

Capacitor and Inductor

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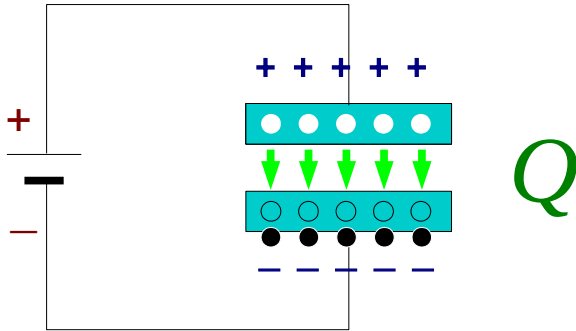
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Energy Storage

Final



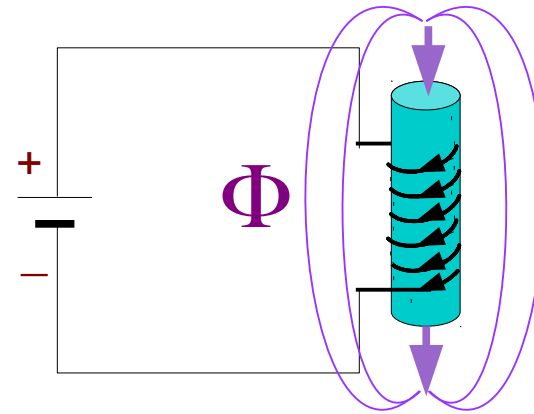
energy stored in **electric** field

potential energy of
accumulated electrons $f(v_c)$

$$Q = CV$$

$$W = \frac{1}{2} CV^2$$

Final



energy stored in **magnetic** field

kinetic energy of
moving electrons $f(i_L)$

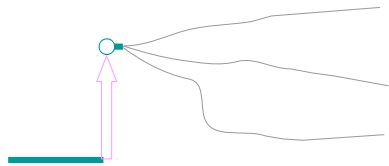
$$N\Phi = LI \quad \Phi = BA$$

$$W = \frac{1}{2} LI^2$$

Newton's First Law of Motion

tendency to try
to maintain **voltage**
at a constant level

a capacitor *resists*
changes in **voltage** drop v_c



~~i_C~~ ~~v_C~~



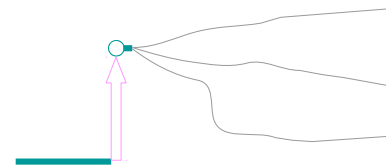
i_C v_C

potential energy

$f(v_c)$

tendency to try
to maintain **current**
at a constant level

an inductor *resists*
changes in **current** flow i_L



~~i_L~~ ~~v_L~~



i_L v_L

kinetic energy

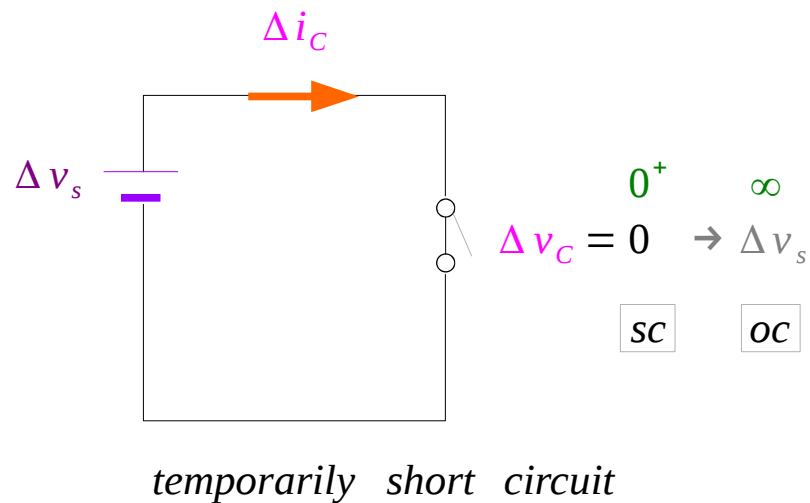
$f(i_L)$

Inertia

when v_c is increased
the capacitor *resists* the increase

by drawing current i_c
from the source of the voltage change

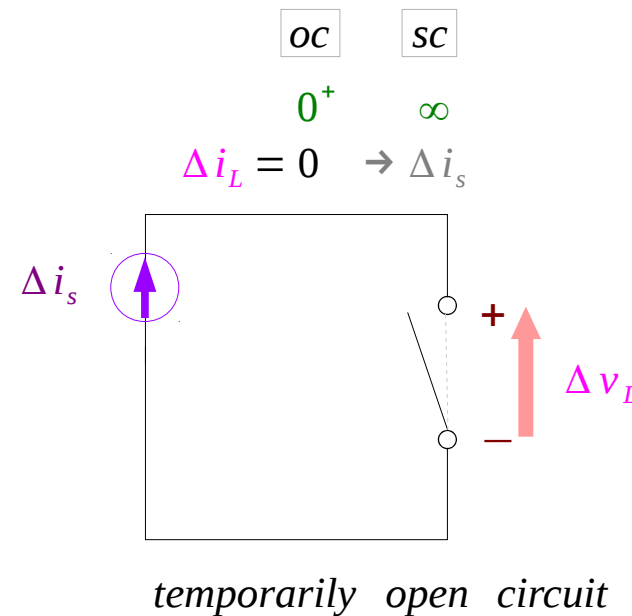
in opposition to the change



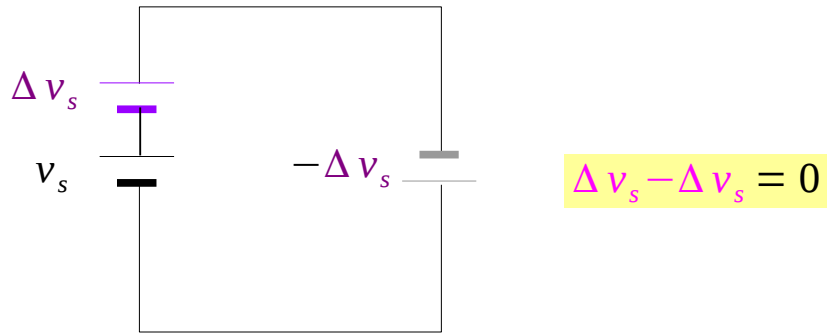
when i_L is increased
the inductor *resists* the increase

by dropping voltage v_L
from the source of the current change

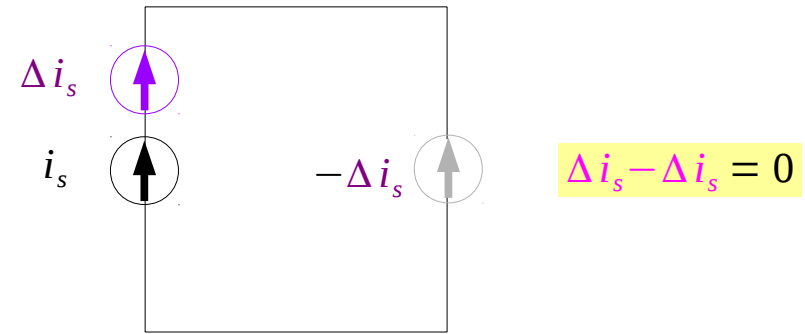
in opposition to the change



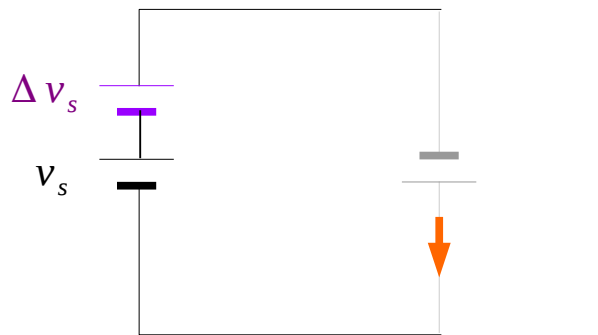
Back voltage drop and current



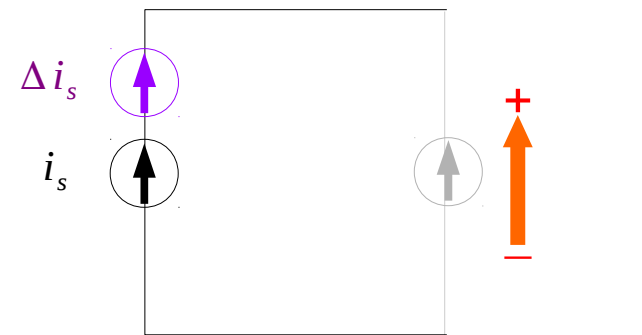
back voltage drop $-\Delta v_s$



back current $-\Delta i_s$



opposing current Δi_c



opposing emf Δv_L

Resisting changes

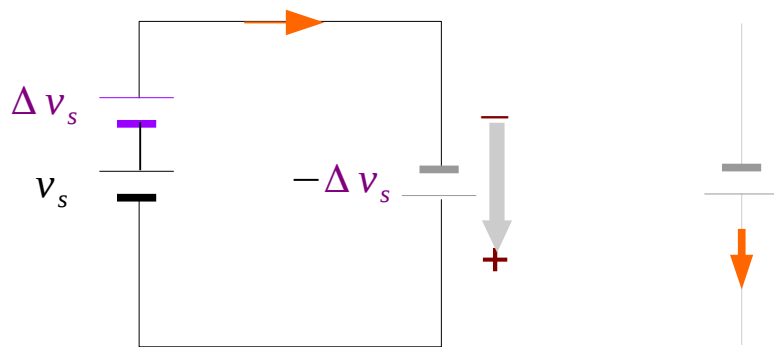
resists the change of **voltage**

increasing $v_c =$

increasing electric field :

opposing **current** →
back voltage drop

acting as reducing the voltage drop :
resists the change of voltage



tries to cancel Δv_s

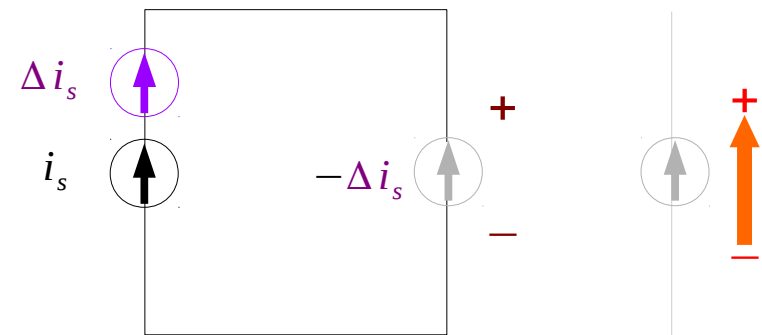
resists the change of **current**

increasing $i_L =$

increasing magnetic field :

opposing **emf** →
back current

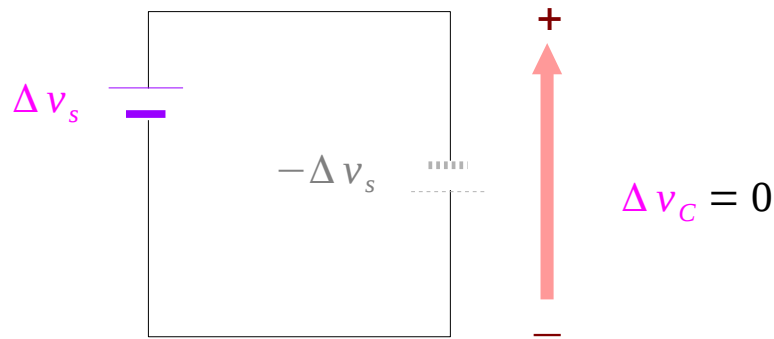
acting as reducing the current :
resists the change of current



tries to cancel Δi_s

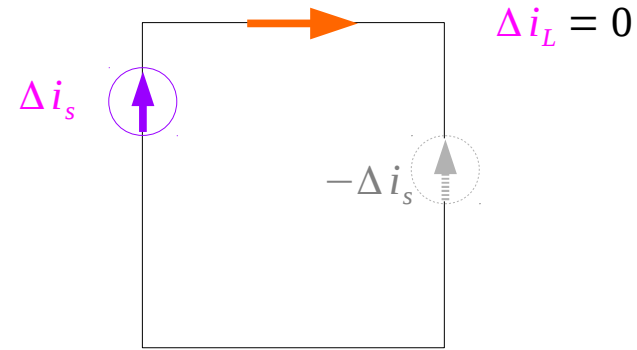
Opposition to the change

Δv_s change at $t = 0$



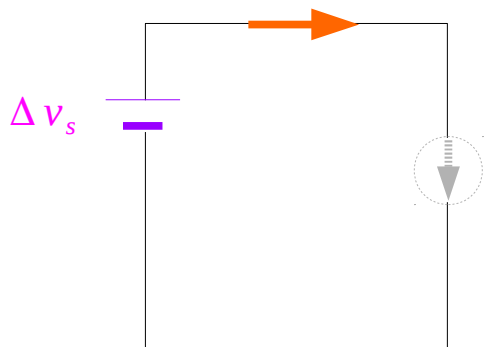
temporarily short circuit

Δi_s change at $t = 0$

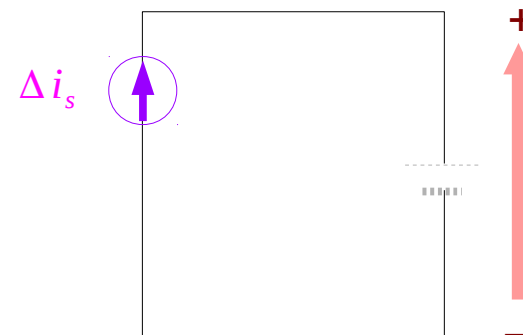


temporarily open circuit

by drawing current Δi_C

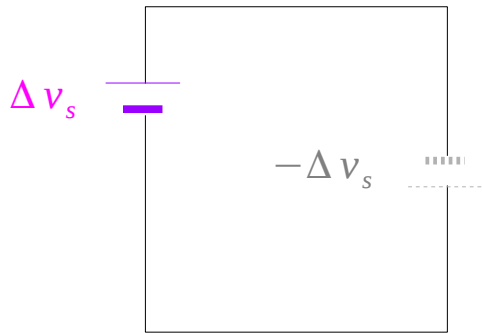


by inducing voltage Δv_L

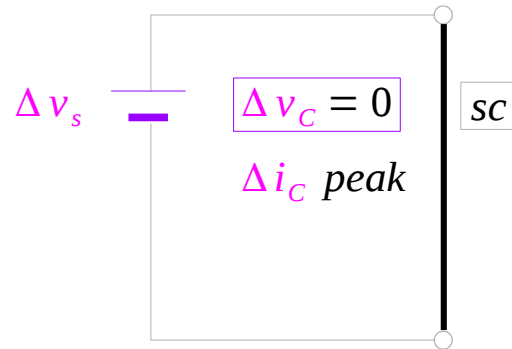


Opposition to the change

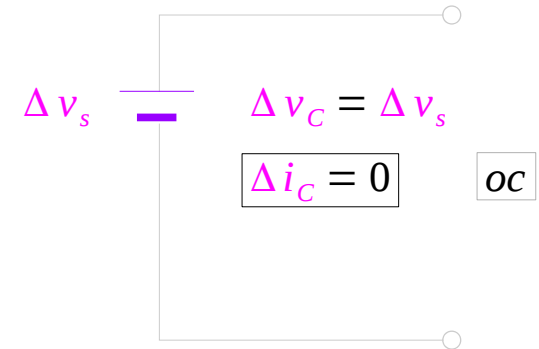
Δv_s change at $t = 0$



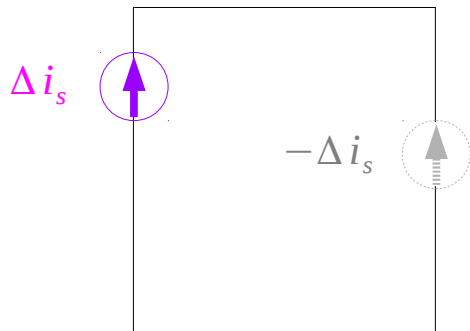
initial $t = 0$



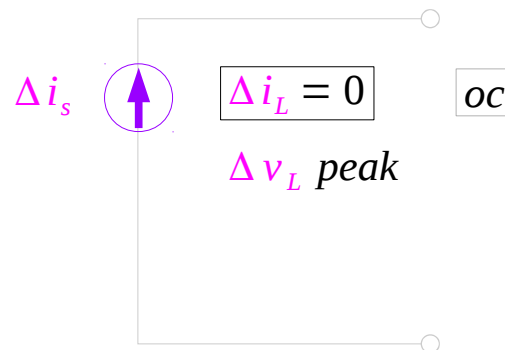
final $t = \infty$



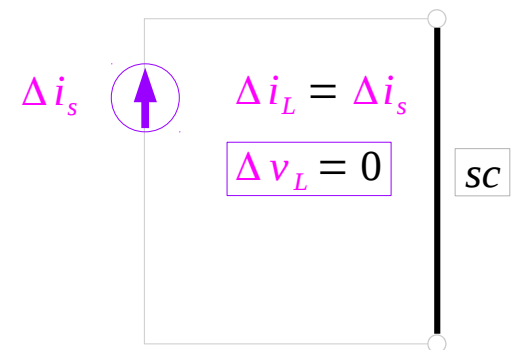
Δi_s change at $t = 0$



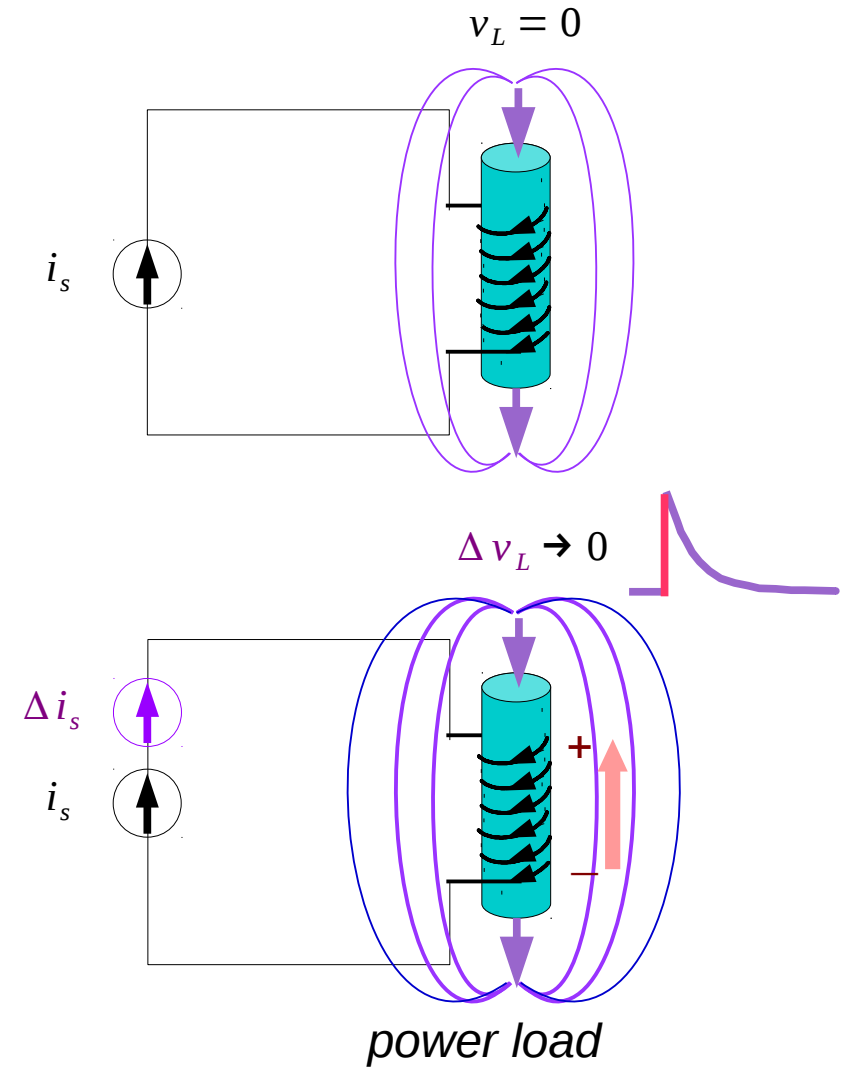
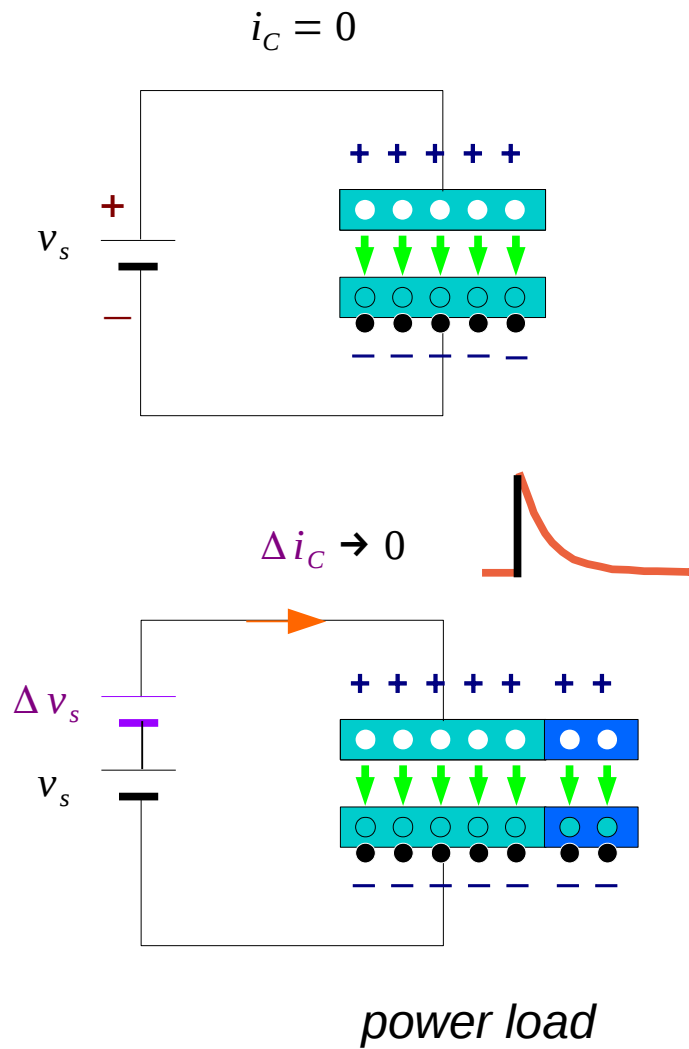
initial $t = 0$



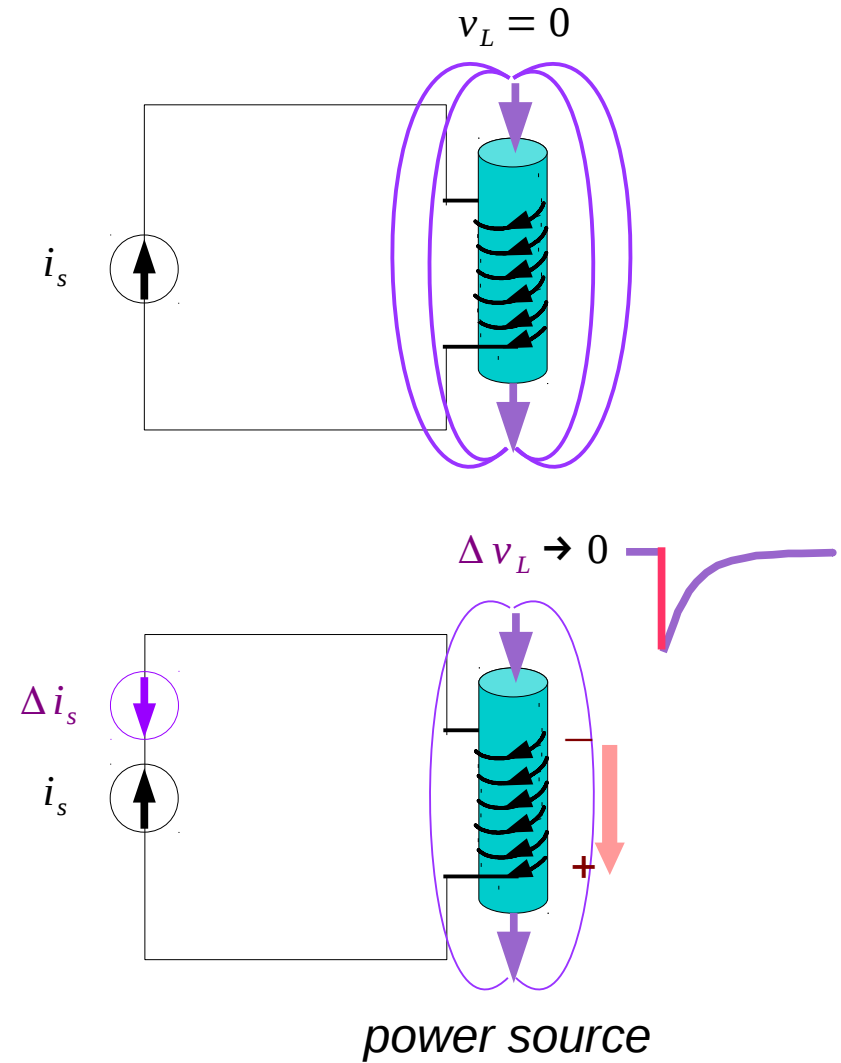
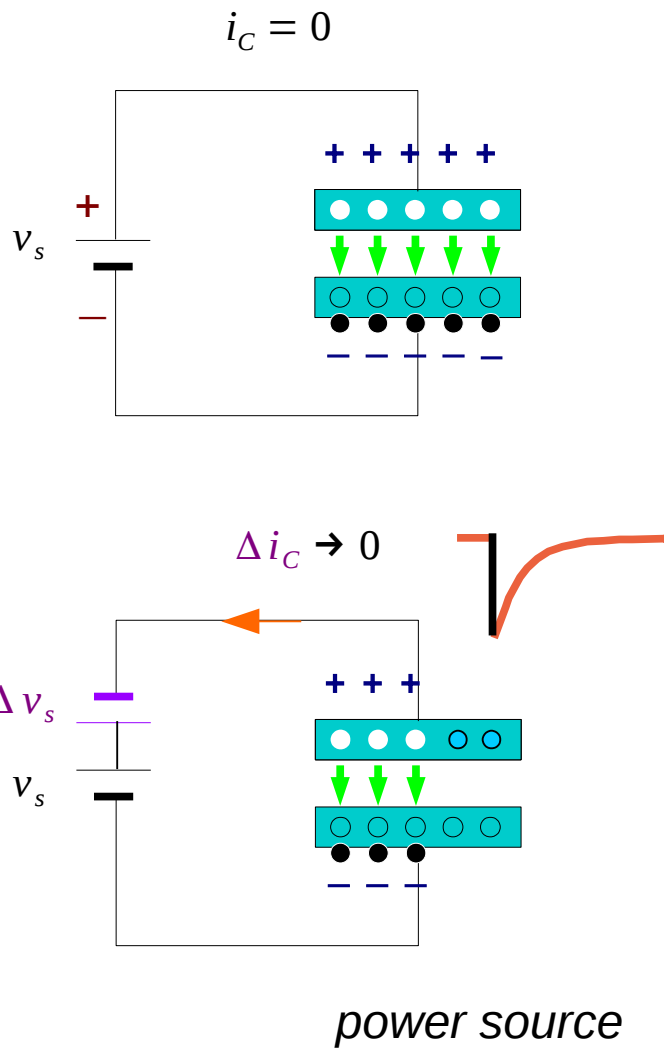
final $t = \infty$



Charging



Discharging

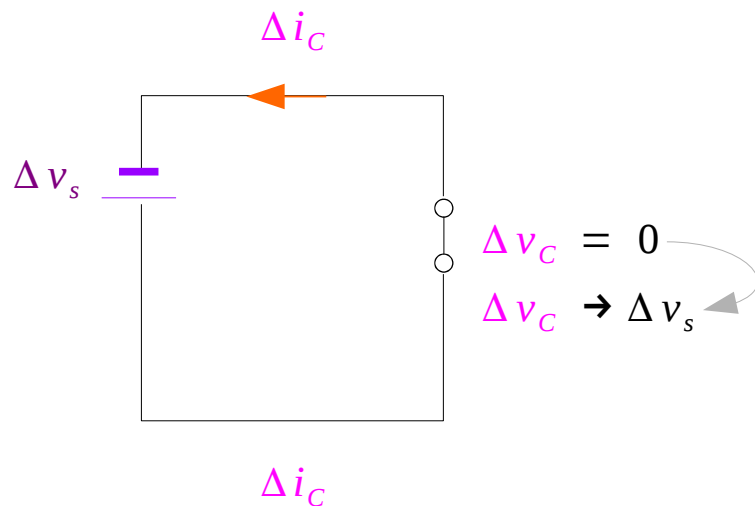


Dissipating Energy

when v_c is decreased
the capacitor resists the decrease

by supplying current i_c
to the source of the voltage change

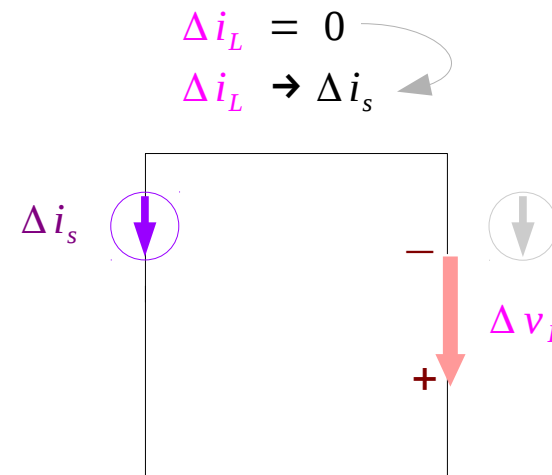
in opposition to the change



when i_L is decreased
the inductor resists the decrease

by producing voltage v_L
to the source of the current change

in opposition to the change



To store more energy

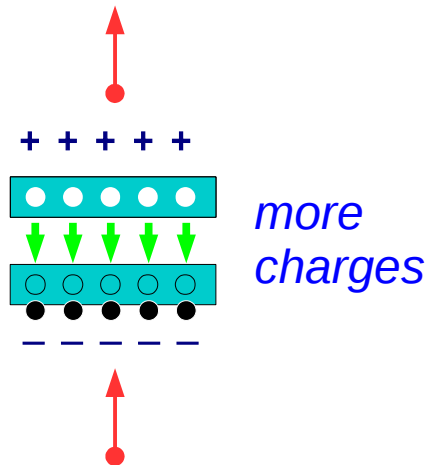
- *static nature*
- *a function of V*

to store more energy

V_c must be increased \rightarrow

*increasing charges on both sides
produces electron movement :
a way of resisting change of V*

$$Q = C \cdot V$$



- *dynamic nature*
- *a function of I*

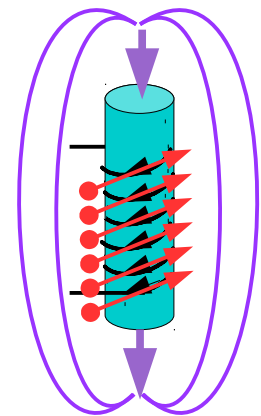
to store more energy

i_L must be increased \rightarrow

*increasing magnetic flux induces emf to
prohibit electron movement :
a way of resisting change of I*

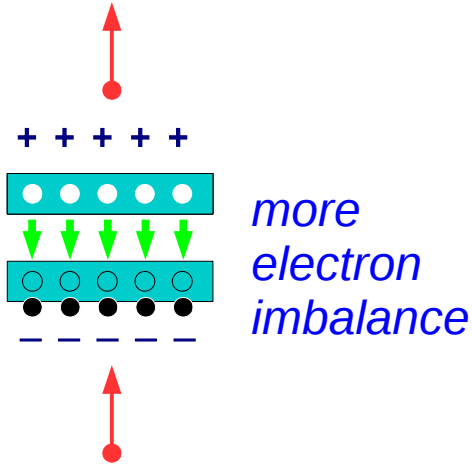
$$\Phi = L \cdot I$$

*more
magnetic flux*



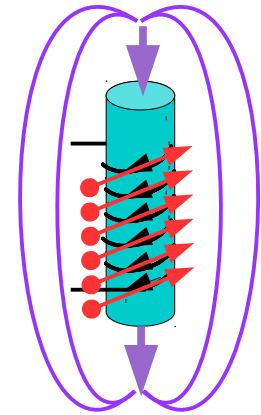
Fast Change

$$Q = C \cdot V$$



$$\Phi = L \cdot I$$

more moving electrons



fast change Δv \Rightarrow fast change Δq

fast change Δi \Rightarrow fast change $\Delta \phi$

large $\frac{\Delta v}{\Delta t}$ \Rightarrow large $\frac{\Delta q}{\Delta t} \propto i$

large $\frac{\Delta i}{\Delta t}$ \Rightarrow large $\frac{\Delta \phi}{\Delta t} \propto e$

Ohm's Law

whenever **voltage** v_C changes
there is a flowing current i_C

the magnitude of the current is
proportional to the rate of change

$$i_C = C \cdot \frac{dv_C}{dt}$$

whenever **current** i_L changes
there is an induced voltage v_L

the magnitude of the voltage is
proportional to the rate of change

$$v_L = L \cdot \frac{di_L}{dt}$$

Stored Energy

resists to the change of **voltage**

to increase v_c ,
energy should be
transferred to capacitors
by the flowing current i_c

The stored energy is a function of **voltage**

$$Q = C \cdot V$$

$$\frac{dq}{dt} = C \cdot \frac{dv}{dt}$$

$$i_c = C \cdot \frac{dv_c}{dt}$$

resists to the change of **current**

to increase i_L ,
energy should be
transferred to the inductors
by the induced voltage v_L

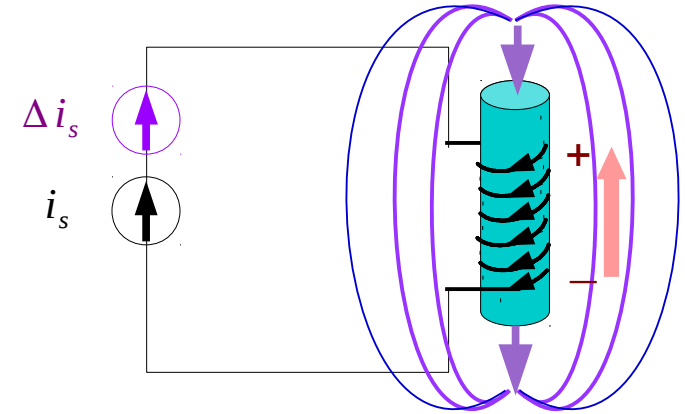
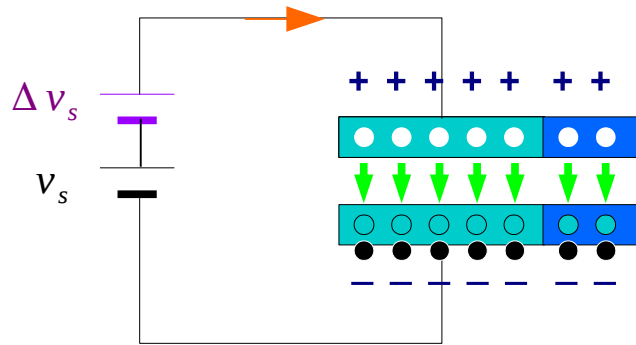
The stored energy is a function of **current**

$$\Phi = L \cdot I$$

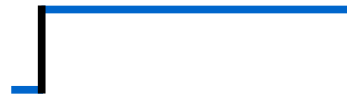
$$\frac{d\phi}{dt} = L \cdot \frac{di}{dt}$$

$$v_L = L \cdot \frac{di_L}{dt}$$

Short term effects



v_s



the short term effect: a way of resisting

$i_C \rightarrow 0$

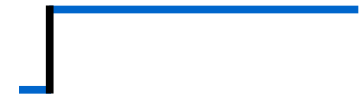


the long term result: voltage change

$v_C \rightarrow v + \Delta v$



i_s



the short term effect: a way of resisting

$v_L \rightarrow 0$

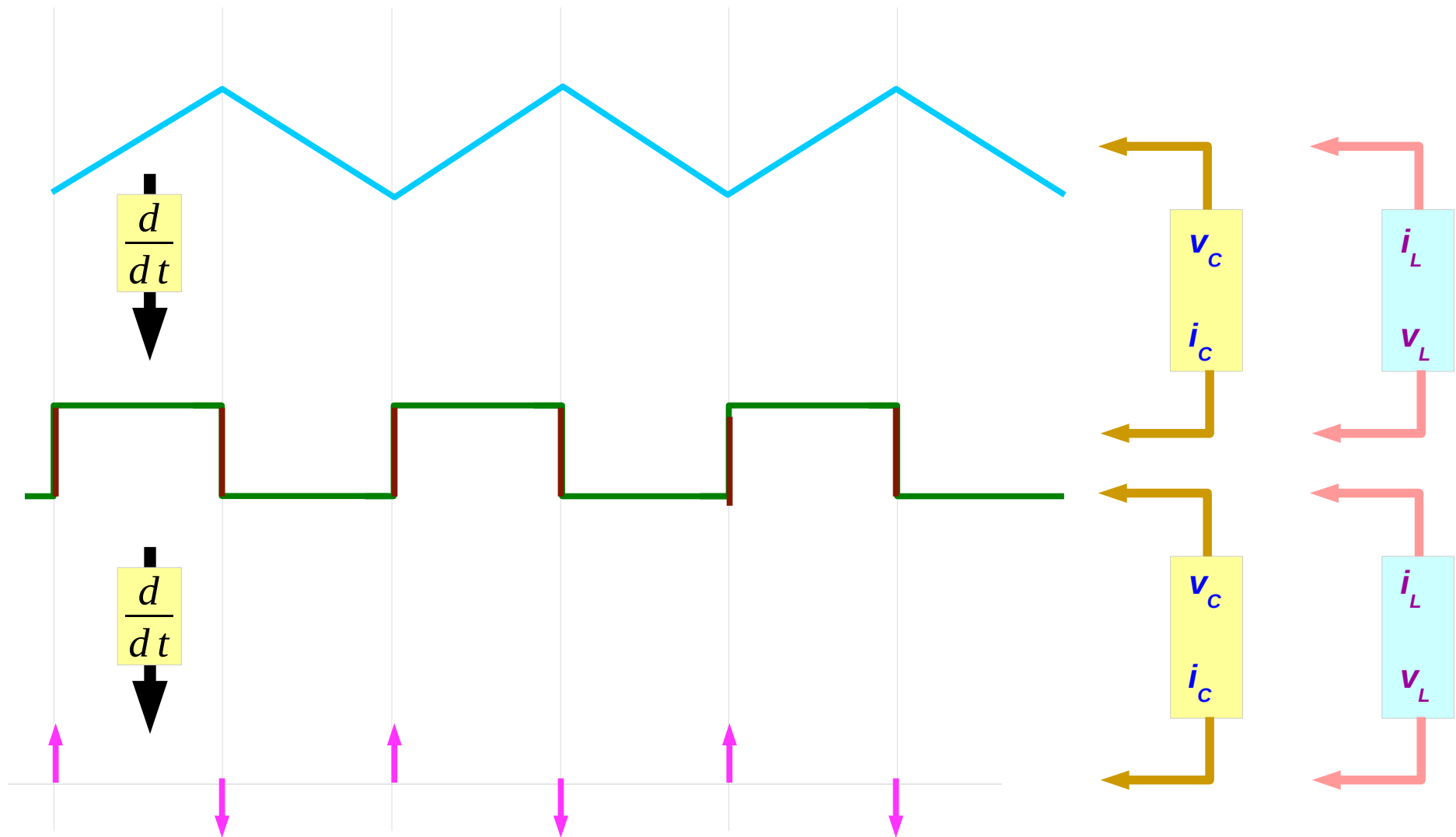


the long term result: current change

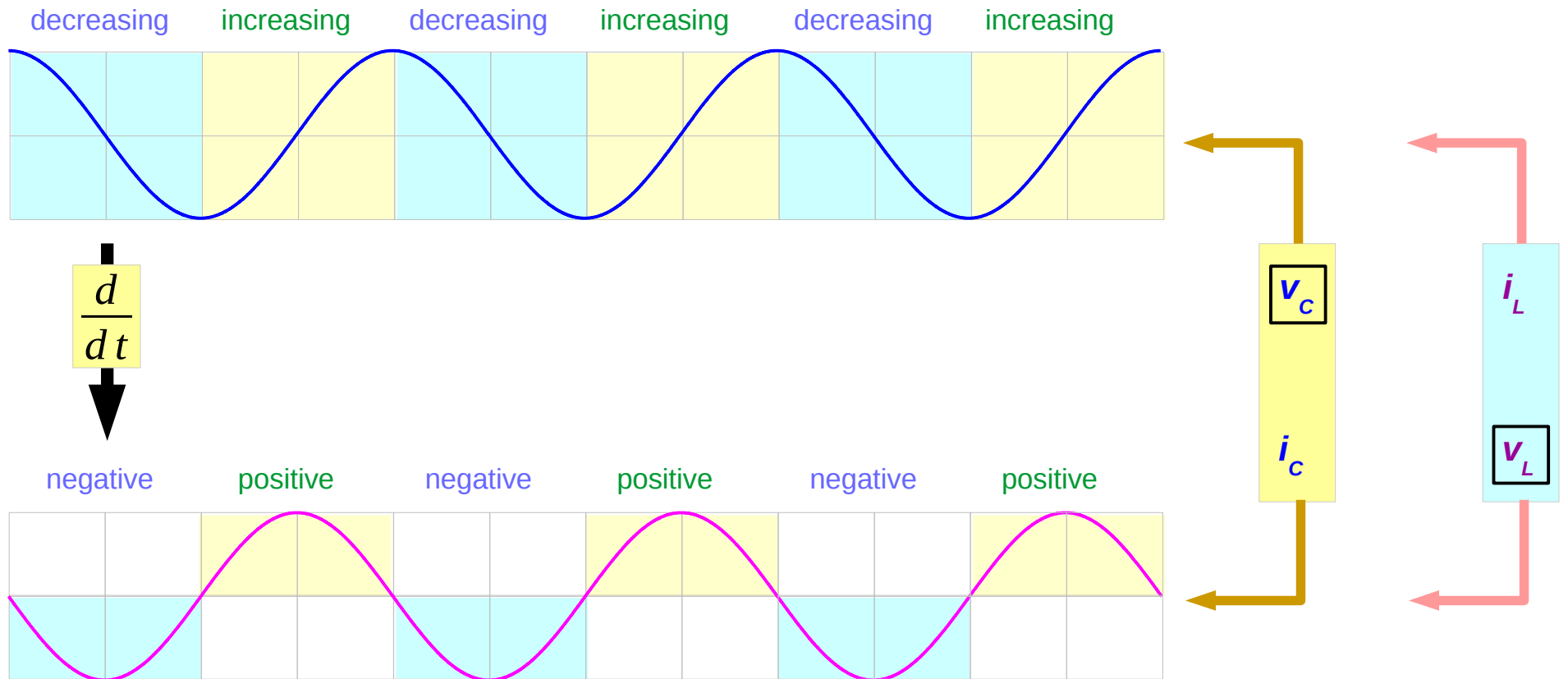
$i_L \rightarrow i + \Delta i$



Some (i,v) signal pair examples

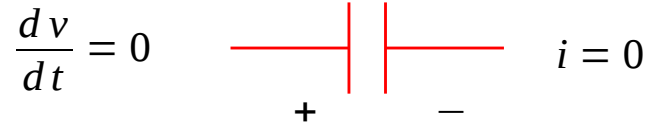


Everchanging signal pairs

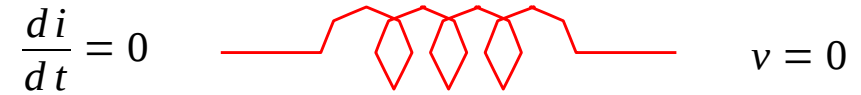


Current & Voltage Changes

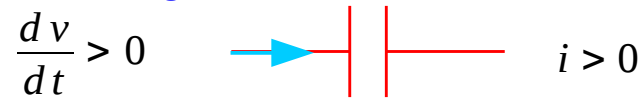
constant v



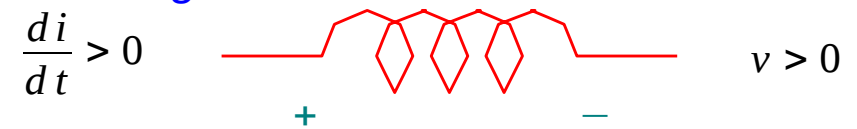
constant i



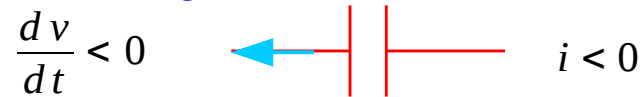
increasing v



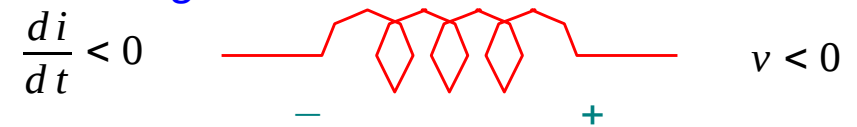
increasing i



decreasing v



increasing i



Sinusoidal voltage and current

$$i_C = C \cdot \frac{dv_C}{dt}$$

$$\begin{aligned}v_C &= A \cos(\omega t) \\i_C &= -\omega C A \sin(\omega t) \\&= \omega C A \cos(\omega t + \pi/2)\end{aligned}$$

$$\frac{v_C}{i_C} = \frac{1}{\omega C} \frac{\cos(\omega t)}{\cos(\omega t + \pi/2)}$$

$$\begin{aligned}V_C &= A \angle 0 \\I_C &= \omega C A \angle \pi/2\end{aligned}$$

$$\begin{aligned}Z_C = \frac{V_C}{I_C} &= \frac{1}{\omega C} \angle -\pi/2 \\&= \frac{-j}{\omega C} = \frac{1}{j\omega C}\end{aligned}$$

$$v_L = L \cdot \frac{di_L}{dt}$$

$$\begin{aligned}i_L &= A \sin(\omega t) \\&= A \cos(\omega t - \pi/2) \\v_L &= \omega L A \cos(\omega t)\end{aligned}$$

$$\frac{v_L}{i_L} = \omega L \frac{\cos(\omega t)}{\cos(\omega t - \pi/2)}$$

$$\begin{aligned}I_L &= A \angle -\pi/2 \\V_L &= \omega L A \angle 0\end{aligned}$$

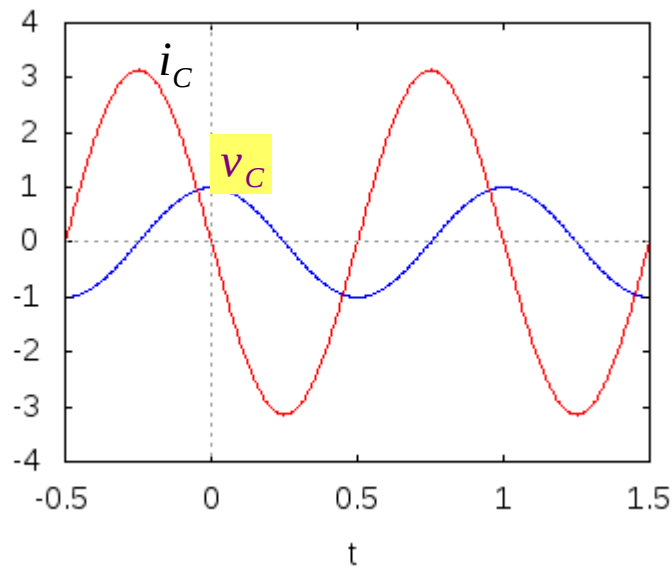
$$\begin{aligned}Z_L = \frac{V_L}{I_L} &= \omega L \angle +\pi/2 \\&= j\omega L\end{aligned}$$

Leading and Lagging Current

$$i_C = C \cdot \frac{dv_C}{dt}$$

$$\begin{aligned}v_C &= \cos(2\pi t) \\i_C &= -\pi \sin(2\pi t) \\&= \pi \cos(2\pi t + \pi/2)\end{aligned}$$

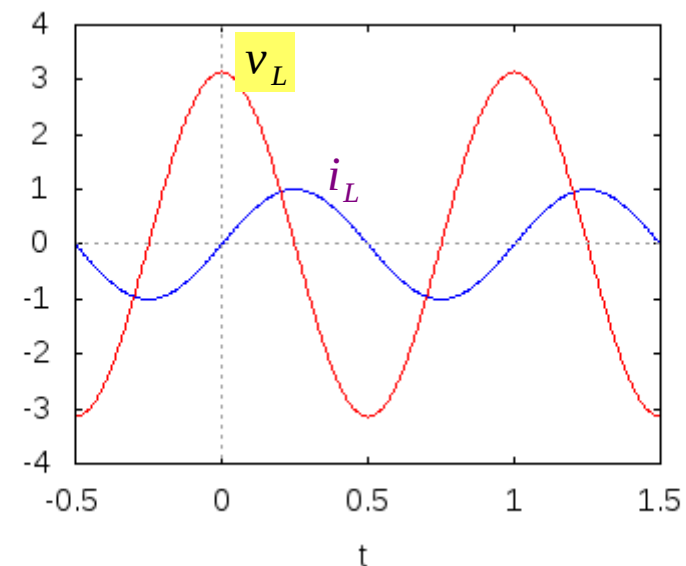
$$C=0.5$$



$$v_L = L \cdot \frac{di_L}{dt}$$

$$\begin{aligned}i_L &= \sin(2\pi t) \\&= \cos(2\pi t - \pi/2) \\v_L &= \pi \cos(2\pi t)\end{aligned}$$

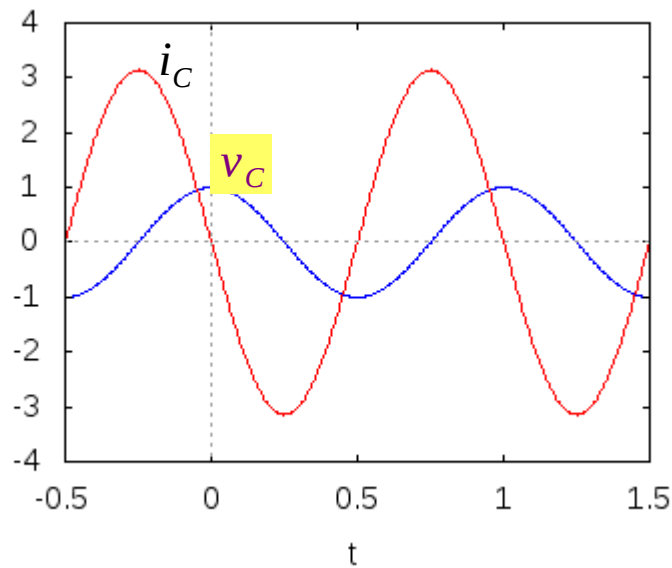
$$L=0.5$$



Ohm's Law

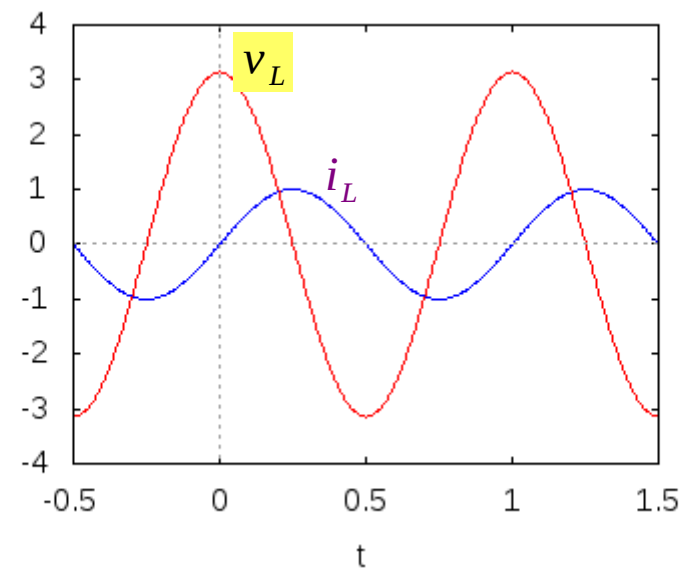
$$\begin{aligned}V_C &= A \angle 0 \\ I_C &= \omega C A \angle \pi/2\end{aligned}$$

$$\begin{aligned}Z_C &= \frac{V_C}{I_C} = \frac{1}{\omega C} \angle -\pi/2 \\ &= \frac{-j}{\omega C} = \frac{1}{j\omega C}\end{aligned}$$



$$\begin{aligned}I_L &= A \angle -\pi/2 \\ V_L &= \omega L A \angle 0\end{aligned}$$

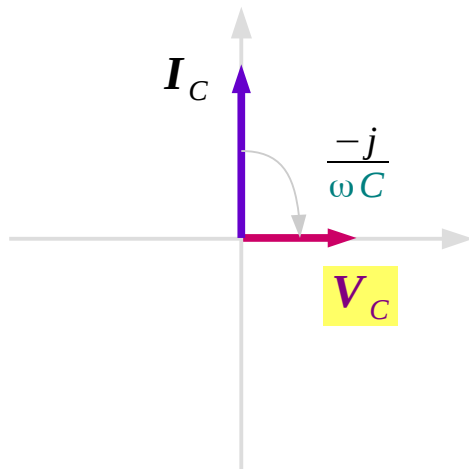
$$\begin{aligned}Z_L &= \frac{V_L}{I_L} = \omega L \angle +\pi/2 \\ &= j\omega L\end{aligned}$$



Phasor and Ohm's Law

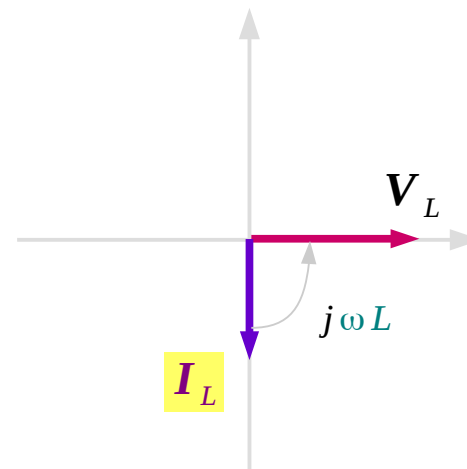
$$\begin{aligned}V_C &= A \angle 0 \\ I_C &= \omega C A \angle \pi/2\end{aligned}$$

$$\begin{aligned}Z_C &= \frac{V_C}{I_C} = \frac{1}{\omega C} \angle -\pi/2 \\ &= \frac{-j}{\omega C} = \frac{1}{j\omega C}\end{aligned}$$



$$\begin{aligned}I_L &= A \angle -\pi/2 \\ V_L &= \omega L A \angle 0\end{aligned}$$

$$\begin{aligned}Z_L &= \frac{V_L}{I_L} = \omega L \angle +\pi/2 \\ &= j\omega L\end{aligned}$$



Phase Lags and Leads

References

[1] <http://en.wikipedia.org/>

[2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003