

# HW Butterfly FFT Sine/Cosine Generator

20170805

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# Wilson ROM based Sine/Cosine Generation

[24] Fu & Willson Sine / Cosine Generation

ROM-based

For high resolution, ROM size grows exponentially

Quarter-wave symmetry

$$\sin \theta = \cos \left( \frac{\pi}{2} - \theta \right)$$

$$\phi \in [0, 2\pi] \longrightarrow [0, \frac{\pi}{4}]$$

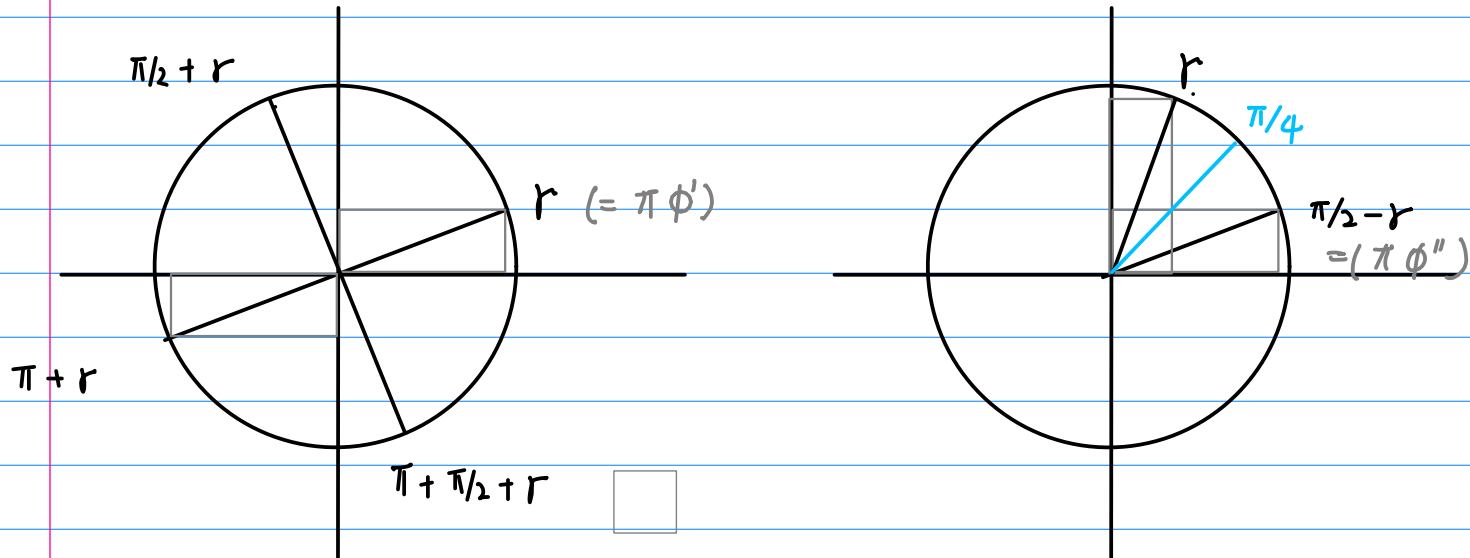
conditionally interchanging inputs  $X_0$  &  $Y_0$

conditionally interchanging and negating outputs  $X$  &  $Y$

$$X = X_0 \cos \phi - Y_0 \sin \phi$$

$$Y = Y_0 \cos \phi + X_0 \sin \phi$$

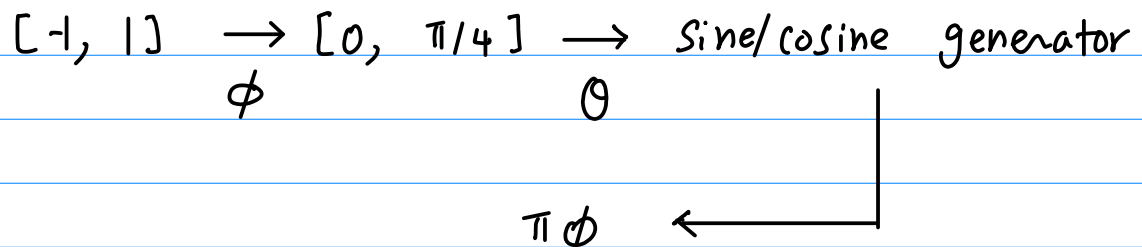
Madisetti VLSI arch



for frequency synthesis

Argument: signed normalized by  $\pi$  angle  $[-1, 1]$

binary representation of a radian angle required



- ① a phase accumulator  $\phi \in [-1, 1]$
- ② a radian converter  $\phi \rightarrow \theta$
- ③ a sine/cosine generator
- ④ an output stage

$$\begin{array}{cc} \sin \theta, & \cos \theta \\ \sin \theta, & \cos \theta \\ \downarrow & \downarrow \\ \sin \pi\phi & \cos \pi\phi \end{array}$$

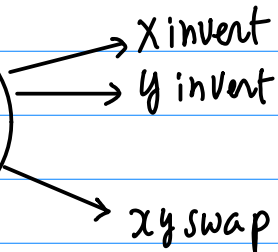
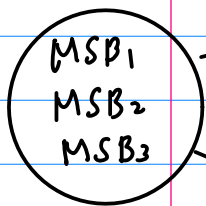
.

Output stage

$$\begin{aligned} \sin \theta &\rightarrow \sin \pi \phi \\ \cos \theta &\rightarrow \cos \pi \phi \end{aligned}$$

$[-\pi, +\pi]$

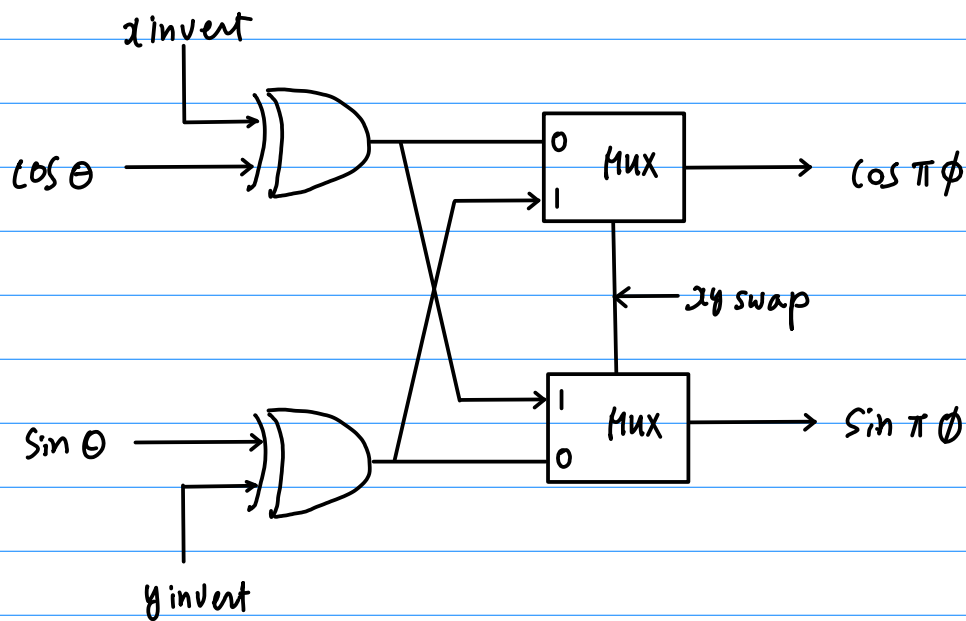
negation / interchange

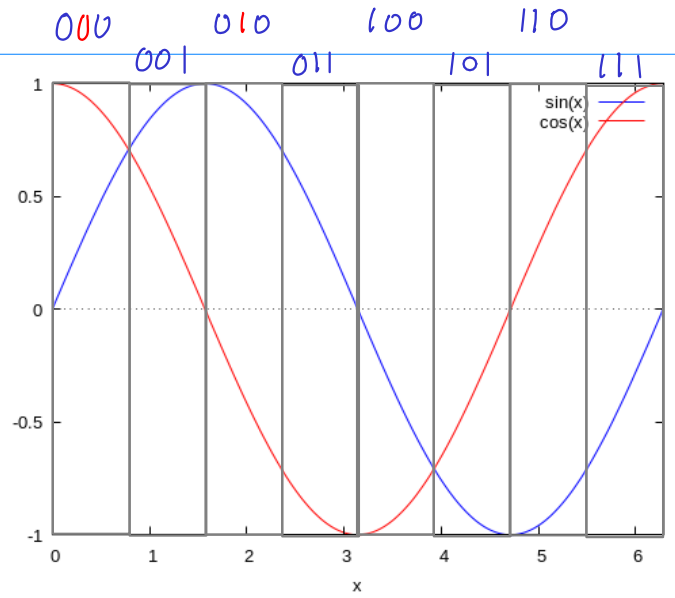
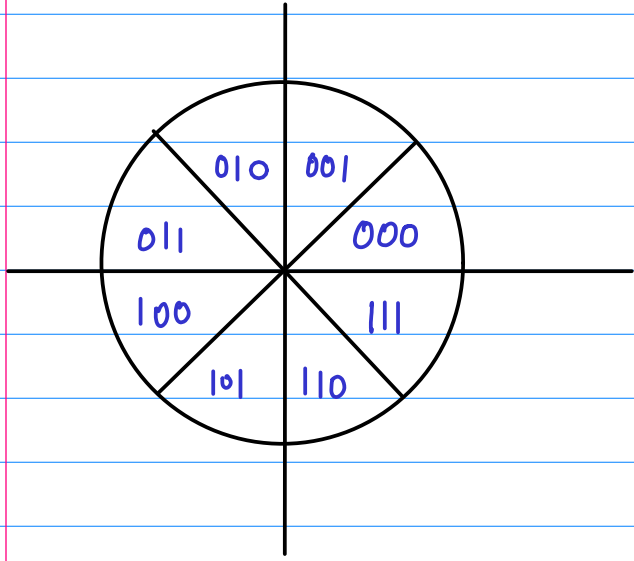


the negation of  $\cos \theta = X_{N+1}$   
 $\sin \theta = Y_{N+1}$

Interchange

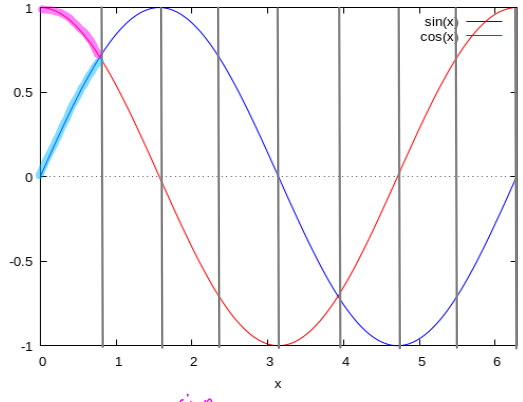
negate before swap



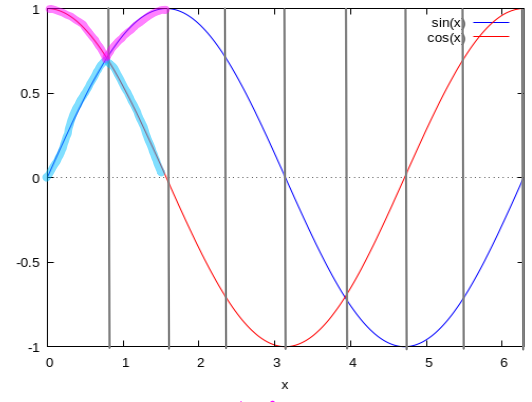


	cos	sin.			
	$x_{inv}$	$y_{inv}$	swap	$\cos \pi \theta$	$\sin \pi \theta$
000	0	0	0	$\cos \theta$	$\sin \theta$
001	0	0	1	$\sin \theta$	$\cos \theta$
010	0	1	1	$-\sin \theta$	$\cos \theta$
011	1	0	0	$-\cos \theta$	$\sin \theta$
100	1	1	0	$-\cos \theta$	$-\sin \theta$
101	1	1	1	$-\sin \theta$	$-\cos \theta$
110	1	0	1	$\sin \theta$	$-\cos \theta$
111	0	1	0	$\cos \theta$	$-\sin \theta$

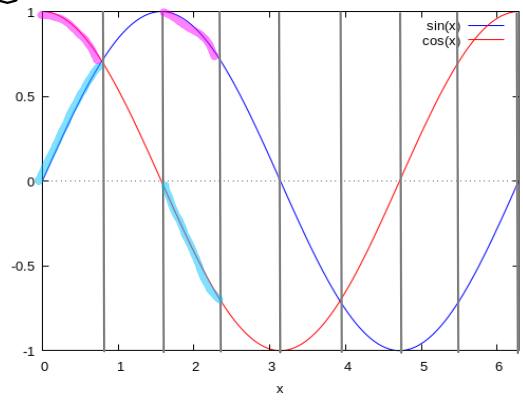
⑥  $\cos \theta$   
 $\sin \theta$



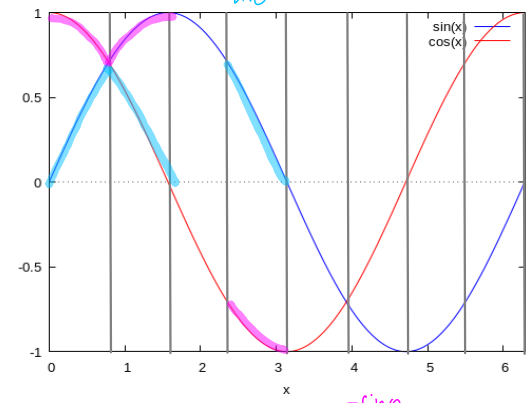
①  $\sin \theta$   
 $\cos \theta$



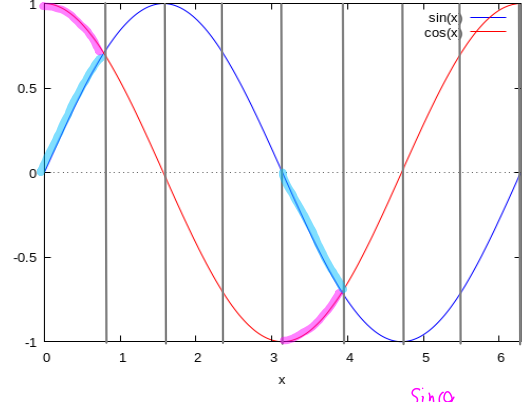
②  $-\sin \theta$   
 $\cos \theta$



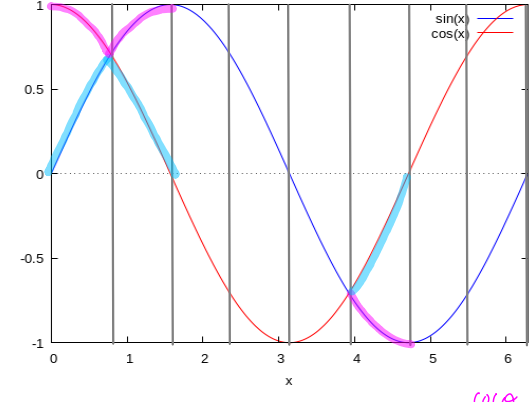
③  $-\cos \theta$   
 $\sin \theta$



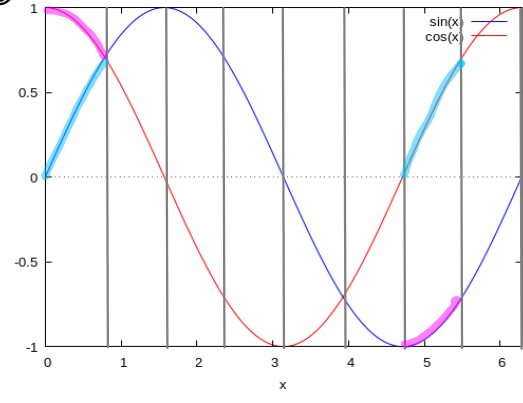
④  $-\cos \theta$   
 $-\sin \theta$



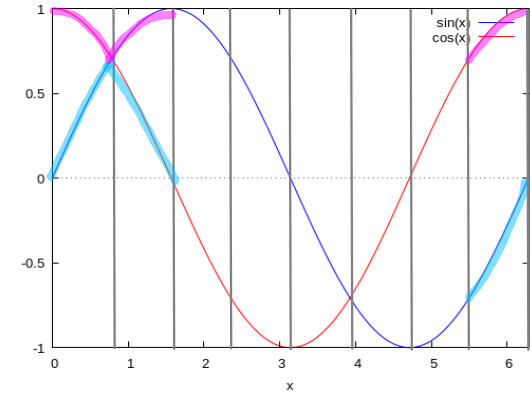
⑤  $-\sin \theta$   
 $-\cos \theta$



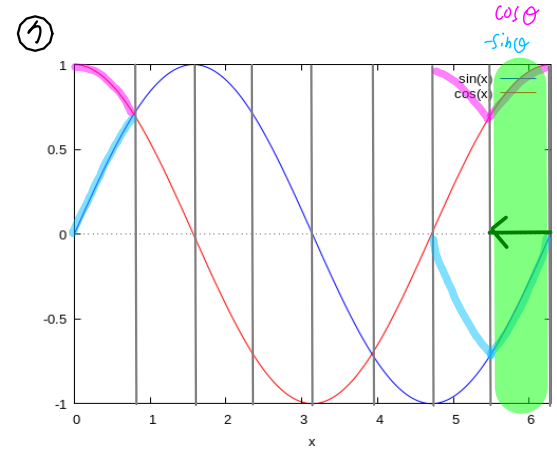
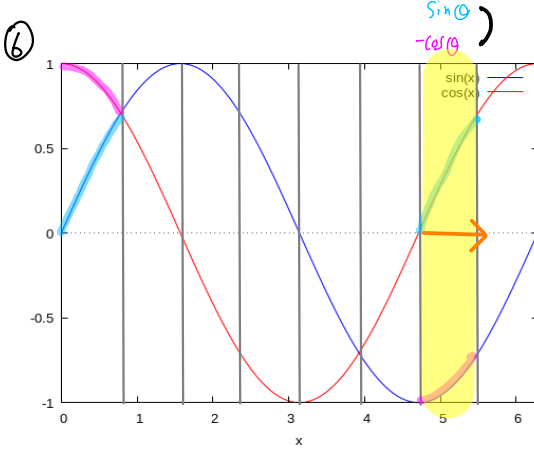
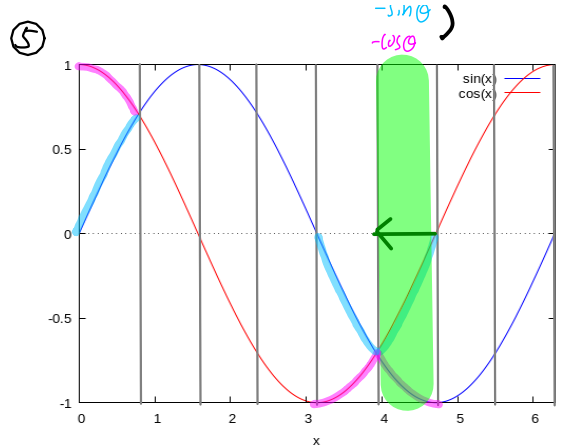
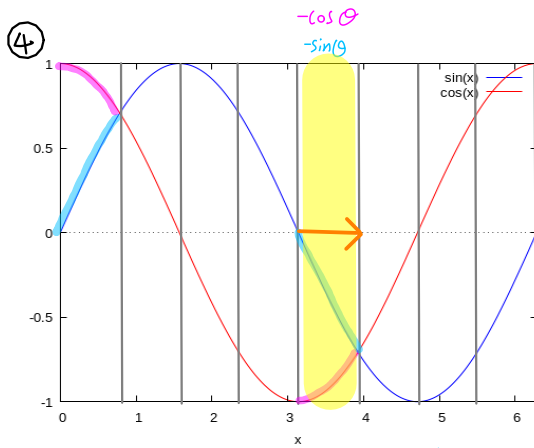
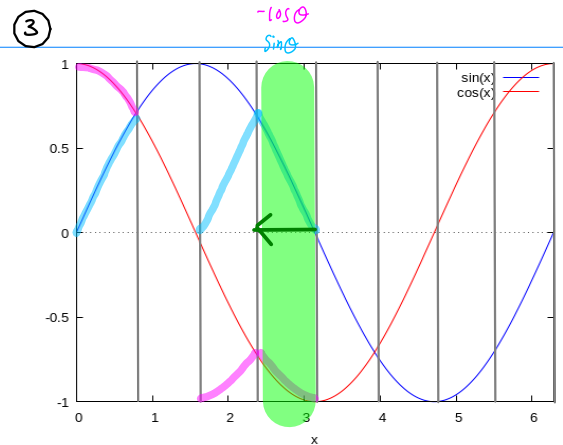
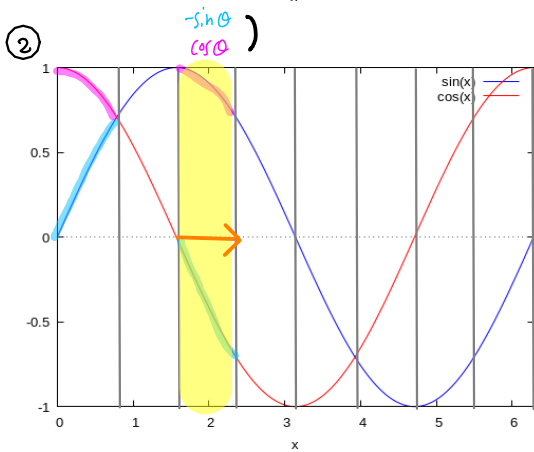
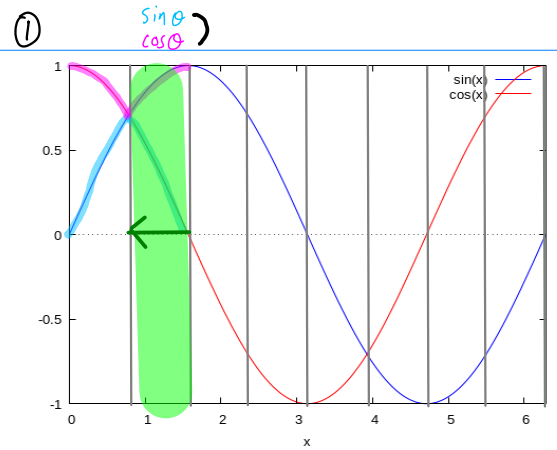
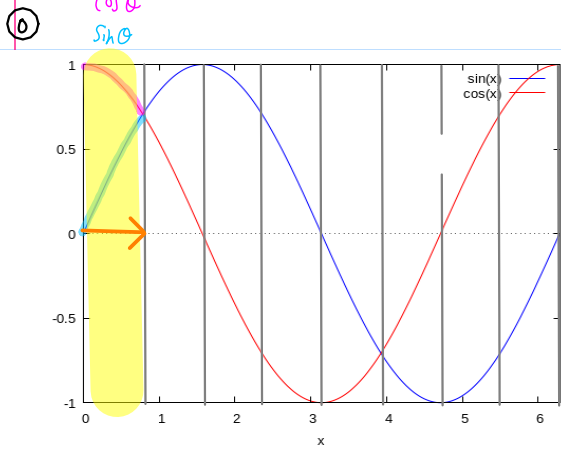
⑥  $\sin \theta$   
 $-\cos \theta$



⑦  $\cos \theta$   
 $-\sin \theta$

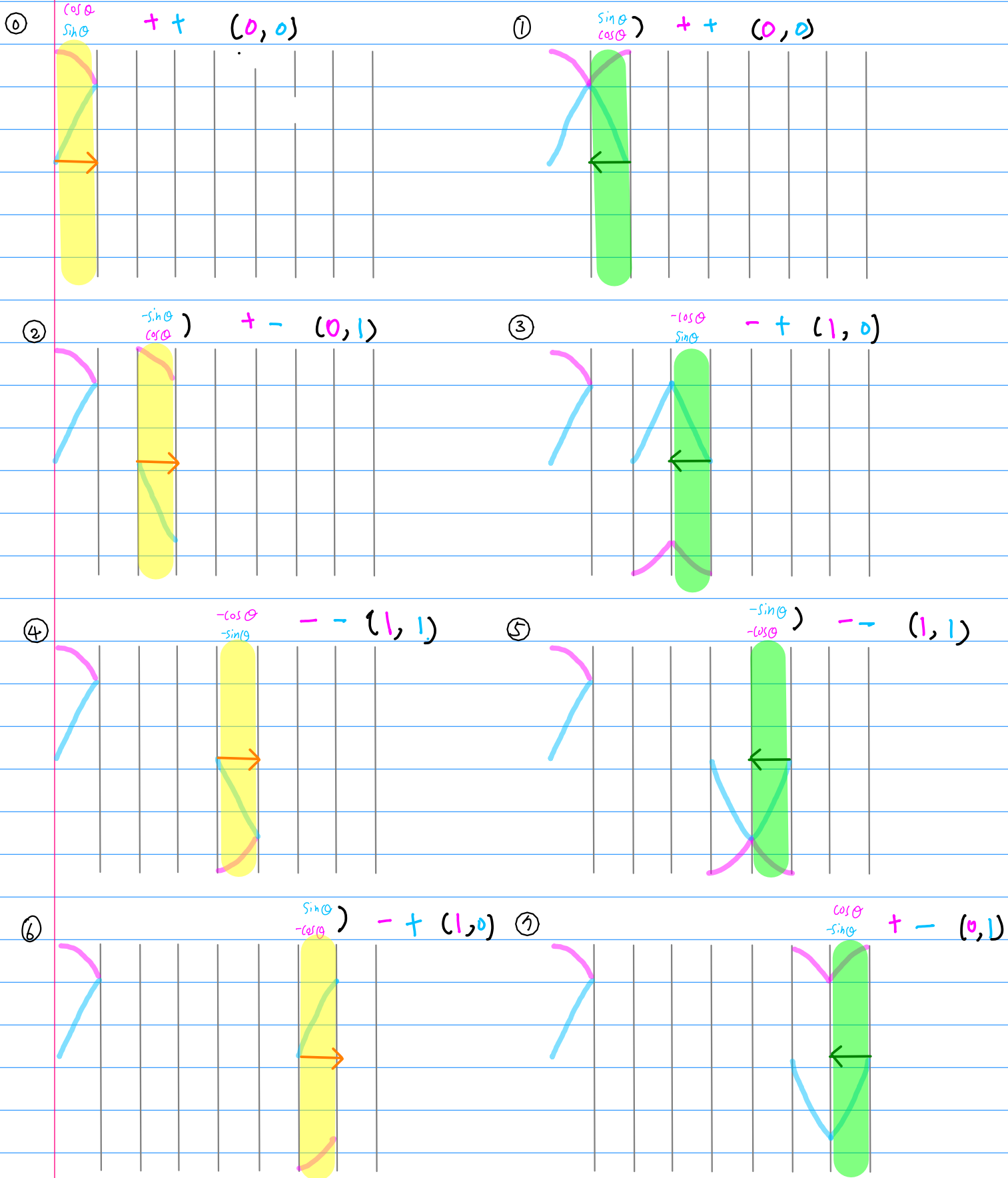


$\left\{ \begin{array}{l} \cos \phi \\ \sin \phi \end{array} \right.$





$\sin \phi$



	$x_{inv}$	$y_{inv}$	swap	$\cos \pi \phi$	$\sin \pi \phi$
0 0 0	0	0	0	$\cos \theta$	$\sin \theta$
0 0 1	0	0	1	$\sin \theta$	$\cos \theta$
0 1 0	0	1	1	$-\sin \theta$	$\cos \theta$
0 1 1	1	0	0	$-\cos \theta$	$\sin \theta$
1 0 0	1	1	0	$-\cos \theta$	$-\sin \theta$
1 0 1	1	1	1	$-\sin \theta$	$-\cos \theta$
1 1 0	1	0	1	$\sin \theta$	$-\cos \theta$
1 1 1	0	1	0	$\cos \theta$	$-\sin \theta$

0	0
0	0
0	1
1	0
1	1
1	0
0	1

0 0 0 0  
 0 1 1 0  
 1 1 1 1  
 1 0 0 1

$$\theta = \sum_{k=1}^N b_k \theta_k$$

$b_k$  sign + N bit — (N+1) bit fractional b

$$b_k \in \{0, 1\}$$

$$\theta_k = 2^{-k}$$

$\theta$  is constrained to be positive  $b_0 = 0$

$$\theta = \sum_{k=1}^N b_k 2^{-k} = \phi_0 + \sum_{k=2}^{N+1} r_k 2^{-k}$$

$r_k \in \{-1, +1\}$  signed digits

$\phi_0$  constant

⊕ subrotation by  $2^{-k}$

2 equal ⊕ half rotations by  $2^{-k-1}$

⊖ subrotation

2 equal opposite half rotations by  $\pm 2^{-k-1}$

## Binary Representation

$b_k = 1$  : rotation by  $2^{-k}$

$b_k = 0$  : zero rotation

$k$ -th rotation

fixed rotation by  $2^{-k-1}$

{ pos rotation  $\leftarrow b_k = 1$   
neg rotation  $\leftarrow b_k = 0$

Combining all the fixed rotations

→ initial fixed rotation

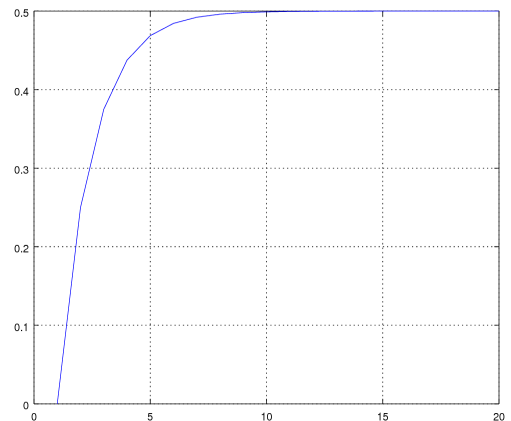
fixed  $\Rightarrow$

$b_1$	$b_2$	$b_3$		$b_N$
$2^{-1}$	$2^{-2}$	$2^{-3}$		$2^{-N}$
$+2^{-2}$	$+2^{-3}$	$+2^{-4}$		$+2^{-N-1}$
$(b_1=1)$ $+2^{-2}$	$(b_2=1)$ $+2^{-3}$	$(b_3=1)$ $+2^{-4}$		$(b_N=1)$ $+2^{-N-1}$
$(b_1=0)$ $-2^{-2}$	$(b_2=0)$ $-2^{-3}$	$(b_3=0)$ $-2^{-4}$		$(b_N=0)$ $-2^{-N-1}$

initial fixed rotation

$$\phi_0 = \frac{1}{2^2} + \frac{1}{2^3} + \dots + \frac{1}{2^{N+1}}$$

$$= \frac{\frac{1}{2^2} (1 - \frac{1}{2^N})}{(1 - \frac{1}{2})} = \frac{1}{2} \left(1 - \frac{1}{2^N}\right) = \frac{1}{2} - \frac{1}{2^{N+1}}$$



## Signed Digit Recoding

the rotation after recoding

— a fixed initial rotation  $\phi_0$

a sequence of  $\oplus/\ominus$  rotations

$b_k = 1$      $+ 2^{-k-1}$     rotation

$b_k = 0$      $- 2^{-k-1}$     rotation

$$r_k = (2b_{k-1} - 1)$$

$$2 \cdot 1 - 1 = +1$$

$$b_{k-1} = 1 \rightarrow r_k = +1$$

$$2 \cdot 0 - 1 = -1$$

$$b_{k-1} = 0 \rightarrow r_k = -1$$

The recoding need not be explicitly performed

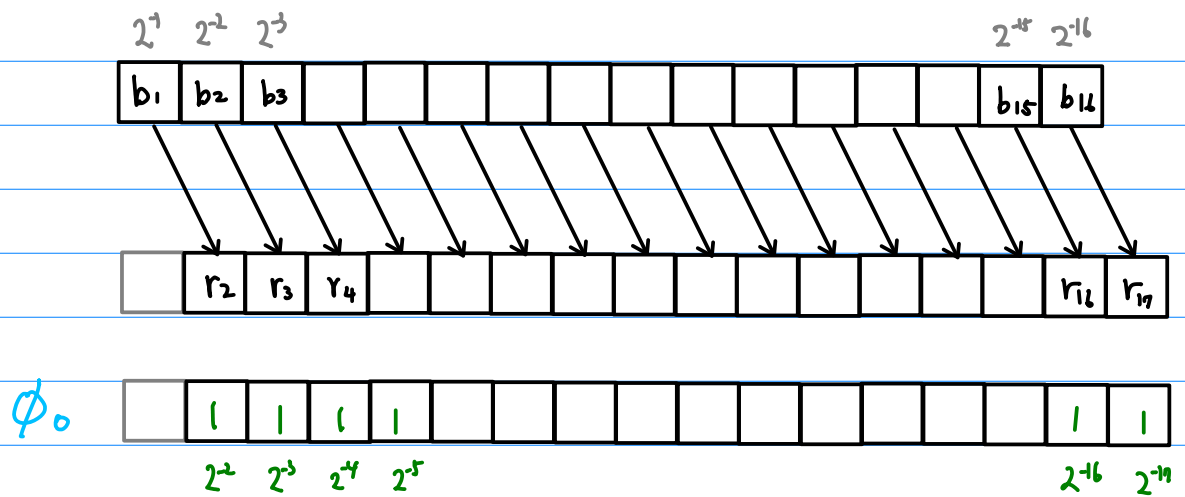
Simply replacing  $b_k = 0$  with  $\ominus$

This recoding maintains

a constant scaling factor  $\ll$

$$\theta = \sum_{k=1}^N b_k 2^{-k} = \phi_0 + \sum_{k=2}^{N+1} r_k 2^{-k}$$

Binary Representation  $\{b_k\}$



Signed Digit Recoding  $\{r_k\}$

The scaling  $K$ .

The initial rotation  $\phi_0$ .

rotation starting point

$$(X_0, Y_0) = (K \cos \phi_0, K \sin \phi_0)$$

— fixed

— no error buildup

— rotation direction

immediately obtained from the binary representation

→ no need for comparison

the subangles

$$\theta_k = 2^{-k}$$

used in recoding

the subangles

$$\theta_k = \tan^{-1}(2^{-k})$$

used in CORDIC

$\tan \theta_k$  multipliers used

in the first few subrotation stages

cannot be implemented

as a simple shift-and-add operations

→ ROM implementation

reduced chip area

higher operating speed.



# Architecture

- ① phase accumulator  $\phi \in [-1, +1]$
- ② radian converter  $\phi \rightarrow \theta \in [0, \frac{\pi}{4}]$
- ③ sine/cosine generator  $\sin(\theta)$   $\cos(\theta)$
- ④ output stage  $\sin(\pi\phi)$   $\cos(\pi\phi)$

Overflowing 2's complement accumulator

normalized by  $\pi$  angle  $\phi$

Need radian angle  $\theta \in [0, \frac{\pi}{4}]$

$0 < \theta < 1$  rad

N-bit binary representation of  $\theta$

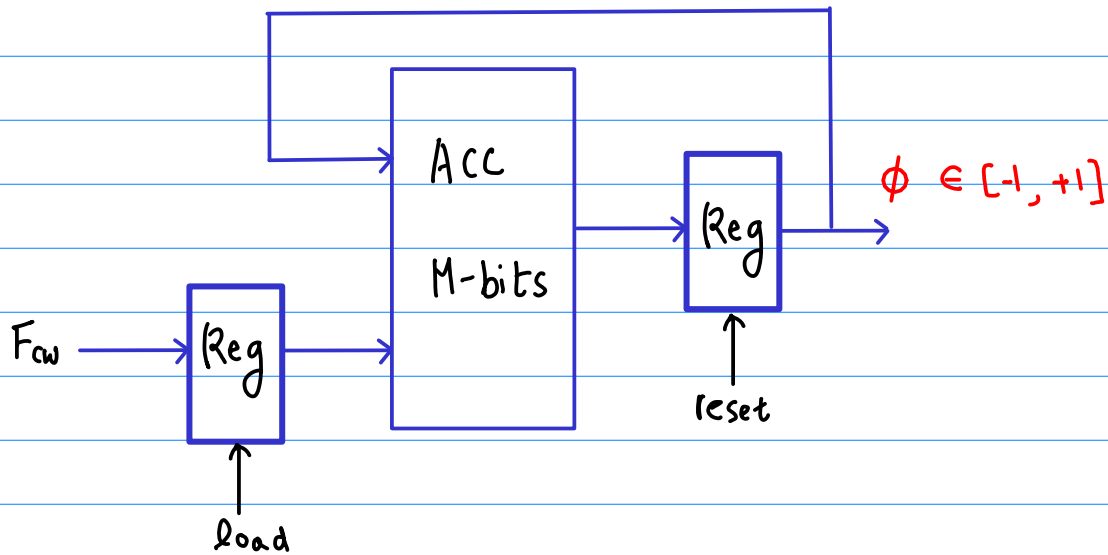
controls the direction of subrotation

N-bit precision of  $\cos \theta$  &  $\sin \theta$

Output stage

$\theta$	$\rightarrow$	$\pi \phi$
$\sin \theta$	$\rightarrow$	$\sin \pi \phi$
$\cos \theta$	$\rightarrow$	$\cos \pi \phi$

# phase accumulator



M-bit address

repeatedly increments the phase angle

by Fcw at each clock cycle

frequency control word

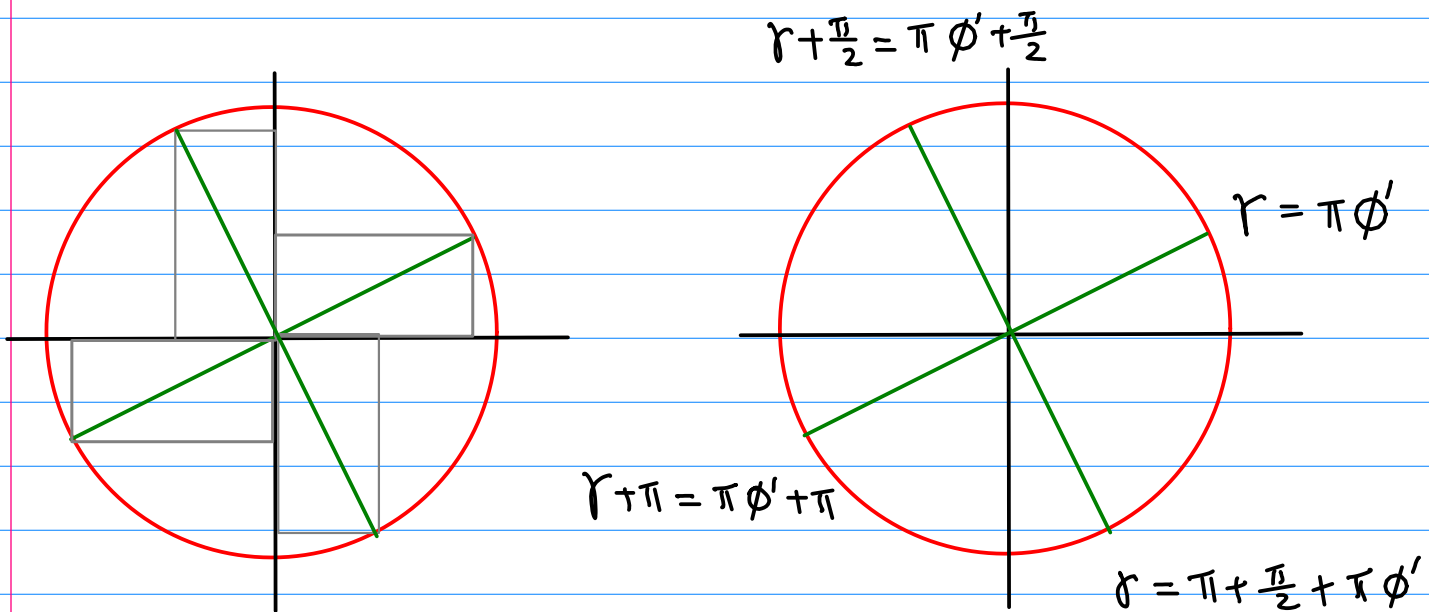
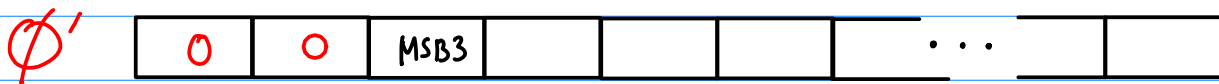
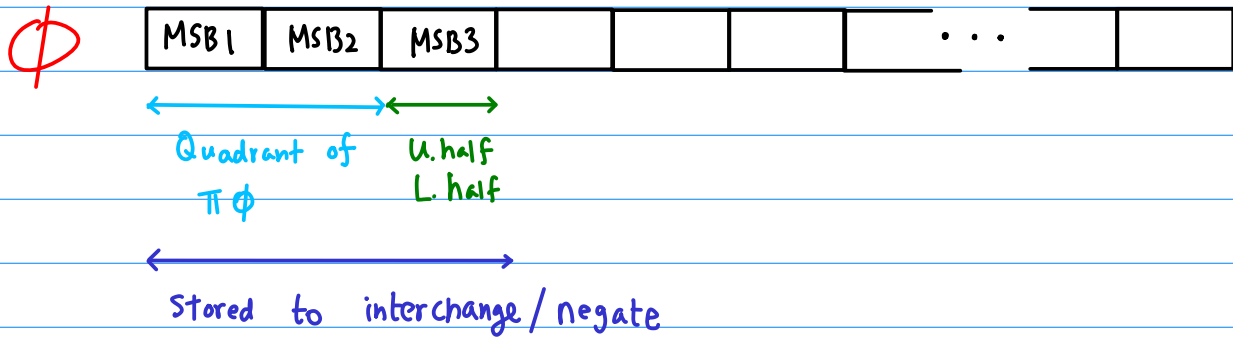
at time  $n$ ,  $\phi = n F_{cw} / 2^M$

$$\cos \phi = \cos (n F_{cw} / 2^M)$$

$$\sin \phi = \sin (n F_{cw} / 2^M)$$

# Radian Converter

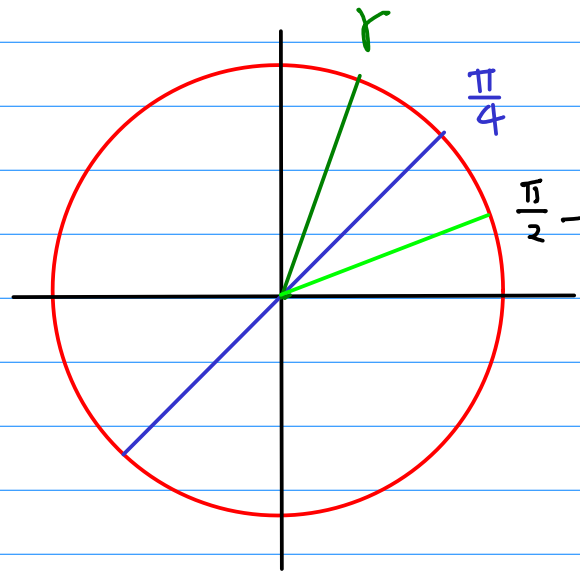
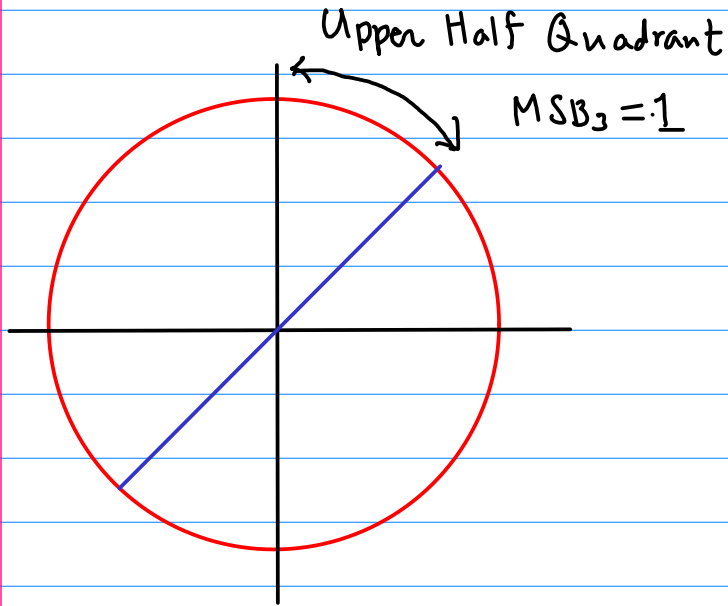
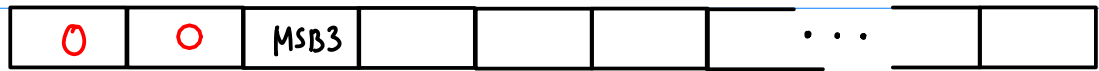
Normalized angle  $\phi$



$\phi$	$\rightarrow$	$\phi'$	$\rightarrow$	$\pi\phi'$	+	$0 \cdot \frac{\pi}{2}$	<b>00</b>
		$\uparrow$		$\pi\phi'$	+	$1 \cdot \frac{\pi}{2}$	<b>01</b>
		1st Quad		$\pi\phi'$	+	$2 \cdot \frac{\pi}{2}$	<b>10</b>
				$\pi\phi'$	+	$3 \cdot \frac{\pi}{2}$	<b>11</b>

# Ist Quadrant

$\phi'$



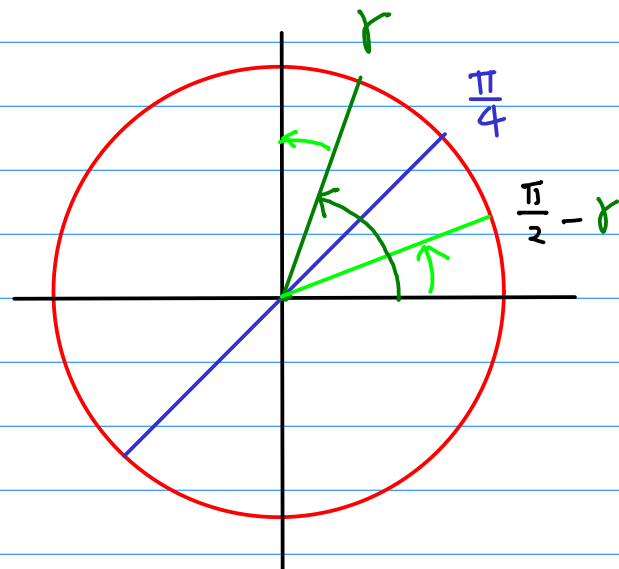
$r > \frac{\pi}{4}$  : Upper Half ( $MSB_3 = 1$ )

$r < \frac{\pi}{4}$  : Lower Half ( $MSB_3 = 0$ )

$$\cos r = \sin\left(\frac{\pi}{2} - r\right)$$

$$\sin r = \cos\left(\frac{\pi}{2} - r\right)$$

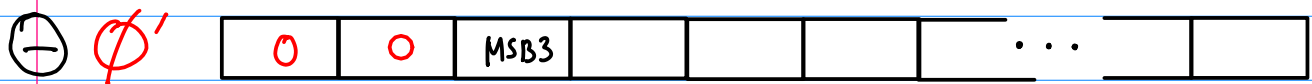
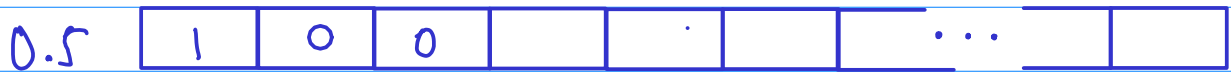
$$r > \frac{\pi}{4} \quad \frac{\pi}{2} - r < \frac{\pi}{4}$$





$MSB_3 = 1 \quad \phi' > \frac{\pi}{4}$

$\phi'' = \frac{\pi}{2} - \phi'$



$$\begin{cases} MSB_3 = 0 & \phi'' = \phi' \\ MSB_3 = 1 & \phi'' = 0.5 - \phi' \end{cases}$$

$\theta = \pi \phi''$  (Handwired Multiplier)

$0 < \theta < \frac{\pi}{4}$

$\phi \longrightarrow \phi' \longrightarrow \phi''$

1st Quad      Lower Half

# Sine / Cosine Generator

Subrotation

$$X_{k+1} = X_k - (r_k \tan \theta_k) Y_k$$

$$Y_{k+1} = Y_k + (r_k \tan \theta_k) X_k$$

$$\begin{bmatrix} X_\theta \\ Y_\theta \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

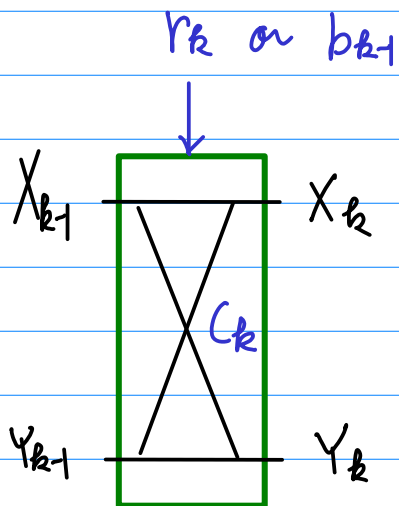
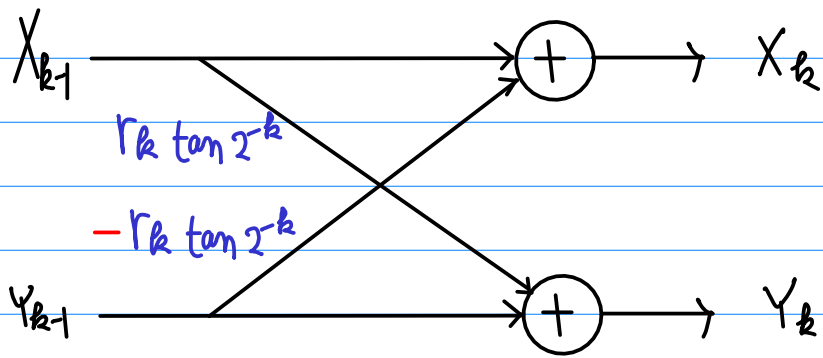
$$= \cos \theta \begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

$$\theta = \sigma_0 \theta_0 + \sigma_1 \theta_1 + \dots + \sigma_N \theta_N$$

$$\sigma_k = \{-1, 0, +1\}$$

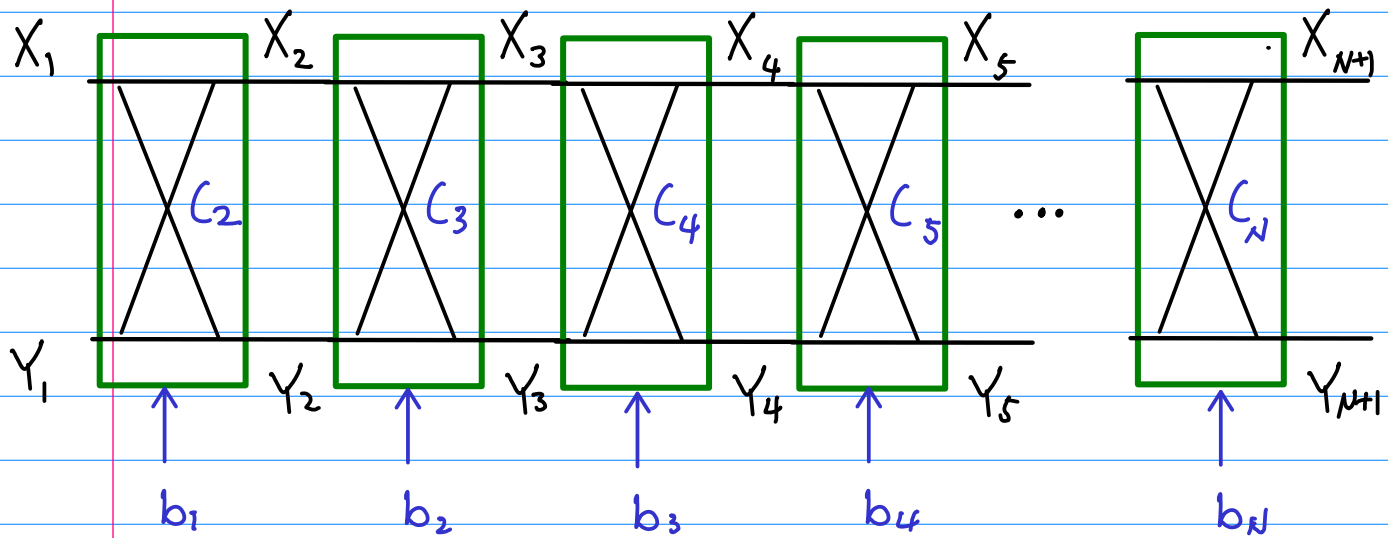
$$\begin{bmatrix} X_\theta \\ Y_\theta \end{bmatrix} = K \begin{bmatrix} 1 & -\tan \sigma_N \theta_N \\ \tan \sigma_N \theta_N & 1 \end{bmatrix} \dots \begin{bmatrix} 1 & -\tan \sigma_0 \theta_0 \\ \tan \sigma_0 \theta_0 & 1 \end{bmatrix} \begin{bmatrix} X_0 \\ Y_0 \end{bmatrix}$$

$$K = \cos \sigma_0 \theta_0 \cdot \cos \sigma_1 \theta_1 \dots \cos \sigma_N \theta_N$$



Butterfly





$$C_2 = \tan\left(\frac{1}{2^2}\right)$$

$$C_3 = \tan\left(\frac{1}{2^3}\right)$$

$$C_4 = \tan\left(\frac{1}{2^4}\right)$$

$$C_5 = \tan\left(\frac{1}{2^5}\right)$$

$$K \cos \phi_0 \rightarrow X_1$$

$$X_{N+1} \rightarrow \cos \theta$$

$$K \sin \phi_0 \rightarrow Y_1$$

$$Y_{N+1} \rightarrow \sin \theta$$

$$\theta \rightarrow \{b_1, b_2, \dots, b_N\}$$

the initial  $(X_0, Y_0)$  always the same

merge the first  $B/3$  butterflies

→  $2^{B/3}$  words ROM implementation

→ no need  $\tan \theta_k$  multipliers

→  $\{b_1, b_2, \dots, b_{B/3}\} \Rightarrow$  address

accesses

$$\cos \left( \phi_0 + \sum_{k=1}^{B/3} b_k 2^{-k+1} \right)$$

$$\sin \left( \phi_0 + \sum_{k=1}^{B/3} b_k 2^{-k+1} \right)$$

Lower Half of the 1st Quadrant

- all positive  $X_k$  &  $Y_k$
- no need sign extension
- reduce the loads
- high speed

## Merging Butterflies

merge  $m$  final butterflies

$$\begin{pmatrix} X_k \\ Y_k \end{pmatrix} \rightarrow \begin{pmatrix} X_{k+m} \\ Y_{k+m} \end{pmatrix} \text{ directly}$$

$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

valid merging  $k \gg (B-1)/2$

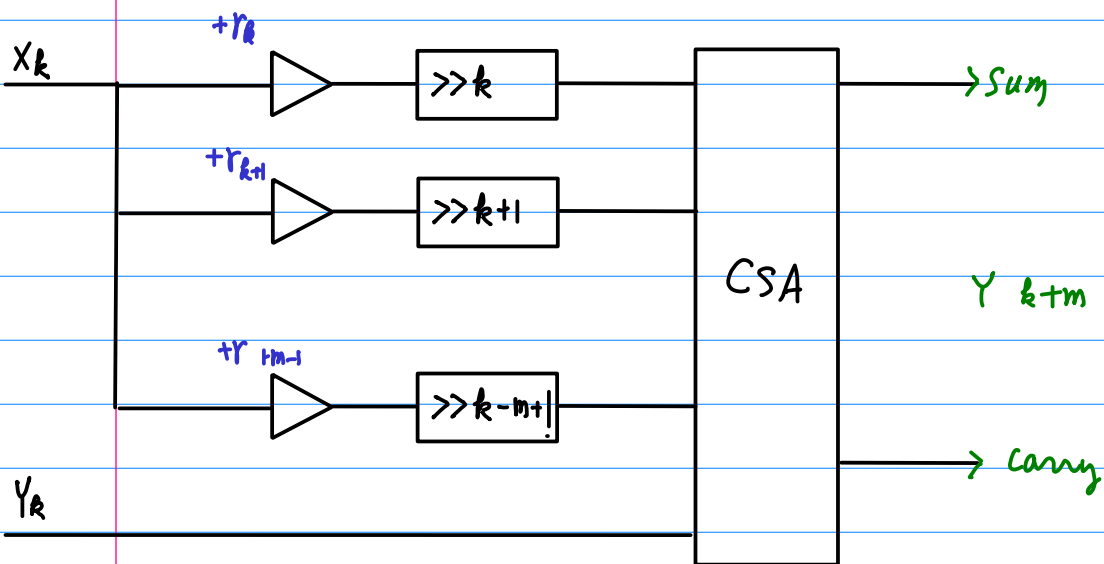
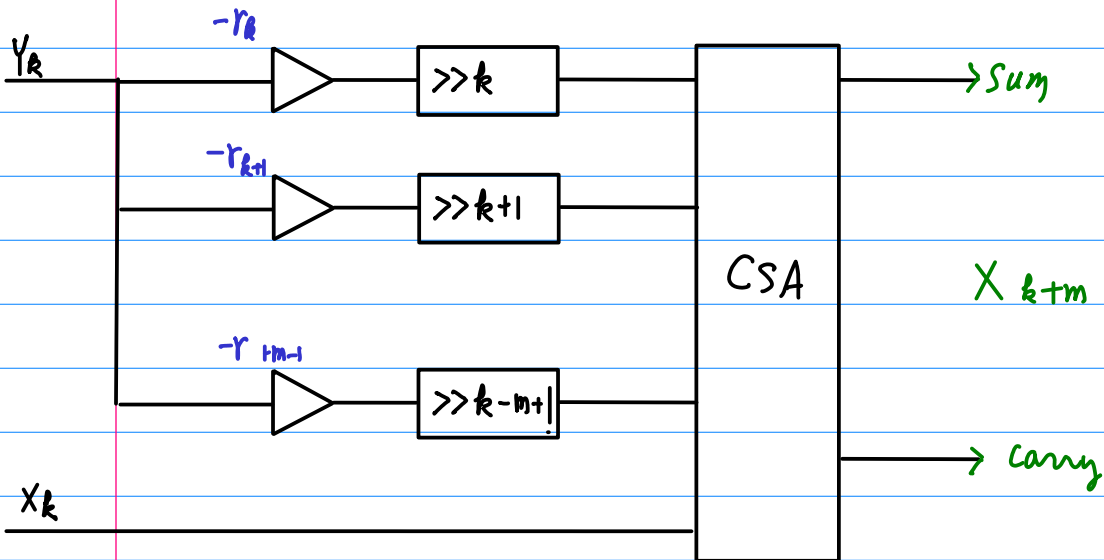
$$\tan(2^{-i}) = 2^{-i} \quad k \gg B/3$$

look ahead by  $m$

the individual terms in the summation  
can be computed independently  
and summed in parallel

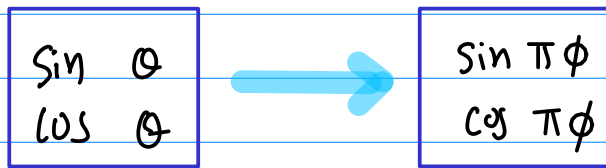
$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$



- + reduced latency
- + reduced routing
- + only the half for a single-ended system.

# Output Stage

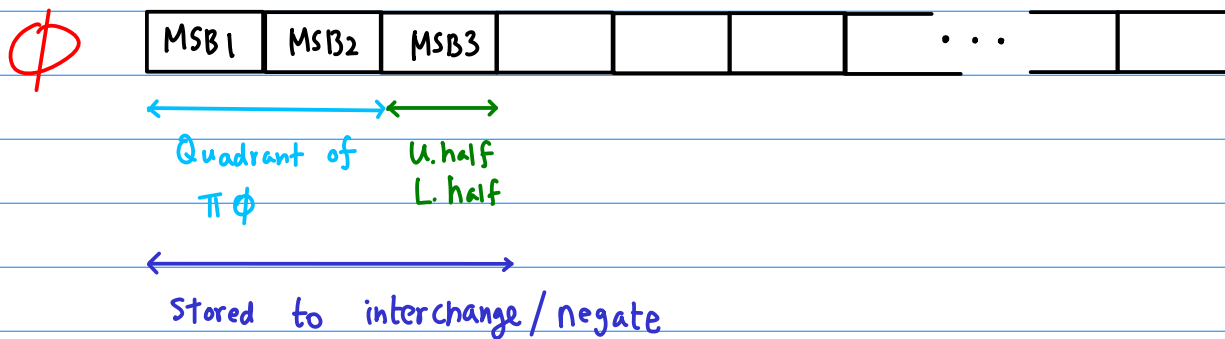


$$\theta \in [0, \frac{\pi}{4}] \longrightarrow \phi \in [1, +1]$$

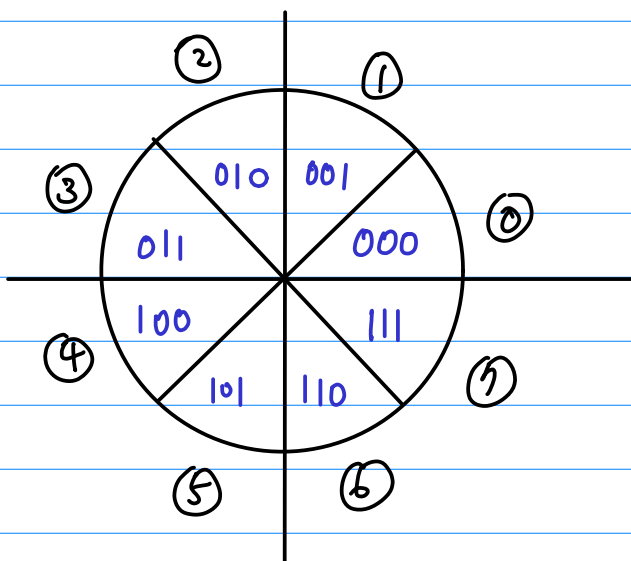
{ negation  
interchange

\* negation before interchange

Normalized angle  $\phi$



MSB of $\phi$	$\phi$	$X_{inv}$	$Y_{inv}$	Swap	$\cos \pi\phi$	$\sin \pi\phi$
0 0 0	⑥	0	0	0	$\cos \theta$	$\sin \theta$
0 0 1	①	0	0	1	$\sin \theta$	$\cos \theta$
0 1 0	②	0	1	1	$-\sin \theta$	$\cos \theta$
0 1 1	③	1	0	0	$-\cos \theta$	$\sin \theta$
1 0 0	④	1	1	0	$-\cos \theta$	$-\sin \theta$
1 0 1	⑤	1	1	1	$-\sin \theta$	$-\cos \theta$
1 1 0	⑦	1	0	1	$\sin \theta$	$-\cos \theta$
1 1 1	⑧	0	1	0	$\cos \theta$	$-\sin \theta$





# IC Implementation

clock: 100 MHz

acc: 36-bit (22-bit + 14-bit)

precision: 16-bit

advantage over traditional  
ROM lookup table approach

accumulator: 36-bit = 22-bit + 14-bit

carry select adder

Speed & layout consideration

36-bit output  $\rightarrow$  truncated to 22-bit

22-bit radian converter

$\pi/4$  multiplier

SDFR  $>$  100 dBc

19-bit ROM address

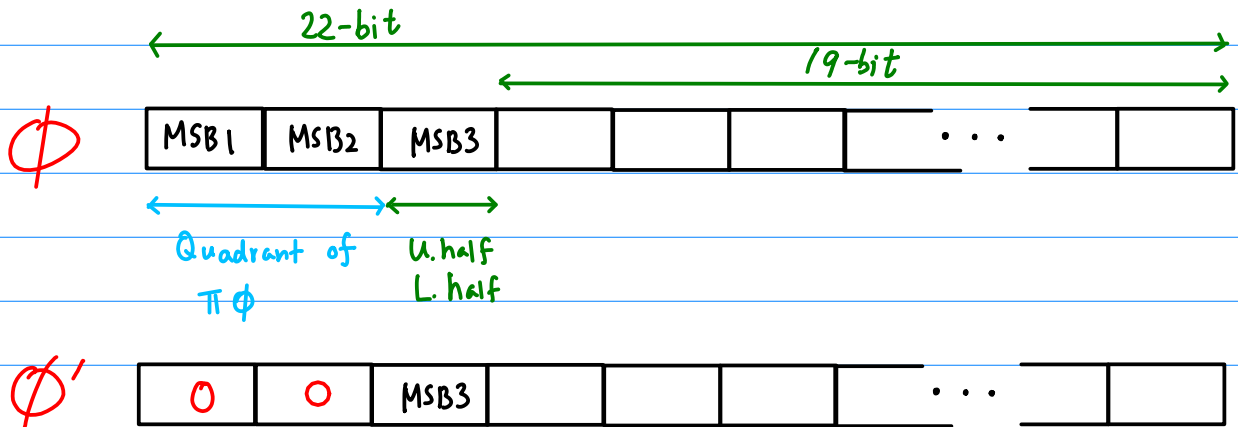
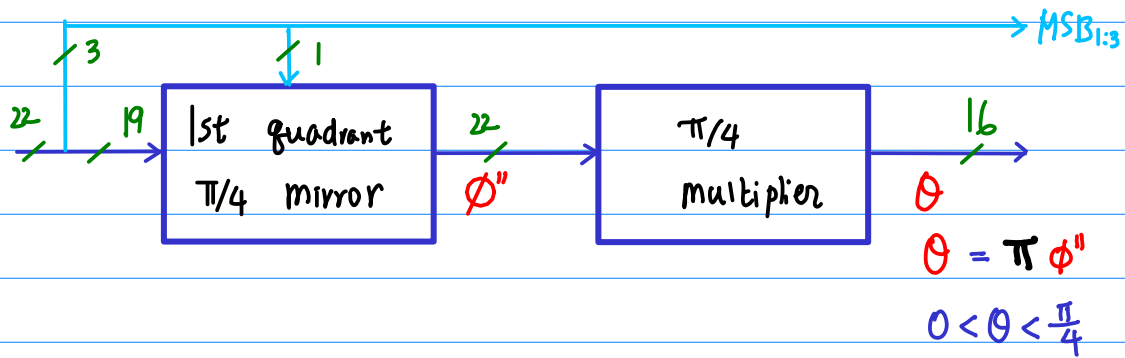
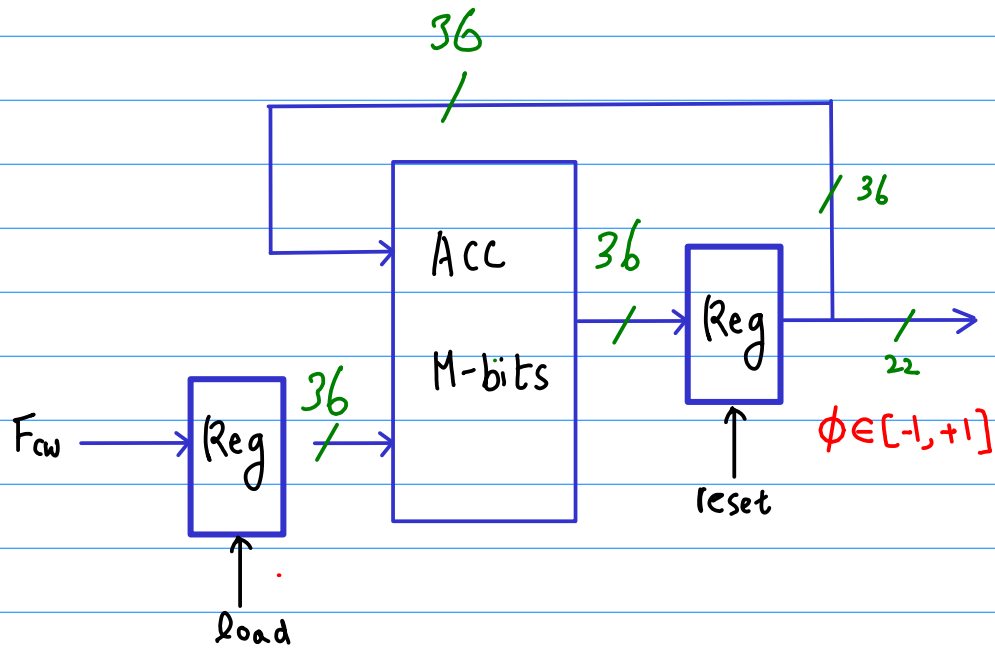
for the similar performance

$\Rightarrow$   $2^{19}$  words HUGE!

Coarse / fine ROM arch

[2] H. T. Nicholas and H. Samueli, "A 150 MHz direct digital frequency synthesizer in 1.25- $\mu$ m CMOS with -90 dBc spurious performance," *IEEE J. Solid-State Circuits*, vol. 26, pp. 1959-1969, Dec. 1991.





$\gamma > \frac{\pi}{4}$  : Upper Half ( $MSB_3 = 1$ )       $\phi'' = \phi'$   
 $\gamma < \frac{\pi}{4}$  : Lower Half ( $MSB_3 = 0$ )       $\phi'' = 0.5 - \phi'$

radian converter

$$\theta = \pi \phi''$$

all internal angle

~ represented as

fractional binary 2's complement numbers

$$\theta = (\pi/4) (4\phi'')$$

$$(\pi/4) = 2^{-1} + 2^{-2} + 2^{-5} + 2^{-8} + 2^{-12}$$

1	2	3	4	5	6	7	8	9	10	11	12
1	1	0	0	1	0	0	1	0	0	0	1

$$2^{-1} = 0.5$$

$$2^{-2} = 0.25$$

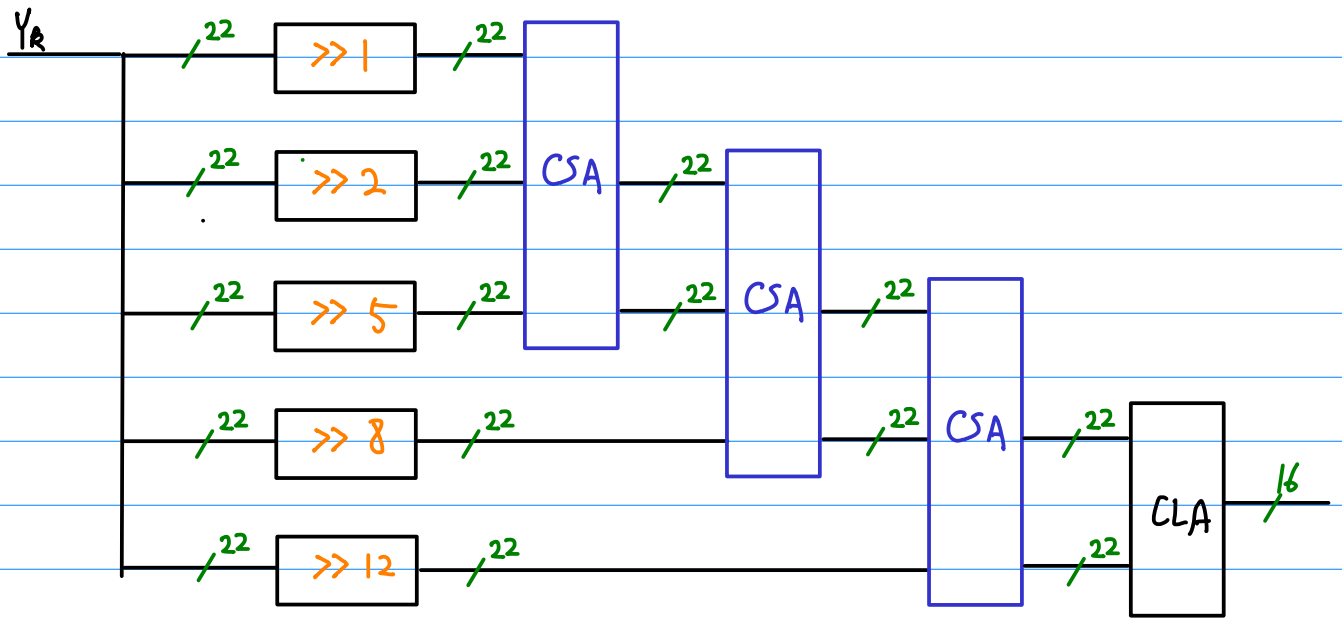
$$2^{-5} = 0.3125$$

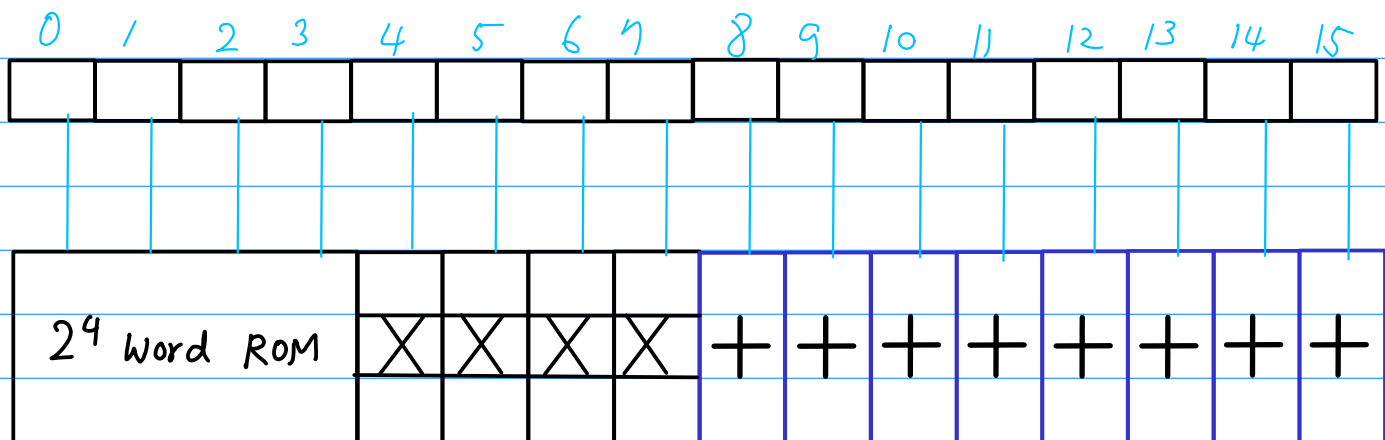
$$2^{-8} = 0.00390625$$

$$2^{-12} = 0.000244141$$

$$\pi/4 = 0.785398163 = 0.785400391$$

only 1st 5 partial products

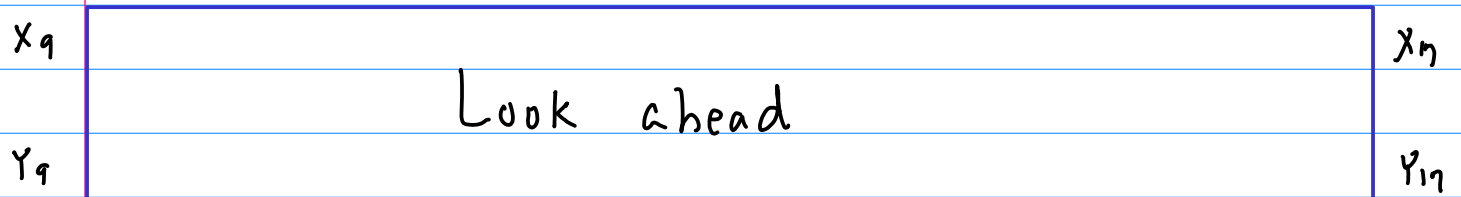
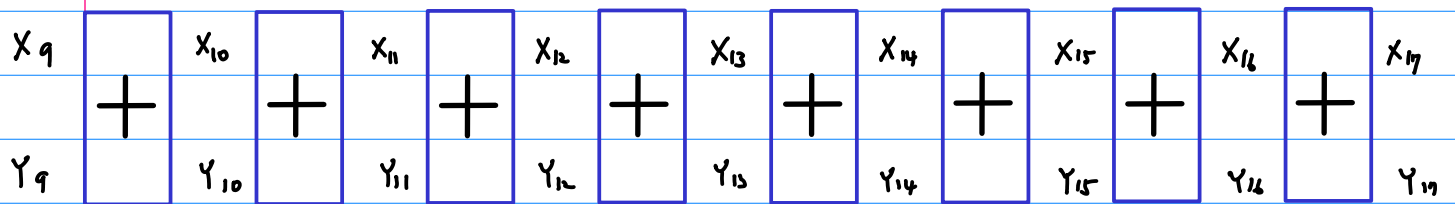




1st 4 stages

4 butterfly stages

8 Lookahead stages

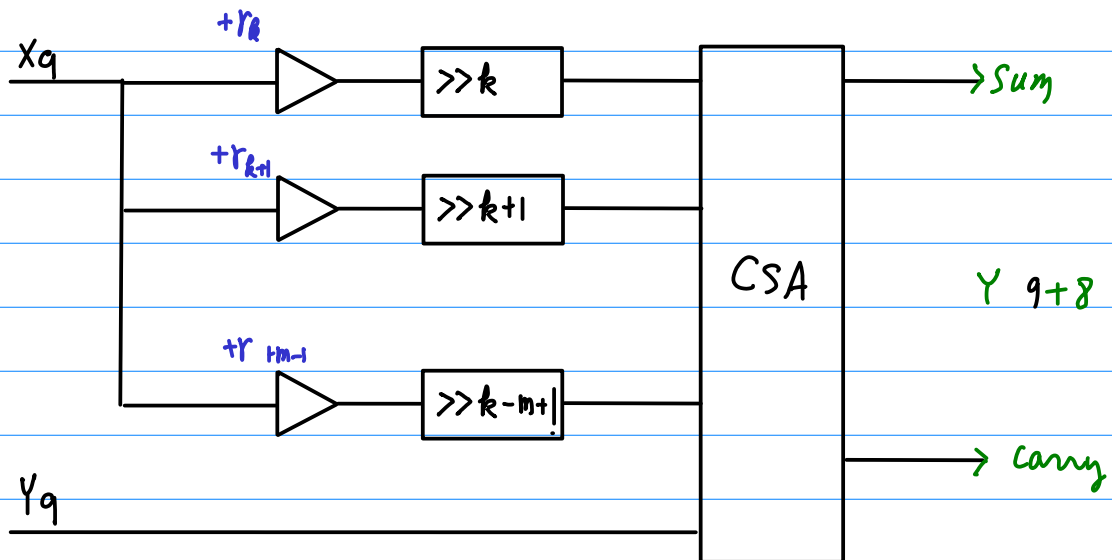
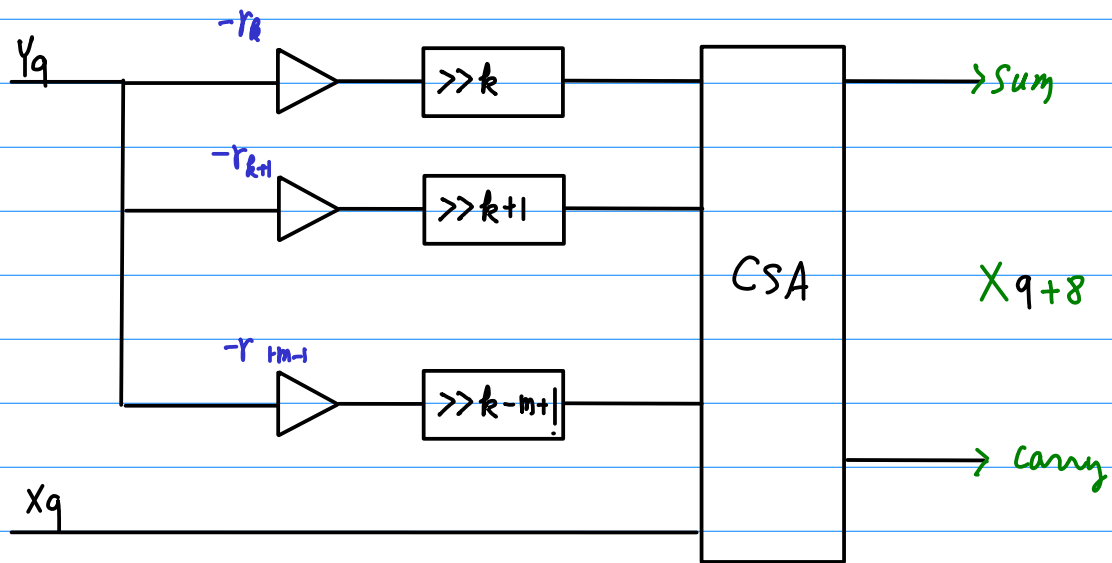


$$9 + 8 = 17$$

# Look ahead

$$X_{k+m} = X_k - Y_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$

$$Y_{k+m} = Y_k + X_k \sum_{i=k}^{k+m-1} r_i \tan 2^{-i}$$





```
>> t'  
ans =
```

```
0  
1  
2  
3  
4  
5  
6  
7  
8  
9  
10  
11  
12  
13  
14  
15
```

```
>> t'/16  
ans =
```

0.00000	0
0.06250	1
0.12500	2
0.18750	3
0.25000	4
0.31250	5
0.37500	6
0.43750	7
0.50000	8
0.56250	9
0.62500	10
0.68750	11
0.75000	12
0.81250	13
0.87500	14
0.93750	15

} no need to be saved

```
>> pi/4  
ans = 0.78540  
>>
```



# Contents of $2^4$ -words ROM

(Cos)

0000	0	11 1111 1110 1010 1010 10
0001	0	11 1111 0111 1010 1100 10
0010	0	11 1110 0110 1011 1000 10
0011	0	11 1100 1110 1101 1110 10
0100	0	11 1010 1111 0011 0110 01
0101	0	11 1000 0111 1101 1111 01
0110	0	11 0101 1001 0000 0001 01
0111	0	11 0010 0010 1100 1010 11
1000	0	10 1110 0101 0111 0010 00
1001	0	10 1010 0001 0011 0100 10
1010	0	10 0101 0110 0101 0110 01
1011	0	10 0000 0101 0010 0010 01
1100	0	101 1010 1101 1110 1001 10

X-value

↑  
binary point

(Sin)

0000	0	000 0011 1111 1111 1010 10
0001	0	000 1011 1111 1011 0000 00
0010	0	001 0011 1110 1010 0101 11
0011	0	001 1011 1100 0101 1101 00
0100	0	010 0011 1000 0101 0111 11
0101	0	010 1011 0010 0001 1010 11
0110	0	011 0010 1001 0010 1011 11
0111	0	011 1001 1101 0001 0011 11
1000	0	100 0000 1101 0101 1111 00
1001	0	100 0111 1001 1001 1101 01
1010	0	100 1110 0001 0110 0010 01
1011	0	101 0100 0100 0100 0110 01
1100	0	101 1010 0001 1110 0110 01

Y-value

↑  
binary point

↑  
4-bit address

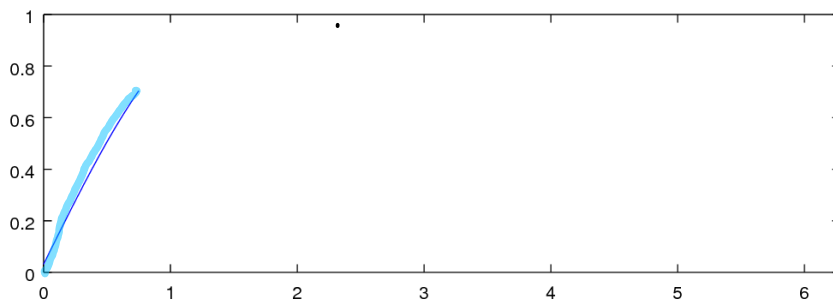
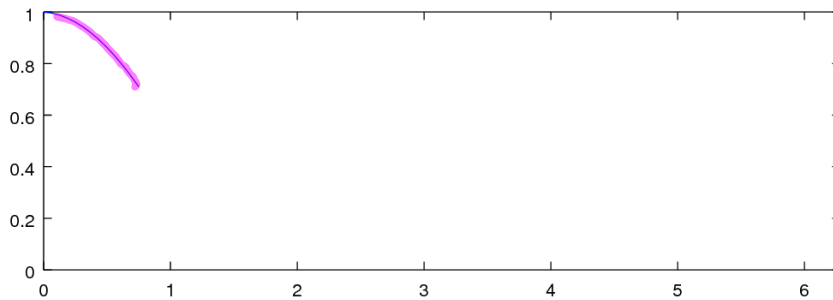
```
C = [ "0111111111101010101010" ;  
      "0111111101111010110010" ;  
      "0111111001101011100010" ;  
      "0111110011101101111010" ;  
      "0111101011110011011001" ;  
      "0111100001111101111101" ;  
      "0111010110010000000101" ;  
      "0111001000101100101011" ;  
      "0110111001010111001000" ;  
      "0110101000010011010010" ;  
      "0110010101100101011001" ;  
      "0110000001010010001001" ;  
      "0101101011011110100110" ]
```

```
S = [ "0000001111111111101010" ;  
      "0000101111111011000000" ;  
      "0001001111101010010111" ;  
      "0001101111000101110100" ;  
      "0010001110000101011111" ;  
      "0010101100100001101011" ;  
      "0011001010010010101111" ;  
      "0011100111010001001111" ;  
      "0100000011010101111100" ;  
      "0100011110011001110101" ;  
      "0100111000010110001001" ;  
      "0101010001000100011001" ;  
      "0101101000011110011001" ]
```

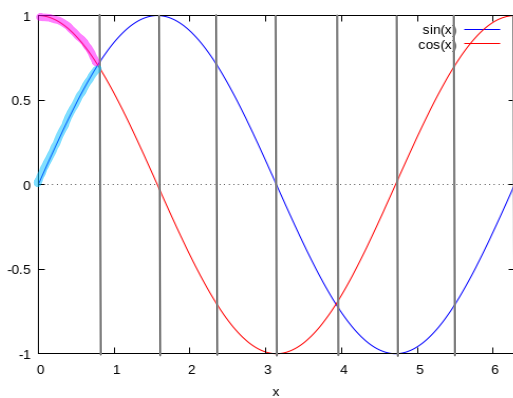
```
CV = zeros(rows(C), 1);  
Cn = 2^rows(C') / 2;  
for i=1:rows(C)  
    CV(i) = bin2dec(C(i, :)) / Cn;  
end
```

```
SV = zeros(rows(S), 1);  
Sn = 2^rows(S') / 2;  
for i=1:rows(S)  
    SV(i) = bin2dec(S(i, :)) / Sn;  
end
```

```
>> subplot(2,1,1)
>> axis([0, 2*pi 0 1])
>> plot(x, CV)
>> axis([0, 2*pi 0 1])
>> subplot(2,1,2)
>> plot(x, SV)
>> axis([0, 2*pi 0 1])
>>
```

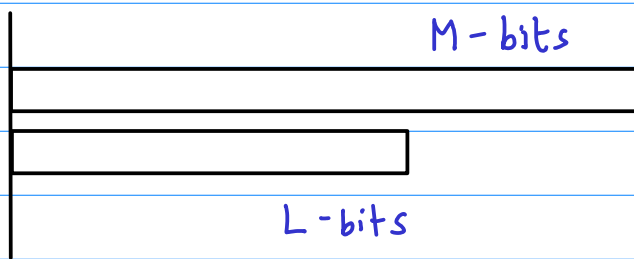
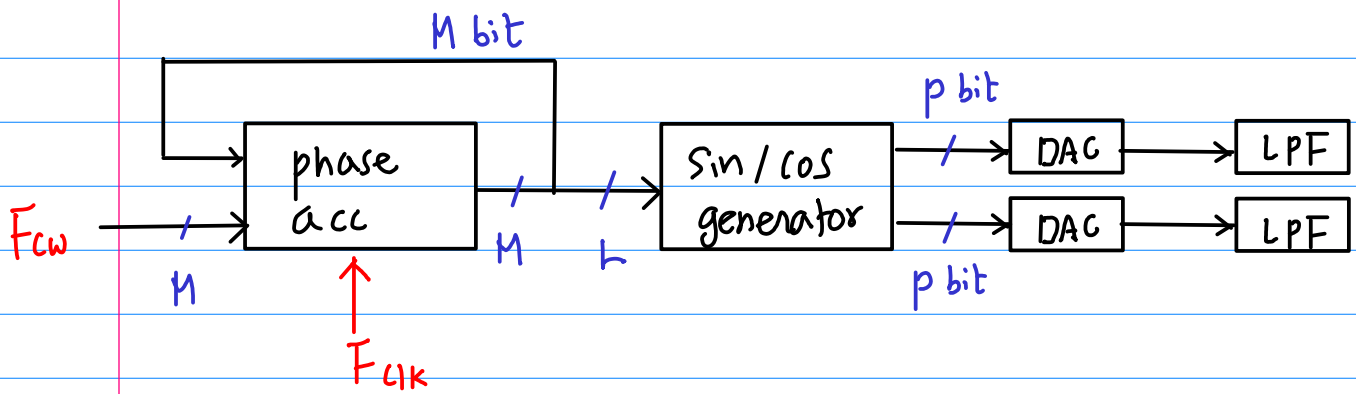


①  $\cos \theta$   
 $\sin \theta$



$-\sin \theta$

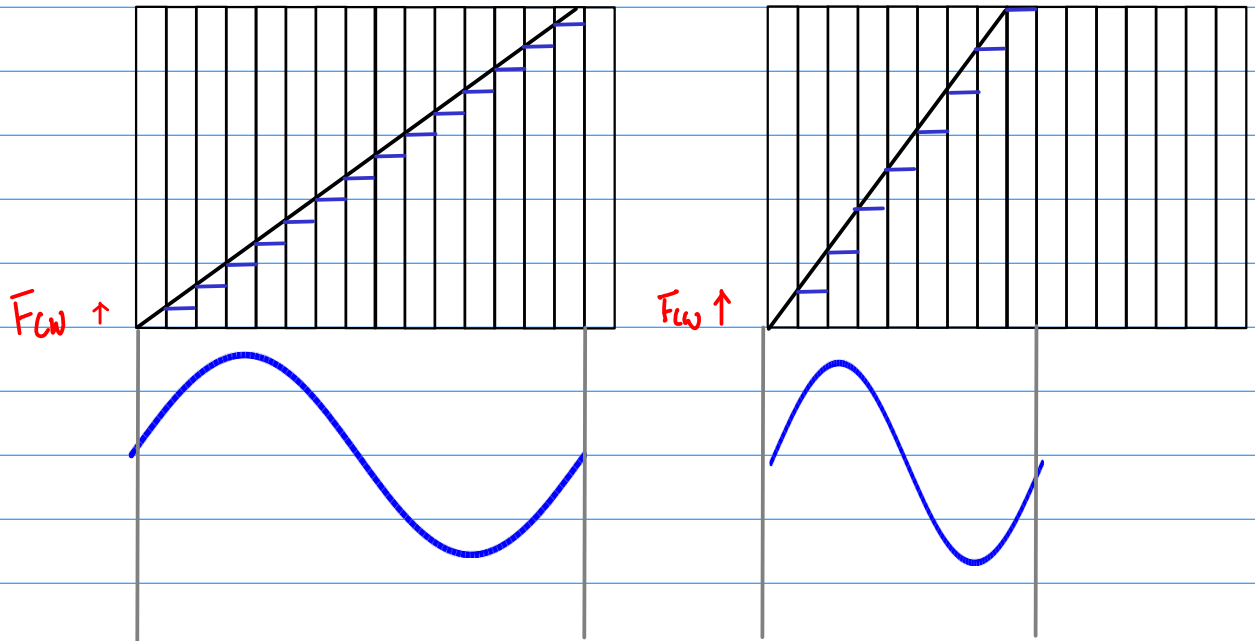
# DDFS (Direct Digital Frequency Synthesis)



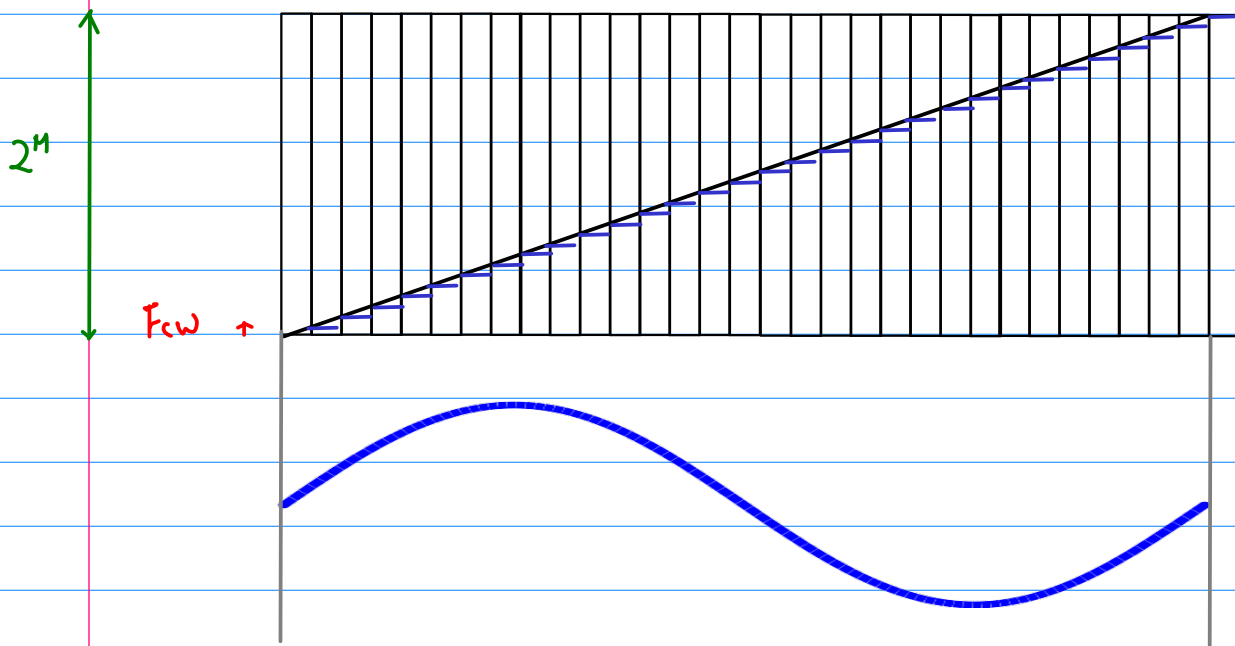
$F_{cw}$  Frequency Control Word

at each  $F_{clk}$ , the phase accumulator increments by  $F_{cw}$  until it overflows and wraps  
↳ one period of a sine wave

$F_{cw}$  controls the rate at which the accumulator overflows  
controls the frequency of the sine or cosine wave.



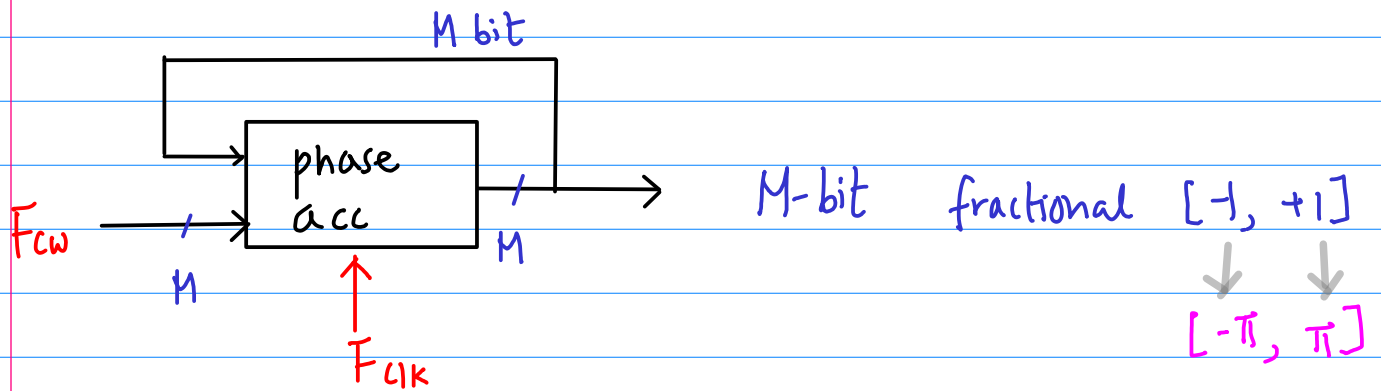
$$\leftrightarrow T_{clk} = 1 / F_{clk}$$



$$T_o = (2^n / F_{cw}) T_{clk}$$

$$F_o = \frac{F_{cw}}{2^n} F_{clk}$$

Output frequency



$$F_o = \frac{d\theta}{dt} = \frac{F_{clk} F_{cw}}{2^M}$$

Nyquist theorem : at least 2 samples / clock cycle

$$\text{Max } F_{cw} = 2^M / 2 = 2^{M-1}$$

$$\text{Max } F_o = \frac{F_{clk} F_{cw}}{2^M} = \frac{F_{clk} 2^{M-1}}{2^M} = \frac{F_{clk}}{2}$$

in practice  $F_o \leq \frac{F_{clk}}{3} \leftarrow \boxed{\text{DAC}}$

The spectrum of the DAC's output signal

images at  $n F_{clk} \pm F_0$

the closest image freq  $\Rightarrow F_{clk} - 2F_0$