Random Process Background

Young W Lim

May 16, 2023

Young W Lim Random Process Background

< 1 →

- ∢ ⊒ →

э

Copyright (c) 2023 - 2018 Young W. Lim. Permission is granted to copy, distribute and/or modify this document under the terms of the GNU Free Documentation License, Version 1.2 or any later version published by the Free Software Foundation; with no Invariant Sections, no Front-Cover Texts, and no Back-Cover Texts. A copy of the license is included in the section entitled "GNU Free Documentation License".

This work is licensed under a Creative Commons "Attribution-NonCommercial-ShareAlike 3.0 Unported" license.



イロト イポト イヨト イヨト

э

Based on Probability, Random Variables and Random Signal Principles, P.Z. Peebles, Jr. and B. Shi

Outline



1 Measurable Space

- Measurable Space
- Sigma Alebra
- Topological Space



Measurable Space **Topological Space**

Outline



1 Measurable Space

- Measurable Space
- Sigma Alebra
- Topological Space



Measurable Space Sigma Alebra Topological Space



• A space consists of

selected mathematical objects that are treated as points, and selected relationships between these points.

- the nature of the points can vary widely: for example, the points can be
 - elements of a set
 - functions on another space
 - subspaces of another space
- It is the relationships that define the nature of the space.

https://en.wikipedia.org/wiki/Space_(mathematics)

Measurable Space Sigma Alebra Topological Space



- While modern mathematics uses many types of spaces, such as
 - Euclidean spaces
 - linear spaces
 - topological spaces
 - Hilbert spaces
 - probability spaces
- it does not define the notion of space itself.

https://en.wikipedia.org/wiki/Space_(mathematics)



• a space is

a set (or a universe) with some added structure

- It is <u>not</u> always clear whether a given <u>mathematical object</u> should be considered as a geometric **space**, or an algebraic **structure**
- A general definition of **structure** embraces all common types of **space**

https://en.wikipedia.org/wiki/Space_(mathematics)

Mathematical objects (1)

A mathematical object is an abstract concept arising in mathematics.

- an mathematical object is anything that has been (or could be) formally <u>defined</u>, and with which one may do
 - deductive reasoning
 - mathematical proofs

https://en.wikipedia.org/wiki/Mathematical_object

Measurable Space Sigma Alebra Topological Space

Mathematical objects (2)

• Typically, a mathematical object

- can be a value that can be assigned to a variable
- therefore can be involved in formulas

https://en.wikipedia.org/wiki/Mathematical_object

< (目) → (目)

Measurable Space Sigma Alebra Topological Space

Mathematical objects (3)

• Commonly encountered mathematical objects include

- numbers
- sets
- functions
- expressions
- geometric objects
- transformations of other mathematical objects
- spaces

https://en.wikipedia.org/wiki/Mathematical_object

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Measurable Space Sigma Alebra Topological Space

Mathematical objects (4)

• Mathematical objects can be very complex;

- for example, the followings are considered as mathematical objects in proof theory.
 - theorems
 - proofs
 - theories

https://en.wikipedia.org/wiki/Mathematical_object

< D > < A > < B > < B >

Structure (1)

• a structure is a set

endowed with some additional features on the set

- e.g. an operation
- relation
- metric
- topology
- Often, the *additional features* are attached or related to the set, so as to provide it with some *additional meaning* or *significance*.

https://www.localmaxradio.com/questions/what-is-a-mathematical-space

< A ▶

Structure (2)

• A partial list of possible structures are

- measures
- algebraic structures (groups, fields, etc.)
- topologies
- metric structures (geometries)
- orders
- events
- equivalence relations
- differential structures
- categories.

https://www.localmaxradio.com/questions/what-is-a-mathematical-space

< A >

Mathematical space (1)

- A mathematical space is, informally, a collection of mathematical objects under consideration.
- The universe of mathematical objects within a space are *precisely* defined entities whose rules of *interaction* come baked into the rules of the space.

Mathematical space (2)

- A space differs from a mathematical set in several important ways:
 - A mathematical set is also a collection of objects
 - but these objects are being pulled from a **space** (or **universe**) of objects where the rules and definitions have already been agreed upon

Measurable Space Sigma Alebra Topological Space

Mathematical space (3)

- A space differs from a mathematical set in several important ways:
 - A mathematical set has no internal structure,
 - whereas a **space** usually has some internal structure.

Mathematical space (4)

- having some internal structure could mean a variety of things, but typically it involves
 - *interactions* and *relationships* between elements of the **space**
 - *rules* on how to *create* and *define new* elements of the **space**

Measurable space (1)

- A measurable space is any space with a sigma-algebra which can then be equipped with a measure
 - collection of **subsets** of the **space** following certain **rules** with a way to assign sizes to those sets.

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

Measurable space (2)

Intuitively,

certain **sets** belonging to a **measurable space** can be given a size in a *consistent way*.

consistent way means that certain axioms are met:

- the empty set is given a size of zero
- if a measurable set is contained inside another one, then its size is less than or equal to the size of the containing set
- the size of a disjoint union of sets is the sum of the individual sets' sizes

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

< A >

Probability space

- A probability space is simply a measurable space equipped with a probability measure.
- A probability measure has the special property of giving the entire **space** a size of **1**.
 - this then implies that the size of any <u>disjoint union</u> of sets (the <u>sum</u> of the sizes of the sets) in the **probability space** is less than or <u>equal to</u> **1**

https://www.quora.com/What-is-a-measurable-space-and-probability-space-

intuitively-What-differences-do-they-have

AP ► < E ►

Measurable Space Sigma Alebra **Topological Space**

Outline



1 Measurable Space

- Measurable Space
- Sigma Alebra
- Topological Space



A ■

Sigma algebra (1)

- We term the structures which allow us to use measure to be sigma algebras
- the <u>only</u> requirements for sigma algebras (on a set X) are:
 - the {} and X are in the **set**.
 - if A is in the **set**, complement(A) is in the **set**.
 - for any sets E_i in the set, $\bigcup_i E_i$ is in the set (for countable *i*).

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

f5cea0cc2e7

- 4 同 6 4 日 6 4 日

Sigma algebra (2)

- The most intuitive way to think about a **sigma algebra** is that it is the kind of **structure** we can do **probability** on.
 - for example, we can assign <u>ratios</u> of <u>areas</u> and <u>length</u>, so the measure on such a set X tells something about the probability of its subsets.
 - we can find the probability of subsets A and B because we know their ratios with respect to a set X ;
 - we also know that
 - (the measure of) their complements are defined, and
 - their unions and intersections are defined,
 - so we know how to find the probability of things in this set X.

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

f5cea0cc2e7

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Sigma algebra (3)

- The sigma algebra which contains the standard topology on R (that is, *all* open sets on R) is called the **Borel Sigma Algebra**, and the elements of this set are called **Borel sets**.
- What this gives us, is the set of sets on which outer measure gives our list of dreams. That is, if we take a Borel set and we check that length follows translation, additivity, and interval length, it will always hold.

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-intuiti

f5cea0cc2e7

Sigma algebra (4)

- The set of Lebesgue measurable sets is the set of **Borel sets**, along with (union) all the sets which differ from a Borel set by a set of measure 0.
- More intuitively, it is all the sets we can normally measure, plus a bunch of stuff that <u>doesn't</u> affect our ideas of area or volume (think about the border of the circle above).

https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-

f5cea0cc2e7

- ∢ ⊒ →

4 A²
▶

Borel Sets (1-1)

- a Borel set is any set in a topological space that can be formed from open sets (or, equivalently, from closed sets) through the operations of
 - countable union,
 - countable intersection, and
 - relative complement.

https://en.wikipedia.org/wiki/Borel_set

Borel Sets (1-2)

- For a topological space X, the collection of all Borel sets on X forms a σ-algebra, known as the Borel algebra or Borel σ-algebra.
- The Borel algebra on X is the smallest σ-algebra containing all open sets (or, equivalently, all closed sets).

https://en.wikipedia.org/wiki/Borel_set

▲ □ ▶ ▲ □ ▶

Borel Sets (1-3)

- Borel sets are important in measure theory, since any measure defined on the open sets of a space, or on the closed sets of a space, must also be defined on all Borel sets of that space.
- Any measure defined on the Borel sets is called a **Borel measure**.
- Borel sets and the associated Borel hierarchy also play a fundamental role in descriptive set theory.

https://en.wikipedia.org/wiki/Borel set

Borel Sets (2)

- Borel sets are those obtained from intervals by means of the operations allowed in a σ-algebra. So we may construct them in a (transfinite) "sequence" of steps:
- ... And again and again.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

(日) (同) (三) (

Borel Sets (3-1)

- 1. Start with finite unions of closed-open intervals. These sets are completely elementary, and they form an algebra.
- 2. Adjoin countable unions and intersections of elementary sets. What you get already includes open sets and closed sets, intersections of an open set and a closed set, and so on. Thus you obtain an algebra, that is still <u>not</u> a σ -algebra.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

Borel Sets (3)

- Again, adjoin countable unions and intersections to 2. Observe that you get a strictly larger class, since a countable intersection of countable unions of intervals is <u>not</u> <u>necessarily</u> included in 2. Explicit examples of sets in 3 but not in 2 include F_σ sets, like, say, the set of *rational numbers*.
- 4. And do the same again.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

Borel Sets (4-1)

• And even after a sequence of steps we are not yet finished. Take, say, a countable union of a set constructed at step 1, a set constructed at step 2, and so on. This union may very well not have been constructed at any step yet. By axioms of σ -algebra, you should include it as well - if you want, as step ∞

https://math.stackexchange.com/questions/220248/understanding-borel-sets

Borel Sets (4-2)

- (or, technically, the first infinite ordinal, if you know what that means).
- And then continue in the same way until you reach the first uncountable ordinal. And only then will you finally obtain the generated σ -algebra.

https://math.stackexchange.com/questions/220248/understanding-borel-sets

< D > < A > < B > < B >

Measurable Space **Topological Space**

Outline



1 Measurable Space

- Measurable Space
- Sigma Alebra
- Topological Space



A ■

Measurable Space Sigma Alebra Topological Space

Topology

topology

from the Greek words tó $\pi o \varsigma$, 'place, location', and $\lambda \delta \gamma o \varsigma$, 'study'

is concerned with the properties of a geometric object

- that are *preserved* under <u>continuous deformations</u>, such as <u>stretching</u>, <u>twisting</u>, <u>crumpling</u>, and <u>bending</u>;
- that is, without closing holes, opening holes, tearing, gluing, or passing through itself.

https://en.wikipedia.org/wiki/Topology

- 4 同 6 4 日 6 4 日 6

Topological space (1)

 a topological space is, roughly speaking, a geometrical space in which closeness is defined but <u>cannot</u> <u>necessarily</u> be measured by a numeric distance.

https://en.wikipedia.org/wiki/Borel_set

- 4 同 6 4 日 6 4 日 6

Topological space (2)

- More specifically, a topological space is
- a set whose elements are called points,
- along with an additional structure called a <u>topology</u>,
 - which can be defined as
 - a set of <u>neighbourhoods</u> for each point
 - that satisfy some axioms
 - formalizing the concept of closeness.

https://en.wikipedia.org/wiki/Borel_set

Image: A = A = A

Measurable Space Sigma Alebra Topological Space

Topological space (3)

 There are several equivalent definitions of a topology, the most commonly used of which is the definition through open sets, which is <u>easier</u> than the others to manipulate.

https://en.wikipedia.org/wiki/Borel_set

< ∃ >

< A ▶

Topological space (4)

- A **topological space** is the most general type of a mathematical space that <u>allows</u> for the definition of
 - limits,
 - continuity, and
 - connectedness.
- Common types of topological spaces include
 - Euclidean spaces,
 - metric spaces and
 - manifolds.

https://en.wikipedia.org/wiki/Borel_set

Image: A = A = A

Topological space (5)

- Although very general, the concept of topological spaces is fundamental, and used in virtually every branch of modern mathematics.
- The study of **topological spaces** in their own right is called point-set topology or general topology.

https://en.wikipedia.org/wiki/Borel_set

Image: A = A = A

Open set (1)

- an open set is a generalization of an open interval in the real line.
- a metric space is a set along with a distance defined between any two points
- in a metric space,

an **open set** is a set that, along with every point P, contains all points that are sufficiently near to P

• all points whose distance to P is less than some value depending on P

https://en.wikipedia.org/wiki/Open set

Open set (2)

- More generally, an open set is
 - a member of a given collection of subsets of a given set,
 - a collection that has the property of containing
 - every union of its members
 - every finite intersection of its members
 - the empty set
 - the whole set itself

https://en.wikipedia.org/wiki/Open_set

< A ▶

Open set (2)

- A set in which such a collection is given is called a **topological space**, and the collection is called a **topology**.
- These conditions are very loose, and allow enormous flexibility in the choice of open sets.
- For example,
 - every subset can be open (the discrete topology), or
 - no subset can be open (the indiscrete topology) except
 - the space itself and
 - the empty set .

https://en.wikipedia.org/wiki/Open_set

Open set (3)

Example:

- The *circle* represents the set of points (x, y) satisfying $x^2 + y^2 = r^2$.
- The *disk* represents the set of points (x, y) satisfying $x^2 + y^2 < r^2$.
- The circle set is an open set,
- the disk set is its boundary set, and
- the union of the *circle* and *disk* sets is a closed set.

https://en.wikipedia.org/wiki/Open_set

Open set (4)

- A set is a collection of distinct objects.
- Given a set A, we say that a is an element of A if a is one of the distinct objects in A, and we write a ∈ A to denote this
- Given two sets A and B, we say that A is a subset of B if every element of A is also an element of B write A ⊆ B to denote this.

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndOpen

< D > < P > < P > < P >

Open set (5) Open Balls

- We give these definitions in general, for when one is working in ℝⁿ since they are really not all that different to define in ℝⁿ than in ℝ²
- An open ball $B_r(a)$ in \mathbb{R}^n <u>centered</u> at $a = (a_1, \dots a_n) \in \mathbb{R}^n$ with <u>radius</u> ris the set of all points $\mathbf{x} = (x_1, \dots x_n) \in \mathbb{R}^n$ such that the <u>distance</u> between x and \mathbf{a} is <u>less than</u> r
- In \mathbb{R}^2 an open ball is often called an open disk

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndVariables/digI

< /₽ > < E >

Measurable Space Sigma Alebra Topological Space

Open set (6) Interior points

- Suppose that $S \subseteq \mathbb{R}^n$.
- A point *p* ∈ S is an interior point of S if there exists an open ball B_r(*p*) ⊆ S.
- Intuitively, *p* is an interior point of S if we can squeeze an entire open ball centered at *p* within S

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndOpen

Measurable Space Sigma Alebra Topological Space

Open set (7) boundary points

- A point *p* ∈ ℝⁿ is a boundary point of S if all open balls centered at *p* contain both points in S and points not in S.
- The boundary of S is the set ∂S that consists of all of the boundary points of S.

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndOpen

Open set (8)

- (Open and Closed Sets)
- A set O ⊆ ℝⁿ is open if every point in O is an interior point.
- A set C ⊆ ℝⁿ is closed if it contains all of its boundary points.

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndVariables/digI

< 47 ►

Open set (8)

- (Open and Closed Sets)
- A set O ⊆ ℝⁿ is open if every point in O is an interior point.
- A set C ⊆ ℝⁿ is closed if it contains all of its boundary points.

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndVariables/digI

< 47 ►

Topologically distinguishable points (1)

- Intuitively, an open set provides a method to distinguish two points.
- For example, if about one of two points in a topological space, there exists an open set not containing the other (distinct) point, the two points are referred to as topologically distinguishable.
- In this manner, one may speak of whether two points, or more generally two subsets, of a topological space are "near" without concretely defining a distance.
- Therefore, topological spaces may be seen as a generalization of spaces equipped with a notion of distance, which are called metric spaces.

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndVariables/digI

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Topologically distinguishable points (2)

- In the set of all real numbers, one has the natural Euclidean metric; that is, a function which measures the distance between two real numbers: d(x, y) = |x y|.
- Therefore, given a real number x, one can speak of the set of all points close to that real number; that is, within ε of x.
- In essence, points within ϵ of x approximate x to an accuracy of degree $\epsilon.$
- Note that $\epsilon>0$ always but as ϵ becomes smaller and smaller, one obtains points that approximate x to a higher and higher degree of accuracy.
- For example, if x = 0 and $\varepsilon = 1$, the points within ε of x are precisely the points of the interval (-1, 1); that is, the set of all real numbers between -1 and 1.
- However, with $\varepsilon = 0.5$, the points within ε of x are precisely the points of (-0.5, 0.5).

Topologically distinguishable points (3)

- The previous discussion shows, for the case x = 0, that one may approximate x to higher and higher degrees of accuracy by defining ε to be smaller and smaller.
- In particular, sets of the form $(-\epsilon, \epsilon)$ give us a lot of information about points close to x = 0.
- Thus, rather than speaking of a concrete Euclidean metric, one may use sets to describe points close to x.
- This innovative idea has far-reaching consequences; in particular, by defining different collections of sets containing 0 (distinct from the sets $(-\epsilon, \epsilon)$), one may find different results regarding the distance between 0 and other real numbers.
- For example, if we were to define R as the only such set for "measuring distance", all points are close to 0 since there is only one possible degree of accuracy one may achieve in approximating 0: being a member of R.
- Thus we find that in some sense every real number is distance 0



Topologically distinguishable points (4)

- In general, one refers to the family of sets containing 0, used to approximate 0, as a neighborhood basis; a member of this neighborhood basis is referred to as an open set.
- In fact, one may generalize these notions to an arbitrary set (X); rather than just the real numbers.
- In this case, given a point (x) of that set, one may define a collection of sets "around" (that is, containing) x, used to approximate x.
- Of course, this collection would have to satisfy certain properties (known as axioms) for otherwise we may not have a well-defined method to measure distance.
- For example, every point in X should approximate x to some degree of accuracy.
- Thus X should be in this family. Once we begin to define "smaller" sets containing x, we tend to approximate x to a greater degree of accuracy.

Measurable Space Sigma Alebra Topological Space



• (Open and Closed Sets)

https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAndOpen

< □ > < 同 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Stochastic Process (1)

In probability theory and related fields, a **stochastic** (/stoʊ'kæstık/) or **random** process is a mathematical object usually defined as a family of **random variables**.

The word stochastic in English was originally used as an adjective with the definition "pertaining to **conjecturing**", and stemming from a Greek word meaning "to <u>aim</u> at a mark, <u>guess</u>", and the Oxford English Dictionary gives the year 1662 as its earliest occurrence.

From Ancient Greek στοχαστικός (stokhastikós), from στοχάζομαι (stokházomai, "aim at a target, guess"), from στόχος (stókhos, "an aim, a guess").

https://en.wikipedia.org/wiki/Stochastic https://en.wiktionary.org/wiki/stochastic

(日) (同) (三) (

Stochastic Process (2)

The definition of a **stochastic process** varies, but a **stochastic process** is *traditionally* defined as a collection of **random variables** indexed by some set.

The terms **random process** and **stochastic process** are considered <u>synonyms</u> and are used <u>interchangeably</u>, without the **index set** being precisely specified.

Both "collection", or "family" are used while instead of "index set", sometimes the terms "parameter set" or "parameter space" are used.

Stochastic Process (3)

The term **random function** is also used to refer to a **stochastic** or **random process**, though sometimes it is only used when the stochastic process takes <u>real values</u>.

This term is also used when the **index sets** are **mathematical spaces** other than the **real line**,

while the terms **stochastic process** and **random process** are usually used when the **index set** is interpreted as <u>time</u>,

and other terms are used such as random field when the index set is *n*-dimensional Euclidean space \mathbb{R}^n or a manifold

Stochastic Process (4)

A stochastic process can be denoted, by $\{X(t)\}_{t\in T}$, $\{X_t\}_{t\in T}$, $\{X(t)\}$, $\{X_t\}$ or simply as X or X(t), although X(t) is regarded as an abuse of function notation.

For example, X(t) or X_t are used to refer to the **random variable** with the **index** t, and not the entire **stochastic process**.

If the **index set** is $T = [0, \infty)$, then one can write, for example, $(X_t, t \ge 0)$ to denote the **stochastic process**.

Stochastic Process Definition (1)

A stochastic process is defined as a <u>collection</u> of **random variables** defined on a common **probability space** (Ω, \mathcal{F}, P) ,

- Ω is a sample space,
- \mathscr{F} is a σ -algebra,
- P is a probability measure;
- the random variables, indexed by some set T,
- all take values in the same **mathematical space** S, which must be **measurable** with respect to some σ -algebra Σ

Stochastic Process Definition (2)

In other words, for a given probability space (Ω, \mathscr{F}, P) and a measurable space (S, Σ) , a stochastic process is a collection of S-valued random variables, which can be written as:

 $\{X(t):t\in T\}.$

https://en.wikipedia.org/wiki/Stochastic process

I ≡ ▶

Stochastic Process Definition (3)

Historically, in many problems from the natural sciences a point $t \in T$ had the meaning of time, so X(t) is a **random variable** representing a value observed at time t.

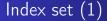
A stochastic process can also be written as $\{X(t, \omega) : t \in T\}$ to reflect that it is actually a function of two variables, $t \in T$ and $\omega \in \Omega$.

Stochastic Process Definition (4)

There are <u>other</u> ways to consider a stochastic process, with the above definition being considered the <u>traditional</u> one.

For example, a stochastic process can be interpreted or defined as a S^{T} -valued **random variable**, where S^{T} is the space of all the possible functions from the set T into the space S.

However this alternative definition as a "**function-valued random variable**" in general requires additional regularity assumptions to be **well-defined**.



The set T is called the **index set** or **parameter set** of the **stochastic process**.

Often this set is some <u>subset</u> of the <u>real line</u>, such as the natural numbers or an interval, giving the set T the interpretation of time.

Index set (2)

In addition to these sets, the index set T can be another set with a **total order** or a more general set, such as the Cartesian plane R^2 or *n*-dimensional **Euclidean space**, where an element $t \in T$ can represent a point in space.

That said, many results and theorems are only possible for **stochastic processes** with a **totally ordered index set**.



The mathematical space S of a stochastic process is called its state space.

This mathematical space can be defined using integers, real lines, *n*-dimensional Euclidean spaces, complex planes, or more abstract mathematical spaces.

The **state space** is defined using elements that reflect the <u>different values</u> that the **stochastic process** can <u>take</u>.

Sample function (1)

A sample function is a single outcome of a stochastic process, so it is formed by taking a single possible value of each random variable of the stochastic process.

More precisely, if $\{X(t, \omega) : t \in T\}$ is a **stochastic process**, then for any point $\omega \in \Omega$, the mapping $X(\cdot, \omega) : T \to S$, is called a **sample function**, a **realization**, or, particularly when T is interpreted as <u>time</u>, a **sample path** of the **stochastic process** $\{X(t, \omega) : t \in T\}$.

Sample function (2)

This means that for a fixed $\omega \in \Omega$, there exists a sample function that maps the index set T to the state space S.

Other names for a **sample function** of a **stochastic process** include **trajectory**, **path function** or **path**

Young W Lim Random Process Background

Ξ.