

Processors

Young W. Lim

May 9, 2016

Copyright (c) 2016 Young W. Lim. Permission is granted to copy, distribute and/or modify this document under the terms of the GNU Free Documentation License, Version 1.2 or any later version published by the Free Software Foundation; with no Invariant Sections, no Front-Cover Texts, and no Back-Cover Texts. A copy of the license is included in the section entitled "GNU Free Documentation License".

Processor Architecture

- Instruction Set
- Microarchitecture - different implementation details
- Synthesis result with area time power tradeoff

Instruction Set

- A Register Set to hold operands and addresses
- Floating Point Registers
- A Register for Program Status Word
 - ▶ including Condition Codes (CC)
- Types
 - ▶ Load-Store (L/S)
 - ▶ Register-Memory (R/M)

Load Store Architecture

- arguments must be in registers before execution
- ALU instructions have source and destination registers
- regularity of execution
- ease of instruction decode
- ease of timing requirements
- RISC microprocessors

Register Memory Architecture

- Operands in registers
- One operand in memory
- ALU instructions can have a operand in memory
- simple program representation
 - ▶ fewer instructions with variable size (complex) instruction types
- complex instruction decoding and timing
- IBM mainframe, Intel x86 series

Branches

- Branches (jumps) handles program control flow
- Unconditional BR
- Conditional BC
 - ▶ check the status of CC
 - ▶ CC is set by an ALU instructions
 - ★ a positive result
 - ★ a negative result
 - ★ a zero result
 - ★ an overflow

Interrupt and Exceptions

- User Requested vs Coerced
- Maskable vs Nonmaskable
- Terminate vs Resume
- Asynchronous vs Synchronous
- Between vs Within Instructions

MicroArchitecture

- an instruction execution pipeline
- issue one instruction for each cycle
 - ▶ many embedded and signal processors
- issue many instructions for each cycle
 - ▶ moder desktop, laptop, server systems
- Components
 - ▶ Memory System
 - ▶ Execution Unit
 - ▶ Instruction Unit

Pipeline Delays

- Data Conflicts - Unavailability of a source operand
 - ▶ the needed operand is the result of a preceding uncompleted instruction
- Resource Contention
 - ▶ multiple successive instructions requires the same resource
- Run-On Delays (In Order Execution Only)
 - ▶ when instructions must complete the WB in program order
- Branches
 - ▶ branch resolution
 - ▶ delay in fetching the branch target instruction

Instruction Unit

- Instruction Register
- Instruction Buffer
 - ▶ for fast instruction decode
- Instruction Decoder
 - ▶ controlling the cache, ALU, registers...
 - ▶ I-Unit : FSM (hardware)
 - ▶ E-Unit : micro-programmed control, micro-instruction
- Interlock Unit
 - ▶ the concurrent execution of multiple instructions
 - ▶ must have the same result when serially executed

Instruction Decoder

- Instruction decoder provide
 - ▶ control and sequencing information
 - ▶ ensure proper execution (dependency exists between instructions)
- schedules the current instruction
 - ▶ delayed : AG (Address Generate) Cycle
- schedules the subsequent instructions
 - ▶ delayed to preserve in-order execution
- selects (predicts) the branch path

Data Interlocks

- may be part of I-Unit
- determines register dependencies
- schedules the AG and EX units
- ensures the current instruction does not use a result of a previous instruction until that result is available
- as an instruction is decoded, its source registers are must be checked
- they are compared against the destination registers previously issued instruction
- because uncompleted instructions may cause dependencies and additional delay must be added

Execution Unit

- Integer Core Processor
- Floating-point Unit
- Arithmetic Algorithms

Buffers

- change the way instruction timing events occur
- decoupling the event occurring time and the data utilizing time
- allows some additional delays without affecting the performance
- latency tolerance
 - ▶ buffers hold the data awaiting entry into a stage

Branches

- reduce significantly performance
- conditional branch instruction (BC) tests the CC
- a number of cycles between decoding the BC and setting the CC
- the simple approach
 - ▶ do nothing but wait for the CC
 - ▶ defer the decoding of BC
 - ▶ if the branch is taken
 - ★ the target is fetched during the allotted time for data fetch
 - ▶ simple to implement and minimizes the amount of excess memory traffic

Reducing the branch cost

- Simple Approaches

- ▶ Branch Elimination

- ★ for certain cases, it is possible to replace the branch with other instruction sets

- ▶ Simple Branch Speedup

- ★ reduces the time required for target instruction fetch and CC determination

- Complex Approaches

- ▶ Branch Target Capture

- ★ keep the target instruction and address in a table for a later use to avoid branch delay

- ▶ Branch Prediction

- ★ predict the branch result and begin processing on the predicted path

Branch Target Buffers (BTBs)

- stores the target instruction of the previous execution of the branch

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Data Interlocks

- may be part of I-Unit
- determines register dependencies

Reference

fgg

[1] H. B. Ahn , “Learning Embedded Linux System using ARM processors”, 2nd ed.