# Quizbank/Electricity and Magnetism (calculus based)/Equations

- These equations<sup>[1]</sup> can be given to students as they take chapter quizzes based on examples in the textbook **OpenStax University Physics**
- A study guide for these quizzes can be found at Quizbank/Electricity and Magnetism (calculus based)
- Most solutions for the questions can be found by reading the examples in Unit 2 of the <u>textbook</u>. (https://cnx.org/contents/eg-X cBxE@10.1:Gofkr9Oy@18/Preface)

#### **Chapter 5**

$$\epsilon_0 = 8.85 \times 10^{-12} \, \text{F/m} = \text{vacuum permittivity}.$$

e =  $1.602 \times 10^{-19}$ C: negative (positive) charge for electrons (protons)

$$ec{F}=Qec{E}$$
 where  $ec{E}=rac{1}{4\piarepsilon_0}\sum_{i=1}^{N}rac{q_i}{r_{Pi}^2}\hat{r}_{Pi}$ 

## Chapter 6

$$\Phi = ec{E} \cdot ec{A} 
ightarrow \int ec{E} \cdot dec{A} = \int ec{E} \cdot \hat{n} \, dA$$
 = electric flux

$$q_{enclosed} = arepsilon_0 \oint ec{E} \cdot dec{A}$$

$$d\operatorname{Vol} = dxdydz = r^2drdA$$
 where  $dA = r^2d\phi d\theta$ 

$$A_{
m sphere} = r^2 \int_0^\pi \sin heta d heta \int_0^{2\pi} d\phi = 4\pi r^2$$

 $ec{E}=\intrac{dq}{r^2}\hat{r}$  where  $dq=\lambda d\ell=\sigma da=
ho dV$ 

 $E=rac{\sigma}{2arepsilon_0}$  = field above an infinite plane of charge.

$$\Delta V_{AB} = V_A - V_B = -\int_A^B ec{E} \cdot dec{\ell}$$
 = electric potential

$$ec{E} = -rac{\partial V}{\partial x}\hat{i} - rac{\partial V}{\partial y}\hat{j} - rac{\partial V}{\partial z}\hat{k} = -ec{
abla}V$$

 $q\Delta V$  = change in potential energy

Electron (proton) mass =  $9.11 \times 10^{-31} \text{kg} (1.67 \times 10^{-27} \text{kg})$ .

$$K = \frac{1}{2}mv^2$$
 = kinetic energy. 1 eV = 1.602×10<sup>-19</sup>J

 $V(r)=krac{q}{r}$  near isolated point charge

Many charges: 
$$V_P = k \sum_1^N rac{q_i}{r_i} 
ightarrow k \int rac{dq}{r}.$$

 $u = \frac{1}{2}QV = \frac{1}{2}CV^2 = \frac{1}{2C}Q^2$  = stored energy

#### **Chapter 8**

$$Q = CV$$
 defines capacitance.

 $C=arepsilon_0rac{A}{d}$  where A is area and d<<A^{1/2} is gap length of parallel plate capacitor

th of parallel 
$$u_E=rac{1}{2}arepsilon_0 E^2$$
 = energy density

Series: 
$$\frac{1}{C_S} = \sum \frac{1}{C_i}$$
. Parallel:  $C_P = \sum C_i$ .

#### **Chapter 9**

Electric current: 1 Amp (A) = 1 Coulomb (C) per second (s)

Current= $I = dQ/dt = nqv_dA$ , where

 $(n, q, v_d, A)$  = (density, charge, speed, Area)

$$I = \int ec{J} \cdot dec{A}$$
 where  $ec{J} = n q ec{v}_d$  = current density.

$$ec{E} = 
ho ec{J}$$
 = electric field where  $ho$  = resistivity

$$\rho = \rho_0 [1 + \alpha (T - T_0)], \text{ and } R = R_0 [1 + \alpha \Delta T],$$

where  $R = \rho \frac{L}{4}$  is resistance

$$V=IR$$
 and Power= $P=IV=I^2R=V^2/R$ 

## Chapter 10

 $V_{terminal} = \varepsilon - Ir_{eq}$  where  $r_{eq}$ =internal resistance and  $\varepsilon$ =emf.

$$R_{series} = \sum_{i=1}^{N} R_i$$
 and  $R_{parallel}^{-1} = \sum_{i=1}^{N} R_i^{-1}$ 

Kirchhoff Loop: 
$$\sum I_{in} = \sum I_{out}$$
 and Junction:  $\sum V = 0$ 

Charging an RC (resistor-capacitor) circuit:  $q(t)=Q\left(1-e^{t/\tau}\right)$  and  $I=I_0e^{-t/\tau}$  where  $\tau=RC$  is RC time,  $Q=\varepsilon C$  and  $I_0=\varepsilon/R$ .

Discharging an RC circuit: 
$$q(t) = Qe^{-t/ au}$$
 and  $I(t) = -rac{Q}{RC}e^{-t/ au}$ 

## Chapter 11

$$|\vec{a} \times \vec{b}| = ab \sin \theta \Leftrightarrow$$

$$(\vec{a}\times\vec{b})_x=(a_yb_z-a_zb_y),$$

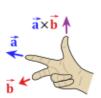
$$(\vec{a}\times\vec{b})_y=(a_zb_x-a_xb_z),$$

$$(\vec{a} \times \vec{b})_z = (a_x b_y - a_y b_x)$$

Magnetic force:  $\vec{F} = a\vec{v} \times \vec{B}$ .

$$d\vec{F} = I \overrightarrow{d\ell} \times \vec{B}$$
.

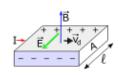
 $ec{v}_d = ec{E} imes ec{B}/B^2$  = EXB drift velocity



cross product

Circular motion (uniform B field):  $r = \frac{mB}{qB}$ . Period= $T = \frac{2\pi m}{qB}$ .

$$\begin{array}{l} \underline{\text{Dipole moment}} = \vec{\mu} = NIA\hat{n}. \ \ \underline{\text{Torque}} = \\ \vec{\tau} = \vec{\mu} \times \vec{B}. \ \text{Stored energy} = U = \vec{\mu} \cdot \vec{B}. \\ \underline{\text{Hall field}} = E = V/\ell = Bv_d = \frac{IB}{neA} \end{array}$$



Hall effect

#### Chapter 12

Free space permeability  $\mu_0 = 4\pi \times 10^{-7} \ \text{T} \cdot \text{m/A}$ Force between parallel wires  $\frac{F}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi r}$ 

Biot-Savart law 
$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{Id\vec{\ell} \times \hat{r}}{r^2}$$

(find's field at center of loop)

Ampère's Law:  $\oint \vec{B} \cdot d\vec{\ell} = 4\pi \mu_0 I_{enc}$  (for straight wire, solenoid, toroid)

Magnetic field inside solenoid with <u>paramagnetic</u> material =  $B = \mu nI$  where  $\mu = (1 + \chi)\mu_0$  = permeability

#### Chapter 13

Magnetic flux 
$$\Phi_m = \int_S \vec{B} \cdot \hat{n} dA$$

Motional  $\boldsymbol{\varepsilon} = \boldsymbol{B} \boldsymbol{\ell} \boldsymbol{v}$  if  $\vec{\boldsymbol{v}} \perp \vec{\boldsymbol{B}}$ 

Electromotive "force" (volts) 
$$\varepsilon = -N \frac{d\Phi_m}{dt} = \oint \vec{E} \cdot d\vec{\ell}$$

rotating coil  $\varepsilon = NBA\omega\sin\omega t$ 

## Chapter 14

Unit of inductance = Henry (H)= $1V \cdot s/A$ 

Mutual inductance:  $M\frac{dI_2}{dt}=N_1\frac{d\Phi_{12}}{dt}=-\varepsilon_1$  where  $\Phi_{12}$ =flux through 1 due to current in 2. Reciprocity:  $M\frac{dI_1}{dt}=-\varepsilon_2$ 

Self-inductance: 
$$N\Phi_m = LI 
ightarrow arepsilon = -Lrac{dI}{dt}$$

$$I(t) = rac{arepsilon}{R} \left( 1 - e^{-t/ au} 
ight)$$
 in LR circuit where  $au = L/R$  .

$$L_{
m solenoid} pprox \mu_0 N^2 A \ell, \;\; L_{
m toroid} pprox rac{\mu_0 N^2 h}{2\pi} \ln rac{R_2}{R_1}, \;\; {
m Stored} \;\; {
m energy} = rac{1}{2} L I^2$$

$$q(t)=q_0\cos(\omega t+\phi)$$
 in LC circuit where  $\omega=\sqrt{rac{1}{LC}}$ 

## Chapter 15

AC voltage and current 
$$v = V_0 \sin(\omega t - \phi)$$
 if  $i = I_0 \sin \omega t$ .

RMS values 
$$I_{rms} = \frac{I_0}{\sqrt{2}}$$
 and  $V_{rms} = \frac{V_0}{\sqrt{2}}$ 

Impedance  $V_0 = I_0 X$ 

Resistor 
$$V_0 = I_0 X_R$$
,  $\phi = 0$ , where  $X_R = R$ 

Capacitor 
$$V_0 = I_0 X_C$$
,  $\phi = -\frac{\pi}{2}$ , where  $X_C = \frac{1}{\omega C}$ 

Inductor 
$$V_0 = I_0 X_L$$
,  $\phi = +\frac{\pi}{2}$ , where  $X_L = \omega L$ 

RLC series circuit 
$$V_0 = I_0 Z$$
 where  $Z = \sqrt{R^2 + \left(X_L^2 - X_C^2\right)}$ 

and 
$$\phi = an^{-1} rac{X_L - X_C}{R}$$

Resonant angular frequency  $\omega_0 = \sqrt{\frac{1}{LC}}$ 

Quality factor  $Q = \frac{\omega_0}{\Delta \omega} = \frac{\omega_0 L}{R}$ 

Average power  $P_{ave}=rac{1}{2}I_0V_0\cos\phi=I_{rms}V_{rms}\cos\phi$ , where  $\phi=0$  for a resistor.

Transformer voltages and currents  $\frac{V_S}{V_P} = \frac{N_S}{N_P} = \frac{I_P}{I_S}$ 

## **Chapter 16**

Displacement current 
$$I_d = arepsilon_0 rac{d\Phi_E}{dt}$$
 where  $\Phi_E = \int \vec{E} \cdot d\vec{A}$  is the electric flux.

Maxwell's equations: 
$$\epsilon_0 \mu_0 = 1/c^2$$

$$\oint_S ec{E} \cdot \mathrm{d}ec{A} = rac{1}{\epsilon_0} Q_{in}$$
 $\oint_S ec{B} \cdot \mathrm{d}ec{A} = 0$ 

$$egin{aligned} \oint_C ec{E} \cdot \mathrm{d}ec{\ell} &= -\int_S rac{\partial ec{B}}{\partial t} \cdot \mathrm{d}ec{A} \ \oint_C ec{B} \cdot \mathrm{d}ec{\ell} &= \mu_0 I + \epsilon_0 \mu_0 rac{\mathrm{d}\Phi_E}{\mathrm{d}t} \end{aligned}$$

$$rac{\partial^2 E_y}{\partial x^2} = arepsilon_0 \mu_0 rac{\partial^2 E_y}{\partial t^2} ext{ and } rac{E_0}{B_0} = c$$

Poynting vector  $\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = \underline{\text{energy flux}}$ 

Average intensity 
$$I=S_{ave}=rac{carepsilon_0}{2}E_0^2=rac{c}{2\mu_0}B_0^2=rac{1}{2\mu_0}E_0B_0$$

Radiation pressure p = I/c (perfect absorber) and p = 2I/c (perfect reflector).

 transclusions between OpenStax\_University\_Physics/E&M#Index and Quizbank/Electricity and Magnetism (calculus based)/Equations

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