

Random Process Background

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Based on
Probability, Random Variables and Random Signal Principles,
P.Z. Peebles,Jr. and B. Shi

Outline

- 1 Measurable Space
 - Measurable Space
 - Sigma Alebra
 - Topological Space

- 2 Stochastic Process

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- 1 Measurable Space
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 - Sigma Alebra
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Space (1)

- A **space** consists of selected **mathematical objects** that are treated as **points**, and selected **relationships** between these **points**.
 - the nature of the **points** can vary widely:
for example, the points can be
 - elements of a set
 - functions on another space
 - subspaces of another space
 - It is the **relationships** that define the nature of the space.

[https://en.wikipedia.org/wiki/Space_\(mathematics\)](https://en.wikipedia.org/wiki/Space_(mathematics))

Space (2)

- While modern mathematics uses many types of **spaces**, such as
 - Euclidean spaces
 - linear spaces
 - topological spaces
 - Hilbert spaces
 - probability spaces
- it does not define the notion of **space** itself.

[https://en.wikipedia.org/wiki/Space_\(mathematics\)](https://en.wikipedia.org/wiki/Space_(mathematics))

Space (3)

- a **space** is
a **set** (or a **universe**) with some added **structure**
- It is not always clear
whether a given **mathematical object** should be considered
as a geometric **space**, or an algebraic **structure**
- A general definition of **structure** embraces
all common types of **space**

[https://en.wikipedia.org/wiki/Space_\(mathematics\)](https://en.wikipedia.org/wiki/Space_(mathematics))

Mathematical objects (1)

- A **mathematical object** is an **abstract concept** arising in mathematics.
- an **mathematical object** is anything that has been (or could be) **formally defined**, and with which one may do
 - **deductive reasoning**
 - **mathematical proofs**

https://en.wikipedia.org/wiki/Mathematical_object

Mathematical objects (2)

- Typically, a **mathematical object**
 - can be a **value** that can be assigned to a **variable**
 - therefore can be involved in **formulas**

https://en.wikipedia.org/wiki/Mathematical_object

Mathematical objects (3)

- Commonly encountered **mathematical objects** include
 - numbers
 - sets
 - functions
 - expressions
 - geometric objects
 - transformations of other mathematical objects
 - spaces

https://en.wikipedia.org/wiki/Mathematical_object

Mathematical objects (4)

- **Mathematical objects** can be very *complex*;
 - for example, the followings are considered as **mathematical objects** in **proof theory**.
 - theorems
 - proofs
 - theories

https://en.wikipedia.org/wiki/Mathematical_object

Structure (1)

- a **structure** is a **set** endowed with some *additional features* on the **set**
 - e.g. an *operation*
 - *relation*
 - *metric*
 - *topology*
- Often, the *additional features* are attached or related to the set, so as to provide it with some *additional meaning* or *significance*.

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Structure (2)

- A partial list of possible **structures** are
 - measures
 - algebraic structures (groups, fields, etc.)
 - topologies
 - metric structures (geometries)
 - orders
 - events
 - equivalence relations
 - differential structures
 - categories.

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Mathematical space (1)

- A **mathematical space** is, informally, a **collection** of **mathematical objects** under consideration.
- The **universe** of **mathematical objects** within a **space** are *precisely defined entities* whose **rules** of *interaction* come baked into the **rules** of the **space**.

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Mathematical space (2)

- A **space** differs from a **mathematical set** in several important ways:
 - A **mathematical set** is also a **collection** of **objects**
 - but these **objects** are being pulled from a **space** (or **universe**) of **objects** where the **rules** and **definitions** have already been agreed upon

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Mathematical space (3)

- A **space** differs from a **mathematical set** in several important ways:
 - A **mathematical set** has no **internal structure**,
 - whereas a **space** usually has some **internal structure**.

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Mathematical space (4)

- having some **internal structure** could mean a variety of things, but typically it involves
 - *interactions* and *relationships* between **elements** of the **space**
 - *rules* on how to *create* and *define* **new elements** of the **space**

<https://www.localmaxradio.com/questions/what-is-a-mathematical-space>

Measurable space (1)

- A **measurable space** is any **space** with a **sigma-algebra** which can then be equipped with a **measure**
 - collection of **subsets** of the **space** following certain **rules** with a way to assign **sizes** to those sets.

<https://www.quora.com/What-is-a-measurable-space-and-probability-space-intuitively-What-differences-do-they-have>

Measurable space (2)

- Intuitively, certain **sets** belonging to a **measurable space** can be given a **size** in a *consistent way*.

consistent way means that certain **axioms** are met:

- the **empty set** is given a **size** of zero
- if a measurable set is **contained** inside another one, then its **size** is **less than** or **equal to** the size of the **containing set**
- the size of a **disjoint union** of sets is the **sum** of the individual sets' **sizes**

<https://www.quora.com/What-is-a-measurable-space-and-probability-space-intuitively-What-differences-do-they-have>

Probability space

- A **probability space** is simply a **measurable space** equipped with a **probability measure**.
- A **probability measure** has the special property of giving the entire space a size of **1**.
 - this then implies that the **size** of any disjoint union of sets (the sum of the **sizes** of the sets) in the **probability space** is less than or equal to 1

<https://www.quora.com/What-is-a-measurable-space-and-probability-space-intuitively-What-differences-do-they-have>

Outline

- 1 Measurable Space
 - Measurable Space
 - **Sigma Alebra**
 - Topological Space

- 2 Stochastic Process

Sigma algebra (1)

- We term the **structures** which allow us to use **measure** to be **sigma algebras**
- the only requirements for **sigma algebras** (on a **set** X) are:
 - the $\{\}$ and X are in the **set**.
 - if A is in the **set**, *complement*(A) is in the **set**.
 - for any **sets** E_i in the set,
 $\bigcup_i E_i$ is in the **set** (for countable i).

<https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-f5cea0cc2e7>

Sigma algebra (2)

- The most intuitive way to think about a **sigma algebra** is that it is the kind of **structure** we can do **probability** on.
 - for example, we can assign ratios of areas and length, so the **measure** on such a **set** X tells something about the **probability** of its **subsets**.
 - we can find the **probability** of **subsets** A and B because we know their ratios with respect to a **set** X ;
 - we also know that
 - (the measure of) their **complements** are defined, and
 - their **unions** and **intersections** are defined,
 - so we know how to find the **probability** of things in this set X .

<https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-f5cea0cc2e7>

Sigma algebra (3)

- The **sigma algebra** which contains the **standard topology** on \mathbb{R} (that is, *all open sets* on \mathbb{R}) is called the **Borel Sigma Algebra**, and the elements of this **set** are called **Borel sets**.
- What this gives us, is the set of **sets** on which outer measure gives our list of dreams. That is, if we take a **Borel set** and we check that length follows translation, additivity, and interval length, it will always hold.

<https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-f5cea0cc2e7>

Sigma algebra (4)

- The **set** of Lebesgue measurable sets is the **set** of **Borel sets**, along with (union) all the sets which differ from a Borel set by a **set of measure 0**.
- More intuitively, it is all the sets we can normally measure, plus a bunch of stuff that doesn't affect our ideas of area or volume (think about the **border** of the circle above).

<https://medium.com/intuition/measure-theory-for-beginners-an-intuitive-approach-f5cea0cc2e7>

Borel Sets (1-1)

- a **Borel set** is any **set** in a **topological space** that can be formed from **open sets** (or, equivalently, from **closed sets**) through the operations of
 - countable union,
 - countable intersection, and
 - relative complement.

https://en.wikipedia.org/wiki/Borel_set

Borel Sets (1-2)

- For a **topological space X** , the collection of all Borel sets on X forms a σ -algebra, known as the **Borel algebra** or **Borel σ -algebra**.
- The **Borel algebra on X** is the smallest **σ -algebra** containing all open sets (or, equivalently, all closed sets).

https://en.wikipedia.org/wiki/Borel_set

Borel Sets (1-3)

- **Borel sets** are important in measure theory, since any measure defined on the open sets of a space, or on the closed sets of a space, must also be defined on all Borel sets of that space.
- Any measure defined on the Borel sets is called a **Borel measure**.
- **Borel sets** and the associated **Borel hierarchy** also play a fundamental role in descriptive set theory.

https://en.wikipedia.org/wiki/Borel_set

Borel Sets (2)

- **Borel sets** are those obtained from intervals by means of the operations allowed in a **σ -algebra**. So we may construct them in a (transfinite) "sequence" of steps:
- ... And again and again.

<https://math.stackexchange.com/questions/220248/understanding-borel-sets>

Borel Sets (3-1)

1. Start with **finite unions** of **closed-open intervals**.
These sets are completely **elementary**, and they form an **algebra**.
2. **Adjoin countable unions** and **intersections** of elementary sets.
What you get already includes **open sets** and **closed sets**, **intersections** of an open set and a closed set, and so on.
Thus you obtain an **algebra**, that is still not a **σ -algebra**.

<https://math.stackexchange.com/questions/220248/understanding-borel-sets>

Borel Sets (3)

3. Again, **adjoin countable unions** and **intersections** to 2.
Observe that you get a strictly larger class, since a **countable intersection** of **countable unions** of intervals is not necessarily included in 2.
Explicit examples of sets in 3 but not in 2 include F_σ sets, like, say, the set of *rational numbers*.
4. And do the same again.

<https://math.stackexchange.com/questions/220248/understanding-borel-sets>

Borel Sets (4-1)

- And even after a sequence of steps we are not yet finished. Take, say, a countable union of a set constructed at step 1, a set constructed at step 2, and so on. This union may very well not have been constructed at any step yet. By axioms of σ -algebra, you should include it as well - if you want, as step ∞

<https://math.stackexchange.com/questions/220248/understanding-borel-sets>

Borel Sets (4-2)

- (or, technically, the first infinite ordinal, if you know what that means).
- And then continue in the same way until you reach the first uncountable ordinal. And only then will you finally obtain the generated σ -algebra.

<https://math.stackexchange.com/questions/220248/understanding-borel-sets>

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Topology

- **topology**
from the Greek words
τόπος, 'place, location',
and λόγος, 'study'
is concerned with the **properties** of a **geometric object**
 - that are *preserved* under continuous deformations,
such as stretching, twisting, crumpling, and bending;
 - that is, without closing holes, opening holes,
tearing, gluing, or passing through itself.

<https://en.wikipedia.org/wiki/Topology>

Topological space (1)

- a **topological space** is, roughly speaking, a **geometrical space** in which **closeness** is defined but cannot necessarily be **measured** by a **numeric distance**.

https://en.wikipedia.org/wiki/Borel_set

Topological space (2)

- More specifically, a **topological space** is
- a set whose elements are called points,
- along with an additional structure called a topology,
 - which can be defined as
 - a set of neighbourhoods for each point
 - that satisfy some axioms
 - formalizing the concept of closeness.

https://en.wikipedia.org/wiki/Borel_set

Topological space (3)

- There are several equivalent **definitions** of a topology, the most commonly used of which is the **definition** through **open sets**, which is easier than the others to manipulate.

https://en.wikipedia.org/wiki/Borel_set

Topological space (4)

- A **topological space** is the most general type of a **mathematical space** that allows for the definition of
 - **limits**,
 - **continuity**, and
 - **connectedness**.
- Common types of **topological spaces** include
 - **Euclidean spaces**,
 - **metric spaces** and
 - **manifolds**.

https://en.wikipedia.org/wiki/Borel_set

Topological space (5)

- Although very general, the concept of **topological spaces** is fundamental, and used in virtually every branch of modern mathematics.
- The study of **topological spaces** in their own right is called point-set topology or general topology.

https://en.wikipedia.org/wiki/Borel_set

Open set (1)

- an **open set** is a generalization of an **open interval** in the real line.
- a **metric space** is a **set** along with a **distance** defined between any two **points**
- in a **metric space**, an **open set** is a **set** that, along with every **point** P , contains all **points** that are **sufficiently near** to P
 - all **points** whose **distance** to P is less than some value depending on P

https://en.wikipedia.org/wiki/Open_set

Open set (2)

- More generally, an **open set** is a **member** of a given **collection** of **subsets** of a given **set**, a **collection** that has the property of **containing**
 - every union of its **members**
 - every finite intersection of its members
 - the **empty set**
 - the **whole set** itself

https://en.wikipedia.org/wiki/Open_set

Open set (2)

- A **set** in which such a **collection** is given is called a **topological space**, and the **collection** is called a **topology**.
- These conditions are very loose, and allow enormous flexibility in the choice of **open sets**.
- For example,
 - every **subset** can be **open** (the discrete topology), or
 - no **subset** can be **open** (the indiscrete topology) except
 - the space itself and
 - the empty set .

https://en.wikipedia.org/wiki/Open_set

Open set (3)

Example:

- The *circle* represents the set of points (x, y) satisfying $x^2 + y^2 = r^2$.
- The *disk* represents the set of points (x, y) satisfying $x^2 + y^2 < r^2$.
- The *circle* set is an **open set**,
- the *disk* set is its **boundary set**, and
- the **union** of the *circle* and *disk* sets is a **closed set**.

https://en.wikipedia.org/wiki/Open_set

Open set (4)

- A **set** is a **collection** of distinct **objects**.
- Given a **set** A , we say that a is an **element** of A if a is one of the distinct **objects** in A , and we write $a \in A$ to denote this
- Given two **sets** A and B , we say that A is a **subset** of B if every element of A is also an element of B write $A \subseteq B$ to denote this.

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Open set (5) Open Balls

- We give these definitions in general, for when one is working in \mathbb{R}^n since they are really not all that different to define in \mathbb{R}^n than in \mathbb{R}^2
- An **open ball** $B_r(\mathbf{a})$ in \mathbb{R}^n centered at $\mathbf{a} = (a_1, \dots, a_n) \in \mathbb{R}^n$ with radius r is the set of all points $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ such that the distance between \mathbf{x} and \mathbf{a} is less than r
- In \mathbb{R}^2 an **open ball** is often called an **open disk**

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Open set (6) Interior points

- Suppose that $S \subseteq \mathbb{R}^n$.
- A point $\mathbf{p} \in S$ is an **interior point** of S if there exists an **open ball** $B_r(\mathbf{p}) \subseteq S$.
- Intuitively, \mathbf{p} is an **interior point** of S if we can *squeeze* an entire open ball centered at \mathbf{p} within S

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Open set (7) boundary points

- A point $\mathbf{p} \in \mathbb{R}^n$ is a **boundary point** of S if all **open balls** centered at \mathbf{p} contain both **points** in S and **points** not in S .
- The **boundary** of S is the **set** ∂S that consists of all of the **boundary points** of S .

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Open set (8)

- (Open and Closed Sets)
- A set $O \subseteq \mathbb{R}^n$ is **open** if every point in O is an **interior point**.
- A set $C \subseteq \mathbb{R}^n$ is **closed** if it contains all of its **boundary points**.

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Open set (8)

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<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Topologically distinguishable points (1)

- Intuitively, an open set provides a method to distinguish two points. For example, if about one of two points in a topological space, there exists an open set not containing the other (distinct) point, the two points are referred to as topologically distinguishable. In this manner, one may speak of whether two points, or more generally two subsets, of a topological space are "near" without concretely defining a distance. Therefore, topological spaces may be seen as a generalization of spaces equipped with a notion of distance, which are called metric spaces.

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>


Topologically distinguishable points (2)

- In the set of all real numbers, one has the natural Euclidean metric; that is, a function which measures the distance between two real numbers: $d(x, y) = |x - y|$. Therefore, given a real number x , one can speak of the set of all points close to that real number; that is, within ϵ of x . In essence, points within ϵ of x approximate x to an accuracy of degree ϵ . Note that $\epsilon > 0$ always but as ϵ becomes smaller and smaller, one obtains points that approximate x to a higher and higher degree of accuracy. For example, if $x = 0$ and $\epsilon = 1$, the points within ϵ of x are precisely the points of the interval $(-1, 1)$; that is, the set of all real numbers between -1 and 1 . However, with $\epsilon = 0.5$, the points within ϵ of x are precisely the points of $(-0.5, 0.5)$. Clearly, these points approximate x to a greater degree of accuracy than when $\epsilon = 1$.

Topologically distinguishable points (3)

- The previous discussion shows, for the case $x = 0$, that one may approximate x to higher and higher degrees of accuracy by defining ε to be smaller and smaller. In particular, sets of the form $(-\varepsilon, \varepsilon)$ give us a lot of information about points close to $x = 0$. Thus, rather than speaking of a concrete Euclidean metric, one may use sets to describe points close to x . This innovative idea has far-reaching consequences; in particular, by defining different collections of sets containing 0 (distinct from the sets $(-\varepsilon, \varepsilon)$), one may find different results regarding the distance between 0 and other real numbers. For example, if we were to define R as the only such set for "measuring distance", all points are close to 0 since there is only one possible degree of accuracy one may achieve in approximating 0: being a member of R . Thus, we find that in some sense, every real number is distance 0 away from 0. It

Topologically distinguishable points (4)

- In general, one refers to the family of sets containing 0, used to approximate 0, as a neighborhood basis; a member of this neighborhood basis is referred to as an open set. In fact, one may generalize these notions to an arbitrary set (X) ; rather than just the real numbers. In this case, given a point (x) of that set, one may define a collection of sets "around" (that is, containing) x , used to approximate x . Of course, this collection would have to satisfy certain properties (known as axioms) for otherwise we may not have a well-defined method to measure distance. For example, every point in X should approximate x to some degree of accuracy. Thus X should be in this family. Once we begin to define "smaller" sets containing x , we tend to approximate x to a greater degree of accuracy. Bearing this in mind, one may define the remaining axioms that the family of sets about x is required to satisfy. 

Open)

- (Open and Closed Sets)
-

<https://ximera.osu.edu/mooculus/calculusE/continuityOfFunctionsOfSeveralVariables/digInOpenAnd>

Stochastic Process (1)

In probability theory and related fields, a **stochastic** (/stou'kæstɪk/) or **random** process is a mathematical object usually defined as a family of **random variables**.

The word stochastic in English was originally used as an adjective with the definition "pertaining to **conjecturing**", and stemming from a Greek word meaning "to aim at a mark, guess", and the Oxford English Dictionary gives the year 1662 as its earliest occurrence.

From Ancient Greek στοχαστικός (stokhastikós), from στοχάζομαι (stokhá-zomai, "aim at a target, guess"), from στόχος (stókhos, "an aim, a guess").

<https://en.wikipedia.org/wiki/Stochastic>
<https://en.wiktionary.org/wiki/stochastic>

Stochastic Process (2)

The definition of a **stochastic process** varies, but a **stochastic process** is *traditionally* defined as a collection of **random variables** indexed by some set.

The terms **random process** and **stochastic process** are considered synonyms and are used interchangeably, without the **index set** being precisely specified.

Both "**collection**", or "**family**" are used while instead of "**index set**", sometimes the terms "**parameter set**" or "**parameter space**" are used.

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process (3)

The term **random function** is also used to refer to a **stochastic** or **random process**, though sometimes it is only used when the stochastic process takes real values.

This term is also used when the **index sets** are **mathematical spaces** other than the **real line**,

while the terms **stochastic process** and **random process** are usually used when the **index set** is interpreted as time,

and other terms are used such as **random field** when the **index set** is n -dimensional **Euclidean space** \mathbb{R}^n or a manifold

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process (4)

A **stochastic process** can be denoted, by $\{X(t)\}_{t \in T}$, $\{X_t\}_{t \in T}$, $\{X(t)\}$, $\{X_t\}$ or simply as X or $X(t)$, although $X(t)$ is regarded as an abuse of function notation.

For example, $X(t)$ or X_t are used to refer to the **random variable** with the **index** t , and not the entire **stochastic process**.

If the **index set** is $T = [0, \infty)$, then one can write, for example, $(X_t, t \geq 0)$ to denote the **stochastic process**.

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process Definition (1)

A **stochastic process** is defined as a collection of **random variables** defined on a common **probability space** (Ω, \mathcal{F}, P) ,

- Ω is a **sample space**,
- \mathcal{F} is a σ -**algebra**,
- P is a **probability measure**;
- the **random variables**, indexed by some set T ,
- all take values in the same **mathematical space** S , which must be **measurable** with respect to some σ -algebra Σ

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process Definition (2)

In other words, for a given **probability space** (Ω, \mathcal{F}, P) and a **measurable space** (S, Σ) , a **stochastic process** is a **collection** of S -valued **random variables**, which can be written as:

$$\{X(t) : t \in T\}.$$

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process Definition (3)

Historically, in many problems from the natural sciences a point $t \in T$ had the meaning of time, so $X(t)$ is a **random variable** representing a value observed at time t .

A **stochastic process** can also be written as $\{X(t, \omega) : t \in T\}$ to reflect that it is actually a function of two variables, $t \in T$ and $\omega \in \Omega$.

https://en.wikipedia.org/wiki/Stochastic_process

Stochastic Process Definition (4)

There are other ways to consider a stochastic process, with the above definition being considered the traditional one.

For example, a stochastic process can be interpreted or defined as a S^T -valued **random variable**, where S^T is the space of all the possible functions from the set T into the space S .

However this alternative definition as a "**function-valued random variable**" in general requires additional regularity assumptions to be **well-defined**.

https://en.wikipedia.org/wiki/Stochastic_process

Index set (1)

The set T is called the **index set** or **parameter set** of the **stochastic process**.

Often this set is some subset of the real line, such as the natural numbers or an interval, giving the set T the interpretation of time.

https://en.wikipedia.org/wiki/Stochastic_process

Index set (2)

In addition to these sets, the index set T can be another set with a **total order** or a more general set, such as the Cartesian plane R^2 or n -dimensional **Euclidean space**, where an element $t \in T$ can represent a point in space.

That said, many results and theorems are only possible for **stochastic processes** with a **totally ordered index set**.

https://en.wikipedia.org/wiki/Stochastic_process

State space

The **mathematical space** S of a **stochastic process** is called its **state space**.

This mathematical space can be defined using integers, real lines, n -dimensional Euclidean spaces, complex planes, or more abstract mathematical spaces.

The **state space** is defined using elements that reflect the different values that the **stochastic process** can take.

https://en.wikipedia.org/wiki/Stochastic_process

Sample function (1)

A **sample function** is a single outcome of a **stochastic process**, so it is formed by taking a single possible value of each **random variable** of the **stochastic process**.

More precisely, if $\{X(t, \omega) : t \in T\}$ is a **stochastic process**, then for any point $\omega \in \Omega$, the mapping $X(\cdot, \omega) : T \rightarrow S$, is called a **sample function**, a **realization**, or, particularly when T is interpreted as time, a **sample path** of the **stochastic process** $\{X(t, \omega) : t \in T\}$.

https://en.wikipedia.org/wiki/Stochastic_process

Sample function (2)

This means that for a fixed $\omega \in \Omega$,
there exists a **sample function**
that maps the **index set** T to the **state space** S .

Other names for a **sample function** of a **stochastic process**
include **trajectory**, **path function** or **path**

https://en.wikipedia.org/wiki/Stochastic_process

