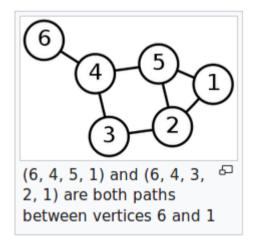
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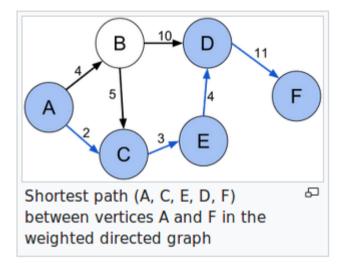
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the shortest path problem is the problem of finding a path between two vertices (or nodes) in a graph such that the sum of the weights of its constituent edges is minimized.





https://en.wikipedia.org/wiki/Shortest_path_problem

The **single-pair shortest path problem:** to find shortest paths from a **source** vertex v to a **destination** vertex w in a graph

The **single-**<u>source</u> shortest path problem: to find shortest paths from a **source** vertex v to **all** other vertices in the graph.

The single-destination shortest path problem:

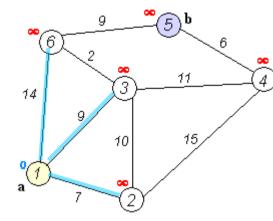
to find shortest paths from **all** vertices in the directed graph to a single **destination** vertex v. This can be reduced to the single-source shortest path problem by reversing the arcs in the directed graph.

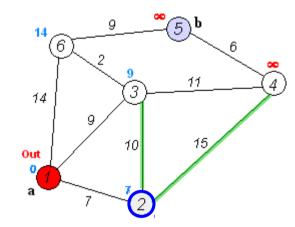
The all-pairs shortest path problem:

to find shortest paths between every **pair** of vertices v, v' in the graph.

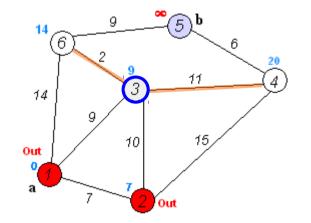
https://en.wikipedia.org/wiki/Shortest_path_problem

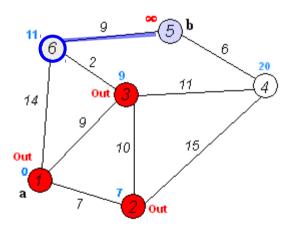
Dijkstra's Algorithm Example Summary





5

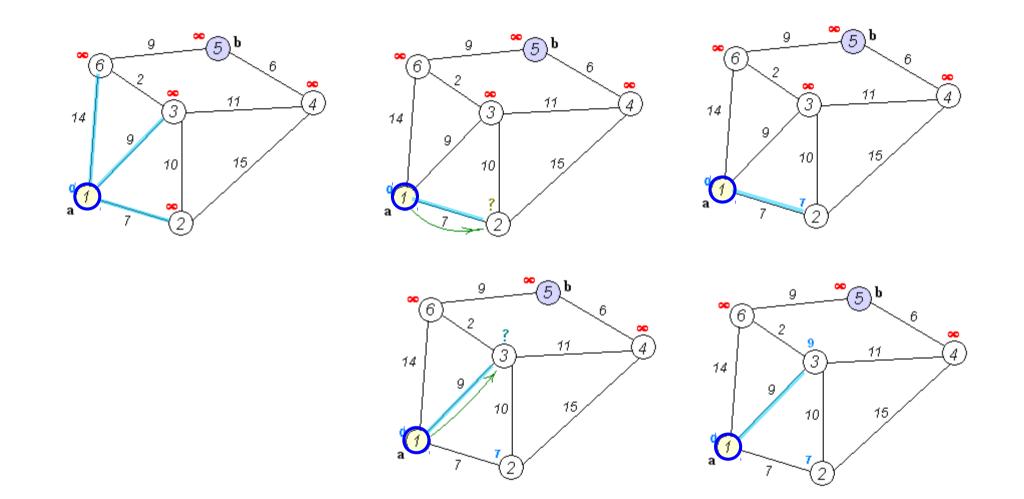




the initial node
the current node
the visited nodes

https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

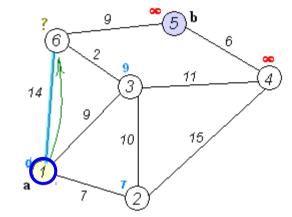
Dijkstra's Algorithm Example (1)

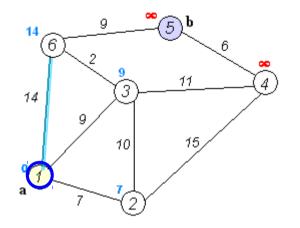


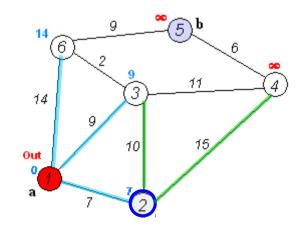
https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Shortest Path Problem (4A)

Dijkstra's Algorithm Example (2)

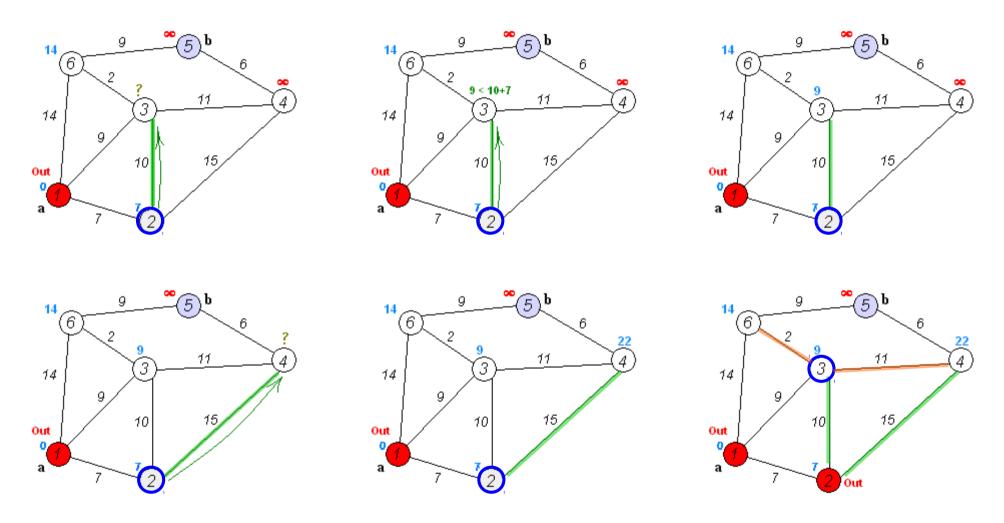






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Dijkstra's Algorithm Example (3)

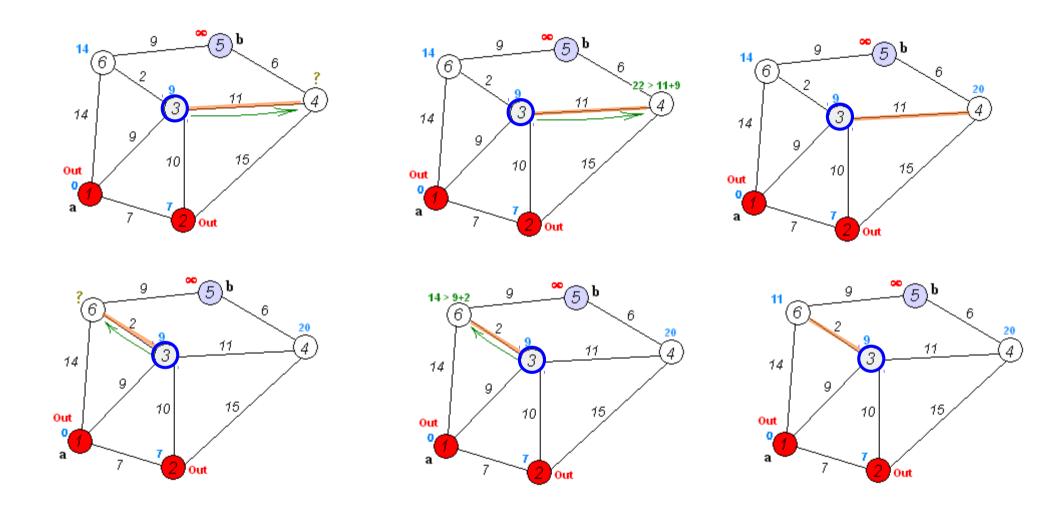


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https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Shortest Path Problem (4A)

Dijkstra's Algorithm Example (4)

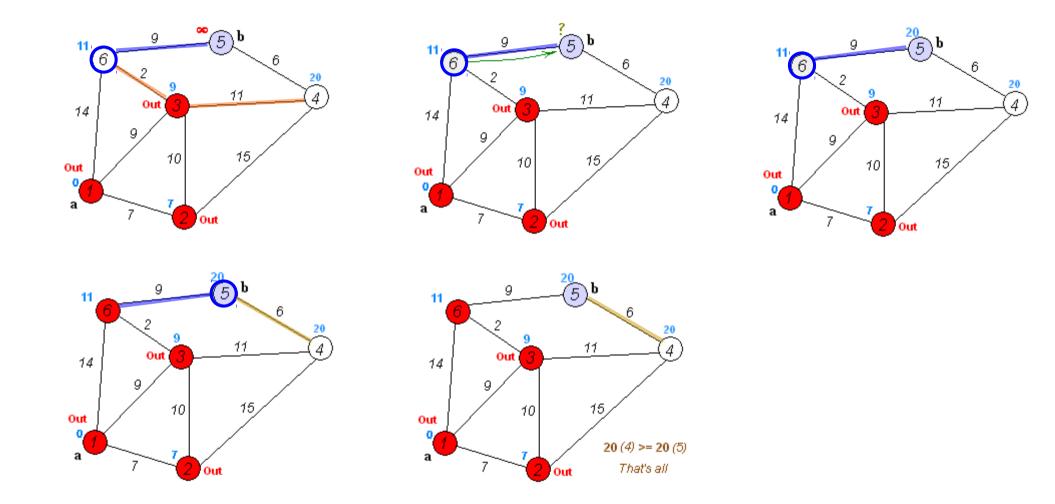


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https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Shortest Path Problem (4A)

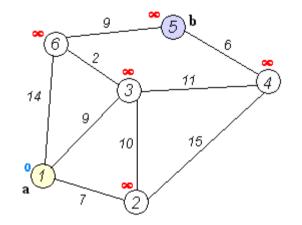
Dijkstra's Algorithm Example (5)



https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Shortest Path Problem (4A)

Hamiltonian Cycles



https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Let the node at which we are starting be called the **initial node**. Let the **distance** of node Y be the **distance** from the **initial node** to Y. Dijkstra's algorithm will assign some **initial distance values** and will try to <u>improve</u> them step by step.

1. Mark all nodes **unvisited**. Create a set of all the unvisited nodes called the **unvisited set**.

2. Assign to every node a tentative distance value: set it to zero for our initial node and to infinity for all other nodes.
Set the initial node as current.

 $https://en.wikipedia.org/wiki/Dijkstra\%27s_algorithm \#/media/File:Dijkstra_Animation.gif$

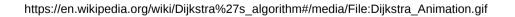
Dijkstra's Algorithm (2)

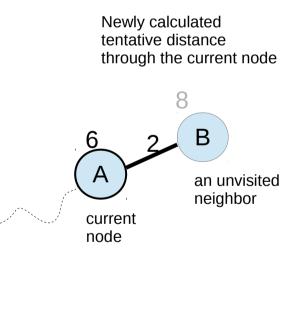
3. Remove the current node from the unvisited set

For all the **unvisited neighbors** of the **current node**, calculate their **tentative distances** <u>through</u> the **current** node.

Compare the <u>newly calculated</u> tentative distance to the <u>current assigned</u> value and assign the <u>smaller</u> one.

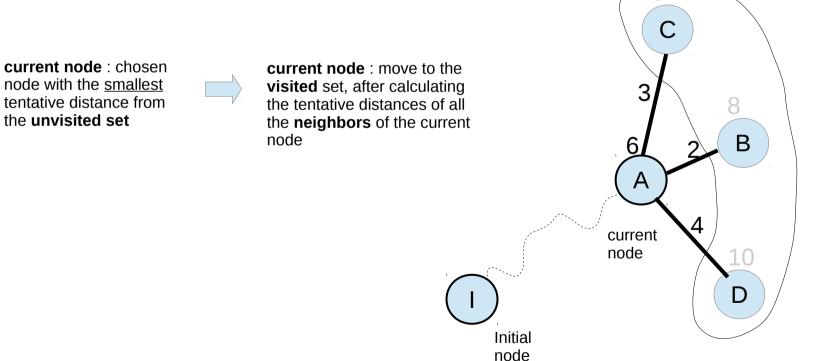
For example, if the current node A is marked with a distance of 6, and the edge connecting it with a neighbor B has length 2, then the distance to B through A will be 6 + 2 = 8. If B was previously marked with a distance greater than 8 then change it to 8. Otherwise, keep the current value.





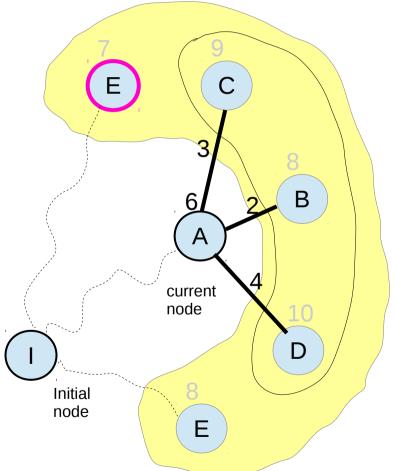
Initial node 4. After considering <u>all</u> of the **neighbors** of the **current node**, mark the **current** node as **visited** and remove it from the **unvisited set**. A **visited node** will never be checked again.

consider all the neighbors of the current node



https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

5. Move to the **next unvisited node** with the <u>smallest</u> tentative distances and repeat the above steps which <u>check neighbors</u> and <u>mark visited</u>.



https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

5-a. If the **destination** node has been marked **visited** (when planning a route between two specific nodes)

or if the smallest tentative distance among the nodes in the unvisited set is **infinity** (when planning a complete traversal; occurs when there is no connection between the initial node and remaining unvisited nodes),

then stop. The algorithm has finished.

5-b. Otherwise, select the **unvisited** node that is marked with the <u>smallest</u> tentative distance, set it as the new **current node**, and go back to step 3.

https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

Dijkstra's Algorithm – Pseudocode 1

```
1 function Dijkstra(Graph, source):
2
3
     create vertex set Q
4
5
     for each vertex v in Graph:
                                                // Initialization
6
        dist[v] ← INFINITY
                                                // Unknown distance from source to v
7
        prev[v] ← UNDEFINED
                                                // Previous node in optimal path from source
8
        add v to O
                                                // All nodes initially in Q (unvisited nodes)
9
      dist[source] ← 0
10
                                                // Distance from source to source
11
12
      while Q is not empty:
13
         u \leftarrow vertex in Q with min dist[u]
                                                // Node with the least distance
                                                // will be selected first
14
15
         remove u from O
16
17
                                                // where v is still in Q.
         for each neighbor v of u:
                                                                                for each v in Q:
18
            alt \leftarrow dist[u] + length(u, v)
19
            if alt < dist[v]:
                                                // A shorter path to v has been found
20
              dist[v] ← alt
21
              prev[v] ← u
22
23
      return dist[], prev[]
```

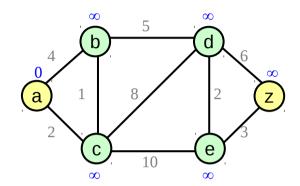
https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm#/media/File:Dijkstra_Animation.gif

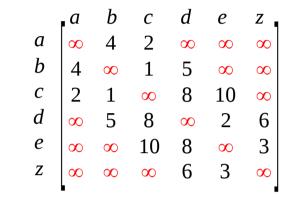
Dijkstra's Algorithm – Pseudocode 2

Procedure Dijkstra(G: weighted connected simple graph, with all positive weights) {**G** has vertices $a = v_0, v_1, \dots, v_n = z$ and length $w(v_i, v_i)$ where $w(v_i, v_j) = \infty$ if $\{v_i, v_j\}$ is not an edge in **G**} **for** i '= 1 to n $L(\mathbf{v}) := \infty$ L(a) := 0S := { } {the labels are now initialized so that the label of a is 0 and All other labels are ∞ , and S is the empty set} while $z \notin S$ u := a vertex not in S with L(u) minimal S := S ∪ {*u*} for all vertices v not in S if L(u) + w(u,v) < L(u) then L(v) := L(u) + w(u,v){this adds a vertex to S with minimal label and updates the labels of vertices not in S} **return** L(z) {L(z) = length of a shortest path from *a* to *z*}

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Dijkstra Algorithm Pseudocode 2 Example (0)

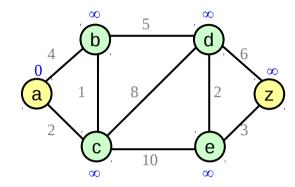


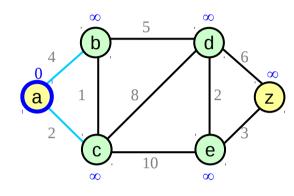


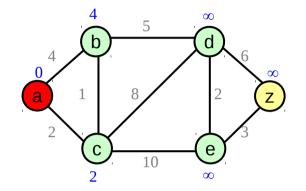
 $w(u_i, u_j)$

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Dijkstra Algorithm Pseudocode 2 Example (1)



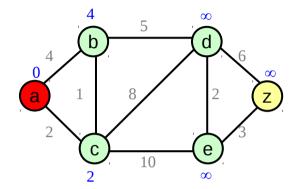


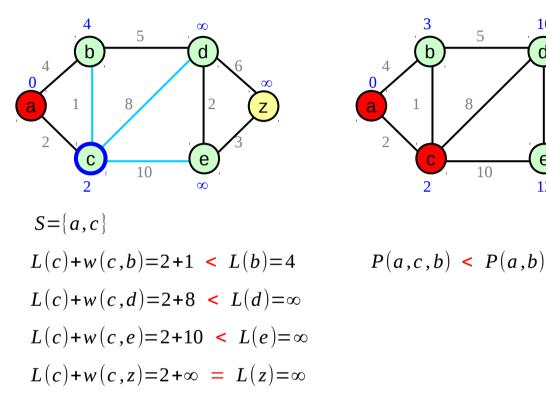


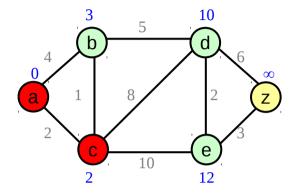
 $S = \{a\}$ $L(a) + w(a,b) = 0 + 4 < L(b) = \infty$ $L(a) + w(a,c) = 0 + 2 < L(c) = \infty$ $L(a) + w(a,d) = 0 + \infty = L(d) = \infty$ $L(a) + w(a,e) = 0 + \infty = L(e) = \infty$ $L(a) + w(a,z) = 0 + \infty = L(z) = \infty$

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Dijkstra Algorithm Pseudocode 2 Example (2)

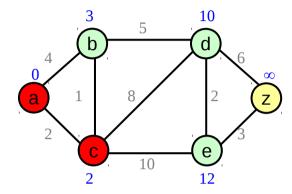


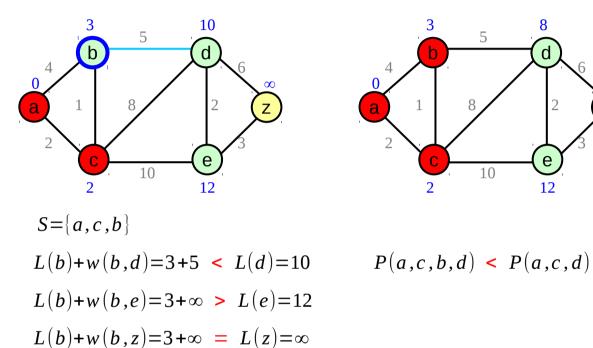


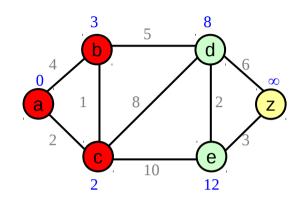


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Dijkstra Algorithm Pseudocode 2 Example (3)

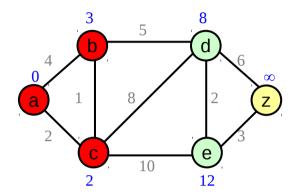


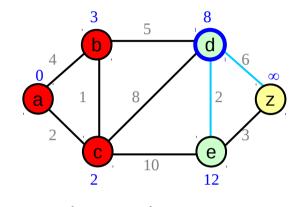




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Dijkstra Algorithm Pseudocode 2 Example (4)

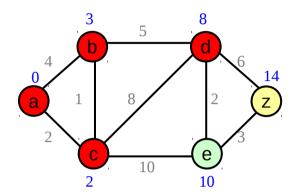


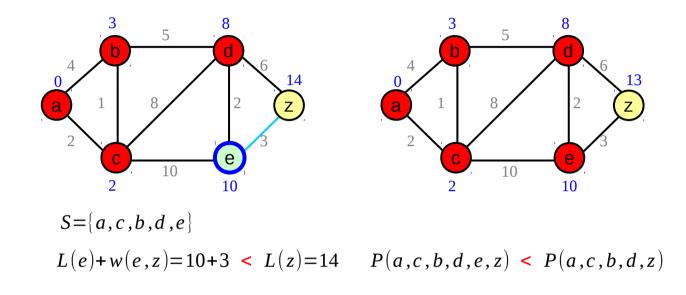


 $S = \{a, c, b, d\}$ L(d)+w(d,e)=8+2 < L(e)=12 P(a,c,b,d,e) < P(a,c,e) $L(d)+w(d,z)=8+6 < L(z)=\infty$

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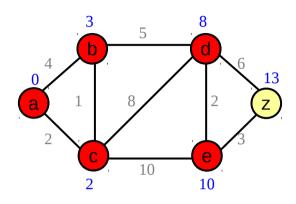
Dijkstra Algorithm Pseudocode 2 Example (5)

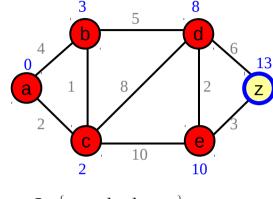


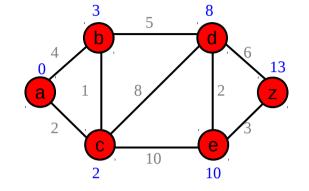


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Dijkstra Algorithm Pseudocode 2 Example (6)







S={a,c,b,d,e,z}

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Shortest Path Problem (4A)



References

