

Mon, 25 Aug 08 : EML 4500

11-1

- * Introduction
- * Motivation of FEM
- * Course organization

Wed, 27 Aug 08 EML 4500 L2-1

Deadline for submitting team structure:
Wed, 3 Sep 08.

Each team (5 or 6 students)
submit a paper of team info:

* team name : 4 char, max 6 char.

* member names + UF ID numb.

* Wikipedia class usernames

real name = WP class username

Fri, 29 Aug 08: EML 4500 13-1

Plan: * Vision: Big picture re mediawiki
and WP
textbooks, Wikiversity Wikipedia
MIT's OpenCourseWare

- * Confidentiality
- * Method of work ← E-learning?
- * Old approach

Vision: - Mediawiki
- Wikiversity, MIT's OpenCourseWare
- collaboration

- * members of a team
- * teams in a class
- * prof + students in class.

WP policies:

WP username \neq WP articles

Confidentiality: course num., semester, team
name, etc

Old approach:

10% HW, 30% + 30% + 30% Exams.

(3.2)

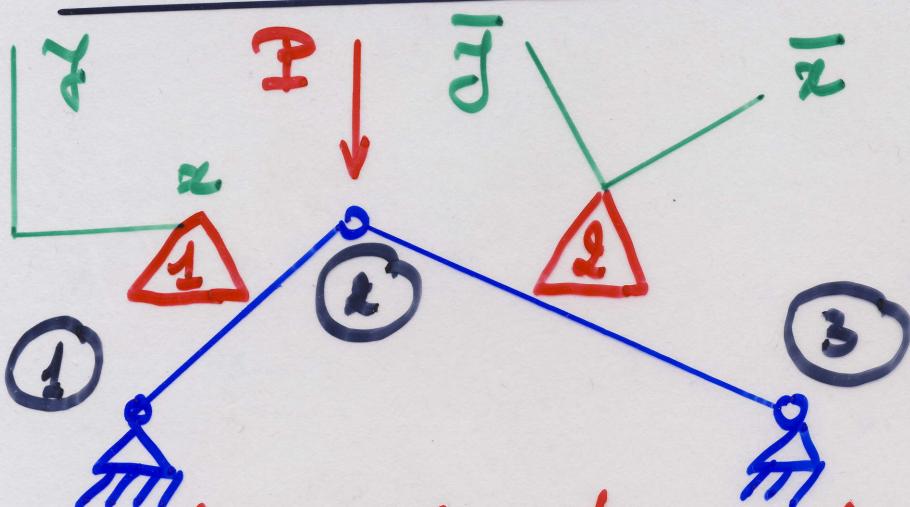
Wed, 3 Sep 08 : EML 4500

(4-1)

Trusses, matrix method.

Book, chap 4

Also MIT's OpenCourseWare:
Class wiki page.



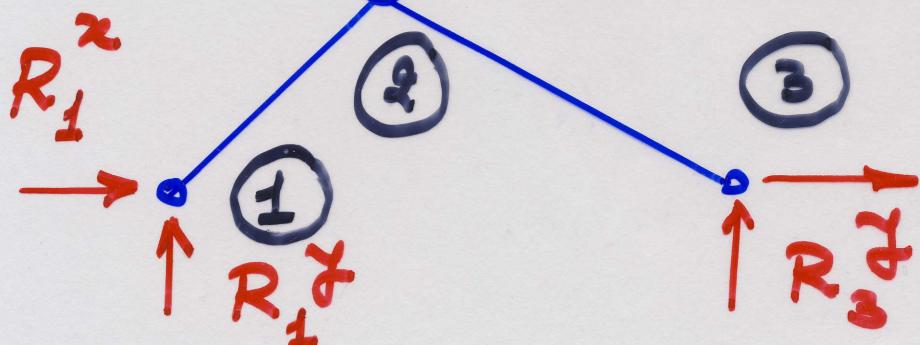
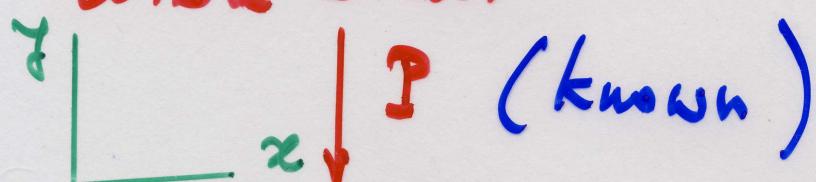
Truss w/ 2 elastic bars
deformable

fixed (unstrained) to zero
disp in both x and y
(in both \bar{x} and \bar{y})

5 stat. indet.
4 actuallly indet.

Global FBD :

whole struct

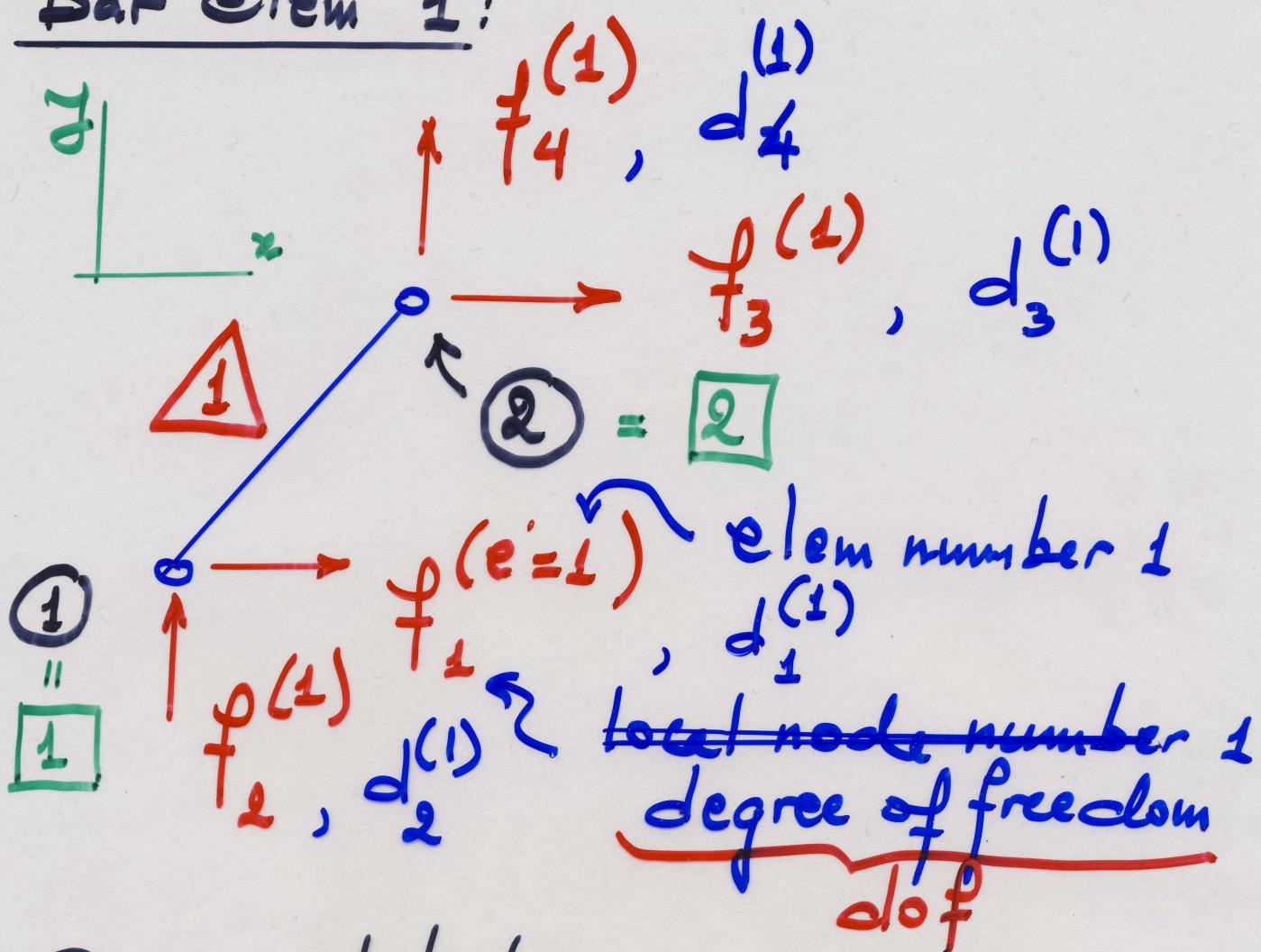


4 unknown reactions:

$R_1^x \rightarrow$
 $R_2^x \rightarrow$
 $R_3^x \Rightarrow$
3 eqs of equil
stati-
cally indeterm.

2 FBD's of 2 bar elems: 4-2

Bar elem 1:



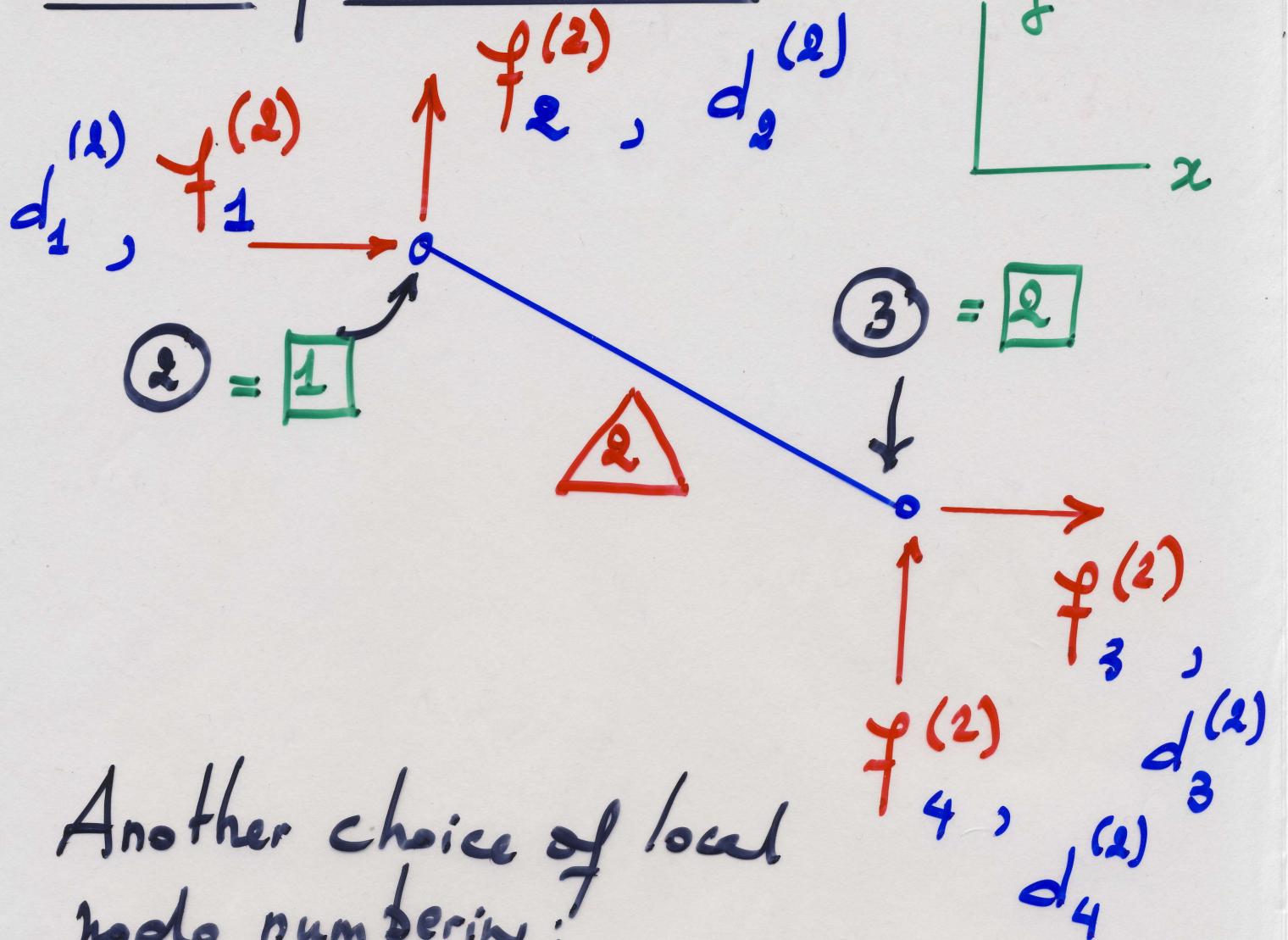
\textcircled{n} = global node number n
whole struct

\boxed{n} = local node number n
each elem separately

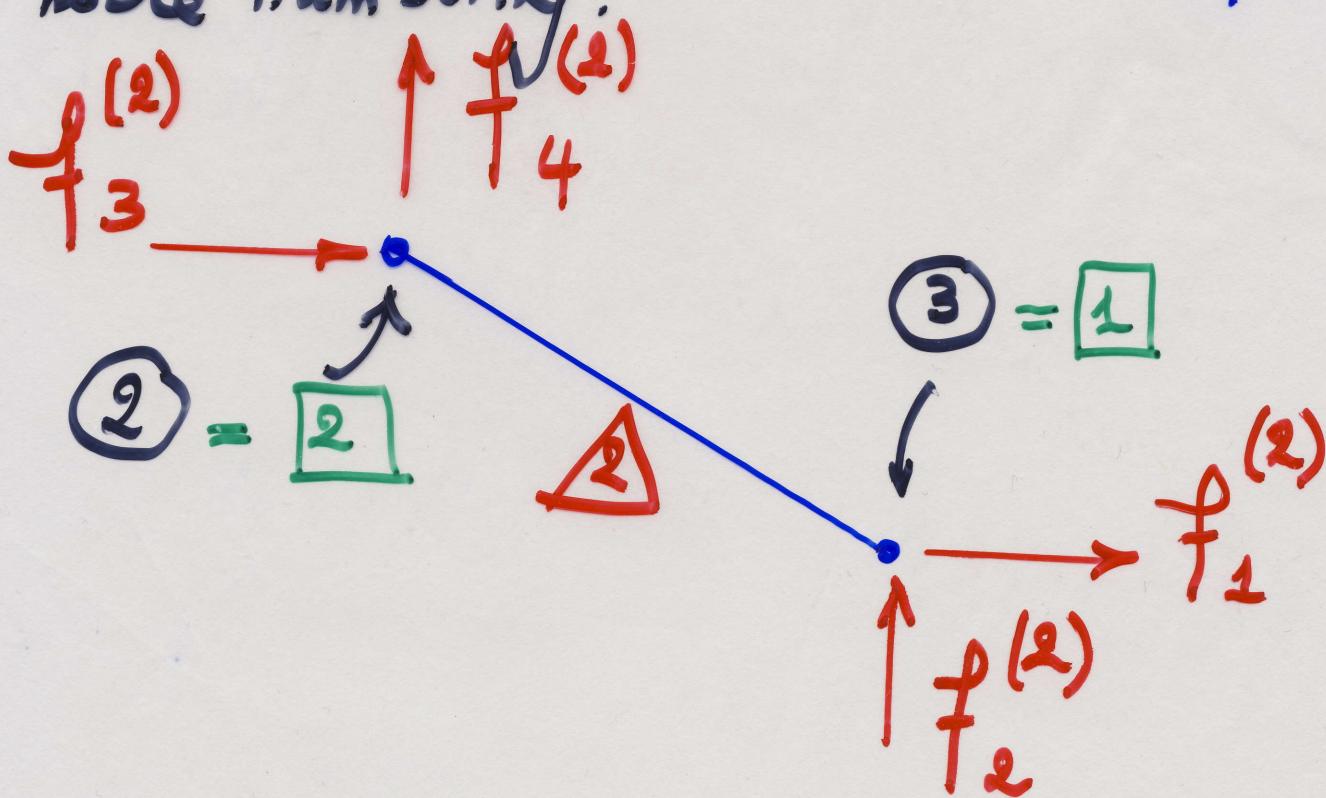
$f_i^{(e)}$ = i th internal force of elem e
 $i = 1, 2, 3, 4 \}$ for this
 $e = 1, 2$ example

FBD of bar elem 2:

14-3

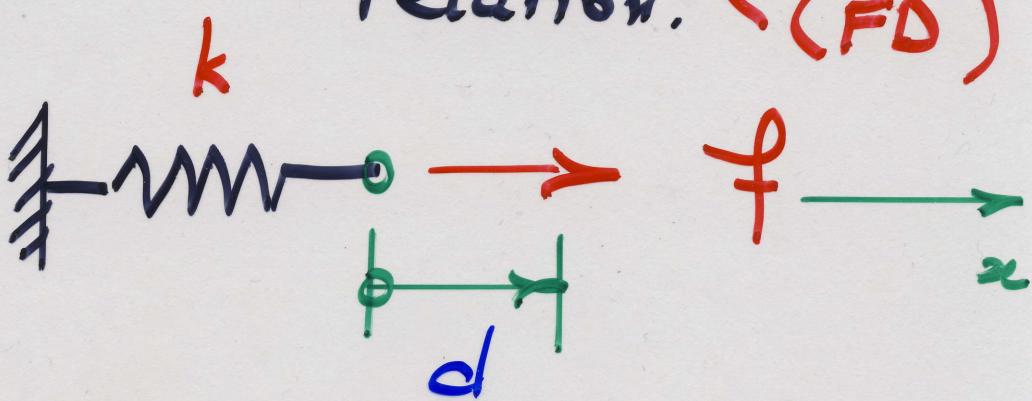


Another choice of local node numbering:



Next big step: Force-disp. (4-4
relation, κ (FD))

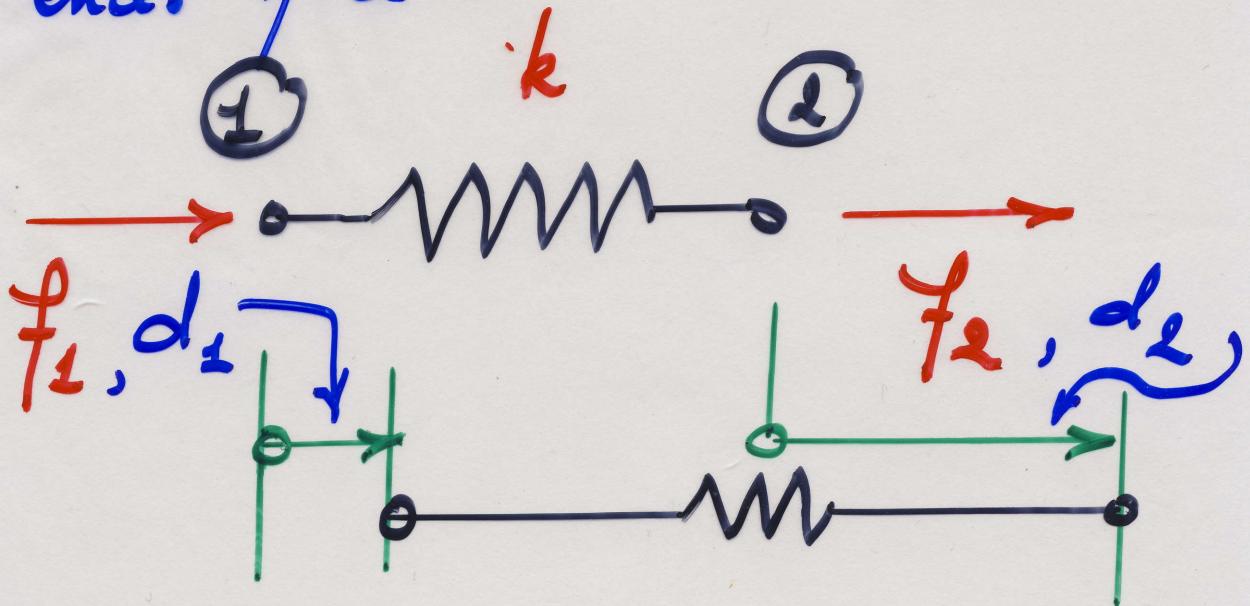
Recall:



FD rel. of 1-D spring elem:
(w/ 1 end fixed)

$$f = k d$$

FD rel. of 1-D spring with
2 ends free:



$$\boxed{\begin{Bmatrix} f_1 \\ f_2 \end{Bmatrix} = \begin{bmatrix} k & -k \\ -k & k \end{bmatrix} \begin{Bmatrix} d_1 \\ d_2 \end{Bmatrix}} \quad \text{L4-5}$$

$\overset{2 \times 1}{\text{row}} \quad \overset{2 \times 1}{\text{col}}$

Case 1: Observer sits on node ①

$$f_2 = k(d_2 - d_1)$$

Case 2: Obs. sits on node ②
or equil. $f_1 + f_2 = 0$

$$\Rightarrow f_1 = -f_2 = -k(d_2 - d_1) \\ = k(d_1 - d_2)$$

Mtg 5: Fri, 5 Sep 08, EML 4500 15-1
Read: Chap 4 (Trusses, beams, frames)

Chap 1: Big picture

Sects 1.1. Discretization

1.1.1 Plane truss elem

1.2. Assembly of elem eqs.

Ex 1.4: Five-bar truss

1.4. Elem soln & model vali-

1.4.1. Plane truss elem.

Steps to solve simple truss syst

described on p. 4-1 (Recipe)

Mtg 4 [↑] & slide #

± Global picture (description) :
At structure level

* global dofs (disp. dofs)

* global unknowns in general
forces

Actually, the disp dofs are partitioned into : 15-2

- * a known part, e.g., fixed dofs, constraints
- * an unknown part: solved using FEM.

(See truss example on p. 4-1)

Similarly for the global forces:

- * a known part: Applied forces
- * an unknown part: Reactions

2. Element picture:

- * Elem dofs }
 - * Elem forces }
- Either in global
coord. syst or
in local coord.
syst.

3. Global FD rel:

- * Elem. stiffness matrices in global coord.
- * Elem. force matrices in global coord.

* Assembly of elem stiff. mat. and elem force mat. into global FD rel. : L5-3

"Free-free" system (unconstrained) $\underline{K} \underline{d} = \underline{F}$

$\underline{K}_{nxn} \quad \underline{d}_{nx1} \quad \underline{F}_{nx1}$

\underline{K} singular

4. Elimination of known defs. to reduce the global FD rel.

(stiffness matrix non-singular
 \rightarrow invertible)

$\bar{\underline{K}} \bar{\underline{d}} = \bar{\underline{F}}$ $m < n$

$m \times m \quad m \times 1 \quad m \times 1$

$m =$ no of unknown disp. def's

$n =$ no of both known and unknown disp. def's.

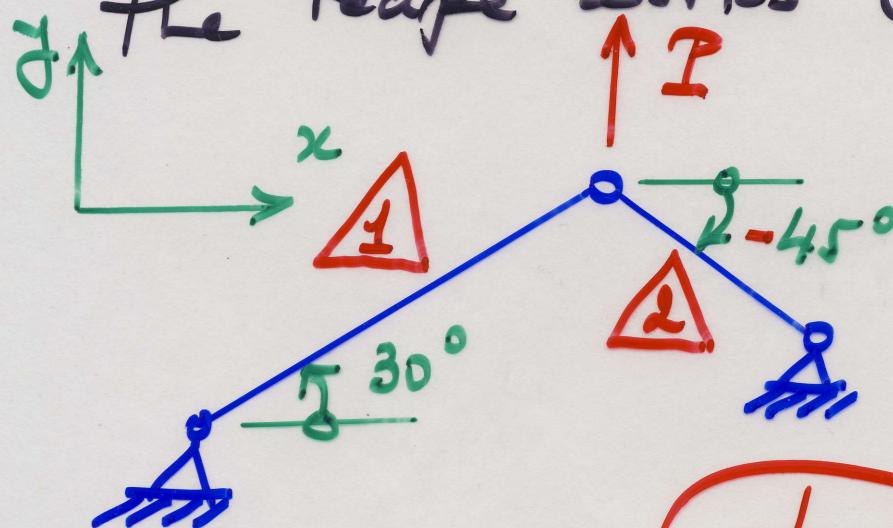
$\bar{\underline{K}}$ non singular $\Rightarrow \bar{\underline{K}}^{-1}$ exists
 $(\bar{\underline{K}}$ invertible)

$$\Rightarrow \underline{\underline{\delta}} = \underline{\underline{K}}^{-1} \underline{\underline{F}}$$

$m \times 1$ $m \times m$ $m \times 1$

5. Compute elem forces from now known $\underline{\underline{\delta}}$ \Rightarrow elem stresses
6. Compute reactions. (unknown forces)

Take a specific example to see how the recipe works (no justification yet)



Data:

Elem length:

$$L^{(1)} = 4$$

$$L^{(2)} = 2$$

Young's modulus:

$$E^{(1)} = 3$$

$$E^{(2)} = 5$$

Cross section area:

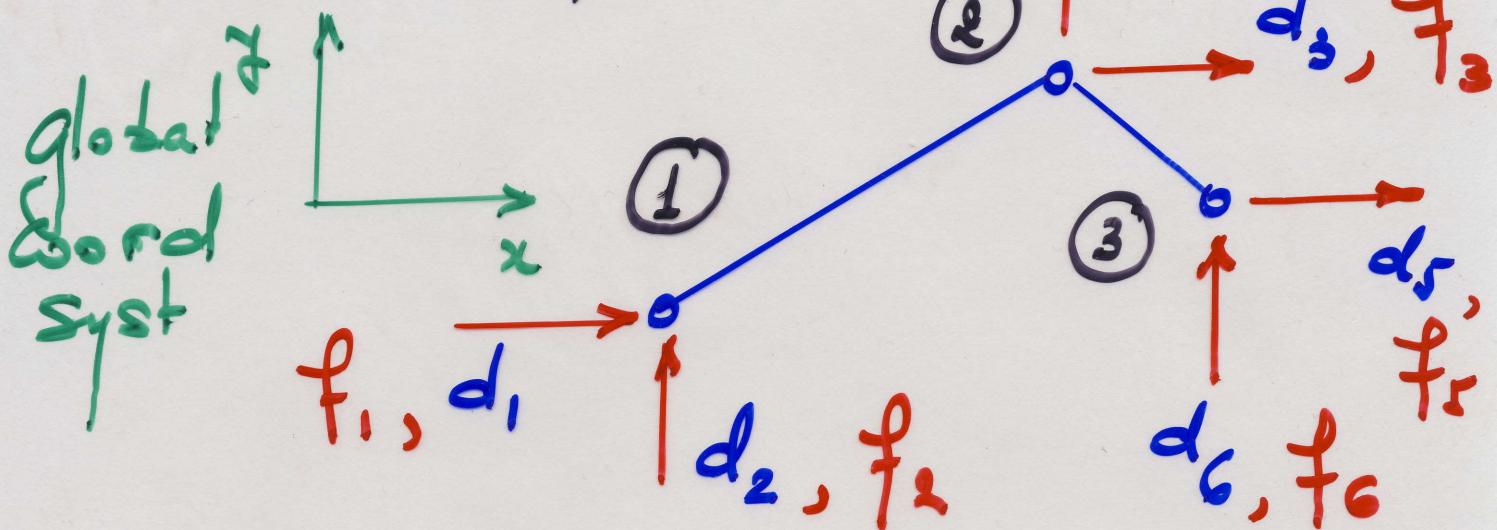
$$A^{(1)} = 1$$

$$A^{(2)} = 2$$

Inclination angle: $\theta^{(1)} = 30^\circ$ L5-5
 $\theta^{(2)} = -45^\circ$

1). Global picture:

Global dofs



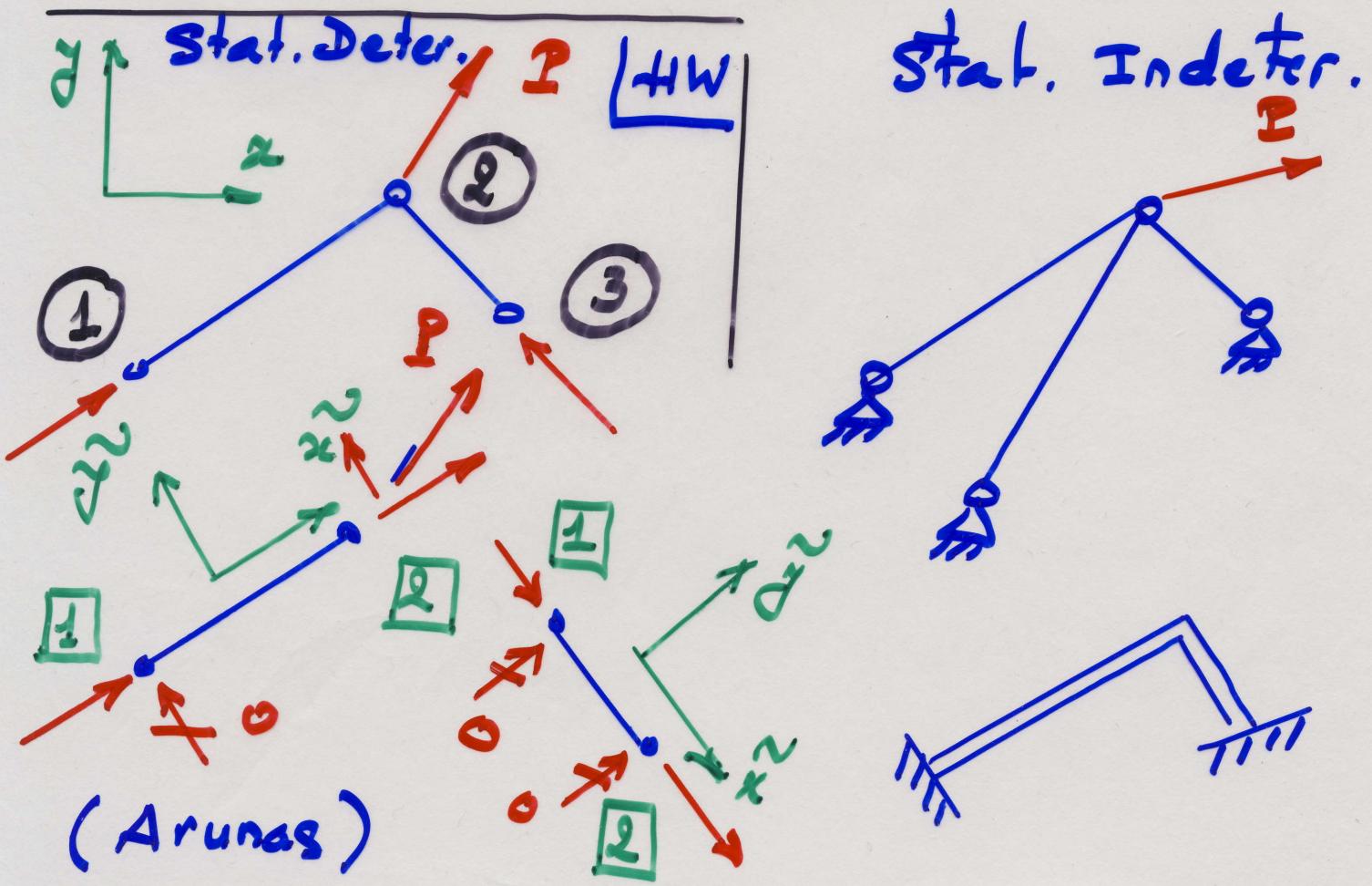
① = global node num., n

Numbering the disp dofs:

- * Follow order of global node num.
- * For each node, follow the order of global coord. axes, number the disp. dofs for that node.

Global forces: same thing (5-6)

$$\begin{array}{l} \text{F}_1 \leftarrow \left\{ \begin{array}{c} f_1 \\ \vdots \\ f_6 \end{array} \right\} = \left[\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \quad \underline{\mathbf{K}} \\ \text{F}_6 \leftarrow \left\{ \begin{array}{c} f_1 \\ \vdots \\ f_6 \end{array} \right\} = \left[\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \quad \underline{\mathbf{d}} \\ \underbrace{\text{F}}_{\substack{6 \times 1}} \quad \underbrace{\text{global stiffness}}_{\substack{\text{matrix}}} \quad \underbrace{\mathbf{K}}_{\substack{6 \times 6}} \\ \text{global force} \\ \text{col. matrix} \end{array}$$



2) Elec. picture

3) Global FD at elem level:

$$\underline{k}^{(e)} \underline{d}^{(e)} = \underline{f}^{(e)}$$

4×4 4×1 $- 4 \times 1$

elem stiffness
matrix for elem e
 $e=1,2$

elem force
mat.

elem disp
mat. of elem e

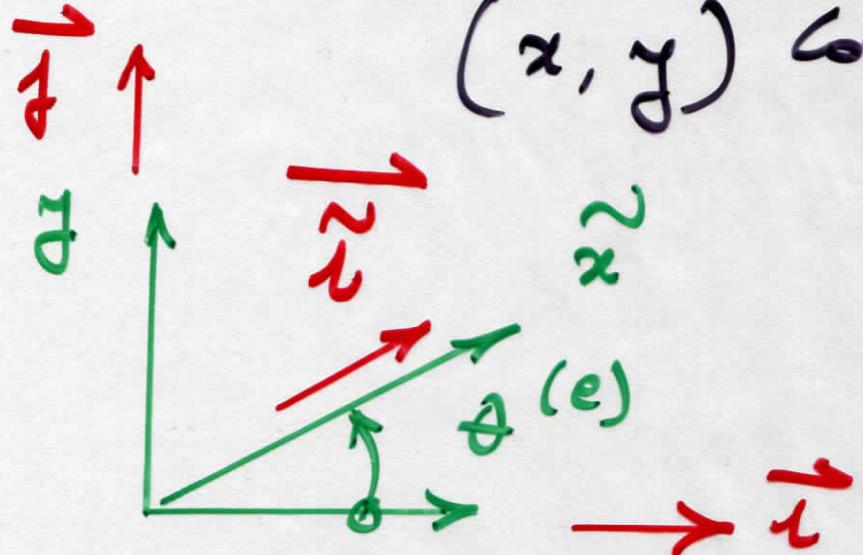
Book p. 225, 2nd eq. from bottom:

$$\underline{k}^{(e)} = \begin{bmatrix} d_1^{(e)} & 2 & 3 & 4 \\ (\ell^{(e)})^2 & \ell_m^{(e)} & -(\ell^{(e)})^2 & -\ell_m^{(e)} \\ \ell_m^{(e)} & (\ell^{(e)})^2 & \ell_m^{(e)} & -(m^{(e)})^2 \\ -(\ell^{(e)})^2 & -\ell_m^{(e)} & (\ell^{(e)})^2 & \ell_m^{(e)} \\ -\ell_m^{(e)} & -(m^{(e)})^2 & \ell_m^{(e)} & (m^{(e)})^2 \end{bmatrix}_{4 \times 4} = \underline{k}^{(e)}$$

$$k^{(e)} = \frac{E^{(e)} A^{(e)}}{L^{(e)}} \quad \text{axial stiffness of bar elem "e"} \quad (6-2)$$

$e = 1, 2$

$l^{(e)}, m^{(e)}$ = director cosines of \tilde{x} axis (goes from $\boxed{1}$ to $\boxed{2}$) wrt global (x, y) coord.



$$l^{(e)} = \tilde{x} \cdot \hat{x} = \cos \theta^{(e)}$$

$$m^{(e)} = \tilde{x} \cdot \hat{y} = \cos\left(\frac{\pi}{2} - \theta^{(e)}\right)$$

$$\tilde{x} = \cos \theta^{(e)} \hat{x} + \sin \theta^{(e)} \hat{y}$$

$$\vec{r}, \vec{x} = A \cdot (\cos \theta^{(e)} \vec{x} + \sin \theta^{(e)} \vec{f})$$

$$= \cos \theta^{(e)} \vec{x} + \sin \theta^{(e)} \vec{f}$$

$$\vec{r} \cdot \vec{f} = HW$$

HW: Write $\underline{k}^{(1)}, \underline{k}^{(2)}$: provide numerical values for all coeff.

Note: The director cosines are the components of \vec{r} (unit vector along \vec{x} axis) wrt basis (\vec{x}, \vec{f})

$$\vec{r} = \underbrace{\cos \theta^{(e)}}_{l^{(e)}} \vec{x} + \underbrace{\sin \theta^{(e)}}_{m^{(e)}} \vec{f}$$

Mtg 7: Wed, 10 Sep 08. EML 4500 (7-1)

Model 2-bar truss syst (Cont'd)

Elem 1: $\theta^{(1)} = 30^\circ$

$$l^{(1)} = \cos \theta^{(1)} = \cos 30^\circ = \frac{\sqrt{3}}{2}$$

$$m^{(1)} = \sin \theta^{(1)} = \sin 30^\circ = \frac{1}{2}$$

$$k^{(1)} = \frac{E^{(1)} A^{(1)}}{L^{(1)}} = \frac{(3)(1)}{4} = \frac{3}{4}$$

$$\underline{k}^{(1)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ k_{11}^{(1)} & k_{12}^{(1)} & k_{13}^{(1)} & k_{14}^{(1)} \\ k_{21}^{(1)} & k_{22}^{(1)} & k_{23}^{(1)} & k_{24}^{(1)} \\ k_{31}^{(1)} & k_{32}^{(1)} & k_{33}^{(1)} & k_{34}^{(1)} \\ k_{41}^{(1)} & . & . & k_{44}^{(1)} \end{bmatrix}_{4 \times 4}$$

$$= \left[k_{ij}^{(e)} \right]_{4 \times 4}$$

row \nearrow { \nwarrow } col

$$i = 1, 2, \dots, 4$$

$$j = 1, \dots, 4$$

4x4

$$k_{11}^{(1)} = k^{(1)} (l^{(1)})^2 = \left(\frac{3}{4}\right) \left(\frac{\sqrt{3}}{2}\right)^2 \quad \text{7.2}$$

row \nearrow col

$$k_{12}^{(1)} = k^{(1)} (l^{(1)} m^{(1)}) = \frac{3\sqrt{3}}{16} \quad (\text{Megan})$$

$$k_{42}^{(1)} = -k^{(1)} (m^{(1)})^2 = -\frac{3}{16} \quad (\text{Megan})$$

Obs: 1) Only need to compute 3 numbers. Other coeffs have same abs value, just differ by \oplus or \ominus .

2) Mat. $\underline{k}^{(1)}$ is symmetric, i.e.,

$$k_{ij}^{(1)} = k_{ji}^{(1)} \quad \text{e.g.}$$

$$k_{13}^{(1)} = k_{31}^{(1)} \quad \begin{array}{l} \text{(just interchange the row} \\ \text{and col. indices)} \end{array}$$

In general, $k_{ij}^{(e)} = k_{ji}^{(e)}$ (7-3)

or $\underline{k}^{(e) \dagger} = \underline{k}^{(e)}$

(Transpose)

The transpose of $\underline{k}^{(e)}$ is equal to

$$\underline{k}^{(e)} = \begin{bmatrix} k_{11}^{(e)} & k_{12}^{(e)} & k_{13}^{(e)} & k_{14}^{(e)} \\ k_{21}^{(e)} & k_{22}^{(e)} & k_{23}^{(e)} & k_{24}^{(e)} \\ k_{31}^{(e)} & k_{32}^{(e)} & k_{33}^{(e)} & k_{34}^{(e)} \\ k_{41}^{(e)} & k_{42}^{(e)} & k_{43}^{(e)} & k_{44}^{(e)} \end{bmatrix}$$

Sym.

upper triangular part

$$\underline{\text{Elem 2:}} \quad k^{(2)} = \frac{E^{(2)} A^{(2)}}{L^{(2)}} = \frac{(5)(2)}{2} = \underline{\underline{5}}$$

$$\theta^{(2)} = -\frac{\pi}{4} \Rightarrow l^{(2)} = \cos\left(-\frac{\pi}{4}\right) = \frac{\sqrt{2}}{2}$$

$$m^{(2)} = \sin\left(-\frac{\pi}{4}\right) = -\frac{\sqrt{2}}{2}$$

$$\underline{k}^{(2)} = \begin{bmatrix} k_{ij}^{(2)} \end{bmatrix}_{4 \times 4}$$

$$k_{11}^{(2)} = k^{(2)} \left(l^{(2)}\right)^2 = (5) \left(\frac{\sqrt{2}}{2}\right)^2 = 2.5$$

Obs: 1) Abs. values of all coeffs

(Luke) $k_{ij}^{(e)}$, $e=2$, $(i,j) = 1, \dots, 4$
are the same \Rightarrow comp. 1 coeff.

For other coeff, add \oplus or \ominus .

2) $\underline{k}^{(2)T} = \underline{k}^{(2)}$, i.e.,
 $\underline{k}^{(2)}$ sym.

$$\text{Elem FD rel. : } \begin{bmatrix} \underline{k}^{(e)} \\ \underline{d}^{(e)} \\ \underline{f}^{(e)} \end{bmatrix}_{4 \times 4} = \begin{bmatrix} \underline{k}^{(e)} \\ \underline{d}^{(e)} \\ \underline{f}^{(e)} \end{bmatrix}_{4 \times 1} \quad \text{for } e=1, 2$$

$$\underline{d}^{(e)} = \begin{Bmatrix} d_1^{(e)} \\ \vdots \\ d_4^{(e)} \end{Bmatrix}_{4 \times 1} \quad \underline{f}^{(e)} = \begin{Bmatrix} f_1^{(e)} \\ \vdots \\ f_4^{(e)} \end{Bmatrix}_{4 \times 1}$$

$$\text{Global FD rel. : ("free-free" struct)}$$

$$\boxed{\underline{K} \underline{d} = \underline{F}}_{n \times n \quad n \times 1 \quad n \times 1}$$

Here, $n=6$ (p. 5-5)

1 2 3 4 5 6

$$\begin{bmatrix} K_{11} & K_{12} & \dots & & K_{16} \\ \vdots & \vdots & \ddots & & \vdots \\ & & & \ddots & \\ K_{61} & \dots & & & K_{66} \end{bmatrix} \begin{Bmatrix} d_1 \\ \vdots \\ d_6 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ \vdots \\ F_6 \end{Bmatrix}$$

Mtg 8 : Fri, 12 Sep 08, EML 4500 (8-1)

Cont'd from P. 7-5:
In Compact notation:

$$[K_{ij}] \{d_j\} = \{F_i\}$$

(more generally $n \times n$)

$$\sum_{j=1}^6 K_{ij} d_j = F_i, \quad i=1, \dots, 6$$

$K = [K_{ij}]$ $n \times n$ = global stiffness mat.

$\underline{d} = \{d_j\}$ $n \times 1$ = global disp. mat.

$\underline{F} = \{F_i\}$ $n \times 1$ = global force mat.

Recall elem FD rel. (p. 7-5) 8-2

$$\boxed{\underline{k}^{(e)} \underline{d}^{(e)} = \underline{f}^{(e)}} \\ \underline{k}^{(e)} \quad \underline{d}^{(e)} \quad \underline{f}^{(e)} \\ \underline{4 \times 4} \quad \underline{4 \times 1} \quad \underline{4 \times 1}$$

$$\underline{k}^{(e)}_{4 \times 4} = [k_{ij}^{(e)}] = \text{elem stiff. mat.}$$

$$\underline{d}^{(e)}_{4 \times 1} = \{d_j^{(e)}\}_{4 \times 1} = \text{elem disp. mat.}$$

$$\underline{f}^{(e)}_{4 \times 1} = \{f_i^{(e)}\}_{4 \times 1} = \text{elem force mat.}$$

How to go from elem matrices
(stiff, disp, force) to global mat?
Through an assembly process:

- * Identify the correspondence betw.
elem disp dofs and global disp.
dofs.

Global level : P. 5-5

L8-3

$$\{d_1, d_2, \dots, d_6\}$$

Elem level : P. 4-3, P. 4-2

* Elem 1 : $\{d_1^{(1)}, d_2^{(1)}, d_3^{(1)}, d_4^{(1)}\}$

* Elem 2 : $\{d_1^{(2)}, \dots, d_4^{(2)}\}$

Identification global-local dofs:

$$d_1 = d_1^{(1)} \leftarrow \begin{matrix} \text{elem } 1 \\ \text{1st dof} \end{matrix} \quad \left. \begin{matrix} \text{global} \\ \text{node } ① \end{matrix} \right\}$$

↑
1st global dof

$$d_2 = d_2^{(1)}$$

$$d_3 = d_3^{(1)} = d_1^{(2)} \quad \left. \begin{matrix} \\ \text{node } ② \end{matrix} \right\}$$
$$d_4 = d_4^{(1)} = d_2^{(2)}$$

$$d_5 = d_3^{(2)} \quad d_6 = d_4^{(2)} \quad \left. \right\} \text{node } ③$$

8-4

Conceptual step of assembly:
(topology of \underline{K})

$$\begin{array}{c}
 \text{Diagram illustrating the decomposition of a } 6 \times 6 \text{ matrix } \mathbf{K} \text{ into } \mathbf{K}^{(1)} \text{ and } \mathbf{K}^{(2)} \\
 \text{Matrix } \mathbf{K}^{(1)} \text{ is a } 6 \times 6 \text{ matrix with a } 3 \times 3 \text{ submatrix highlighted in red.} \\
 \text{Matrix } \mathbf{K}^{(2)} \text{ is a } 6 \times 6 \text{ matrix with a } 3 \times 3 \text{ submatrix highlighted in blue.} \\
 \text{The equation shows } \mathbf{K} = \mathbf{K}^{(1)} + \mathbf{K}^{(2)} \\
 \text{Dimensions: } \mathbf{K} \in \mathbb{R}^{6 \times 6}, \mathbf{K}^{(1)} \in \mathbb{R}^{6 \times 6}, \mathbf{K}^{(2)} \in \mathbb{R}^{6 \times 6}, \mathbf{d} \in \mathbb{R}^{6 \times 1}, \mathbf{f} \in \mathbb{R}^{6 \times 1}
 \end{array}$$

$M_{\text{b}} + M_{\text{g}} = M_{\text{tot}}$, $S_{\text{tot}} = S_{\text{b}} + S_{\text{g}}$

1	2	3	4	5	6
$k_{11}^{(1)}$	$k_{12}^{(1)}$	$k_{13}^{(1)}$	$k_{14}^{(1)}$		
$k_{21}^{(1)}$	$k_{22}^{(1)}$	$k_{23}^{(1)}$	$k_{24}^{(1)}$		
$k_{31}^{(1)}$	$k_{32}^{(1)}$	$(k_{33}^{(1)} + k_{11}^{(2)})$	$(k_{34}^{(1)} + k_{12}^{(2)})$	$k_{13}^{(2)}$	$k_{14}^{(2)}$
$k_{41}^{(1)}$	$k_{42}^{(1)}$	$(k_{43}^{(1)} + k_{21}^{(2)})$	$(k_{44}^{(1)} + k_{22}^{(2)})$	$k_{23}^{(2)}$	$k_{24}^{(2)}$
		$k_{31}^{(2)}$	$k_{32}^{(2)}$	$k_{33}^{(2)}$	$k_{34}^{(2)}$
		$k_{41}^{(2)}$	$k_{42}^{(2)}$	$k_{43}^{(2)}$	$k_{44}^{(2)}$

$K_{6 \times 6}$

$$K_{11} = k_{11}^{(1)} = \frac{9}{16}$$

$$K_{12} = k_{12}^{(1)} = \frac{3\sqrt{3}}{16}$$

...

$$K_{33} = k_{33}^{(1)} + k_{11}^{(2)} = \frac{9}{16} + \frac{5}{2} = 3.0625$$

$$K_{34} = k_{34}^{(1)} + k_{12}^{(2)} = \frac{3\sqrt{3}}{16} + \left(-\frac{5}{2}\right)$$

$$\begin{aligned} K_{43} &= K_{34} = k_{43}^{(1)} + k_{21}^{(2)} \\ &\quad || \qquad \qquad \qquad || \\ -2.1752 &\qquad \qquad \qquad k_{34}^{(1)} \qquad \qquad \qquad k_{12}^{(2)} \end{aligned}$$

$$K_{44} = k_{44}^{(1)} + k_{22}^{(2)} = \frac{3}{16} + \frac{5}{2}$$

$$= 2.6875$$

4) Elimination of known dofs \Rightarrow
reduce global FD rel. (p. 5-3)

$$d_1 = d_2 = d_5 = d_6 = 0$$