

Digital Signal Octave Codes (0A)

- Periodic Conditions

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Based on

M.J. Roberts, Fundamentals of Signals and Systems

S.K. Mitra, Digital Signal Processing : a computer-based approach 2nd ed

S.D. Stearns, Digital Signal Processing with Examples in MATLAB

A Cosine Waveform

```
n = [0:29];  
x = cos(2*pi*(n/10));
```

$$nT_s = n \cdot \frac{1}{10}$$

```
x = cos((2/10)*pi*n);
```

$$nT_s = n \cdot 1$$

$$\omega_0 nT_s = 2\pi f_0 nT_s = \frac{2\pi}{T_0} nT_s = 2\pi n \frac{T_s}{T_0}$$

$$\omega_0 t = 2\pi f t$$

$$\omega_0 nT_s = 2\pi f_0 nT_s = 2\pi \cdot 1 \cdot n \cdot \frac{1}{10}$$

$$\omega_0 nT_s = 2\pi f_0 nT_s = 2\pi \cdot \frac{1}{10} \cdot n \cdot 1$$

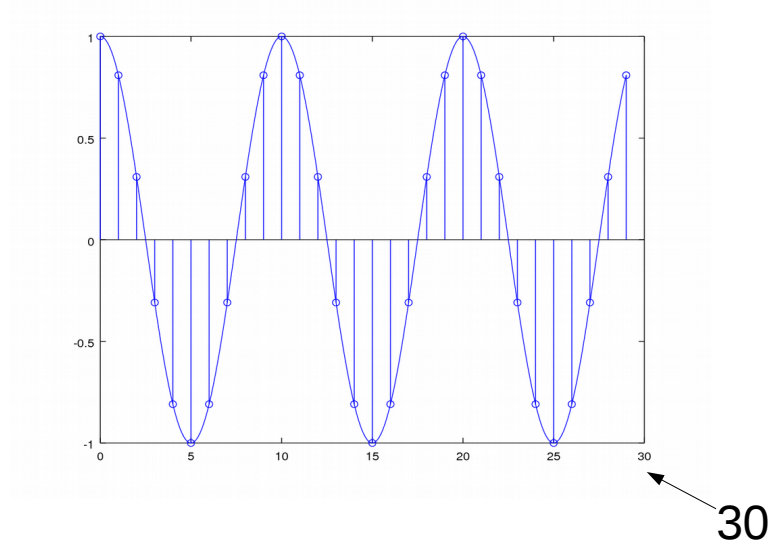
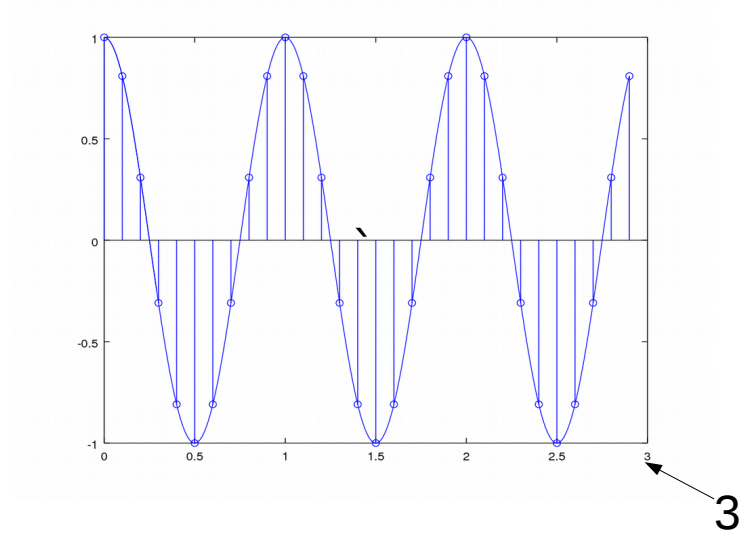
$$f_0 = 1 \quad T_0 = 1 \quad T_s = 0.1$$

$$f_0 = 0.1 \quad T_0 = 10 \quad T_s = 1$$

Many waveforms share the same sampled data

x

1.00000
0.80902
0.30902
-0.30902
-0.80902
-1.00000
-0.80902
-0.30902
0.30902
0.80902
1.00000
0.80902
0.30902
-0.30902
-0.80902
-1.00000
-0.80902
-0.30902
0.30902
0.80902
1.00000
0.80902
0.30902
-0.30902
-0.80902
-1.00000
-0.80902
-0.30902
0.30902
0.80902



U of Rhode Island, ELE 436, FFT Tutorial

Cosine Wave 1

```
n = [0:29];  
x = cos(2*pi*n/10);
```

```
t = [0:29]/10;  
y = cos(2*pi*t);  
stem(t, y)  
hold on  
t2 = [0:290]/100;  
y2 = cos(2*pi*t2);  
plot(t2, y2)
```

```
t = [0:29];  
y = cos(0.2*pi*t);  
stem(t, y)  
hold on  
t2 = [0:290]/10;  
y2 = cos(0.2*pi*t2);  
plot(t2, y2)
```

$$\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0} \quad f_0 = 1 \quad T_0 = 1 \quad T_s = 0.1$$

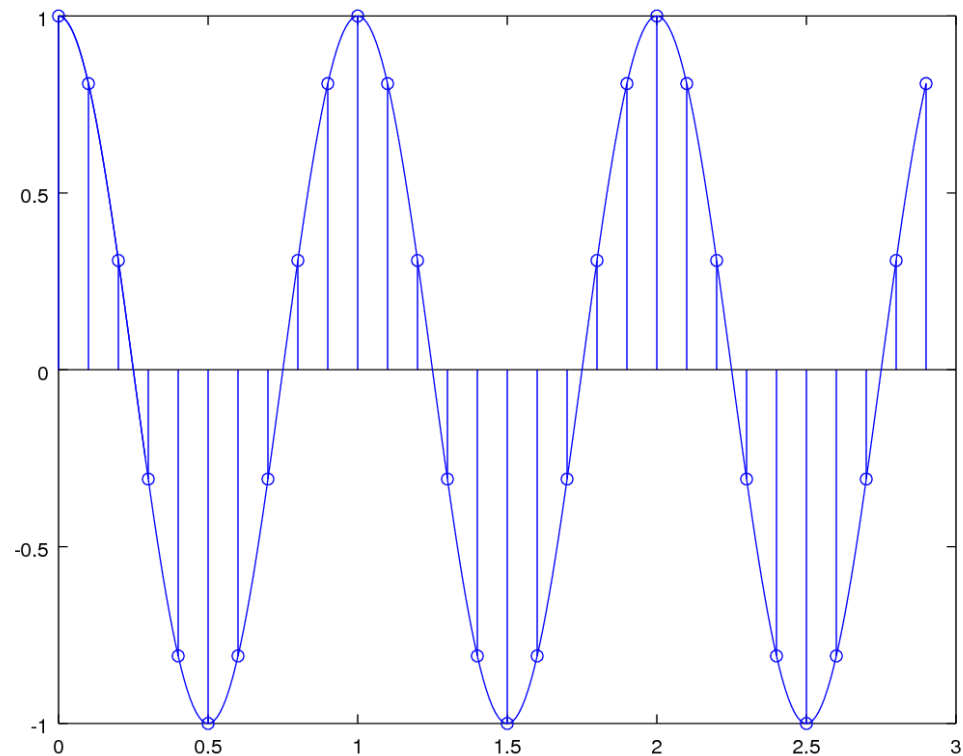
$$\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0} \quad f_0 = 0.1 \quad T_0 = 10 \quad T_s = 1$$

Cosine Wave 1

```
n = [0:29];  
x = cos(2*pi*n/10);
```

$$\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0} \quad f_0 = 1 \quad T_0 = 1 \quad T_s = 0.1$$

```
t = [0:29]/10;  
y = cos(2*pi*t);  
stem(t, y)  
hold on  
t2 = [0:290]/100;  
y2 = cos(2*pi*t2);  
plot(t2, y2)
```



U of Rhode Island, ELE 436, FFT Tutorial

Cosine Wave 2

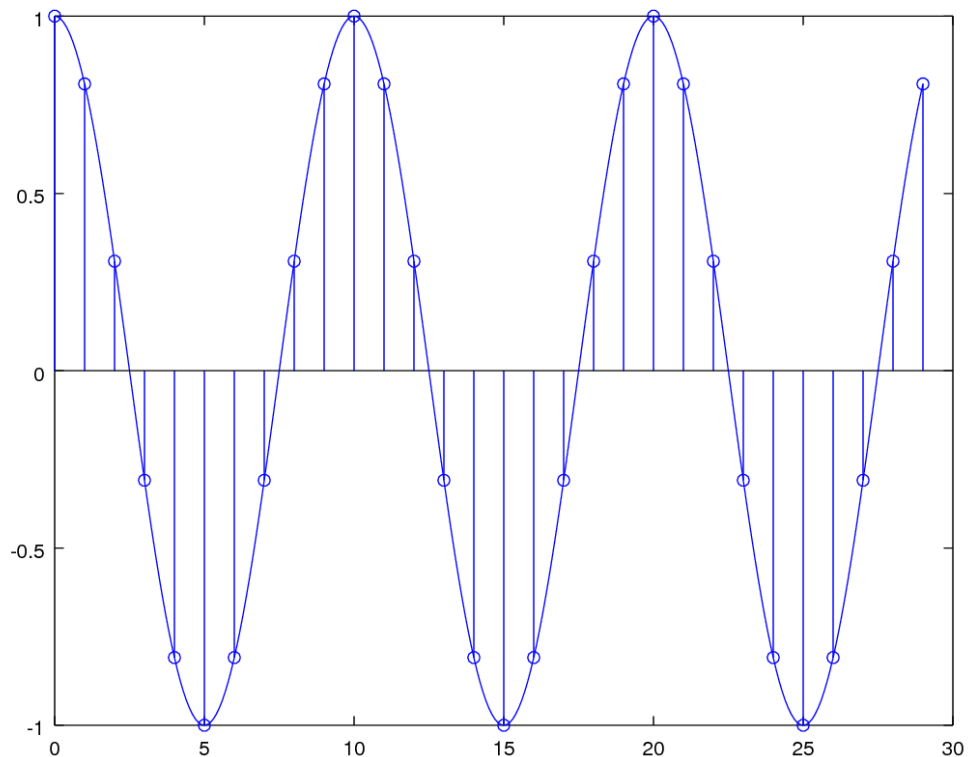
```
n = [0:29];  
x = cos(2*pi*n/10);
```

$$\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0} \quad f_0 = 0.1 \quad T_0 = 10 \quad T_s = 1$$

```
t = [0:29];  
y = cos(0.2*pi*t);  
stem(t, y)  
hold on  
t2 = [0:290]/10;  
y2 = cos(0.2*pi*t2);  
plot(t2, y2)
```

$$\omega_0 n T_s = 2\pi f_0 n T_s = 2\pi \cdot \frac{1}{10} \cdot n \cdot 1$$

$$f_0 = 0.1 \quad T_0 = 10 \quad T_s = 1$$



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Sampled Sinusoids

$$g[n] = A e^{\beta n}$$

$$g[n] = A z^n \quad z = e^{\beta}$$

$$g[n] = A \cos(2\pi n/N_0 + \theta)$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$g[n] = A \cos(\Omega_0 n + \theta)$$

$$1/N_0$$

$$= F_0$$

$$= \Omega_0/2\pi$$

$$2\pi/N_0$$

$$= 2\pi F_0$$

$$= \Omega_0$$

M.J. Roberts, Fundamentals of Signals and Systems

Sampling Period and Frequency

$$g(t) = A \cos(2\pi f_0 t + \theta)$$

$$g[n] = g(nT_s)$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$g(nT_s) = A \cos(2\pi f_0 T_s n + \theta)$$

$$F_0 = f_0 T_s = f_0 / f_s$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$T_s = \frac{1}{f_s}$$

sampling period

$$\frac{1}{T_s} = f_s$$

sampling frequency
sampling rate

M.J. Roberts, Fundamentals of Signals and Systems

Periodic Condition of a Sampled Signal

$$2\pi F_0 n = 2\pi m$$

$$F_0 n = m \quad \text{Integers } n, m$$

$$F_0 = \frac{m}{n}$$

$$F_0 = \frac{m}{n} = \frac{f_0}{f_s} \quad \begin{array}{l} \text{Fundamental Frequency} \\ \text{Sampling Frequency} \end{array}$$

$$\text{Rational Number } F_0 = \frac{m}{n}$$

$$g(nT_s) = A \cos(2\pi f_0 T_s n + \theta)$$

$$F_0 = f_0 T_s = f_0 / f_s$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

Periodic Condition Examples

$$g(t) = A \cos(2\pi f_0 t + \theta)$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$g[t] = 4 \cos\left(\frac{72\pi t}{19}\right) = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot t\right)$$

$$g[n] = 4 \cos\left(\frac{72\pi n}{19}\right) = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot n\right) \quad T_s = 1$$

$$g(t) = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (t + T_0)\right)$$

$$T_0 = \frac{19}{36} \quad \text{Fundamental Period of } g(t)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (n + N_0)\right)$$

$$N_0 = 19 \quad \text{Fundamental Period of } g[n]$$

$$N_0 \neq \frac{1}{F_0} \quad \frac{N_0}{q} = \frac{1}{F_0} \quad \frac{q}{N_0} = F_0$$

M.J. Roberts, Fundamentals of Signals and Systems

Periodic Condition Examples

$$g(t) = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (t + T_0)\right) \quad T_0 = \frac{19}{36} \quad \text{Fundamental Period of } g(t)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (n + N_0)\right) \quad N_0 = 19 \quad \text{Fundamental Period of } g[n]$$

$$F_0 = \frac{36}{19} = \frac{q}{N_0}$$

← the number of cycles in N_0 samples
← the smallest integer : fundamental period

$$N_0 \neq \frac{1}{F_0} \quad \frac{N_0}{q} = \frac{1}{F_0} \quad \frac{q}{N_0} = F_0$$

M.J. Roberts, Fundamentals of Signals and Systems

Periodic Condition Examples

$$F_0 = \frac{36}{19} = \frac{q}{N_0}$$

← the number of cycles in N_0 samples
← the smallest integer : fundamental period

“When F_0 is not the reciprocal of an integer ($q=1$), a discrete-time sinusoid may not be immediately recognizable from its graph as a sinusoid.”

Periodic Condition Examples

$$g[n] = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (n + N_0)\right)$$

$$\frac{36}{19} \cdot (n + N_0)$$

integer

$$\frac{1}{19} \cdot N_0 = k$$

integer

$$N_0$$

integer

$N_0 = 19$ Fundamental period of $g[n]$

$$g(t) = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot (t + T_0)\right)$$

$$\frac{36}{19} \cdot (t + T_0)$$

integer

$$\frac{36}{19} \cdot T_0 = k$$

integer

$$T_0$$

~~integer~~

$T_0 = \frac{19}{36}$ Fundamental period of $g(t)$

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Periodic Condition Examples

$$g[n] = 4 \cos\left(2\pi \cdot \frac{1}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{2}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{3}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot n\right)$$

```
clf
n = [0:36]; t = [0:3600]/100;
y1 = 4*cos(2*pi*(1/19)*n);
y2 = 4*cos(2*pi*(2/19)*n);
y3 = 4*cos(2*pi*(3/19)*n);
y4 = 4*cos(2*pi*(36/19)*n);
yt1 = 4*cos(2*pi*(1/19)*t);
yt2 = 4*cos(2*pi*(2/19)*t);
yt3 = 4*cos(2*pi*(3/19)*t);
yt4 = 4*cos(2*pi*(36/19)*t);
```

```
subplot(4,1,1);
stem(n, y1); hold on;
plot(t, yt1);
subplot(4,1,2);
stem(n, y2); hold on;
plot(t, yt2);
subplot(4,1,3);
stem(n, y3); hold on;
plot(t, yt3);
subplot(4,1,4);
stem(n, y4); hold on;
plot(t, yt4);
```

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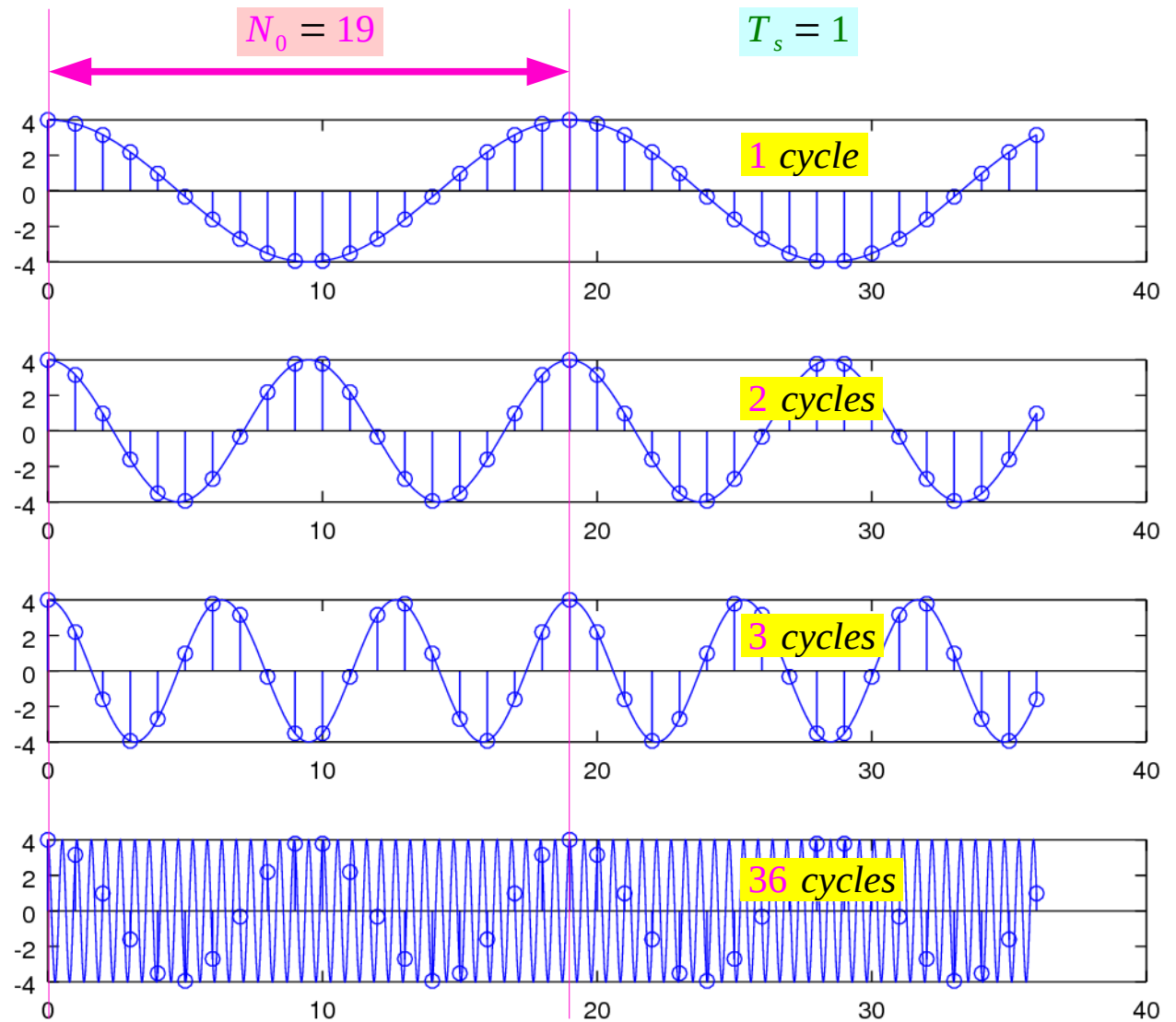
Periodic Condition Examples

$$g[n] = 4 \cos\left(2\pi \cdot \frac{1}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{2}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{3}{19} \cdot n\right)$$

$$g[n] = 4 \cos\left(2\pi \cdot \frac{36}{19} \cdot n\right)$$



Periodic Condition Examples

$$g(t) = A \cos(2\pi f_0 t + \theta)$$

$$g_1(t) = 4 \cos(2\pi \cdot 1 \cdot t)$$

$$g_2(t) = 4 \cos(2\pi \cdot 2 \cdot t)$$

$$g_3(t) = 4 \cos(2\pi \cdot 3 \cdot t)$$

$$t \leftarrow nT_1$$

$$t \leftarrow nT_2$$

$$t \leftarrow nT_3$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$g_1[n] = 4 \cos(2\pi n T_{s1})$$

$$g_2[n] = 4 \cos(2\pi n T_{s2})$$

$$g_3[n] = 4 \cos(2\pi n T_{s3})$$

$$t \leftarrow nT_1$$

$$T_1 = \frac{1}{10}$$

$$n = 0, 1, 2, 3, \dots \rightarrow 1 \cdot t = 0, 0.1, 0.2, 0.3, \dots$$

$$t \leftarrow nT_2$$

$$T_2 = \frac{1}{20}$$

$$n = 0, 1, 2, 3, \dots \rightarrow 2 \cdot t = 0, 0.1, 0.2, 0.3, \dots$$

$$t \leftarrow nT_3$$

$$T_3 = \frac{1}{30}$$

$$n = 0, 1, 2, 3, \dots \rightarrow 3 \cdot t = 0, 0.1, 0.2, 0.3, \dots$$

$$\{g_1[n]\} \equiv \{g_2[n]\} \equiv \{g_3[n]\}$$

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Periodic Condition Examples

$$g(t) = A \cos(2\pi f_0 t + \theta)$$

$$g[n] = A \cos(2\pi F_0 n + \theta)$$

$$\begin{aligned} g[n] &= 4 \cos\left(\frac{72\pi n}{19}\right) \\ &= 4 \cos\left(2\pi \left(\frac{36}{19}\right) n\right) \\ &= 4 \cos\left(2\pi \left(\frac{36}{19} \cdot (n + N_0)\right)\right) \\ &\quad \text{smallest } N_0 = 19 \end{aligned}$$

$$2\pi F_0 n = 2\pi m$$

$$\frac{36}{19} n = m$$

smallest $n = 19$

$$\frac{36}{19} = \frac{m}{n}$$

$$\frac{36}{19} = \frac{m}{n} = \frac{f_0}{f_s}$$

$$F_0 = \frac{q}{N_0}$$

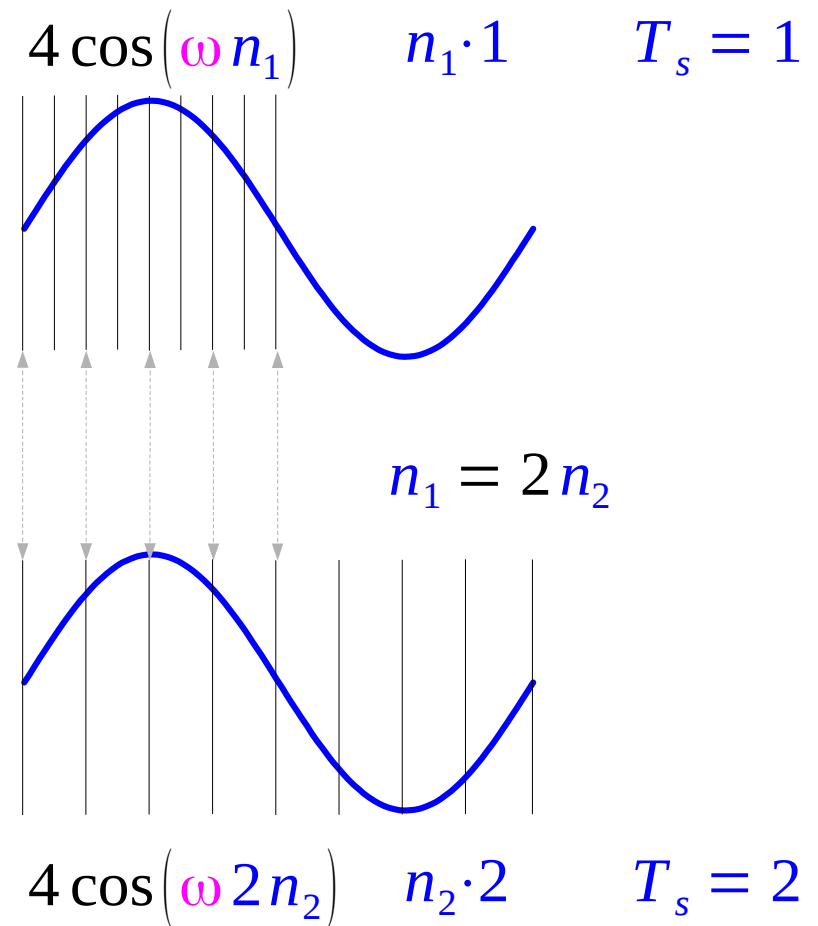
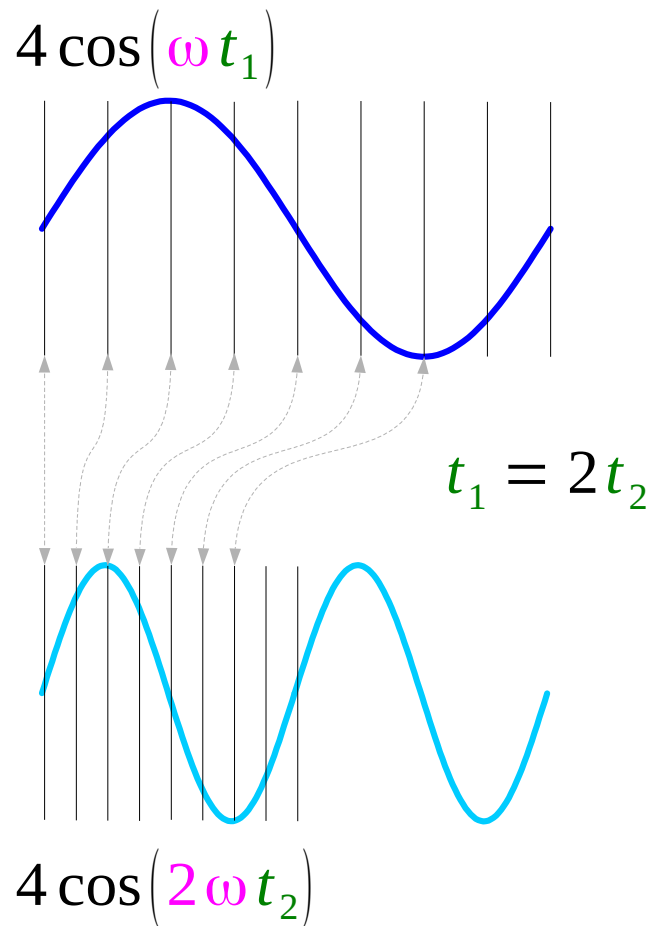
$$1/N_0$$

$$= F_0$$

$$= \Omega_0/2\pi$$

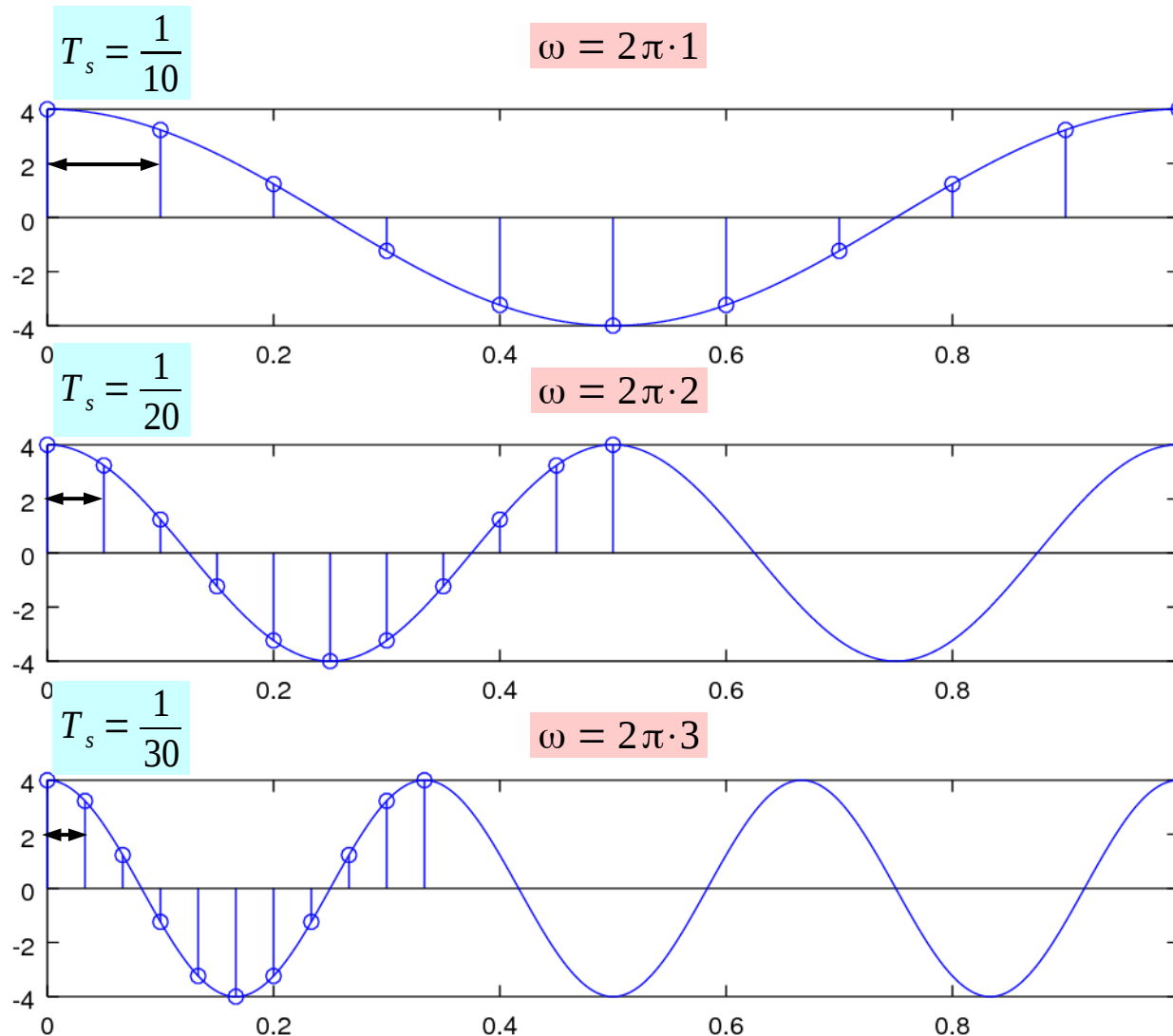
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Periodic Condition Examples



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Periodic Condition Examples



```
clf
n = [0:10]; t = [0:1000]/1000;
y1 = 4*cos(2*pi*1*n/10);
y2 = 4*cos(2*pi*2*n/20);
y3 = 4*cos(2*pi*3*n/30);
yt1 = 4*cos(2*pi*t);
yt2 = 4*cos(2*pi*2*t);
yt3 = 4*cos(2*pi*3*t);
```

```
subplot(3,1,1);
stem(n, y1); hold on;
plot(t, yt1);
subplot(3,1,2);
stem(n/20, y2); hold on;
plot(t, yt2);
subplot(3,1,3);
stem(n/30, y3); hold on;
plot(t, yt3);
```

M.J. Roberts, Fundamentals of Signals and Systems

References

- [1] <http://en.wikipedia.org/>
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003
- [3] M.J. Roberts, Fundamentals of Signals and Systems
- [4] S.J. Orfanidis, Introduction to Signal Processing
- [5] K. Shin, et al., Fundamentals of Signal Processing for Sound and Vibration Engineerings

- [6] A “graphical interpretation” of the DFT and FFT, by Steve Mann