ELF1 7A Relocation Background - ELF Study 1999

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Outline



Overview

- 3 Relocs and memory locations
- 4 Symbols and sections
- 5 Global and local symbol relocs

6 PIC relocation

- In the code
- In the PLT
- In the GOT
- 7 Load addresses
- 8 Static and dynamic linkers

"Study of ELF loading and relocs", 1999 http://netwinder.osuosl.org/users/p/patb/public_html/elf_ relocs.html

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- gcc -v
- gcc -m32 t.c
- sudo apt-get install gcc-multilib
- sudo apt-get install g++-multilib
- gcc-multilib
- g++-multilib
- gcc -m32
- objdump -m i386

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linking in the old days

- at compile time, inter-related references are not resolved
- .o files include a reloc object that contains the information on these inter-related references
- at link time, the linker would merge these informations in .o files building a table of where symbols are ultimately located.
- the linker would run through the set of relocs, filling them in

- A reloc consists of three parts:
 - where in memory the fix is to be made
 - the symbol which is involved in the fix
 - an algorithm that the linker should use to create the fixup
- The algorithm can be as simple as R_386_32
 "use the symbol memory location; store it in binary"
- complicated, such as R_ARM_PC26
 "calculate the distance from here to the symbol, divide by 4, subtract 2 and add the result to the 3 lower bytes"

- these relocs are <u>scattered</u> through the .o files, and are used at <u>link time</u> create the correct binary executable file.
- resolving all the relocs is necessary
- in the days of static linking

run-time linking

the designers of the ELF format enabled reloc entites to hold run-time resolution information.

- So now executable files may have relocs in them, even after linking
 - ELF implements run time linking by deferring function resolution until the function is called.

- However, new algorithms are required to inform how these fixups are to be done.
- Hence the introduction of a new family of reloc algorithms

- Binary <u>executables</u> often need certain bits of information *fixed up* before they execute
- ELF binaries carry a list of relocs (relocation table) which describe these *fixups*

• Each reloc contains relocation entry

- the address in the binary that is to get the *fixup* (offset)
- the algorithm to calculate the fixup (type)
- a symbol (string and object length)

• At *fixup* time,

the algorithm (type) uses the offset & symbol, along with the value (addend) currently in the file, to calculate a new value to be <u>stored</u> into memory.

- One of the characteristics of the ELF binary system is a separation of code and data.
- The code of apps and libraries is marked read-only and executable
- The data is marked read-write, and not-executable.

• The code is read-only

so that multiple processes can share the code,

- the code is loaded into memory only once.
- the code is <u>never</u> modified, and appears <u>identical</u> in each process space.

- Each process has its <u>own page tables</u>, mapping the code into its <u>own memory</u>.
 - therefore the code must be position independent
 - each process can load the code into a different address
- The code segment is allowed to contain constant pointers and strings (.rodata).

- The data segment is read-write and is mapped into each process space differently.
- In Linux, each data segment is loaded from the same base mmap (identical), but it is marked copy-on-write (own copy later)

- after the <u>first write</u>, each process has its <u>own copy</u> of the data. (in its own read-write segment)
- therefore, relocs can only point to the data segment (_identically_)

• the relocs in the data segment are *easy* to be done

- add relative offsets or
- write absolute addresses
- the relocs in the code area are more difficult.
 - the ELF reloc design makes the code relocs intact
 - an GOT <u>entry</u> in the data area is to be filled, (Global Offset Table).

- if code needs to refer to a global object, it refers to an entry in the GOT[],
 - at <u>run-time</u>, the <u>GOT</u> <u>entry</u> is *fixed-up* to point to the <u>correct</u> address of the global object.
 - the code space need <u>never</u> be *fixed-up* at <u>run time</u>.

- if the code needs to refer to a local object, it refers to it relative to the &GOT[0];
 - no run-time fixed-up
 - this too is position independent

- If the code needs to jump to a subroutine in a different module, the linker creates an array of jump-stubs called the PLT (procedure linkup table)
- these jump-stubs in the PLT jump indirect, using an entry in the GOT[] to implement the far call

- ELF implements run time <u>linking</u> by <u>deferring</u> <u>function</u> resolution until the function is called.
- calls to library functions go through a *fix-up* process just after the first time call is made

- GOT-relative (GOTOFF) code is made relative to the start of the GOT table (O)
- relative to the load address of the module (X)

• static variables

- initialized at <u>compile</u> time, since their <u>address</u> is known and fixed.
- initialization to zero does not incur a run time cost

automatic variables

- initialized at <u>run</u> time incurs run time <u>cost</u> each time the function is called
- different addresses for each different call
- if you do need that initialization, then request it.

https://stackoverflow.com/questions/14049777/why-are-global-variables-always-init

• global and static variables are stored

- in the .data section when initialized
- in the .bss section when uninitialized
- a fixed memory location is allocated at compile time.
- thus, have '0' as their default values.

• auto variables are stored

- on the stack, not a fixed memory location
- stack memory is allocated at run time
- thus, have their default value as garbage

https://stackoverflow.com/questions/14049777/why-are-global-variables-always-init

- an object with automatic storage duration if not initialized explicitly, its value is indeterminate
- an object that has static storage duration if not initialized explicitly, then:
 - if it has pointer type, a null pointer;
 - if it has arithmetic type, (signed or unsigned) zero;
 - if it is an aggregate, every member is initialized
 - if it is a union, the first named member is initialized

https://stackoverflow.com/questions/13251083/the-initialization-of-static-variable

- the universal zero initializer
 - initializes everything in an object to 0, whether it's static or not
 - sometype $var = \{0\};$
 - someothertype var[SOMESIZE] = {0};
 - anytype var[SIZE1][SIZE2][SIZE3] = {0};

https://stackoverflow.com/questions/18251083/the-initialization-of-static-variable

- static variables (or arrays)
 - Initialized static variables
 - given value from code at compile time
 - usually stored in .data though this is compiler specific
 - Uninitialized statics
 - initialized at run time
 - stored into .bss though again this is compiler specific

https://stackoverflow.com/questions/13251083/the-initialization-of-static-variable

- The .bss section is guaranteed to be all zeros when the program is loaded into memory.
- the .bss section can have global data
 - uninitialized
 - initialized to zero

• static int g_myGlobal = 0; // <--- in .bss section

https://stackoverflow.com/questions/16557677/difference-between-data-section-and-

- the .bss section data are not included in the ELF file on disk
 - there isn't a whole region of zeros in the file for the .bss section
- instead, the loader knows from the section headers how much to allocate for the .bss section, and simply zero it out before transfer control

https://stackoverflow.com/questions/16557677/difference-between-data-section-and-

• the readelf -S section headers output:

[3] .data PROGBITS 0000000 000110 000000 00 WA 0 0 4 [4] .bss NOBITS 0000000 000110 000000 00 WA 0 0 4

• .data is marked as **PROGBITS**

- there are "bits" of program data in the ELF file that the loader needs to read out into memory
- .bss is marked NOBITS
 - there's nothing in the file that needs to be read into memory as part of the load.

https://stackoverflow.com/questions/16557677/difference-between-data-section-and-

- a list of locations in the .text section to be modified when the linker combines this object file with others
- <u>modify</u> any instruction in the code section that
 - calls an external function or
 - references a global variable
- do not modify any instructions in the code section that
 - calls local functions
- <u>executable</u> files do <u>not</u> include relocation information unless the user explicitly instructs the linker

- relocation information for any global variable that are referenced or defined by the module
- <u>modify</u> the initial value of any initialized global variable whose initial value is
 - the address of a global variable or
 - externally defined function

- global relocs must neccessarily involve the three aspects of a reloc:
 - where in memory the reloc is to be made
 - the symbol involved in the reloc
 - the algorithm used to make the fixup.

- a local symbol can be <u>fixed</u> in memory with respect to a memory "section",
- the object file is allowed to drop the local symbol name, and replace it with a section-plus-offset

.section .text		
	mov	r0, r0 @sample code
.L2:	call	_do_something
	ldr	r6, .L3 @this code need a reloc!
	mov	r0, r0
.L4:	.word	Lextern
.L3:	.word	.L2 Othis read-only data needs a reloc

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- the code on the 3rd line (the call) needs to be fixed up, but that's easy, since it's a PC relative fixup.
 - .L2: call _do_something
- If the .o file has no idea where .Lextern is,
 - .L4: .word Lextern

it must neccessarily create a reloc which refers to symbol Lextern

.L4: .word 0 R_ARM_32 Lextern

• the word at .L3 needs a fixup as well.

.L3: .word .L2 @this read-only data needs a reloc

- If the .o file can determine the location of a local symbol, such as L2, then it is allowed to <u>replace</u> the symbol with a <u>section-plus-offset</u>
- The offset is stored in the reloc target address, and the section is an entry in the reloc symbol table

.L3: .word 4 R_ARM_32 .text

• This reduces the number of symbols in the symbol table, making run-time linking easier.

- the R_*_GOTOFF and R_*_GOT32 relocs include
 - R_386_GOTOFF : GOT-relative, local symbol address
 - R_386_GOT32 : GOT-relative, GOT entry address

an <u>offset</u> from &GOT[0], which is usually about halfway through the module.

• The R_ARM_RELATIVE relocs, on the other hand, contains an offset from the beginning of the module. Tradition.

• ELF dynamic linking <u>defers</u> the <u>resolution</u> of jump / call <u>addresses</u> until the last minute.

Constraints

- should not force a change in the assembly code produced for apps but may cause changes as an assembly code is changed for PIC
- all <u>executable codes</u> must <u>not</u> be <u>modified</u> at run time any <u>modified data</u> must <u>not</u> be <u>executed</u> at run time

- start in the code
- 2 go through the PLT
- using a pointer from the GOT
 - the GOT entries that are used for PLT execution are preloaded to <u>default</u> addresses
 - back to the corresponding PLT entry stub
 - push and jmp PLT[0] sequence

call function_call_n

- the *relative* jump or call
- the target is a PLT entry PLT[n+1]
 - it is (n+1)-th entry not n-th entry
 - consider that PLT[0] is a special entry
- identical to a normal call
- assume n is a number

- the PLT is a synthetic area, created by the linker
- exists in both executable and libraries
- an array of stubs, one per imported function call
- through the special entry PLT[0], the resolver is called at last

```
PLT[n+1]: jmp *GOT[n+3]
push #n ; push n as a argument to the resolver
jmp PLT[0]
```

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• a call to PLT[n+1] will result in *indirect call* through GOT[n+3]

• because of three special GOT entries : GOT[0,1,2]

jmp *GOT[n+3] ; 6-byte long

- initially, the value at GOT[n+3] points back to PLT[n+1]+6
 - the default value at GOT[n+3] is PLT[n+1]+6
 - the next instruction after the 6 byte instruction

PLT[n+1]: jmp *GOT[n+3] ; 6 bytes insturction PLT[n+1]+6: push #n ; push n as a argument to the resolver jmp PLT[0]

http://netwinder.osuosl.org/users/p/patb/public_html/elf_relocs.html

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- at PLT[n+1], n is pushed onto the stack as an argument for the resolver
- consider n as an ID for a library function
- the resolver uses the argument n on the stack in resolving the symbol n

PLT[n+1]: jmp *GOT[n+3] ; 6 bytes insturction PLT[n+1]+6: push #n ; push n as a argument to the resolver jmp PLT[0]

(4) overriding the default GOT[n+3]

- the resolver is called by the stub at PLT[0]
- the resolver modifies the default value at GOT[n+3] to point the correct target symbol n
- overrides PLT[n+1]+6 (the default value at G[n+3])
- thus after the first call, the control is taken directly to the correct target symbol n (function_call_n) instead of executing the push-jump sequence

PLT[n+1]: jmp *GOT[n+3] ; 6 bytes insturction PLT[n+1]+6: push #n ; push n as a argument to the resolver jmp PLT[0]

(5) the special entry PLT[0]

• the resolver needs 2 argument

- symbol n is already on the stack
- pointer to the relocation table : GOT[1]
- &GOT[1] is added on the stack
- the resolver that is located in Id-linux.so.2 can determine *which library function* is asked for its service using these two arguments on the stack
- GOT[2] : entry point of dynamic linker

PLT[0]: push &GOT[1] jmp GOT[2] ; entry point of dynamic linker

- if an object file participates in dynamic linking, its program header table will have an element of type PT_DYNAMIC.
- this segment contains the .dynamic section.
- A special symbol, <u>DYNAMIC</u>, labels the section, which contains an array of the dynamic structures

https://docs.oracle.com/cd/E23824_01/html/819-0690/chapter6-42444.html

- _ DYNAMIC symbol enables a program, such as the runtime linker, to <u>locate</u> its own dynamic structure without having yet processed its relocation entries
- this method is especially important for the runtime linker, because it must <u>initialize</u> itself <u>without</u> relying on other programs to relocate its memory image.

https://docs.oracle.com/cd/E23824_01/html/819-0690/chapter6-74186.html

- essentially holds a number of arguments that inform on influence parts of the dynamic linker's behavior
- as a component of the run-time, the dynamic linker does many other things besides just relocate functions, it also executes other house keeping functions like INIT and FINI
- see elf/elf.h

http://blog.k3170makan.com/2018/11/introduction-to-elf-format-part-vii.html

 .dynamic section contains information that the dynamic linker uses to <u>bind</u> procedure addresses such as the symbol table and relocation information

Computer Architecture : A Programmer's Perspective

- the GOT contains *helper pointers* for both PLT fixups and GOT fixups
 - the first 3 entries are special and reserved
 - the next M entries belong to the PLT fixups
 - the next D entries belong to various data fixups
- the GOT is a synthetic area, createdy by the linker exists in both executables and libraries
- each library and executable gets its own PLT and GOT array

- the special 3 entries in the GOT
- GOT[0] : linked list pointer used by the dynamic linker address of .dynamic section
- GOT[1] : pointer to the reloc table for this module module identification info for the linker
- GOT[2] : pointer to the fixup / resolver code, located in Id-linux.so.2 entry point in dynamic linker

- when the GOT is first set up, all the GOT entries related to PLT fixups
- GOT[n+3] are pointing back to PLT[n+1]+6 which jump to PLT[0] to call the resolver

PLT[n+1]: jmp *GOT[n+3] push #n ; push n as a argument to the resolver jmp PLT[0]

(4) the PLT/data fixup GOT entries

• M entries belong to the PLT fixups

GOT[3]	indirect function call helpers
GOT[4]	indirect function call helpers
GOT[3+M-1]	indirect function call helpers,

• D entries belong to various data fixups

GOT[3+M]	indirect pointers to global data references
GOT[3+M+1]	indirect pointers to global data references
GOT[end]	indirect pointers to global data references

- in a typical Linux system, the addresses 0 - 3fff_fff (4 GB) are available for the user program space.
- <u>exectuable</u> <u>binary</u> <u>files</u> include header information that indicates a load address
- libraries, because they are position-independent, do not need a load address, but contain a 0 in this field.

Start	Len	Usage
0000_0000	4k	zero page
0000_1000	128M	not used
0800_0000	896M	app code/data space
		followed by small-malloc() space
4000_0000	1G	mmap space
		library load space
		large-malloc() space
8000_0000	1G	stack space
		working back from BFFF.FFE0

Start	Len	Usage
		stack space
8000_0000	1G	working back from BFFF.FFE0
		memory mapped region
		for shared libraries
4000_0000	1G	large-malloc() space
		small-malloc() space
0800_0000	896M	app data / code space
0000_1000	128M	not used
0000_0000	4k	zero page

Linux Run-time Memory Image (increasing from the bottom)

			memory invisible
0xc000_	0000	Kernel virtual memory	to the user code
		User <mark>stack</mark>	
		created at run time	\leftarrow %esp stack ptr
		$\downarrow \downarrow \downarrow$	
		$\uparrow \uparrow \uparrow$	
		memory mapped region	
0x4000_	0000	for shared libraries	
		$\uparrow\uparrow\uparrow$	
		Run time <mark>heap</mark>	$\leftarrow \texttt{brk}$
		created by malloc	
		R/W segment	
		(.data, .bss)	
		RO segment	
0x0804_	8000	(.init, .text, .rodata)	
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- mmap (2) is a POSIX-compliant Unix system call that maps files or devices into memory.
- a method of memory-mapped file I/O
- implements demand paging,
 - file contents are not read from disk directly
 - initially do not use physical RAM at all.
- The actual reads from disk are performed in a lazy manner, after a specific location is accessed.

https://en.wikipedia.org/wiki/Mmap



#include <sys/mman.h>

- creates a <u>new mapping</u> in the *virtual address space* of the *calling process*
- the starting address for the new mapping is specified in addr
- the length argument specifies the length of the mapping
- the contents of a file mapping are initialized using length bytes starting at offset offset in the file (or other object) referred to by the file descriptor fd

http://man7.org/linux/man-pages/man2/mmap.2.html

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- the sys_brk system call is provided by the kernel, to allocate memory without the need of moving it later
- allocates memory right behind the application image in the memory
- allows you to set the highest available address in the data section.
 - takes one parameter (the highest memory address)

https://www.tutorialspoint.com/assembly_programming/assembly_memory_management.htm

#include <unistd.h>

```
int brk(void *addr);
void *sbrk(intptr_t increment);
```

- brk() and sbrk() change the location of the program break, which defines the end of the process's data segment
- the program break is the first location after the end of the uninitialized data segment
- increasing / decreasing the program break has the effect of allocating / deallocating memory to the process;
- sbrk() increments the program's data space by increment bytes.

http://man7.org/linux/man-pages/man2/brk.2.html

- The kernel has a preferred location for mmap data objects at 0x4000_0000.
- since the shared libraries are loaded by mmap, they end up here.
- large mallocs are realized by creating a mmap, so these end up in the pool at 0x4000_0000.

- the library GLIBC that is mostly used for malloc handles small mallocs by calling sys_brk(), which extends the data area after the app, at 0x0800_0000+sizeof(app).
- As the mmap pool grows upward, the stack grows downward. between them, they share 2G bytes.

- The shared library design usually <u>loads</u> app first, then the loader notices that it need support and loads the dynamic loader library (using .interp section) (usually /lib/ld-linux.so.2) at 0x4000_0000
- other libraries are loaded after ld.so.1
- see which and where libraries will be loaded by ldd ldd foo_app

- dynamic loader
- dynamic linker
- runtime linker
- interpreter
- o ld-linux.so.2
- o ld-linux.so
- ld.so

- There is a diagnostic case where the app is invoked by /lib/ld-linux.so.2 foo_app foo_arg
 - the ld-linux.so.2 is loaded as an app
 - since it was built as a library, it tries to load at 0
 - [In ArmLinux, this is forbidden, so the kernel pushes it up to =0x1000=]
- Once ld-linux.so.2 <u>loads</u>, it <u>reads</u> it argv[1] and <u>loads</u> the foo_app at its preferred location (0x0800.0000)
- other libraries are loaded up a the mmap area.

• So, in this case, the user memory map appears as

start	Len	Usage
0000_0000	128M	ld-linux.so.2
		followed by small-malloc() space
0800_0000	896M	app code/data space
4000_0000	1G	mmap space
		lib space
		large-malloc() space
8000_0000	1G	stack space,
		working backward from BFFF_FFE0

http://netwinder.osuosl.org/users/p/patb/public_html/elf_relocs.html

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 Notice that the small malloc space is much smaller in this case, but this is supposed to be for <u>load</u> testing and <u>diagnostics</u> so it's not too bad.

• 1d is a static linker

- a static library has the suffix name .a denoting archive
- created by the ar utility

• ld.so is a dynamic linker

- so represents shared object
- a suffix name of shared libraries
- libraries that may be dynamically linked into programs
- one library is shared among several programs

https://unix.stackexchange.com/questions/356709/difference-between-ld-and-ld-so

- A static linker links a program or library at compile time usually as the last step in the compilation process, creating a binary executable or a library.
- A dynamic linker loads the libraries
 - into the process' address space at run time.
 - that were dynamically linked at compile time

https://unix.stackexchange.com/questions/356709/difference-between-ld-and-ld-so

• a statically linked binary

with all libraries loaded into the executable itself

 a dynamically linked binary with only <u>some</u> libraries statically linked

https://unix.stackexchange.com/questions/356709/difference-between-ld-and-ld-so

- When you statically link a file into an executable, the contents of that file are included at link time.
- When you dynamically link a file into an executable, a pointer to the file is included in the executable but the contents of the file are not included at link time.

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamica

statically linked vs dynamically linked (2)

- these dynamically linked files are <u>not</u> bought in until you run the executable
- they are only bought into the in-memory copy of the executable, not the one on disk.
 - no files are modified on the disk
 - a shared library is shared across several processes
- statically linked files are 'locked' to the executable at link time so they never change
- A dynamically linked file referenced by an executable can change just by replacing the file on the disk.

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamical

the vast majority of pages are exactly the same for every process

 processes a and b may load the library at different logical addresses, but they will point to the same physical pages: thus, the memory will be shared. the data in RAM exactly matches what is on disk, so it can be loaded only when needed by the page fault handler.

https://unix.stackexchange.com/questions/116327/loading-of-shared-libraries-and-ra

- most pages of the library will need link edits, and will be different.
- they must be separate physical pages (as they contain different data).
- that means they're not shared.
- the pages don't match what is on disk
- the entire library could be loaded subsequently be swapped out to disk (in the swapfile)

https://stackoverflow.com/questions/311882/what-do-statically-linked-and-dynamica

- the concept of re-entrant code, i.e., programs that cannotmodify themselves while running. it is necessary to write libraries.
- re-entrant code is useful for shared libraries
- Some functions in a library may be reentrant, whereas others in the same library are non-reentrant.
- A library is reentrant if and only if all of the functions in it are reentrant.

http://cs.boisestate.edu/~amit/teaching/297/notes/libraries-and-plugins-handout.p. https://bytes.com/topic/c/answers/528112-basic-doubt-shared-libraries

- a shared library does not need to be reentrant
- the code area of the library is shared by multiple processes
- the data area of the library is copied separately for each process
- reentrant codes are required when running in multi-thread

http://cs.boisestate.edu/~amit/teaching/297/notes/libraries-and-plugins-handout.pehttps://bytes.com/topic/c/answers/528112-basic-doubt-shared-libraries

- load-time dynamic linking is when symbols in the library that are referenced by the executable (or another library) are handled when the executable / library is loaded into memory, by the os
- run-time dynamic linking is when you use an API provided by the OS or through a library to load a .so when you need it, and perform the symbol resolution then.

https://stackoverflow.com/questions/2055840/difference-between-load-time-dynamic-

- 1d is not called at either compile or run time
- only at the link step is /usr/bin/ld is invoked.
- a link step is performed as a final step in producing an <u>executable</u>, or a <u>shared library</u>
 - this is called static linking, to differentiate this step from dynamic loading that will happen at run time
- on Linux, 1d is part of the binutils package.

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and

• The linker records

- which shared libraries are required at the run time,
- possibly which versions of libraries or symbols are required.
- which run time loader should be used
- The kernel loads executable into memory, and checks whether the run time loader was requested at static link time.
- If it was, the dynamic loader is also loaded into memory, and execution control is passed to it (instead of the main executable).

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and

- then the dynamic loader is to examine the executable for instructions on which other libraries are required, check whether correct versions can be found, load them into memory, and prepare symbol resolution between the main executable and the shared libraries.
- This is the run time loading step, often also called dynamic linking
- The dynamic loader can be part of the OS, but on Linux it's part of libc (GLIBC, uClibc and musl each have their own loader).

https://stackoverflow.com/questions/52118756/is-ld-called-at-both-compile-time-and

- The programs ld.so and ld-linux.so find and load the shared libraries require by a program, prepare the program to run, and then run it.
- linux binaries require dynamic linking (linking at run time) unless the -static option was given to ld(1) during compilation.
- ld.so handles a.out binaries (a format used long ago)
- ld-linux.so handles ELF
 - /lib/ld-linux.so.1 for libc5,
 - /lib/ld-linux.so.2 for glibc2

https://linux.die.net/man/8/ld-linux

C library described in ANSI,c99,c11 standards.

- It includes macros, symbols, function implementations etc.
- (printf(), malloc() etc)

POSIX standard library.

- he "userland" glue of system calls. (open(), read() etc.
- no actual implementations of system calls. (kernel does it)
- but glibc provides the user land interface to the services provided by kernel so that user application can use a system call just like a ordinary function.
- Some nonstandard but useful stuff.

https://linux.die.net/man/8/ld-linux

- Id.so, ld-linux.so are linux's dynamic loader / linker
- most modern programs are dynamically linked
- when a <u>dynamically linked</u> <u>application</u> is <u>loaded</u> by the operating system, the <u>dynamic</u> <u>loader</u> must locate and load the <u>dynamic</u> libraries it needs for execution.
- on linux, that job is handled by Id-linux.so.2
- you can see the libraries used by a given <u>application</u> with the <u>ldd</u> command:

https://www.cs.virginia.edu/~dww4s/articles/ld_linux.html

- The dynamic linker can be executed either indirectly by running some dynamically linked program or shared object
 - the dynamic linker is specified in the .interp section of an ELF file the program to be executed
 - no command-line options to the dynamic linker
- executed directly by the command-line
 - /lib/ld-linux.so.* [OPTIONS] [PROGRAM [ARGUMENTS]]

man ld-linux.so

- run time linker for dynamic objects
- a dynamic applications
 - consist of one or more dynamic objects
 - typically a <u>dynamic</u> <u>executable</u> and one or more <u>shared</u> <u>object</u> dependencies
- In Solaris, this interpreter is referred to as the run time linker
 - dynamic linker
 - dynamic loader

https://docs.oracle.com/cd/E19253-01/816-5165/ld.so.1-1/index.html

- As part of the *initialization* and *execution* of a <u>dynamic</u> application, an <u>interpreter</u> is called
- this interpreter completes the binding of the <u>application</u> to its <u>shared object</u> dependencies.

https://docs.oracle.com/cd/E19253-01/816-5165/ld.so.1-1/index.html