

# Characteristics of Multiple Random Variables

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Based on  
Probability, Random Variables and Random Signal Principles,  
P.Z. Peebles, Jr. and B. Shi

# Outline

## 1 Joint Gaussian Random Variables

# Bivariate Gaussian Density

two random variables

## Definition

The two random variables  $X$  and  $Y$  are said to be jointly Gaussian, if their joint density function is

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho^2}} \cdot \exp\left\{ \frac{-1}{2(1-\rho^2)} \cdot \left[ \frac{(x-\bar{X})^2}{\sigma_X^2} - \frac{2\rho(x-\bar{X})(y-\bar{Y})}{\sigma_X\sigma_Y} + \frac{(y-\bar{Y})^2}{\sigma_Y^2} \right] \right\}$$

$$\bar{X} = E[X],$$

$$\bar{Y} = E[Y],$$

$$\rho = E[(X-\bar{X})(Y-\bar{Y})]/\sigma_X\sigma_Y$$

$$\sigma_X^2 = E[(X-\bar{X})^2],$$

$$\sigma_Y^2 = E[(Y-\bar{Y})^2],$$

# Bivariate Gaussian Density - Maximum value

two random variables

$$f_{X,Y}(x,y) \leq f_{X,Y}(\bar{X}, \bar{Y}) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho^2}}.$$

# Bivariate Gaussian Density - Uncorrelated

two random variables

$f_{X,Y}(x,y) = f_X(x)f_Y(x)$  is sufficient to guarantee that  $X$  and  $Y$  are statistically independent. Any uncorrelated Gaussian random variables are also statistically independent a coordinate rotation (linear transformation of  $X$  and  $Y$ ) through the angle

$$\theta = \frac{1}{2} \tan^{-1} \left[ \frac{2\rho\sigma_X\sigma_Y}{\sigma_X^2 - \sigma_Y^2} \right]$$

is sufficient to convert correlated random variables  $X$  and  $Y$  having  $\sigma_X^2$  and  $\sigma_Y^2$ , respectively, correlation coefficient  $\rho$ , and the joint density of  $f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho^2}} \cdot \exp[\dots]$  into two statistically independent Gaussian random variables

# Multi-variate Gaussian Density

$N$  random variables

$N$  random variables  $X_1, X_2, \dots, X_N$  are called jointly Gaussian if their joint density function can be written as

$$f_{X_1, \dots, X_N}(x_1, \dots, x_N) = \frac{|[C_X]^{-1}|^{1/2}}{(2\pi)^{N/2}} \exp \left\{ -\frac{[x - \bar{X}]^t [C_X] [x - \bar{X}]}{2} \right\}$$

where

$$[x - \bar{X}] = \begin{bmatrix} x_1 - \bar{X}_1 \\ x_2 - \bar{X}_2 \\ \vdots \\ x_N - \bar{X}_N \end{bmatrix}, \quad [C_X] = \begin{bmatrix} C_{11} & C_{12} & \cdots & C_{1N} \\ C_{21} & C_{22} & \cdots & C_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ C_{N1} & C_{N2} & \cdots & C_{NN} \end{bmatrix}$$

## Multi-variate Gaussian Density - notations

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where  $[\bullet]^t$  denotes a matrix transposition,

$[\bullet]^{-1}$  denotes a matrix inversion

$|\bullet|$  denotes a matrix determinant



# Covariance Matrix

$N$  random variables

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where  $[C_X]$  is called the covariance matrix of  $N$  random variables

$$C_{ij} = E[(X_i - \bar{X}_i)(X_j - \bar{X}_j)] = \begin{cases} \sigma_{X_i}^2 & i = j \\ C_{X_i X_j} & i \neq j \end{cases}$$

Covariance Matrix ( $N = 2$ ) $N$  random variables

$$f_{X_1 X_2}(x_1, x_2) = \frac{|[C_X]^{-1}|^{1/2}}{(2\pi)^{2/2}} \exp \left\{ -\frac{[x - \bar{X}]^t [C_X] [x - \bar{X}]}{2} \right\}$$

$$[C_X] = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} \sigma_{X_1}^2 & \rho \sigma_{X_1} \sigma_{X_2} \\ \rho \sigma_{X_1} \sigma_{X_2} & \sigma_{X_2}^2 \end{bmatrix}$$

$$[C_X]^{-1} = \frac{1}{1 - \rho^2} \begin{bmatrix} \sigma_{X_1}^2 & -\rho / \sigma_{X_1} \sigma_{X_2} \\ -\rho / \sigma_{X_1} \sigma_{X_2} & \sigma_{X_2}^2 \end{bmatrix}$$

$$|[C_X]^{-1}| = 1 / \sigma_{X_1}^2 \sigma_{X_2}^2 (1 - \rho^2)$$

# Properties of Gaussian Random Variables

$N$  random variables

- completely defined through only their first and second order moments - their means, variances, and covariances
- if uncorrelated, then statistically independent
- a linear transformation of Gaussian random variables will produce Gaussian random variables
- any  $k$ -dimensional ( $k$ -variate) marginal density function obtained from the  $N$ -dimensional density function by integrating  $N - k$  random variables will be Gaussian
- $X_1, \dots, X_k$  by integrating out  $X_{k+1}, \dots, X_N$
- the covariance of  $X_1, \dots, X_k$  is the  $k \times k$  submatrix of the  $N \times N$  covariance matrix of  $X_1, \dots, X_N$



