

BJT Bias Operating Point (H.4)

20170421-2

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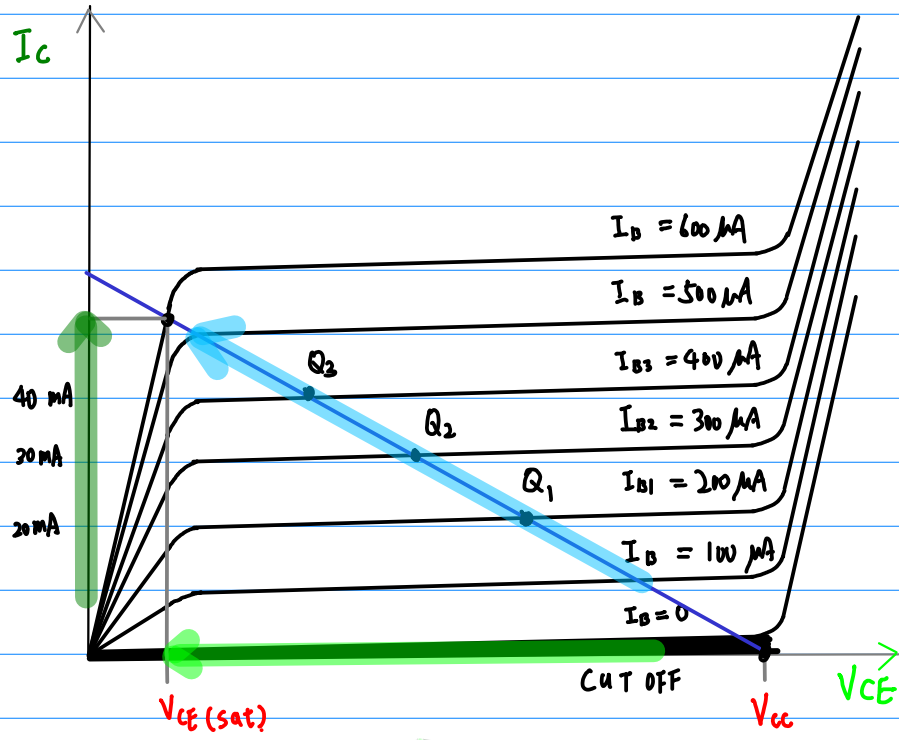
References

Based

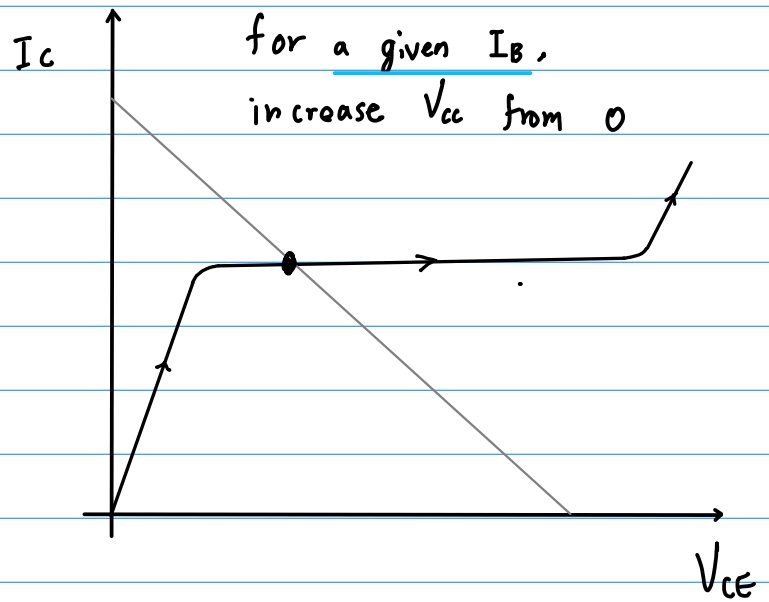
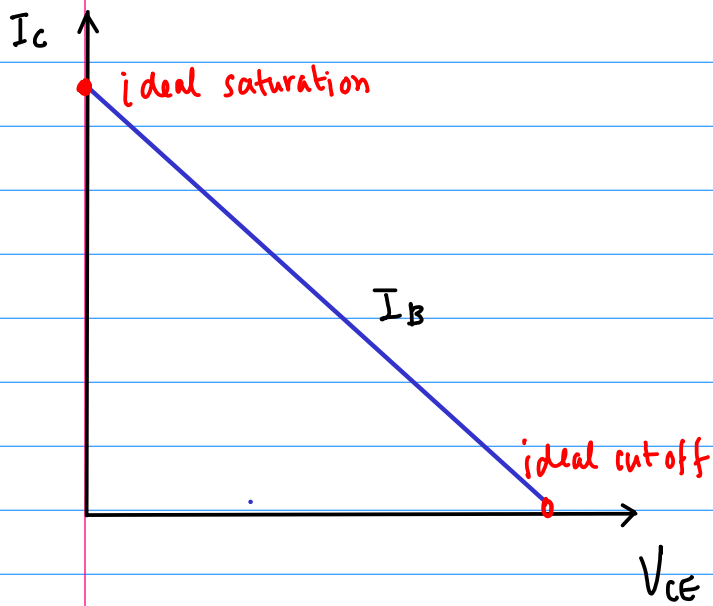
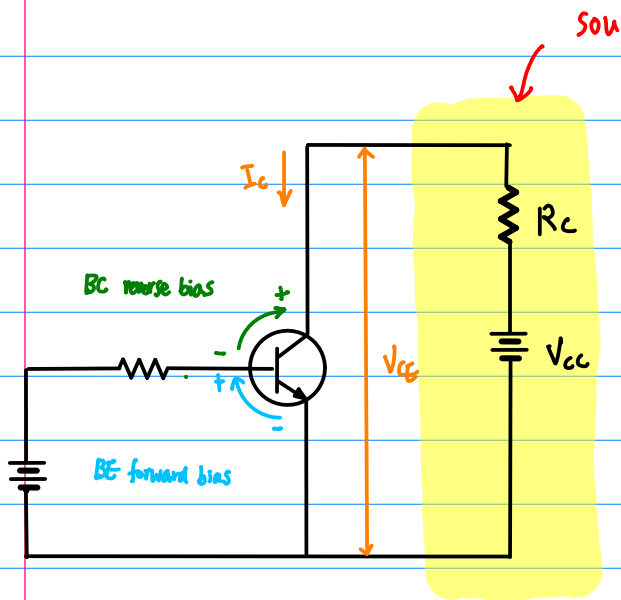
[1] Floyd, Electronic Devices 7th ed

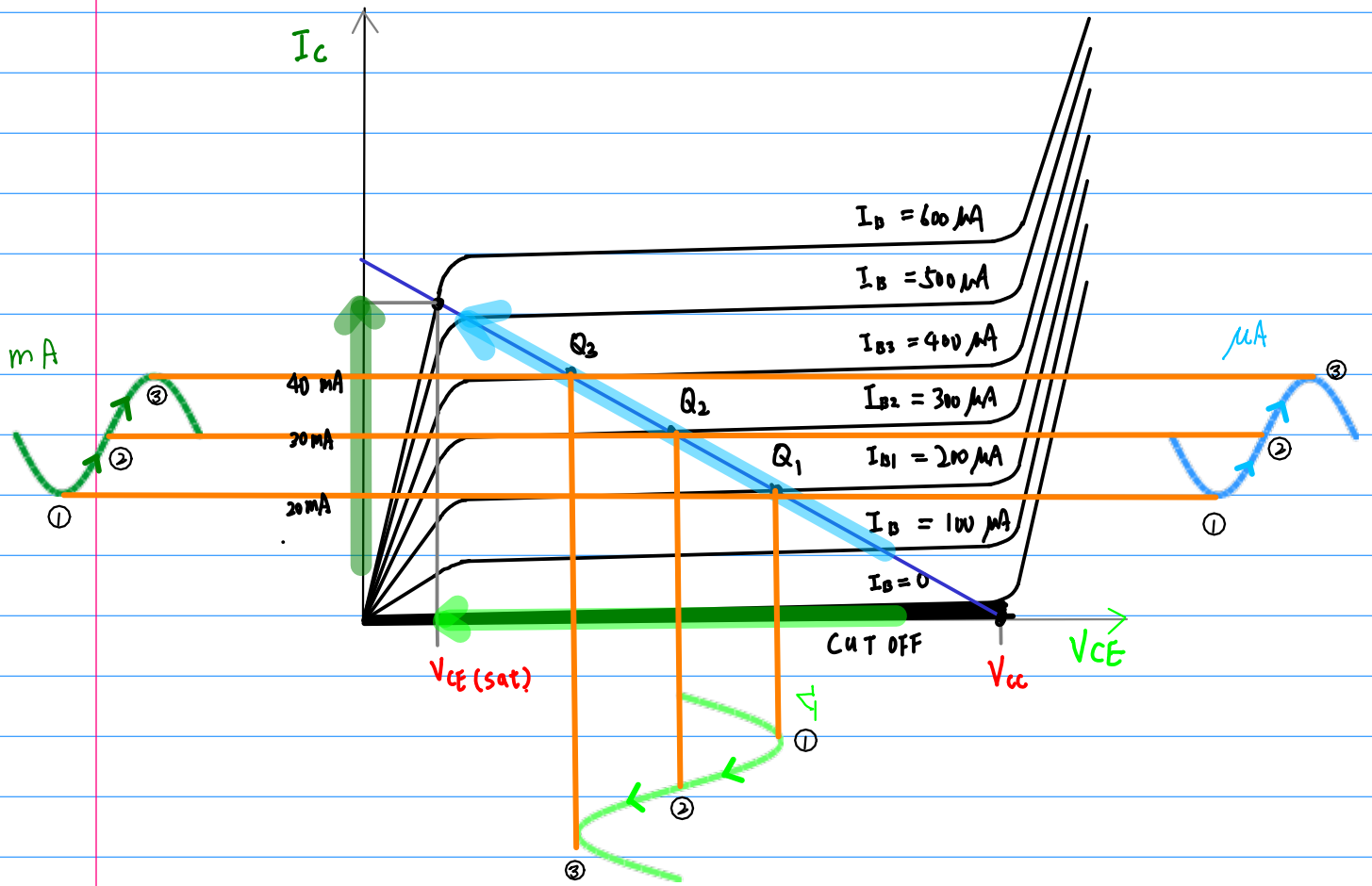
[2] Cook,

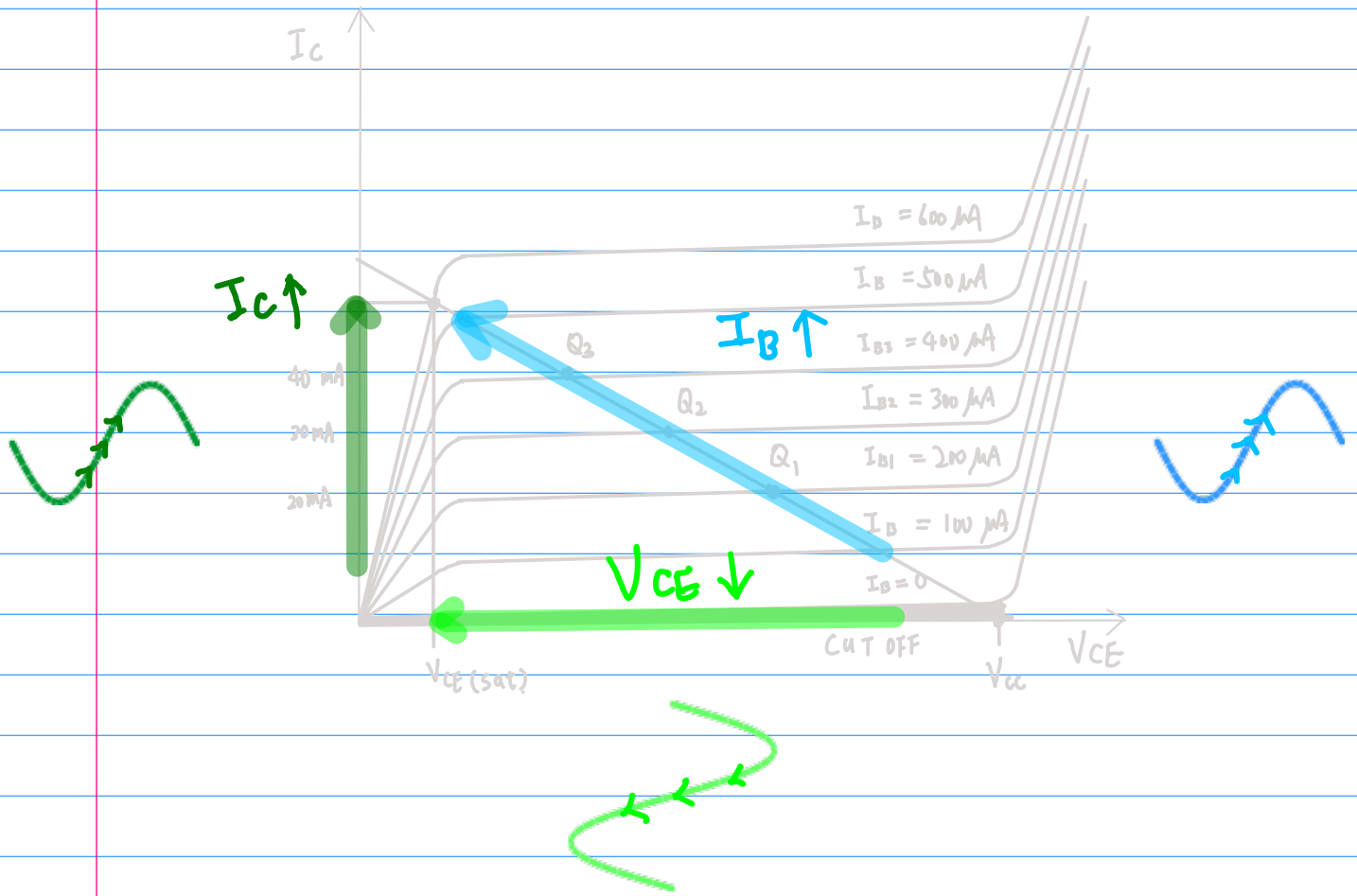
[2] en.wikipedia.org



Simultaneous Equations Solution



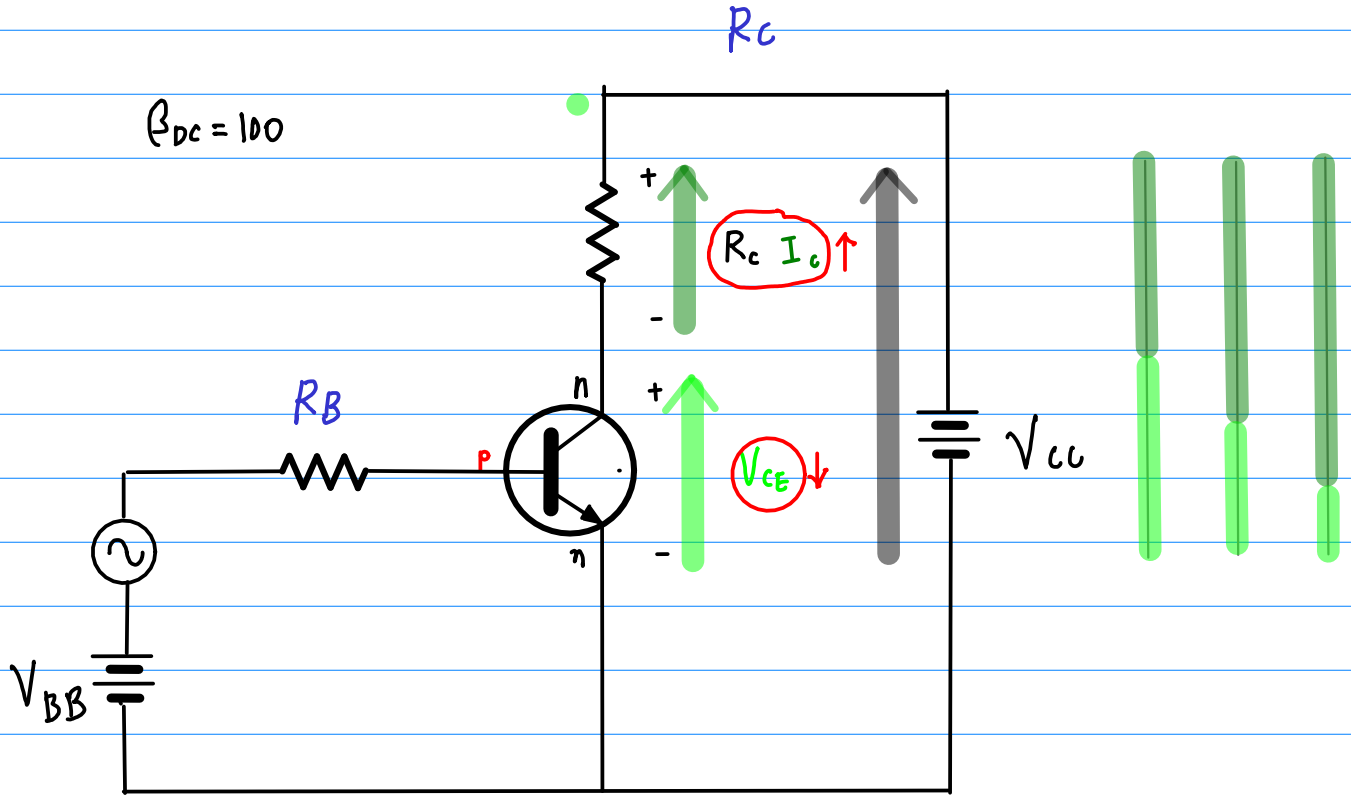


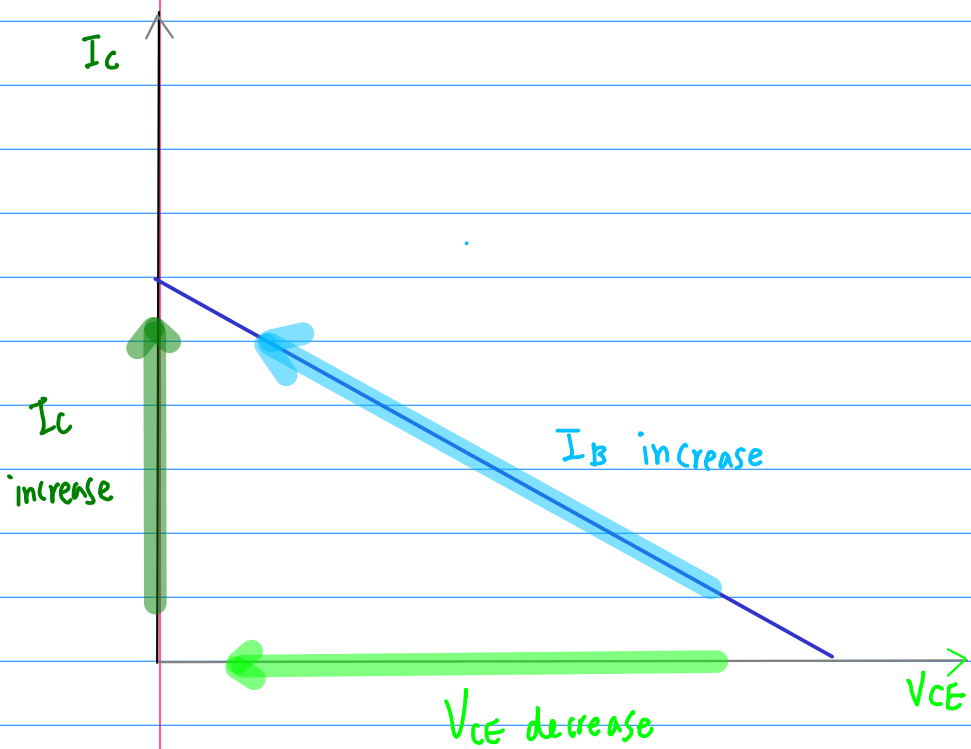
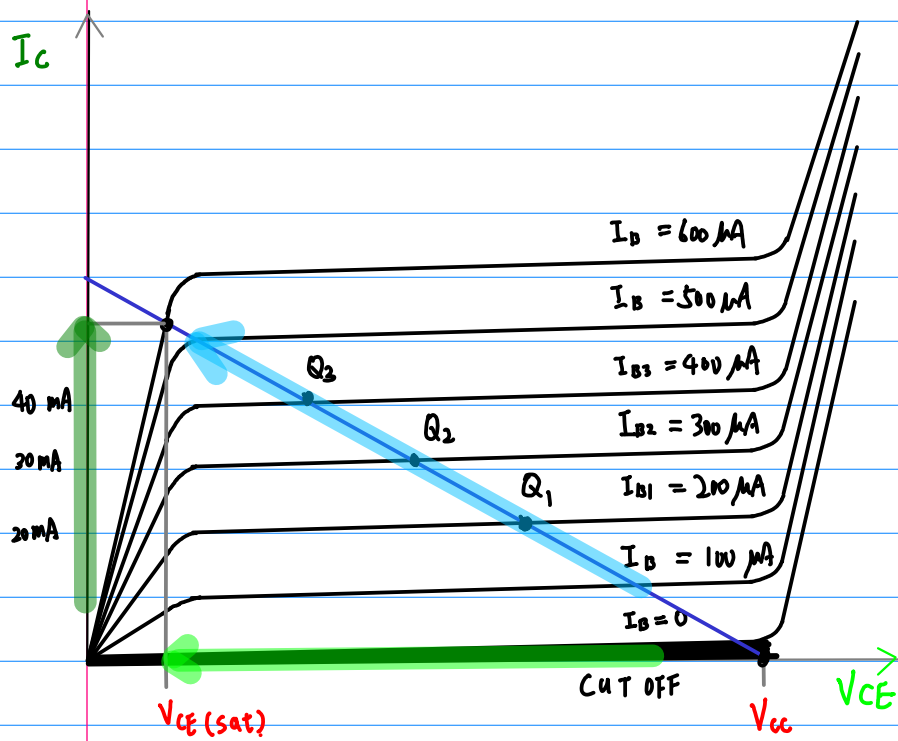


$I_c \uparrow$

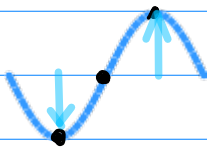


$V_{CE} \downarrow$



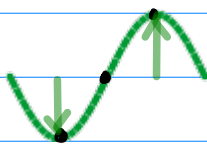


I Δ



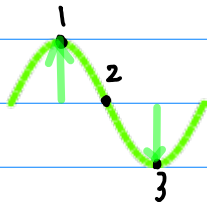
$$I_B = 400 \mu A$$
$$I_B = 300 \mu A$$
$$I_B = 200 \mu A$$

$$300 \mu A + 100 \mu A = 300 \mu A + \Delta I_B$$
$$300 \mu A = 300 \mu A$$
$$300 \mu A - 100 \mu A = 300 \mu A - \Delta I_B$$



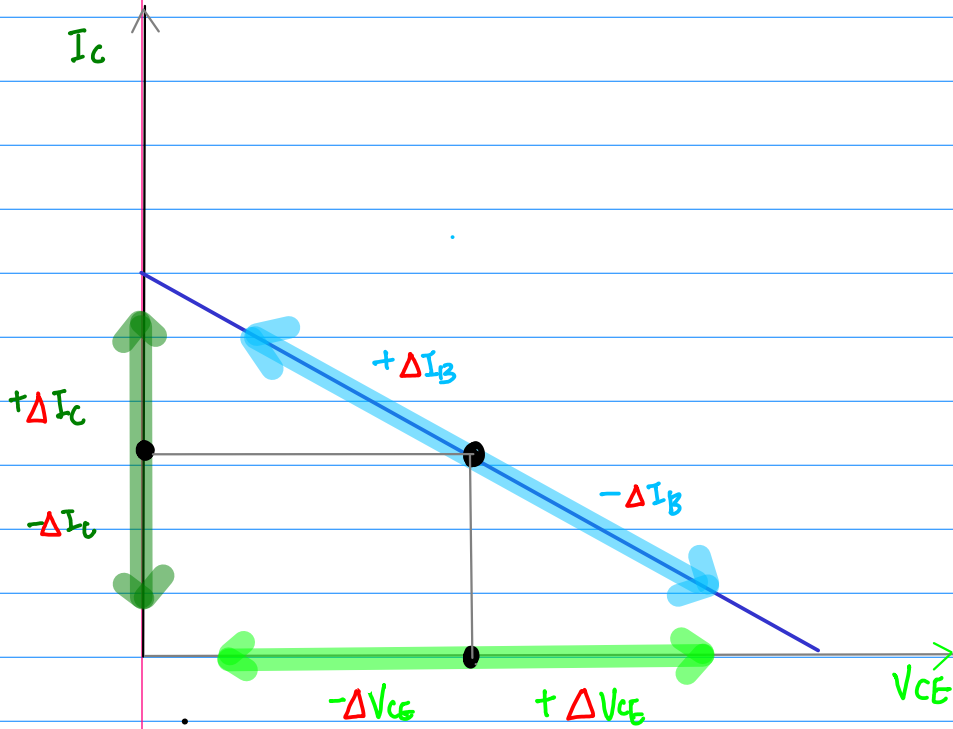
$$I_C = 40 \text{ mA}$$
$$I_C = 30 \text{ mA}$$
$$I_C = 20 \text{ mA}$$

$$30 \text{ mA} + 10 \text{ mA} = 30 \text{ mA} + \Delta I_C$$
$$30 \text{ mA} = 30 \text{ mA}$$
$$30 \text{ mA} - 10 \text{ mA} = 30 \text{ mA} - \Delta I_C$$



$$V_{CE} = V_1$$
$$V_{CE} = V_2$$
$$V_{CE} = V_3$$

$$V_2 + (V_1 - V_2) = V_2 + \Delta V_{CE}$$
$$V_2 = V_2$$
$$V_2 + (V_3 - V_2) = V_2 - \Delta V_{CE}$$

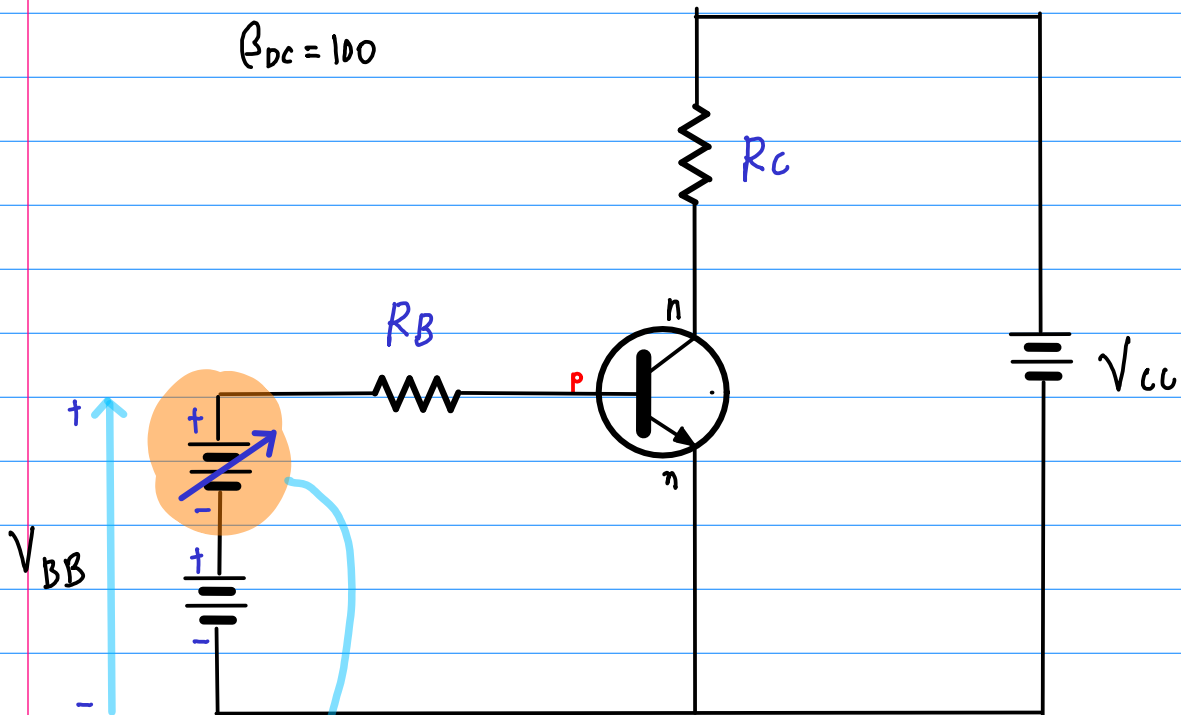


$$I_B \rightarrow I_B + \Delta I_B \quad \rightarrow \quad \begin{matrix} I_C \rightarrow I_C + \Delta I_C \\ V_{CE} \rightarrow V_{CE} - \Delta V_{CE} \end{matrix}$$

$$I_B \rightarrow I_B - \Delta I_B \quad \rightarrow \quad \begin{matrix} I_C \rightarrow I_C - \Delta I_C \\ V_{CE} \rightarrow V_{CE} + \Delta V_{CE} \end{matrix}$$

$$I_B = (V_{BB} - 0.7) / R_B$$

$$\beta_{DC} = 100$$

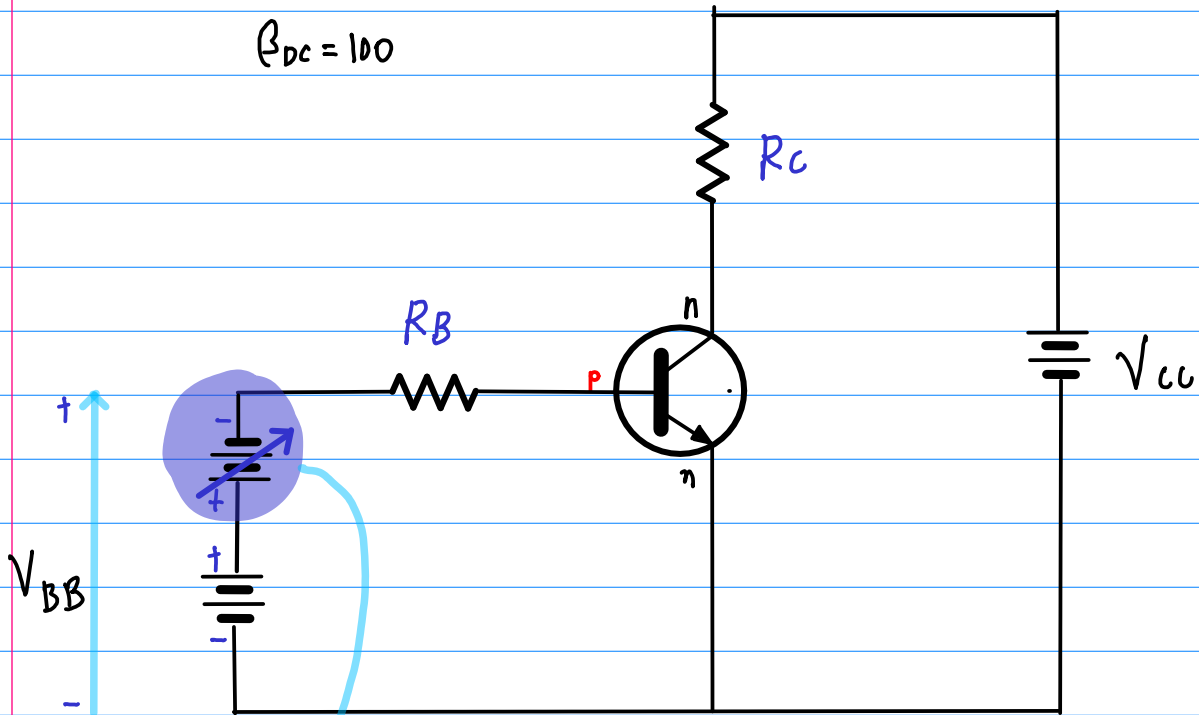


$$I_B \rightarrow I_B + \Delta I_B$$

$$\begin{aligned} I_C &\rightarrow I_C + \Delta I_C \\ V_{CE} &\rightarrow V_{CE} - \Delta V_{CE} \end{aligned}$$

$$I_B = (V_{BB} - 0.7) / R_B$$

$$\beta_{DC} = 100$$



$$I_B \rightarrow I_B - \Delta I_B$$

$$\begin{aligned} I_C &\rightarrow I_C - \Delta I_C \\ V_{CE} &\rightarrow V_{CE} + \Delta V_{CE} \end{aligned}$$

Current Controlled Device (I_B)

$$\begin{array}{l} I_B \uparrow \rightarrow R_{CE} \downarrow \\ I_B \uparrow \rightarrow I_C \uparrow \end{array} \left. \vphantom{\begin{array}{l} I_B \uparrow \rightarrow R_{CE} \downarrow \\ I_B \uparrow \rightarrow I_C \uparrow \end{array}} \right\} V_{CE} \downarrow$$

$$\boxed{V = I R}$$

$\downarrow \quad \uparrow \quad \downarrow$

decrease move faster

$$\boxed{\downarrow R = \frac{V \downarrow}{I \uparrow}}$$

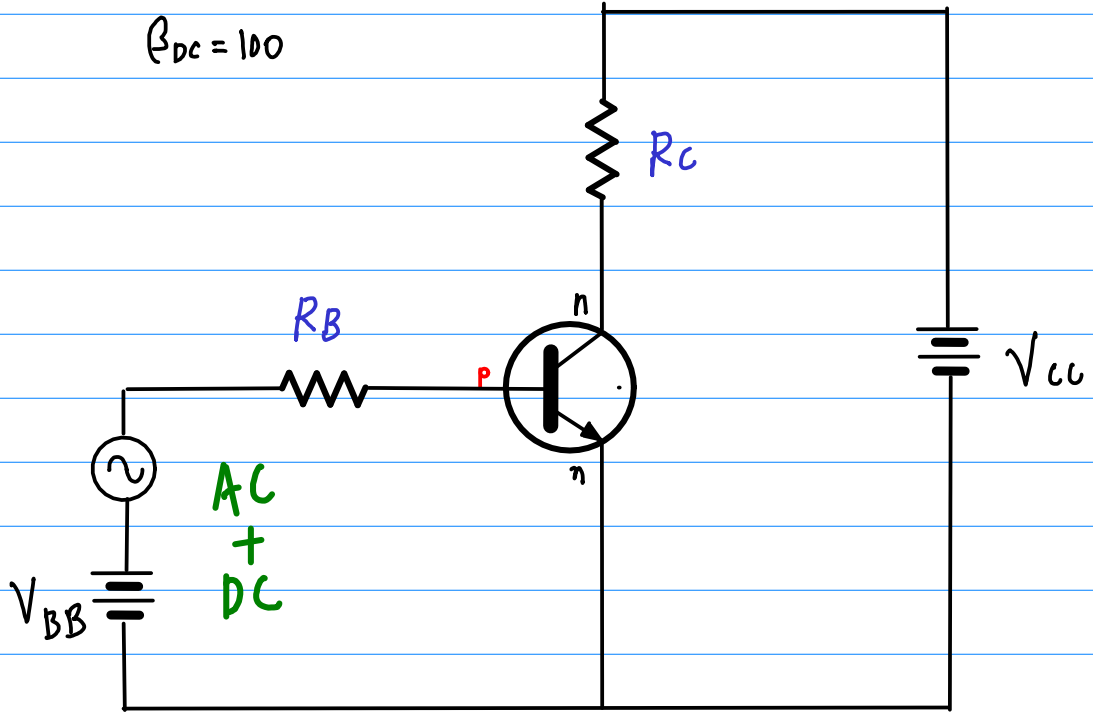
Only for Active Region

$$\boxed{\beta \cdot I_B = I_C}$$

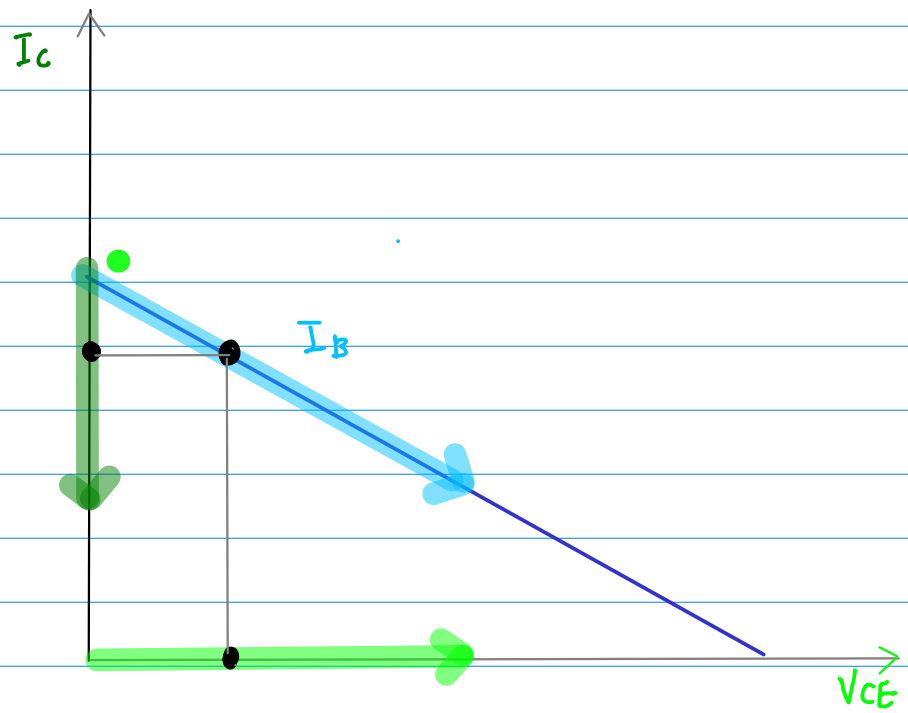
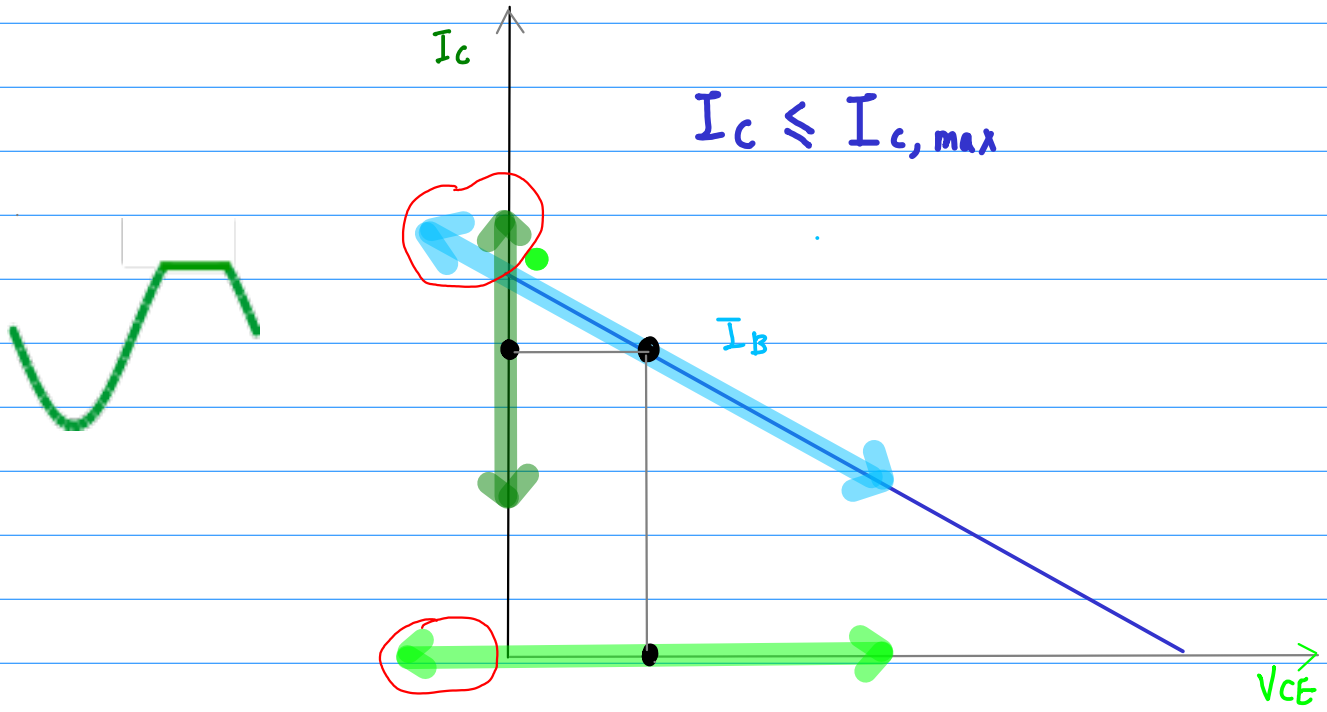
$$\beta = 100 \sim 200$$

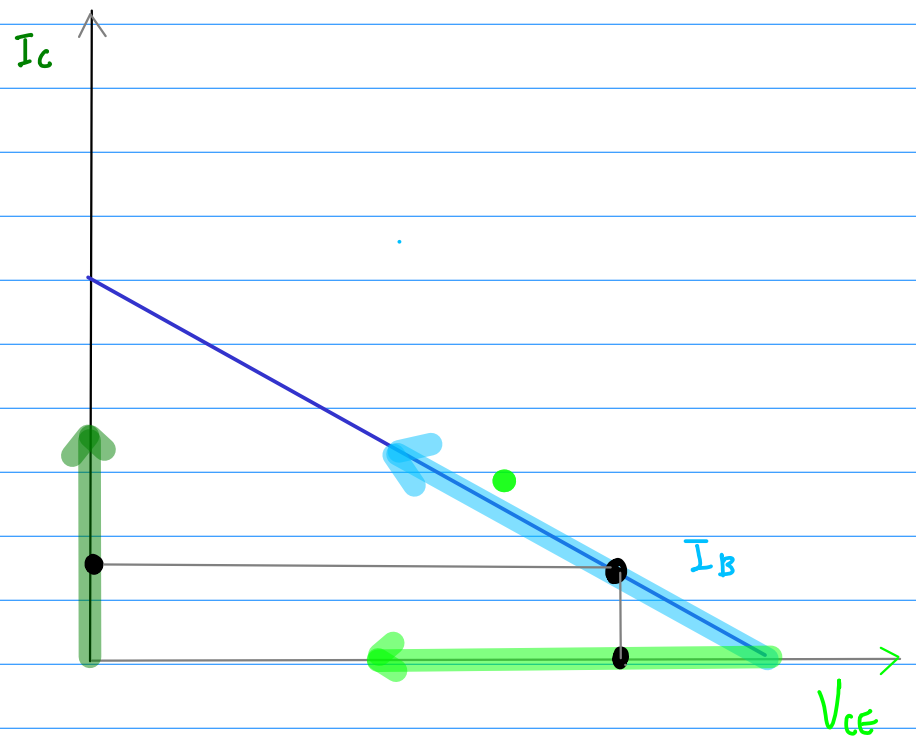
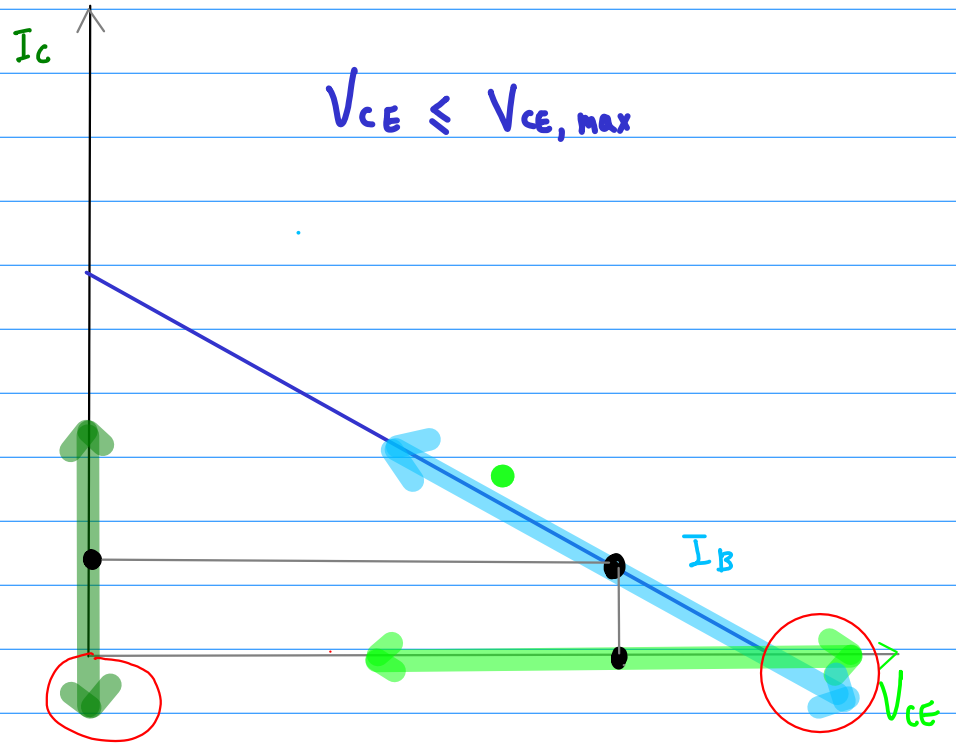
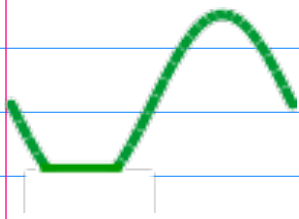
$$\beta \cdot \boxed{2I_B} = \boxed{2I_C}$$

$$\beta \cdot \boxed{3I_B} = \boxed{3I_C}$$

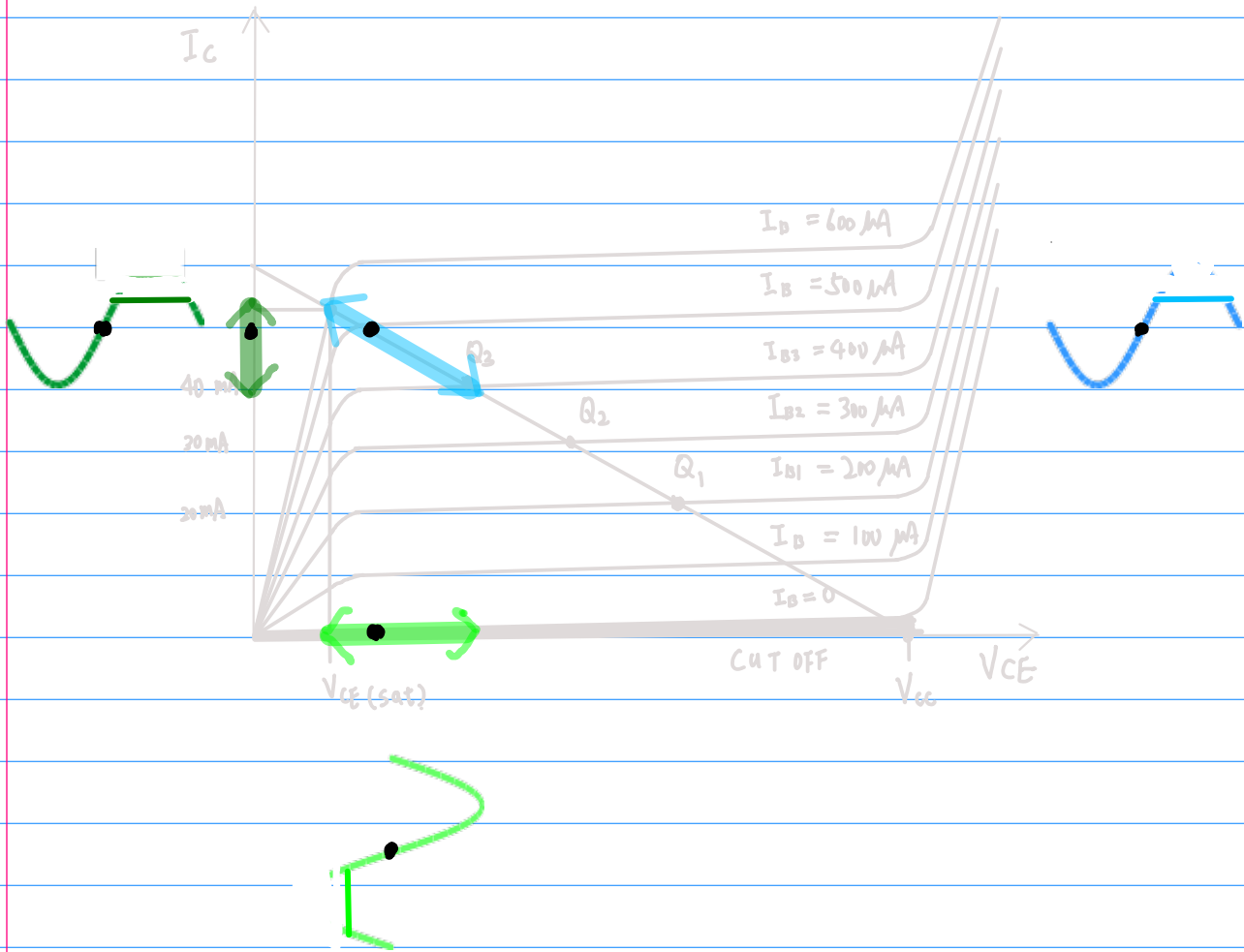


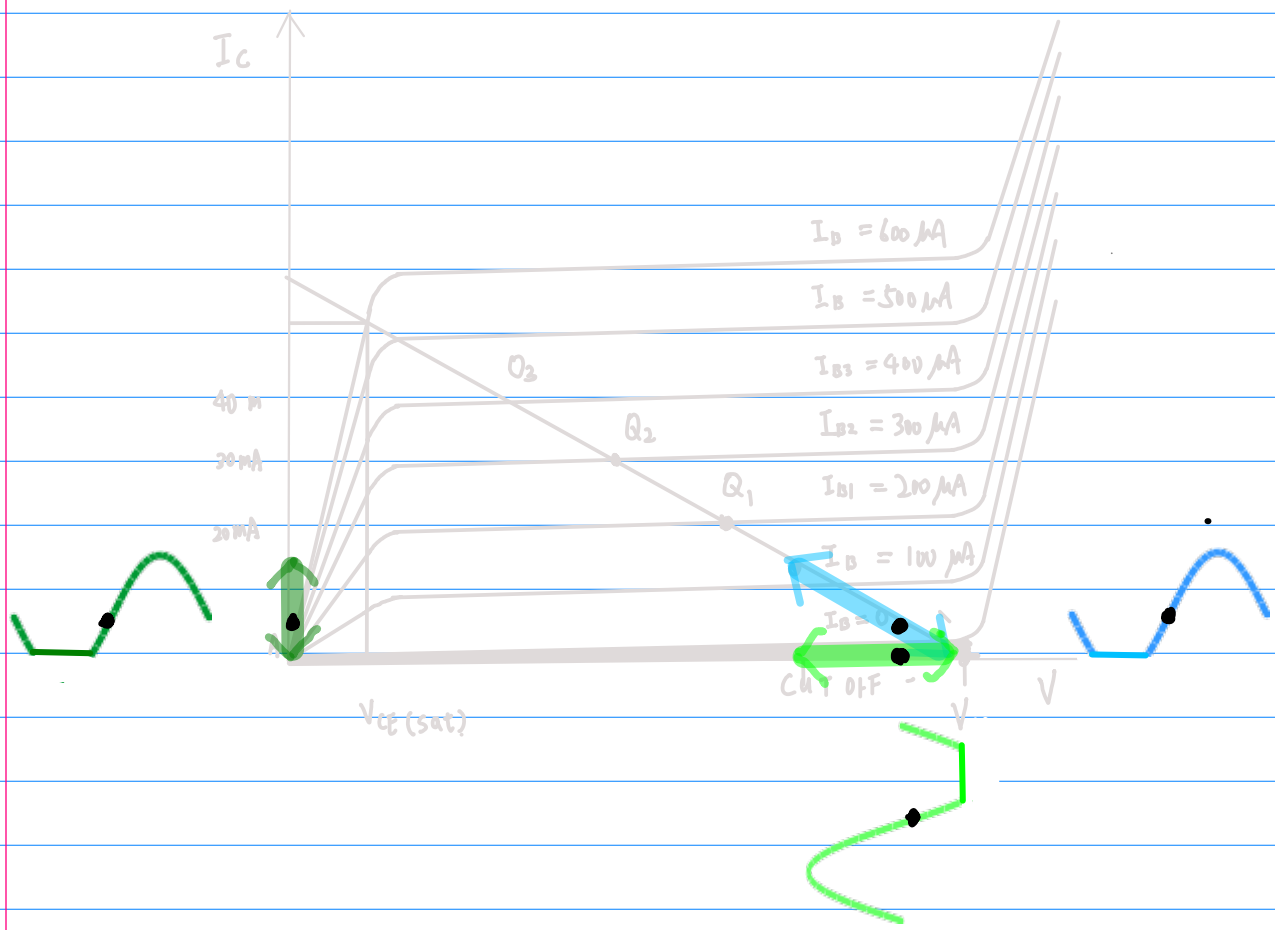
The Central Point





Solution Ranges

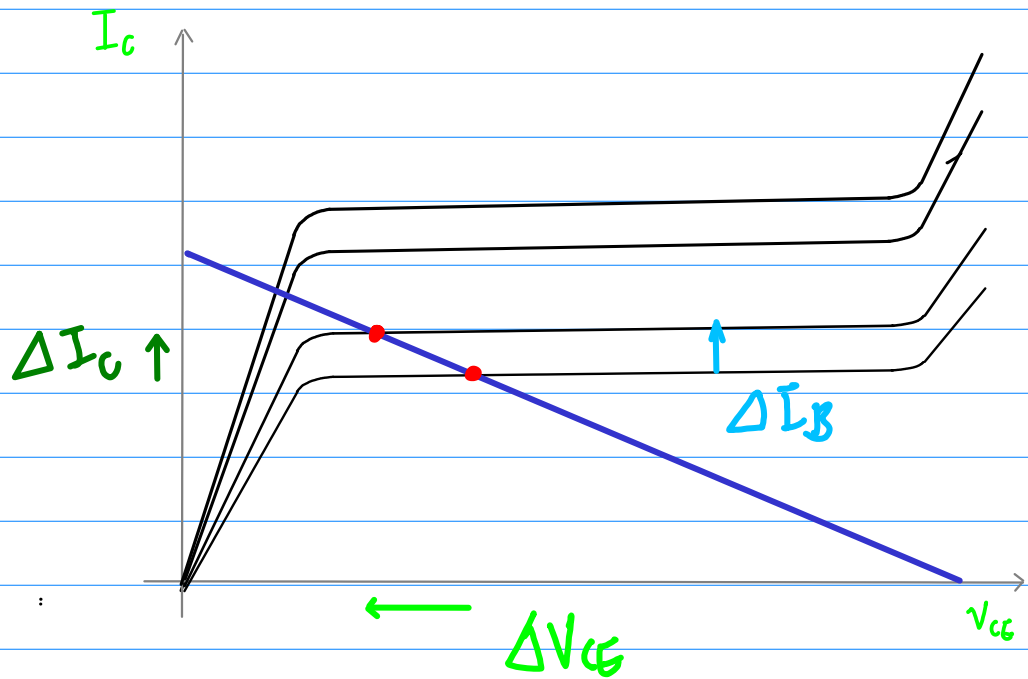






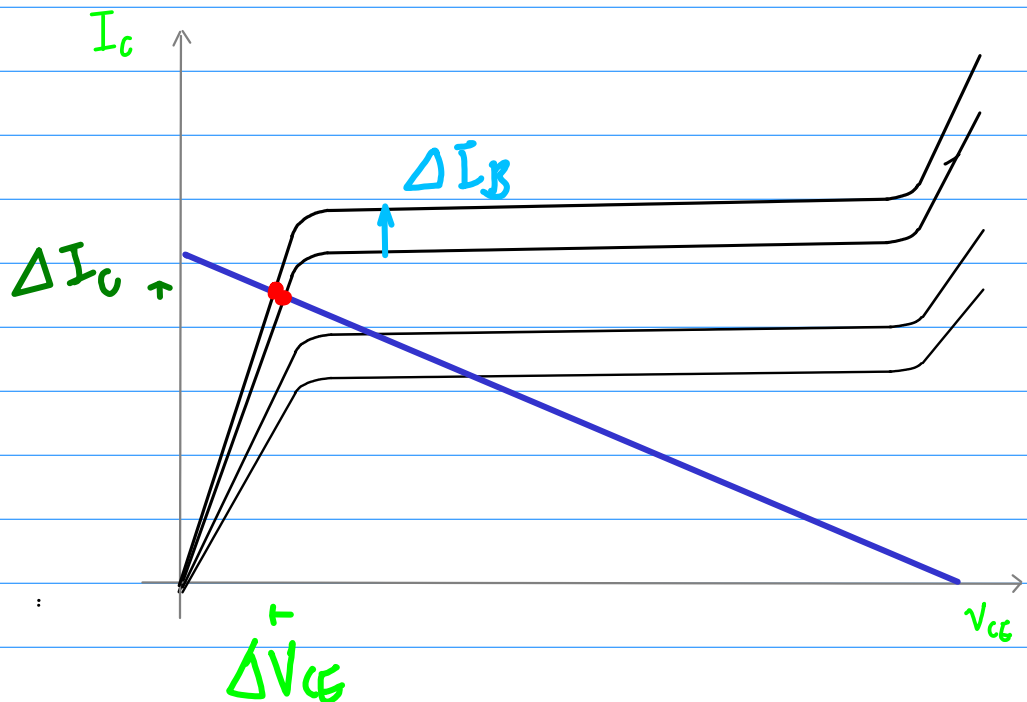
Why saturation

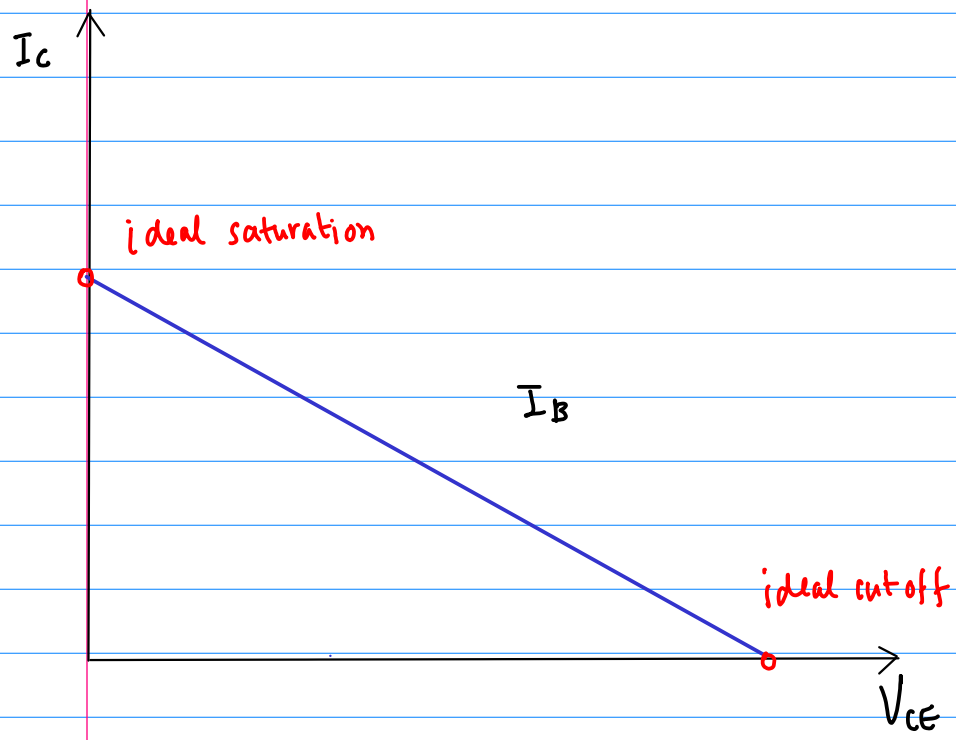
Active Region

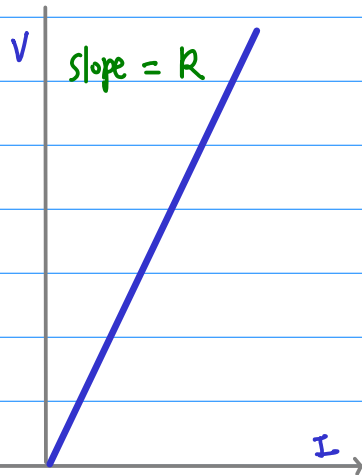


Saturation Region

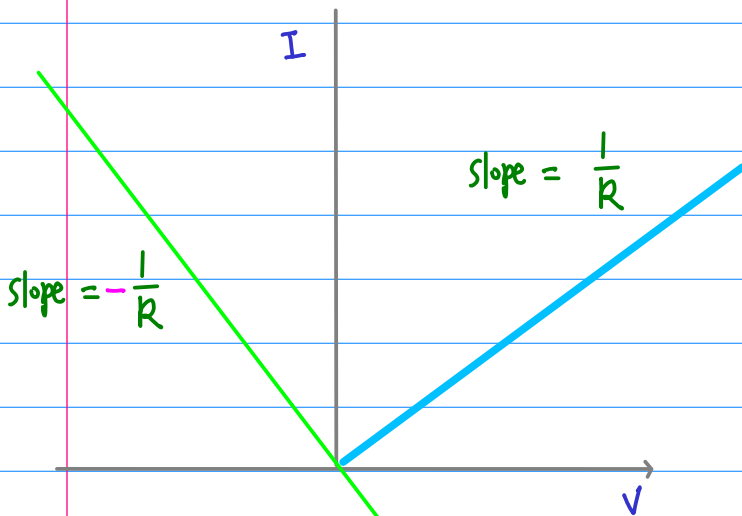
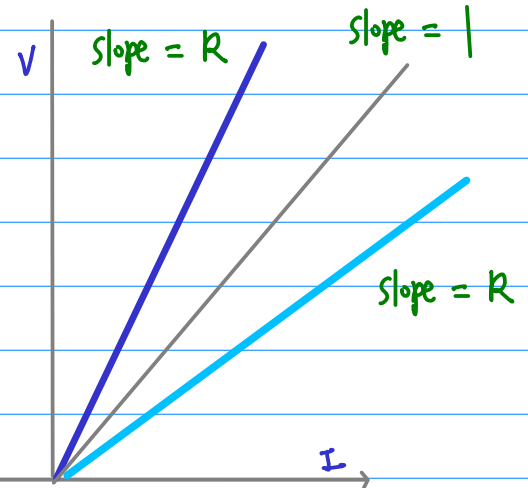
very small change
no visible change
Saturated







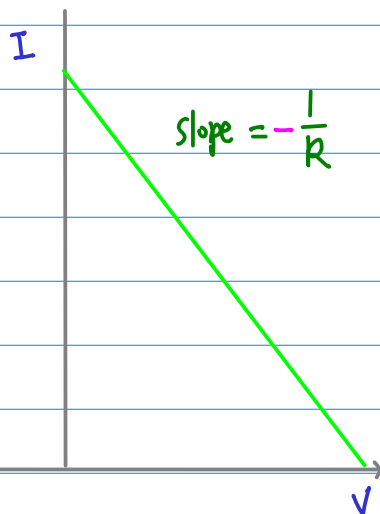
$$V = RI$$



* Change axis $I \leftrightarrow V$

$$V = RI \rightarrow I = \frac{1}{R} V$$

* reflect along V-axis

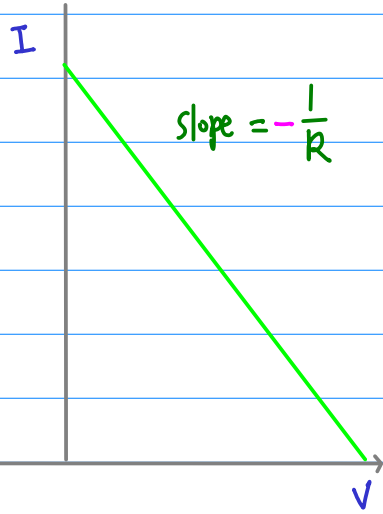


* shift to the right by V_{cc}

$$I = -\frac{1}{R} (V - V_{cc})$$

$$IR = -V + V_{cc}$$

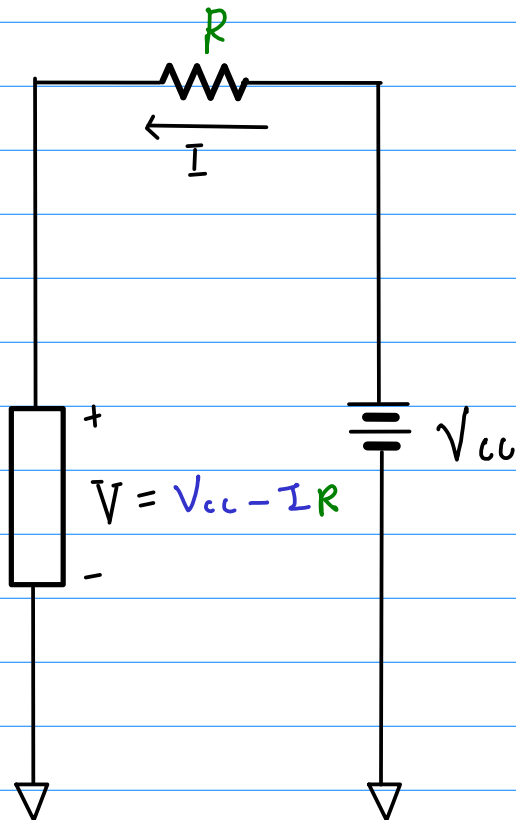
$$V = V_{cc} - IR$$

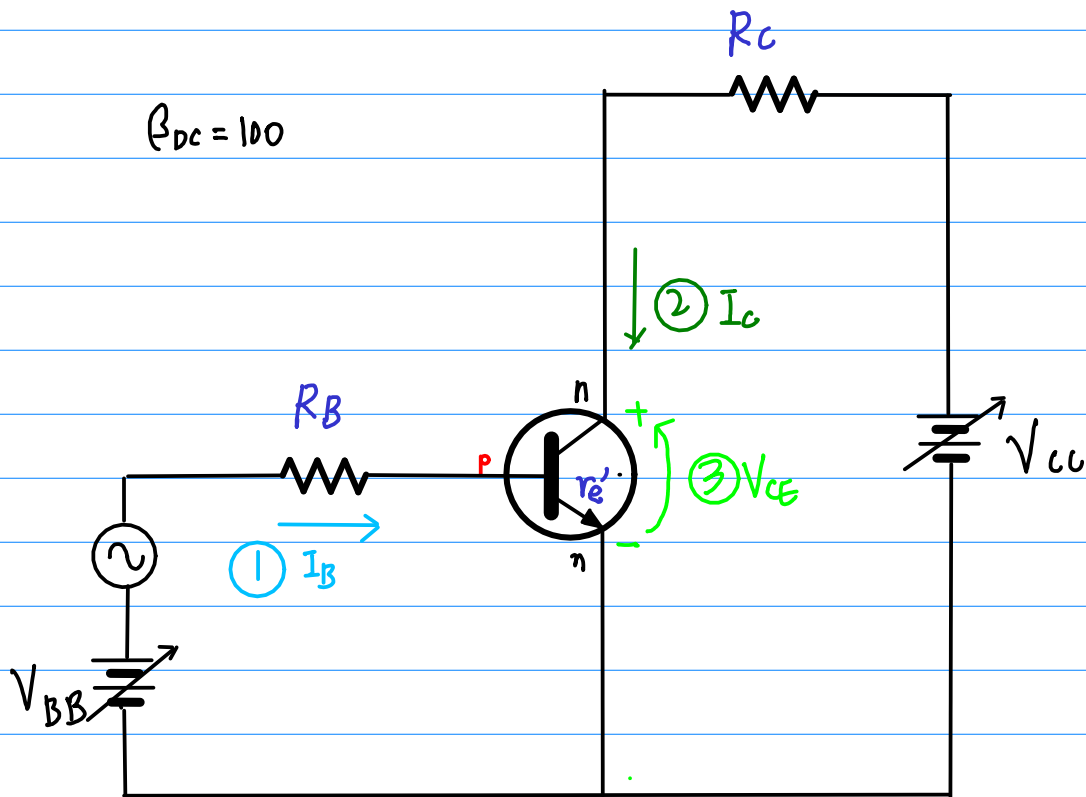


$$I = -\frac{1}{R} (V - V_{cc})$$

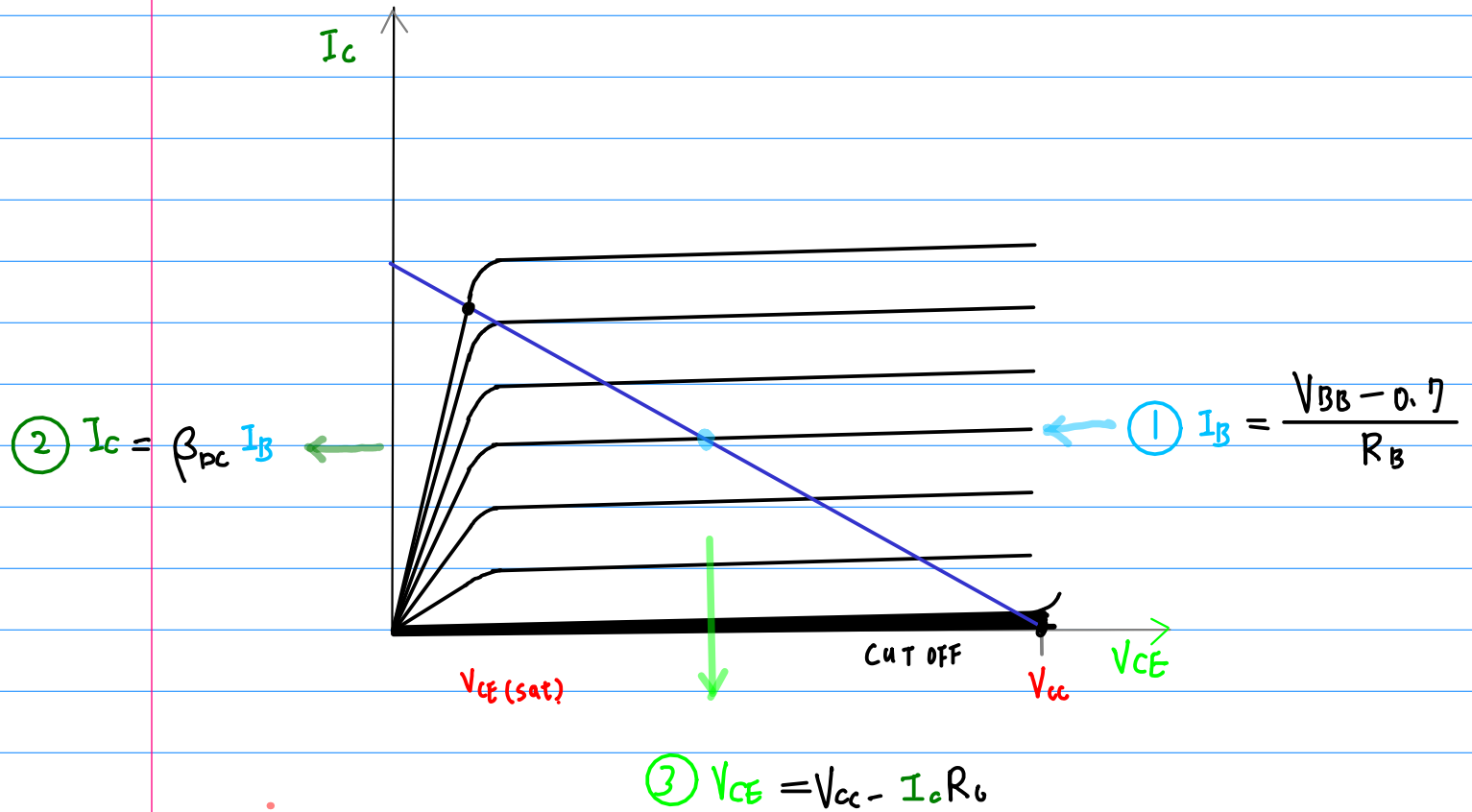
$$IR = -V + V_{cc}$$

$$V = V_{cc} - IR$$





$$\textcircled{1} I_B = \frac{V_{BB} - 0.7}{R_B} \rightarrow \textcircled{2} I_C = \beta_{DC} I_B \rightarrow \textcircled{3} V_{CE} = V_{CC} - I_C R_C$$

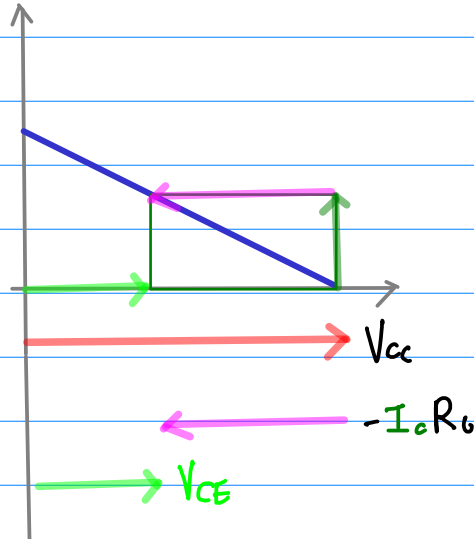


① $I_B = \frac{V_{BB} - 0.7}{R_B}$ → ② $I_c = \beta_{DC} I_B$ → ③ $V_{ce} = V_{cc} - I_c R_o$

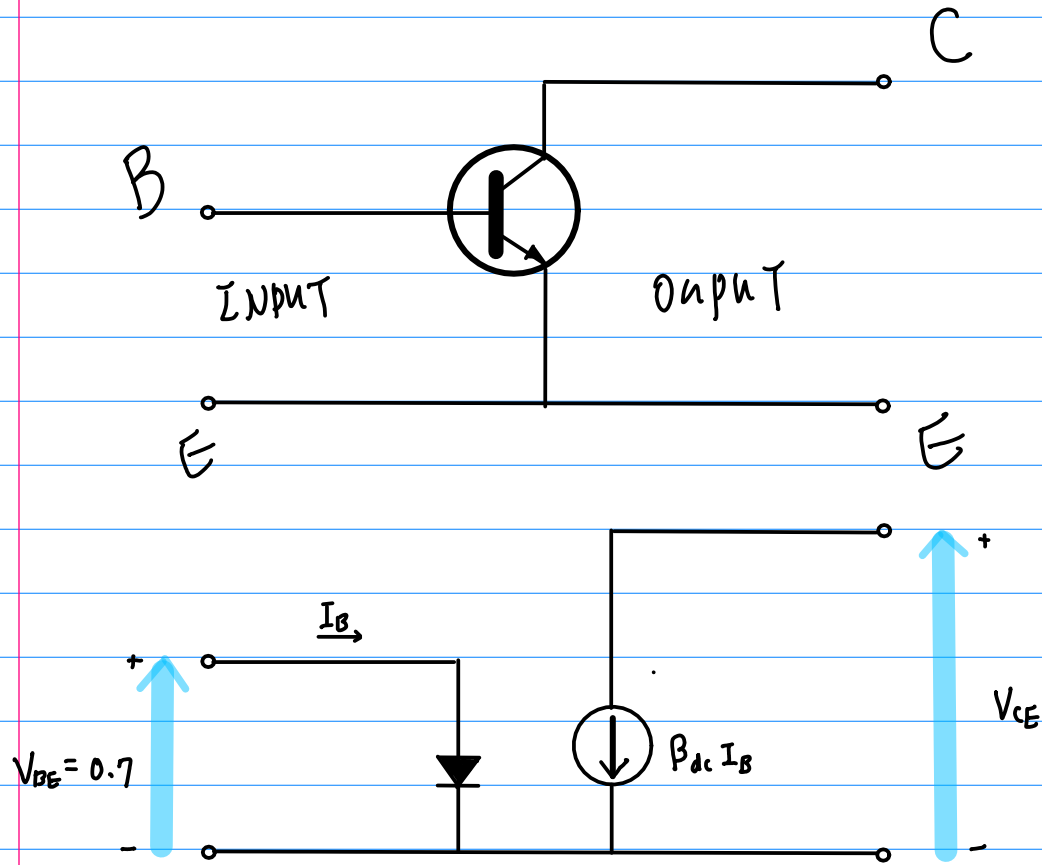
③ $V_{ce} = V_{cc} - I_c R_o$

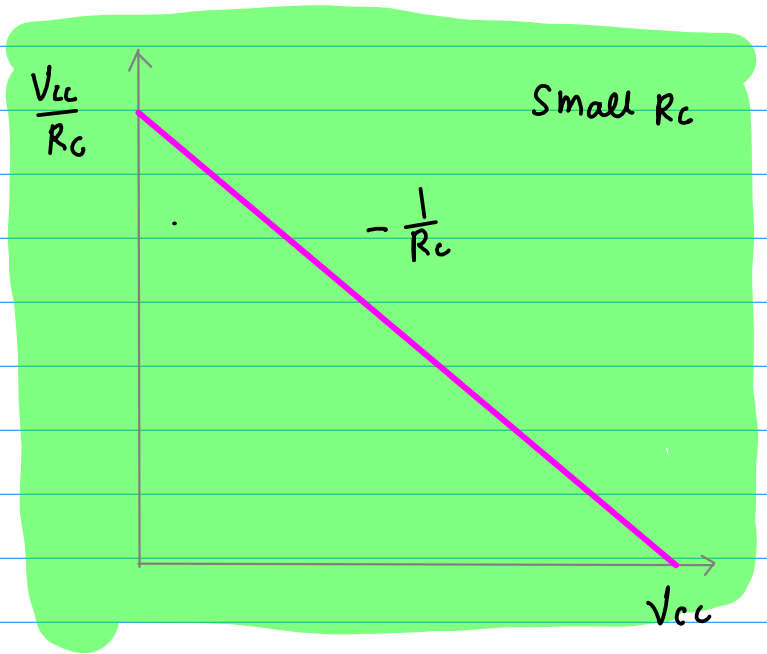
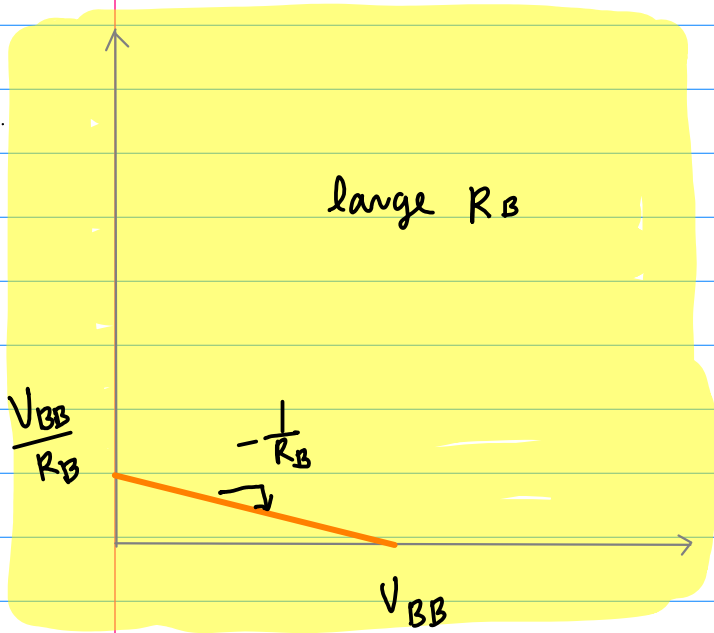
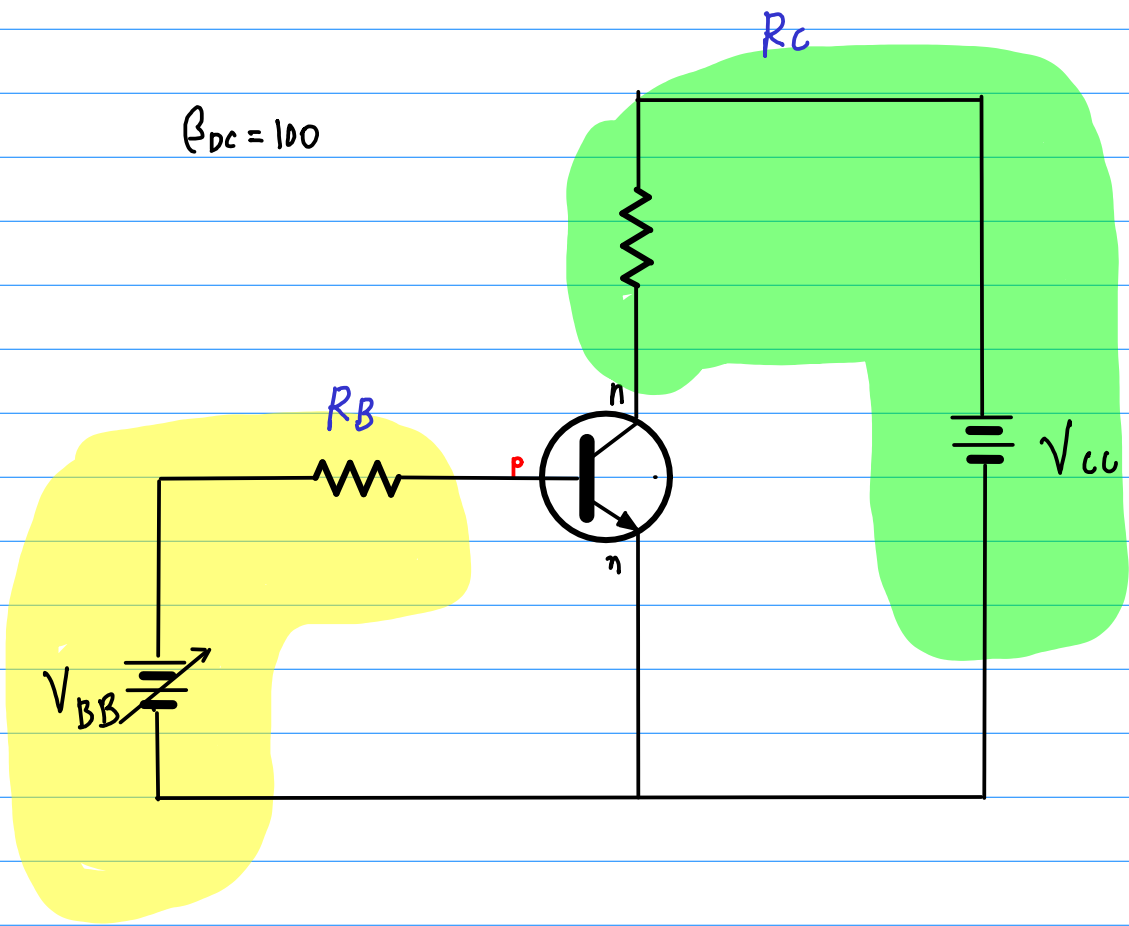
$I_c = \frac{1}{R_o} \cdot (V_{ce} - V_{cc})$

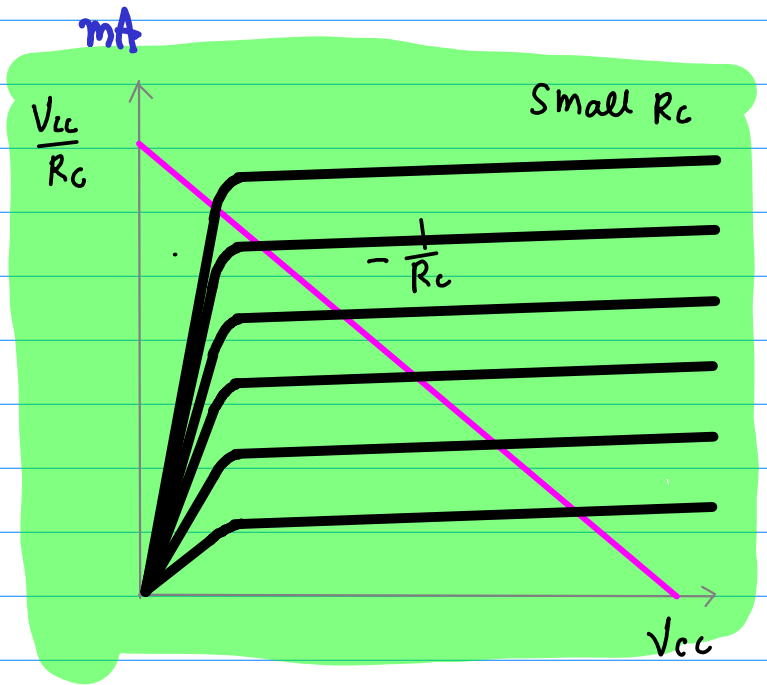
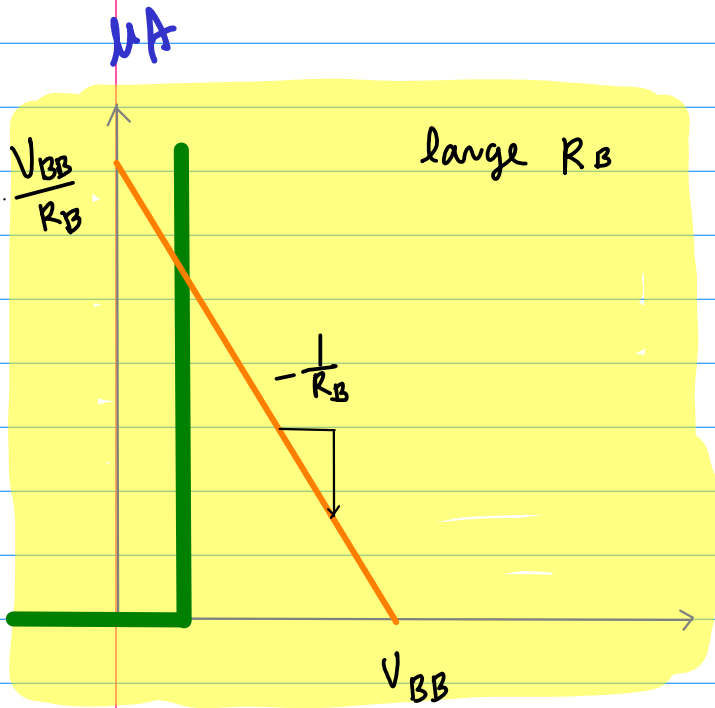
↓ ↑
y x

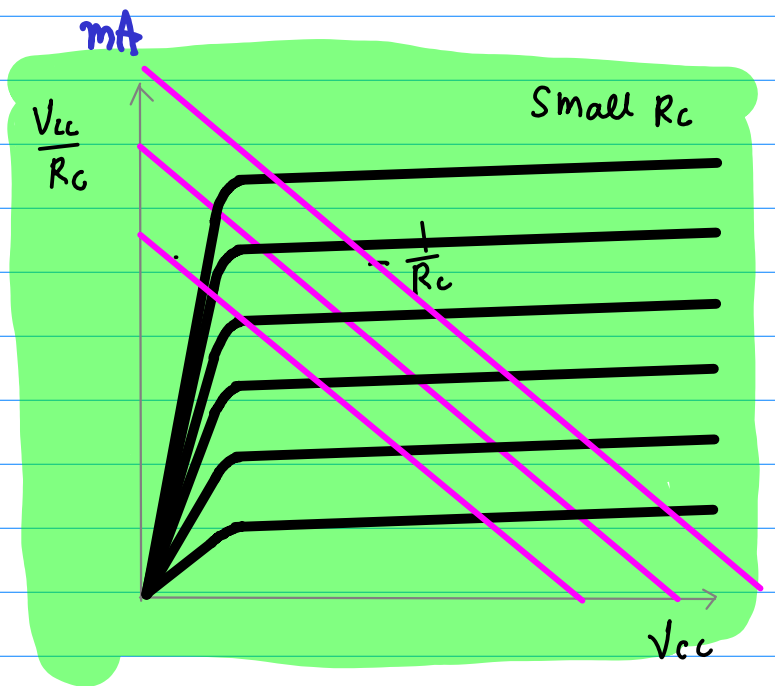
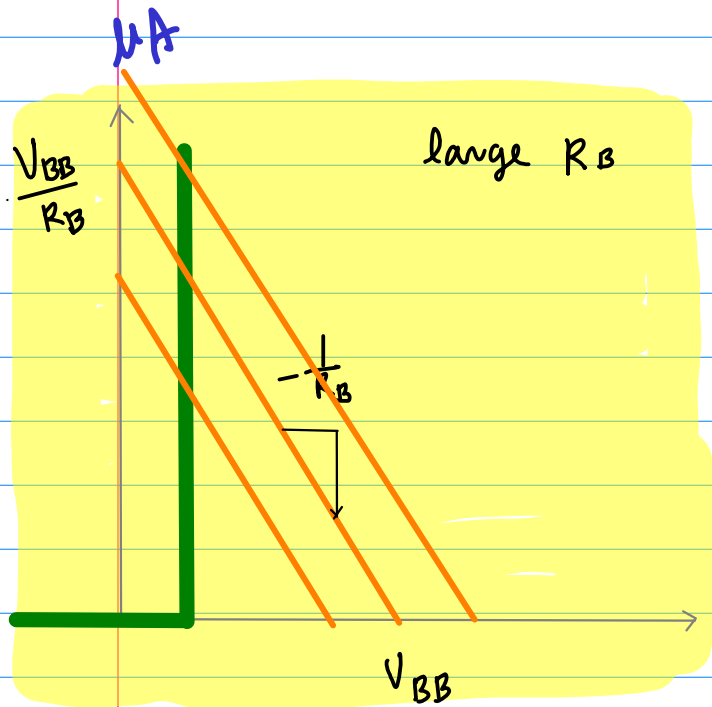
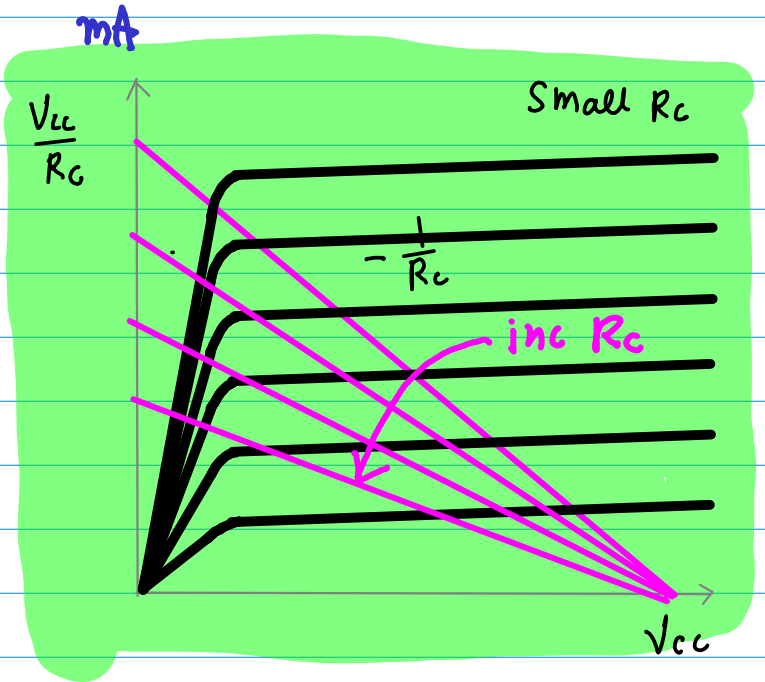
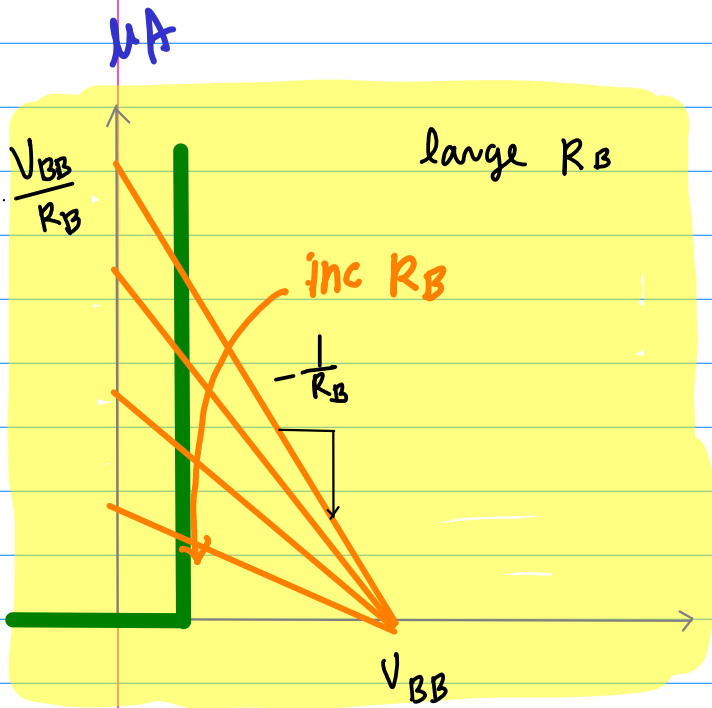


Transistor Approximation









→ inc V_{BB}

→ inc V_{CC}



