
| 34 | -10 | 10 | 37 55927 | 2 42755 | 32 49551 | 18 99034 | | | 32 66785 | 19 037545 |
| 34 | -10 | 15 | 36 79708 | 2 34445 | 31 81716 | 18 63303 | | | 31 9895 | 18 680235 |
| 34 | -10 | 15 | 37 08484 | 2 39437 | 32 08364 | 18 75255 | | | 32 25598 | 18 799755 |
| 34 | -10 | 15 | 37 16865 | 2 3767 | 32 14325 | 18 81407 | | | 32 31559 | 18 861275 |
| 34 | -10 | 15 | 36 91761 | 2 34651 | 31 91824 | 18 69872 | | | 32 09058 | 18 745925 |
| 34 | -10 | 15 | 37 17294 | 2 39559 | 32 15736 | 18 80081 | | | 32 3297 | 18 848015 |
| 34 | -10 | 20 | 36 91278 | 2 35409 | 31 91847 | 18 68974 | | | 32 09081 | 18 736945 |
| 34 | -10 | 20 | 37 07438 | 2 38414 | 32 06925 | 18 75519 | | | 32 24159 | 18 802395 |
| 34 | -10 | 20 | 37 00784 | 2 40391 | 32 02514 | 18 70159 | | | 32 19748 | 18 748795 |
| 34 | -10 | 20 | 36 89685 | 2 37912 | 31 91926 | 18 66008 | | | 32 0916 | 18 707285 |
| 34 | -10 | 20 | 36 80487 | 2 36838 | 31 837 | 18 61755 | | | 32 00934 | 18 664755 |
| 34 | -10 | 20 | 36 79094 | 2 35556 | 31 81828 | 18 62039 | | | 31 99062 | 18 667595 |
| 34 | -10 | 25 | 36 81366 | 2 33401 | 31 82507 | 18 65096 | | | 31 99741 | 18 698165 |
| 34 | -10 | 25 | 37 13314 | 2 36631 | 32 10799 | 18 80283 | | | 32 28033 | 18 850035 |
| 34 | -10 | 25 | 37 32177 | 2 40349 | 32 28516 | 18 87748 | | | 32 4575 | 18 924685 |
| 34 | -10 | 25 | 37 1873 | 2 3656 | 32 15249 | 18 8337 | | | 32 32483 | 18 880905 |
| 34 | -10 | 25 | 37 05544 | 2 34193 | 32 02995 | 18 77959 | | | 32 20229 | 18 826795 |
| 34 | -10 | 0 | -0 16835 | -0 05487 | -0 17025 | -0 04865 | | | 0 00209 | -0 001445 |
| 34 | -10 | 0 | -0 17019 | -0 0596 | -0 17443 | -0 04576 | | | -0 00209 | 0 001445 |
| 19_2c | | | | | | | | | | |
| 34 | -10 | 0 | 0 00196 | 0 0013 | 0 00235 | 0 00002 | -0 084565 | -0 032395 | | |
| 34 | -10 | 5 | 37 83676 | 2 45333 | 32 73998 | 19 12414 | | | 32 824545 | 19 156535 |
| 34 | -10 | 5 | 38 2621 | 2 51239 | 33 12563 | 19 31303 | | | 33 210195 | 19 345425 |
| 34 | -10 | 5 | 37 77113 | 2 43808 | 32 67704 | 19 10008 | | | 32 761605 | 19 132475 |
| 34 | -10 | 5 | 38 14484 | 2 48568 | 33 01348 | 19 2696 | | | 33 098045 | 19 301995 |
| 34 | -10 | 5 | 37 86552 | 2 46003 | 32 76757 | 19 13468 | | | 32 852135 | 19 167075 |
| 34 | -10 | 5 | 37 61676 | 2 42238 | 32 54029 | 19 02679 | | | 32 624855 | 19 059185 |
| 34 | -10 | 10 | 37 62272 | 2 46968 | 32 57168 | 18 9909 | | | 32 656245 | 19 023295 |
| 34 | -10 | 10 | 37 69141 | 2 46421 | 32 62556 | 19 03385 | | | 32 710125 | 19 066245 |
| 34 | -10 | 10 | 37 55301 | 2 45371 | 32 50496 | 18 96515 | | | 32 589525 | 18 997545 |
| 34 | -10 | 10 | 37 55909 | 2 45807 | 32 51243 | 18 96495 | | | 32 596995 | 18 997345 |
| 34 | -10 | 10 | 37 40044 | 2 41788 | 32 35843 | 18 90955 | | | 32 442995 | 18 941945 |

| | | | | | | | | | | |
|----|-----|----|----------|----------|----------|----------|--|--|-----------|-----------|
| 34 | -10 | 15 | 37 29648 | 2 45331 | 32 29206 | 18 82204 | | | 32 376625 | 18 854435 |
| 34 | -10 | 20 | 37 06977 | 2 42369 | 32 08754 | 18 71982 | | | 32 172105 | 18 752215 |
| 34 | -10 | 20 | 37 20507 | 2 43098 | 32 20379 | 18 78944 | | | 32 288355 | 18 821835 |
| 34 | -10 | 20 | 37 30727 | 2 441 | 32 29412 | 18 83828 | | | 32 378685 | 18 870675 |
| 34 | -10 | 20 | 37 09243 | 2 42713 | 32 10826 | 18 72964 | | | 32 192825 | 18 762035 |
| 34 | -10 | 20 | 37 14503 | 2 41737 | 32 1464 | 18 76714 | | | 32 230965 | 18 799535 |
| 34 | -10 | 25 | 38 46036 | 2 23433 | 33 1345 | 19 65442 | | | 33 219065 | 19 686815 |
| 34 | -10 | 25 | 38 28902 | 2 22655 | 32 98811 | 19 56505 | | | 33 072675 | 19 597445 |
| 34 | -10 | 25 | 38 52346 | 2 2556 | 33 19871 | 19 67207 | | | 33 283275 | 19 704465 |
| 34 | -10 | 25 | 38 49261 | 2 25935 | 33 17523 | 19 65171 | | | 33 259795 | 19 684105 |
| 34 | -10 | 25 | 38 21335 | 2 52363 | 33 09149 | 19 27645 | | | 33 176055 | 19 308845 |
| 34 | -10 | 0 | -0 08657 | -0 02026 | -0 0831 | -0 03161 | | | | |
| 34 | -10 | 0 | -0 08988 | -0 0206 | -0 08603 | -0 03318 | | | | |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------------|--------|-----|----------|----------|----------|----------|----------|---------|------------|------------|
| 18_d | | | | | | | | | | |
| 22 | 4 | 0 | -0.00736 | -0.0025 | -0.00776 | -0.00044 | -0.59663 | 0.6968 | | |
| 22 | 4 | 0 | 31.07424 | 0.59169 | 29.03319 | 11.09201 | | | 29.6298233 | 10.3951667 |
| 22 | 4 | 0 | 31.08945 | 0.57437 | 29.04079 | 11.11377 | | | 29.6374233 | 10.4169267 |
| 22 | 4 | 0 | 30.91127 | 0.564 | 28.87171 | 11.05663 | | | 29.4683433 | 10.3597867 |
| 22 | 4 | 0 | 31.07087 | 0.56302 | 29.01932 | 11.11733 | | | 29.6159533 | 10.4204867 |
| 22 | 4 | 0 | 30.94145 | 0.5493 | 28.89418 | 11.08157 | | | 29.4908133 | 10.3847267 |
| 22 | 4 | 0 | 31.0912 | 0.5776 | 29.04363 | 11.11143 | | | 29.6402633 | 10.4145867 |
| 22 | 4 | 0 | 31.227 | 0.59576 | 29.17635 | 11.14546 | | | 29.7729833 | 10.4486167 |
| 22 | 4 | 0 | 30.99523 | 0.56749 | 28.95086 | 11.08485 | | | 29.5474933 | 10.3880067 |
| 22 | 4 | 0 | 31.37042 | 0.61409 | 29.31619 | 11.18219 | | | 29.9128233 | 10.4853467 |
| 22 | 4 | 0 | 31.21757 | 0.60439 | 29.17084 | 11.13393 | | | 29.7674733 | 10.4370867 |
| 22 | 4 | 0 | -0.2645 | -0.92306 | -0.59103 | 0.75676 | | | | |
| 22 | 4 | 0 | -0.30388 | -0.84712 | -0.59909 | 0.6716 | | | | |
| 22 | 4 | 0 | -0.30806 | -0.83864 | -0.59978 | 0.66217 | | | | |
| | | | | | | | | | 29.6483393 | 10.4150737 |
| 18_e | | | | | | | | | | |
| 22 | 4 | 0 | -0.00143 | -0.00348 | -0.00263 | 0.00269 | 1.53516 | 0.3648 | | |
| 22 | 4 | 0 | 31.46339 | 0.94538 | 29.52649 | 10.90985 | | | 27.99133 | 10.54508 |
| 22 | 4 | 0 | 31.79638 | 0.99772 | 29.85484 | 10.98606 | | | 28.31968 | 10.62129 |
| 22 | 4 | 0 | 31.62071 | 0.96382 | 29.67927 | 10.95169 | | | 28.14411 | 10.58692 |
| 22 | 4 | 0 | 31.43195 | 0.95912 | 29.50249 | 10.88533 | | | 27.96733 | 10.52056 |
| 22 | 4 | 0 | 31.48499 | 0.97408 | 29.55728 | 10.89133 | | | 28.02212 | 10.52656 |
| 22 | 4 | 0 | 31.56488 | 0.97123 | 29.63028 | 10.9239 | | | 28.09512 | 10.55913 |
| 22 | 4 | 0 | 31.55297 | 0.97294 | 29.61988 | 10.91785 | | | 28.08472 | 10.55308 |
| 22 | 4 | 0 | 31.65399 | 0.97173 | 29.71309 | 10.95682 | | | 28.17793 | 10.59205 |
| 22 | 4 | 0 | 31.66766 | 0.97714 | 29.72778 | 10.95692 | | | 28.19262 | 10.59215 |
| 22 | 4 | 0 | 31.71168 | 1.00152 | 29.77774 | 10.95081 | | | 28.24258 | 10.58604 |
| 22 | 4 | 0 | 1.6126 | 0.27167 | 1.59695 | 0.3522 | | | | |
| 22 | 4 | 0 | 1.50744 | 0.20207 | 1.47337 | 0.37734 | | | | |
| | | | | | | | | | 28.123754 | 10.568286 |
| 18_f | | | | | | | | | | |
| 22 | 4 | 0 | -0.00358 | -0.00163 | -0.00393 | 0.00017 | 0.85711 | 0.1467 | | |
| 22 | 4 | 0 | 30.5542 | 0.87734 | 28.65802 | 10.63235 | | | 27.80091 | 10.485665 |
| 22 | 4 | 0 | 30.46127 | 0.88843 | 28.57601 | 10.58725 | | | 27.7189 | 10.440565 |
| 22 | 4 | 0 | 30.51857 | 0.89769 | 28.63261 | 10.60014 | | | 27.7755 | 10.453455 |
| 22 | 4 | 0 | 30.40341 | 0.88334 | 28.52045 | 10.5703 | | | 27.66334 | 10.423615 |
| 22 | 4 | 0 | 30.58486 | 0.89828 | 28.69429 | 10.62442 | | | 27.83718 | 10.477735 |
| 22 | 4 | 0 | 30.49858 | 0.89809 | 28.61422 | 10.59227 | | | 27.75711 | 10.445585 |
| 22 | 4 | 0 | 30.40451 | 0.89508 | 28.52587 | 10.55983 | | | 27.66876 | 10.413145 |
| 22 | 4 | 0 | 30.74074 | 0.92427 | 28.84855 | 10.65872 | | | 27.99144 | 10.512035 |
| 22 | 4 | 0 | 30.63069 | 0.90929 | 28.74091 | 10.63138 | | | 27.8838 | 10.484695 |
| 22 | 4 | 0 | 0.85472 | 0.18191 | 0.86063 | 0.15152 | | | | |
| 22 | 4 | 0 | 0.84458 | 0.18824 | 0.85359 | 0.14185 | | | | |
| | | | | | | | | | 27.7885489 | 10.4596106 |

| Alpha | deltac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|----------|----------|-----------|-----------|
| f8_7g | | | | | | | | | | |
| 22 | 7 | 0 | 0 0011 | 0 00328 | 0 00225 | -0 00263 | 0 74935 | 0 435915 | | |
| 22 | 7 | 0 | 31 90164 | 0 53137 | 29 77774 | 11 45788 | | | 29 02839 | 11 021965 |
| 22 | 7 | 0 | 31 91644 | 0 54683 | 29 79726 | 11 44909 | | | 29 04791 | 11 013175 |
| 22 | 7 | 0 | 31 92946 | 0 5402 | 29 80685 | 11 46012 | | | 29 0575 | 11 024205 |
| 22 | 7 | 0 | 32 01633 | 0 54447 | 29 88899 | 11 4887 | | | 29 13964 | 11 052785 |
| 22 | 7 | 0 | 31 75223 | 0 52617 | 29 63726 | 11 40674 | | | 28 88791 | 10 970825 |
| 22 | 7 | 0 | 31 88155 | 0 55147 | 29 76664 | 11 43173 | | | 29 01729 | 10 995815 |
| 22 | 7 | 0 | 31 73667 | 0 53483 | 29 62608 | 11 39288 | | | 28 87673 | 10 956965 |
| 22 | 7 | 0 | 31 49488 | 0 50331 | 29 39008 | 11 33153 | | | 28 64073 | 10 895615 |
| 22 | 7 | 0 | 31 79455 | 0 54468 | 29 68343 | 11 40543 | | | 28 93408 | 10 969515 |
| 22 | 7 | 0 | 31 80663 | 0 55473 | 29 6984 | 11 40064 | | | 28 94905 | 10 964725 |
| 22 | 7 | 0 | 0 86229 | -0 12838 | 0 7514 | 0 44205 | | | | |
| 22 | 7 | 0 | 0 85388 | -0 11854 | 0 7473 | 0 42978 | | | | |
| | | | | | | | | | 28 957923 | 10 986559 |
| f8_7h | | | | | | | | | | |
| 22 | 7 | 0 | 0 00464 | 0 00196 | 0 00503 | -0 00008 | 0 147735 | 0 10499 | | |
| 22 | 7 | 0 | 31 37217 | 0 69388 | 29 3477 | 11 10887 | | | 29 199965 | 11 00388 |
| 22 | 7 | 0 | 31 4579 | 0 70042 | 29 42964 | 11 13492 | | | 29 281905 | 11 02993 |
| 22 | 7 | 0 | 31 62975 | 0 72285 | 29 59738 | 11 1785 | | | 29 449645 | 11 07351 |
| 22 | 7 | 0 | 31 32207 | 0 71252 | 29 30823 | 11 07281 | | | 29 160495 | 10 96782 |
| 22 | 7 | 0 | 31 21184 | 0 68765 | 29 19671 | 11 05459 | | | 29 048975 | 10 9496 |
| 22 | 7 | 0 | 31 25055 | 0 68913 | 29 23316 | 11 06771 | | | 29 085425 | 10 96272 |
| 22 | 7 | 0 | 31 30629 | 0 70282 | 29 28996 | 11 0759 | | | 29 142225 | 10 97091 |
| 22 | 7 | 0 | 31 31798 | 0 69745 | 29 29879 | 11 08526 | | | 29 151055 | 10 98027 |
| 22 | 7 | 0 | 31 22276 | 0 68233 | 29 20484 | 11 06361 | | | 29 057105 | 10 95862 |
| 22 | 7 | 0 | 31 47353 | 0 71185 | 29 44841 | 11 13018 | | | 29 300675 | 11 02519 |
| 22 | 7 | 0 | 0 18473 | -0 04152 | 0 15573 | 0 1077 | | | | |
| 22 | 7 | 0 | 0 16788 | -0 04249 | 0 13974 | 0 10228 | | | | |
| | | | | | | | | | 29 187747 | 10 992245 |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|---------|----------|-----------|-----------|
| f8_7i | | | | | | | | | | |
| 22 | 10 | 0 | -0.00241 | 0.00619 | 0.00009 | -0.00664 | 0.43776 | 0.063985 | | |
| 22 | 10 | 0 | 30.29243 | 0.01867 | 28.09365 | 11.33043 | | | 27.65589 | 11.266445 |
| 22 | 10 | 0 | 30.26281 | -0.00197 | 28.05846 | 11.33847 | | | 27.6207 | 11.274485 |
| 22 | 10 | 0 | 30.34999 | 0.01804 | 28.14678 | 11.35258 | | | 27.70902 | 11.288595 |
| 22 | 10 | 0 | 30.31127 | 0.03574 | 28.11751 | 11.32166 | | | 27.67975 | 11.257675 |
| 22 | 10 | 0 | 30.16542 | 0.02702 | 27.97902 | 11.27511 | | | 27.54126 | 11.211125 |
| 22 | 10 | 0 | 30.5247 | 0.02776 | 28.31241 | 11.40902 | | | 27.87465 | 11.345035 |
| 22 | 10 | 0 | 30.19614 | -0.01542 | 27.99159 | 11.32597 | | | 27.55383 | 11.261985 |
| 22 | 10 | 0 | 30.4833 | 0.00374 | 28.26502 | 11.41578 | | | 27.82726 | 11.351795 |
| 22 | 10 | 0 | 30.44404 | 0.01464 | 28.23271 | 11.39096 | | | 27.79495 | 11.326975 |
| 22 | 10 | 0 | 30.37891 | 0.01319 | 28.17177 | 11.36791 | | | 27.73401 | 11.303925 |
| 22 | 10 | 0 | 0.4372 | 0.10768 | 0.4457 | 0.06394 | | | | |
| 22 | 10 | 0 | 0.42251 | 0.10165 | 0.42982 | 0.06403 | | | | |
| | | | | | | | | | 27.699132 | 11.288804 |
| f8_7j | | | | | | | | | | |
| 22 | 10 | 0 | -0.0096 | -0.00307 | -0.01005 | -0.00075 | 0.98632 | 0.52066 | | |
| 22 | 10 | 0 | 29.76166 | -0.12333 | 27.54833 | 11.26327 | | | 26.56201 | 10.74261 |
| 22 | 10 | 0 | 29.99974 | -0.09387 | 27.78011 | 11.32513 | | | 26.79379 | 10.80447 |
| 22 | 10 | 0 | 30.18648 | 0.06846 | 27.96277 | 11.37153 | | | 26.97645 | 10.85087 |
| 22 | 10 | 0 | 30.14477 | -0.06979 | 27.9236 | 11.35714 | | | 26.93728 | 10.83648 |
| 22 | 10 | 0 | 30.05109 | -0.07977 | 27.833 | 11.3313 | | | 26.84668 | 10.81064 |
| 22 | 10 | 0 | 29.74399 | -0.11668 | 27.53444 | 11.25048 | | | 26.54812 | 10.72982 |
| 22 | 10 | 0 | 29.87518 | -0.12213 | 27.65404 | 11.30467 | | | 26.66772 | 10.78401 |
| 22 | 10 | 0 | 29.94318 | -0.09471 | 27.72735 | 11.30473 | | | 26.74103 | 10.78407 |
| 22 | 10 | 0 | 30.05563 | -0.09924 | 27.82992 | 11.35105 | | | 26.8436 | 10.83039 |
| 22 | 10 | 0 | 29.94534 | -0.09238 | 27.73023 | 11.30338 | | | 26.74391 | 10.78272 |
| 22 | 10 | 0 | 1.1182 | -0.11439 | 0.99392 | 0.52495 | | | | |
| 22 | 10 | 0 | 1.10089 | -0.11214 | 0.97872 | 0.51637 | | | | |
| | | | | | | | | | 26.766059 | 10.795608 |
| f8_7k | | | | | | | | | | |
| 22 | 10 | 0 | -0.00218 | 0.0063 | 0.00034 | -0.00666 | 0.58517 | 0.20833 | | |
| 22 | 10 | 0 | 29.0459 | -0.06998 | 26.90467 | 10.94567 | | | 26.3195 | 10.73734 |
| 22 | 10 | 0 | 29.32488 | -0.06396 | 27.16559 | 11.0446 | | | 26.58042 | 10.83627 |
| 22 | 10 | 0 | 29.41918 | -0.0449 | 27.26017 | 11.06225 | | | 26.675 | 10.85392 |
| 22 | 10 | 0 | 29.0485 | -0.07941 | 26.90356 | 10.95539 | | | 26.31839 | 10.74706 |
| 22 | 10 | 0 | 29.36942 | -0.03759 | 27.21677 | 11.03683 | | | 26.6316 | 10.8285 |
| 22 | 10 | 0 | 29.53231 | -0.03731 | 27.3679 | 11.09759 | | | 26.78273 | 10.88926 |
| 22 | 10 | 0 | 29.33399 | -0.05674 | 27.17674 | 11.04131 | | | 26.59157 | 10.83298 |
| 22 | 10 | 0 | 29.36772 | -0.04919 | 27.21085 | 11.04694 | | | 26.62568 | 10.83861 |
| 22 | 10 | 0 | 29.26748 | -0.05562 | 27.1155 | 11.01536 | | | 26.53033 | 10.80703 |
| 22 | 10 | 0 | 29.34477 | -0.05921 | 27.18582 | 11.04764 | | | 26.60065 | 10.83931 |
| 22 | 10 | 0 | 29.24413 | -0.07476 | 27.08668 | 11.02436 | | | 26.50151 | 10.81603 |
| 22 | 10 | 0 | 29.1505 | -0.07521 | 26.9997 | 10.9897 | | | 26.41453 | 10.78137 |

| Alpha | deltac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|-----------|-----------|-----------|-----------|
| f8_8a | | | | | | | | | | |
| 34 | -4 | 0 | 0 0009 | -0.00252 | -0 00066 | 0 00259 | -0 300755 | -0 388825 | | |
| 34 | -4 | 0 | 40 22267 | 1 97294 | 34 44936 | 20 85659 | | | 34 750115 | 21 245415 |
| 34 | -4 | 0 | 39 89114 | 1 94119 | 34 15676 | 20 69752 | | | 34 457515 | 21 086345 |
| 34 | -4 | 0 | 40 00079 | 1 95653 | 34 25623 | 20 74612 | | | 34 556985 | 21 134945 |
| 34 | -4 | 0 | 40 00304 | 1 95192 | 34 25552 | 20 7512 | | | 34 556275 | 21 140025 |
| 34 | -4 | 0 | 39 98239 | 1 95791 | 34 24176 | 20 73469 | | | 34 542515 | 21 123515 |
| 34 | -4 | 0 | 39 78644 | 1 93615 | 34 06714 | 20 64315 | | | 34 367895 | 21 031975 |
| 34 | -4 | 0 | 39 93771 | 1 9491 | 34 19978 | 20 71701 | | | 34 500535 | 21 105835 |
| 34 | -4 | 0 | 39 79936 | 1 92229 | 34 0701 | 20 66187 | | | 34 370855 | 21 050695 |
| 34 | -4 | 0 | 39 94145 | 1 9582 | 34 20798 | 20 71156 | | | 34 508735 | 21 100385 |
| 34 | -4 | 0 | 39 97606 | 1 9509 | 34 23259 | 20 73696 | | | 34 533345 | 21 125785 |
| 34 | -4 | 0 | -0 47321 | 0 13272 | -0 31809 | -0 37465 | | | | |
| 34 | -4 | 0 | -0 46032 | 0 17562 | -0 28342 | -0 403 | | | | |
| | | | | | | | | | 34 514477 | 21 114492 |
| f8_8b | | | | | | | | | | |
| 34 | -4 | 0 | 0 00112 | 0 00033 | 0 00111 | 0 00035 | 0 675522 | 0 381124 | | |
| 34 | -4 | 0 | 40 50123 | 1 87626 | 34 62623 | 21 09251 | | | 33 950708 | 20 711386 |
| 34 | -4 | 0 | 40 69895 | 1 88873 | 34 79712 | 21 19273 | | | 34 121598 | 20 811606 |
| 34 | -4 | 0 | 40 6547 | 1 86863 | 34 7492 | 21 18465 | | | 34 073678 | 20 803526 |
| 34 | -4 | 0 | 40 60938 | 1 8773 | 34 71648 | 21 15213 | | | 34 040958 | 20 771006 |
| 34 | -4 | 0 | 40 36395 | 1 84504 | 34 49497 | 21 04163 | | | 33 819448 | 20 660506 |
| 34 | -4 | 0 | 40 70757 | 1 86007 | 34 78824 | 21 22132 | | | 34 112718 | 20 840196 |
| 34 | -4 | 0 | 40 61171 | 1 85734 | 34 70725 | 21 16997 | | | 34 031728 | 20 788846 |
| 34 | -4 | 0 | 40 31008 | 1 83283 | 34 44348 | 21 02162 | | | 33 767958 | 20 640496 |
| 34 | -4 | 0 | 40 40606 | 1 80956 | 34 51003 | 21 09459 | | | 33 834508 | 20 713466 |
| 34 | -4 | 0 | 40 38613 | 1 83102 | 34 50551 | 21 06565 | | | 33 829988 | 20 684526 |
| 34 | -4 | 0 | 0 83796 | 0 06411 | 0 73055 | 0 41543 | | | | |
| 34 | -4 | 0 | 0 80925 | 0 06238 | 0 70578 | 0 40081 | | | | |
| 34 | -4 | 0 | 0 78429 | 0 06304 | 0 68546 | 0 38631 | | | | |
| 34 | -4 | 0 | 0 73 | 0 06503 | 0 64157 | 0 3543 | | | | |
| 34 | -4 | 0 | 0 70426 | 0 05434 | 0 61425 | 0 34877 | | | | |
| | | | | | | | | | 33 958329 | 20 742556 |
| f8_8c | | | | | | | | | | |
| 34 | -4 | 0 | -0 00433 | 0 00013 | -0 00352 | -0 00253 | 0 2601 | 0 151165 | | |
| 34 | -4 | 0 | 40 25666 | 1 73935 | 34 34691 | 21 06925 | | | 34 08681 | 20 918085 |
| 34 | -4 | 0 | 40 09141 | 1 72334 | 34 20096 | 20 99012 | | | 33 94086 | 20 838955 |
| 34 | -4 | 0 | 40 2247 | 1 72195 | 34 31069 | 21 06581 | | | 34 05059 | 20 914645 |
| 34 | -4 | 0 | 40 23239 | 1 72236 | 34 3173 | 21 06976 | | | 34 0572 | 20 918595 |
| 34 | -4 | 0 | 40 15007 | 1 70787 | 34 24094 | 21 03574 | | | 33 98084 | 20 884575 |
| 34 | -4 | 0 | 40 24087 | 1 72757 | 34 32724 | 21 07019 | | | 34 06714 | 20 919025 |
| 34 | -4 | 0 | 40 12837 | 1 73277 | 34 23688 | 21 00297 | | | 33 97678 | 20 851805 |
| 34 | -4 | 0 | 40 05269 | 1 68996 | 34 1502 | 20 99614 | | | 33 8901 | 20 844975 |
| 34 | -4 | 0 | 40 18229 | 1 72324 | 34 27626 | 21 04102 | | | 34 01616 | 20 889855 |

| Alpha | deltac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|----------|----------|-----------|-----------|
| fb_8d | | | | | | | | | | |
| 34 | -7 | 0 | 0 0029 | 0 00273 | 0 00393 | -0 00064 | -0 03056 | 0 25898 | | |
| 34 | -7 | 0 | 41 05867 | 1 83191 | 35 06357 | 21 44099 | | | 35 09413 | 21 18201 |
| 34 | -7 | 0 | 41 04169 | 1 83885 | 35 05337 | 21 42575 | | | 35 08393 | 21 16677 |
| 34 | -7 | 0 | 41 00061 | 1 84751 | 35 02416 | 21 39559 | | | 35 05472 | 21 13661 |
| 34 | -7 | 0 | 41 08687 | 1 86157 | 35 10353 | 21 43218 | | | 35 13409 | 21 1732 |
| 34 | -7 | 0 | 41 03503 | 1 8505 | 35 05437 | 21 41236 | | | 35 08493 | 21 15338 |
| 34 | -7 | 0 | 40 96817 | 1 83286 | 35 00566 | 21 40078 | | | 35 03622 | 21 1418 |
| 34 | -7 | 0 | 40 91791 | 1 8479 | 34 95582 | 21 34902 | | | 34 98638 | 21 09004 |
| 34 | -7 | 0 | 40 85591 | 1 81953 | 34 88855 | 21 33787 | | | 34 91911 | 21 07889 |
| 34 | -7 | 0 | 40 93922 | 1 83857 | 34 96826 | 21 36868 | | | 34 99882 | 21 1097 |
| 34 | -7 | 0 | 41 19049 | 1 85859 | 35 18778 | 21 49258 | | | 35 21834 | 21 2336 |
| 34 | -7 | 0 | 0 14069 | -0 24088 | -0 01806 | 0 27837 | | | | |
| 34 | -7 | 0 | 0 1183 | -0 23086 | -0 03102 | 0 25755 | | | | |
| 34 | -7 | 0 | 0 09946 | -0 22364 | -0 0426 | 0 24102 | | | | |
| | | | | | | | | | 35 061067 | 21 1466 |
| fb_8e | | | | | | | | | | |
| 34 | -7 | 0 | -0 00396 | -0 00142 | -0 00407 | -0 00104 | 0 481075 | 0 161965 | | |
| 34 | -7 | 0 | 40 81865 | 2 14591 | 35 04017 | 21 04645 | | | 34 559095 | 20 884485 |
| 34 | -7 | 0 | 41 1198 | 2 17603 | 35 30668 | 21 18989 | | | 34 825605 | 21 027925 |
| 34 | -7 | 0 | 41 09325 | 2 1627 | 35 27722 | 21 18609 | | | 34 796145 | 21 024125 |
| 34 | -7 | 0 | 40 85238 | 2 15713 | 35 07441 | 21 05602 | | | 34 593335 | 20 894055 |
| 34 | -7 | 0 | 41 06923 | 2 16638 | 35 25936 | 21 16961 | | | 34 778285 | 21 007645 |
| 34 | -7 | 0 | 40 68771 | 2 13516 | 34 92561 | 20 98215 | | | 34 444535 | 20 820185 |
| 34 | -7 | 0 | 40 98004 | 2 17203 | 35 18858 | 21 11505 | | | 34 707505 | 20 953085 |
| 34 | -7 | 0 | 40 9968 | 2 14082 | 35 18502 | 21 1503 | | | 34 703945 | 20 988335 |
| 34 | -7 | 0 | 41 05697 | 2 17231 | 35 25251 | 21 15784 | | | 34 771435 | 20 995875 |
| 34 | -7 | 0 | 40 85895 | 2 1407 | 35 07067 | 21 07332 | | | 34 589595 | 20 911355 |
| 34 | -7 | 0 | 0 50234 | 0 13466 | 0 49176 | 0 16926 | | | | |
| 34 | -7 | 0 | 0 47646 | 0 13482 | 0 47039 | 0 15467 | | | | |
| | | | | | | | | | 34 676948 | 20 950707 |
| fb_8f | | | | | | | | | | |
| 34 | -7 | 0 | -0 00019 | -0 00109 | -0 00077 | 0 0008 | 0 44318 | 0 24702 | | |
| 34 | -7 | 0 | 41 56317 | 2 12513 | 35 64578 | 21 48002 | | | 35 2026 | 21 233 |
| 34 | -7 | 0 | 41 23483 | 2 06886 | 35 34212 | 21 34306 | | | 34 89894 | 21 09604 |
| 34 | -7 | 0 | 41 10831 | 2 07755 | 35 24208 | 21 26511 | | | 34 7989 | 21 01809 |
| 34 | -7 | 0 | 41 31058 | 2 08975 | 35 4166 | 21 3681 | | | 34 97342 | 21 12108 |
| 34 | -7 | 0 | 41 12817 | 2 08238 | 35 26125 | 21 27221 | | | 34 81807 | 21 02519 |
| 34 | -7 | 0 | 41 5554 | 2 12624 | 35 63997 | 21 47475 | | | 35 19679 | 21 22773 |
| 34 | -7 | 0 | 41 44997 | 2 10485 | 35 5406 | 21 43353 | | | 35 09742 | 21 18651 |
| 34 | -7 | 0 | 41 62684 | 2 11147 | 35 69094 | 21 52695 | | | 35 24776 | 21 27993 |
| 34 | -7 | 0 | 41 30564 | 2 08305 | 35 40875 | 21 3709 | | | 34 96557 | 21 12388 |
| 34 | -7 | 0 | 41 44951 | 2 11948 | 35 5484 | 21 42114 | | | 35 10522 | 21 17412 |
| 34 | -7 | 0 | 41 43381 | 2 11353 | 35 53206 | 21 41729 | | | 35 08888 | 21 17027 |

| Alpha | dellac | osc | Axial | Normal | Lift | Drag | L Drift | D Drift | LIFT | DRAG |
|-------|--------|-----|----------|----------|----------|----------|---------|---------|-----------|-----------|
| f8_8g | | | | | | | | | | |
| 34 | -10 | 0 | 0 00844 | 0 01712 | 0 01657 | -0 00947 | 0 00405 | 0 1813 | | |
| 34 | -10 | 0 | 0 0024 | -0 00284 | 0 00041 | 0 0037 | | | | |
| 34 | -10 | 0 | 40 03282 | 2 19241 | 34 41469 | 20 56848 | | | 34 41064 | 20 38715 |
| 34 | -10 | 0 | 40 32609 | 2 24197 | 34 68554 | 20 69138 | | | 34 68149 | 20 51005 |
| 34 | -10 | 0 | 40 05069 | 2 22244 | 34 4463 | 20 55358 | | | 34 44225 | 20 37225 |
| 34 | -10 | 0 | 40 04791 | 2 22091 | 34 44314 | 20 55329 | | | 34 43909 | 20 37196 |
| 34 | -10 | 0 | 40 17809 | 2 22976 | 34 55601 | 20 61875 | | | 34 55196 | 20 43742 |
| 34 | -10 | 0 | 40 56853 | 2 26761 | 34 90087 | 20 8057 | | | 34 89682 | 20 62437 |
| 34 | -10 | 0 | 40 49889 | 2 26368 | 34 84094 | 20 77001 | | | 34 83689 | 20 58868 |
| 34 | -10 | 0 | 40 539 | 2 26119 | 34 8728 | 20 79451 | | | 34 86875 | 20 61318 |
| 34 | -10 | 0 | 40 6697 | 2 25222 | 34 97613 | 20 87503 | | | 34 97208 | 20 6937 |
| 34 | -10 | 0 | 40 52405 | 2 25634 | 34 85769 | 20 79017 | | | 34 85364 | 20 60884 |
| 34 | -10 | 0 | 0 11281 | -0 15027 | 0 0095 | 0 18766 | | | | |
| 34 | -10 | 0 | 0 09669 | -0 14586 | -0 0014 | 0 175 | | | | |
| | | | | | | | | | 34 695361 | 20 52076 |
| f8_8h | | | | | | | | | | |
| 34 | -10 | 0 | -0 00218 | 0 00347 | 0 00013 | -0 0041 | 0 13682 | 0 1239 | | |
| 34 | -10 | 0 | 40 65121 | 2 33943 | 35 00957 | 20 79239 | | | 34 872755 | 20 668475 |
| 34 | -10 | 0 | 40 07881 | 2 29232 | 34 50869 | 20 51136 | | | 34 371875 | 20 387445 |
| 34 | -10 | 0 | 40 48873 | 2 33822 | 34 87419 | 20 70254 | | | 34 737375 | 20 578625 |
| 34 | -10 | 0 | 40 25462 | 2 30787 | 34 66314 | 20 59679 | | | 34 526325 | 20 472875 |
| 34 | -10 | 0 | 40 49042 | 2 35252 | 34 88359 | 20 69163 | | | 34 746775 | 20 567715 |
| 34 | -10 | 0 | 40 41445 | 2 32625 | 34 80592 | 20 67092 | | | 34 669105 | 20 547005 |
| 34 | -10 | 0 | 40 17815 | 2 31386 | 34 60309 | 20 54906 | | | 34 466275 | 20 425145 |
| 34 | -10 | 0 | 40 29335 | 2 31648 | 34 70006 | 20 6113 | | | 34 563245 | 20 487385 |
| 34 | -10 | 0 | 40 38095 | 2 35012 | 34 7915 | 20 63241 | | | 34 654685 | 20 508495 |
| 34 | -10 | 0 | 40 30584 | 2 33729 | 34 72205 | 20 60104 | | | 34 585235 | 20 477125 |
| 34 | -10 | 0 | 0 19398 | -0 02678 | 0 14585 | 0 13067 | | | | |
| 34 | -10 | 0 | 0 17145 | -0 02568 | 0 12778 | 0 11716 | | | | |
| | | | | | | | | | 34 619365 | 20 512029 |

APPENDIX F: BASELINE VERIFICATION DATA

| Alpha | Dellac | Osc. | Axial | Normal | Lift | Drag |
|---------------|--------|------|----------|----------|----------|----------|
| f7_23a | | | | | | |
| 22 | 7 | 0 | -0.00366 | 0.00625 | -0.00105 | -0.00716 |
| 22 | 7 | 0 | 43.22227 | 1.81439 | 40.75467 | 14.50907 |
| 22 | 7 | 0 | 43.08132 | 1.81535 | 40.62435 | 14.45538 |
| 22 | 7 | 0 | 42.96693 | 1.8219 | 40.52074 | 14.40646 |
| 22 | 7 | 0 | 43.06607 | 1.811 | 40.60858 | 14.45371 |
| 22 | 7 | 0 | 43.00628 | 1.84902 | 40.56739 | 14.39605 |
| 22 | 7 | 0 | -3.84245 | 1.97197 | -2.82395 | -3.26778 |
| f7_23b | | | | | | |
| 22 | 7 | 0 | 0.00539 | -0.00016 | 0.00493 | 0.00217 |
| 22 | 7 | 0 | 48.87875 | 1.55483 | 45.90204 | 16.86869 |
| 22 | 7 | 0 | 48.78839 | 1.55381 | 45.81787 | 16.83578 |
| 22 | 7 | 0 | 48.73988 | 1.55201 | 45.77222 | 16.81928 |
| 22 | 7 | 0 | 48.54549 | 1.55417 | 45.5928 | 16.74446 |
| 22 | 7 | 0 | 48.52331 | 1.5433 | 45.56816 | 16.74623 |
| 22 | 7 | 0 | 4.04242 | 1.92216 | 4.46812 | -0.26788 |
| 22 | 7 | 0 | 3.96778 | 1.94074 | 4.40587 | -0.31306 |
| f7_23c | | | | | | |
| 22 | 7 | 0 | 0.01158 | 0.01869 | 0.01774 | -0.01299 |
| 22 | 7 | 0 | -0.00142 | 0.00136 | -0.00081 | -0.00179 |
| 22 | 7 | 0 | 45.54404 | 0.7319 | 42.50187 | 16.38249 |
| 22 | 7 | 0 | 45.4931 | 0.72367 | 42.45156 | 16.37104 |
| 22 | 7 | 0 | 45.58084 | 0.74295 | 42.54014 | 16.38603 |
| 22 | 7 | 0 | 45.29687 | 0.7019 | 42.26146 | 16.31772 |
| 22 | 7 | 0 | 45.0858 | 0.69297 | 42.06242 | 16.24692 |
| 22 | 7 | 0 | 0.48201 | 0.39913 | 0.59643 | -0.18951 |
| 22 | 7 | 0 | 0.47209 | 0.41565 | 0.59342 | -0.20853 |
| f7_23d | | | | | | |
| 22 | 7 | 0 | -0.00318 | 0.00164 | -0.00234 | -0.00271 |
| 22 | 7 | 0 | 45.14908 | 0.9999 | 42.23607 | 15.98606 |
| 22 | 7 | 0 | 45.18414 | 0.9762 | 42.25969 | 16.02116 |
| 22 | 7 | 0 | 45.08298 | 0.98417 | 42.16889 | 15.97587 |
| 22 | 7 | 0 | 45.19839 | 0.98736 | 42.27709 | 16.01615 |
| 22 | 7 | 0 | 0.91205 | 1.31556 | 1.33845 | -0.8781 |
| f7_23e | | | | | | |
| 22 | 7 | 0 | -0.00028 | 0.00085 | 0.00006 | -0.00089 |
| 22 | 7 | 0 | 44.91719 | 0.54877 | 41.85206 | 16.31746 |
| 22 | 7 | 0 | 44.82931 | 0.53856 | 41.76676 | 16.29401 |
| 22 | 7 | 0 | 44.78014 | 0.538 | 41.72097 | 16.27611 |
| 22 | 7 | 0 | 44.81276 | 0.55827 | 41.7588 | 16.26954 |

| | | | | | | | |
|--------|----|---|---|----------|----------|----------|----------|
| | 22 | 7 | 0 | 0.41215 | -0.4754 | 0.20405 | 0.59518 |
| f7_24a | | | | | | | |
| | 22 | 7 | 0 | 0.00276 | 0.00114 | 0.00298 | -0.00002 |
| | 22 | 7 | 0 | 45.64971 | 0.98359 | 42.69413 | 16.18872 |
| | 22 | 7 | 0 | 45.80381 | 1.01084 | 42.84722 | 16.22118 |
| | 22 | 7 | 0 | 46.00458 | 1.03341 | 43.04183 | 16.27545 |
| | 22 | 7 | 0 | 45.84045 | 0.99294 | 42.87449 | 16.2515 |
| | 22 | 7 | 0 | 45.89534 | 0.99177 | 42.92494 | 16.27315 |
| | 22 | 7 | 0 | 1.13744 | 1.24304 | 1.52027 | -0.72643 |
| | 22 | 7 | 0 | 1.11732 | 1.24617 | 1.50278 | -0.73688 |
| f7_24b | | | | | | | |
| | 22 | 7 | 0 | 0.00131 | 0.00216 | 0.00202 | -0.00151 |
| | 22 | 7 | 0 | 45.9755 | 0.63683 | 42.8663 | 16.63227 |
| | 22 | 7 | 0 | 45.8311 | 0.62404 | 42.72762 | 16.59003 |
| | 22 | 7 | 0 | 45.69937 | 0.61853 | 42.60342 | 16.5458 |
| | 22 | 7 | 0 | 45.67146 | 0.62341 | 42.57938 | 16.53081 |
| | 22 | 7 | 0 | 45.79478 | 0.62915 | 42.69586 | 16.57169 |
| | 22 | 7 | 0 | 0.39956 | 0.8246 | 0.67936 | -0.61487 |
| f7_31c | | | | | | | |
| | 22 | 7 | 0 | -0.00498 | 0.00948 | -0.00107 | -0.01065 |
| | 22 | 7 | 0 | -0.0061 | 0.00612 | -0.00336 | -0.00796 |
| | 22 | 7 | 0 | 44.29352 | 1.51677 | 41.63642 | 15.18632 |
| | 22 | 7 | 0 | 44.24351 | 1.53731 | 41.59775 | 15.14855 |
| | 22 | 7 | 0 | 44.02367 | 1.51325 | 41.38491 | 15.0885 |
| | 22 | 7 | 0 | 44.31361 | 1.54449 | 41.66544 | 15.16814 |
| | 22 | 7 | 0 | 44.24907 | 1.51762 | 41.59554 | 15.16888 |
| | 22 | 7 | 0 | 0.84917 | 1.5769 | 1.37806 | -1.14397 |
| | 22 | 7 | 0 | 0.84568 | 1.58478 | 1.37777 | -1.15259 |
| f7_31d | | | | | | | |
| | 22 | 7 | 0 | -0.00241 | -0.00009 | -0.00227 | -0.00082 |
| | 22 | 7 | 0 | 45.51758 | 1.76652 | 42.86491 | 15.41329 |
| | 22 | 7 | 0 | 45.66733 | 1.77627 | 43.00741 | 15.46035 |
| | 22 | 7 | 0 | 46.08508 | 1.81421 | 43.40895 | 15.58167 |
| | 22 | 7 | 0 | 45.65885 | 1.7745 | 42.99888 | 15.45882 |
| | 22 | 7 | 0 | 45.77572 | 1.79078 | 43.11335 | 15.4875 |
| | 22 | 7 | 0 | 45.69706 | 1.81211 | 43.0484 | 15.43826 |
| | 22 | 7 | 0 | 1.37173 | 1.98313 | 2.01474 | -1.32487 |
| f7_31e | | | | | | | |
| | 22 | 4 | 0 | -0.00409 | 0.00144 | -0.00326 | -0.00287 |
| | 22 | 4 | 0 | 45.42909 | 1.56251 | 42.70645 | 15.5693 |
| | 22 | 4 | 0 | 45.35989 | 1.53503 | 42.63199 | 15.56886 |

| | | | | | | |
|--------|----|---|----------|---------|----------|----------|
| 22 | 4 | 0 | 45.41503 | 1.55866 | 42.69196 | 15.56761 |
| 22 | 4 | 0 | 45.23514 | 1.5373 | 42.51718 | 15.52003 |
| 22 | 4 | 0 | 45.28674 | 1.5322 | 42.5631 | 15.54408 |
| 22 | 4 | 0 | 0.09442 | 0.3104 | 0.20383 | -0.25243 |
| 22 | 4 | 0 | 0.09302 | 0.347 | 0.21624 | -0.28689 |
| f7_31f | | | | | | |
| 22 | 4 | 0 | -0.00013 | 0.01764 | 0.00648 | -0.0164 |
| 22 | 4 | 0 | 0.00261 | 0.02046 | 0.01009 | -0.018 |
| 22 | 4 | 0 | 0.00093 | 0.00244 | 0.00178 | -0.00191 |
| 22 | 4 | 0 | 0.0019 | 0.01081 | 0.00581 | -0.00931 |
| 22 | 4 | 0 | 45.70637 | 1.56307 | 42.96375 | 15.67266 |
| 22 | 4 | 0 | 45.36468 | 1.54013 | 42.63835 | 15.56592 |
| 22 | 4 | 0 | 45.19558 | 1.52913 | 42.47743 | 15.51278 |
| 22 | 4 | 0 | 45.43248 | 1.54663 | 42.70364 | 15.5853 |
| 22 | 4 | 0 | 45.43199 | 1.55858 | 42.70766 | 15.57403 |
| 22 | 4 | 0 | 0.31819 | 0.21651 | 0.37613 | -0.08155 |
| f7_31g | | | | | | |
| 22 | 7 | 0 | -0.00197 | 0.00505 | 0.00007 | -0.00542 |
| 22 | 7 | 0 | 46.09751 | 2.26241 | 43.58838 | 15.17076 |
| 22 | 7 | 0 | 45.82527 | 2.24549 | 43.32962 | 15.08447 |
| 22 | 7 | 0 | 45.74109 | 2.2269 | 43.24461 | 15.07017 |
| 22 | 7 | 0 | 45.91938 | 2.26097 | 43.42268 | 15.10537 |
| 22 | 7 | 0 | 45.96782 | 2.25972 | 43.46713 | 15.12467 |
| 22 | 7 | 0 | 0.09739 | 0.68963 | 0.34864 | -0.60293 |
| f7_31h | | | | | | |
| 22 | 7 | 0 | -0.00016 | 0.00198 | 0.0006 | -0.0019 |
| 22 | 7 | 0 | 45.8176 | 1.30976 | 42.97198 | 15.94918 |
| 22 | 7 | 0 | 45.83929 | 1.2934 | 42.98596 | 15.97248 |
| 22 | 7 | 0 | 45.73742 | 1.2825 | 42.88743 | 15.94443 |
| 22 | 7 | 0 | 45.4699 | 1.25252 | 42.62816 | 15.87201 |
| 22 | 7 | 0 | 45.78298 | 1.28259 | 42.92971 | 15.96141 |
| 22 | 7 | 0 | 2.50588 | 0.97523 | 2.68874 | 0.0345 |
| 22 | 7 | 0 | 2.45943 | 0.98105 | 2.64785 | 0.0117 |
| f7_31i | | | | | | |
| 22 | 10 | 0 | 0.00256 | 0.00362 | 0.00374 | -0.0024 |
| 22 | 10 | 0 | 45.84462 | 0.86715 | 42.83123 | 16.36969 |
| 22 | 10 | 0 | 44.99778 | 0.80006 | 42.02093 | 16.11467 |
| 22 | 10 | 0 | 45.23752 | 0.80734 | 42.24593 | 16.19772 |
| 22 | 10 | 0 | 45.36601 | 0.84841 | 42.38045 | 16.20777 |
| 22 | 10 | 0 | 45.0211 | 0.81808 | 42.04929 | 16.10669 |
| 22 | 10 | 0 | 45.47394 | 0.84321 | 42.47857 | 16.25302 |
| 22 | 10 | 0 | 45.3379 | 0.86152 | 42.3593 | 16.18509 |

| | | | | | | |
|--------|----|---|----------|----------|----------|----------|
| 22 | 10 | 0 | 0.76737 | 0.68249 | 0.96716 | -0.34533 |
| | | | | | | |
| f7_31j | | | | | | |
| 22 | 10 | 0 | -0.00484 | -0.00298 | -0.0056 | 0.00095 |
| 22 | 10 | 0 | 43.86147 | 0.15559 | 40.72593 | 16.28654 |
| 22 | 10 | 0 | 44.08762 | 0.18305 | 40.9459 | 16.34579 |
| 22 | 10 | 0 | 43.79933 | 0.17162 | 40.67432 | 16.24839 |
| 22 | 10 | 0 | 44.07719 | 0.18537 | 40.9371 | 16.33973 |
| 22 | 10 | 0 | 43.78001 | 0.15706 | 40.65095 | 16.25465 |
| 22 | 10 | 0 | -0.1228 | -0.4055 | -0.26576 | 0.32997 |
| | | | | | | |
| f7_31k | | | | | | |
| 22 | 7 | 0 | 0.00841 | 0.00364 | 0.00916 | -0.00023 |
| 22 | 7 | 0 | 47.31729 | 1.38383 | 44.39022 | 16.44231 |
| 22 | 7 | 0 | 47.44788 | 1.42378 | 44.52627 | 16.45418 |
| 22 | 7 | 0 | 47.56302 | 1.42304 | 44.63275 | 16.498 |
| 22 | 7 | 0 | 47.57654 | 1.40812 | 44.63969 | 16.5169 |
| 22 | 7 | 0 | 47.33187 | 1.38893 | 44.40565 | 16.44303 |
| 22 | 7 | 0 | 3.01299 | 0.68643 | 3.05073 | 0.49224 |
| 22 | 7 | 0 | 2.9889 | 0.68428 | 3.0276 | 0.48521 |

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