Random Process Background (1B)

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Mar 25, 2024

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Based on Probability, Random Variables and Random Signal Principles, P.Z. Peebles, Jr. and B. Shi

Outline



Borel Sets

- Measurable Space
- Topological Space II
- Borel Sets



Measurable Space Topological Space II Borel Sets

Outline



• Measurable Space

- Topological Space II
- Borel Sets



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Mathematical objects (1)

• a mathematical object is

an abstract concept arising in mathematics.

- an mathematical object is anything that has been (or could be) formally <u>defined</u>, and with which one may do
 - deductive reasoning
 - mathematical proofs

https://en.wikipedia.org/wiki/Mathematical_object

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Mathematical objects (2)

• typically, a mathematical object

- can be a value that can be assigned to a variable
- therefore can be involved in formulas

https://en.wikipedia.org/wiki/Mathematical_object

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Mathematical objects (3)

• commonly encountered mathematical objects include

- numbers
- sets
- functions
- expressions
- geometric objects
- transformations of other mathematical objects
- spaces

https://en.wikipedia.org/wiki/Mathematical_object

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Measurable Space Topological Space II Borel Sets

Mathematical objects (4)

• Mathematical objects can be very complex;

- for example, the followings are considered as mathematical objects in proof theory.
 - theorems
 - proofs
 - theories

https://en.wikipedia.org/wiki/Mathematical_object

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Structure (1)

• a structure is a set

endowed with some additional features on the set

- an operation
- relation
- metric
- topology
- often, the *additional features* are attached or related to the set, so as to provide it with some *additional meaning* or *significance*.

https://www.localmaxradio.com/questions/what-is-a-mathematical-space

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Structure (2)

- A partial list of possible structures are
 - measures
 - algebraic structures (groups, fields, etc.)
 - topologies
 - metric structures (geometries)
 - orders
 - events
 - equivalence relations
 - differential structures
 - categories.

https://www.localmaxradio.com/questions/what-is-a-mathematical-space

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• A space consists of

selected mathematical objects that are treated as points, and selected relationships between these points.

- the *nature* of the points can vary widely: for example, the points can be
 - elements of a set
 - functions on another space
 - subspaces of another space
- It is the relationships between points that define the *nature* of the **space**.

https://en.wikipedia.org/wiki/Space (mathematics)

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- modern mathematics uses many types of spaces, such as
 - Euclidean spaces
 - linear spaces
 - topological spaces
 - Hilbert spaces
 - probability spaces
- *modern mathematics* does <u>not</u> <u>define</u> the notion of **space** itself.

https://en.wikipedia.org/wiki/Space (mathematics)



• a space is

a set (or a universe) with some added features

- it is <u>not</u> always clear whether a given mathematical object should be considered as a geometric space, or an algebraic structure
- a general <u>definition</u> of **structure** embraces all common types of **space**

https://en.wikipedia.org/wiki/Space_(mathematics)

Mathematical space (1)

- A mathematical space is, informally, a collection of mathematical objects under consideration.
- The universe of mathematical objects within a space are *precisely* defined entities whose rules of *interaction* come baked into the rules of the space.

Mathematical space (2)

- A space differs from a mathematical set in several important ways:
 - A mathematical set is also a collection of objects
 - but these objects are being pulled from a **space** (or **universe**) of objects where the rules and definitions have already been <u>agreed</u> upon

Measurable Space Topological Space II Borel Sets

Mathematical space (3)

- A space differs from a mathematical set in several important ways:
 - a mathematical set has no internal structure,
 - a **space** usually has some internal structure.

Mathematical space (4)

- having some internal structure could mean a variety of things, but typically it involves
 - *interactions* and *relationships* between elements of the **space**
 - *rules* on how to *create* and *define new* elements of the **space**

Measurable space (1)

- A measurable space is any space with a sigma-algebra which can then be equipped with a measure
 - collection of subsets of the space following certain rules with a way to assign sizes to those sets.

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

Measurable space (2)

Intuitively,

certain sets belonging to a measurable space can be given a size in a *consistent way*.

consistent way means that certain axioms are met:

- the empty set is given a size of zero
- if a measurable set is contained inside another one, then its size is less than or equal to the size of the containing set
- the size of a disjoint union of sets is the sum of the individual sets' sizes

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

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The set of all real numbers

 In the set of all real numbers, one has the natural Euclidean metric; that is, a function which *measures* the distance between two real numbers: d(x,y) = |x - y|.

https://en.wikipedia.org/wiki/Open_set

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All points close to a real number x

- Therefore, given a real number x, one can speak of the set of all points <u>close</u> to that real number x; that is, within ɛ of x.
- In essence, points within ε of x
 approximate x to an accuracy of degree ε.
- Note that ɛ > 0 always, but as ɛ becomes smaller and smaller, one obtains points that approximate x to a higher and higher degree of accuracy.

https://en.wikipedia.org/wiki/Open_set

The points within ε of x

- For example, if x = 0 and ε = 1, the points within ε of x are precisely the points of the interval (-1,1);
- However, with ε = 0.5, the points within ε of x are precisely the points of (-0.5, 0.5).
- Clearly, these points <u>approximate</u> x to a greater degree of accuracy than when ε = 1.

https://en.wikipedia.org/wiki/Open set

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without a concrete Euclidean metric

• The previous examples shows,

for the case x = 0, that one may **approximate** x to *higher* and *higher* degrees of accuracy by defining ε to be *smaller* and *smaller*.

- In particular, sets of the form $(-\varepsilon, \varepsilon)$ give us a lot of <u>information</u> about points close to x = 0.
- Thus, <u>rather than</u> speaking of a <u>concrete</u> <u>Euclidean metric</u>, one may <u>use sets</u> to <u>describe</u> points <u>close</u> to <u>x</u>.

https://en.wikipedia.org/wiki/Open set

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Different collections of sets containing 0

• This innovative idea has far-reaching consequences; in particular, by defining

 $\frac{\text{different collections of sets containing 0}}{(\text{distinct from the sets } (-\varepsilon, \varepsilon)),}$ one may find <u>different results</u> regarding the <u>distance</u> between 0 and other real numbers.

https://en.wikipedia.org/wiki/Open_set

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A set for measuring distance

- For example, if we were to define *R* as the *only* such set for "*measuring distance*", all points are close to 0
- since there is only <u>one</u> possible degree of accuracy one may achieve in <u>approximating</u> 0: being a member of *R*.

https://en.wikipedia.org/wiki/Open_set

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The measure as a binary condition

- Thus, we find that in some sense, every real number is distance 0 away from 0.
- It may help in this case to think of the measure as being a binary condition:
 - all things in **R** are equally close to 0,
 - while any item that is <u>not</u> in *R* is <u>not close</u> to 0.

https://en.wikipedia.org/wiki/Open_set

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Probability space

- A probability space is simply
 - a measurable space equipped with a probability measure.
- A probability measure has the special property of giving the entire **space** a size of **1**.
 - this then implies that the size of any <u>disjoint union</u> of sets (the <u>sum</u> of the sizes of the sets) in the **probability space** is <u>less than</u> or <u>equal to</u> **1**

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

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Euclidean space definition (1)

• A subset U of the Euclidean n-space \mathbb{R}^n is open

if, for every point x in U, there exists a positive real number ε (depending on x)

such that any point in \mathbb{R}^n whose Euclidean distance from x is smaller than ε

belongs to U

https://en.wikipedia.org/wiki/Open_set

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Euclidean space definition (2)

• Equivalently, a subset U of \mathbb{R}^n is open

if every point in U is the center of an open ball contained in U

 \bullet An example of a subset of ${\mathbb R}$ that is not open is

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the closed interval [0,1], since neither 0 - \varepsilon nor 1 + \varepsilon belongs to [0,1] for any \varepsilon > 0, no matter how small.
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https://en.wikipedia.org/wiki/Open_set

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Metric space definition (1)

• A subset U of a metric space (M,d) is called open

if, for any point x in U, there exists a real number $\varepsilon > 0$ such that any point $y \in M$ satisfying $d(x,y) < \varepsilon$ belongs to U.

- Equivalently, *U* is open if every point in *U* has a neighborhood contained in *U*.
- This generalizes the Euclidean space example, since Euclidean space with the Euclidean distance is a metric space.

https://en.wikipedia.org/wiki/Open_set

Metric space definition (2)

formally, a metric space is an ordered pair (M, d) where M is a set and d is a metric on M, i.e., a function

$$d: M \times M \to \mathbb{R}$$

satisfying the following axioms for all points $x, y, z \in M$:

•
$$d(x,x)=0.$$

• if
$$x \neq y$$
, then $d(x, y) > 0$.

•
$$d(x,y) = d(y,x)$$
.

•
$$d(x,z) \leq d(x,y) + d(y,z)$$
.

https://en.wikipedia.org/wiki/Open_set

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Metric space definition (3)

- satisfying the following axioms for all points $x, y, z \in M$:
 - the distance from a point to itself is zero:
 - (Positivity) the distance between two distinct points is always positive:
 - (Symmetry) the distance from x to y is always the same as the distance from y to x:
 - (Triangle inequality) you can arrive at z from x by taking a detour through y, but this will not make your journey any faster than the shortest path.
- If the metric *d* is <u>unambiguous</u>, one often refers by abuse of notation to "the **metric space** *M*".

https://en.wikipedia.org/wiki/Open_set

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Outline





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Definition via Open Sets (1)

• A topology au on a set X is

a set of subsets of X with the *properties* below.

- a topology τ on a set X : a set of subsets of X
- members of τ : subsets of X
- each member of τ is called an open set.
- X together with τ is called a **topological space**

https://en.wikipedia.org/wiki/Open_set

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Definition via Open Sets (2)

- topology τ : a set of subsets of X has the *properties* below
 - $X \in \tau$ and $\varnothing \in \tau$
 - any union of sets in τ belong to τ : any union of subsets of X belong to τ : if {U_i : i ∈ I} ⊆ τ then

$$\bigcup_{i\in I}U_i\in\tau$$

any finite intersection of sets in τ belong to τ
any finite intersection of subsets of X belong to τ :
if U₁,..., U_n ∈ τ then

$$U_1 \cap \cdots \cap U_n \in \tau$$

https://en.wikipedia.org/wiki/Open_set

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Definition via Open Sets (3)

- Infinite intersections of open sets need not be open.
- For example, the intersection of all intervals of the form (-1/n, 1/n), where *n* is a positive integer, is the set $\{0\}$ which is not open in the real line.
- A metric space is a topological space, whose topology consists of the collection of all subsets that are unions of open balls.
- There are, however, topological spaces that are not metric spaces.

https://en.wikipedia.org/wiki/Open set

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Definition via Open Sets (4)

- A topology on a set X may be defined as a collection τ of subsets of X, called open sets and satisfying the following axioms:
 - The empty set and X itself belong to τ .
 - any arbitrary (finite or infinite) union of members of τ belongs to τ .
 - the intersection of any finite number of members of τ belongs to τ .

https://en.wikipedia.org/wiki/Topological_space

Definition via Open Sets (5)

- As this definition of a topology is the most <u>commonly used</u>, the set τ of the open sets is commonly called a **topology** on X.
- A subset $C \subseteq X$ is said to be closed in (X, τ) if its complement $X \setminus C$ is an open set.

https://en.wikipedia.org/wiki/Topological space

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Definition via Neighborhoods (1)

- This axiomatization is due to Felix Hausdorff.
- Let X be a set;
- the elements of X are usually called points, though they can be any mathematical object.
- We allow X to be empty.

https://en.wikipedia.org/wiki/Topological_space

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Definition via Neighborhoods (2)

- Let \mathscr{N} be a function assigning to each x (point) in X a non-empty collection $\mathscr{N}(x)$ of subsets of X.
- The elements of *N*(x) will be called neighbourhoods of x with respect to *N* (or, simply, neighbourhoods of x).
- The function \mathcal{N} is called a neighbourhood topology if *the axioms* below are satisfied; and
- then X with \mathcal{N} is called a topological space.

https://en.wikipedia.org/wiki/Topological_space

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Definition via Neighborhoods (3)

- If N is a neighbourhood of x (i.e., N ∈ N(x)), then x ∈ N. In other words, each point belongs to every one of its neighbourhoods.
- If N is a subset of X and includes a neighbourhood of x, then N is a neighbourhood of x.
 i.e., every superset of a neighbourhood of a point x ∈ X is again a neighbourhood of x.
- The intersection of two neighbourhoods of x is a neighbourhood of x.
- Any neighbourhood \mathcal{N} of x includes a neighbourhood \mathcal{M} of x such that \mathcal{N} is a neighbourhood of each point of M.

https://en.wikipedia.org/wiki/Topological_space

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Definition via Neighborhoods (4)

- The first three axioms for neighbourhoods have a clear meaning.
- The fourth axiom has a very important use in the structure of the theory, that of linking together the neighbourhoods of different points of X.
- A standard example of such a system of neighbourhoods is for the real line ℝ, where a subset N of ℝ is defined to be a neighbourhood of a real number x if it includes an open interval containing x.

https://en.wikipedia.org/wiki/Topological space

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Definition via Neighborhoods (5)

- Given such a structure, a subset U of X is defined to be **open** if U is a neighbourhood of all points in U.
- The **open sets** then satisfy the axioms given below.
- Conversely, when given the open sets of a topological space, the neighbourhoods satisfying the above axioms can be recovered by defining N to be a neighbourhood of x if N includes an open set U such that x ∈ U.

https://en.wikipedia.org/wiki/Topological_space

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Definition via Closed Sets (1)

• Using de Morgan's laws,

the above axioms defining **open sets** become axioms defining **closed sets**:

- The empty set and X are closed.
 - The intersection of any collection of **closed sets** s also **closed**.
 - The union of any finite number of closed sets is also closed.
- Using these axioms, another way to define a topological space is as a set X together with a collection τ of closed subsets of X. Thus the sets in the topology τ are the closed sets, and their complements in X are the open sets.

https://en.wikipedia.org/wiki/Open_set

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Homeomorphism (1)

a homeomorphism

(from Greek ὅμοιος (homoios) 'similar, same', and μορφή (morphē) 'shape, form', named by Henri Poincaré), **topological isomorphism**, or **bicontinuous function** is a bijective and continuous function between topological spaces that has a continuous inverse function.

https://en.wikipedia.org/wiki/Homeomorphism

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Homeomorphism (2)

- Homeomorphisms are the isomorphisms in the category of topological spaces – the mappings that preserve all the topological properties of a given space.
- Two spaces with a homeomorphism

between them are called homeomorphic, and from a topological viewpoint they are the same.

https://en.wikipedia.org/wiki/Homeomorphism

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Homeomorphism (3)

Very roughly speaking,
 a topological space is a geometric object,
 and the homeomorphism is
 a continuous stretching and bending
 of the object into a new shape.

https://en.wikipedia.org/wiki/Homeomorphism

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Homeomorphism (4)

- Thus, a *square* and a *circle* are homeomorphic to each other, but a *sphere* and a *torus* are not.
- However, this description can be misleading.
- Some continuous deformations are <u>not</u> homeomorphisms, such as the *deformation* of a *line* into a *point*.
- Some homeomorphisms are not continuous deformations, such as the homeomorphism between a trefoil knot and a circle.

https://en.wikipedia.org/wiki/Homeomorphism

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Borel Sets Stochatic Process Measurable Space Topological Space II Borel Sets

Outline



Borel Sets

Measurable SpaceTopological Space II

Borel Sets



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Sigma algebra (1)

- We term the structures which allow us to use measure to be sigma algebras
- the <u>only</u> requirements for sigma algebras (on a set X) are:
 - the {} and X are in the **set**.
 - if A is in the **set**, complement(A) is in the **set**.
 - for any sets E_i in the set, $\bigcup_i E_i$ is in the set (for countable *i*).

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

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Sigma algebra (2)

- The most intuitive way to think about a **sigma algebra** is that it is the kind of **structure** we can do probability on.
 - for example, we can assign <u>ratios</u> of <u>areas</u> and <u>length</u>, so the measure on such a set X tells something about the probability of its subsets.
 - we can find the probability of subsets A and B because we know their ratios with respect to a set X ;
 - we also know that
 - (the measure of) their complements are defined, and
 - their unions and intersections are defined,
 - so we know how to find the probability of things in this set X.

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

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Sigma algebra (3)

- The sigma algebra which contains the standard topology on R (that is, *all* open sets on R) is called the **Borel Sigma Algebra**, and the elements of this set are called **Borel sets**.
- What this gives us, is the set of sets on which outer measure gives our list of dreams. That is, if we take a Borel set and we check that length follows translation, additivity, and interval length, it will always hold.

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-intuiti

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Sigma algebra (4)

- The set of Lebesgue measurable sets is the set of **Borel sets**, along with (union) all the sets which differ from a Borel set by a set of measure 0.
- More intuitively, it is all the sets we can normally measure, plus a bunch of stuff that <u>doesn't</u> affect our ideas of area or volume (think about the border of the circle above).

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

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Borel Sets (1-1)

- a Borel set is any set in a topological space that can be formed from open sets (or, equivalently, from closed sets) through the operations of
 - countable union,
 - countable intersection, and
 - relative complement.

https://en.wikipedia.org/wiki/Borel_set

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Borel Sets (1-2)

- For a topological space X, the collection of all Borel sets on X forms a σ-algebra, known as the Borel algebra or Borel σ-algebra.
- The Borel algebra on X is the smallest σ-algebra containing all open sets (or, equivalently, all closed sets).

https://en.wikipedia.org/wiki/Borel_set

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Borel Sets (1-3)

- Borel sets are important in measure theory, since any measure defined on the open sets of a space, or on the closed sets of a space, must also be defined on all Borel sets of that space.
- Any measure defined on the Borel sets is called a **Borel measure**.
- Borel sets and the associated Borel hierarchy also play a fundamental role in descriptive set theory.

https://en.wikipedia.org/wiki/Borel set

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- Borel sets are those obtained from intervals by means of the operations allowed in a σ-algebra. So we may construct them in a (transfinite) "sequence" of steps:
- ... And again and again.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

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Borel Sets (3-1)

- 1. Start with finite unions of closed-open intervals. These sets are completely elementary, and they form an algebra.
- 2. Adjoin countable unions and intersections of elementary sets. What you get already includes open sets and closed sets, intersections of an open set and a closed set, and so on. Thus you obtain an algebra, that is still <u>not</u> a σ -algebra.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

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Borel Sets (3)

- Again, adjoin countable unions and intersections to 2. Observe that you get a strictly larger class, since a countable intersection of countable unions of intervals is <u>not</u> <u>necessarily</u> included in 2. Explicit examples of sets in 3 but not in 2 include F_σ sets, like, say, the set of *rational numbers*.
- 4. And do the same again.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

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Borel Sets (4-1)

• And even after a sequence of steps we are not yet finished. Take, say, a countable union of a set constructed at step 1, a set constructed at step 2, and so on. This union may very well not have been constructed at any step yet. By axioms of σ -algebra, you should include it as well - if you want, as step ∞

https://math.stackexchange.com/questions/220248/understanding-borel-sets

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Borel Sets (4-2)

- (or, technically, the first infinite ordinal, if you know what that means).
- And then continue in the same way until you reach the first uncountable ordinal. And only then will you finally obtain the generated σ -algebra.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

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Stochastic Process (1)

In probability theory and related fields, a **stochastic** (/stoʊ'kæstık/) or **random** process is a mathematical object usually defined as a family of **random variables**.

The word stochastic in English was originally used as an adjective with the definition "pertaining to **conjecturing**", and stemming from a Greek word meaning "to <u>aim</u> at a mark, <u>guess</u>", and the Oxford English Dictionary gives the year 1662 as its earliest occurrence.

From Ancient Greek στοχαστικός (stokhastikós), from στοχάζομαι (stokházomai, "aim at a target, guess"), from στόχος (stókhos, "an aim, a guess").

https://en.wikipedia.org/wiki/Stochastic https://en.wiktionary.org/wiki/stochastic

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Stochastic Process (2)

The definition of a **stochastic process** varies, but a **stochastic process** is *traditionally* defined as a collection of **random variables** indexed by some set.

The terms **random process** and **stochastic process** are considered <u>synonyms</u> and are used <u>interchangeably</u>, without the **index set** being precisely specified.

Both "collection", or "family" are used while instead of "index set", sometimes the terms "parameter set" or "parameter space" are used.

Stochastic Process (3)

The term **random function** is also used to refer to a **stochastic** or **random process**, though sometimes it is only used when the stochastic process takes <u>real values</u>.

This term is also used when the **index sets** are **mathematical spaces** other than the **real line**,

while the terms **stochastic process** and **random process** are usually used when the **index set** is interpreted as <u>time</u>,

and other terms are used such as random field when the index set is *n*-dimensional Euclidean space \mathbb{R}^n or a manifold

Stochastic Process (4)

A stochastic process can be denoted, by $\{X(t)\}_{t\in T}$, $\{X_t\}_{t\in T}$, $\{X(t)\}$, $\{X_t\}$ or simply as X or X(t), although X(t) is regarded as an abuse of function notation.

For example, X(t) or X_t are used to refer to the **random variable** with the **index** t, and not the entire **stochastic process**.

If the **index set** is $T = [0, \infty)$, then one can write, for example, $(X_t, t \ge 0)$ to denote the **stochastic process**.

Stochastic Process Definition (1)

A stochastic process is defined as a <u>collection</u> of **random variables** defined on a common **probability space** (Ω, \mathcal{F}, P) ,

- Ω is a sample space,
- \mathscr{F} is a σ -algebra,
- P is a probability measure;
- the random variables, indexed by some set T,
- all take values in the same **mathematical space** S, which must be **measurable** with respect to some σ -algebra Σ

Stochastic Process Definition (2)

In other words, for a given probability space (Ω, \mathscr{F}, P) and a measurable space (S, Σ) , a stochastic process is a collection of S-valued random variables, which can be written as:

 $\{X(t):t\in T\}.$

Stochastic Process Definition (3)

Historically, in many problems from the natural sciences a point $t \in T$ had the meaning of time, so X(t) is a **random variable** representing a value observed at time t.

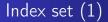
A stochastic process can also be written as $\{X(t, \omega) : t \in T\}$ to reflect that it is actually a function of two variables, $t \in T$ and $\omega \in \Omega$.

Stochastic Process Definition (4)

There are <u>other</u> ways to consider a stochastic process, with the above definition being considered the <u>traditional</u> one.

For example, a stochastic process can be interpreted or defined as a S^{T} -valued **random variable**, where S^{T} is the space of all the possible functions from the set T into the space S.

However this alternative definition as a "**function-valued random variable**" in general requires additional regularity assumptions to be **well-defined**.



The set T is called the **index set** or **parameter set** of the **stochastic process**.

Often this set is some <u>subset</u> of the <u>real line</u>, such as the natural numbers or an interval, giving the set T the interpretation of time.

Index set (2)

In addition to these sets, the index set T can be another set with a **total order** or a more general set, such as the Cartesian plane R^2 or *n*-dimensional **Euclidean space**, where an element $t \in T$ can represent a point in space.

That said, many results and theorems are only possible for **stochastic processes** with a **totally ordered index set**.



The mathematical space S of a stochastic process is called its state space.

This mathematical space can be defined using integers, real lines, *n*-dimensional Euclidean spaces, complex planes, or more abstract mathematical spaces.

The **state space** is defined using elements that reflect the different values that the **stochastic process** can take.

Sample function (1)

A sample function is a single outcome of a stochastic process, so it is formed by taking a single possible value of each random variable of the stochastic process.

More precisely, if $\{X(t, \omega) : t \in T\}$ is a **stochastic process**, then for any point $\omega \in \Omega$, the mapping $X(\cdot, \omega) : T \to S$, is called a **sample function**, a **realization**, or, particularly when T is interpreted as <u>time</u>, a **sample path** of the **stochastic process** $\{X(t, \omega) : t \in T\}$.

Sample function (2)

This means that for a fixed $\omega \in \Omega$, there exists a sample function that maps the index set T to the state space S.

Other names for a **sample function** of a **stochastic process** include **trajectory**, **path function** or **path**

Borel Sets Stochatic Process

Young W Lim Random Process Background (1B)

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