

# Redundant CORDIC Timmermann (C)

## 20170204

Termination Algorithms  
Modified CORDIC  
CSD (Canonic Sign Digit) Encoding  
Booth Encoding

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Low Latency Time CORDIC Algorithms - Timmermann (1992)  
Redundant and on-line CORDIC - Ercegovac & Lang (1990)

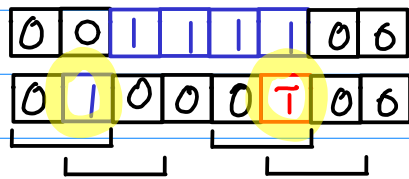
# CSD (Canonic Signed Digit)

like Booth encoding (not modified Booth)

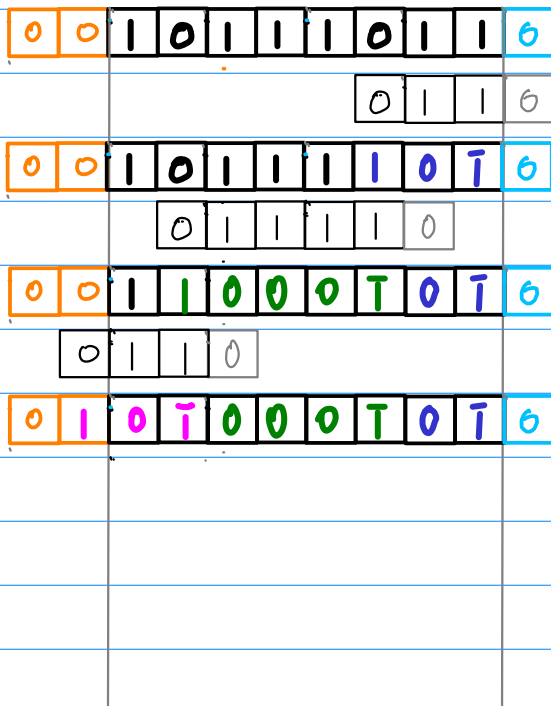
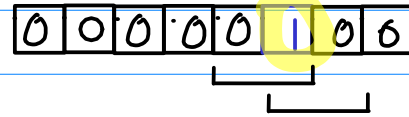
all non-zero digits are separated by zeros

$$\Rightarrow \sigma_i \sigma_{i+1} = 0$$

1-run



$$\begin{array}{ll} 0 \cdot 1 = 0 & 0 \cdot \bar{1} = 0 \\ 1 \cdot 0 = 0 & \bar{1} \cdot 0 = 0 \end{array}$$



Iterative Reduction of 1-runs

$$\sigma_i \sigma_{i+1} = 0$$

Unique encoding

# Two successive iteration steps

$$\begin{aligned}
 x_{i+1} &= x_i - m \sigma_i 2^{-s(m,i)} y_i \\
 y_{i+1} &= y_i + \sigma_i 2^{-s(m,i)} x_i \\
 z_{i+1} &= z_i - \sigma_i \alpha_{m,i}
 \end{aligned}$$

$$\textcircled{i+1} \begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} = \begin{bmatrix} 1 & -m \sigma_i 2^{-i} \\ \sigma_i 2^{-i} & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\textcircled{i+2} \begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 & -m \sigma_{i+1} 2^{-i-1} \\ \sigma_{i+1} 2^{-i-1} & 1 \end{bmatrix} \begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -m \sigma_{i+1} 2^{-i-1} \\ \sigma_{i+1} 2^{-i-1} & 1 \end{bmatrix} \begin{bmatrix} 1 & -m \sigma_i 2^{-i} \\ \sigma_i 2^{-i} & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$= \begin{bmatrix} 1 - m \sigma_{i+1} \sigma_i 2^{-2i-1} & -m \sigma_i 2^{-i} - m \sigma_{i+1} 2^{-i-1} \\ \sigma_{i+1} 2^{-i-1} + \sigma_i 2^{-i} & -m \sigma_{i+1} \sigma_i 2^{-2i-1} + 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$= \begin{bmatrix} 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} & -m (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

## CSD

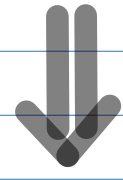
$$\begin{bmatrix} 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} & -m (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} \end{bmatrix}$$

$$\sigma_i \neq 0 \rightarrow \sigma_i \sigma_{i+1} = 0$$

property of Booth encoding

$$\begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} = \begin{bmatrix} 1 & -m \sigma_i 2^{-i} \\ \sigma_i 2^{-i} & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$



$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{aligned} x_{i+2} &= x_i - m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) y_i \\ y_{i+2} &= (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) x_i + y_i \end{aligned}$$

### CSD

$$\begin{aligned} x_{i+2} &= x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i \\ y_{i+2} &= y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i \\ z_{i+2} &= z_i - \sigma_i \alpha_{m,i} - \sigma_{i+1} \alpha_{m,i+1} \end{aligned}$$

$\sigma_i = 0$   $\rightarrow$  inc/dec no rotation,  
but compensate the scale factor.

$$\begin{aligned} x_{i+1} &= x_i + m \cdot 2^{-2i-1} x_i && \text{inc/dec} \\ y_{i+1} &= y_i + m \cdot 2^{-2i-1} y_i && \text{inc/dec} \\ z_{i+1} &= z_i && m=+1/m=-1 \end{aligned}$$

$$\begin{aligned} x_{i+1} &= \left( 1 + m \cdot 2^{-2i-1} \right) x_i \\ y_{i+1} &= \left( 1 + m \cdot 2^{-2i-1} \right) y_i \\ z_{i+1} &= z_i \end{aligned}$$

$$\begin{aligned} x_{i+2} &= \left( 1 + m \cdot 2^{-2i-3} \right) x_{i+1} = \left( 1 + m \cdot 2^{-2i-3} \right) \left( 1 + m \cdot 2^{-2i-1} \right) x_i \\ y_{i+2} &= \left( 1 + m \cdot 2^{-2i-3} \right) y_{i+1} = \left( 1 + m \cdot 2^{-2i-3} \right) \left( 1 + m \cdot 2^{-2i-1} \right) y_i \\ z_{i+1} &= z_i \end{aligned}$$

$$2^{-2i-3} \cdot 2^{-2i-1} = 2^{-4i-4} \ll 1$$

$$\begin{aligned} x_{i+2} &= \left( 1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1} \right) x_i \\ y_{i+2} &= \left( 1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1} \right) y_i \\ z_{i+1} &= z_i \end{aligned}$$

$$m=1, S(m, i) = i$$

### CSD

Cond (I)  $0 \leq i \leq \frac{1}{4}(n-3)$

$$\begin{aligned} x_{i+1} &= x_i - \sigma_i 2^{-i} y_i \\ y_{i+1} &= y_i + \sigma_i 2^{-i} x_i \\ z_{i+1} &= z_i - \sigma_i \tan^{-1}(2^{-i}) \end{aligned}$$

$$\begin{aligned} x_{i+1} &= x_i - \sigma_i 2^{-i} y_i \\ y_{i+1} &= y_i + \sigma_i 2^{-i} x_i \\ z_{i+1} &= z_i - \sigma_i \tan^{-1}(2^{-i}) \end{aligned}$$

Cond (II)  $\frac{1}{4}(n-3) < i \leq \frac{1}{2}(n+1)$

$\sigma_i \neq 0$

$$\begin{aligned} x_{i+1} &= x_i - \sigma_i 2^{-i} y_i \\ y_{i+1} &= y_i + \sigma_i 2^{-i} x_i \\ z_{i+1} &= z_i - \sigma_i \tan^{-1}(2^{-i}) \end{aligned}$$

$\sigma_i \neq 0$

$$\begin{aligned} x_{i+2} &= x_i - m\sigma_i 2^{-i} y_i - m\sigma_{i+1} 2^{-i-1} y_i \\ y_{i+2} &= y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i \\ z_{i+2} &= z_i - \sigma_i \alpha_{m,i} - \sigma_{i+1} \alpha_{m,i+1} \end{aligned}$$

$\sigma_i = 0$

$$\begin{aligned} x_{i+1} &= x_i + m \cdot 2^{-2i-1} x_i \\ y_{i+1} &= y_i + m \cdot 2^{-2i-1} y_i \\ z_{i+1} &= z_i \end{aligned}$$

$\sigma_i = 0$

$$\begin{aligned} x_{i+2} &= (1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1}) x_i \\ y_{i+2} &= (1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1}) y_i \\ z_{i+1} &= z_i \end{aligned}$$

Cond (III)  $\frac{1}{2}(n+1) < i$

$\sigma_i \neq 0$

$$\begin{aligned} x_{i+1} &= x_i - \sigma_i 2^{-i} y_i \\ y_{i+1} &= y_i + \sigma_i 2^{-i} x_i \\ z_{i+1} &= z_i - \sigma_i \tan^{-1}(2^{-i}) \end{aligned}$$

$\sigma_i \neq 0$  or  $\sigma_i = 0$

$$\begin{aligned} x_{i+2} &= x_i - m\sigma_i 2^{-i} y_i - m\sigma_{i+1} 2^{-i-1} y_i \\ y_{i+2} &= y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i \\ z_{i+2} &= z_i - \sigma_i \alpha_{m,i} - \sigma_{i+1} \alpha_{m,i+1} \end{aligned}$$

$\sigma_i = 0$

$$\begin{aligned} x_{i+1} &= x_i \\ y_{i+1} &= y_i \\ z_{i+1} &= z_i \end{aligned}$$

$i \leftarrow i+1$

$i \leftarrow i+2$

$$\begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} = \begin{bmatrix} 1 & -m \sigma_i 2^{-i} \\ \sigma_i 2^{-i} & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 - m \boxed{\sigma_i \sigma_{i+1}} 2^{-2i-1} & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \boxed{\sigma_i \sigma_{i+1}} 2^{-2i-1} \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\sigma_i = 0$$

$$\rightarrow \sigma_i \sigma_{i+1} = 0$$

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 & -m(\cancel{\sigma_i} 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\cancel{\sigma_i} 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{aligned} x_{i+2} &= x_i - m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) y_i \\ y_{i+2} &= (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) x_i + y_i \end{aligned}$$

$$\begin{aligned} x_{i+2} &= x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i \\ y_{i+2} &= y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i \end{aligned}$$

$$\sigma_i = 0$$

$$\sigma_{i+1} \neq 0$$

$$x_{i+2} = x_i$$

$$y_{i+2} = y_i$$

$$\begin{aligned} &- m \sigma_{i+1} 2^{-i-1} y_i \\ &+ \sigma_{i+1} 2^{-i-1} x_i \end{aligned}$$

$$\sigma_i \neq 0$$

$$\sigma_{i+1} = 0$$

$$x_{i+2} = x_i$$

$$y_{i+2} = y_i$$

$$\begin{aligned} &- m \sigma_i 2^{-i} y_i \\ &+ \sigma_i 2^{-i} x_i \end{aligned}$$

$$\sigma_i = 0$$

$$\sigma_{i+1} = 0$$

$$x_{i+2} = x_i$$

$$y_{i+2} = y_i$$



Cond (II)  $\frac{1}{4}(n-3) < i \leq \frac{1}{2}(n+1)$

$\sigma_i \neq 0$

parallel ←

$x_{i+2} = x_i - m\sigma_i 2^{-i} y_i - m\sigma_{i+1} 2^{-i-1} y_i$
$y_{i+2} = y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i$
$z_{i+2} = z_i - \sigma_i \alpha_{m,i} - \sigma_{i+1} \alpha_{m,i+1}$

$\sigma_i = 0$

parallel ←

$x_{i+2} = (1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1}) x_i$
$y_{i+2} = (1 + m \cdot 2^{-2i-3} + m \cdot 2^{-2i-1}) y_i$
$z_{i+1} = z_i$

$\sigma_i = 0$

- postpone this computation

until the whole iteration process has been completed

- use a Wallace tree to implement this in parallel

$\sigma_i \neq 0$

- executes a rotation by either  $\alpha_{m,i}$  or  $\alpha_{m,i+1}$

- multiplex the different shifts, 4-to-2 cell

Cond (iii)  $\cdot \frac{1}{2}(n+1) < i$

- analogous to the termination algorithm

- but improved design regularity

∴ tree structures are not necessary

- the original iterations are paired

always two subsequent iterations are

merged into a new single iteration

- a 4-to-2 adder cell  $(x_i, y_i)$

a 3-to-2 adder cell  $(z_i)$

a 3:1 multiplexer

$\sigma_i \sigma_{i+1}$

0 0

0 1

1 0

# Termination Algorithm

quit the iteration process as early as possible

Termination algorithm

- T.C. Chen IBM Journal of Research and Development  
1972

Automatic computation of exponentials  
logarithms, ratios, and square roots

- Timmermann Modified CORDIC algorithms

the 2<sup>nd</sup> half of the  $n$  iterations

- can be substituted by 2 multiplications in parallel

A fully parallel  $n$ -bit wallace tree multiplier

-  $2 \cdot \log_2(n)$  FA time units

algorithm + prediction + termination

$$(n+1) + 2\log_2\left(\frac{n}{2}\right) + \log_2(n) = n + 3\log_2(n) - 1$$

# Modified CORDIC

Modified CORDIC

Timmermann 1989 Electronics Letters

$$\begin{aligned}x_n &= k_m \{ x_0 \cos[\sqrt{(m)} \alpha] - \sqrt{(m)} y_0 \sin[\sqrt{(m)} \alpha] \} \\y_n &= k_m \{ 1/\sqrt{(m)} x_0 \sin[\sqrt{(m)} \alpha] + y_0 \cos[\sqrt{(m)} \alpha] \} \\z_n &= z_0 + \alpha\end{aligned}$$

$k_m$  : the scaling factor

$m$  : the coordinate system (0, 1, +1)

$\alpha$  : the rotation angle

$\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}$  : the initial values depends on the iteration goal

Data dependency across iteration

→ CSA no benefit

① 1st half iterations : the most significant contribution

the rotation angle  $\alpha_i = \frac{1}{\sqrt{(m)}} \tan^{-1} [\sqrt{(m)} 2^{-S(m, i)}]$

$S(m, i)$  the iteration shift values

$\alpha_i$  decreases with the increasing iteration index  $i$

② 2nd half iterations : can improve the accuracy only by one bit each

Cond (I)	$0 \leq i \leq \frac{1}{4}(n-3)$	}	1 <sup>st</sup> half
Cond (II)	$\frac{1}{4}(n-3) < i \leq \frac{1}{2}(n+1)$		
Cond (III)	$\frac{1}{2}(n+1) < i$	}	2 <sup>nd</sup> half

rotation  $z_n \rightarrow 0$

$$x_n = k_m \{ x_0 \cos[\sqrt{m} \alpha] - \sqrt{m} y_0 \sin[\sqrt{m} \alpha] \}$$

$$y_n = k_m \{ 1/\sqrt{m} x_0 \sin[\sqrt{m} \alpha] + y_0 \cos[\sqrt{m} \alpha] \}$$

Vectoring  $y_n \rightarrow 0$

$$x_n = k_m \sqrt{x_0^2 + m y_0^2}$$

$$z_n = z_0 + 1/\sqrt{m} \tan^{-1}[\sqrt{m} y_0 / x_0]$$

2nd half iterations : can improve the accuracy  
only by one bit each

replace these iterations by a single rotation  
after the remaining rotation angle  
has been reduced using a fixed number of  
pure CORDIC iterations

this truncation reduces the latency time and saves area  
although the truncation requires extra hardware

the necessary minimum number of iterations

Rotation mode ( $z \rightarrow 0$ )

After  $j$  CORDIC rotations have been performed  $(x_j, y_j)$   
the  $z$  path contains the remaining rotation angle  $z_j$

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \begin{bmatrix} \cos[\sqrt{m} z_j] & -\sqrt{m} \sin[\sqrt{m} z_j] \\ 1/\sqrt{m} \sin[\sqrt{m} z_j] & \cos[\sqrt{m} z_j] \end{bmatrix} \begin{bmatrix} x_j \\ y_j \end{bmatrix}$$

$$x_n = k_m \{ x_0 \cos[\sqrt{m} \alpha] - \sqrt{m} y_0 \sin[\sqrt{m} \alpha] \}$$

$$y_n = k_m \{ 1/\sqrt{m} x_0 \sin[\sqrt{m} \alpha] + y_0 \cos[\sqrt{m} \alpha] \}$$

$$z_n = z_0 + \alpha$$

assume  $k_m = 1$  ← 2<sup>nd</sup> half iteration does not  
affect scaling factors



$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \begin{bmatrix} \cos [\sqrt{(m)} \epsilon_j] & -\sqrt{(m)} \sin [\sqrt{(m)} \epsilon_j] \\ 1/\sqrt{(m)} \sin [\sqrt{(m)} \epsilon_j] & \cos [\sqrt{(m)} \epsilon_j] \end{bmatrix} \begin{bmatrix} x_j \\ y_j \end{bmatrix}$$

Taylor Series expansions to  $\sin \theta$ ,  $\cos \theta$   
take only the first terms

$$\sin \theta = x - \frac{1}{3!} x^3 + \frac{1}{5!} x^5 - \frac{1}{7!} x^7 + \dots$$

$$\cos \theta = 1 - \frac{1}{2!} x^2 + \frac{1}{4!} x^4 - \frac{1}{6!} x^6 + \dots$$

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & -\sqrt{(m)} \cdot \sqrt{(m)} \epsilon_j \\ 1/\sqrt{(m)} \cdot \sqrt{(m)} \epsilon_j & 1 \end{bmatrix} \begin{bmatrix} x_j \\ y_j \end{bmatrix}$$

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & -m \epsilon_j \\ \epsilon_j & 1 \end{bmatrix} \begin{bmatrix} x_j \\ y_j \end{bmatrix}$$

for a sufficiently small  $\epsilon_j$

the required precision of  $n$ -bit  
the upper limit on the maximal remainder

$$\epsilon_j \leq \frac{1}{\sqrt{(m)}} \tan^{-1} [\sqrt{(m)} 2^{-j+1}]$$

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & -m z_j \\ z_j & 1 \end{bmatrix} \begin{bmatrix} x_j \\ y_j \end{bmatrix}$$

for a sufficiently small  $z_j$

the required precision of  $n$ -bit  
the upper limit on the maximal remainder

$$\frac{1}{2} z_j^2 \leq 2^{-n} \quad \longrightarrow \quad z_j^2 \leq 2^{-n+1} \quad \longrightarrow \quad z_j \leq 2^{-\frac{n+1}{2}}$$

$$z_j \leq \frac{1}{\sqrt{(m)}} \tan^{-1} [\sqrt{(m)} 2^{-j+1}]$$

$$j > \frac{n+1}{2}$$

Cond (I)	$0 \leq i \leq \frac{1}{4}(n-3)$	} 1 <sup>st</sup> half
Cond (II)	$\frac{1}{4}(n-3) < i \leq \frac{1}{2}(n+1)$	
Cond (III)	$\frac{1}{2}(n+1) < i$	} 2 <sup>nd</sup> half

## Rotation mode

$$\begin{aligned}x_n &= x_j - m z_j y_j & (j > (n+1)/2) \\y_n &= z_j x_j + y_j & (j > (n+1)/2)\end{aligned}$$

## Vectoring mode

$$\begin{aligned}x_n &= z_j & j > (n+1)/2 \\z_n &= z_j + y_j/x_j & j > (n/3) + 0.4n2\end{aligned}$$

the prediction algorithm : rotation mode (OK)  
vectoring mode (X)

2nd half of the  $n$  iterations in rotation mode  
~ replaced by 2 multiplications in parallel

$$\begin{cases} z_j * x_j \\ z_j * y_j \end{cases}$$

A fully parallel  $n$ -bit Wallace tree multiplier :  $2 \log_2(n)$  FA time unit

prediction + termination.

# the Truncated. CORDIC Algorithm

- reduces the number of CORDIC iterations

- Multiplication / division hardware

  - Booth Technique halves the amount of partial products
  - Carry Save Architecture

$k_m \neq 1 \Rightarrow$  multiplication  $\Rightarrow$  multiplier anyway

# Modified Booth Encoding CSD

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$x_{i+2} = x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i$$

$$y_{i+2} = y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i$$

$$x_{i+2} = (x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i) \\ (1 + \lambda(\sigma_i) m 2^{-2i-1} x_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} x_i)$$

$$y_{i+2} = (y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i) \\ (1 + \lambda(\sigma_i) m 2^{-2i-1} y_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} y_i)$$

✦ In Timmermann's paper, the modified Booth encoding refers to CSD (Canonic Signed Digit)  $\sigma_i \sigma_{i+1} = 0$  not the generally known modified Booth encoding.

$$\begin{bmatrix} x_{i+2} \\ y_{i+2} \end{bmatrix} = \begin{bmatrix} 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} & -m(\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) \\ (\sigma_i 2^{-i} + \sigma_{i+1} 2^{-i-1}) & 1 - m \sigma_i \sigma_{i+1} 2^{-2i-1} \end{bmatrix} \begin{bmatrix} x_i \\ y_i \end{bmatrix}$$

$$\begin{aligned} x_{i+2} &= (x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i) - m \sigma_i \sigma_{i+1} 2^{-2i-1} x_i \\ y_{i+2} &= (y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i) - m \sigma_i \sigma_{i+1} 2^{-2i-1} y_i \end{aligned}$$

$$\begin{aligned} x_{i+2} &= (x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i) (1 + \lambda(\sigma_i) m 2^{-2i-1} x_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} x_i) \\ y_{i+2} &= (y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i) (1 + \lambda(\sigma_i) m 2^{-2i-1} y_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} y_i) \end{aligned}$$

$$\lambda(\sigma_i) = 1 \quad \text{for } |\sigma_i| = 0 \quad \{0\}$$

$$\lambda(\sigma_i) = 0 \quad \text{for } |\sigma_i| = 1 \quad \{1, \bar{1}\}$$

$$\lambda(\sigma_{i+1}) = 1 \quad \text{for } |\sigma_{i+1}| = 0 \quad \{0\}$$

$$\lambda(\sigma_{i+1}) = 0 \quad \text{for } |\sigma_{i+1}| = 1 \quad \{1, \bar{1}\}$$

$$x_{i+2} = (x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i) (1 + \lambda(\sigma_i) m 2^{-2i-1} x_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} x_i)$$

$$y_{i+2} = (y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i) (1 + \lambda(\sigma_i) m 2^{-2i-1} y_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} y_i)$$

rotation by  $\alpha_{m,i}$  or  $\alpha_{m,i+1}$

multiplex the diff. shifts

⇒ 4-to-2 cells  $x_{i+2}, y_{i+2}$

3-to-2 cells  $z_{i+2}$

Timmermann's constant scaling factor

for n-bit precision.

parallelizable

late evaluation

after all iterations

Wallace Tree

$\sigma_i$ 's are recoded in parallel  
 # of non-zero  $\sigma_i$ 's at most half of max value w/o recoding

$$\sigma_i \sigma_{i+1} = 0$$

$$\sigma_i \sigma_{i+1}$$

case ① 0 1

case ② 1 0

case ③ 0 0

$$(1 + m 2^{-2i-1})(1 + m 2^{-2i-3}) = 1 + m 2^{-2i-1} + m 2^{-2i-3}$$

$$\prod_{j=0}^n (1 + m 2^{-2i-2j-1}) = 1 + \sum_{j=0}^n m 2^{-2i-2j-1}$$

$$\begin{aligned} & (1 + m 2^{-2i-0-1})(1 + m 2^{-2i-2-1})(1 + m 2^{-2i-4-1})(1 + m 2^{-2i-6-1}) \dots \\ = & 1 + m 2^{-2i-0-1} + m 2^{-2i-2-1} + m 2^{-2i-4-1} + m 2^{-2i-6-1} \dots \end{aligned}$$



# Modified Booth Encoding

$$\lambda(t) = 1 \quad \text{for } |t| = 0$$

$$\lambda(t) = 0 \quad \text{for } |t| = 1 \quad \{1, \bar{1}\}$$

$$\begin{aligned} x_{i+2} &= (x_i - m \sigma_i 2^{-i} y_i - m \sigma_{i+1} 2^{-i-1} y_i) \\ &= (1 + \lambda(\sigma_i) m 2^{-2i-1} x_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} x_i) \end{aligned}$$

$$\begin{aligned} y_{i+2} &= (y_i + \sigma_i 2^{-i} x_i + \sigma_{i+1} 2^{-i-1} x_i) \\ &= (1 + \lambda(\sigma_i) m 2^{-2i-1} y_i + \lambda(\sigma_{i+1}) m 2^{-2i-3} y_i) \end{aligned}$$

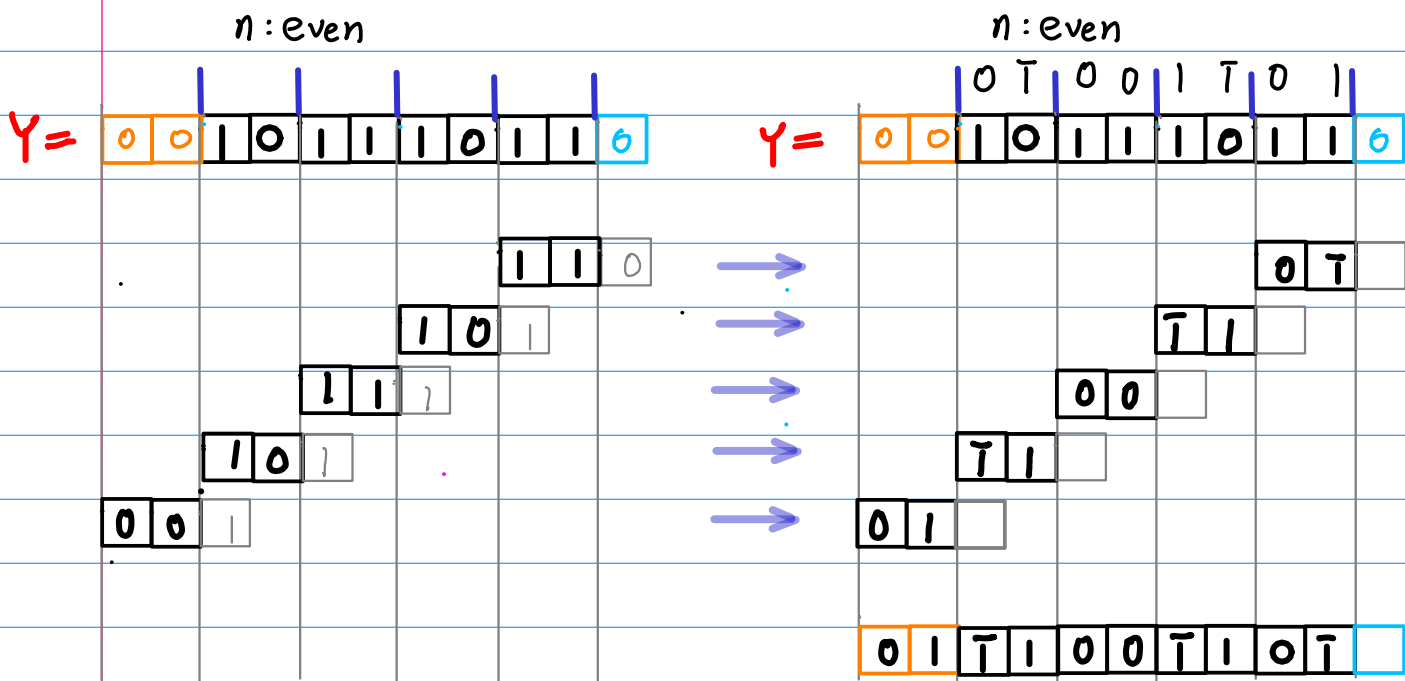
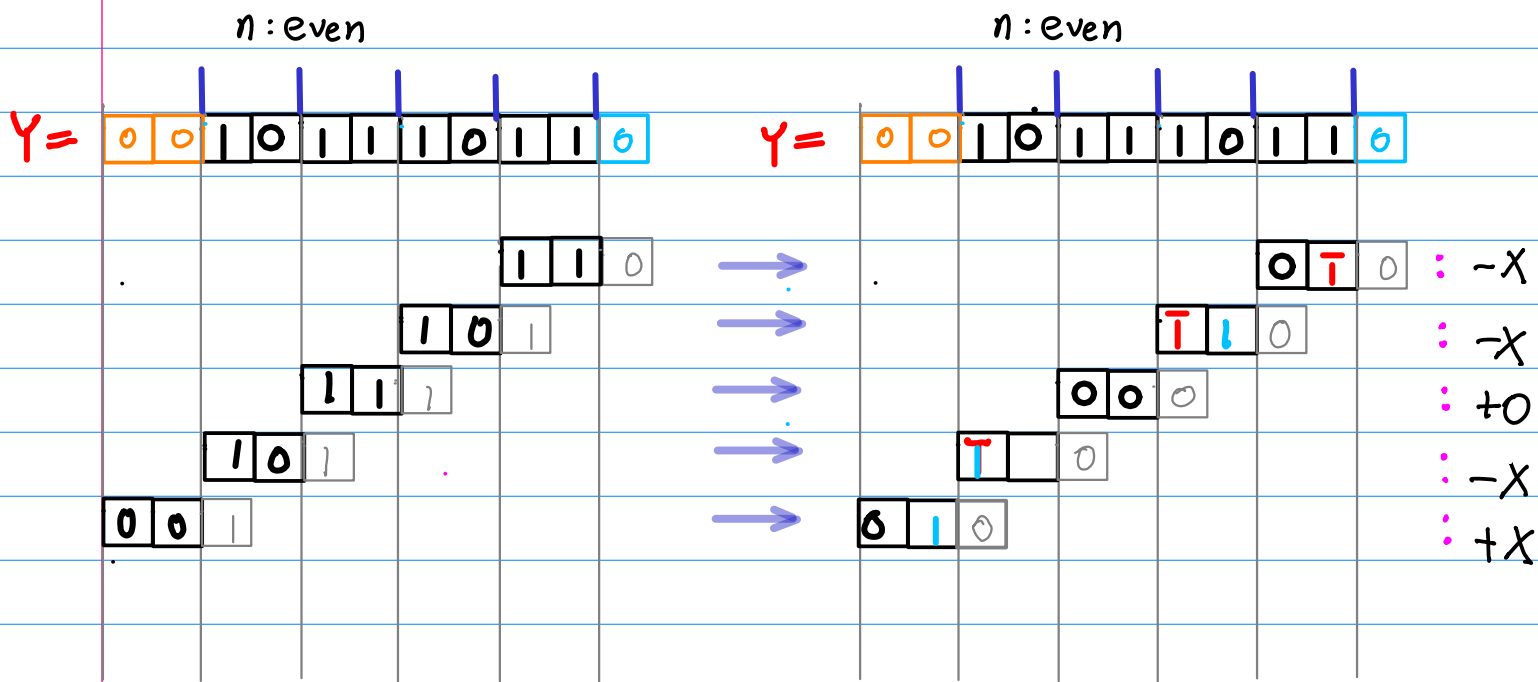
# Modified Booth Encoding

2-bit encoding		$2^1$ $2^0$ ↓ ↓	scale factor		
all zero's	$\boxed{0} \boxed{0} \boxed{0}$	→	$\boxed{0} \boxed{0} \boxed{0}$	$0 \cdot 2 + 0 = +0$	+0
end of 1's	$\boxed{0} \boxed{0} \boxed{1}$	→	$\boxed{0} \boxed{1} \boxed{0}$	$0 \cdot 2 + 1 = +1$	+X
isolated 1	$\boxed{0} \boxed{1} \boxed{0}$	→	$\boxed{1} \boxed{T} \boxed{0}$	$1 \cdot 2 + T = +1$	+X
end of 1's	$\boxed{0} \boxed{1} \boxed{1}$	→	$\boxed{1} \boxed{0} \boxed{0}$	$1 \cdot 2 + 0 = +2$	+2X
start of 1's	$\boxed{1} \boxed{0} \boxed{0}$	→	$\boxed{T} \boxed{0} \boxed{0}$	$T \cdot 2 + 0 = -2$	-2X
isolated 0	$\boxed{1} \boxed{0} \boxed{1}$	→	$\boxed{T} \boxed{1} \boxed{0}$	$T \cdot 2 + 1 = -1$	-X
start of 1's	$\boxed{1} \boxed{1} \boxed{0}$	→	$\boxed{0} \boxed{T} \boxed{0}$	$0 \cdot 2 + T = -1$	-X
all 1's	$\boxed{1} \boxed{1} \boxed{1}$	→	$\boxed{0} \boxed{0} \boxed{0}$	$0 \cdot 2 + 0 = 0$	+0

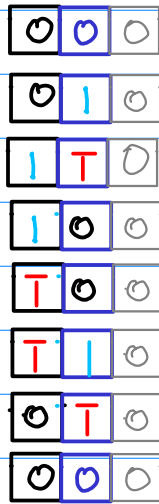
Scale factor  $\{0, \pm 1, \pm 2\}$

not the one Timmermann's paper refers to

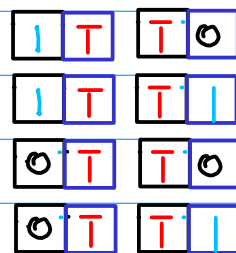
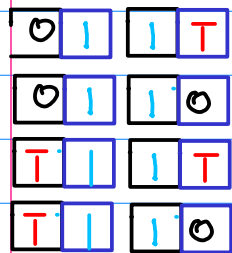
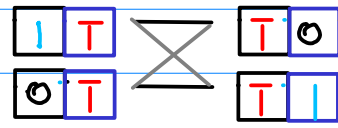
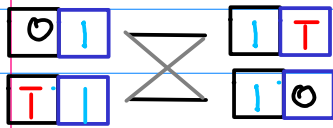
# Original Booth Encoding



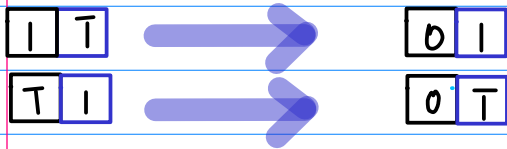
# After the 1<sup>st</sup> Pass



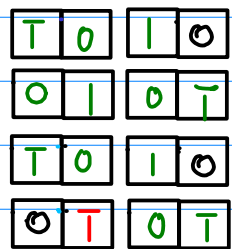
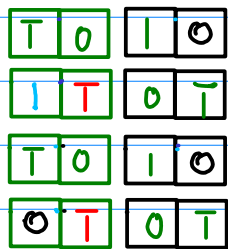
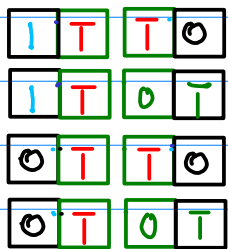
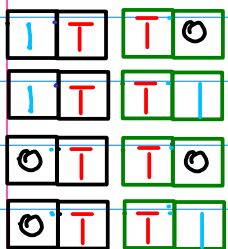
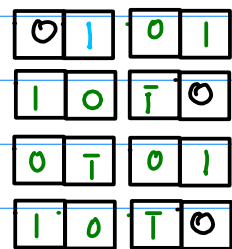
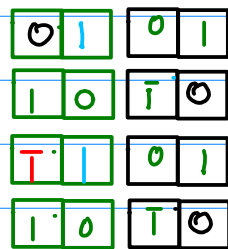
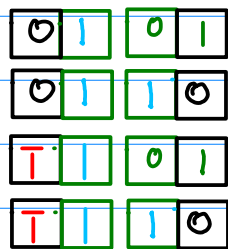
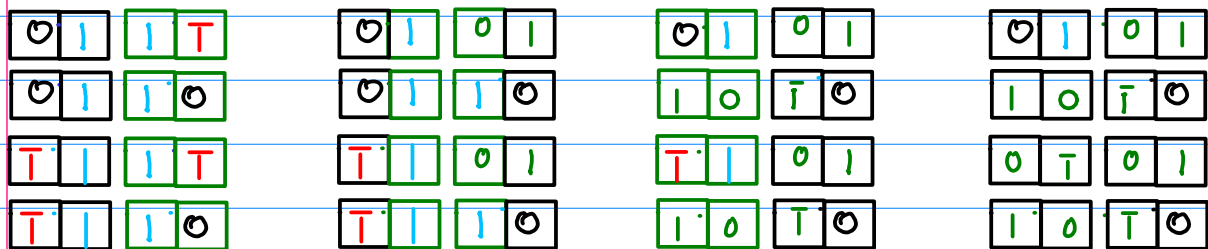
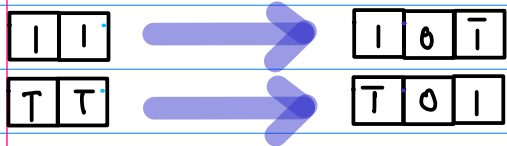
possible boundary cases



# Pass 2 Operation



iterative application



$$\sigma_i \sigma_{i+1} = 0$$

the 2<sup>nd</sup> pass

$\gamma =$ 

0	0	1	0	1	1	1	0	1	1	0
---	---	---	---	---	---	---	---	---	---	---

$\sigma_i \sigma_{i+1} \neq 0$

0	1	$\bar{1}$	1	0	0	$\bar{1}$	1	0	$\bar{1}$	
---	---	-----------	---	---	---	-----------	---	---	-----------	--

0	$\bar{1}$
---	-----------

0	1	$\bar{1}$	1	0	0	$\bar{1}$	1	0	$\bar{1}$	
---	---	-----------	---	---	---	-----------	---	---	-----------	--

1	0
---	---

0	1	$\bar{1}$	1	0	0	$\bar{1}$	1	0	$\bar{1}$	
---	---	-----------	---	---	---	-----------	---	---	-----------	--

$\bar{1}$	1
-----------	---

0	1	$\bar{1}$	1	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	-----------	---	---	---	---	-----------	---	-----------	--

0	0
---	---

0	1	$\bar{1}$	1	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	-----------	---	---	---	---	-----------	---	-----------	--

0	0
---	---

0	1	$\bar{1}$	1	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	-----------	---	---	---	---	-----------	---	-----------	--

1	0
---	---

0	1	$\bar{1}$	1	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	-----------	---	---	---	---	-----------	---	-----------	--

$\bar{1}$	1
-----------	---

0	1	0	$\bar{1}$	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	---	-----------	---	---	---	-----------	---	-----------	--

1	0
---	---

0	1	0	$\bar{1}$	0	0	0	$\bar{1}$	0	$\bar{1}$	
---	---	---	-----------	---	---	---	-----------	---	-----------	--

$\sigma_i \sigma_{i+1} = 0$

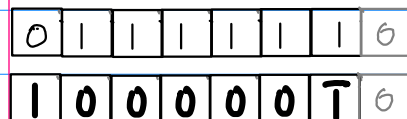
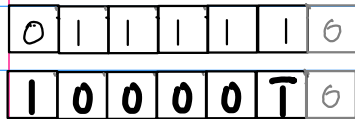
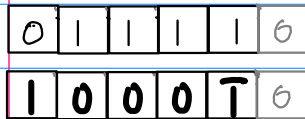
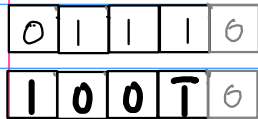
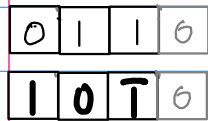
# CSD approach



Iterative Reduction of 1-runs

$$\sigma_i \sigma_{i+1} = 0$$

Unique encoding



# Verification

	$2^7$	$2^6$	$2^5$	$2^4$	$2^3$	$2^2$	$2^1$	$2^0$			
	0	0	1	0	1	1	1	0	1	1	6
	0	1	$\bar{1}$	1	0	0	$\bar{1}$	1	0	$\bar{1}$	
	0	1	0	$\bar{1}$	0	0	0	$\bar{1}$	0	$\bar{1}$	
	0	1	0	$\bar{1}$	0	0	0	$\bar{1}$	0	$\bar{1}$	6

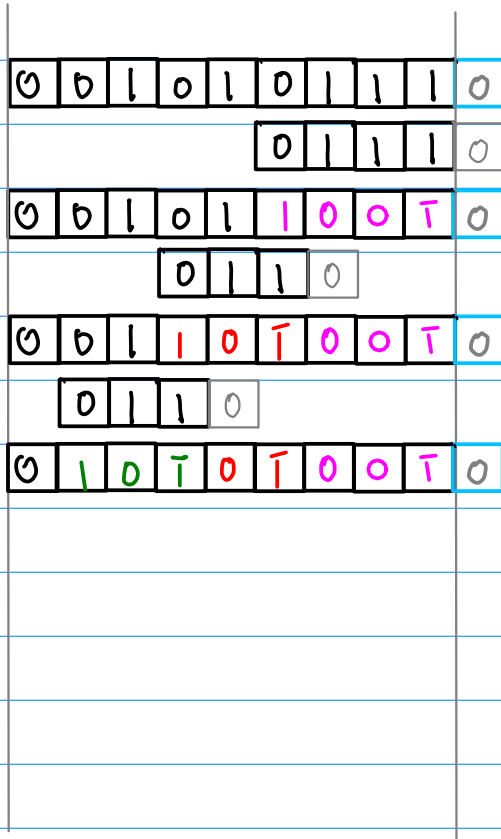
$$2^9 + 2^5 + 2^4 + 2^3 + 2^1 + 2^0 = 128 + 32 + 16 + 8 + 2 + 1 = 187$$

$$2^8 - 2^7 + 2^4 - 2^3 + 2^2 - 2^0 = 256 - 128 + 64 - 8 + 4 - 1 = 187$$

$$2^8 - 2^6 - 2^2 - 2^0 = 256 - 64 - 4 - 1 = 187$$

$$2^8 - 2^6 - 2^2 - 2^0 = 256 - 64 - 4 - 1 = 187$$





# Canonical Signed Digit (CSD)

(1) the number of non-zero digits is minimal

(2) no two consecutive digits are both non-zero  
two non-zero digits are not adjacent

