ELF1 7A Linking Background - ELF Study 1999

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Outline

- Based on
- Types of linking
 - TOC
 - Staic vs. dynamic linking
 - Static vs. dynamic binaries
 - Build-time, load-time, run-time linking
- 3 Linking for dynamic executables / libraries
 - TOC
 - Build-time linking for dynamic executables / libraries
 - Load-time linking for dynamic executables / libraries

Based on

"Study of ELF loading and relocs", 1999 http://netwinder.osuosl.org/users/p/patb/public_html/elf_ relocs.html

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Compling 32-bit program on 64-bit gcc

- gcc -v
- gcc -m32 t.c
- sudo apt-get install gcc-multilib
- sudo apt-get install g++-multilib
- gcc-multilib
- g++-multilib
- gcc -m32
- objdump -m i386

TOC: Types of linking

- Static vs. dynamic linking
- Static vs. dynamic binaries
- Build-time, load-time, run-time linking

TOC: Static and dynamic linking

- Binary executable files
- Statically linked files
- Dynamically linked files
- In-memory copy of an executable

Binary executable file

- a statically linked binary with all libraries loaded into the executable itself
- a dynamically linked binary with only some libraries statically linked

 $\verb|https://unix.stackexchange.com/questions/356709/difference-between-ld-and-ld-som/questions/3$

Statically linked files

- when you statically link a file into an executable, the contents of the files are included in the executable at link time.
- statically linked executable and library files <u>never change</u> (the last step in the compilation prcess)

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamical

Dynamically linked files

- when you dynamically link a file into an executable, a pointer to the file is <u>included</u> in the executable but the <u>contents</u> of the file are not included at <u>link</u> time.
- these referenced dynamically linked files are
 - not brought in the memory until you run the executable
 - loaded into memory by the dynamic linker at run time

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamical

In-memory copy of an executable

- dynamically linked files are only brought into the in-memory copy of the executable, not the executable file on the disk.
 - files on the disk are not modified
 - a shared library is shared across several processes
- dynamically loaded libraries
 can <u>change</u> at the <u>next run</u> time
 just by <u>replacing</u> the corresponding files on the disk.

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamical

TOC: Static vs. dynamic binaries

- Static binary (1) copying
- Static binary (2) non PIC
- Static binary (3) link time optimization
- Static binary (4) performance
- Dynamic binary (1) a program and its dependencies
- Dynamic binary (2) kernel
- Dynamic binary (3) vDSO
- Dynamic binary (4) dynamic linker

Static binary (1) copying

- dynamic binaries <u>load</u> code from <u>external</u> binaries (.so file) at <u>run</u> time
- in static binairies, library code (.a libraries) is copied inside the binary at build time
- advantages of dynamic binaries are
 - libraries can be reused between different running applications.
 - so they need less memory
 - libraries can be <u>changed</u> later on <u>without recompiling</u> as long as the <u>ABI</u> (Application binary interface) of the library doesn't change.

Static binary (2) non PIC

- code in a static library need not be PIC
 - position <u>dependent</u> code can jump and call <u>directly</u> without needing any intermediate steps
 - the linker adjusts the instructions/data for direct cross-references
- this performance benefit shows up only in high-performance code;
 e.g., you might get a teenthy boost from a video encoder
 if you statically compile & link it.
- if the program does any blocking I/O it won't matter at all.

Static binary (3) link time optimization

- modern linkers are able to do link-time optimization (LTO)
 - the compiler does its job and emits some GIMPLE bytecode along with the usual machine code in the object file.
 - the bytecode gives a gist of
 - what functions/variables are where,
 - what everything does,
 - how to piece it together,
 - and possibly some analysis that's been done as well, since that's a side-effect of optimization.

Static binary (4) performance

- The linker can use optimization analysis to knit together code from several object files when it's producing the final executable,
- without LTO, the linker basically mashes pieces of object files together as indivisible blocks (+noise).
- So in theory, you might be able to do significantly better with static compilation as long as
 - sufficiently many of your object files are produced by gcc -flto
 - linker supports LTO
 - burning on inter-object calls/accesses in loops.

Dynamic binary (1) a program and its dependencies

- the shared libraries must be able to be <u>loaded</u> <u>anywhere</u> in the process' virtual address space and must be <u>relocated</u>
- the kernel does only <u>map</u> the program file in memory the dynamic linker (the interpreter) must
 - locate and map all dependencies as well as shared object specified in LD_PRELOAD
 - relocate the files

 $\verb|https://www.gabriel.urdhr.fr/2015/01/22/elf-linking/\#base-address||$

Dynamic binary (2) kernel

- the kernels initialises the process:
- it maps in the virtual address space
 - the main program,
 - the interpreter (dynamic linker) segments
 - the vDSO (virtual Dynamic Shared Object)
- it sets up the stack (passing the arguments, environment)
- calls the dynamic linker entry point

https://www.gabriel.urdhr.fr/2015/01/22/elf-linking/#base-address

Dynamic binary (3) vDSO

- the vDSO (virtual Dynamic Shared Object)
 - a Linux kernel mechanism for exporting a carefully selected <u>set</u> of kernel space routines to user space applications
 - to overcome the performance penalty of a mode switch from user to kernel mode that is inherent when system call interface is used

https://www.gabriel.urdhr.fr/2015/01/22/elf-linking/#base-address

Dynamic binary (4) dynamic linker

- the dynamic linker <u>loads</u> the different ELF objects and <u>binds</u> them together
 - relocates itself
 - finds and loads the necessary libraries
 - does the relocations (which binds the ELF objects)
 - <u>calls</u> the <u>initialisation functions</u> of the shared objects
 - those functions are <u>specified</u> in the DT_INIT and DT_INIT_ARRAY entries of the ELF objects.
 - calls the main program entry point
 - <u>found</u> in the AT_ENTRY entry of the <u>auxiliary vector</u>: it has been <u>initialised</u> by the <u>kernel</u> from the e <u>entry ELF</u> header field.
- the executable then initialises itself.

https://www.gabriel.urdhr.fr/2015/01/22/elf-linking/#base-address

TOC: Build-time, load-time, run-time linking

- Build-time, load-time, run-time
- Build-time vs. load-time linking
- (1) build-time linking for staic executables / libraries
- (2) build-time linking for dynamic executables / libraries
- (3) load-time linking for dynamic executables / libraries
- Load-time vs. run-time dynamic linking
- Run-time dynamic linking
- Build-time linker 1d
- Run-time linker ld.so
- Linker at the build time
- Kernel at the load time
- Dynamic loader at the load time



Build-time, load-time, run-time

compile step	link step	run step	run step
build-time	build-time	load-time	run-time

 $\verb|https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and the composition of th$

Build-time and. load-time linkers

build-time linking	build-time linking	load-time linking
static linking	static linking	dynamic linking
ld	ld	ld.so
for statically	for dynamically	for dynamically
		,
linked exectuables	linked executables	linked executables
•	,	,

 $\verb|https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are also as the control of t$

(1) build-time linking for static executables / libraries

- static linking, at build-time the build-time linker 1d
 - resolves all the objects used in the program during the build,
 - · merges the objects which are used, and
 - produces an executable binary which doesn't use external libraries;

 $\verb|https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are all the control of the c$

(2) build-time linking for dynamic executables / libraries

- static linking, at build-time: the build-time linker 1d
 - resolves all objects used in the program, but
 - it only stores *references* to them;
 - instead of storing them in the executable (no merge)
 - records
 - which shared libraries are required at the run time,
 - possibly which versions of libraries or symbols are required.
 - which run time loader should be used

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(3) load-time linking for dynamic executables / libraries

- dynamic linking, at <u>run-time</u> (specifically <u>load-time</u>):
 the run-time linker <u>ld.so</u>, or <u>dynamic linker</u>,
 - resolves all the references stored in the executable,
 - loading all the required libraries (shared objects) and
 - updating all the object references before running the program.

https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are

Load-time vs. run-time dynamic linking

- load-time dynamic linking the OS handles unresolved symbols in the library
 - referenced by the executable (or another library)
 - resolved when the executable/library is loaded into memory
- run-time dynamic linking an API provided by the OS or through a <u>library</u>
 - can explicitly load a DLL or DSO when you need it
 - and then perform the symbol resolution

https://stackoverflow.com/questions/2055840/difference-between-load-time-dynamic-

Run-time dynamic linking

• using libdl

<pre>dlopen()</pre>	gain access to an executable object file
dclose()	close a dlopen object
dlsym()	obtain the address of a symbol from a dlopen object
dlvsym()	Programming interface to dynamic linking loader.
dlerror()	get diagnostic information
-	

http://www.yolinux.com/TUTORIALS/LibraryArchives-StaticAndDynamic.html

Build-time linker 1d

- a static linker
 - links a program or library at compile (build) time
 - usually as the last step in the compilation process, creating a binary executable or a library.
- a static library
 - has the suffix name .a denoting archive
 - is created by the ar utility
- 1d is a static linker (build-time linker)
- 1d also plays a role in dynamic linking (build-time linker)
 - stores all object references in a dynamic executable

Run-time linker 1d.so

- a dynamic linker
 - <u>loads</u> the dynamic libraries into the process' address space at <u>run</u> time.
 - libraries were dynamically linked at compile (build) time
- a dynamic library
 - so represents shared object
 - the suffix name of shared libraries
 - a library that may be dynamically linked into programs
 - one library is shared among several programs
- ld.so is a dynamic linker (run-time linker)

https://unix.stackexchange.com/questions/356709/difference-between-ld-and-ld-so

Linker at the build time

- compile, link, run
 - 1d is not called at either compile or run time
 - only at the link step is /usr/bin/ld is invoked.
 - on Linux, 1d is part of the binutils package.
- a link step is performed as a <u>final step</u> in producing an <u>executable</u>, or a <u>shared library</u> (<u>build time</u>)
 - this is called static linking, to differentiate this step from dynamic loading that will happen at run time (specifically load time)

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and-

kernel at the load time

The kernel

- · loads executable into memory, and
- checks whether runtime loader was requested at static link time.
- If it was, the dynamic loader is also loaded into memory, and
- execution control is passed to it (instead of the main executable).

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and-

dynamic loader at the load time

- the dynamic loader
 - examines the executable
 - · which other libraries are required
 - whether correct versions can be found,
 - loads them into memory, and
 - performs symbol resolution
 between the main executable and the shared libraries
 - this is the runtime loading step, often also called dynamic linking
 - on Linux, dynamic loader is a part of libc (GLIBC, uClibc and musl each have their own loader).

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and-called-at-both-called-at-both-compile-time-and-called-at-both

TOC: Linking for dynamic executables / libraries

- Build-time linking for dynamic executables / libraries
- Load-time linking for dynamic executables / libraries

TOC: Build-time linking for dynamic executables / libraries

- Unresolved symbols
- Referenced libraries
- Copy relocation and symbol table
- PLT thunks
- Dynamic symbol table
- Dynamic relocation table
- Converted relocation types

Unresolved symbols

- unresolved symbols in a dynamic execuble
 - should be resolved
- unresolved symbols in a shared library
 - remain valid

Referenced libraries

- 1d stores the needed library in a DT_NEEDED record of the _DYNAMIC object of the output file
 - When the application starts, the dynamic linker looks at the DT_NEEDED field to find the required libraries.
 This field contains the soname of the library, so the next step is for the dynamic linker to walk through all the libraries in its search path looking for it.

http://bottomupcs.sourceforge.net/csbu/x4012.htm https://stackoverflow.com/questions/19736853/what-does-ld-do-when-linking-against

Copy relocation and symbol table

- If the output is <u>not</u> position-independent and references *data* objects in the shared library,
 - generate a copy relocation to copy the original image of the object into the main program's data segment at load time,
 - create a proper symbol table entry
 so that references to the object in the shared library itself
 get resolved to the new copy in the main program,
 rather than the original copy in the library.

PLT thunks

- generating PLT thunks
 for the destination of each function call in the output
 - remain unresolved at build-time

https://stackoverflow.com/questions/19736853/what-does-ld-do-when-linking-against

Dynamic symbol table

- creating a dynamic symbol table,
 - the runtime linker ld.so can use dynamic symbol table to link the executable against the library at run-time
- To see details:

```
objdump -T myprog (--dynamic-syms)
```

Dynamic relocation table

- creating the dynamic relocation table to check which machine code locations need to be changed to point toynamically linked symbols.
- To see details:

```
objdump -R myprog (--dynamic-reloc)
```

Converted relocation types

- that 1d takes object files with various relocation types
 - representing anything the compiler or assembler can produce
- resolves most of them except a small number of relocation types
 - for static linking, unresolved relocations are not allowed
 - for dynamic linking, all the remaining relocations shall be <u>converted</u> into a limited set of relocation types shall be resolved by the dynamic linker at load time.

initializing and terminating routines

- Dynamic objects may supply code for
 - runtime initialization processing
 - this code is executed once each time the dynamic object is loaded in a process
 - runtime termination processing
 - this is executed once each time the dynamic object is <u>unloaded</u> from a process or at <u>process termination</u>

https://docs.oracle.com/cd/E19253-01/817-1984/chapter2-48195/index.html

related sections for initializing and terminating routines

- an array of function pointers
 - .preinit_array section : arrays of runtime pre-initialization
 - .init_array section : arrays of initialization
 - .fini_array section : arrays of termination
- 2 a single code block.
 - .init section : a runtime initialization code block
 - .fini section : a runtime termination code block
 - Each of these section types is built from a <u>concatenation</u> of like sections from the input relocatable objects.

https://docs.oracle.com/cd/E19253-01/817-1984/chapter2-48195/index.html

Making an array of function pointers

- the link editor identifies these arrays with the .dynamic tags
 - DT_PREINIT_ARRAY and DT_PREINIT_ARRAYSZ
 - DT_INIT_ARRAY and DT_INIT_ARRAYSZ
 - DT_FINI_ARRAY and DT_FINI_ARRAYSZ

so that they may be called by the runtime linker

 functions that are assigned to these arrays must be provided from the object that is being built.

https://docs.oracle.com/cd/E19253-01/817-1984/chapter2-48195/index.html

Making a single code block

- the compiler drivers typically supply .init and .fini sections with <u>files</u> they add to the beginning and end of your input file list.
- these compiler provided <u>files</u> have the effect of <u>encapsulating</u> the .init and .fini code from your relocatable objects into individual functions
 - the function identified by the symbol _init
 - the function identified by the symbol _fini
- the link-editor identifies these symbols with the .dynamic tags
 - DT_INIT
 - DT_FINI

so that they may be <u>called</u> by the <u>runtime linker</u>

 $\verb|https://docs.oracle.com/cd/E19253-01/817-1984/chapter2-48195/index.html|$

TOC: Load-time linking for dynamic executables / libraries

- At the link time
- ld-linux.so vs. ld.so
- glibc
- ld-linux.so

$\left(1\right)$ dynamic applications

- a dynamic applications (binary, executable)
 - consist of one or more dynamic objects
 - typically a <u>dynamic</u> <u>executable</u> and one or more <u>shared</u> <u>object</u> <u>dependencies</u>
- run time linker for dynamic objects

https://renenyffenegger.ch/notes/development/dynamic-loader https://docs.oracle.com/cd/E19253-01/816-5165/ld.so.1-1/index.html

(2) search shared libraries

- to see the shared object libraries used by a given <u>application</u> use the <u>ldd</u> command
- shared library directories
 - /lib
 - /usr/lib.
- additional search directory
 - /etc/ld.so.conf can be used to configure the dynamic loader to search for other directories (eg. /usr/local/lib or /opt/lib)

https://renenyffenegger.ch/notes/development/dynamic-loader https://docs.oracle.com/cd/E19253-01/816-5165/ld.so.1-1/index.html

(3) 1dd print shared object dependencies

- 1dd prints the shared objects (shared libraries) required by each program or shared object specified on the command line.
- An example of its use and output is the following:

```
$ ldd /bin/ls
linux-vdso.so.1 (0x00007ffcc3563000)
libselinux.so.1 => /lib64/libselinux.so.1 (0x00007f87e5459000)
libcap.so.2 => /lib64/libcap.so.2 (0x00007f87e5254000)
libc.so.6 => /lib64/libc.so.6 (0x00007f87e4e92000)
libpcre.so.1 => /lib64/libpcre.so.1 (0x00007f87e4c22000)
libdl.so.2 => /lib64/libdl.so.2 (0x00007f87e4a1e000)
/lib64/ld-linux-x86-64.so.2 (0x00005574bf12e000)
libattr.so.1 => /lib64/libattr.so.1 (0x00007f87e4817000)
libpthread.so.0 => /lib64/libpthread.so.0 (0x00007f87e45fa000)
```

https://stackoverflow.com/questions/19736853/what-does-ld-do-when-linking-against

(4) loading shared libraries

- most modern programs are dynamically linked
- when a dynamically linked application is <u>loaded</u> by the operating system kernel
- the dynamic loader must <u>locate</u> and <u>load</u>
 the dynamic libraries it needs for execution.

https://www.cs.virginia.edu/~dww4s/articles/ld_linux.html

(5) interpreter

- As part of the *initialization* and *execution*of a dynamic application, an *interpreter* is called
 - to run the executable, an interpreter program is used
- this interpreter completes
 the binding of the application
 to its shared object dependencies.

(6) ld-linux.so vs. ld.so

- The programs ld.so and ld-linux.so
 <u>find</u> and <u>load</u> the shared libraries require by a program,
 prepare the program to run, and then run it.
- linux binaries require dynamic linking (linking at run time)
 unless the -static option was given to ld(1) during compilation.

ld.so	a.out	
ld-linux.so	ELF	
/lib/ld-linux.so.1		libc5
/lib/ld-linux.so.2		glibc2

https://linux.die.net/man/8/ld-linux

(7) specifying an interpreter

- ELF allows executables to specify an interpreter,
 - the compiler and static linker set the interpreter of executables
 - the interpreter is set to be /lib/ld-linux-ia64.so.2 which is the dynamic linker
- when the kernel loads the binary executable
 - it will check if the PT_INTERP field is present
 - if so load what it points to into memory and start it.

(8) dynamic linker name

- linux's dynamic loader / linker
 - ld.so for a.out
 - ld-linux.so for ELF
 - Id-linux.so.2 for glibc
 - /lib/ld-linux.so.2
 - /lib/ld-linux-x86-64.so.2
- finding the name of the dynamic loader with readelf -l executable | grep interpreter
 - readelf -1 dsplays the information contained in the file's segment headers

https://www.cs.virginia.edu/~dww4s/articles/ld_linux.html

(9) executing an interpreter

- indirect execution
 by running some dynamically linked program or shared object
 - the dynamic linker is specified in the .interp section of an ELF file (program)
 - no command-line options to the dynamic linker
- direct execution by the command-line
 - /lib/ld-linux.so.* [OPTIONS] [PROGRAM [ARGUMENTS]]

man ld-linux.so

(10) managing shared libraries

- The dynamic linker is the program that manages shared dynamic libraries on behalf of an executable.
 - load libraries into memory
 - modify the program at runtime (resolving relocation)
 - <u>call</u> the functions in the library

(11) relocations

- dynamically linked executables leave behind references that will be fixed at the runtime
 - eg. the address of a function in a shared library.
 - the references that are left behind are called relocations
- the essential part of the dynamic linker is fixing up these unresolved addresses at runtime,
 - these addresses can be known only when the executable and shared libraries are loaded in memory

(12) resolving relocations

- A relocation can simply be thought of as a <u>note</u> that a particular <u>address</u> will need to be <u>fixed</u> at the <u>load time</u> of the <u>runtime</u>
- before the code is ready to run all the relocations need to be resolved
 - fixing the addresses it refers to to point to the right place.

(13) base address

- the <u>executable</u> code is <u>not</u> shared, and each executable gets its own fresh <u>address</u> space
 - in an executable file, the <u>code</u> and <u>data</u> <u>segments</u> are given by a <u>base address</u> in <u>virtual memory</u>
 - the compiler knows exact location of the data section and can reference it directly
- shared libraries have no such guarantee.
 - the data section will be a specified as an offset from the base address
 - but exact location of the base address can only be known at runtime



(14) PIC

- all the shared libraries must be produced as position independent codes (PIC).
- note that the data section is still specified as a fixed offset from the code section;
- but to actually find the <u>address</u> of <u>data</u>
 the <u>offset</u> needs to be added to the <u>load</u> address

(15) SONAME

- the string written to the <u>executable</u> will actually be the <u>SONAME</u> of the library, e.g. mylib.so.0
- This will ensure that even when a <u>newer</u> and <u>incompatible</u> mylib.so.1.42 is installed later, the executable will use the compatible ABI version 0 instead.
 - To see details:ldd myprog

(16) Symbolic link

- Usually dynamic libraries are set up using symlinks only
 - libfoo.so is used by ld, and
 - libfoo.so points to libfoo.so.1 or to whatever which is used by ld.so, and
 - libfoo.so is itself typically a symlink to the currently-installed version of the library, e.g. libfoo.so.1.2.3

 $\verb|https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are also as the control of t$

(17) libc

- libc implements both standard C functions like strcpy() and POSIX functions (which may be system calls) like getpid() Note that not all standard C functions are in libc
 - most math functions are in libm

https://stackoverflow.com/questions/11372872/what-is-the-role-of-libcglibc-in-our

(18) System calls and thunks

- system calls is different from normal functions because they <u>call to the kernel</u> they can't be resolved by the linker
- architecture-specific assembly language thunks are used to call into the kernel
- libc provides those assembly language thunks

https://stackoverflow.com/questions/11372872/what-is-the-role-of-libcglibc-in-our

(19) libc and glibc

- in Linux, it is the combination of the kernel and libc that provides the POSIX API
- libc is a single library file (both .so and .a versions are available) in most cases resides in /usr/lib
- the glibc (GNU libc) project provides more than just libc it also provides the libm and other core libraries like libpthread
- So libc is just one of the libraries provided by glibc and there are other alternate implementations of libc other than glibc

https://stackoverflow.com/questions/11372872/what-is-the-role-of-libcglibc-in-our

(20) glibc

- C library described in ANSI,c99,c11 standards.
 - includes macros, symbols, function implementations etc.
 - printf(), malloc() etc
- 2 POSIX standard library.
 - the "userland" glue of system calls. (open(), read() etc)
 - no actual implementations of system calls (kernel does it)
 - but glibc provides the user land interface to the services provided by kernel so that user application can use a system call just like a ordinary function.
- Also some nonstandard but useful stuff.

https://linux.die.net/man/8/ld-linux

(21) libc.so

- libc.so is usually a linker script
 - pointing to
 - the 64-bit C library (dynamic or shared)
 - dynamic linker
 - used to link 64-bit executables at the build-time
 - provides instructions for 1d

https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are

(22) Linker script

- In the GNU C library's case dynamically linked programs still need some symbols from the <u>static library</u> so a <u>linker script</u> is used instead so that the linker can try both (dynamic linking and static linking)
- the linker script also <u>refers</u> to the <u>dynamic linker</u> which will be used at the <u>runtime</u>
 (/lib/x86_64-linux-gnu/ld-linux-x86-64.so.2)
 its name is embedded in executables in .interp

https://unix.stackexchange.com/questions/449107/what-differences-and-relations-are