

ODE Background: Complex Variables (4A)

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Complex Numbers

Complex Numbers

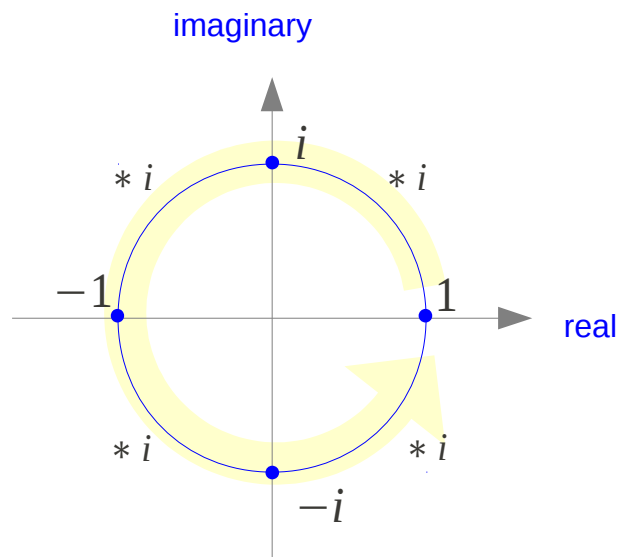
$$i = \sqrt{-1}$$
$$i^2 = -1$$

$$i^3 = -i$$

$$i^2 \cdot i = -i$$

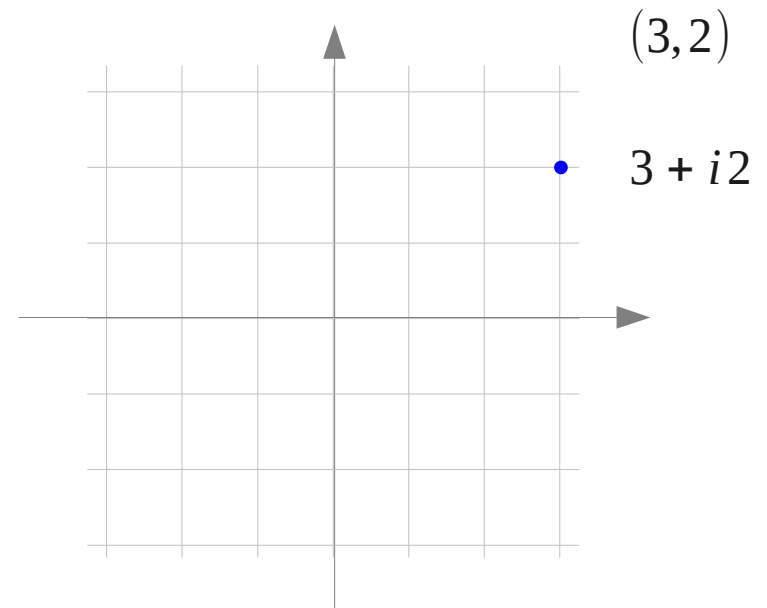
$$i^4 = +1$$

$$i^2 \cdot i^2 = +1$$

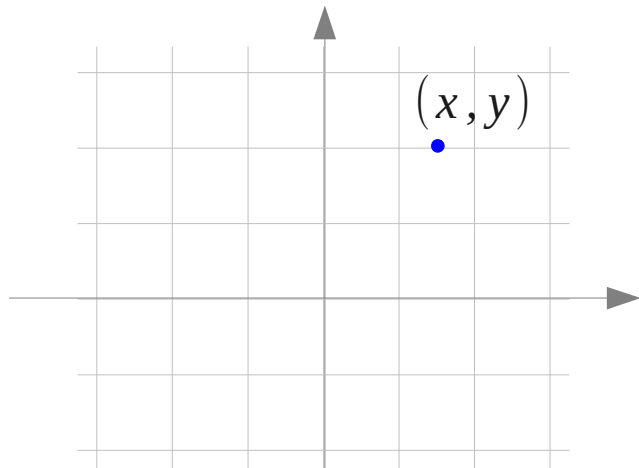


$(3,2)$ **two** real numbers
2-d coordinate

$3 + i2$ **one** complex number
with real part of 3
and imaginary part of 2



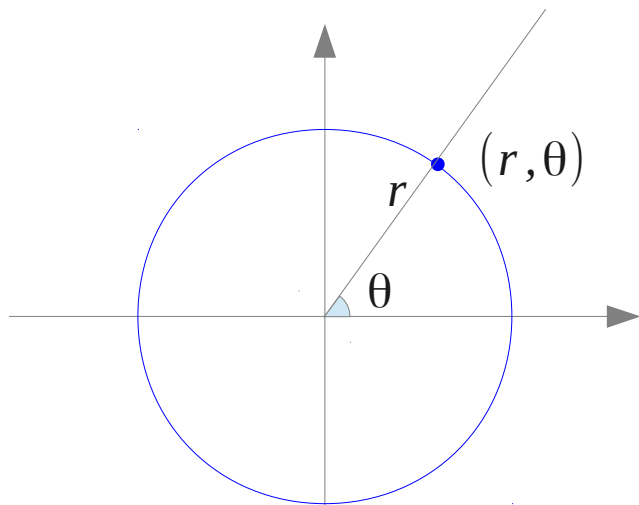
Coordinate Systems



(a) Cartesian Coordinate System

$$x = r \cos \theta$$

$$y = r \sin \theta$$

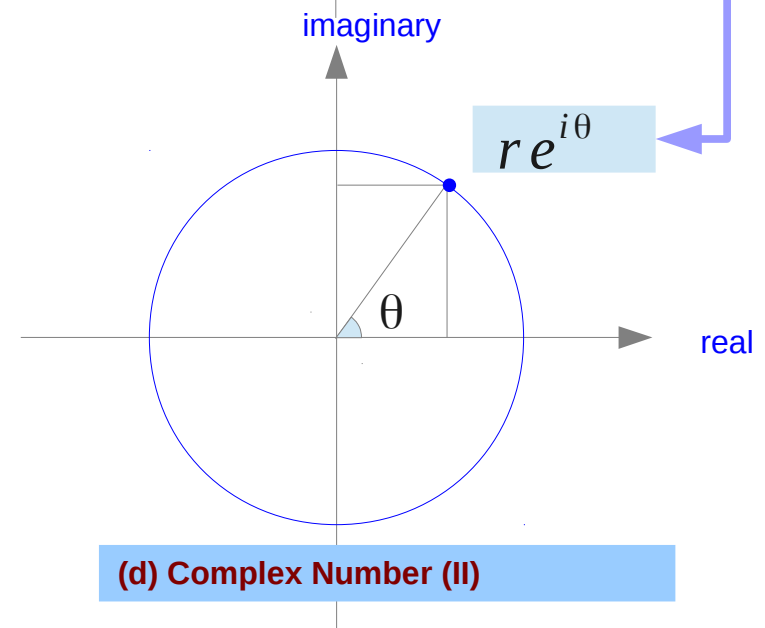
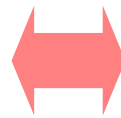
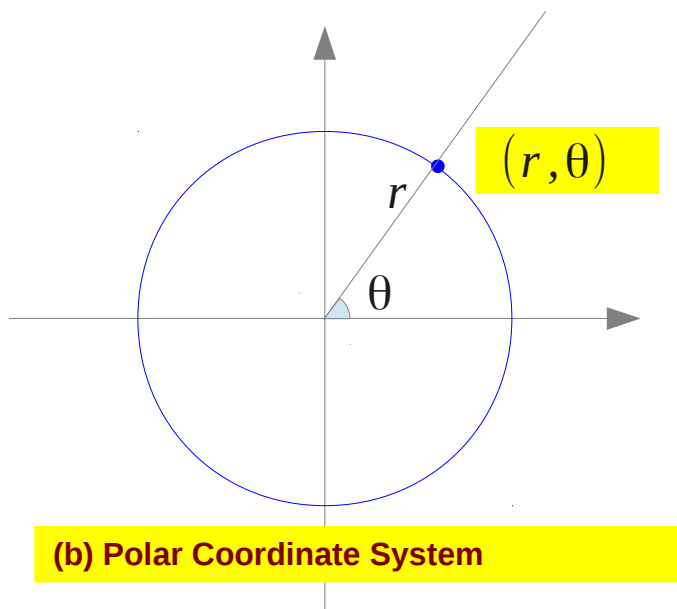
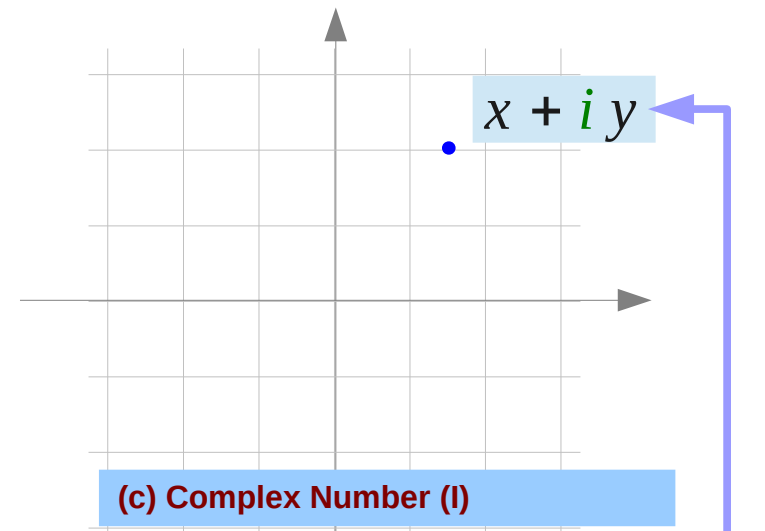
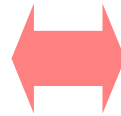
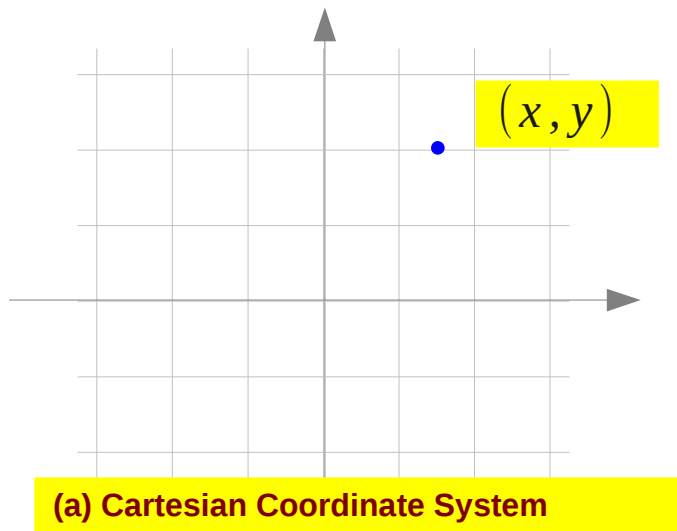


(b) Polar Coordinate System

$$r = \sqrt{x^2 + y^2}$$

$$\tan \theta = \frac{y}{x}$$

Coordinate Systems and Complex Numbers



Complex Numbers

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}$$

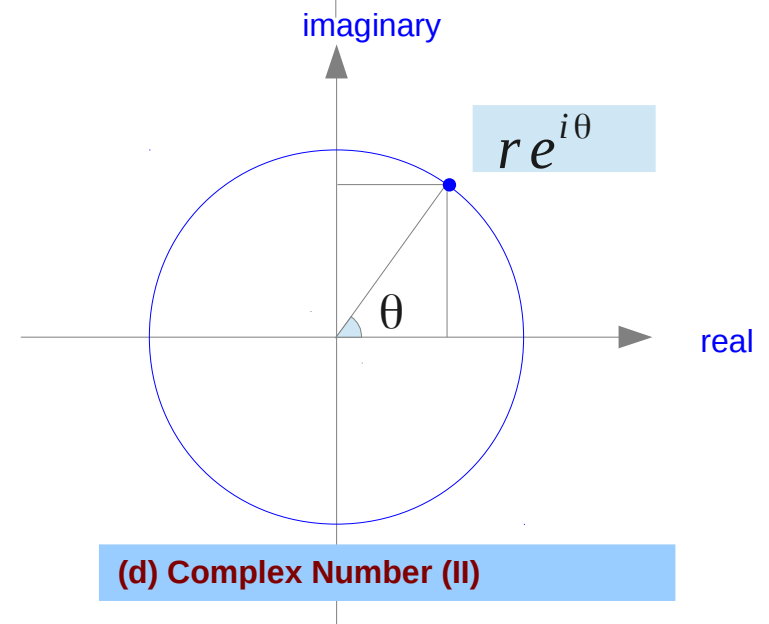
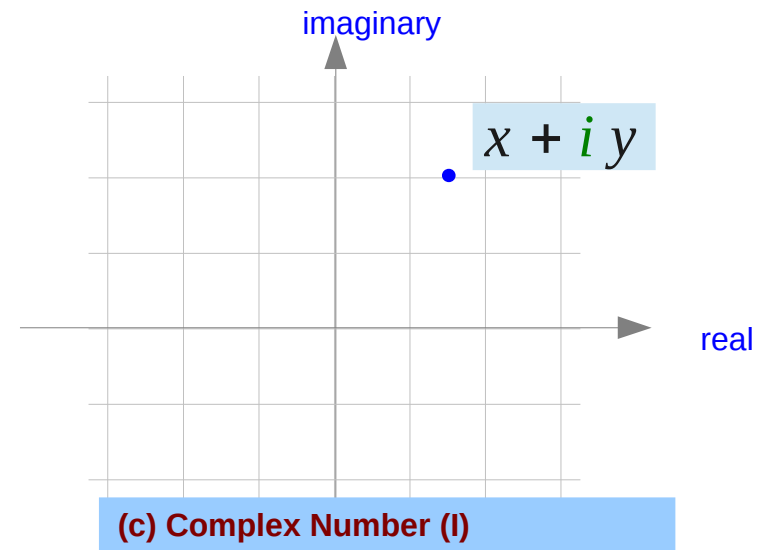
$$\tan \theta = \frac{y}{x}$$

$$x + iy = r \cos \theta + ir \sin \theta$$

$$= r(\cos \theta + i \sin \theta)$$

$$= r e^{i\theta}$$

$$e^{i\theta} = \cos \theta + i \sin \theta$$



Euler's Formula (1)

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$x \quad \Rightarrow \quad \Re\{e^{i\theta}\} = \cos \theta$$

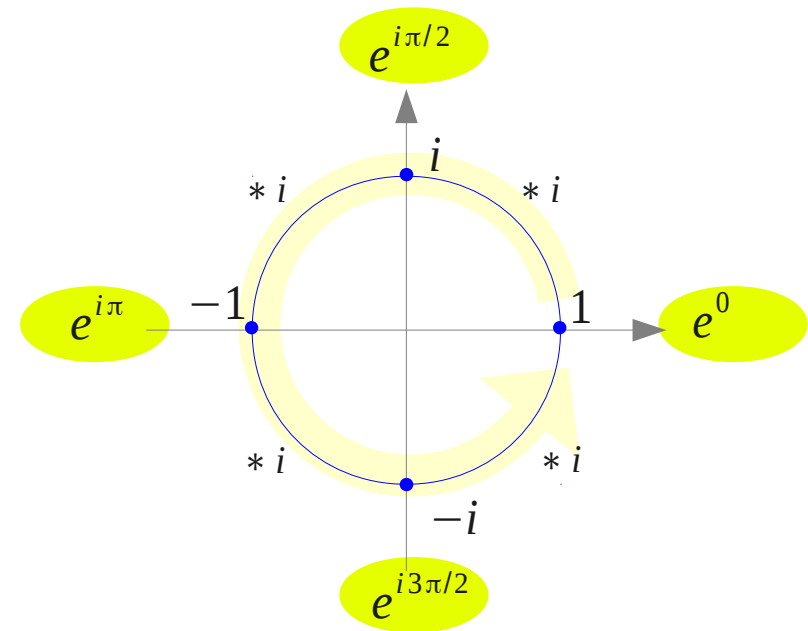
$$y \quad \Rightarrow \quad \Im\{e^{i\theta}\} = \sin \theta$$

$$e^0 = +1 + 0i$$

$$e^{i\pi/2} = 0 + 1i$$

$$e^{i\pi} = -1 + 0i$$

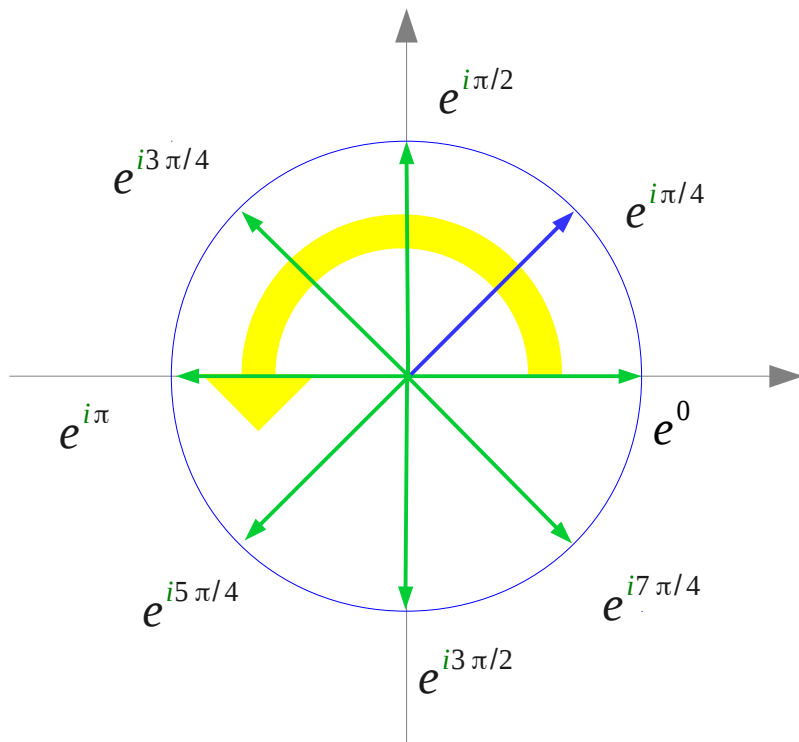
$$e^{i3\pi/2} = 0 - 1i$$



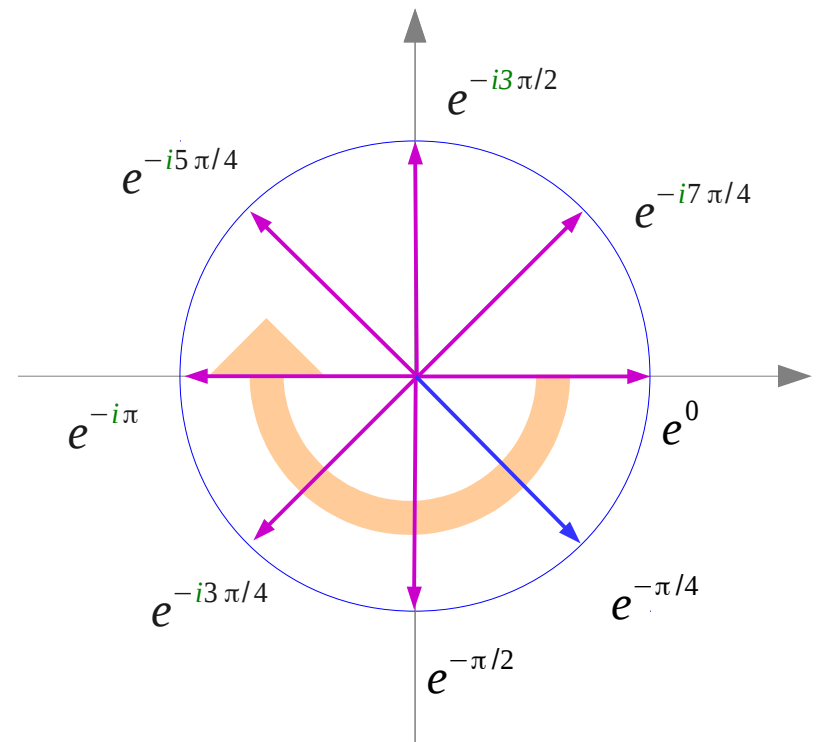
$$\begin{aligned} &= +1 & &= e^{-i2\pi} \\ &= +i & &= e^{-i3\pi/2} \\ &= -1 & &= e^{-i\pi} \\ &= -i & &= e^{-i\pi/2} \end{aligned}$$

Euler's Formula (2)

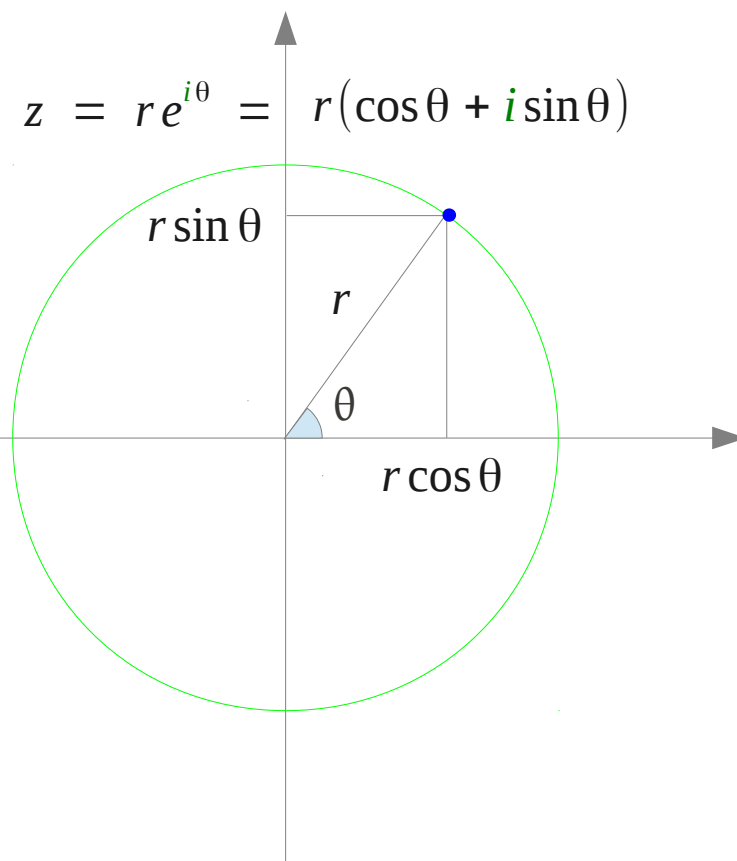
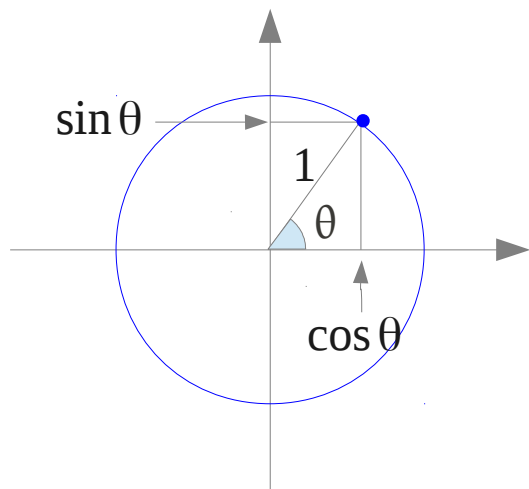
$$e^{+i\theta} = \cos \theta + i \sin \theta$$



$$e^{-i\theta} = \cos \theta - i \sin \theta$$



Absolute Values and Arguments



absolute value

$$|z| = r$$

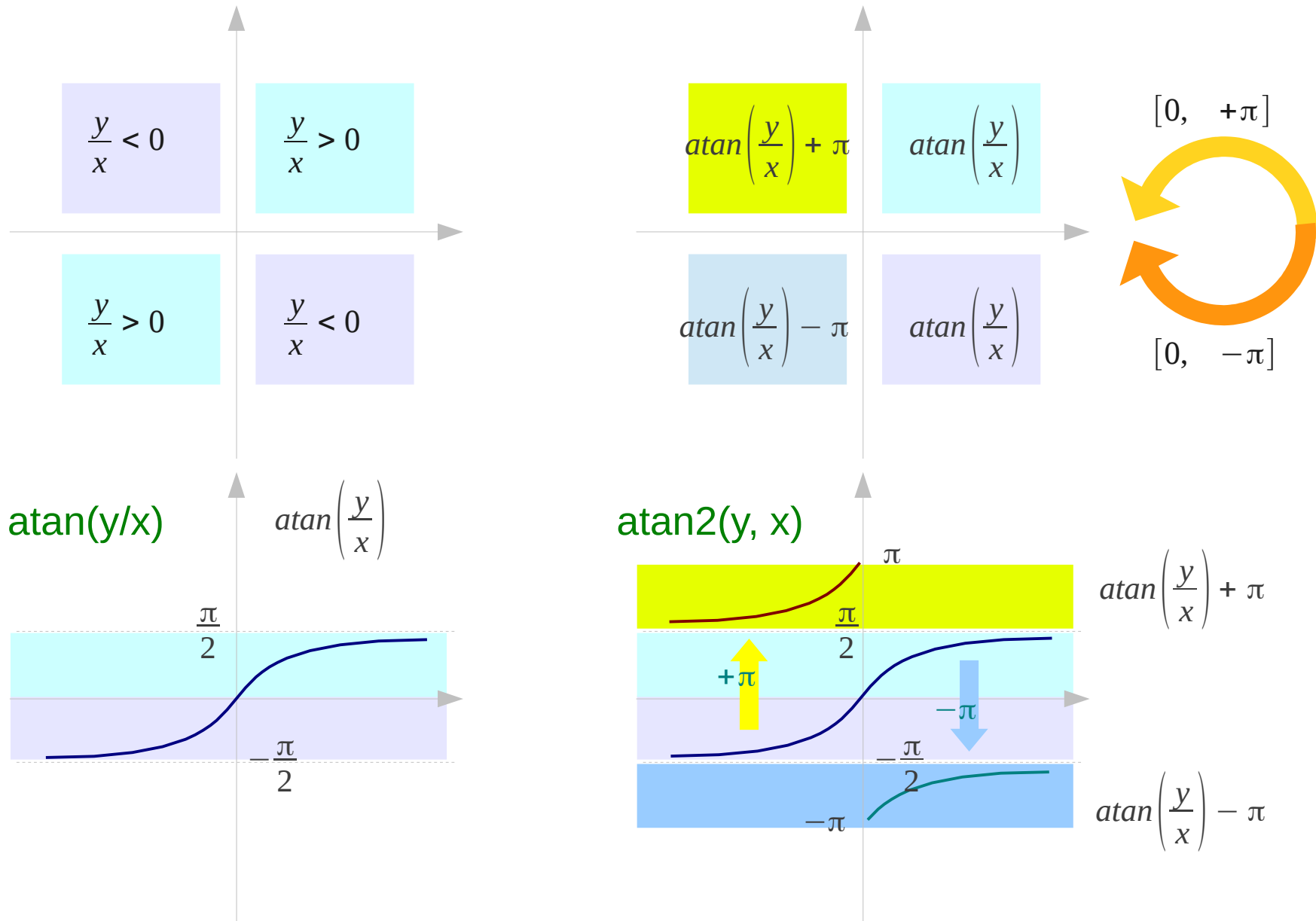
$$\Rightarrow |r e^{i\theta}| = |r| |e^{i\theta}| = r \sqrt{\cos^2 \theta + \sin^2 \theta}$$

argument, phase

$$\arg(z) = \theta$$

$$\Rightarrow \arg(r e^{i\theta})$$

Computing Complex Number Argument



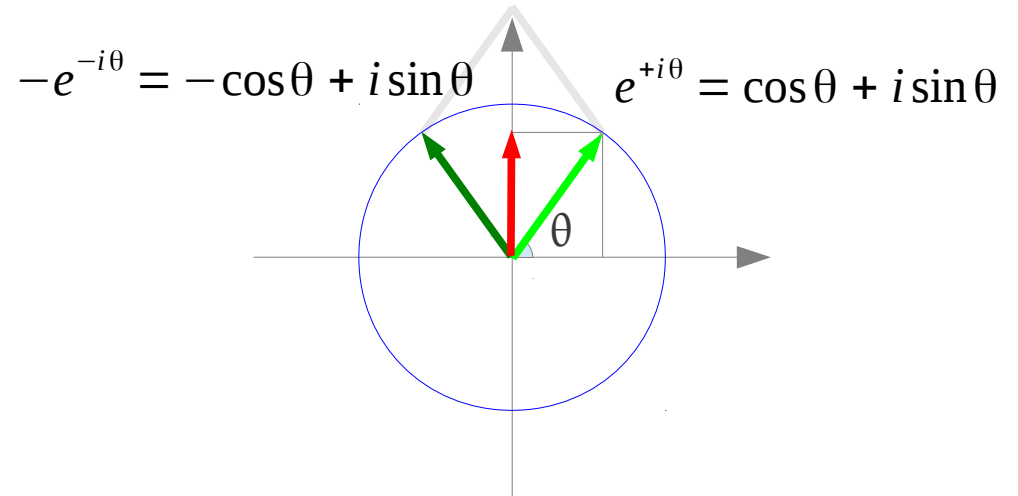
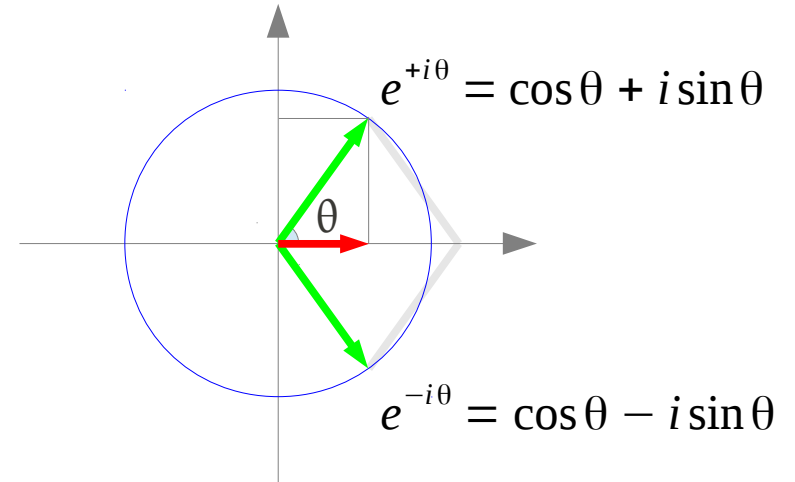
sin and cos

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$e^{-i\theta} = \cos \theta - i \sin \theta$$

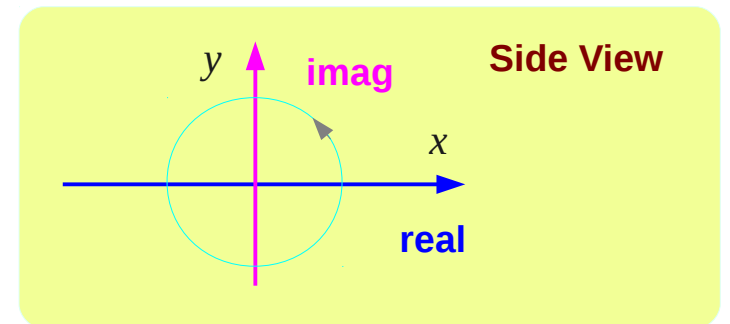
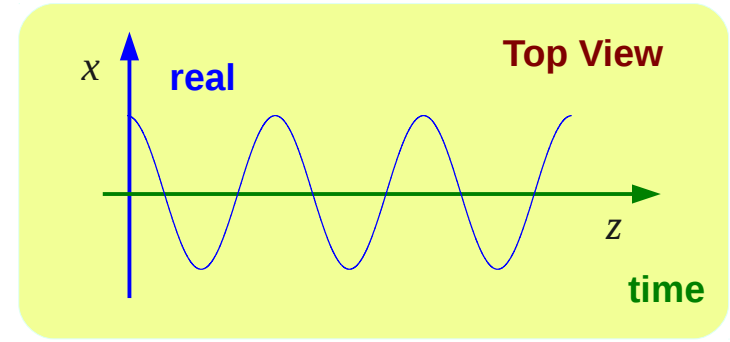
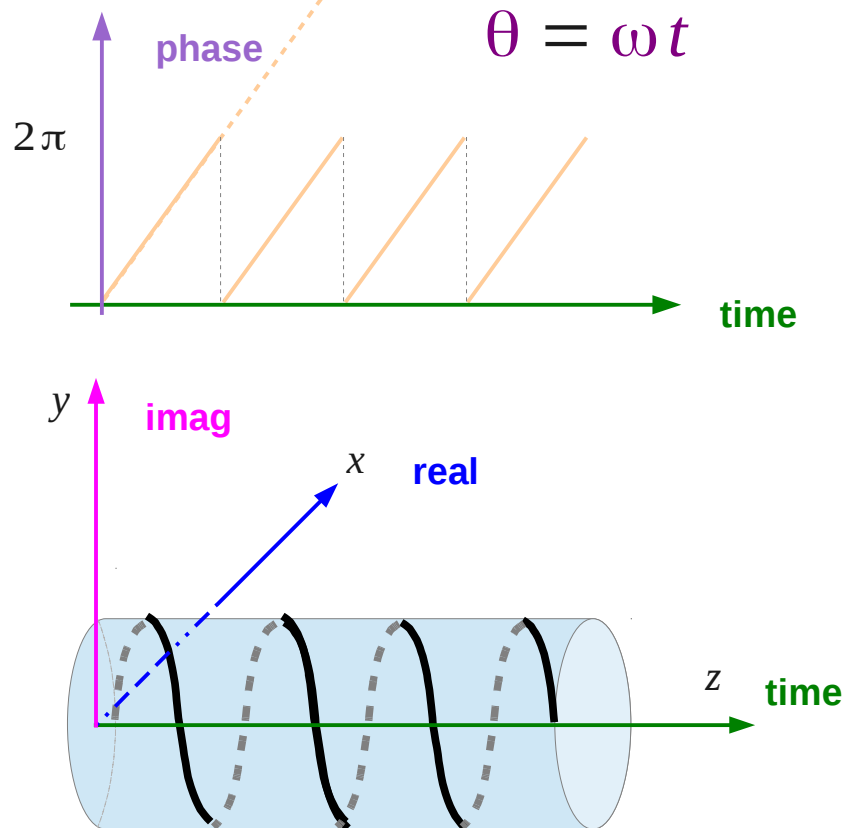
$$\Re\{e^{i\theta}\} = \cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

$$\Im\{e^{i\theta}\} = \sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

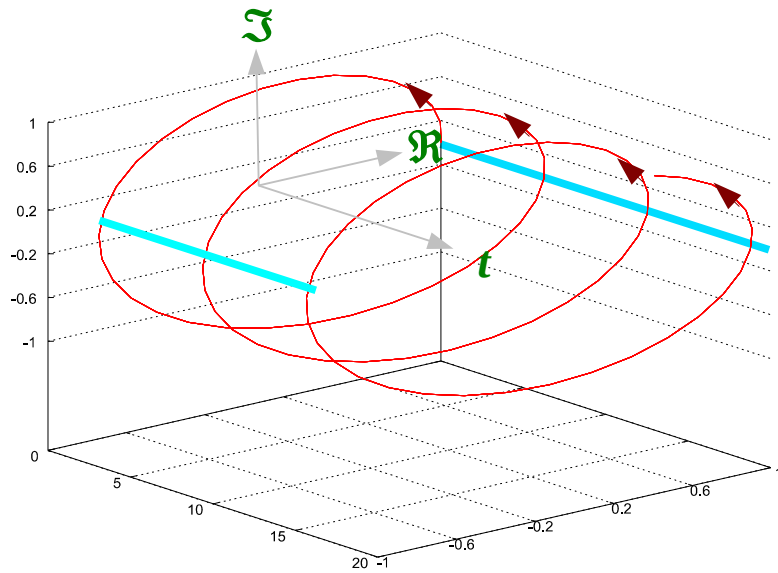


Complex Exponential

$$e^{+j\omega t} = \cos \omega t + j \sin \omega t$$

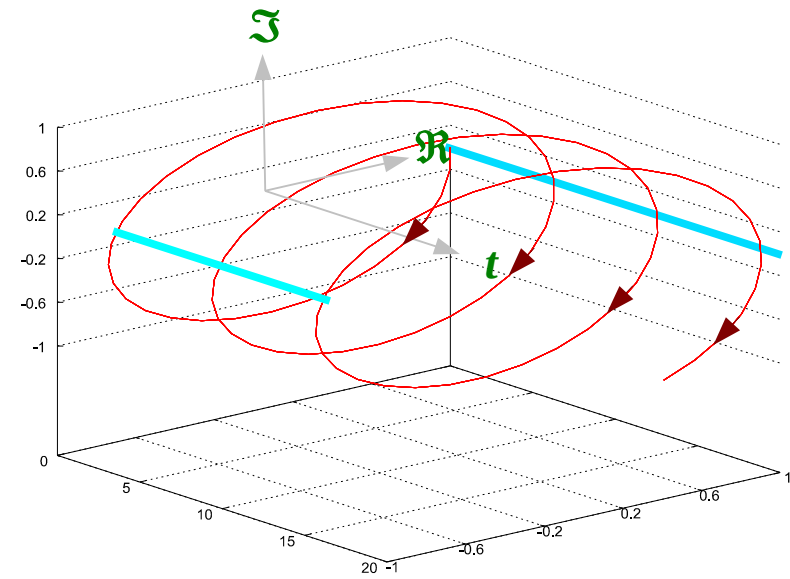


Conjugate Complex Exponential



$$e^{+j\omega_0 t} = \cos(\omega_0 t) + j \sin(\omega_0 t)$$

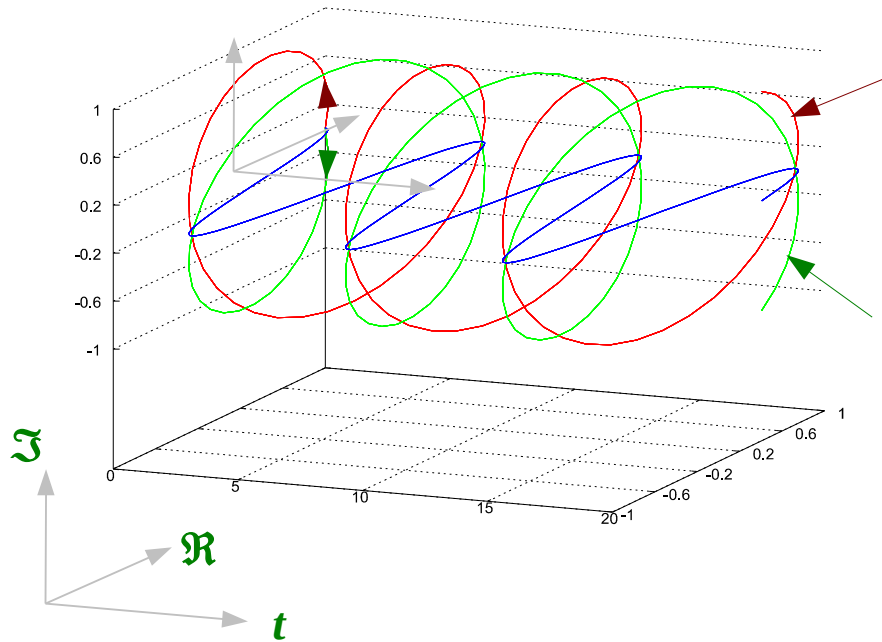
$$e^{+jt} = \cos(t) + j \sin(t) \quad (\omega_0 = 1)$$



$$e^{-j\omega_0 t} = \cos(\omega_0 t) - j \sin(\omega_0 t)$$

$$e^{-jt} = \cos(t) - j \sin(t) \quad (\omega_0 = 1)$$

Cos($\omega_0 t$)



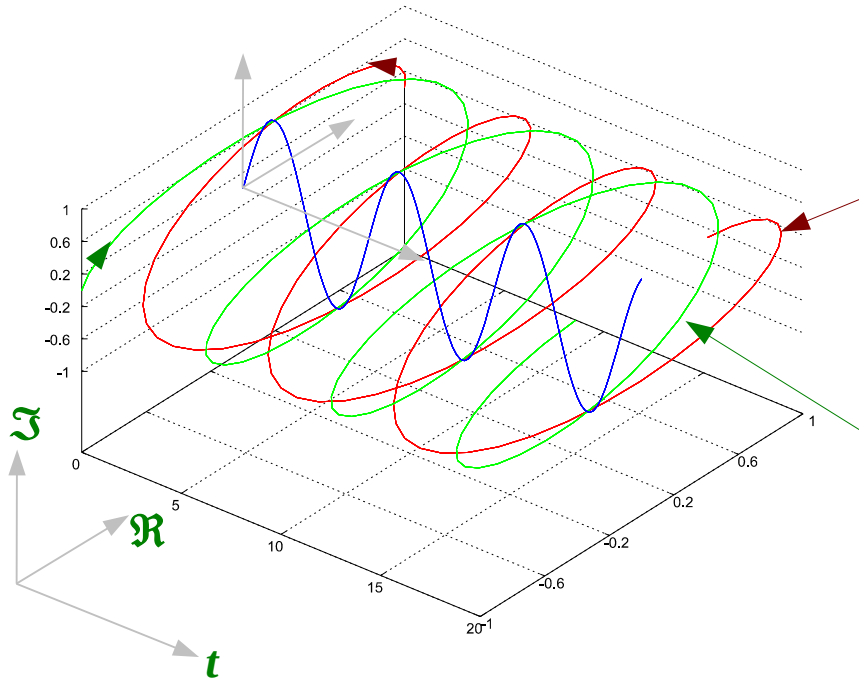
$$e^{+jt} = \cos(t) + j \sin(t)$$

$$(e^{+jt} + e^{-jt}) = 2 \cos(t)$$

$$e^{-jt} = \cos(t) - j \sin(t)$$

$$\begin{aligned} x(t) &= A \cos(\omega_0 t) \\ &= \frac{A}{2} e^{+j\omega_0 t} + \frac{A}{2} e^{-j\omega_0 t} \end{aligned}$$

Sin($\omega_0 t$)



$$e^{+jt} = \cos(t) + j \sin(t)$$

$$(e^{+jt} - e^{-jt}) = 2j \sin(t)$$

$$-e^{-jt} = -\cos(t) + j \sin(t)$$

$$\begin{aligned} x(t) &= A \sin(\omega_0 t) \\ &= \frac{A}{2j} e^{+j\omega_0 t} - \frac{A}{2j} e^{-j\omega_0 t} \end{aligned}$$

Complex Power Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$e^{i\theta} = 1 + (i\theta) + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \frac{(i\theta)^4}{4!} + \frac{(i\theta)^5}{5!} + \dots$$

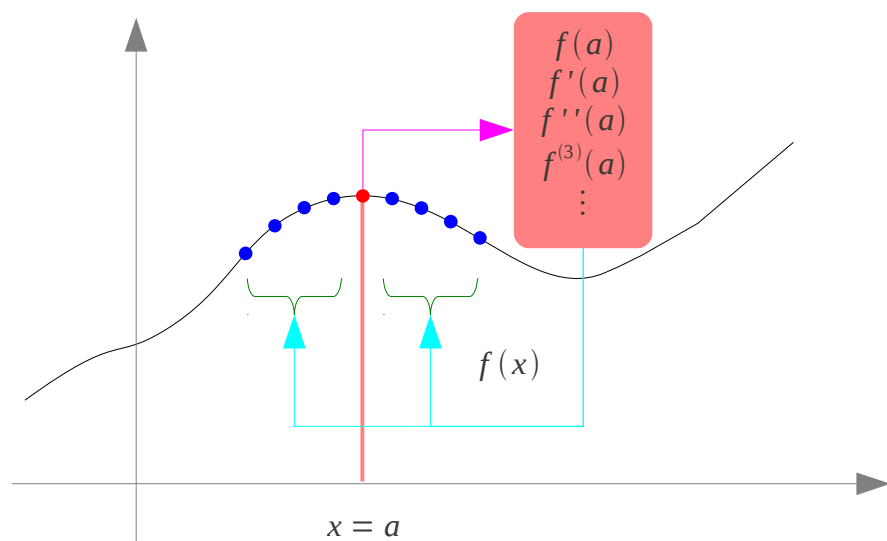
$$= 1 + i\theta - \frac{\theta^2}{2!} - i\frac{\theta^3}{3!} + \frac{\theta^4}{4!} + i\frac{\theta^5}{5!} + \dots$$

$$= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} + \dots \right) + i \left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} + \dots \right)$$

$$e^{i\theta} = \cos \theta + i \sin \theta$$

Taylor Series

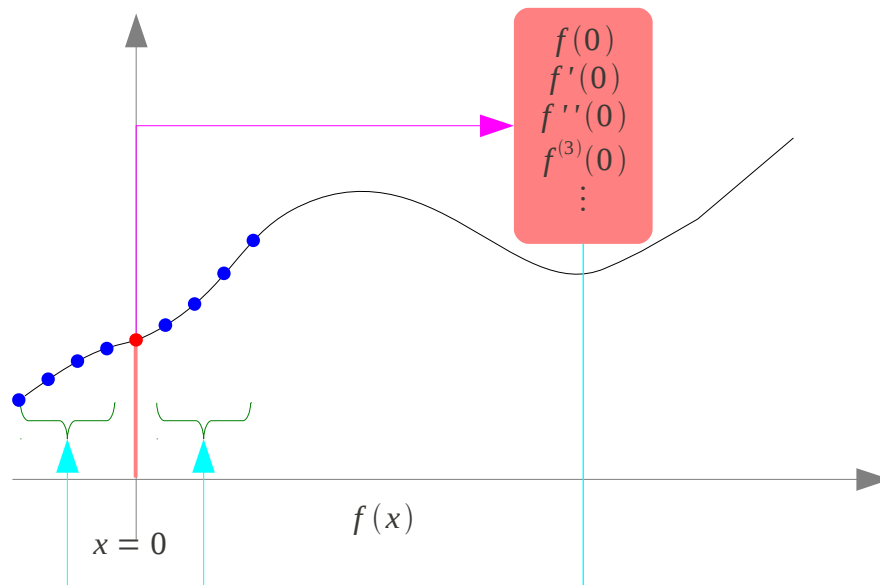
$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \cdots$$



Maclaurin Series

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \cdots$$

$$f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \cdots + \frac{f^{(n)}(0)}{n!}x^n + \cdots$$



Power Series Expansion

$$f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \cdots + \frac{f^{(n)}(0)}{n!}x^n + \cdots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \cdots$$

Complex Arithmetic

$$z = a + ib$$

$$w = c + id$$

$$z+w = (a+c) + i(b+d)$$

$$z = a + ib$$

$$w = c + id$$

$$zw = (ac-bd) + i(ad+bc)$$

$$z = a + ib$$

$$w = c + id$$

$$z-w = (a-c) + i(b-d)$$

$$z = a + ib$$

$$w = c + id$$

$$\frac{z}{w} = \left(\frac{a+ib}{c+id} \right)$$

$$= \left(\frac{a+ib}{c+id} \right) \left(\frac{c-id}{c-id} \right)$$

$$= \left(\frac{ac+bd}{c^2+d^2} \right) + i \left(\frac{-ad+bc}{c^2+d^2} \right)$$

Complex Conjugate

$$z = x + iy = \Re\{z\} + i\Im\{z\}$$

$$\bar{z} = x - iy = \Re\{z\} - i\Im\{z\}$$

$$\Re\{z\} = \frac{1}{2}(z + \bar{z})$$

$$\Im\{z\} = \frac{1}{2i}(z - \bar{z})$$

$$\overline{z + w} = \bar{z} + \bar{w}$$

$$\overline{z - w} = \bar{z} - \bar{w}$$

$$\overline{\bar{z}w} = z\bar{w}$$

$$\overline{\left(\frac{z}{w}\right)} = \frac{\bar{z}}{\bar{w}}$$

$$z\bar{z} = (x + iy)(x - iy) = x^2 + y^2$$

$$\frac{1}{z} = \frac{1}{z} \cdot \frac{\bar{z}}{\bar{z}} = \frac{\bar{z}}{z\bar{z}} = \frac{\bar{z}}{x^2 + y^2} = \frac{\bar{z}}{|z|^2}$$

Complex Power (1)

$$a = e^{\log_e a} = e^{\ln a}$$

$$a^b = (e^{\log_e a})^b = (e^{\ln a})^b = e^{b \ln a}$$

$$\begin{aligned} a^{ib} &= (e^{\log_e a})^{ib} = (e^{\ln a})^{ib} = e^{ib \ln a} \\ &= \cos(b \ln a) + i \sin(b \ln a) \end{aligned}$$

$$a^{c+ib} = a^c (e^{\log_e a})^{ib} = a^c (e^{\ln a})^{ib} = a^c e^{ib \ln a}$$

Complex Power (2)

$$a = e^{\ln a}$$

$$a^b = e^{b \ln a}$$

$$a^{ib} = e^{ib \ln a} = [\cos(b \ln a) + i \sin(b \ln a)]$$

$$a^{c+ib} = a^c e^{ib \ln a} = a^c [\cos(b \ln a) + i \sin(b \ln a)]$$

Matrices

Determinant (1)

Determinant of order 2

$$\begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 \end{bmatrix} \quad \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

Determinant of order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$\begin{bmatrix} a_1 & & \\ & b_2 & b_3 \\ & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} & a_2 & \\ b_1 & & b_3 \\ c_1 & & c_3 \end{bmatrix} \quad \begin{bmatrix} & & a_3 \\ b_1 & b_2 & \\ c_1 & c_2 & \end{bmatrix}$$

Determinant (2)

Determinant of order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$\begin{bmatrix} + \\ a_1 \\ \begin{array}{cc} b_2 & b_3 \\ c_2 & c_3 \end{array} \end{bmatrix} \quad \begin{bmatrix} - \\ a_2 \\ \begin{array}{cc} b_1 & b_3 \\ c_1 & c_3 \end{array} \end{bmatrix} \quad \begin{bmatrix} + \\ a_3 \\ \begin{array}{cc} b_1 & b_2 \\ c_1 & c_2 \end{array} \end{bmatrix}$$

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = + a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

Determinant (3)

Determinant of order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$\begin{bmatrix} -a_2 & & \\ b_1 & & b_3 \\ c_1 & & c_3 \end{bmatrix} \quad \begin{bmatrix} a_1 & & a_3 \\ +b_2 & & \\ c_1 & & c_3 \end{bmatrix} \quad \begin{bmatrix} a_1 & & a_3 \\ b_1 & & b_3 \\ -c_2 & & \end{bmatrix}$$

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = -a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + b_2 \begin{vmatrix} a_1 & a_3 \\ c_1 & c_3 \end{vmatrix} - c_2 \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix}$$

Determinant – Rule of Sarrus

Determinant of order 3

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$= a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

$$= a_{11}(a_{22}a_{33} - a_{23}a_{32})$$

$$- a_{12}(a_{21}a_{33} - a_{23}a_{31})$$

$$+ a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

Recursive Method

Determinant of order 3 only

$$\begin{bmatrix} + & & - \\ a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$+ a_{11}a_{22}a_{33} - a_{11}a_{23}a_{32}$$

$$\begin{bmatrix} & + & & - \\ a_{11} & a_{12} & a_{13} & a_{11} \\ a_{21} & a_{22} & a_{23} & a_{21} \\ a_{31} & a_{32} & a_{33} & a_{31} \end{bmatrix} \quad \begin{bmatrix} a_{12} & a_{13} & a_{11} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$+ a_{12}a_{23}a_{31} - a_{12}a_{21}a_{33}$$

Rule of Sarrus

$$\begin{bmatrix} & & + & & - \\ a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{bmatrix} \quad \begin{bmatrix} a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$+ a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31}$$

Solving Linear Equations

A set of linear equations

$$\begin{aligned} ax + by &= e \\ cx + dy &= f \end{aligned}$$



$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} e \\ f \end{bmatrix}$$



If the inverse matrix exists

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} \begin{bmatrix} e \\ f \end{bmatrix}$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc \neq 0$$



$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \begin{bmatrix} e \\ f \end{bmatrix}$$

$$\begin{vmatrix} e & b \\ f & d \end{vmatrix} = de - bf$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{ad - bc} \begin{bmatrix} de - bf \\ -ce + af \end{bmatrix}$$

$$\begin{vmatrix} a & e \\ c & f \end{vmatrix} = af - ce$$

Cramer's Rule

$$x = \frac{\begin{vmatrix} e & b \\ f & d \end{vmatrix}}{\begin{vmatrix} a & b \\ c & d \end{vmatrix}} \quad y = \frac{\begin{vmatrix} a & e \\ c & f \end{vmatrix}}{\begin{vmatrix} a & b \\ c & d \end{vmatrix}}$$

Cramer's Rule

Determinant of order 3

$$a_1x + a_2y + a_3z = d$$

$$b_1x + b_2y + b_3z = e$$

$$c_1x + c_2y + c_3z = f$$



$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} d \\ e \\ f \end{bmatrix}$$

$$x = \frac{\begin{vmatrix} \downarrow d & a_2 & a_3 \\ e & b_2 & b_3 \\ f & c_2 & c_3 \end{vmatrix}}{\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}}$$

$$y = \frac{\begin{vmatrix} a_1 & \downarrow d & a_3 \\ b_1 & e & b_3 \\ c_1 & f & c_3 \end{vmatrix}}{\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}}$$

$$z = \frac{\begin{vmatrix} a_1 & a_2 & \downarrow d \\ b_1 & b_2 & e \\ c_1 & c_2 & f \end{vmatrix}}{\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}}$$

Linear Independence

Wronskian

$$W(f_1, f_2, \dots, f_n) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f'_1 & f'_2 & \cdots & f'_n \\ \vdots & \vdots & \cdots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}$$

$$W(f_1(x), f_2(x), \dots, f_n(x)) = \begin{vmatrix} f_1(x) & f_2(x) & \cdots & f_n(x) \\ \frac{df_1}{dx} & \frac{df_2}{dx} & \cdots & \frac{df_n}{dx} \\ \vdots & \vdots & \cdots & \vdots \\ \frac{d^{(n-1)}f_1}{dx^{(n-1)}} & \frac{d^{(n-1)}f_2}{dx^{(n-1)}} & \cdots & \frac{d^{(n-1)}f_n}{dx^{(n-1)}} \end{vmatrix}$$

Linear Independent Functions and Wronskian

$$C_1 y_1 + C_2 y_2 = 0 \quad \Rightarrow \quad C_1 = C_2 = 0$$

always zero means all coefficients must be zero

y_1 and y_2 are linearly independent functions

$$\begin{aligned} C_1 y_1 + C_2 y_2 &= 0 \\ \Rightarrow C_1 y_1' + C_2 y_2' &= 0 \end{aligned}$$

$$\begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

If the inverse matrix exists

$$\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \neq 0 \quad \Leftrightarrow \quad \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

the only solution: trivial

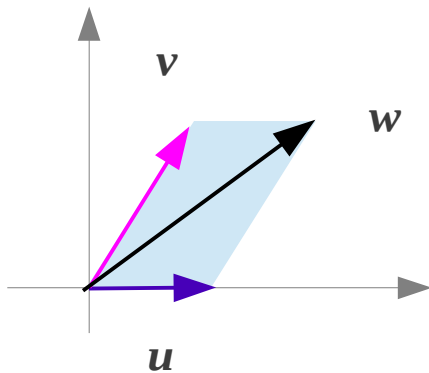
$$W(y_1, y_2) \neq 0$$

Linear Dependent (1)

$\{u, v, w\}$ linearly dependent

$$w = u + v$$

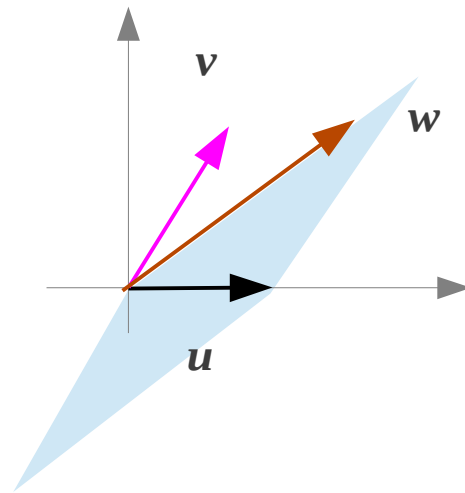
w in terms of u & v



$$u + v - w = 0$$

$$u = w - v$$

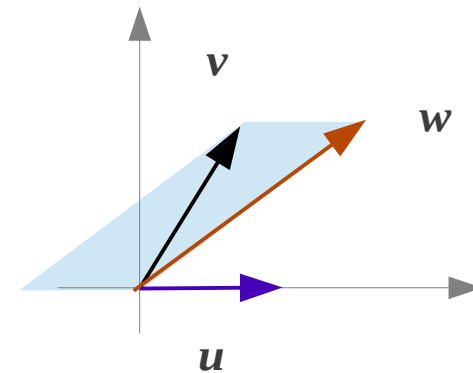
u in terms of w & v



$$u + v - w = 0$$

$$v = w - u$$

v in terms of w & u

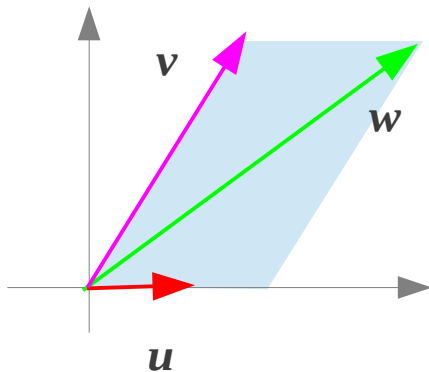


$$u + v - w = 0$$

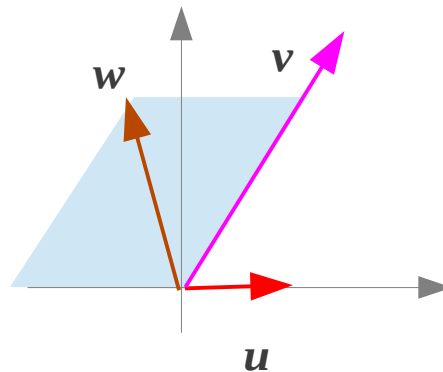
Linear Dependent (2)

$\{u, v, w\}$ linearly dependent

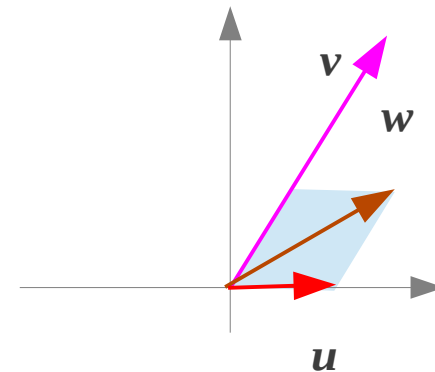
w1 in terms of u & v



w2 in terms of u & v



w3 in terms of u & v



$$k_1 u + k_2 v + k_3 w = 0$$

$$(k_1 = 0) \wedge (k_2 = 0) \wedge (k_3 = 0)$$
$$(k_1 \neq 0) \vee (k_2 \neq 0) \vee (k_3 \neq 0)$$

$$m_1 u + m_2 v + m_3 w = 0$$

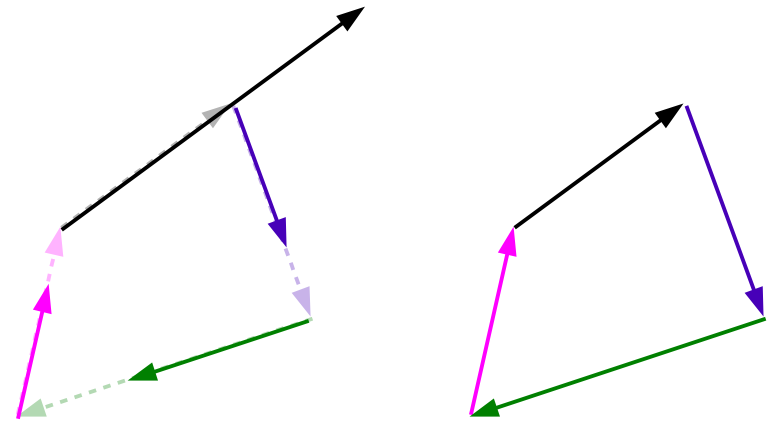
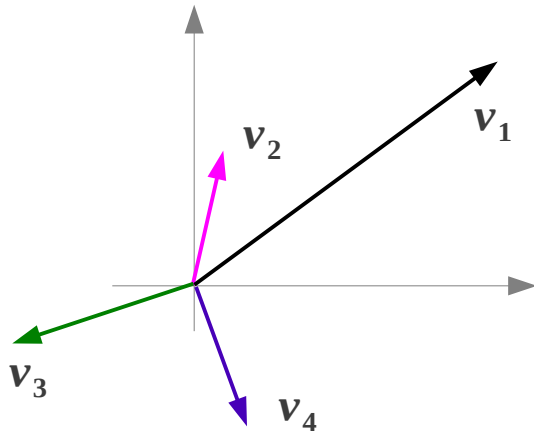
$$(m_1 = 0) \wedge (m_2 = 0) \wedge (m_3 = 0)$$
$$(m_1 \neq 0) \vee (m_2 \neq 0) \vee (m_3 \neq 0)$$

$$n_1 u + n_2 v + n_3 w = 0$$

$$(n_1 = 0) \wedge (n_2 = 0) \wedge (n_3 = 0)$$
$$(n_1 \neq 0) \vee (n_2 \neq 0) \vee (n_3 \neq 0)$$

Linear Dependent (3)

$\{v_1, v_2, v_3, v_4\}$ linearly dependent



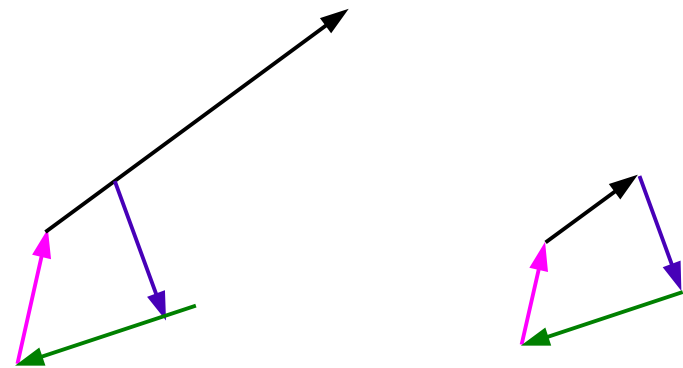
$$k_1 v_1 + k_2 v_2 + k_3 v_3 + k_4 v_4 = \mathbf{0}$$

$$(k_1 \neq 0) \vee (k_2 \neq 0) \vee (k_3 \neq 0) \vee (k_4 \neq 0)$$



$$0 v_1 + m_2 v_2 + m_3 v_3 + m_4 v_4 = \mathbf{0}$$

$$(m_1 = 0) \vee (m_2 \neq 0) \vee (m_3 \neq 0) \vee (m_4 \neq 0)$$

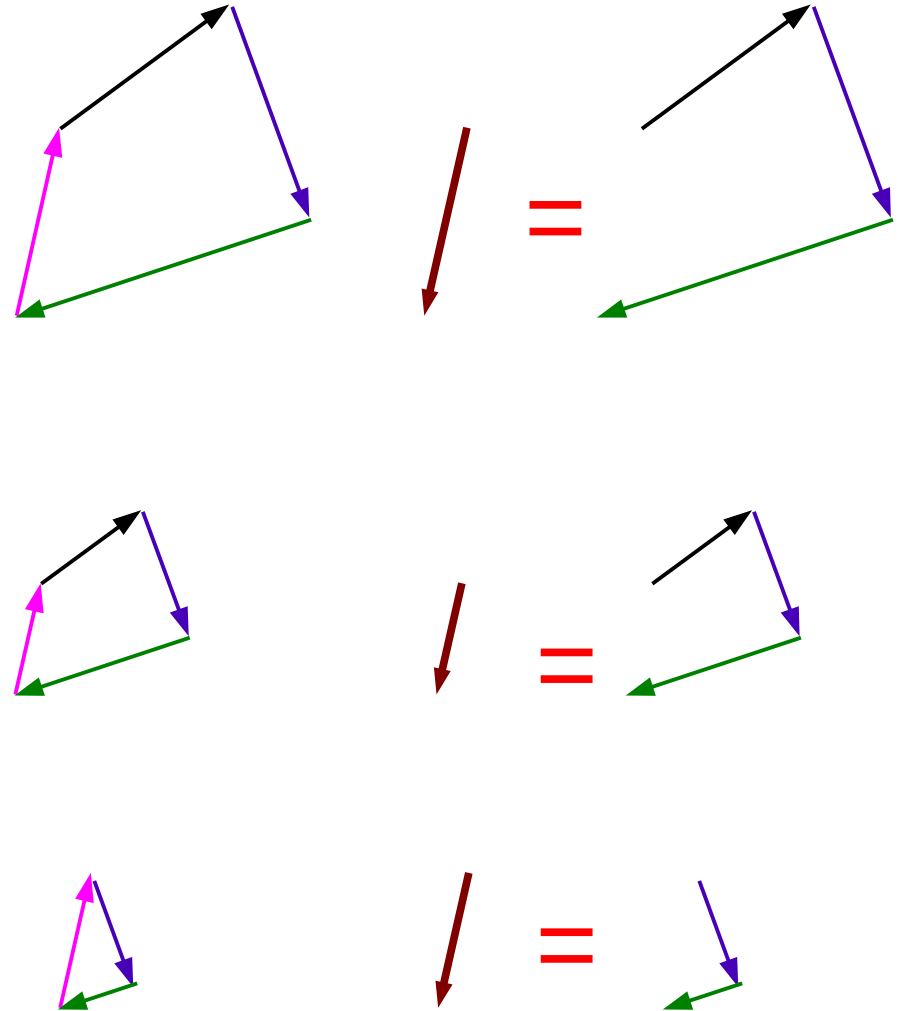
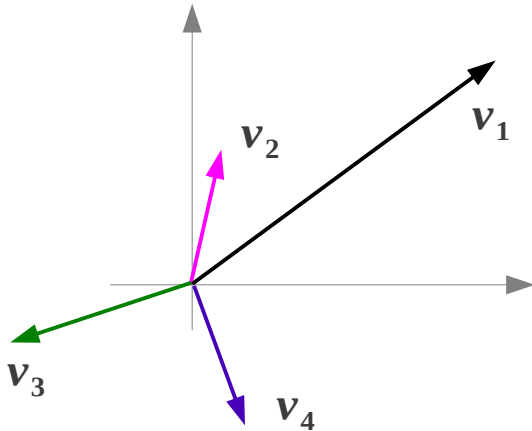


$$m_1 v_1 + m_2 v_2 + m_3 v_3 + m_4 v_4 = \mathbf{0}$$

$$(m_1 \neq 0) \vee (m_2 \neq 0) \vee (m_3 \neq 0) \vee (m_4 \neq 0)$$

Linear Dependent (4)

$\{v_1, v_2, v_3, v_4\}$ linearly dependent



Linear Independent (1)

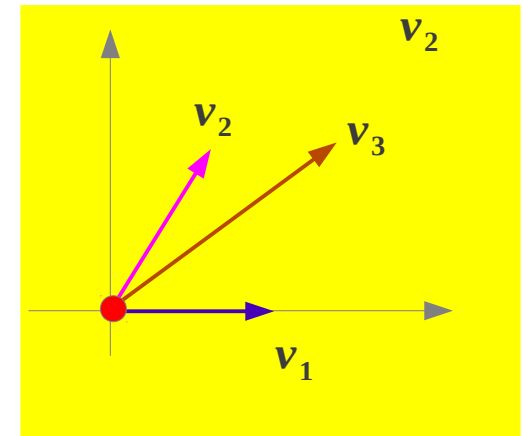
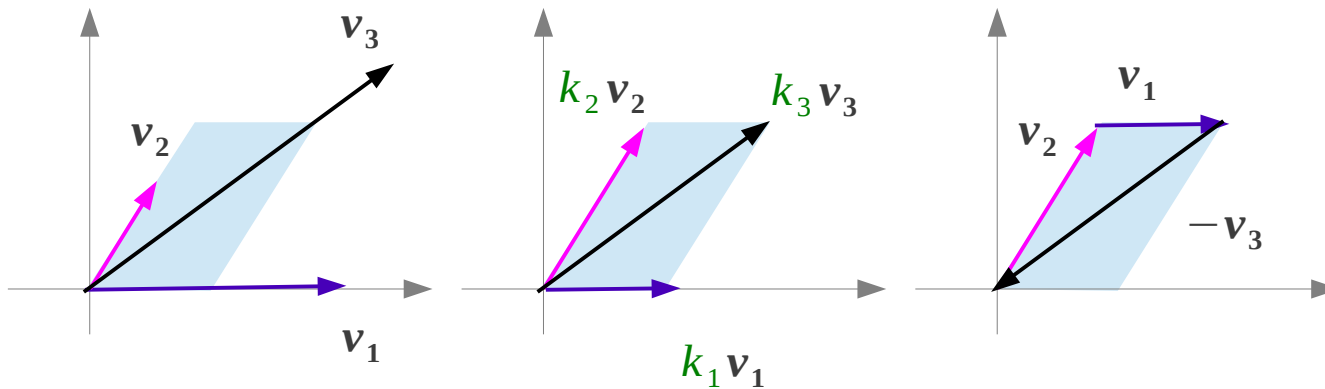
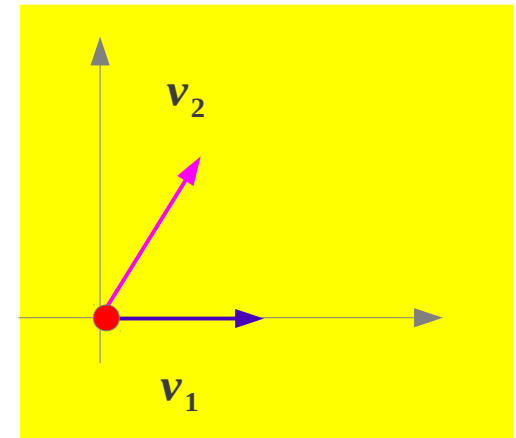
$S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ non-empty set of vectors in V

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_n \mathbf{v}_n = \mathbf{0}$$

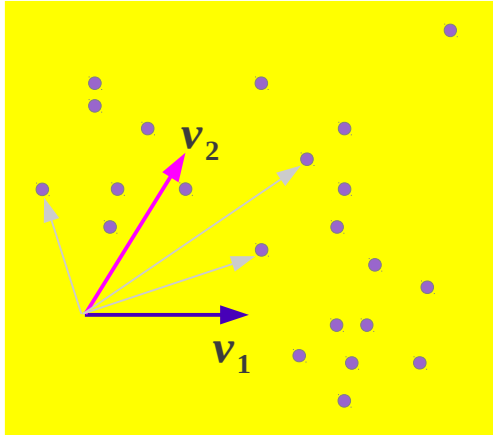
the solution of the above equation

trivial solution: $k_1 = k_2 = \dots = k_n = 0$

{	if other solution exists	S linearly dependent
	if no other solution exists	S linearly independent



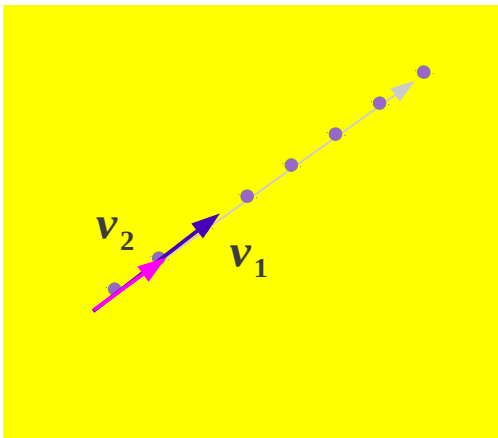
Linear Independent (2)



every point in \mathbb{R}^2 can be represented by

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2$$

linear combination of \mathbf{v}_1 and \mathbf{v}_2
which are one set of linear independent
two vectors



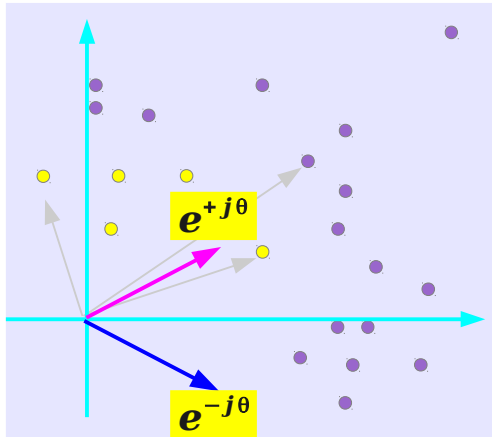
only points on a line in \mathbb{R}^2

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2$$

linear combination of \mathbf{v}_1 and \mathbf{v}_2
which are one set of linear dependent
two vectors

Basis

Basis : a set of linear independent spanning vectors



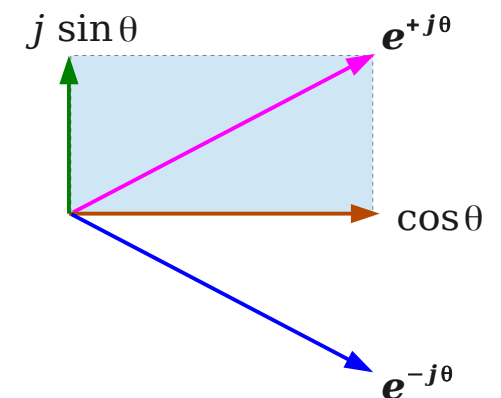
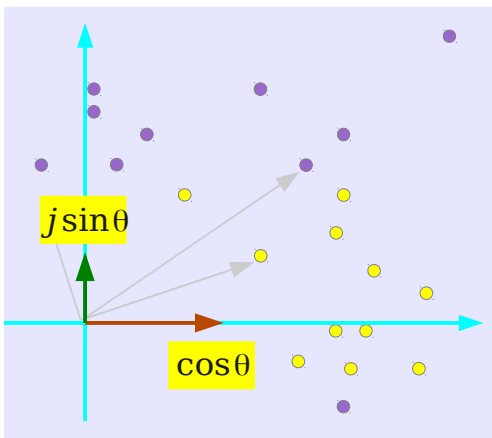
every complex number can be represented by

$$\boxed{k_1} e^{+j\theta} + \boxed{k_2} e^{+j\theta}$$

linear combination of $e^{+j\theta}$ and $e^{+j\theta}$
which are one set of linear independent
two vectors

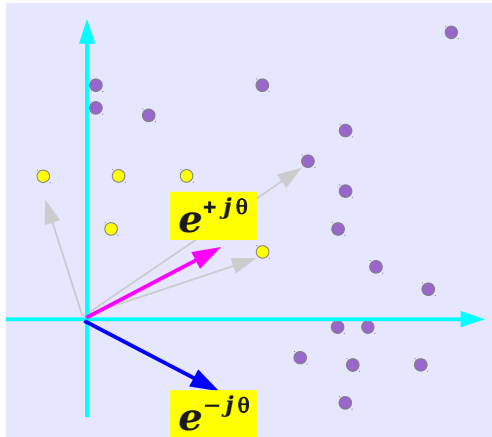
every complex number can also be represented by

$$\boxed{l_1} \cos\theta + \boxed{l_2 j} \sin\theta$$

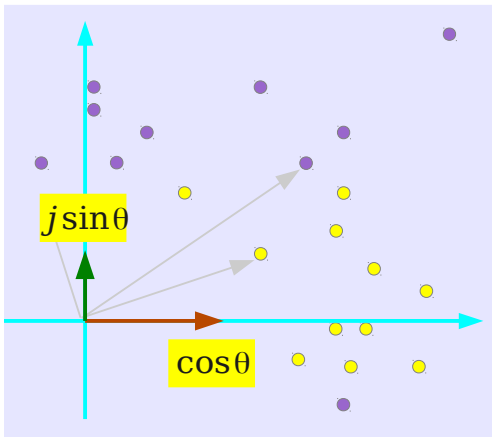
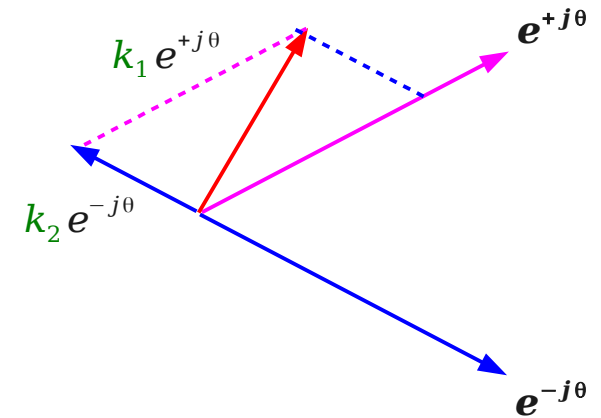


Basis (2)

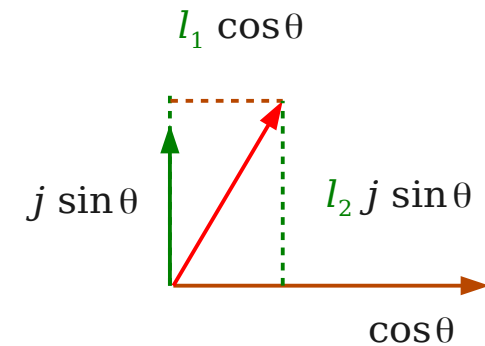
Basis : a set of linear independent spanning vectors



$$\boxed{k_1} e^{+j\theta} + \boxed{k_2} e^{+j\theta}$$

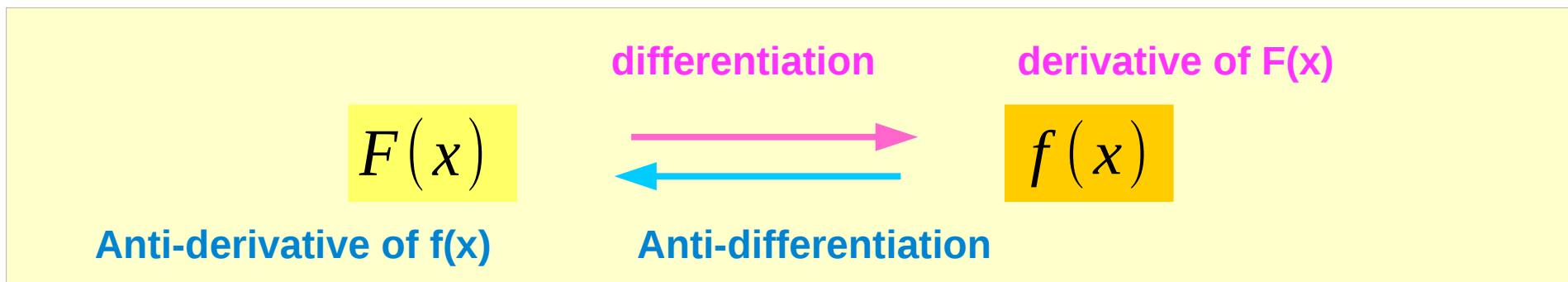


$$\boxed{l_1} \cos\theta + \boxed{l_2 j} \sin\theta$$



Leibniz Formula

Anti-derivative Examples



$$\int_0^x f(x) dx = \left[\frac{1}{3}x^3 \right]_0^x = \frac{1}{3}x^3 \quad f(x) = x^2$$

$$\int_a^x f(x) dx = \left[\frac{1}{3}x^3 \right]_a^x = \frac{1}{3}x^3 - \frac{1}{3}a^3$$

$$\int_a^x f(t) dt = \left[\frac{1}{3}t^3 \right]_a^x = \frac{1}{3}x^3 - \frac{1}{3}a^3$$

anti-derivative
by the definite
integral of $f(x)$

$$\int_a^x f(t) dt = \frac{1}{3}x^3 + C$$

$$\frac{d}{dx} \int_a^x f(t) dt = f(x) = x^2$$

the Indefinite
Integral of $f(x)$

$$\int x^2 dx = \frac{1}{3}x^3 + C$$

Fundamental Theorem of Calculus

Derivative of an Antiderivative

$$F(x) = \int_a^x f(t) dt$$

$$F'(x) = f(x)$$

$$F(g(x)) = \int_a^{g(x)} f(t) dt$$

$$F'(g(x)) = f(g(x))g'(x)$$

$$F(x) = \int_a^x t^2 dt = \frac{1}{3}x^3 - \frac{1}{3}a^3$$

$$f(x) = x^2$$

$$F(2x+1) = \int_a^{2x+1} t^2 dt = \frac{1}{3}(2x+1)^3 - \frac{1}{3}a^3$$

$$F'(2x+1) = \frac{d}{dx} \left(\frac{1}{3}(2x+1)^3 - \frac{1}{3}a^3 \right) = \frac{1}{3}(2x+1)^2 \cdot 2$$

an Antiderivative and an Definite Integral

$$F'(x) = f(x)$$

$$\int_a^b f(t) dt = F(b) - F(a)$$

Differentiation under the Integral Sign

$$F(x) = \int_a^x f(t) dt \quad F'(x) = f(x)$$

$$F(g(x)) = \int_a^{g(x)} f(t) dt \quad F'(g(x)) = f(g(x))g'(x)$$

$$\frac{d}{dx} \left(\int_{a(x)}^{b(x)} f(t) dt \right) = f(b(x))b'(x) - f(a(x))a'(x)$$

$$\frac{d}{dx} \left(\int_{a(x)}^{b(x)} f(x, t) dt \right) = f(x, b(x))b'(x) - f(x, a(x))a'(x) + \int_{a(x)}^{b(x)} \frac{\partial}{\partial x} f(x, t) dt$$

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- [1] <http://en.wikipedia.org/>
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- [4] D. G. Zill, W. S. Wright, “Advanced Engineering Mathematics”
- [5] www.chem.arizona.edu/~salzmanr/480a