

Hybrid CORDIC 2.A Sine/Cosine Generator

20170729

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Wilson ROM based Sine/Cosine Generation

[24] Fu & Willson Sine / Cosine Generation

ROM-based

for high resolution, ROM size grows exponentially

quarter-wave symmetry

$$\sin \theta = \cos \left(\frac{\pi}{2} - \theta \right)$$

$$\phi \in [0, 2\pi] \longrightarrow [0, \frac{\pi}{4}]$$

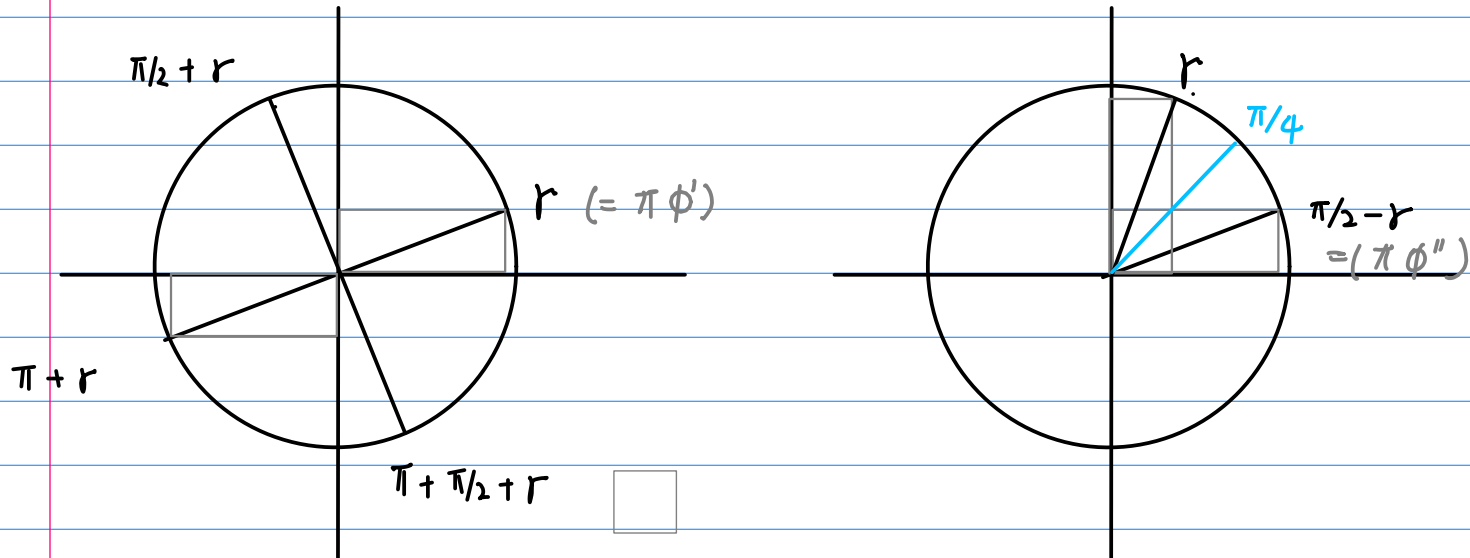
conditionally interchanging inputs X_0 & Y_0

conditionally interchanging and negating outputs X & Y

$$X = X_0 \cos \phi - Y_0 \sin \phi$$

$$Y = Y_0 \cos \phi + X_0 \sin \phi$$

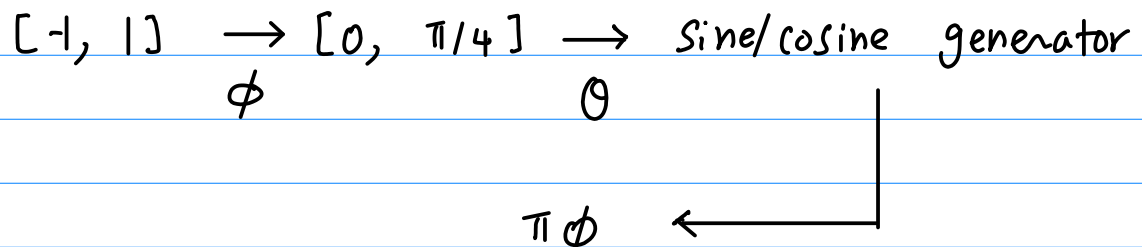
Madisetti VLSI arch



for frequency synthesis

Argument: signed normalized by π angle $[-1, 1]$

binary representation of a radian angle required



- ① a phase accumulator ϕ $[-1, 1]$
- ② a radian converter $\phi \rightarrow \theta$
- ③ a sine/cosine generator
- ④ an output stage

$$\begin{array}{cc}
 \sin \theta, & \cos \theta \\
 \sin \theta, & \cos \theta \\
 \downarrow & \downarrow \\
 \sin \pi\phi & \cos \pi\phi
 \end{array}$$

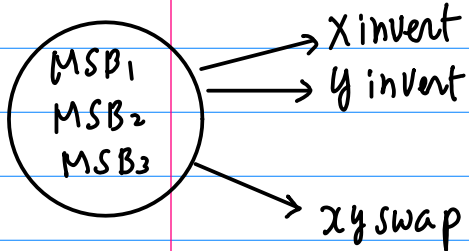
.

Output stage

$$\begin{aligned} \sin \theta &\rightarrow \sin \pi \phi \\ \cos \theta &\rightarrow \cos \pi \phi \end{aligned}$$

$[-\pi, +\pi]$

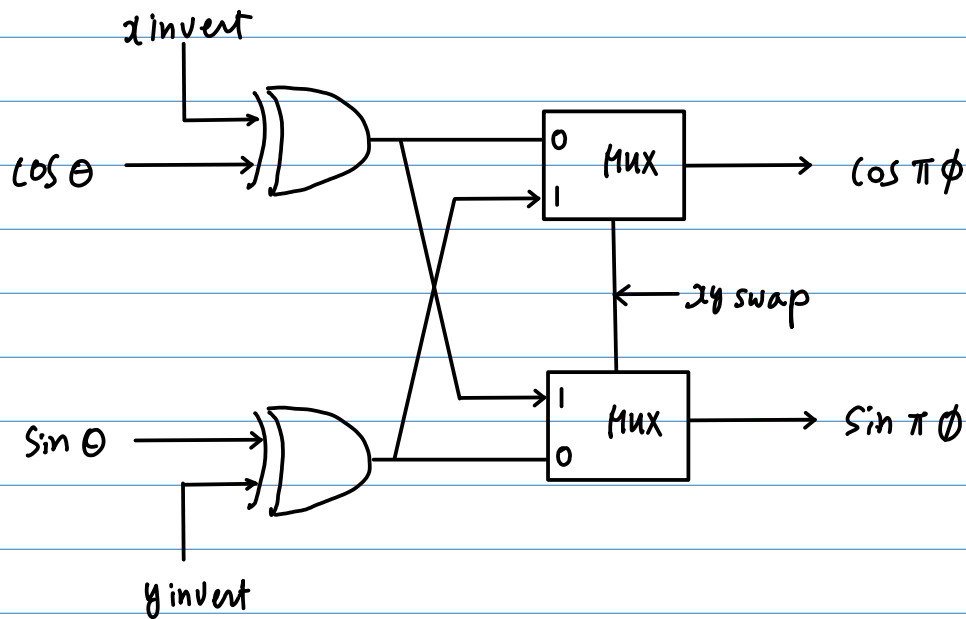
Negation / interchange

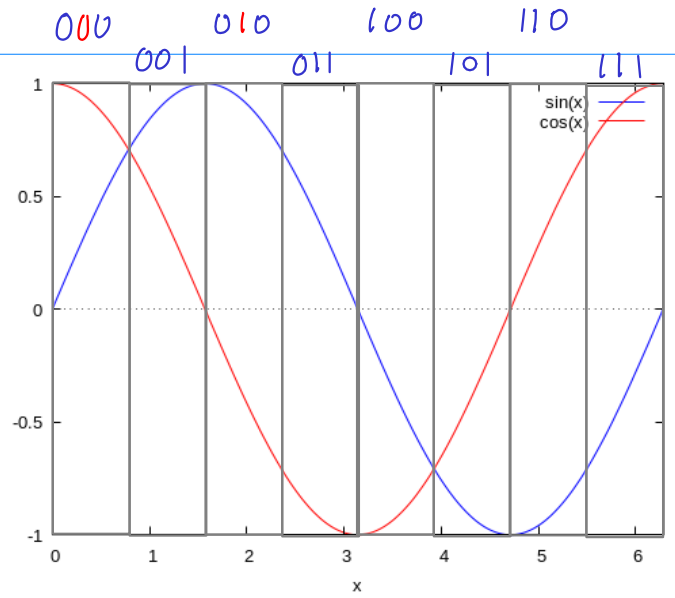
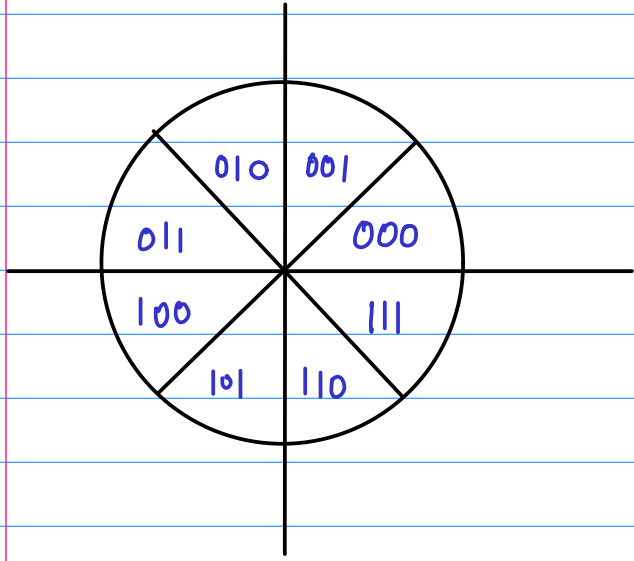


the negation of $\cos \theta = X_{N+1}$
 $\sin \theta = Y_{N+1}$

Interchange

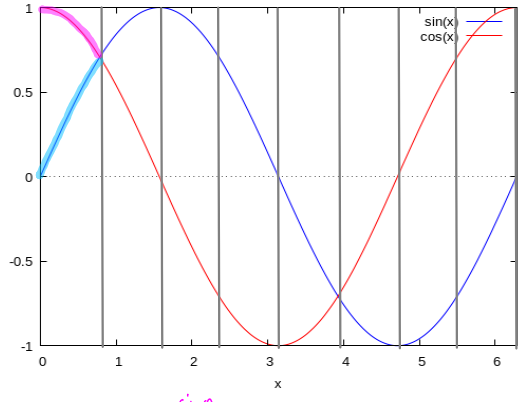
Negate before swap



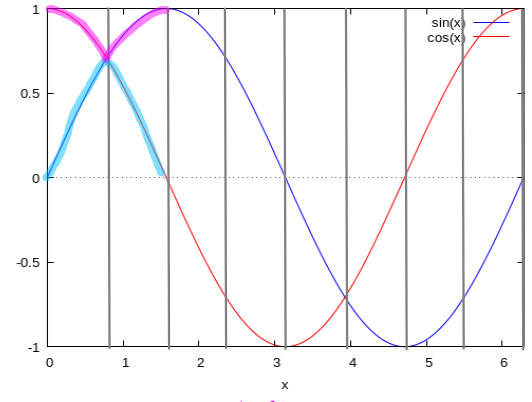


	cos	sin.			
	x_{inv}	y_{inv}	swap	$\cos \pi \theta$	$\sin \pi \theta$
000	0	0	0	$\cos \theta$	$\sin \theta$
001	0	0	1	$\sin \theta$	$\cos \theta$
010	0	1	1	$-\sin \theta$	$\cos \theta$
011	1	0	0	$-\cos \theta$	$\sin \theta$
100	1	1	0	$-\cos \theta$	$-\sin \theta$
101	1	1	1	$-\sin \theta$	$-\cos \theta$
110	1	0	1	$\sin \theta$	$-\cos \theta$
111	0	1	0	$\cos \theta$	$-\sin \theta$

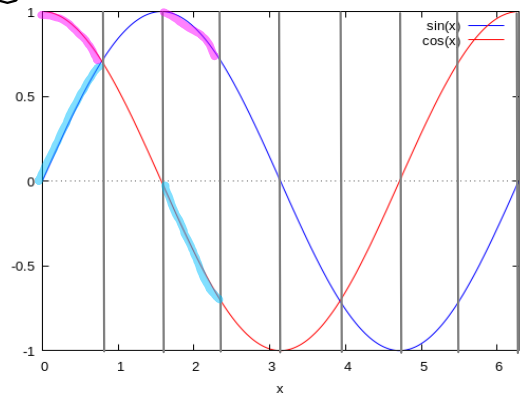
⑥ $\cos \theta$
 $\sin \theta$



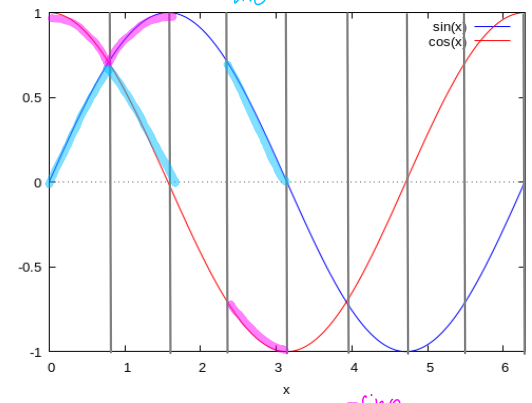
① $\sin \theta$
 $\cos \theta$



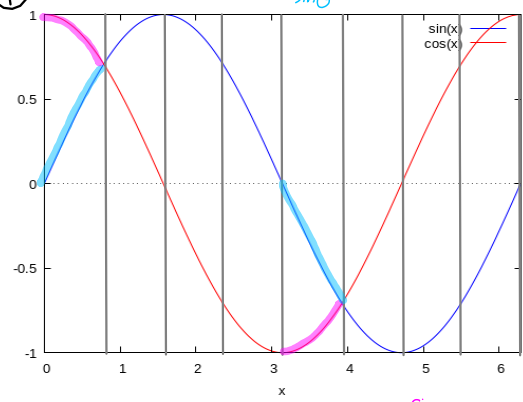
② $-\sin \theta$
 $\cos \theta$



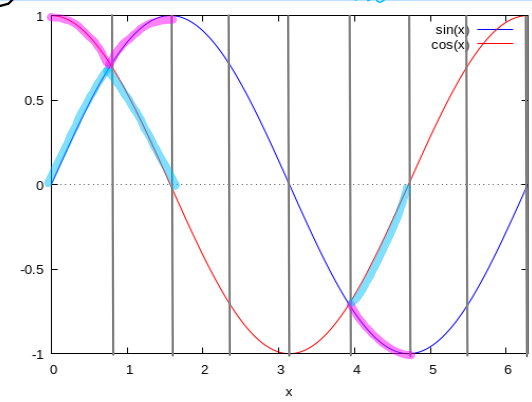
③ $-\cos \theta$
 $\sin \theta$



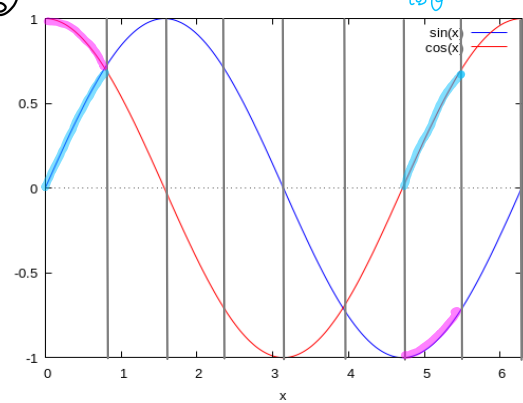
④ $-\cos \theta$
 $-\sin \theta$



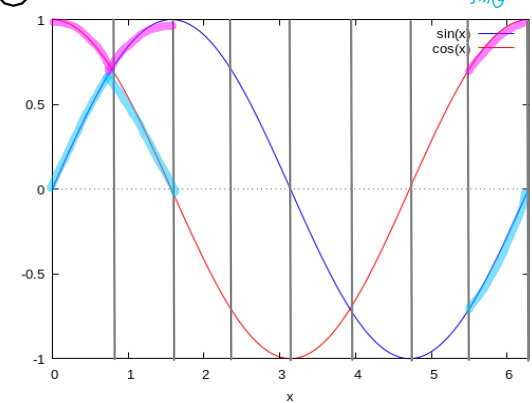
⑤ $-\sin \theta$
 $-\cos \theta$



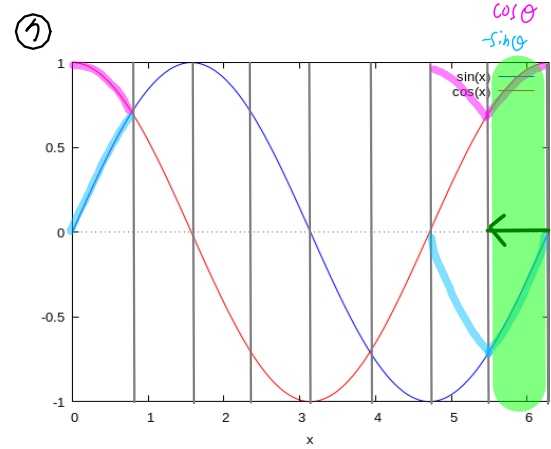
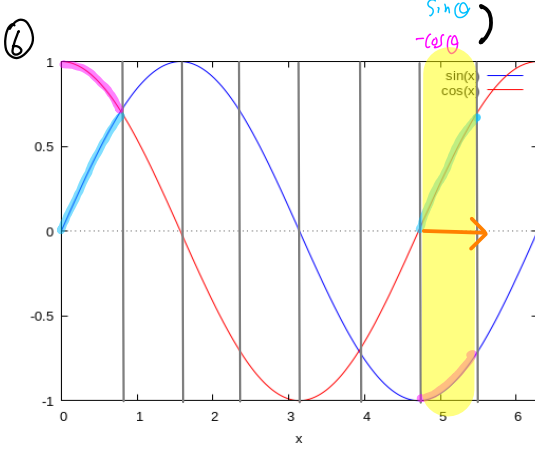
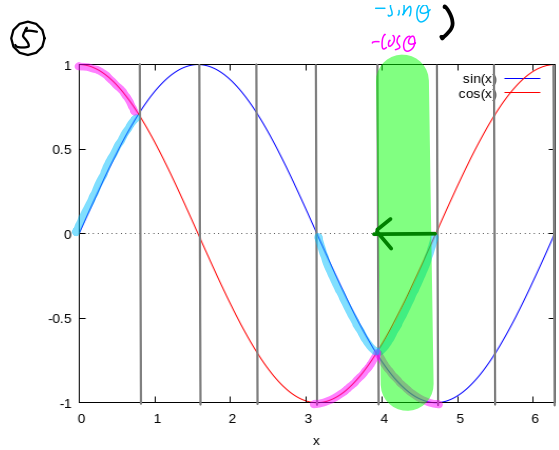
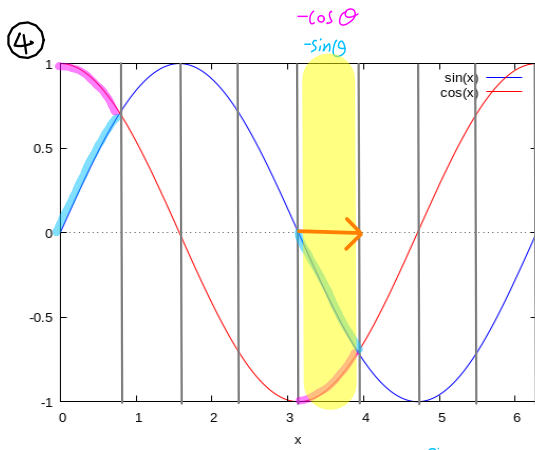
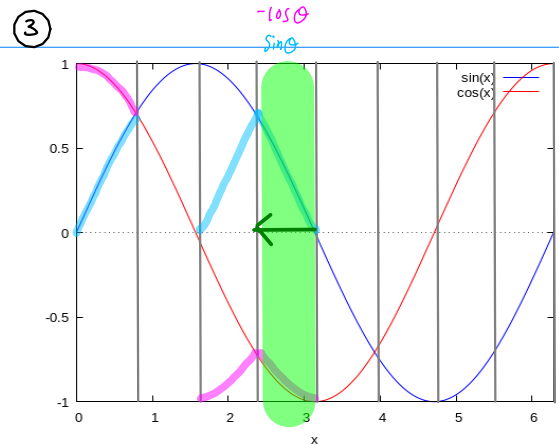
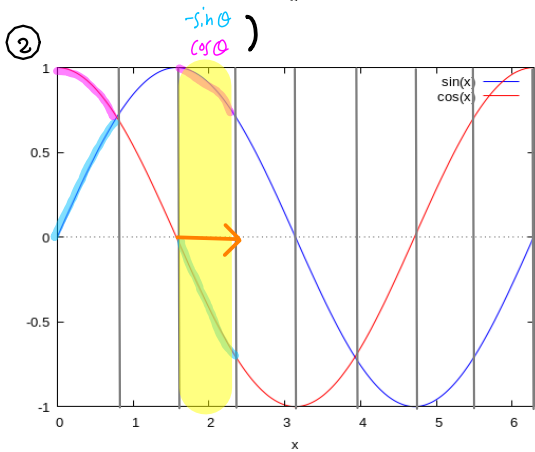
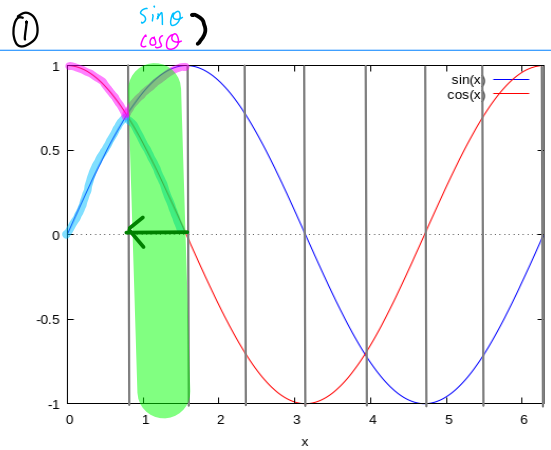
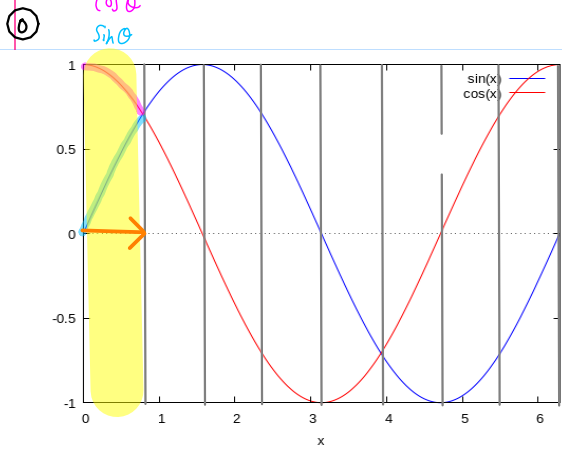
⑥ $\sin \theta$
 $-\cos \theta$



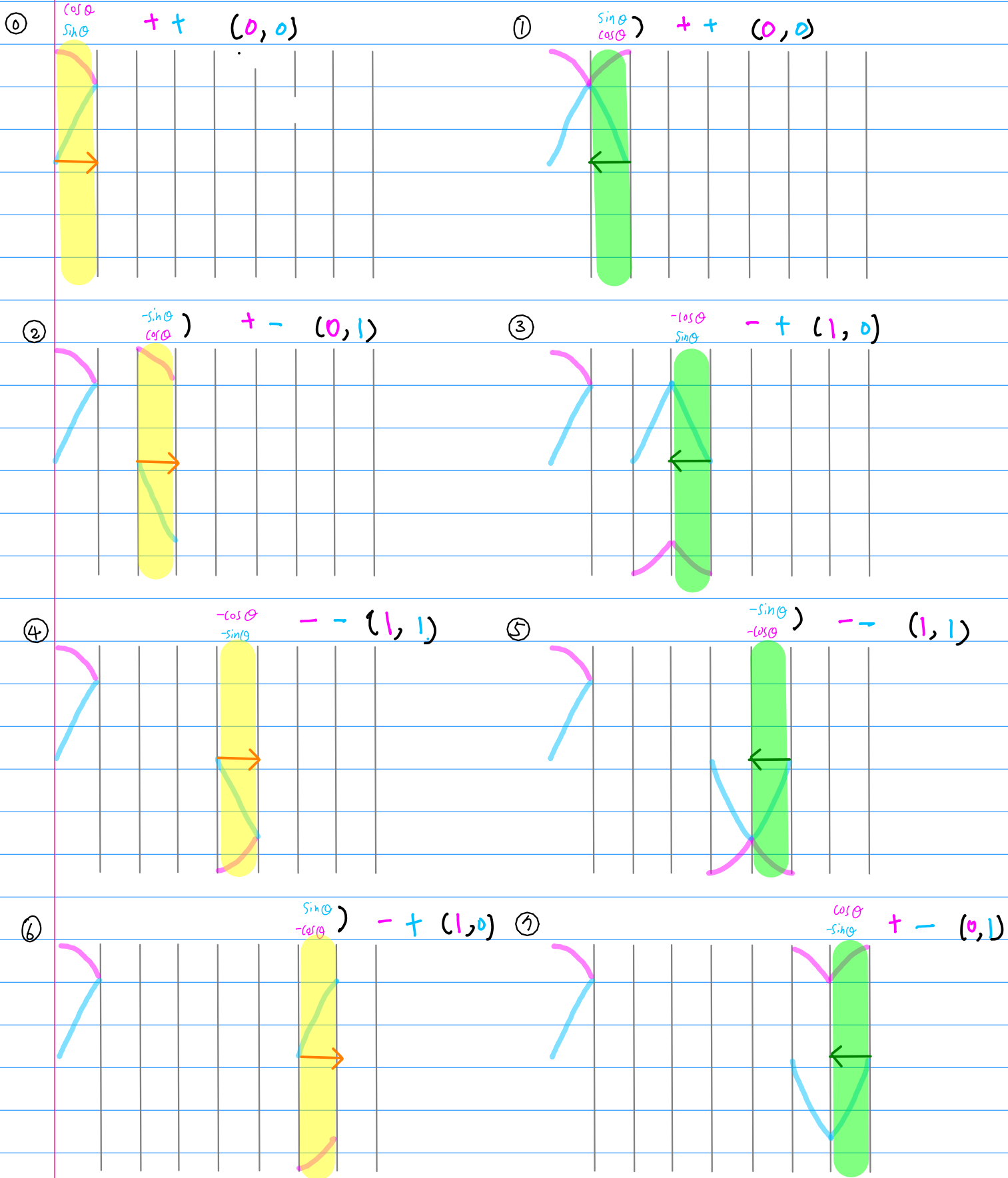
⑦ $\cos \theta$
 $-\sin \theta$



$\left\{ \begin{array}{l} \cos \phi \\ \sin \phi \end{array} \right.$



$\sin \phi$



	x_{inv}	y_{inv}	swap	$\cos \pi \phi$	$\sin \pi \phi$
0 0 0	0	0	0	$\cos \theta$	$\sin \theta$
0 0 1	0	0	1	$\sin \theta$	$\cos \theta$
0 1 0	0	1	1	$-\sin \theta$	$\cos \theta$
0 1 1	1	0	0	$-\cos \theta$	$\sin \theta$
1 0 0	1	1	0	$-\cos \theta$	$-\sin \theta$
1 0 1	1	1	1	$-\sin \theta$	$-\cos \theta$
1 1 0	1	0	1	$\sin \theta$	$-\cos \theta$
1 1 1	0	1	0	$\cos \theta$	$-\sin \theta$

0	0
0	0
0	1
1	0
1	1
1	0
0	1

0 0 0 0
 0 1 1 0
 1 1 1 1
 1 0 0 1

$$\theta = \sum_{k=1}^N b_k \theta_k$$

b_k sign + N bit — (N+1) bit fractional b

$$b_k \in \{0, 1\}$$

$$\theta_k = 2^{-k}$$

θ is constrained to be positive $b_0 = 0$

$$\theta = \sum_{k=1}^N b_k 2^{-k} = \phi_0 + \sum_{k=2}^{N+1} r_k 2^{-k}$$

$r_k \in \{-1, +1\}$ signed digits

ϕ_0 constant

⊕ subrotation by 2^{-k}

2 equal ⊕ half rotations by 2^{-k-1}

⊖ subrotation

2 equal opposite half rotations by $\pm 2^{-k-1}$

Binary Representation

$b_k = 1$: rotation by 2^{-k}

$b_k = 0$: zero rotation

k -th rotation

fixed rotation by 2^{-k-1}

{ pos rotation $\leftarrow b_k = 1$
neg rotation $\leftarrow b_k = 0$

Combining all the fixed rotations

→ initial fixed rotation

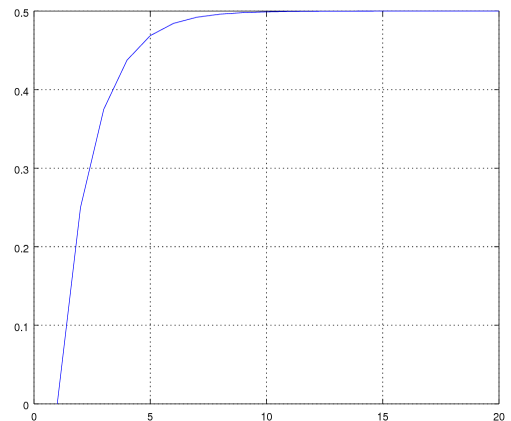
fixed \Rightarrow

b_1	b_2	b_3		b_N
2^{-1}	2^{-2}	2^{-3}		2^{-N}
$+2^{-2}$	$+2^{-3}$	$+2^{-4}$		$+2^{-N-1}$
$(b_1=1)$ $+2^{-2}$	$(b_2=1)$ $+2^{-3}$	$(b_3=1)$ $+2^{-4}$		$(b_N=1)$ $+2^{-N-1}$
$(b_1=0)$ -2^{-2}	$(b_2=0)$ -2^{-3}	$(b_3=0)$ -2^{-4}		$(b_N=0)$ -2^{-N-1}

initial fixed rotation

$$\phi_0 = \frac{1}{2^2} + \frac{1}{2^3} + \dots + \frac{1}{2^{N+1}}$$

$$= \frac{\frac{1}{2^2} (1 - \frac{1}{2^N})}{(1 - \frac{1}{2})} = \frac{1}{2} \left(1 - \frac{1}{2^N}\right) = \frac{1}{2} - \frac{1}{2^{N+1}}$$



Signed Digit Recoding

the rotation after recoding

— a fixed initial rotation ϕ_0

a sequence of \oplus/\ominus rotations

$b_k = 1$ $+ 2^{-k-1}$ rotation

$b_k = 0$ $- 2^{-k-1}$ rotation

$$r_k = (2b_{k-1} - 1)$$

$$2 \cdot 1 - 1 = +1$$

$$b_{k-1} = 1 \rightarrow r_k = +1$$

$$2 \cdot 0 - 1 = -1$$

$$b_{k-1} = 0 \rightarrow r_k = -1$$

The recoding need not be explicitly performed

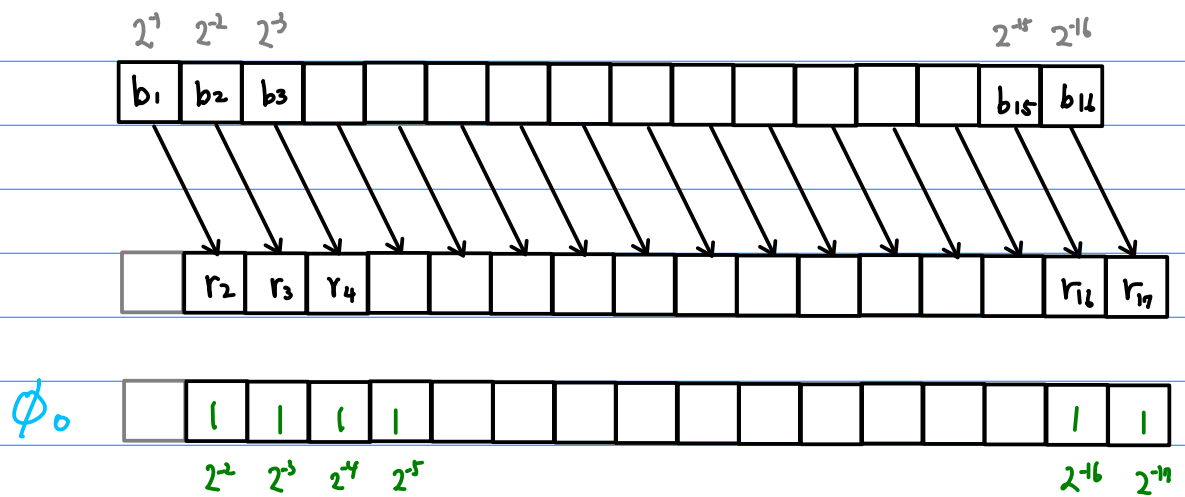
Simply replacing $b_k = 0$ with \ominus

This recoding maintains

a constant scaling factor \ll

$$\theta = \sum_{k=1}^N b_k 2^{-k} = \phi_0 + \sum_{k=2}^{N+1} r_k 2^{-k}$$

Binary Representation $\{b_k\}$



Signed Digit Recoding $\{r_k\}$

The scaling K .

The initial rotation ϕ_0 .

rotation starting point

$$(X_0, Y_0) = (K \cos \phi_0, K \sin \phi_0)$$

— fixed

— no error buildup

— rotation direction

immediately obtained from the binary representation

→ no need for comparison

the subangles

$$\theta_k = 2^{-k}$$

used in recoding

the subangles

$$\theta_k = \tan^{-1}(2^{-k})$$

used in CORDIC

$\tan \theta_k$ multipliers used

in the first few subrotation stages

cannot be implemented

as a simple shift-and-add operations

→ ROM implementation

reduced chip area

higher operating speed.

Architecture

- ① phase accumulator $\phi \in [-1, +1]$
- ② radian converter $\phi \rightarrow \theta \in [0, \frac{\pi}{4}]$
- ③ sine/cosine generator $\sin(\theta)$ $\cos(\theta)$
- ④ output stage $\sin(\pi\phi)$ $\cos(\pi\phi)$

Overflowing 2's complement accumulator

normalized by π angle ϕ

Need radian angle $\theta \in [0, \frac{\pi}{4}]$

$0 < \theta < 1$ rad

N-bit binary representation of θ

controls the direction of subrotation

N-bit precision of $\cos \theta$ & $\sin \theta$

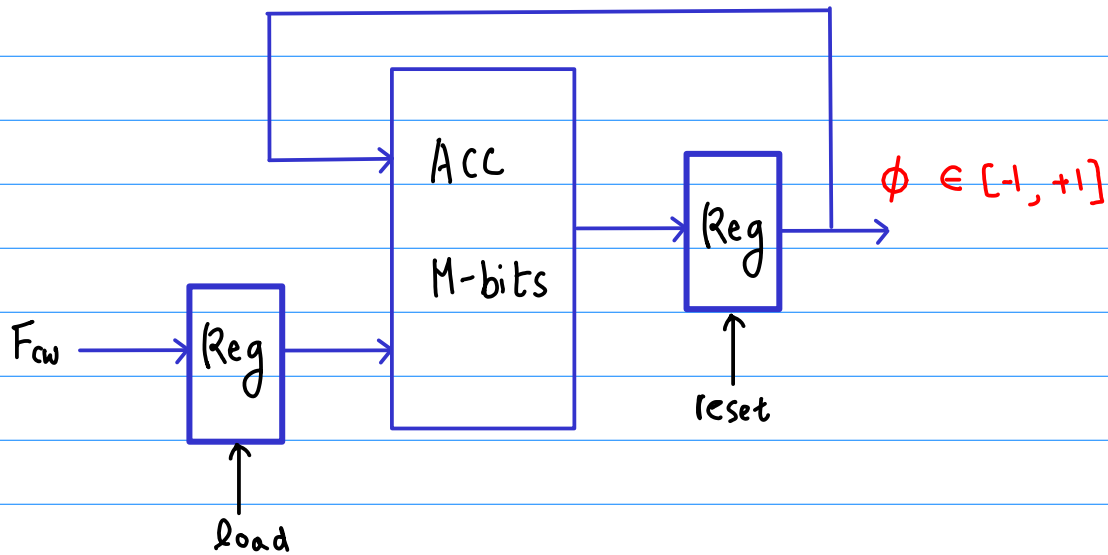
Output stage

$\theta \rightarrow \pi \phi$

$\sin \theta \rightarrow \sin \pi \phi$

$\cos \theta \rightarrow \cos \pi \phi$

phase accumulator



M-bit address

repeatedly increments the phase angle

by Fcw at each clock cycle

frequency control word

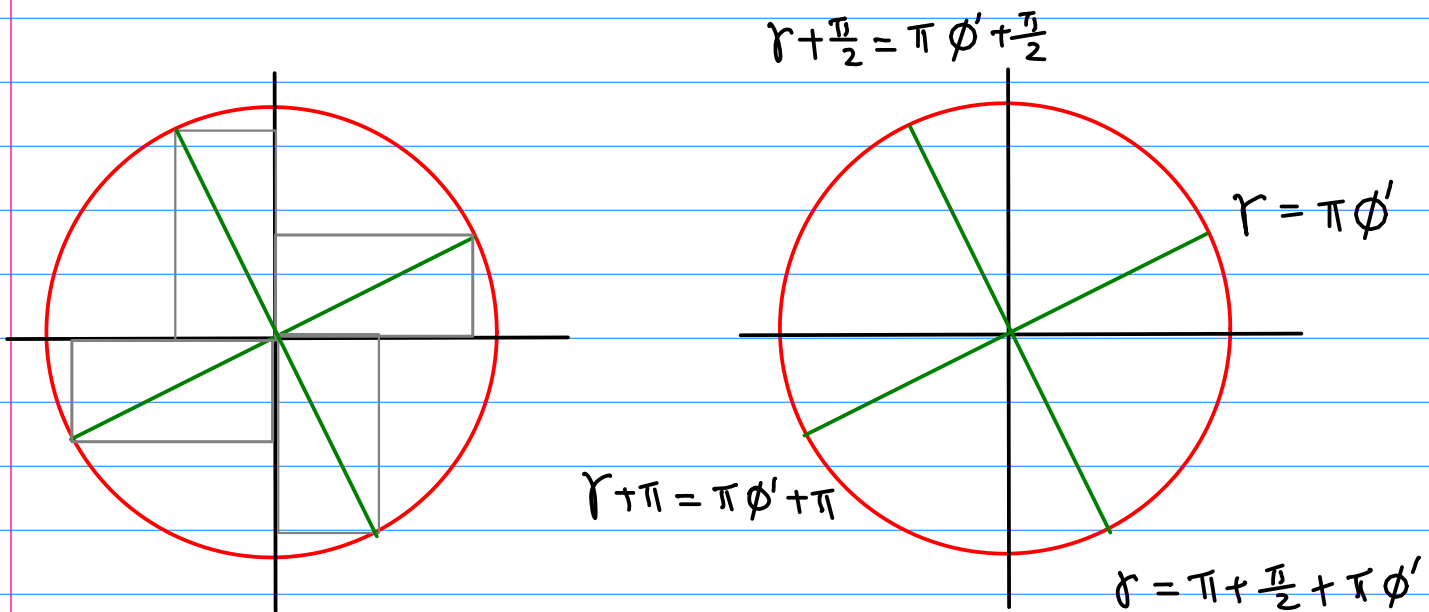
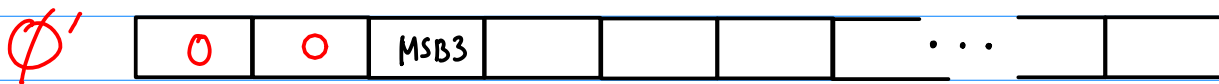
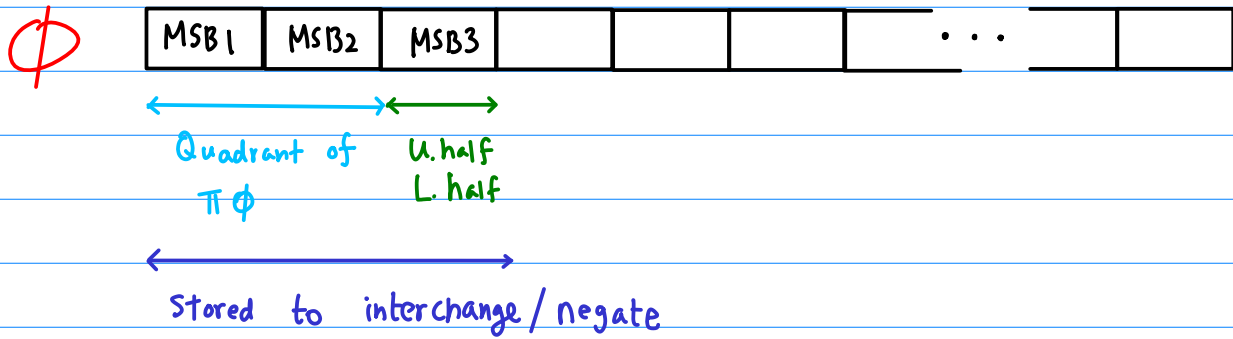
at time n , $\phi = n F_{cw} / 2^M$

$$\cos \phi = \cos (n F_{cw} / 2^M)$$

$$\sin \phi = \sin (n F_{cw} / 2^M)$$

Radian Converter

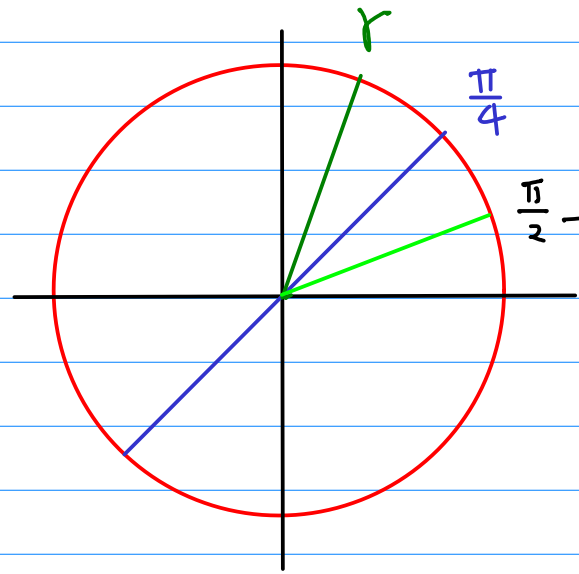
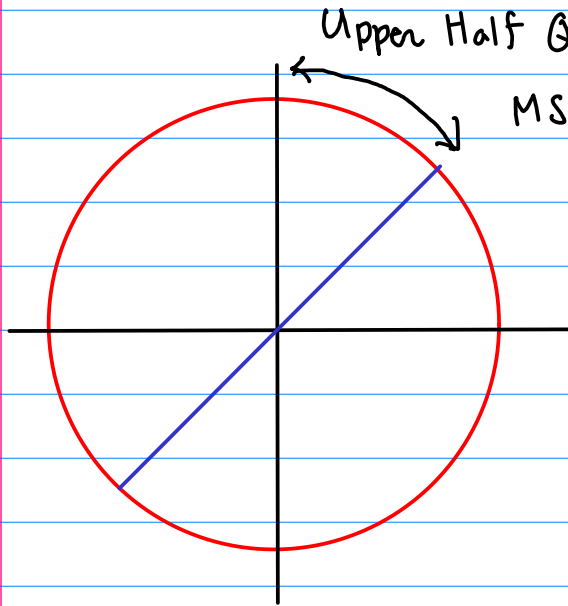
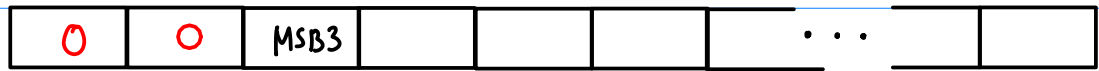
Normalized angle ϕ



ϕ	→	ϕ'	→	$\pi\phi'$	+	$0 \cdot \frac{\pi}{2}$	00
		↑		$\pi\phi'$	+	$1 \cdot \frac{\pi}{2}$	01
		1st Quad		$\pi\phi'$	+	$2 \cdot \frac{\pi}{2}$	10
				$\pi\phi'$	+	$3 \cdot \frac{\pi}{2}$	11

Ist Quadrant

ϕ'



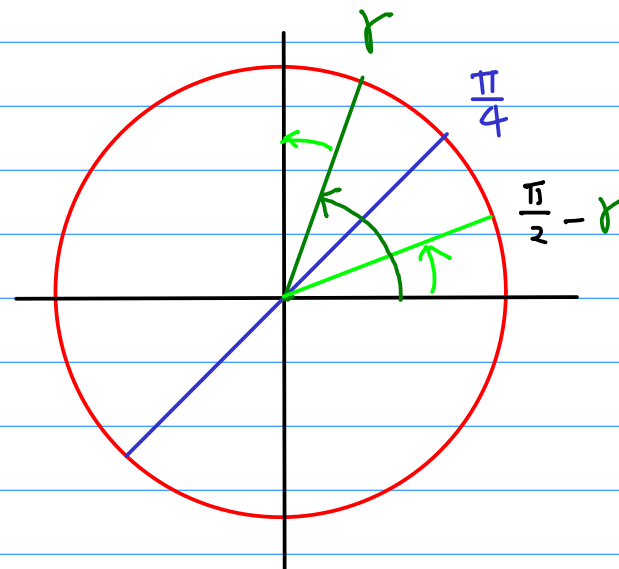
$r > \frac{\pi}{4}$: Upper Half (MSB₃ = 1)

$r < \frac{\pi}{4}$: Lower Half (MSB₃ = 0)

$$\cos r = \sin\left(\frac{\pi}{2} - r\right)$$

$$\sin r = \cos\left(\frac{\pi}{2} - r\right)$$

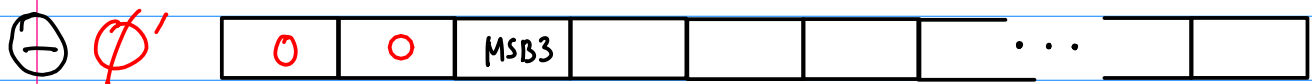
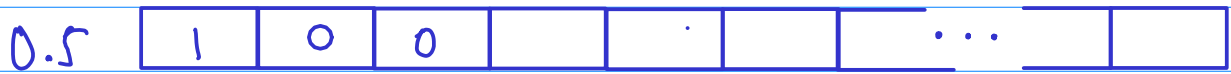
$$r > \frac{\pi}{4} \quad \frac{\pi}{2} - r < \frac{\pi}{4}$$





$MSB_3 = 1 \quad \phi' > \frac{\pi}{4}$

$\phi'' = \frac{\pi}{2} - \phi'$



$$\begin{cases} MSB_3 = 0 & \phi'' = \phi' \\ MSB_3 = 1 & \phi'' = 0.5 - \phi' \end{cases}$$

$\theta = \pi \phi''$ (Handwired Multiplier)

$0 < \theta < \frac{\pi}{4}$

$\phi \longrightarrow \phi' \longrightarrow \phi''$

Ist Quad Lower Half

Sine / Cosine Generator

Subrotation

$$X_{k+1} = X_k - (r_k \tan \theta_k) Y_k$$

$$Y_{k+1} = Y_k + (r_k \tan \theta_k) X_k$$

$$\begin{bmatrix} X_\theta \\ Y_\theta \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

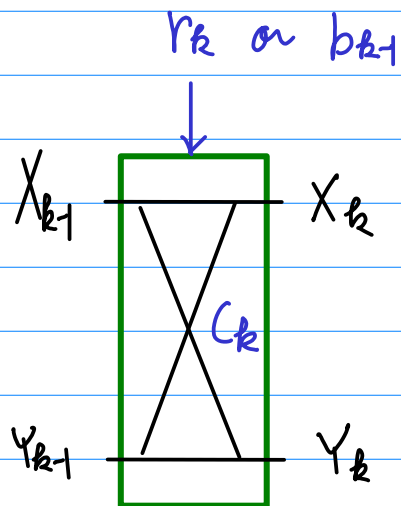
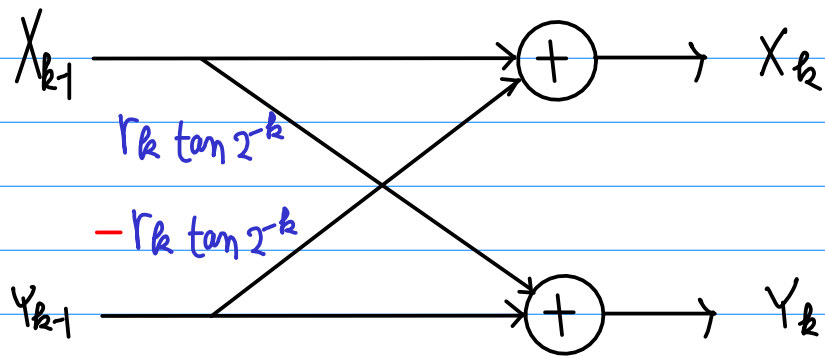
$$= \cos \theta \begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

$$\theta = \sigma_0 \theta_0 + \sigma_1 \theta_1 + \dots + \sigma_N \theta_N$$

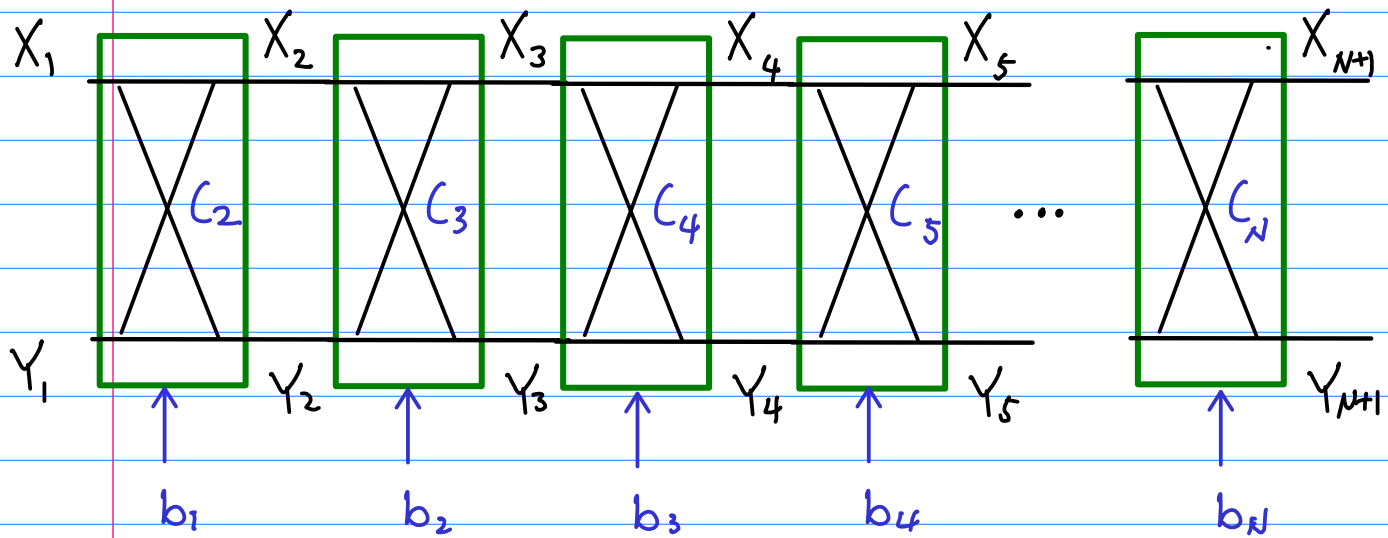
$$\sigma_k = \{-1, 0, +1\}$$

$$\begin{bmatrix} X_\theta \\ Y_\theta \end{bmatrix} = K \begin{bmatrix} 1 & -\tan \sigma_N \theta_N \\ \tan \sigma_N \theta_N & 1 \end{bmatrix} \dots \begin{bmatrix} 1 & -\tan \sigma_0 \theta_0 \\ \tan \sigma_0 \theta_0 & 1 \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

$$K = \cos \sigma_0 \theta_0 \cdot \cos \sigma_1 \theta_1 \dots \cos \sigma_N \theta_N$$



Butterfly



$$C_2 = \tan\left(\frac{1}{2^2}\right)$$

$$C_3 = \tan\left(\frac{1}{2^3}\right)$$

$$C_4 = \tan\left(\frac{1}{2^4}\right)$$

$$C_5 = \tan\left(\frac{1}{2^5}\right)$$

$$K \cos \phi_0 \rightarrow X_1$$

$$X_{N+1} \rightarrow \cos \theta$$

$$K \sin \phi_0 \rightarrow Y_1$$

$$Y_{N+1} \rightarrow \sin \theta$$

$$\theta \rightarrow \{b_1, b_2, \dots, b_N\}$$

the initial (X_0, Y_0) always the same

merge the first $B/3$ butterflies

→ $2^{B/3}$ words ROM implementation

→ no need $\tan \theta_k$ multipliers

→ $\{b_1, b_2, \dots, b_{B/3}\} \Rightarrow$ address

accesses

$$\cos \left(\phi_0 + \sum_{k=1}^{B/3} b_k 2^{-k+1} \right)$$

$$\sin \left(\phi_0 + \sum_{k=1}^{B/3} b_k 2^{-k+1} \right)$$

Lower Half of the 1st Quadrant

- all positive X_k & Y_k
- no need sign extension
- reduce the loads
- high speed

Merging Butterflies

merge m final butterflies

$$\begin{pmatrix} X_k \\ Y_k \end{pmatrix} \rightarrow \begin{pmatrix} X_{k+m} \\ Y_{k+m} \end{pmatrix} \text{ directly}$$

$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

valid merging $k \gg (B-1)/2$

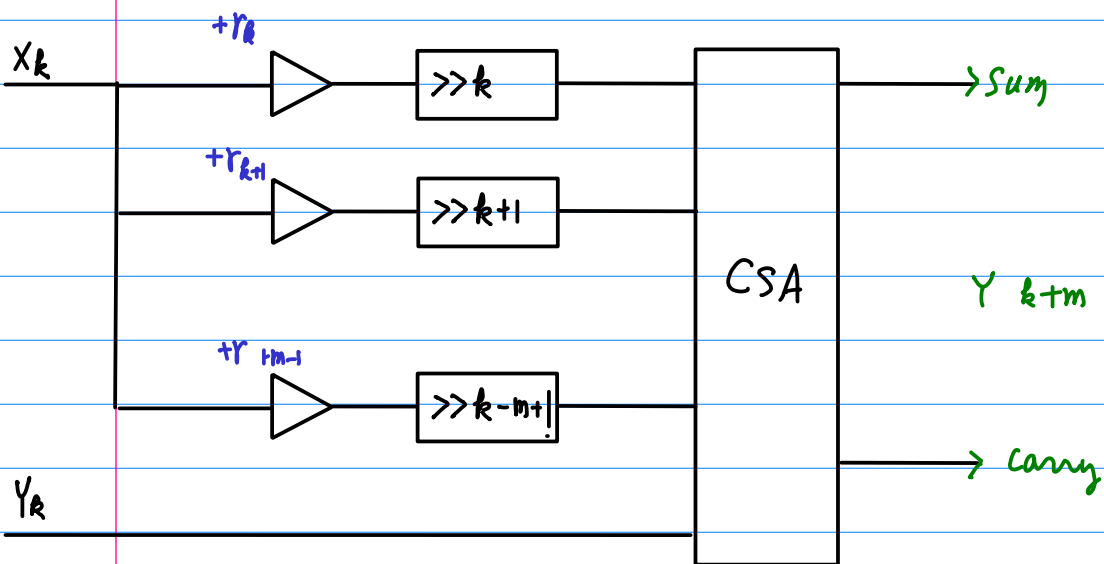
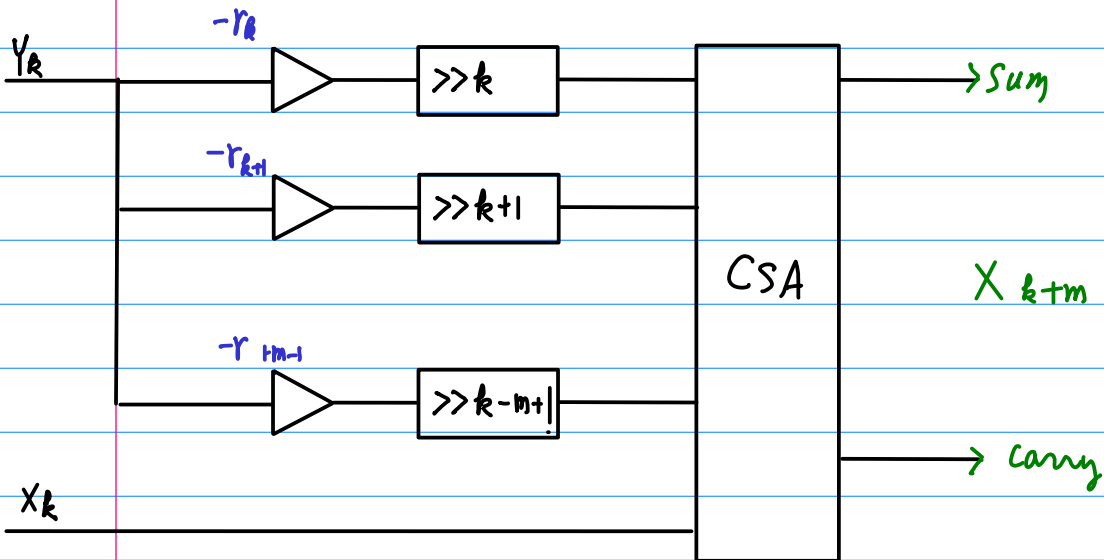
$$\tan(2^{-i}) = 2^{-i} \quad k \gg B/3$$

look ahead by m

the individual terms in the summation
can be computed independently
and summed in parallel

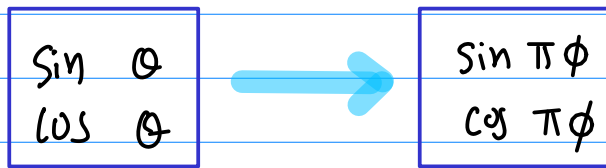
$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$



- + reduced latency
- + reduced routing
- + only the half for a single-ended system.

Output Stage

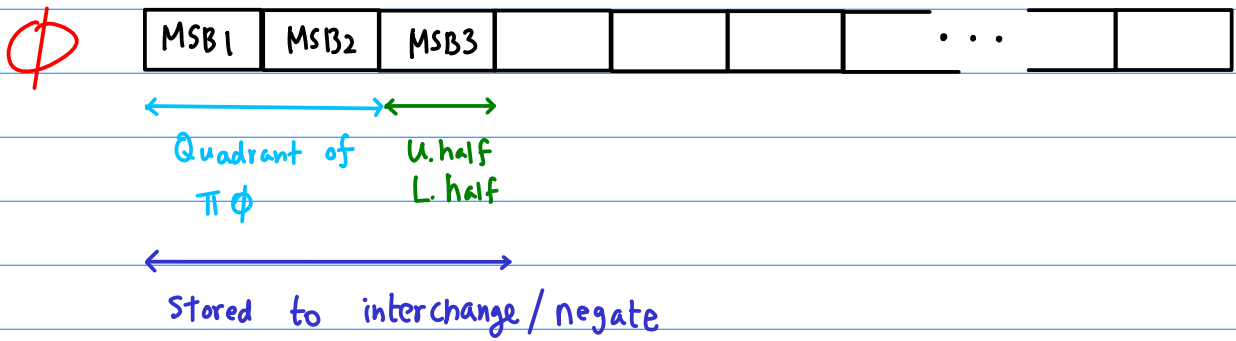


$$\theta \in [0, \frac{\pi}{4}] \longrightarrow \phi \in [1, +1]$$

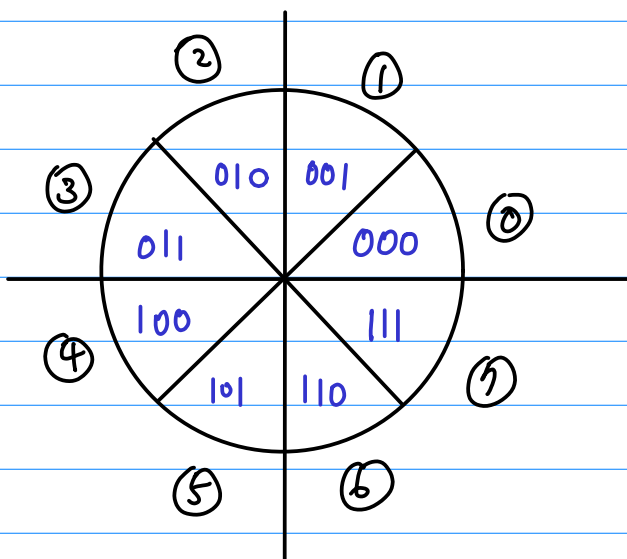
{ negation
interchange

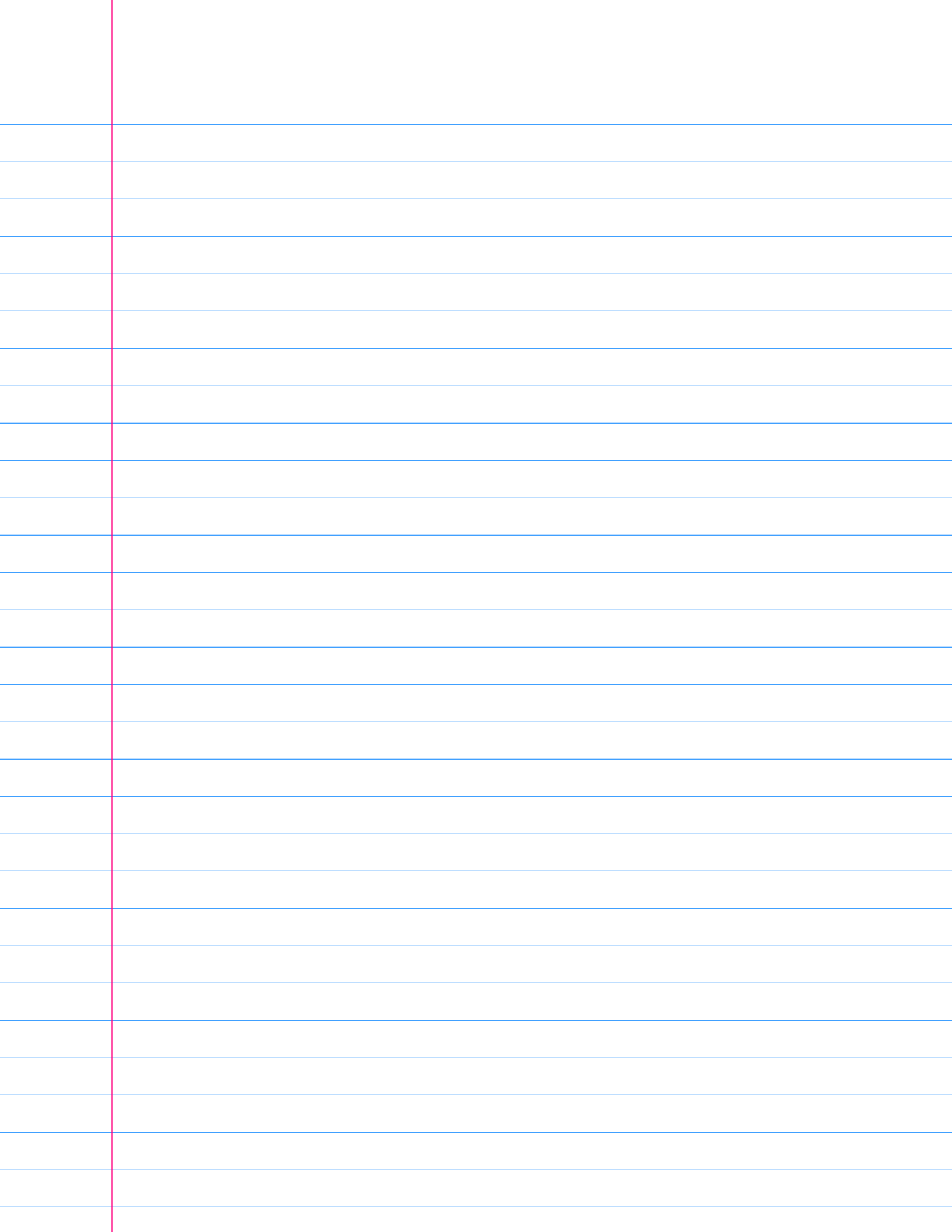
* negation before interchange

Normalized angle ϕ



MSB of ϕ	ϕ	X_{inv}	Y_{inv}	Swap	$\cos \pi\phi$	$\sin \pi\phi$
0 0 0	⑥	0	0	0	$\cos \theta$	$\sin \theta$
0 0 1	①	0	0	1	$\sin \theta$	$\cos \theta$
0 1 0	②	0	1	1	$-\sin \theta$	$\cos \theta$
0 1 1	③	1	0	0	$-\cos \theta$	$\sin \theta$
1 0 0	④	1	1	0	$-\cos \theta$	$-\sin \theta$
1 0 1	⑤	1	1	1	$-\sin \theta$	$-\cos \theta$
1 1 0	⑦	1	0	1	$\sin \theta$	$-\cos \theta$
1 1 1	⑧	0	1	0	$\cos \theta$	$-\sin \theta$





IC Implementation

clock: 100 MHz

acc: 36-bit (22-bit + 14-bit)

precision: 16-bit

advantage over traditional
ROM lookup table approach

accumulator: 36-bit = 22-bit + 14-bit

carry select adder

Speed & layout consideration

36-bit output \rightarrow truncated to 22-bit

22-bit radian converter

$\pi/4$ multiplier

SDFR $>$, 100 dBc

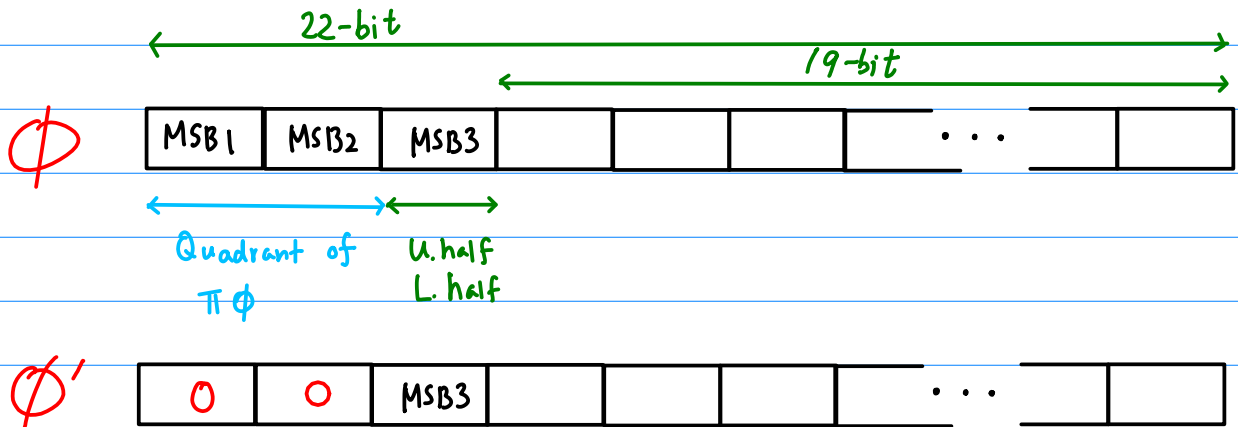
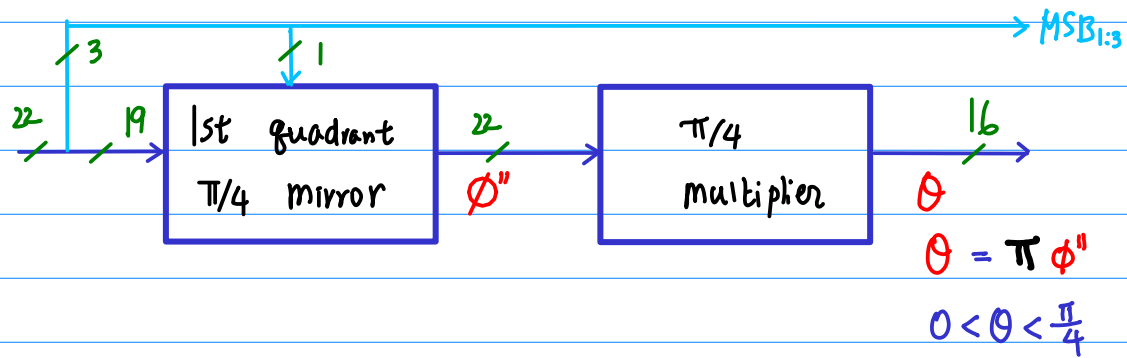
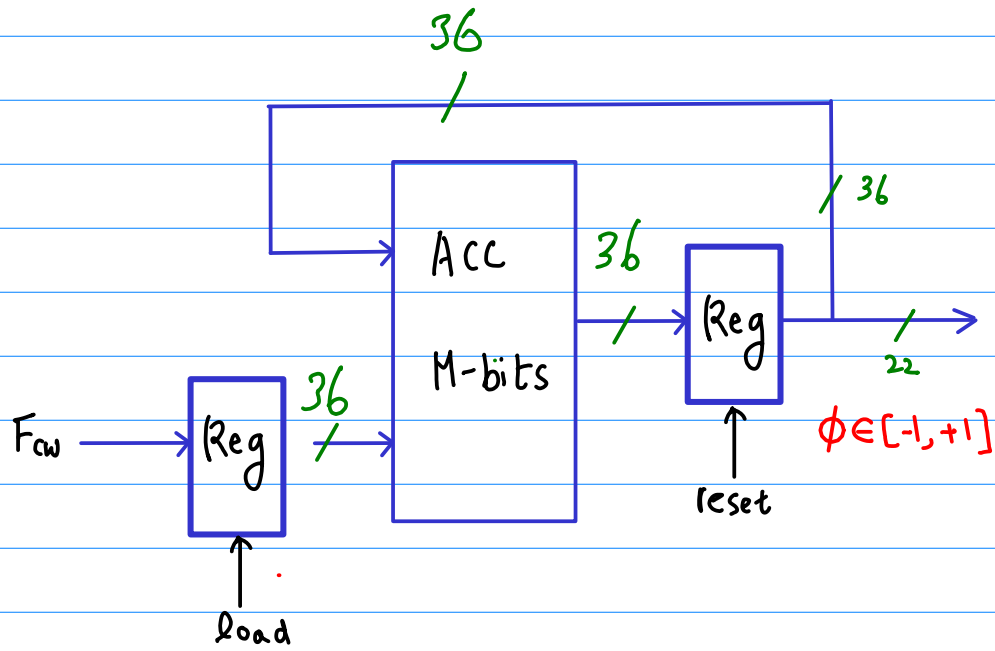
19-bit ROM address

for the similar performance

\Rightarrow 2^{19} words HUGE!

Coarse / fine ROM arch

[2] H. T. Nicholas and H. Samueli, "A 150 MHz direct digital frequency synthesizer in 1.25- μ m CMOS with -90 dBc spurious performance," *IEEE J. Solid-State Circuits*, vol. 26, pp. 1959-1969, Dec. 1991.



$\gamma > \frac{\pi}{4}$: Upper Half ($MSB_3 = 1$) $\phi'' = \phi'$
 $\gamma < \frac{\pi}{4}$: Lower Half ($MSB_3 = 0$) $\phi'' = 0.5 - \phi'$

radian converter

$$\theta = \pi \phi''$$

all internal angle

~ represented as

fractional binary 2's complement numbers

$$\theta = (\pi/4) (4\phi'')$$

$$(\pi/4) = 2^{-1} + 2^{-2} + 2^{-5} + 2^{-8} + 2^{-12}$$

1	2	3	4	5	6	7	8	9	10	11	12
1	1	0	0	1	0	0	1	0	0	0	1

$$2^{-1} = 0.5$$

$$2^{-2} = 0.25$$

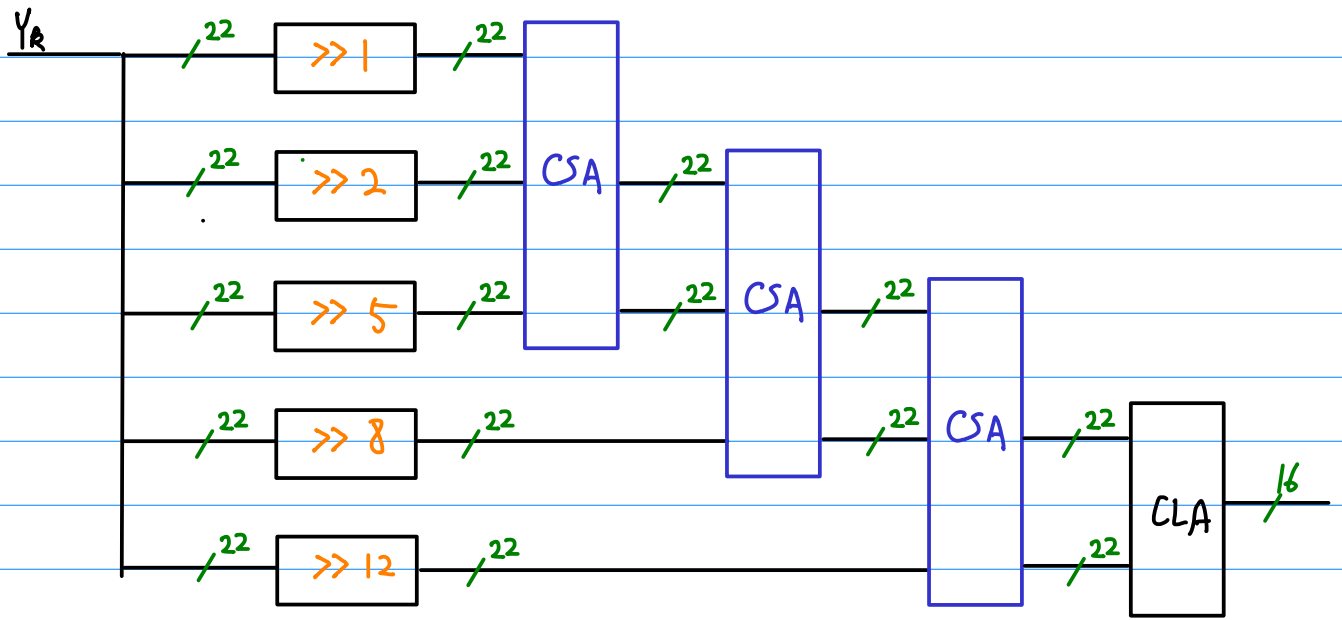
$$2^{-5} = 0.3125$$

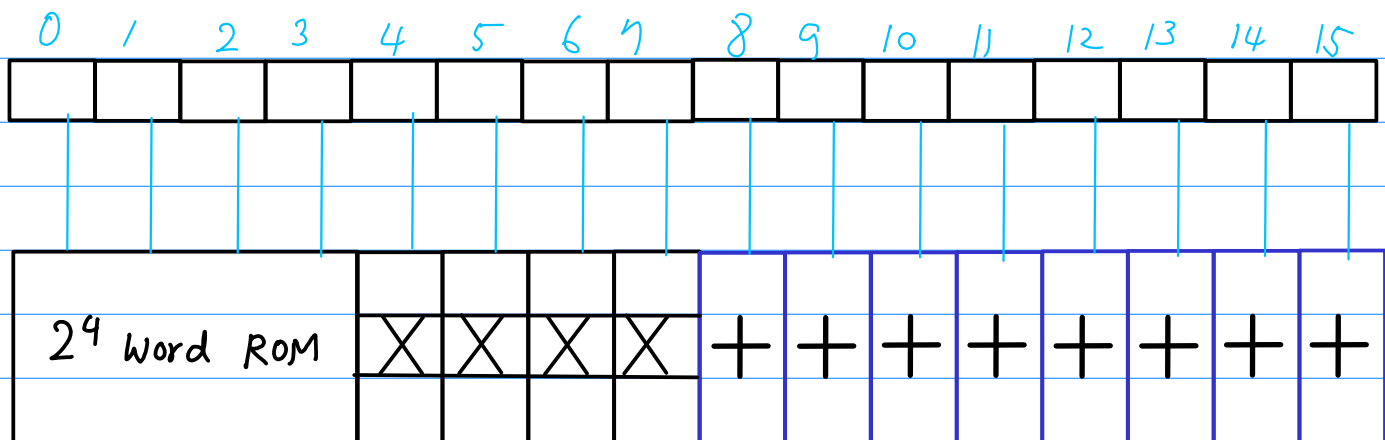
$$2^{-8} = 0.00390625$$

$$2^{-12} = 0.000244141$$

$$\pi/4 = 0.785398163 = 0.785400391$$

only 1st 5 partial products

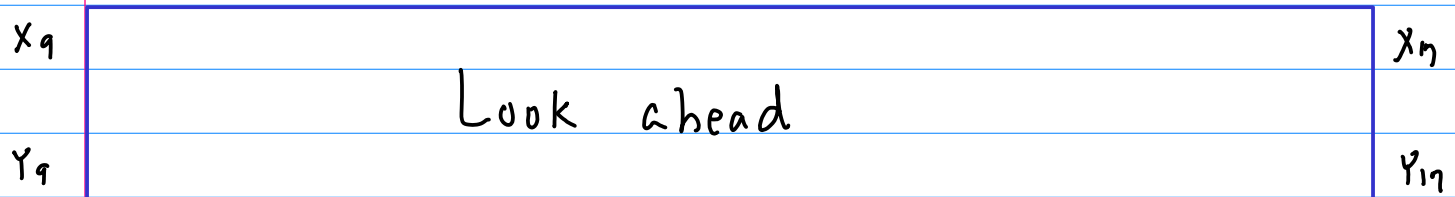
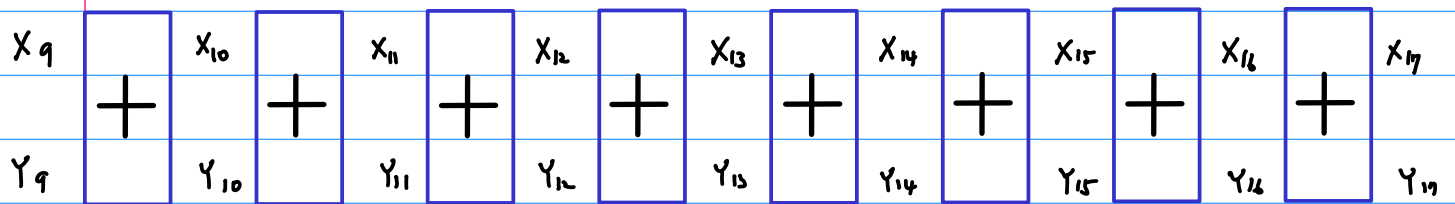




1st 4 stages

4 butterfly stages

8 Lookahead stages

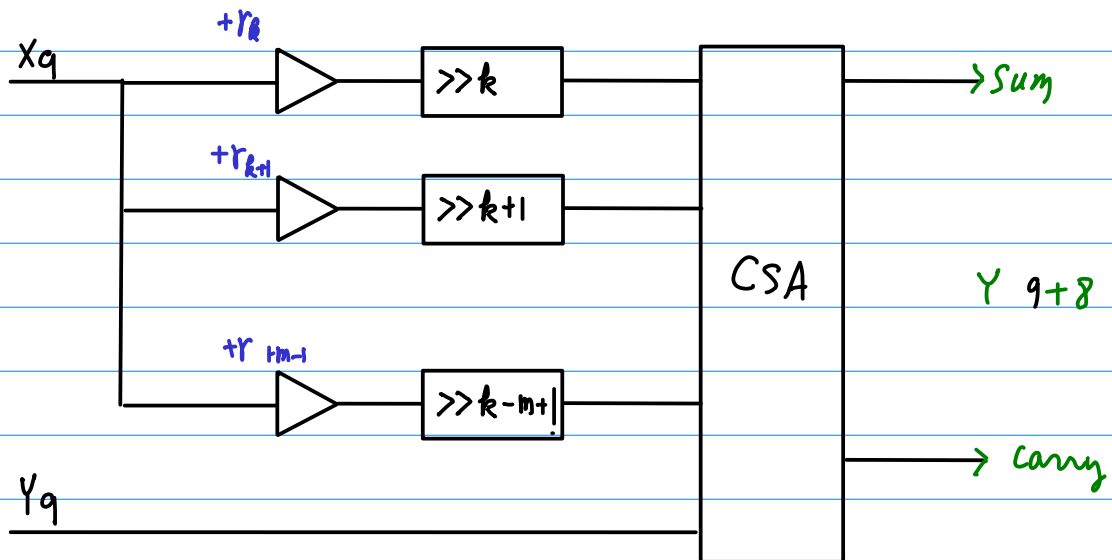
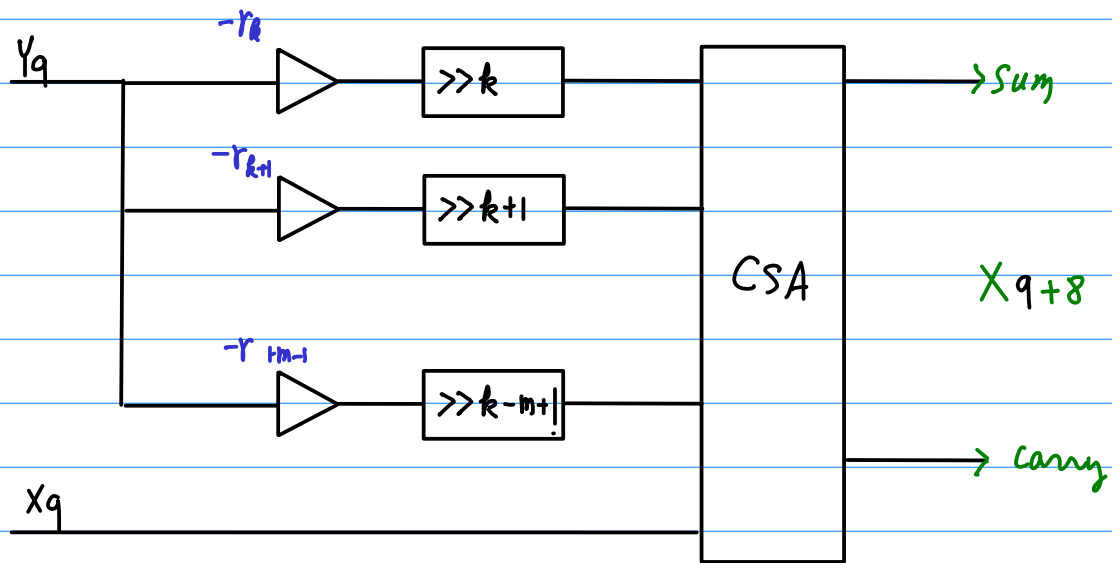


$$9 + 8 = 17$$

Look ahead

$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$




```
>> t'  
ans =
```

```
0  
1  
2  
3  
4  
5  
6  
7  
8  
9  
10  
11  
12  
13  
14  
15
```

```
>> t'/16  
ans =
```

```
0.00000  
0.06250  
0.12500  
0.18750  
0.25000  
0.31250  
0.37500  
0.43750  
0.50000  
0.56250  
0.62500  
0.68750  
0.75000  
0.81250  
0.87500  
0.93750
```

```
>> pi/4  
ans = 0.78540  
>>
```


0000	0111 1111 1110 1010 1010 10
0001	0111 1111 0111 1010 1100 10
0010	0111 1110 0110 1011 1000 10
0011	0111 1100 1110 1101 1110 10
0100	0111 1010 1111 0011 0110 01
0101	0111 1000 0111 1101 1111 01
0110	0111 0101 1001 0000 0001 01
0111	0111 0010 0010 1100 1010 11
1000	0110 1110 0101 0111 0010 00
1001	0110 1010 0001 0011 0100 10
1010	0110 0101 0110 0101 0110 01
1011	0110 0000 0101 0010 0010 01
1100	0101 1010 1101 1110 1001 10

0000	0000 0011 1111 1111 1010 10
0001	0000 1011 1111 1011 0000 00
0010	0001 0011 1110 1010 0101 11
0011	0001 1011 1100 0101 1101 00
0100	0010 0011 1000 0101 0111 11
0101	0010 1011 0010 0001 1010 11
0110	0011 0010 1001 0010 1011 11
0111	0011 1001 1101 0001 0011 11
1000	0100 0000 1101 0101 1111 00
1001	0100 0111 1001 1001 1101 01
1010	0100 1110 0001 0110 0010 01
1011	0101 0100 0100 0100 0110 01
1100	0101 1010 0001 1110 0110 01

```
C = [ "0111111111101010101010" ;  
      "0111111101111010110010" ;  
      "0111111001101011100010" ;  
      "0111110011101101111010" ;  
      "0111101011110011011001" ;  
      "0111100001111101111101" ;  
      "0111010110010000000101" ;  
      "0111001000101100101011" ;  
      "0110111001010111001000" ;  
      "0110101000010011010010" ;  
      "0110010101100101011001" ;  
      "0110000001010010001001" ;  
      "0101101011011110100110" ]
```

```
S = [ "0000001111111111101010" ;  
      "0000101111111011000000" ;  
      "0001001111101010010111" ;  
      "0001101111000101110100" ;  
      "0010001110000101011111" ;  
      "0010101100100001101011" ;  
      "0011001010010010101111" ;  
      "0011100111010001001111" ;  
      "0100000011010101111100" ;  
      "0100011110011001110101" ;  
      "0100111000010110001001" ;  
      "0101010001000100011001" ;  
      "0101101000011110011001" ]
```

```
CV = zeros(rows(C), 1);  
Cn = 2^rows(C) / 2;  
for i=1:rows(C)  
    CV(i) = bin2dec(C(i, :)) / Cn;  
end
```

```
SV = zeros(rows(S), 1);  
Sn = 2^rows(S) / 2;  
for i=1:rows(S)  
    SV(i) = bin2dec(S(i, :)) / Sn;  
end
```

```
>> subplot(2,1,1)
>> axis([0, 2*pi 0 1])
>> plot(x, CV)
>> axis([0, 2*pi 0 1])
>> subplot(2,1,2)
>> plot(x, SV)
>> axis([0, 2*pi 0 1])
>>
```

