

Angle Recoding 2. Wu

1. Conventional CORDIC

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① Conventional CORDIC

elementary angle $\alpha(i) = \tan^{-1}(2^{-i})$

the number of elementary angles N

the rotation sequence $\mu(i) = \{-1, +1\}$
 $+1, -1, -1, +1, +1, \dots$

the i -th rotation angle $\alpha(i)$

the w -bit word length

the iteration number $N \leq w$

the angle quantization error

$$\xi_{m, \text{CORDIC}} \equiv \theta - \sum_{i=0}^{M-1} \mu(i) \alpha(i)$$

AQ & conventional CORDIC

EAS (Elementary Angle Set)

comprises of all $a(i)$ for $0 \leq i \leq N-1$

$$S = \{a(i) : 0 \leq i \leq N-1\}$$

the CORDIC algorithm essentially performs AQ
tries to perform the rotation
by sequential applications of
micro-rotations of all elementary angles

given a target rotation angle θ

(the first rotation sequence $\mu(0)$
for the most significant elementary angle $a(0)$

(the second rotation sequence $\mu(1)$
for the ^{next} most significant elementary angle $a(1)$

repeated until the last elementary angle is applied.

the sub-angle θ_i in AQ
 $\theta_i = \mu(i) a(i)$ in CORDIC

$$\mu(i) = \{-1, +1\}$$
$$a(i) = \tan^{-1}(2^{-i})$$

the number of sub-angles

N_A in AQ

N in CORDIC

CORDIC algorithm sequentially apply all θ_i 's
for $i = 0, 1, \dots, N-1$
to approximate the target angle θ

iteration number	elementary angle	value in radian
i=0	$a(0)=\text{atan}(2^{\{-0\}})$	
i=1	$a(1)=\text{atan}(2^{\{-1\}})$	
i=2	$a(1)=\text{atan}(2^{\{-2\}})$	
i=3	$a(1)=\text{atan}(2^{\{-3\}})$	
i=4	$a(1)=\text{atan}(2^{\{-4\}})$	
i=5	$a(1)=\text{atan}(2^{\{-5\}})$	
i=6	$a(1)=\text{atan}(2^{\{-6\}})$	
i=7	$a(1)=\text{atan}(2^{\{-7\}})$	

$$\xi_{m, \text{CORDIC}} \equiv \theta - \sum_{i=0}^M \mu(i) \alpha(i) \quad \mu(i) = \{-1, 0, +1\}$$

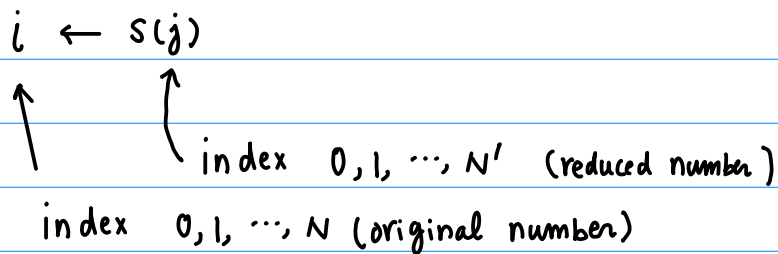
$$= \theta - \sum_{j=0}^{N'} \tilde{\theta}(j)$$

$$N' \equiv \sum_{i=0}^{N-1} |\mu(i)| \quad \{+1, 0, +1\}$$

the effective iteration number N'

$S(j)$ the rotational sequence

determines the micro-rotation angle in the j -th iteration



$$\mu(S(j)) \leftarrow \alpha(j)$$

\downarrow \uparrow
 $\{-1, +1\}$

$$\mu(i) = \begin{cases} \mu(S(j)) & i = S(j) \\ 0 & i \neq S(j) \end{cases} \quad \text{--- reduced index}$$

er

$$\begin{aligned}
 i &= 0, \overset{\text{see}}{\boxed{1, 2}}, 3, \dots, N-1 \\
 s(j) &= 0, \boxed{1, 2}, 3, \dots, N-1 && \text{rotational sequence} \\
 \alpha(j) &= -, \boxed{0, 0}, +, \dots, - && \text{directional sequence} \\
 j &= 0, -, -, 1, \dots, N'-1 && \text{effective iteration number} \\
 N' &= N-2
 \end{aligned}$$

the j -th micro-rotation of $a(s(j))$

elementary angle

$$a(i) = \tan^{-1}(2^{-i})$$

$$a(s(j)) = \tan^{-1}(2^{-s(j)})$$

$$\alpha(j) a(s(j)) = \alpha(j) \tan^{-1}(2^{-s(j)})$$

$$\alpha(j) \in \{-1, +1\}$$

$$\Leftrightarrow \mu(i) a(i)$$

$$\mu(i) \in \{-1, 0, +1\}$$

$$\xi_{m, \text{CORDIC}} \equiv \theta - \sum_{i=0}^{M-1} \mu(i) a(i) \quad \mu(i) \in \{-1, 0, +1\}$$

$$= \theta - \left[\sum_{j=0}^{N'} \tilde{\theta}(j) \right]$$

$$= \theta - \left[\sum_{j=0}^{N'} \tan^{-1}(\alpha(j) \cdot 2^{-s(j)}) \right] \quad \alpha(j) \in \{-1, +1\}$$

$$\tilde{\theta}(j) = \alpha(j) \tan^{-1}(2^{-s(j)})$$

$$= \tan^{-1}(\alpha(j) \cdot 2^{-s(j)})$$

$$S_1 = \left\{ \tan^{-1}(\boxed{\alpha} \cdot 2^{-\boxed{s}}) \mid \boxed{\alpha} \in \{-1, 0, +1\}, \boxed{s} \in \{0, 1, 2, \dots, N-1\} \right\}$$


```
>> mu = [1, -1, 1, 1, -1, 1, -1, -1, 1, -1, -1, 1, 1, -1, 1, 1]
>> length(mu)
ans = 16
>> s = [ 0: 15]
>> atan(1)
ans = 0.78540
>> pi/4
ans = 0.78540
>> sum(atan(2.^(-s)) .* mu)
ans = 0.63815
>> 13 * pi / 32
ans = 1.2763
```