

Eulerian Cycle (2A)

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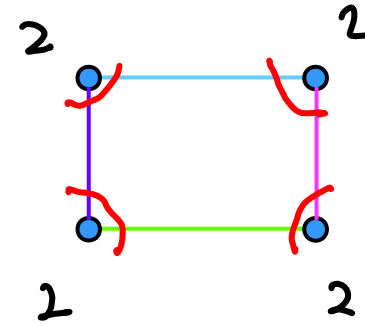
Euler Cycle

visits every edge exactly once

the existence of **Eulerian cycles**

all **vertices** in the graph have an **even** degree

connected graphs with **all vertices** of **even** degree have an **Eulerian cycles**



https://en.wikipedia.org/wiki/Eulerian_path

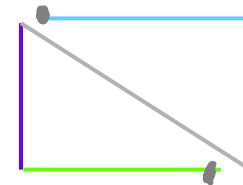
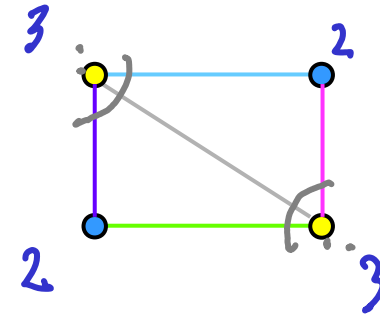
Euler Path

visits every edge exactly once

the existence of **Eulerian paths**

all the **vertices** in the graph have an **even** degree

except only **two** vertices with an **odd** degree



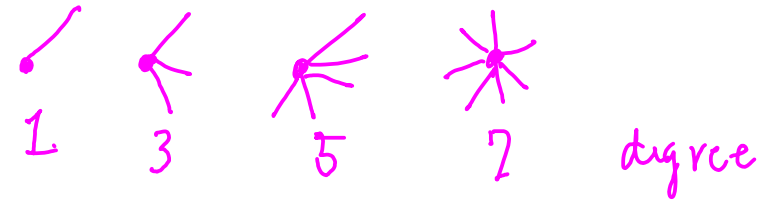
An **Eulerian path** starts and ends at different vertices
An **Eulerian cycle** starts and ends at the same vertex.

https://en.wikipedia.org/wiki/Eulerian_path

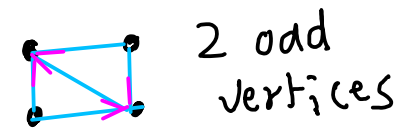
Conditions for Eulerian Cycles and Paths

An **odd vertex** = a vertex with an odd degree

An even vertex = a vertex with an even degree



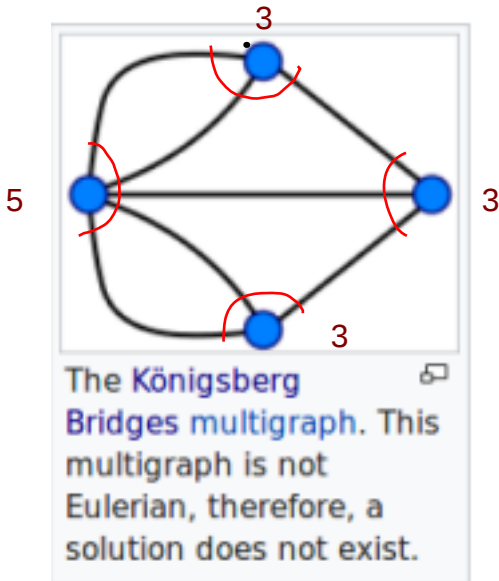
# of odd vertices	Eulerian Path	Eulerian Cycle
0	No	Yes
2	Yes	No
4, 6, 8, ...	No	No
1, 3, 5, 7, ...	No such graph	No such graph



↓
vertices
with degree
3

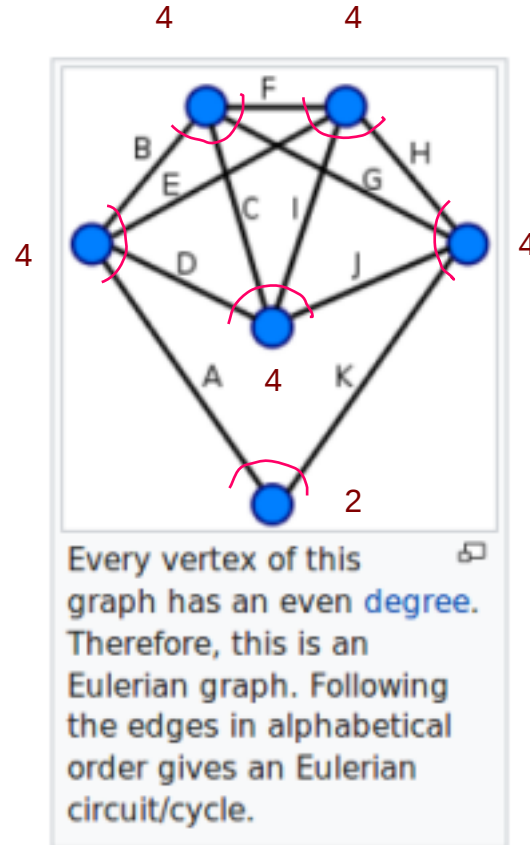
If the graph is connected

Odd Degree and Even Degree

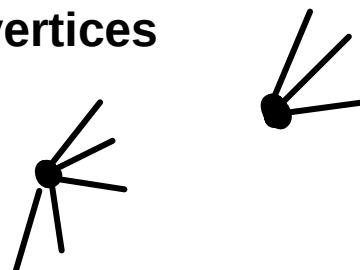


0 ... E. cycle
 2 ... E. path
 4
 6
 8
 ...
 E.C X
 E.P X

↑
 # of odd vertices
degree odd



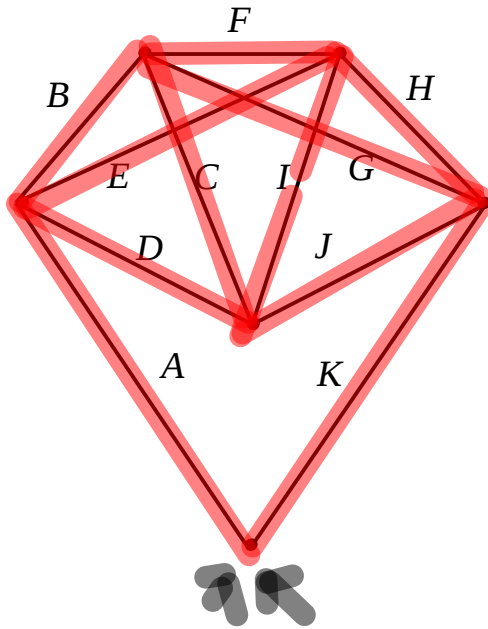
All odd degree vertices



All even degree vertices

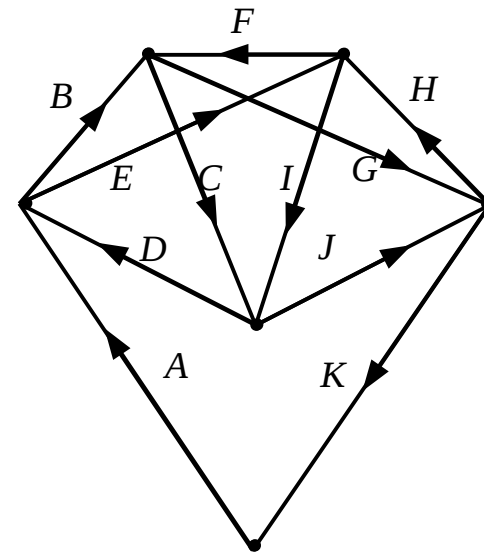
https://en.wikipedia.org/wiki/Eulerian_path

Euler Cycle Example



ABCDEFGHIJK

a path denoted by
the edge names

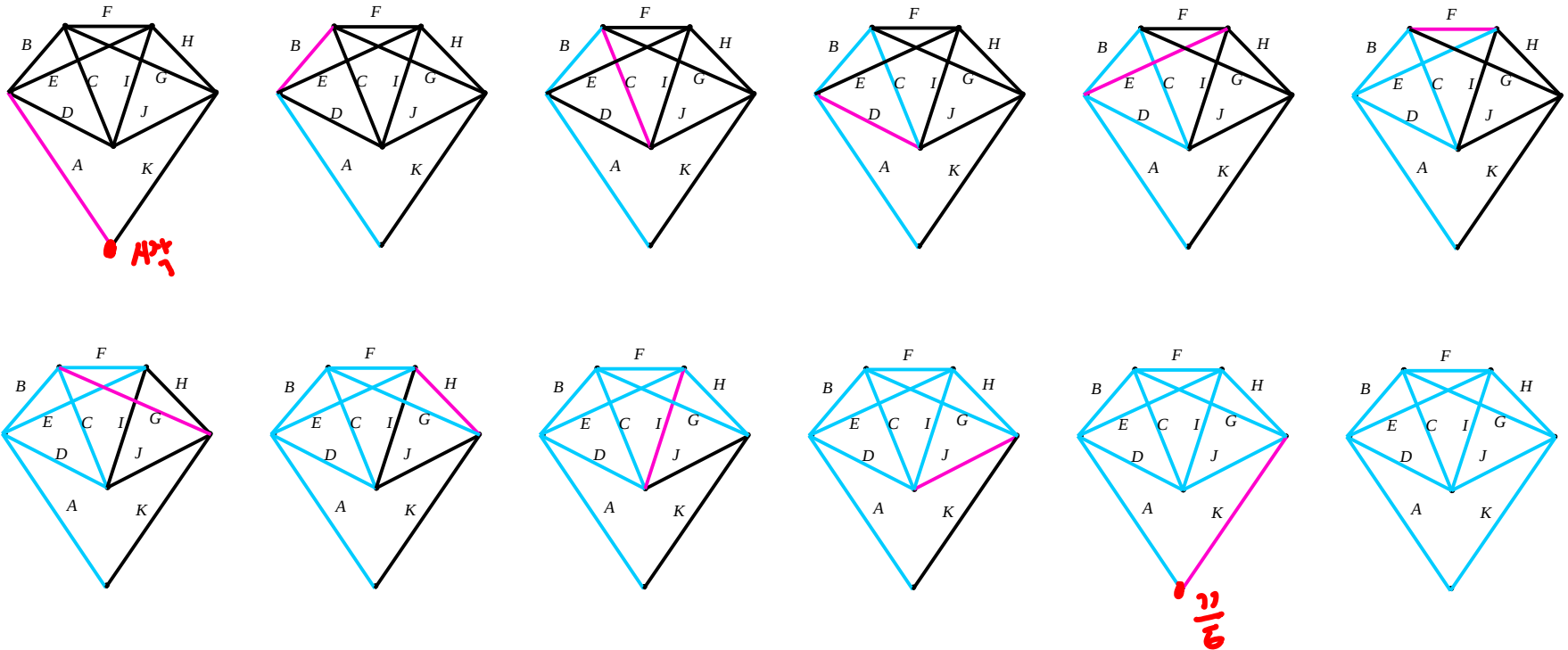


**All even degree vertices
Eulerian Cycles**

en.wikipedia.org

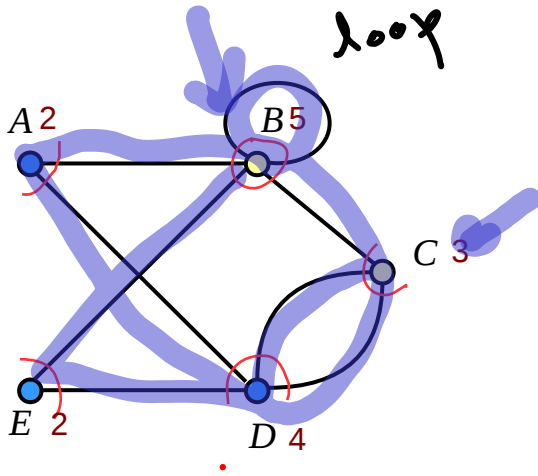
Euler Cycle Example

ABCDEFGHIJK

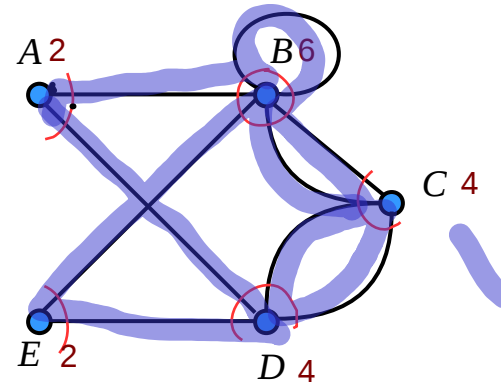


en.wikipedia.org

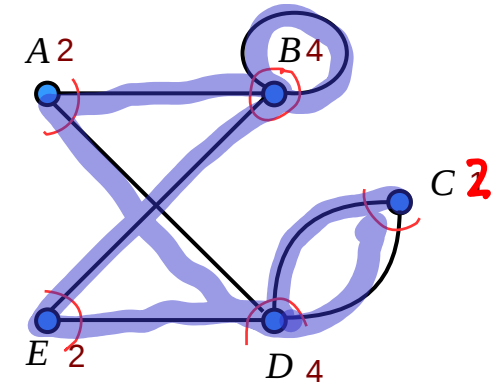
Euler Path and Cycle Examples



Eulerian Path
 1. BBADCDEBC
 2. CDCBBADEB



Eulerian Cycle
 1. CDCBBADEBC

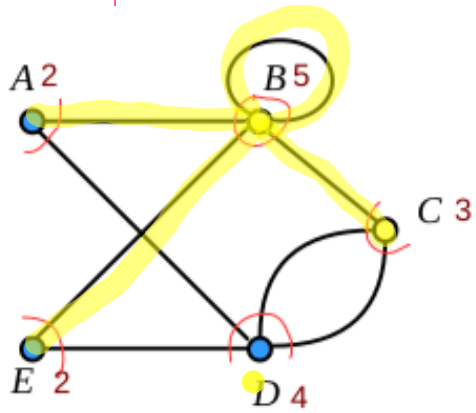


Eulerian Cycle
 2. CDEBBADC

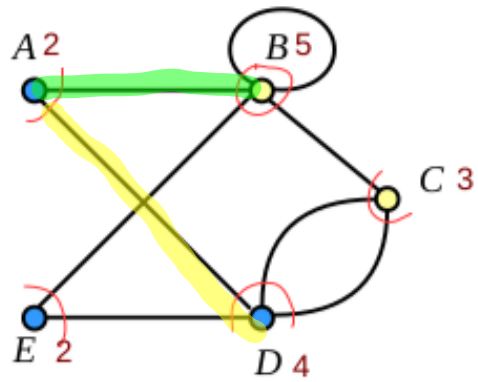
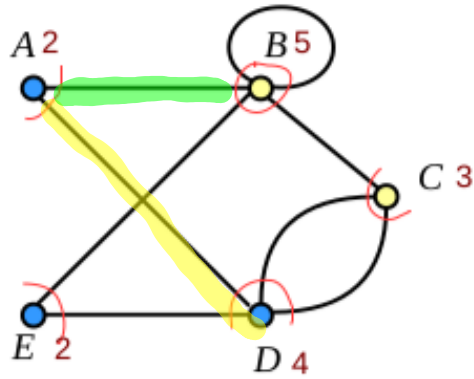
a path denoted by
 the vertex names

<http://people.ku.edu/~jlmartin/courses/math105-F11/Lectures/chapter5-part2.pdf>

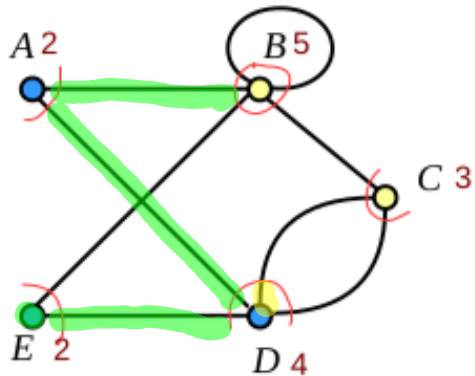
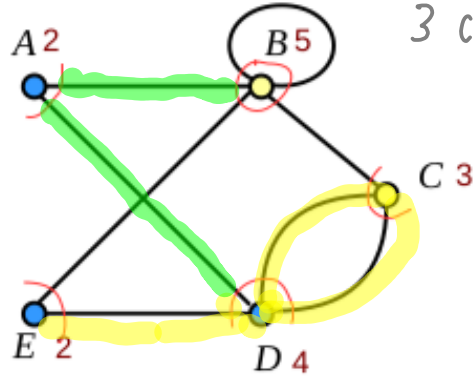
3 choices



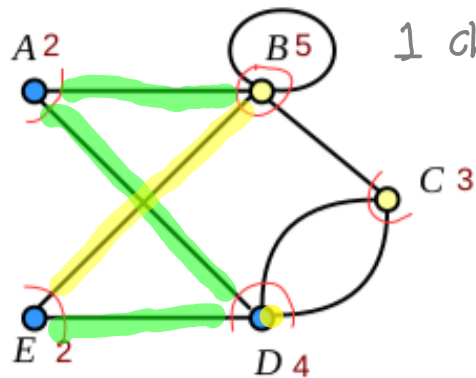
1 choice



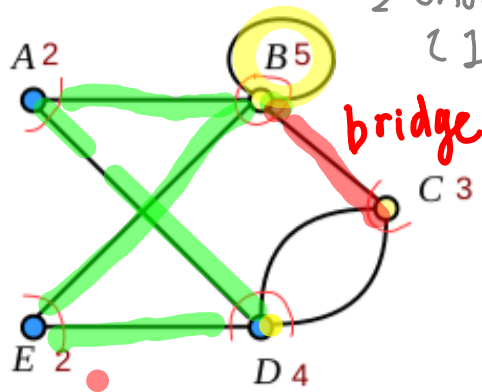
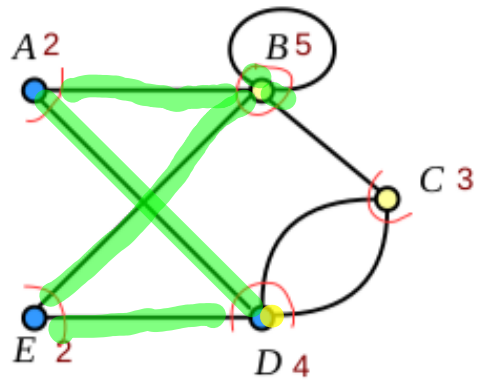
3 choices



1 choice

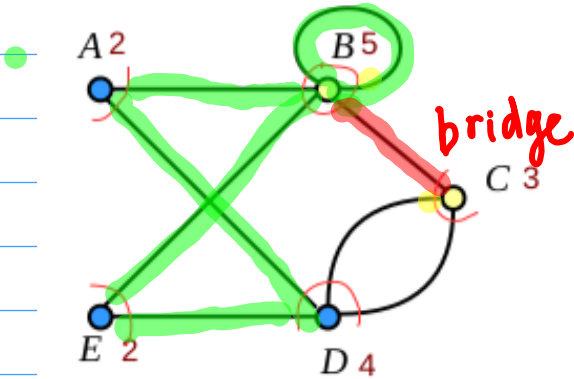
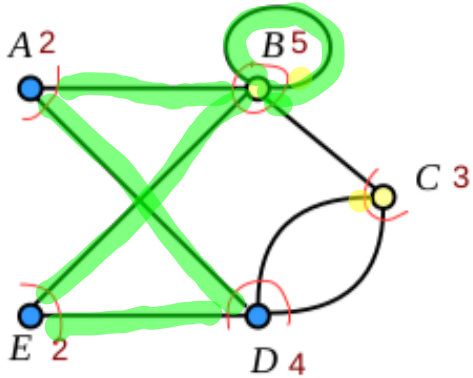


BADE

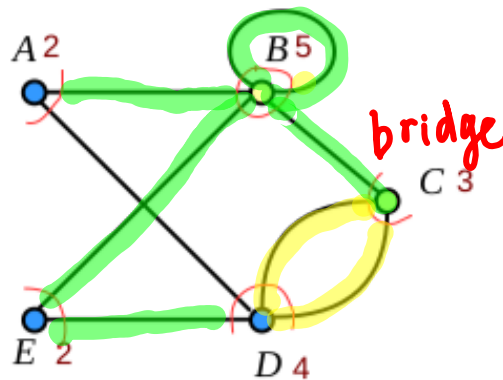
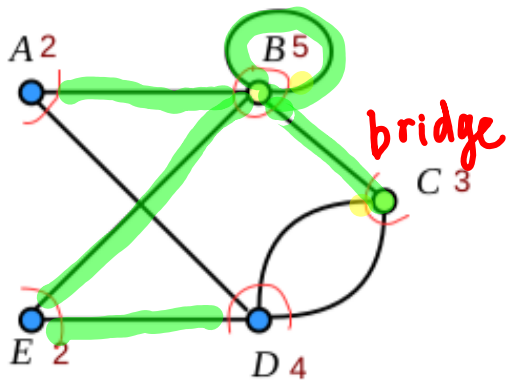


2 choices
(1 choice is a bridge)

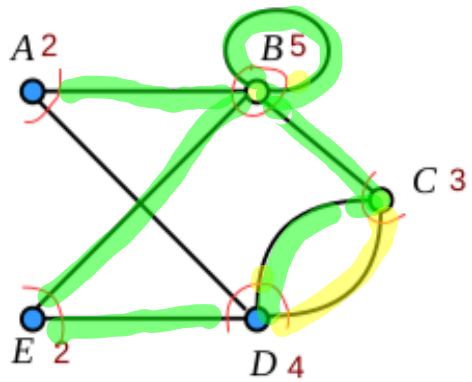
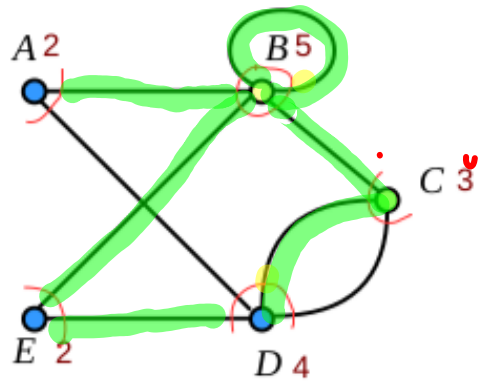
BADEBBCDC



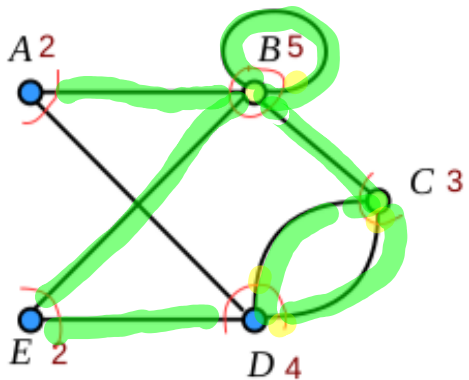
1 choice



2 choices



1 choices



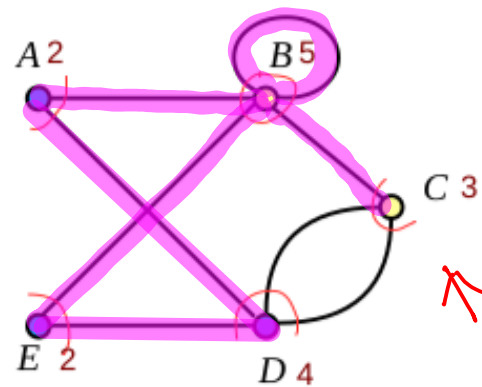
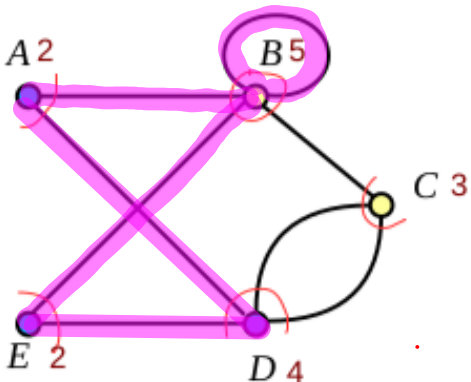
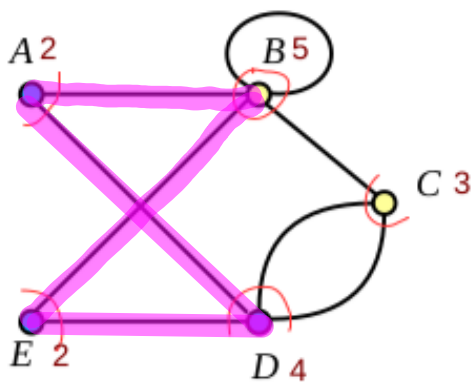
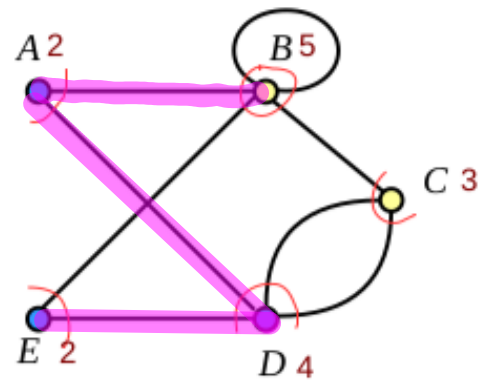
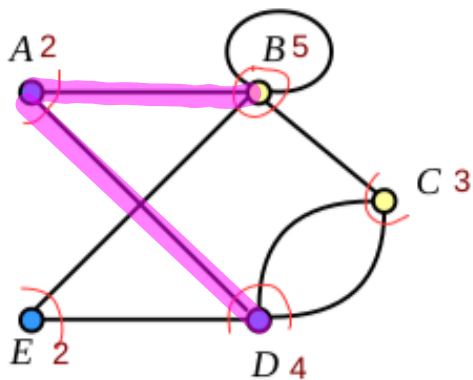
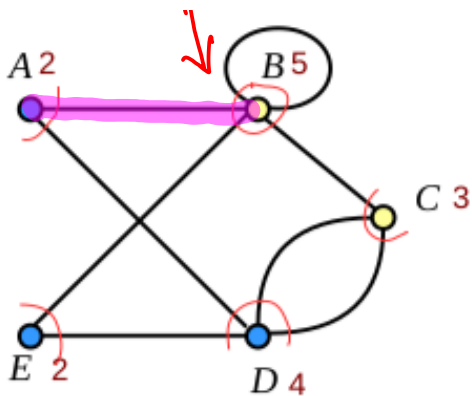
BADEBBCDC

could be many Eulerian paths (not unique)

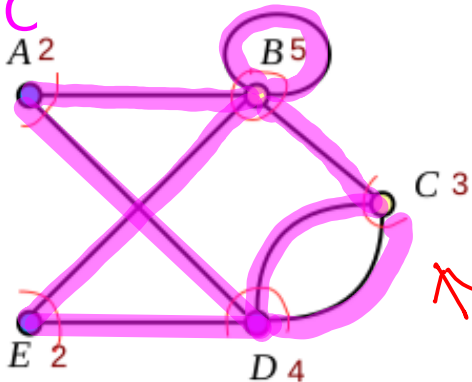
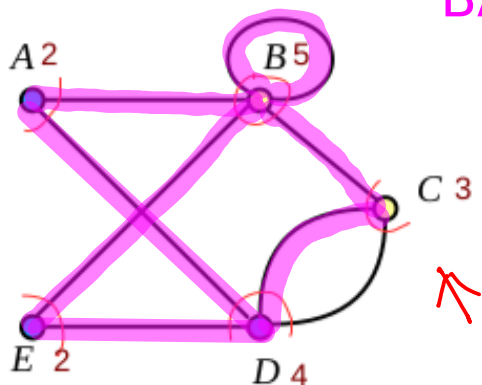
Eulerian Path

1. BBADCDEBC
2. CDCBBADEB

BADEBBCDC



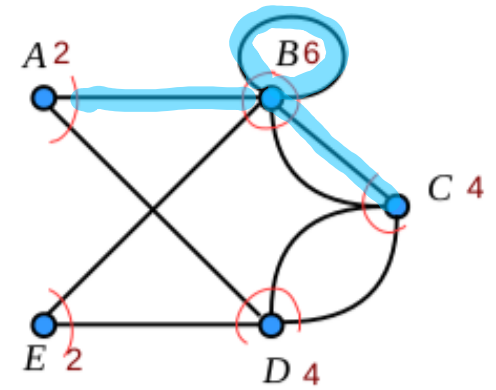
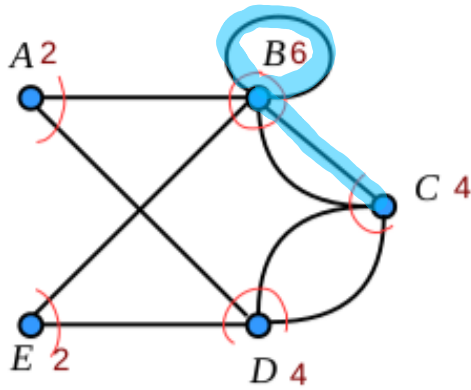
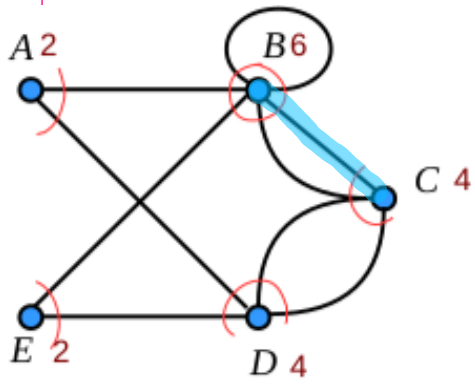
BADEBBCDC



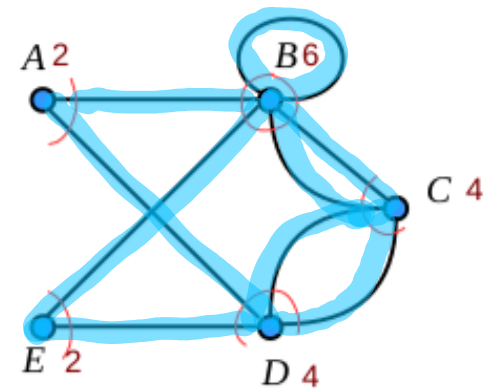
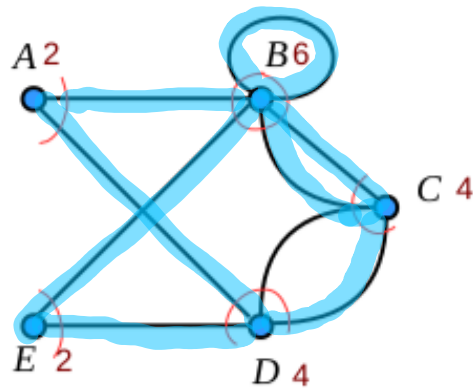
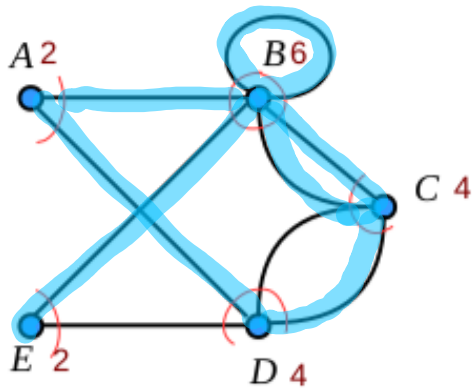
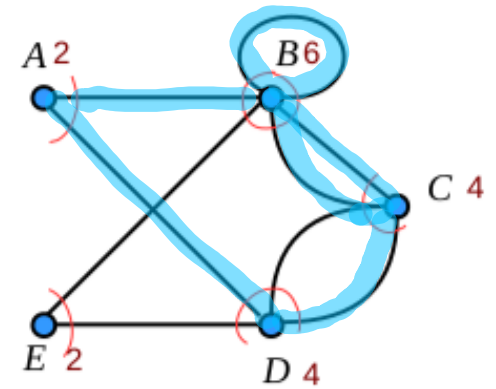
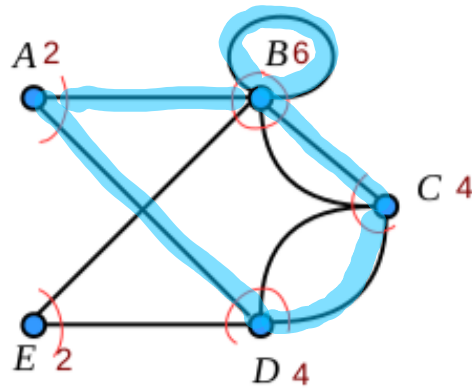
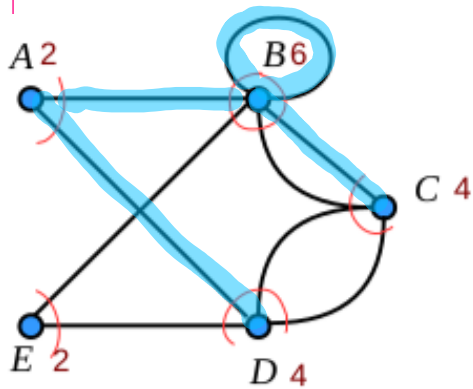
Eulerian Cycle

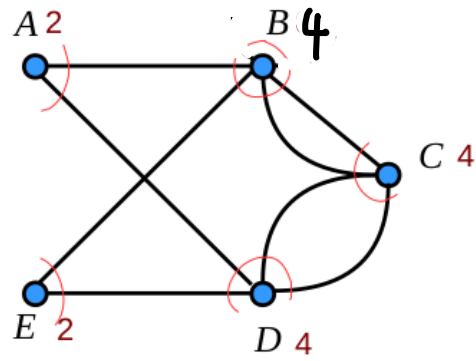
1. CDCBBADEBC

could be many Eulerian cycles (not unique)



CBBABCDBEDC



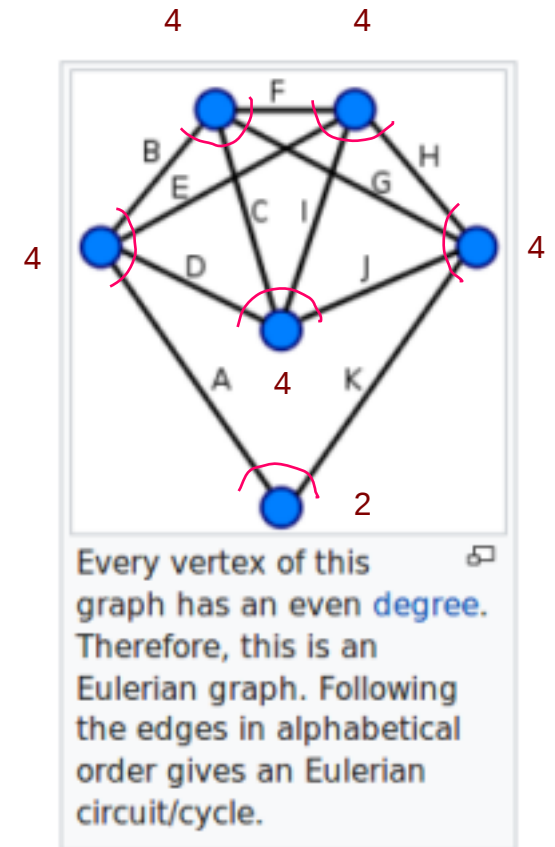


Eulerian Cycles of Undirected Graphs

An **undirected** graph has an **Eulerian cycle** if and only if every **vertex** has **even degree**, and all of its **vertices** with **nonzero degree** belong to a **single connected component**.

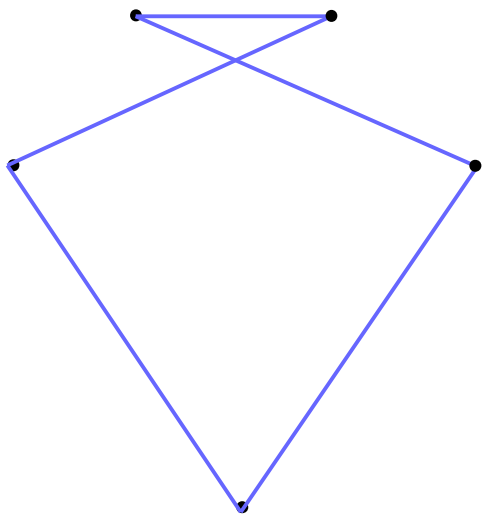
An **undirected** graph can be decomposed into **edge-disjoint cycles** if and only if all of its **vertices** have **even degree**.

So, a graph has an **Eulerian cycle** if and only if it can be decomposed into **edge-disjoint cycles** and its **nonzero-degree** vertices belong to a **single connected component**.

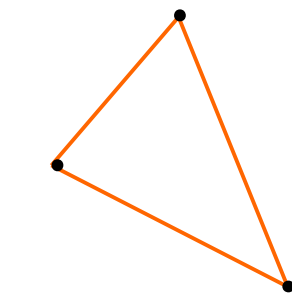
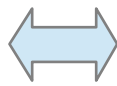


https://en.wikipedia.org/wiki/Eulerian_path

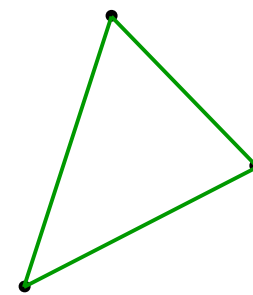
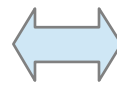
Edge Disjoint Cycle Decomposition



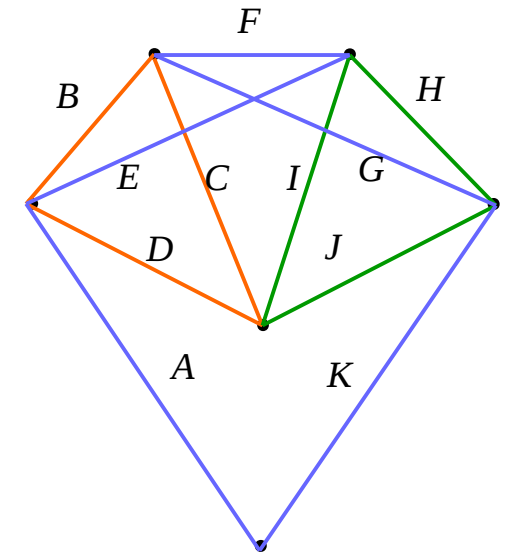
All even
vertices



Eulerian
Cycle



Edge Disjoint
Cycles



Eulerian Paths of Undirected Graphs

An undirected graph has an **Eulerian trail** if and only if exactly **zero** or **two vertices** have **odd degree**, and all of its vertices with **nonzero degree** belong to a **single connected component**.

https://en.wikipedia.org/wiki/Eulerian_path

Eulerian Cycles of DiGraphs

A directed graph has an **Eulerian cycle** if and only if every vertex has **equal in degree** and **out degree**, and all of its vertices with nonzero degree belong to a single strongly connected component.

Equivalently, a directed graph has an Eulerian cycle if and only if it can be decomposed into **edge-disjoint directed cycles** and all of its vertices with nonzero degree belong to a single strongly connected component.

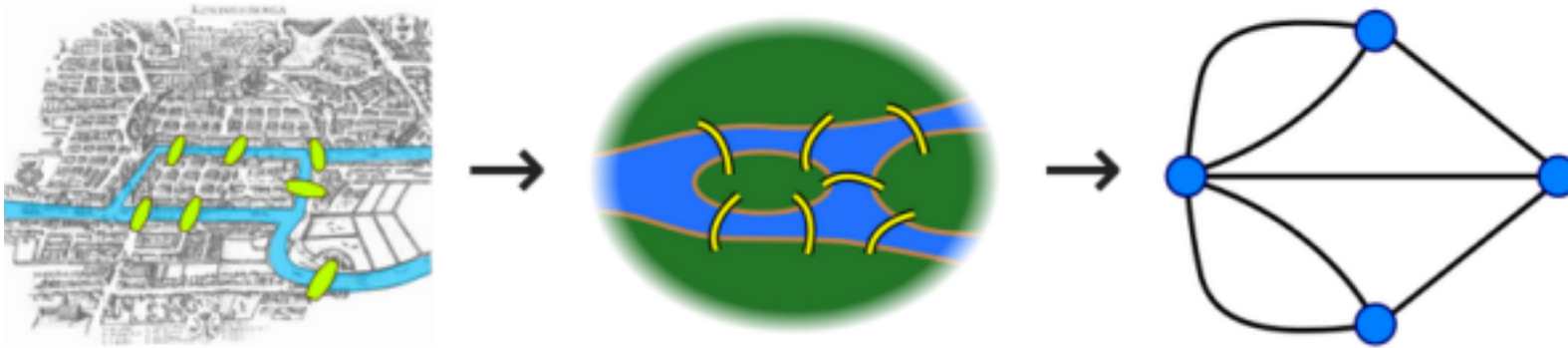
https://en.wikipedia.org/wiki/Eulerian_path

Eulerian Paths of DiGraphs

A directed graph has an **Eulerian path** if and only if **at most one** vertex has $(\text{out-degree}) - (\text{in-degree}) = 1$, **at most one** vertex has $(\text{in-degree}) - (\text{out-degree}) = 1$, every other vertex has equal in-degree and out-degree, and all of its vertices with nonzero degree belong to a single connected component of the underlying undirected graph.

https://en.wikipedia.org/wiki/Eulerian_path

Seven Bridges of Königsberg

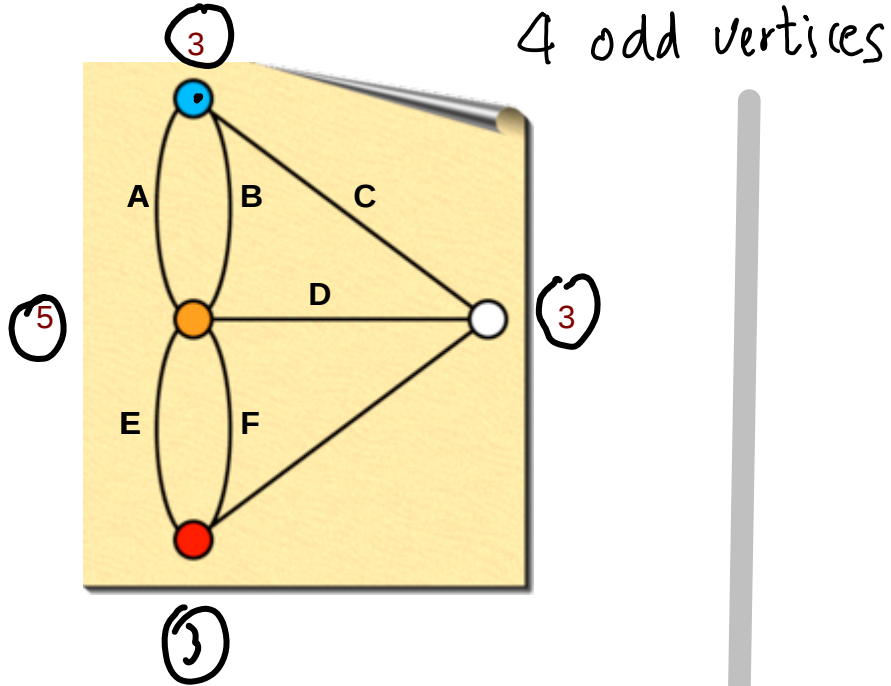


The problem was to devise a walk through the city that would cross each of those bridges once and only once.

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

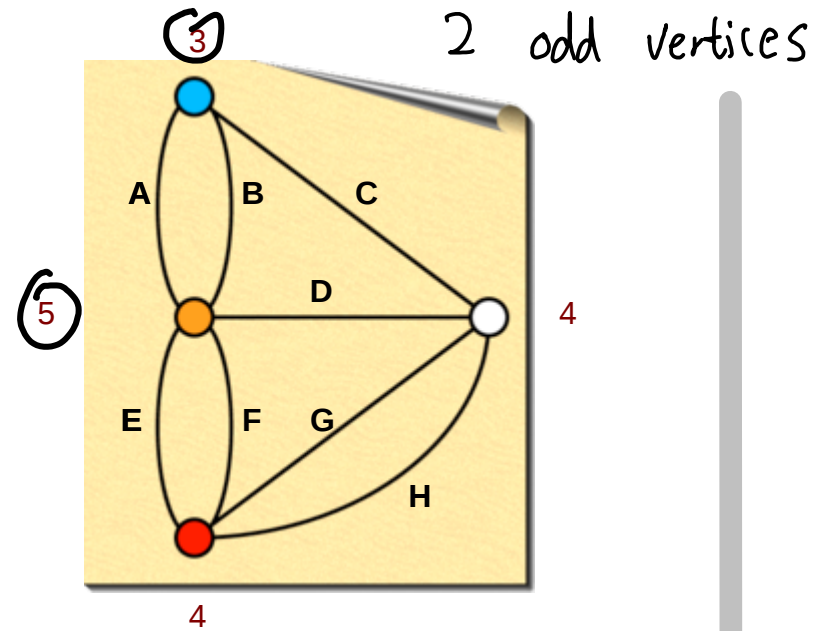
Seven and Eight Bridges Problems

7 bridges problem



.E. path X
E cycle X

8 bridges problem



Eulerian Path

● AEHGFDCB ●

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

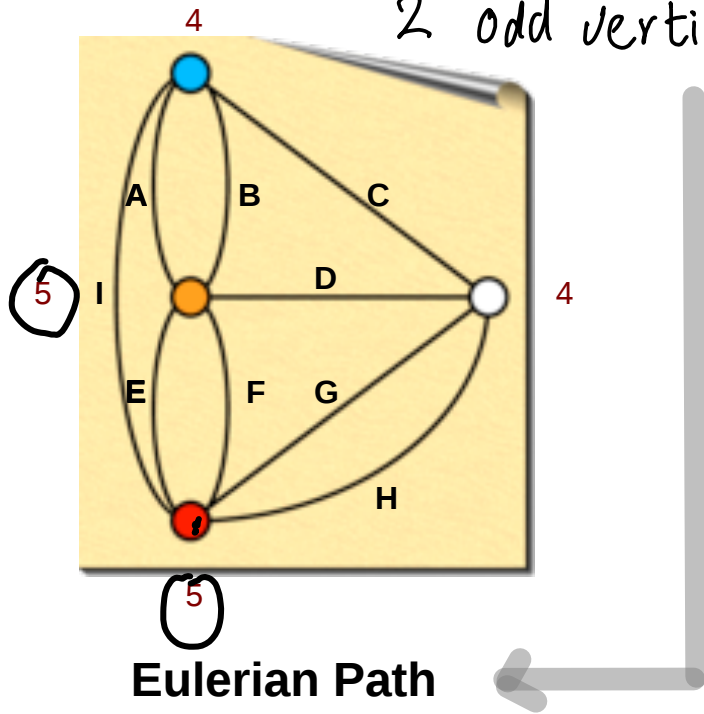
Nine and Ten Bridges Problems

check how many odd vertices!

odd degree

9 bridges problem

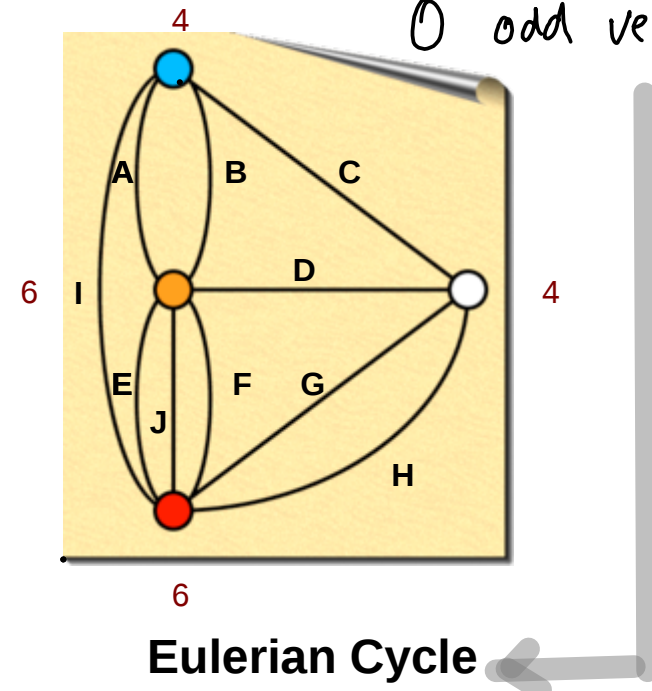
2 odd vertices



● EHGFD CBA I ●

10 bridges problem

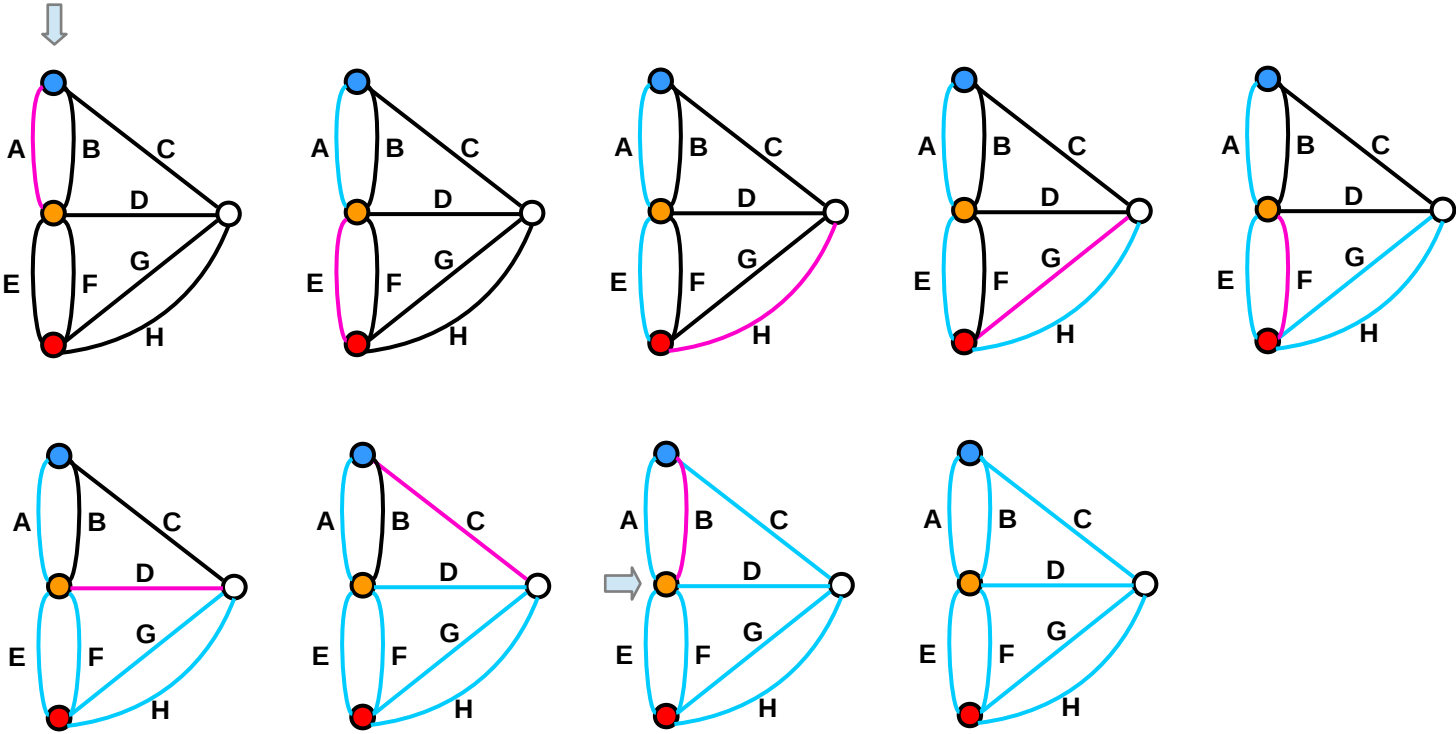
0 odd vertex



● A EHGFD C B J I ●

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

8 bridges – Eulerian Path

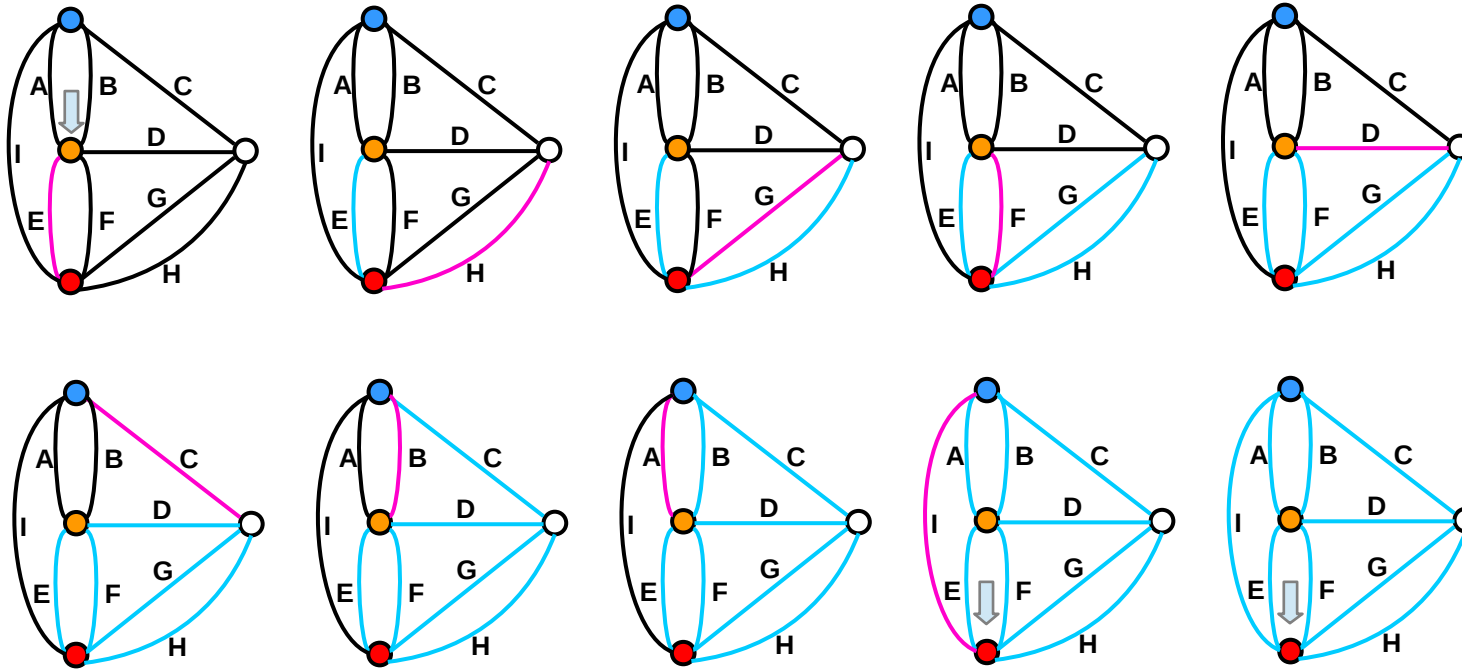


Eulerian Path

● AEHGFDCB ●

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

9 bridges – Eulerian Path

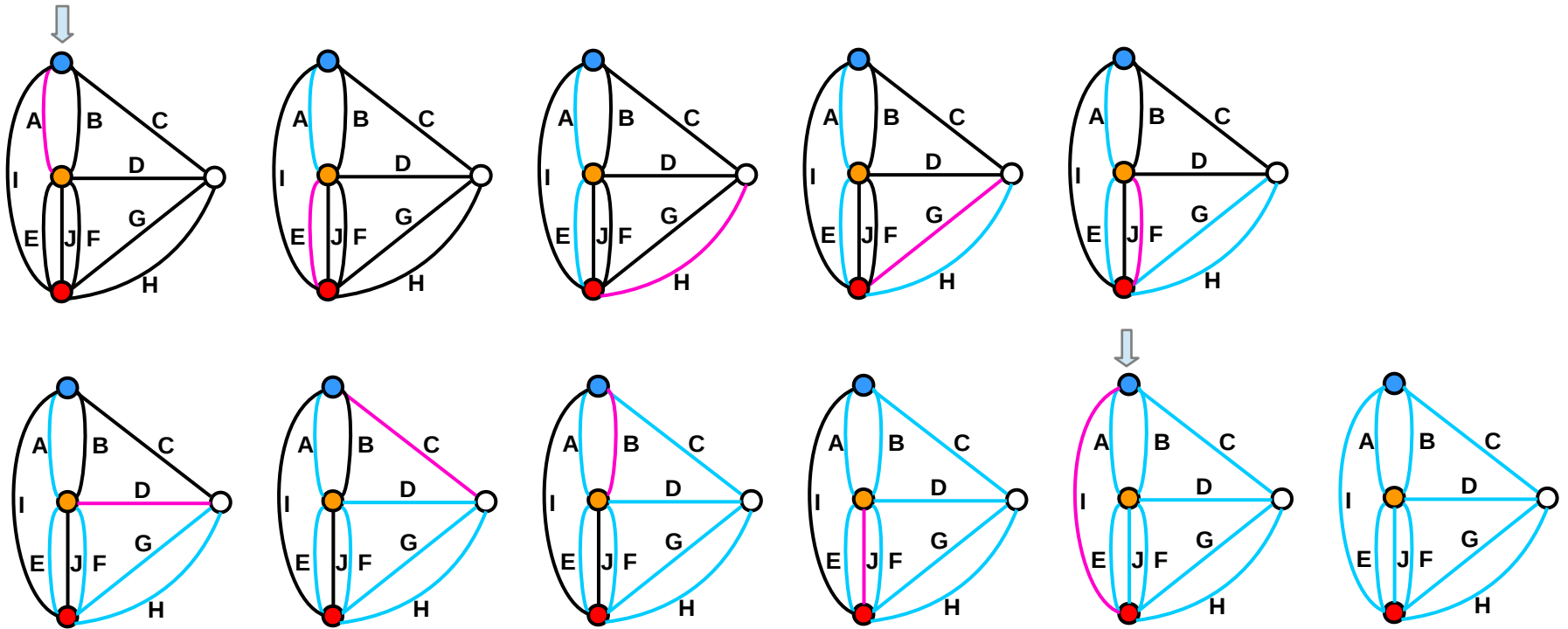


Eulerian Path

●EHGFDCAI●

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

10 bridges – Eulerian Cycle



Eulerian Cycle

●AEHGFDCBBI●

https://en.wikipedia.org/wiki/Seven_Bridges_of_K%C3%B6nigsberg

Fleury's Algorithm

To find an Eulerian path or an Eulerian cycle:

1. make sure the graph has either **0** or **2 odd** vertices

2. if there are **0 odd** vertex, start anywhere.

If there are **2 odd** vertices, start at one of the two vertices

3. follow edges one at a time.

If you have a choice between a **bridge** and a **non-bridge**,
Always choose the **non-bridge**

4. stop when you run out of edge

Bridges

A bridge edge

Removing a single edge from a connected graph can make it disconnected

Non-bridge edges

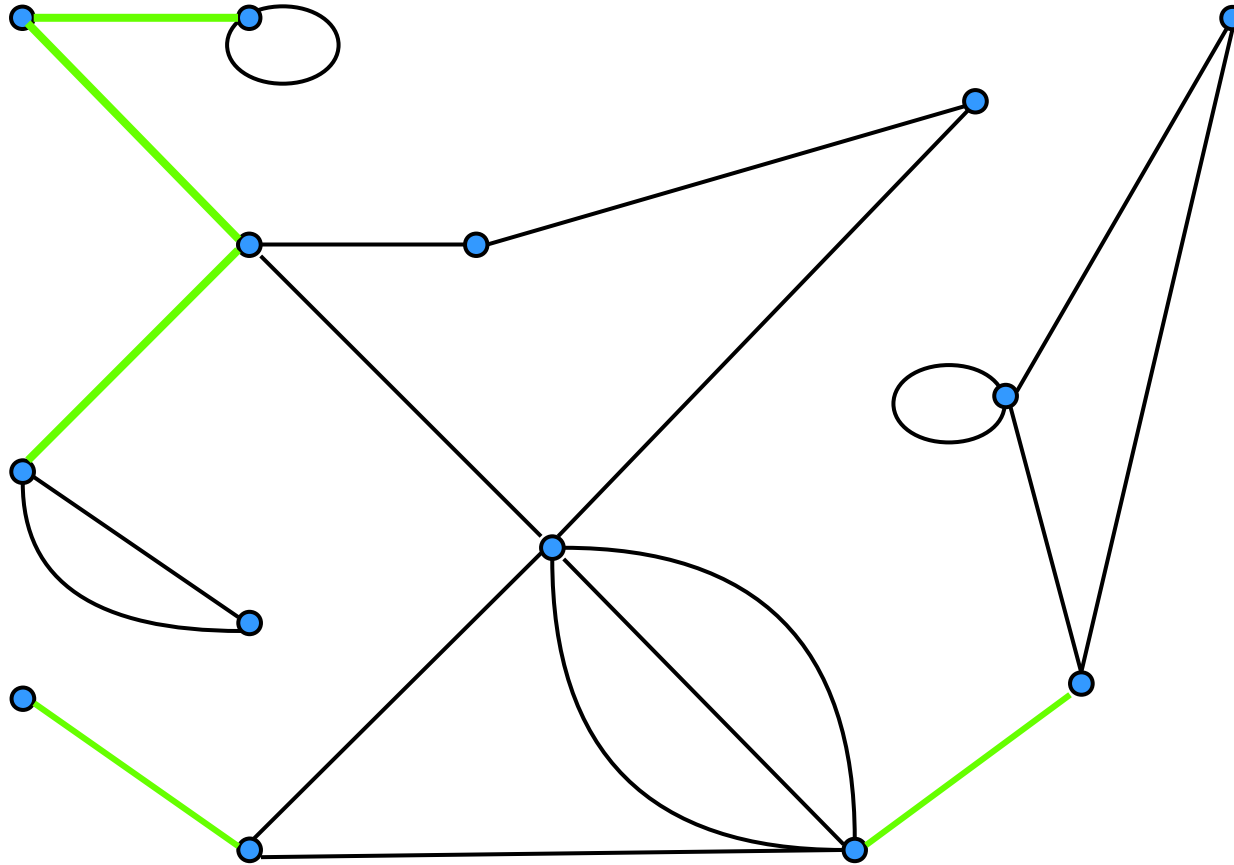
Loops cannot be bridges



Multiple edges cannot be bridges

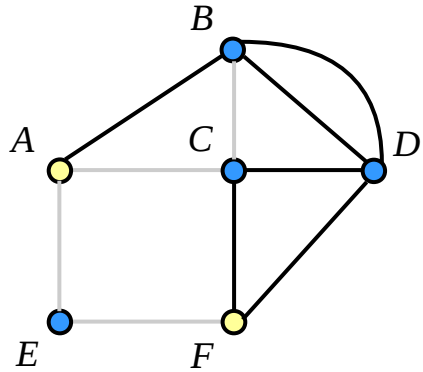


Bridge examples in a graph

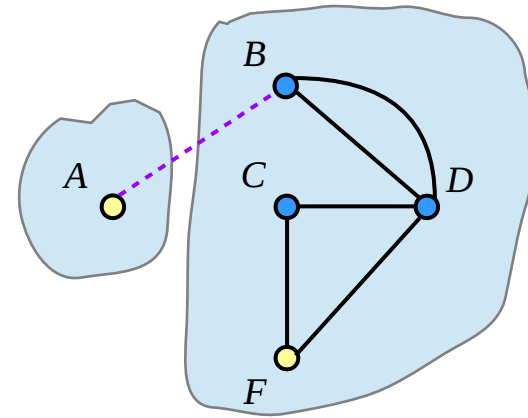
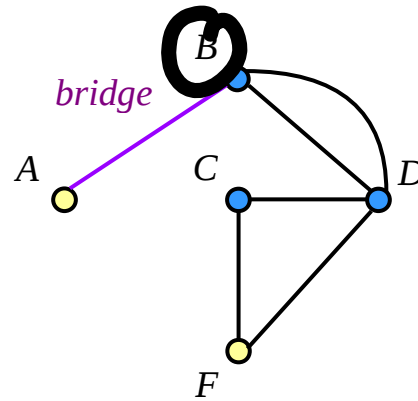


<http://people.ku.edu/~jlmartin/courses/math105-F11/Lectures/chapter5-part2.pdf>

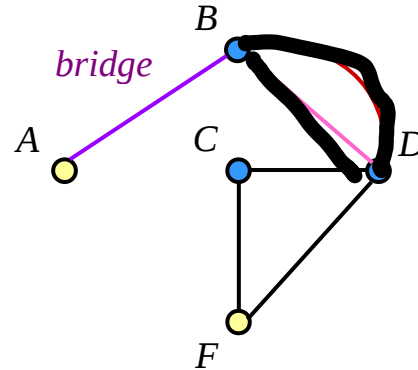
Bridges must be avoided, if possible



FEACB

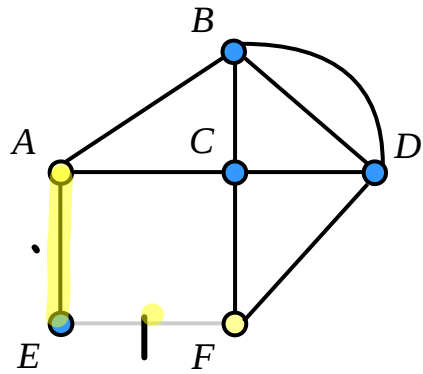
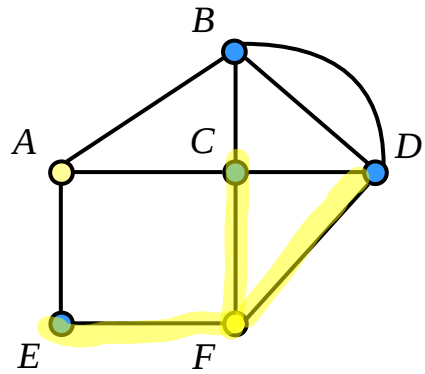


If there exists other choice other than a bridge
The bridge must not be chosen.

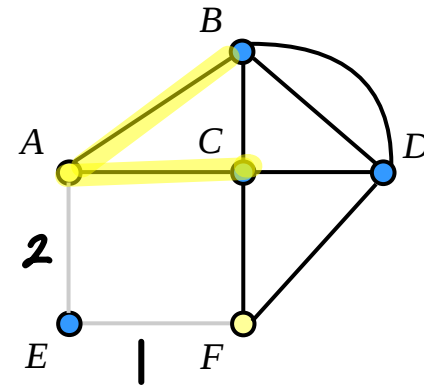


<http://people.ku.edu/~jlmartin/courses/math105-F11/Lectures/chapter5-part2.pdf>

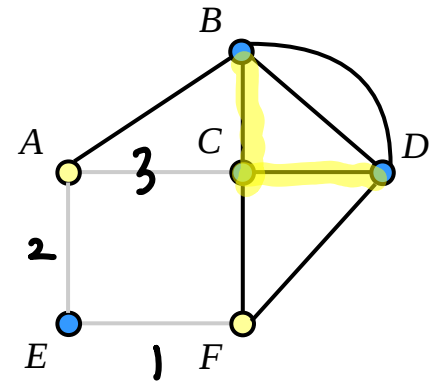
Flery's Algorithm (1)



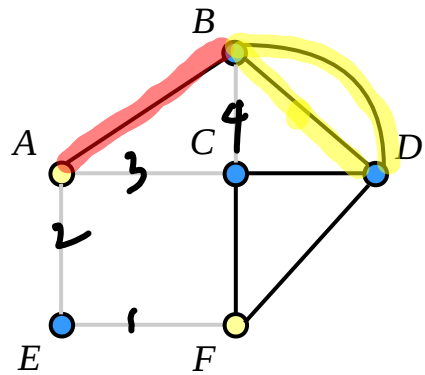
FE



FEA



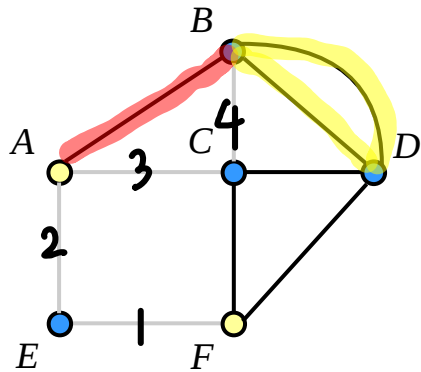
FEAC



FEACB

<http://people.ku.edu/~jlmartin/courses/math105-F11/Lectures/chapter5-part2.pdf>

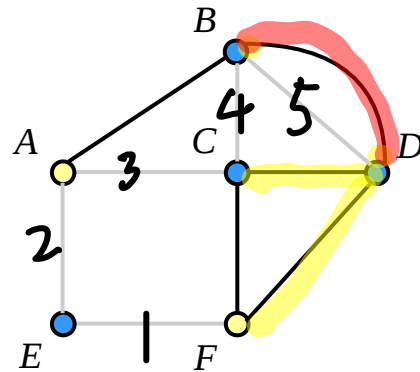
Fleury's Algorithm (2)



FEACB

BA: *bridge*

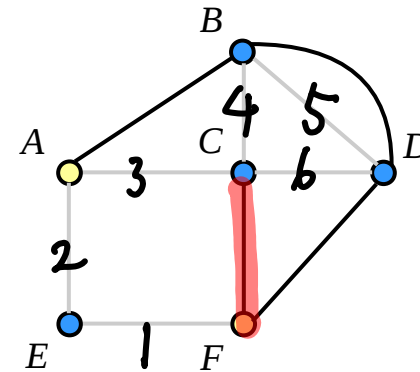
BD: *chosen*



FEACBD

DB: *bridge*

DC: *chosen*

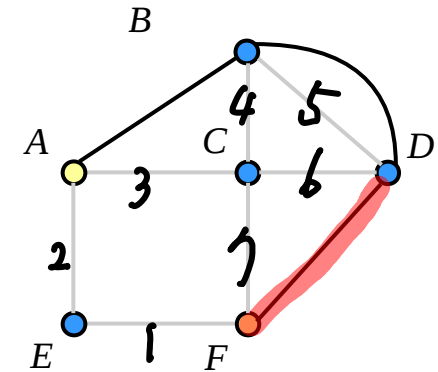


FEACBDC

CF: *bridge*

CF: *chosen*

no other choice



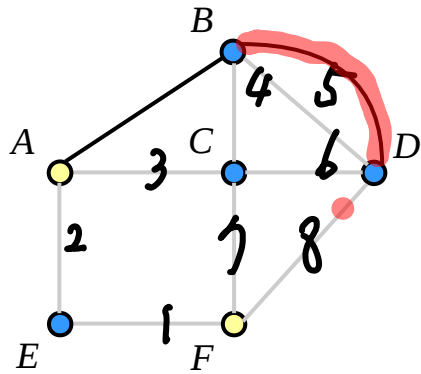
FEACBD CF

FD: *bridge*

FD: *chosen*

no other choice

Fleury's Algorithm (3)

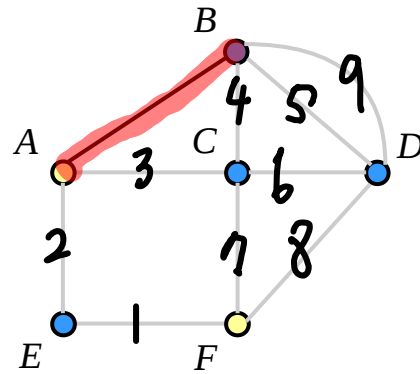


FEACBDCFD

DB: *bridge*

DB: *chosen*

no other choice

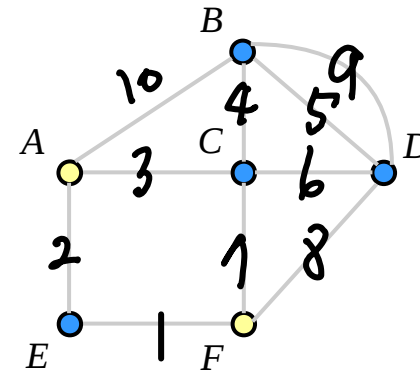


FEACBDCFDB

BA: *bridge*

BA: *chosen*

no other choice



edge names

(F) 1-2-3-4-5-6-7-8-9-10 (A)

E. Path.

References

[1] <http://en.wikipedia.org/>

[2]

Hamiltonian Cycle (3A)

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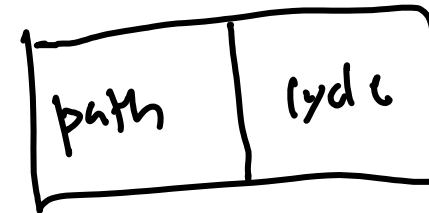
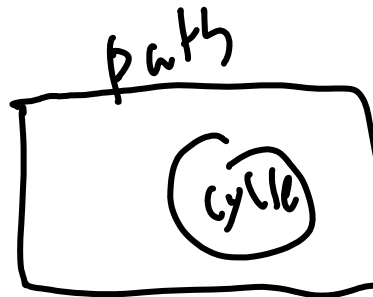
This document was produced by using LibreOffice and Octave.

Hamiltonian Cycles

A Hamiltonian path is a path in an undirected or directed graph that visits each vertex exactly once.

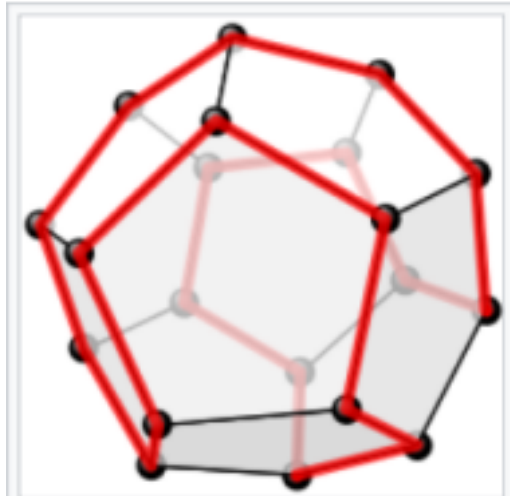
(A Hamiltonian cycle is a Hamiltonian path that is a cycle.)

the Hamiltonian path problem is NP-complete.

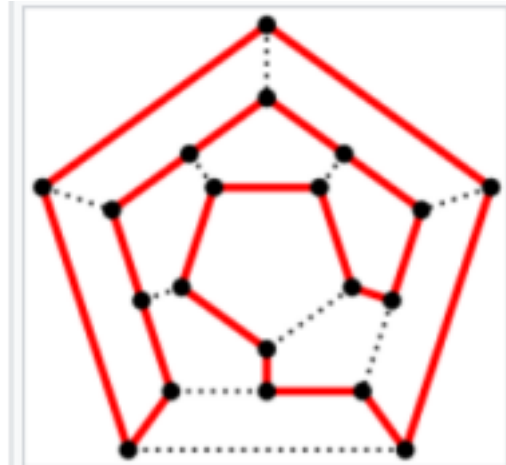


https://en.wikipedia.org/wiki/Hamiltonian_path

Hamiltonian Cycles



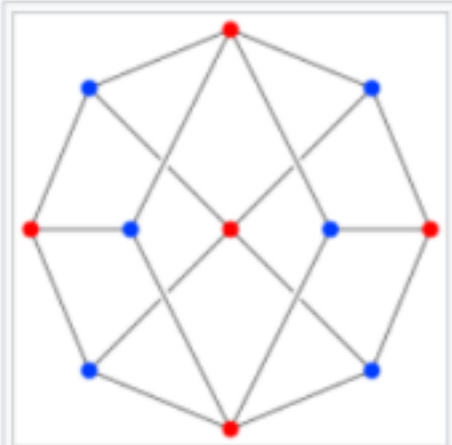
One possible **Hamiltonian cycle** through every vertex of a **dodecahedron** is shown in red - like all **platonic solids**, the dodecahedron is Hamiltonian



The above as a two-dimensional planar graph

https://en.wikipedia.org/wiki/Hamiltonian_path

Hamiltonian Cycles



The Herschel graph is the smallest possible polyhedral graph that does not have a Hamiltonian cycle.

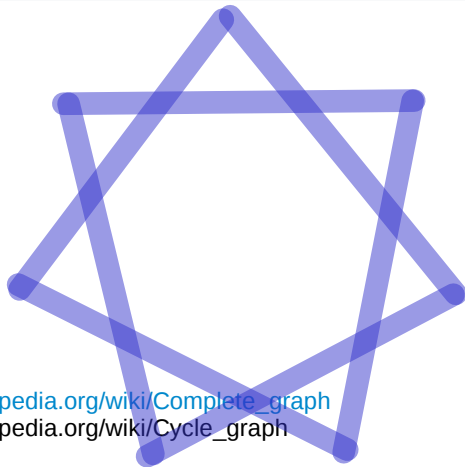
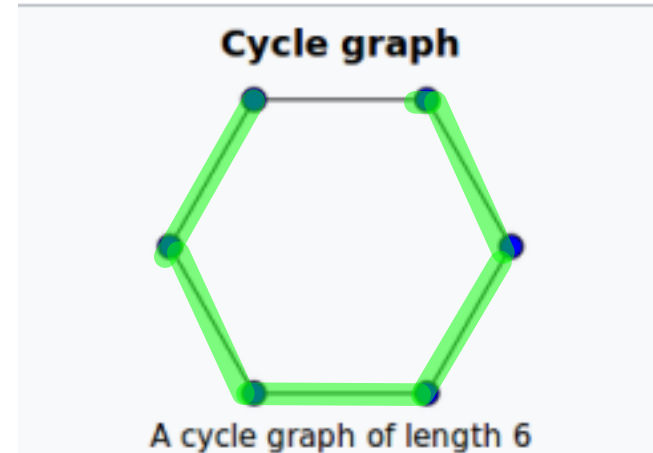
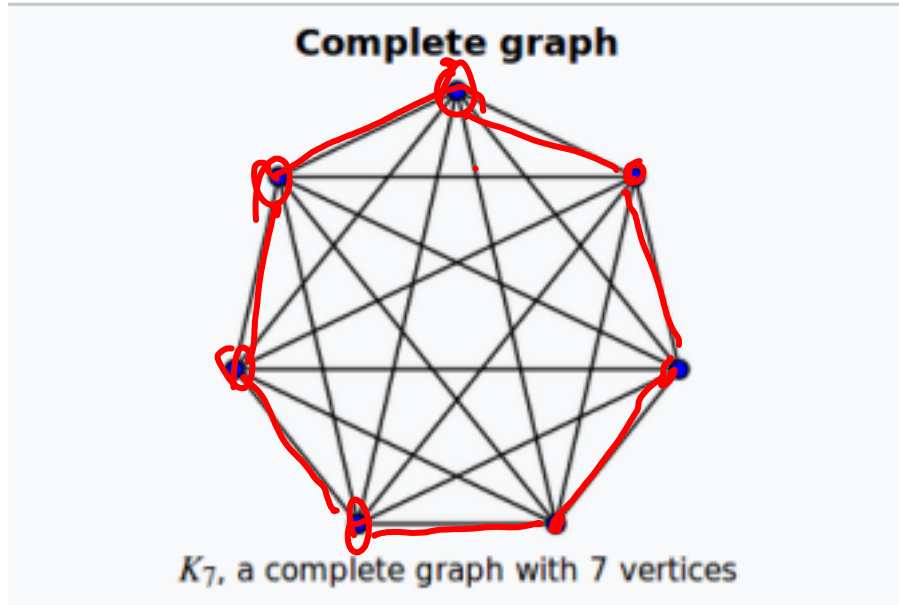
https://en.wikipedia.org/wiki/Hamiltonian_path

Hamiltonian Cycles

- a **complete graph** with more than two vertices is Hamiltonian
- every **cycle graph** is Hamiltonian
- every **tournament** has an odd number of Hamiltonian paths
- every **platonic solid**, considered as a graph, is Hamiltonian
- the **Cayley graph** of a finite **Coxeter** group is Hamiltonian



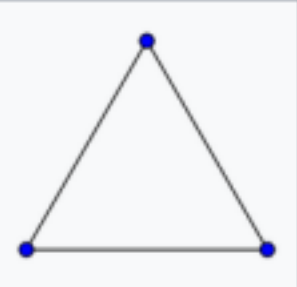
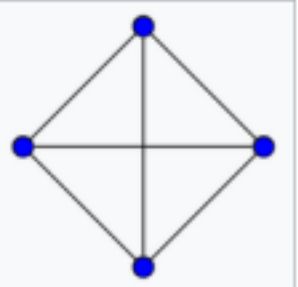
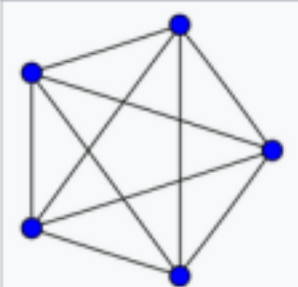
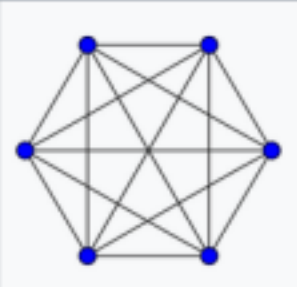
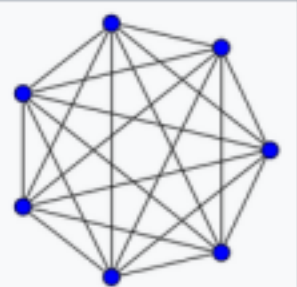
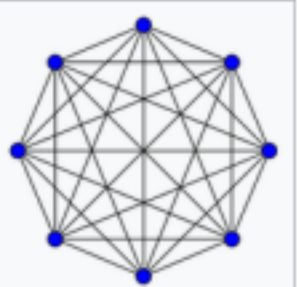
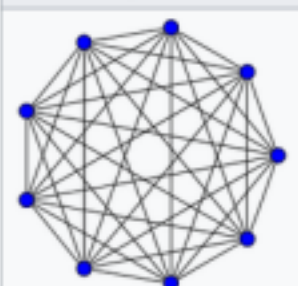
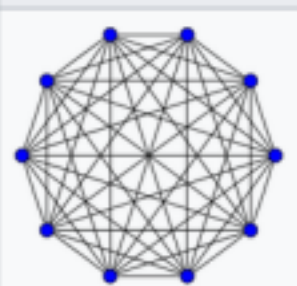


https://en.wikipedia.org/wiki/Hamiltonian_path

Complete Graphs and Cycle Graphs



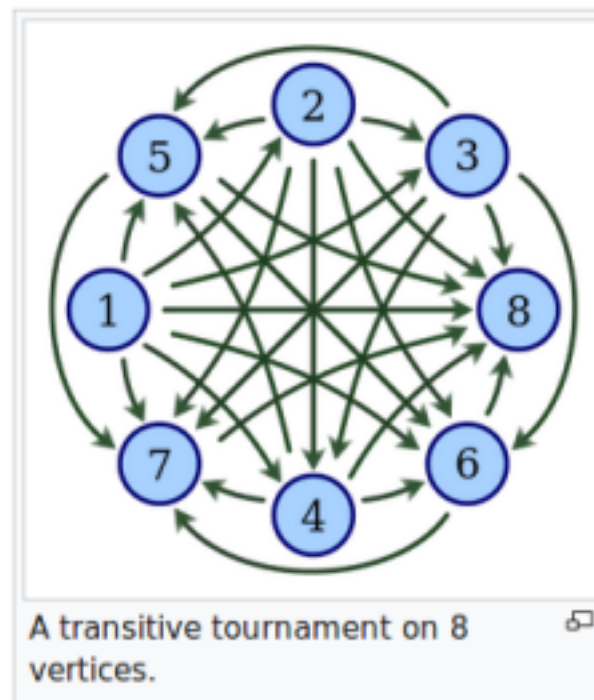
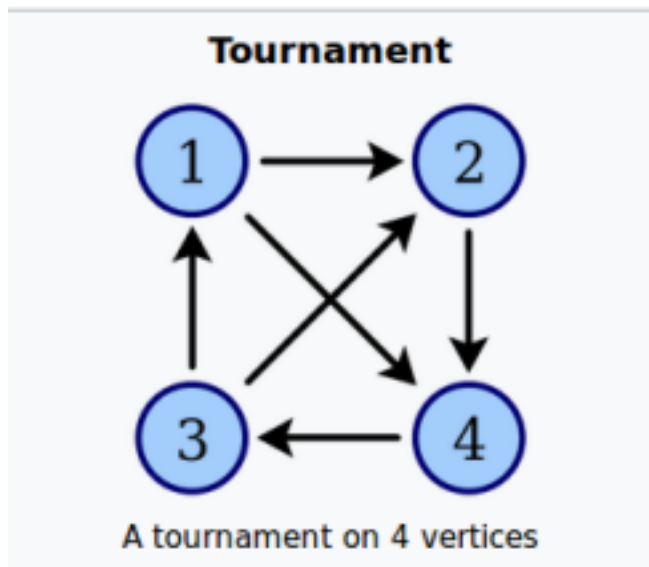
https://en.wikipedia.org/wiki/Complete_graph
https://en.wikipedia.org/wiki/Cycle_graph

Complete Graphs

$K_1: 0$	$K_2: 1$	$K_3: 3$	$K_4: 6$
			
$K_5: 10$	$K_6: 15$	$K_7: 21$	$K_8: 28$
			
$K_9: 36$	$K_{10}: 45$	$K_{11}: 55$	$K_{12}: 66$
			






https://en.wikipedia.org/wiki/Complete_graph

Tournament Graphs



[https://en.wikipedia.org/wiki/Tournament_\(graph_theory\)](https://en.wikipedia.org/wiki/Tournament_(graph_theory))

Platonic Solid Graphs

Tetrahedron	Cube	Octahedron	Dodecahedron	Icosahedron
Four faces	Six faces	Eight faces	Twelve faces	Twenty faces
				
(Animation) (3D model)	(Animation) (3D model)	(Animation) (3D model)	(Animation) (3D model)	(Animation) (3D model)

https://en.wikipedia.org/wiki/Platonic_solid

Hamiltonian Cycles – Properties (1)

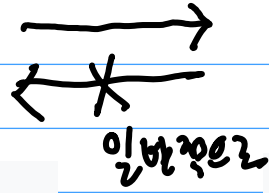
Any **Hamiltonian cycle** can be converted to a **Hamiltonian path** by removing one of its edges,

but a **Hamiltonian path** can be extended to **Hamiltonian cycle** only if its endpoints are adjacent.

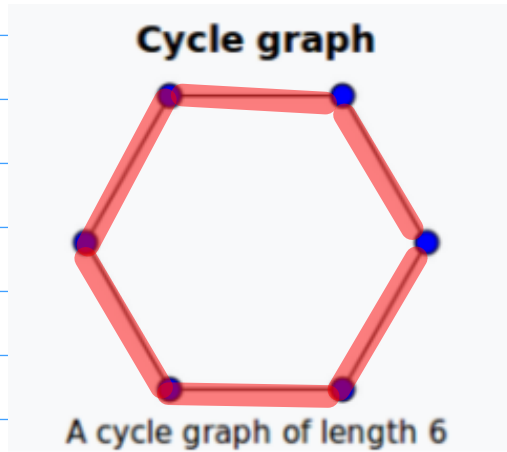
All **Hamiltonian graphs** are **biconnected**, but a biconnected graph need not be Hamiltonian .

https://en.wikipedia.org/wiki/Hamiltonian_path

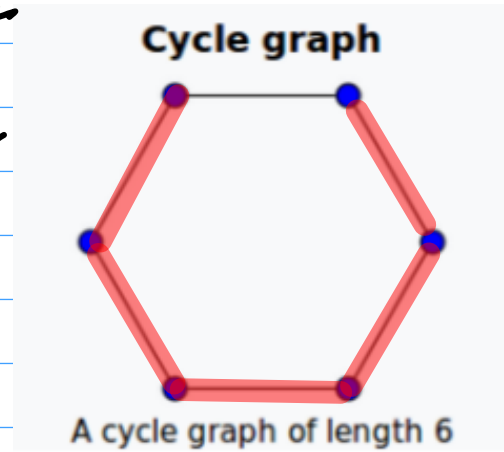
H. cycle



H. Path



이반향성
OK.



Biconnected Graph

a biconnected graph is a connected and "nonseparable" graph, meaning that if any one vertex were to be removed, the graph will remain connected.

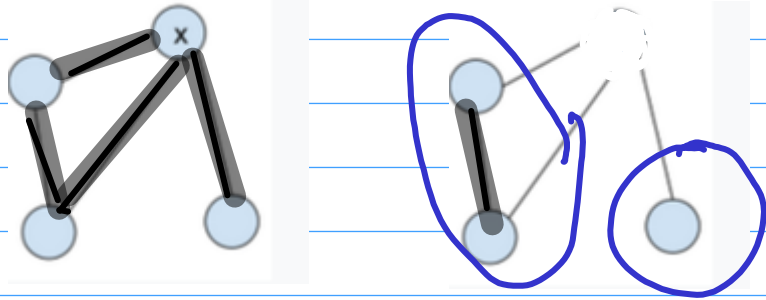
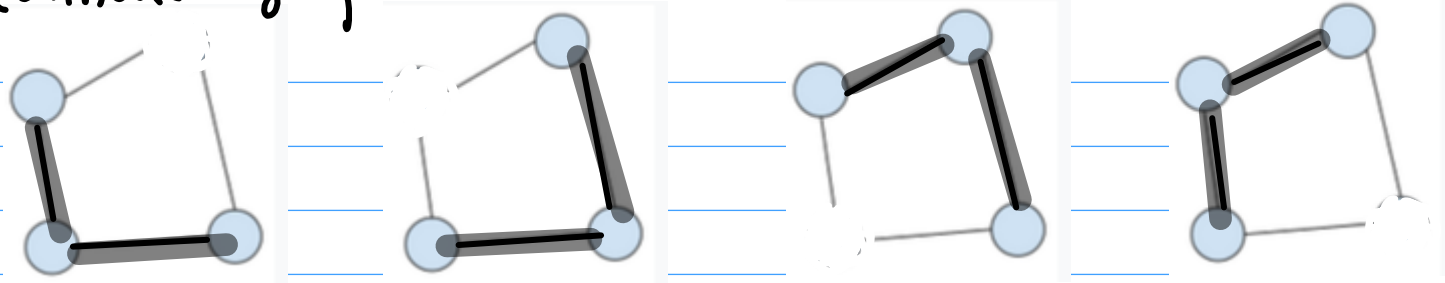
a biconnected graph has no articulation vertices.

The property of being **2-connected** is equivalent to **biconnectivity**, with the caveat that the complete graph of two vertices is sometimes regarded as biconnected but not 2-connected.

https://en.wikipedia.org/wiki/Biconnected_graph

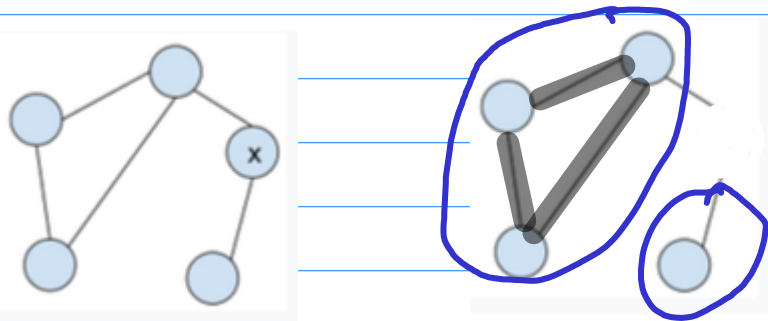
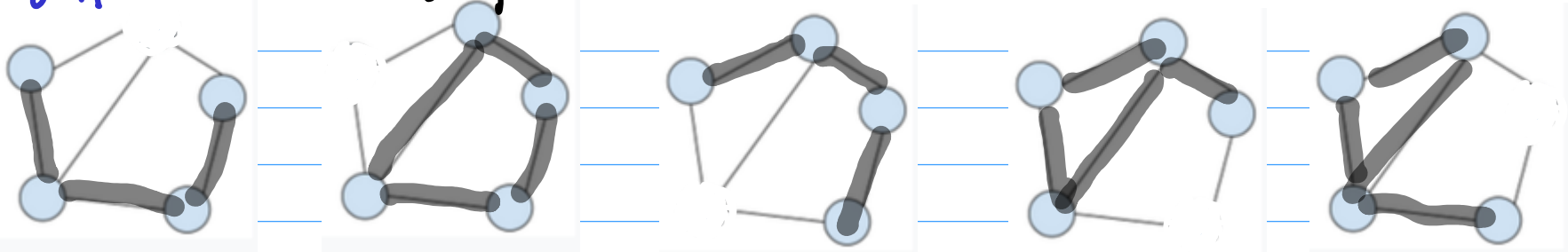
all

connected graph



2 components (disconnected)

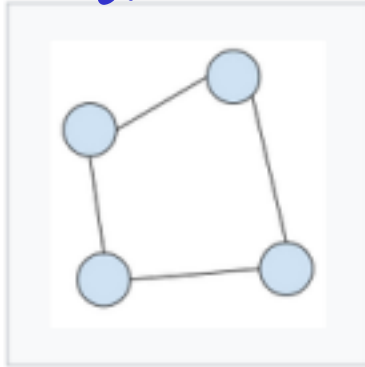
all connected graph



2 components (disconnected)

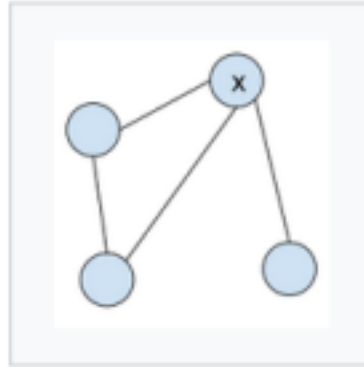
Biconnected Graph Examples

biconnected

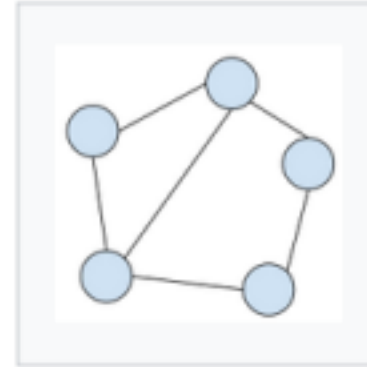


A biconnected graph on four vertices and four edges

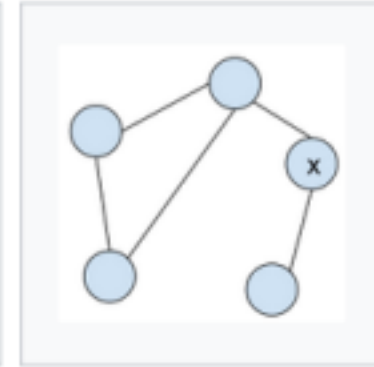
biconnected



A graph that is not biconnected. The removal of vertex x would disconnect the graph.



A biconnected graph on five vertices and six edges



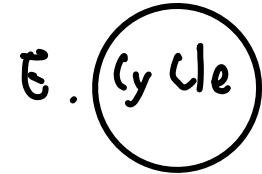
A graph that is not biconnected. The removal of vertex x would disconnect the graph.

https://en.wikipedia.org/wiki/Biconnected_graph

Hamiltonian Cycles – Properties (2)

An **Eulerian graph** G :

a **connected** graph in which every vertex has even degree →



An **Eulerian graph** G necessarily has an **Euler path**,
a closed walk passing through each **edge** of G exactly **once**.

This **Eulerian path** corresponds to a **Hamiltonian cycle** in
the **line graph** $L(G)$, so the line graph of every **Eulerian**
graph is **Hamiltonian**.

Line graphs may have other Hamiltonian cycles that do not
correspond to Euler paths.

The **line graph** $L(G)$ of every **Hamiltonian graph** G is itself
Hamiltonian, regardless of whether the graph G is **Eulerian**.

https://en.wikipedia.org/wiki/Hamiltonian_path

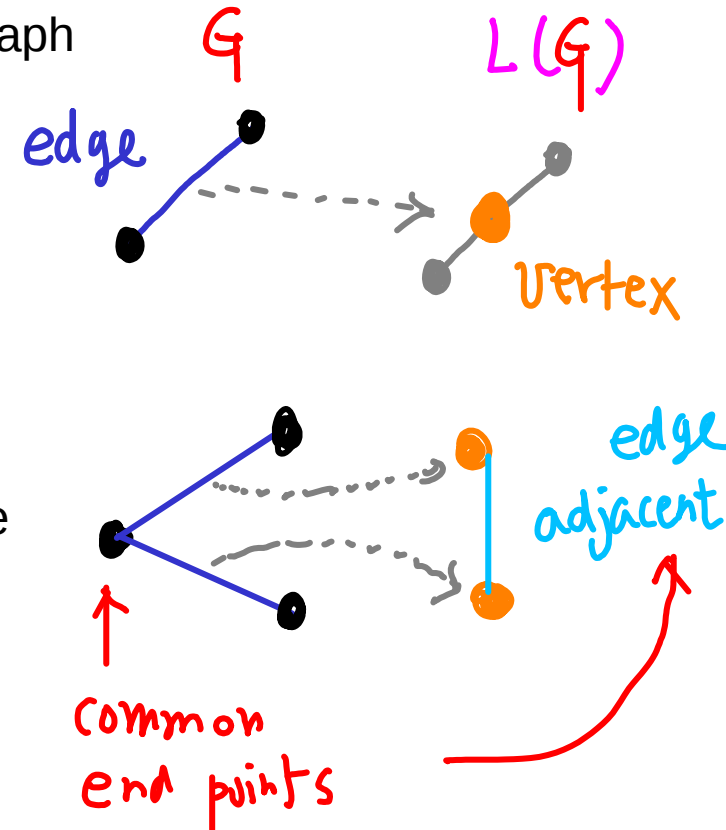
Line Graphs

In the mathematical discipline of graph theory, the line graph of an undirected graph G is another graph $L(G)$ that represents the adjacencies between edges of G .

Given a graph G , its line graph $L(G)$ is a graph such that

- each **vertex** of $L(G)$ represents an **edge** of G ; and
- two vertices of $L(G)$ are **adjacent** if and only if their corresponding edges share a **common endpoint** ("are incident") in G .

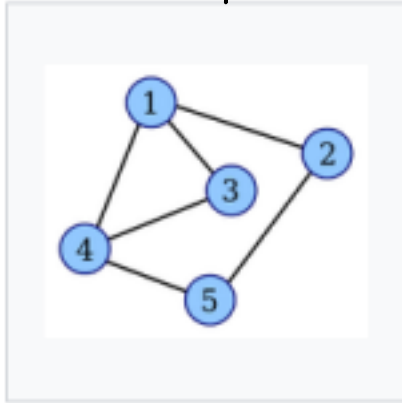
That is, it is the **intersection graph** of the edges of G , representing each edge by the set of its two endpoints.



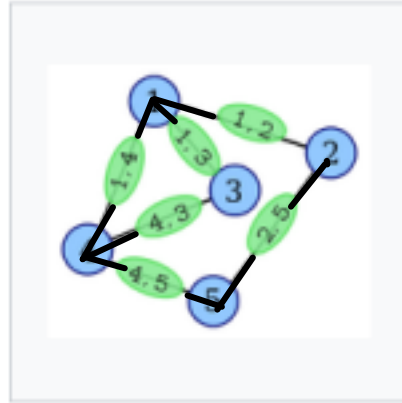
https://en.wikipedia.org/wiki/Line_graph

Line Graphs Examples

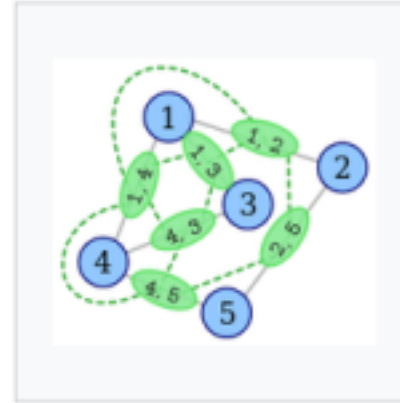
G



Graph G

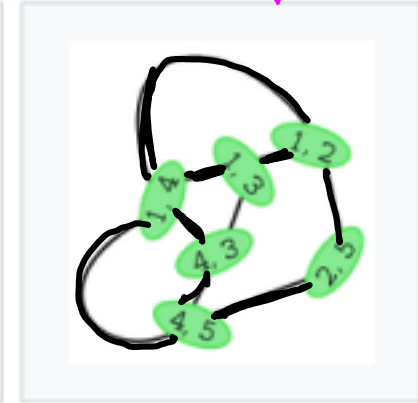


Vertices in $L(G)$
constructed from edges
in G



Added edges in $L(G)$

$L(G)$

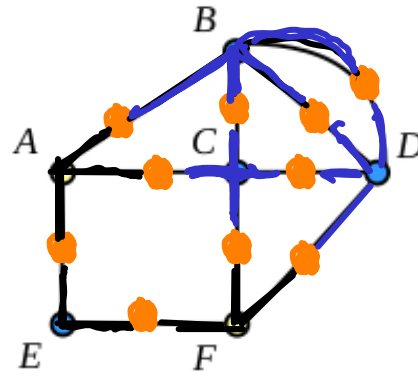
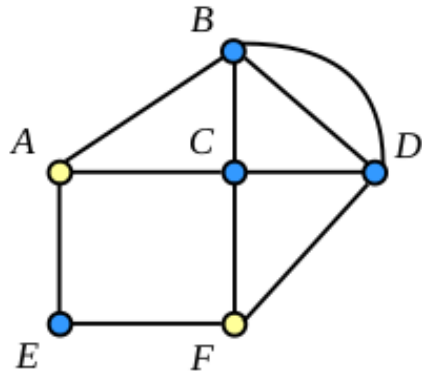


The line graph $L(G)$

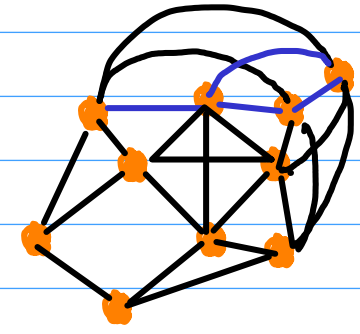
https://en.wikipedia.org/wiki/Line_graph



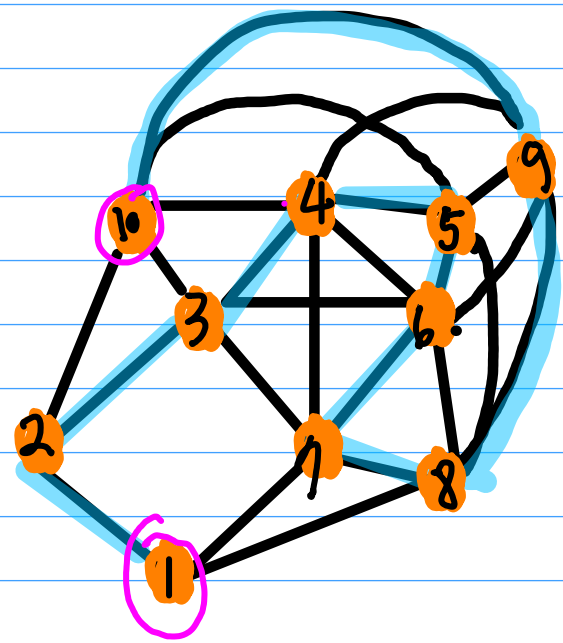
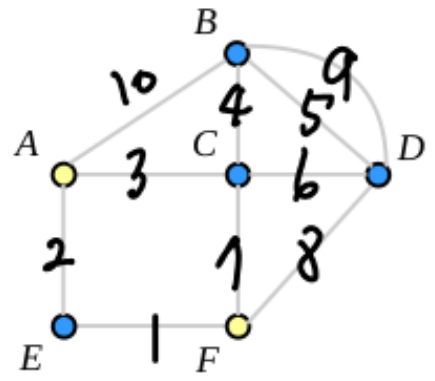
E. path



Hamilton cycle

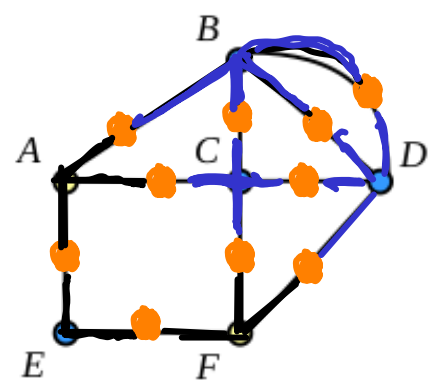
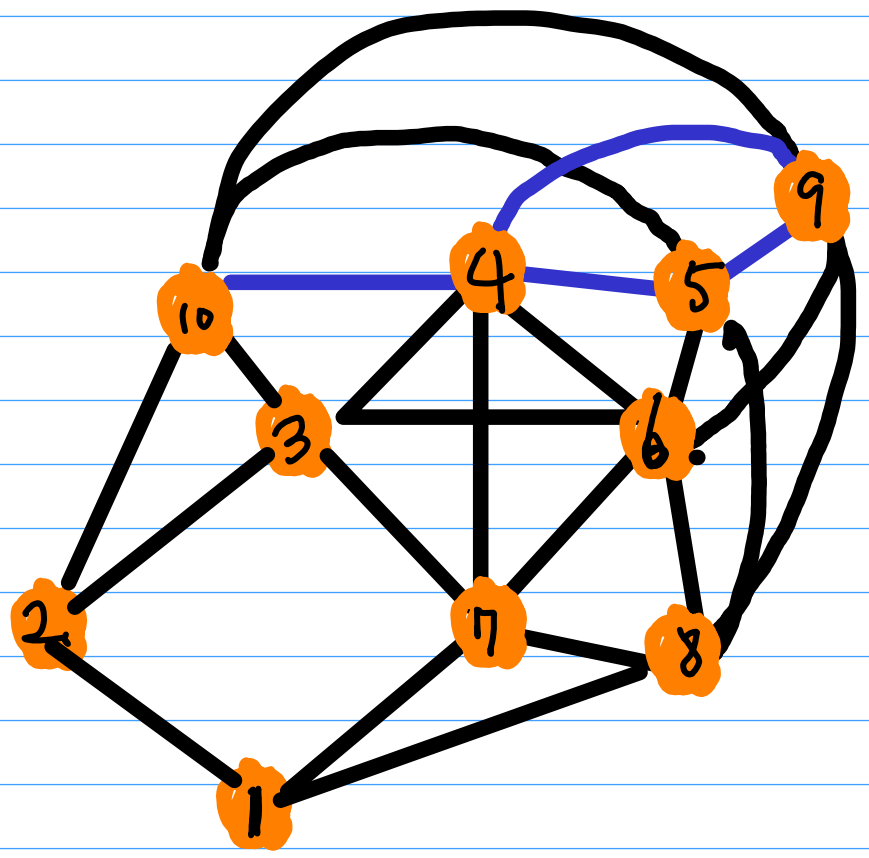
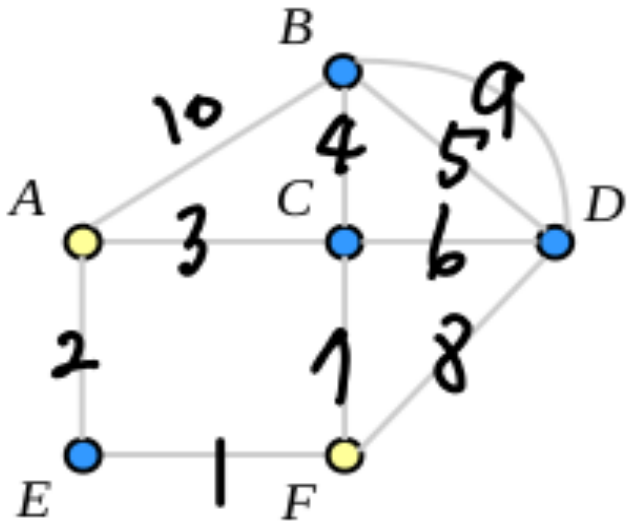


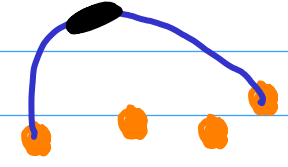
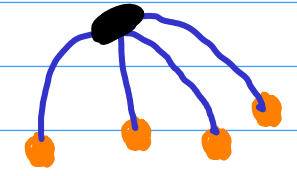
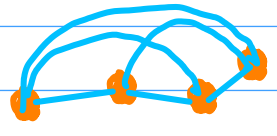
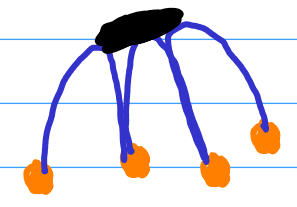
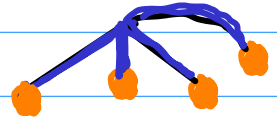
G
 모든 edge
 포함



L(G)
 모든 Vertex
 포함

12345678910





Hamiltonian Cycles – Properties (3)

A tournament (with more than two vertices) is Hamiltonian if and only if it is **strongly connected**.

The number of different Hamiltonian cycles
in a complete undirected graph on n vertices is $(n - 1)! / 2$
in a complete directed graph on n vertices is $(n - 1)!$.

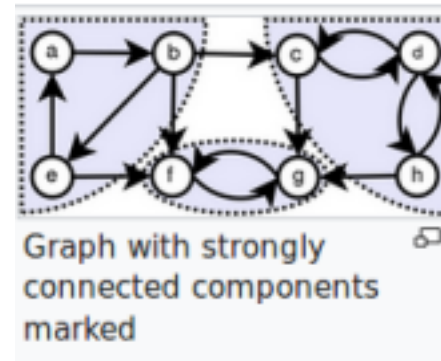
These counts assume that cycles that are the same apart from their starting point are not counted separately.

https://en.wikipedia.org/wiki/Hamiltonian_path

Strongly Connected Component

a directed graph is said to be **strongly connected** or **disconnected** if every **vertex** is reachable from every other **vertex**.

The **strongly connected components** or **disconnected components** of an arbitrary directed graph form a **partition** into **subgraphs** that are themselves **strongly connected**.



https://en.wikipedia.org/wiki/Hamiltonian_path

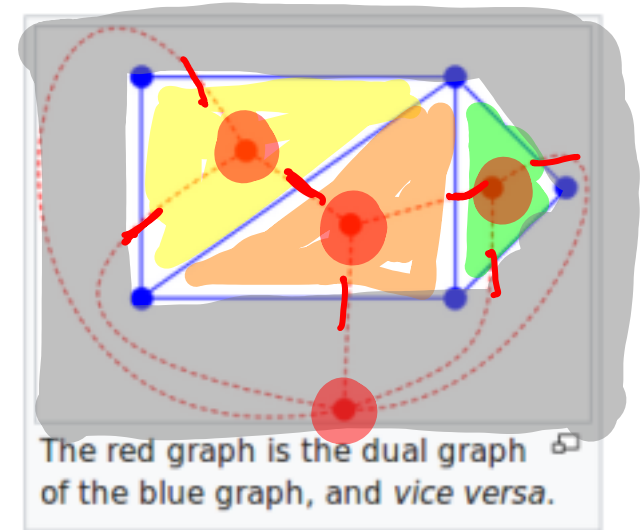
Dual Graph

the dual graph of a plane graph G is a graph that has a **vertex** for each **face** of G .

The dual graph has an **edge** whenever two **faces** of G are separated from each other by an **edge**,

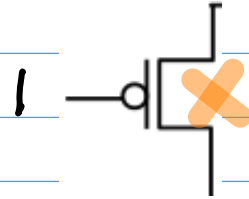
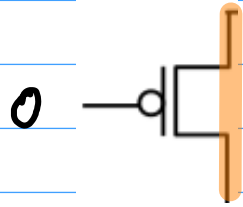
and a **self-loop** when the same face appears on both sides of an **edge**.

each **edge e** of G has a corresponding **dual edge**, whose endpoints are the **dual vertices** corresponding to the **faces** on either side of **e** .

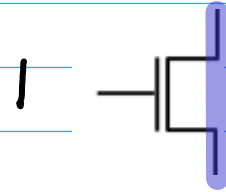
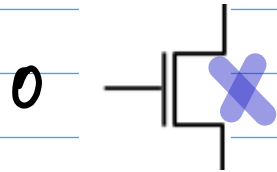


https://en.wikipedia.org/wiki/Hamiltonian_path

pMOS



nMOS

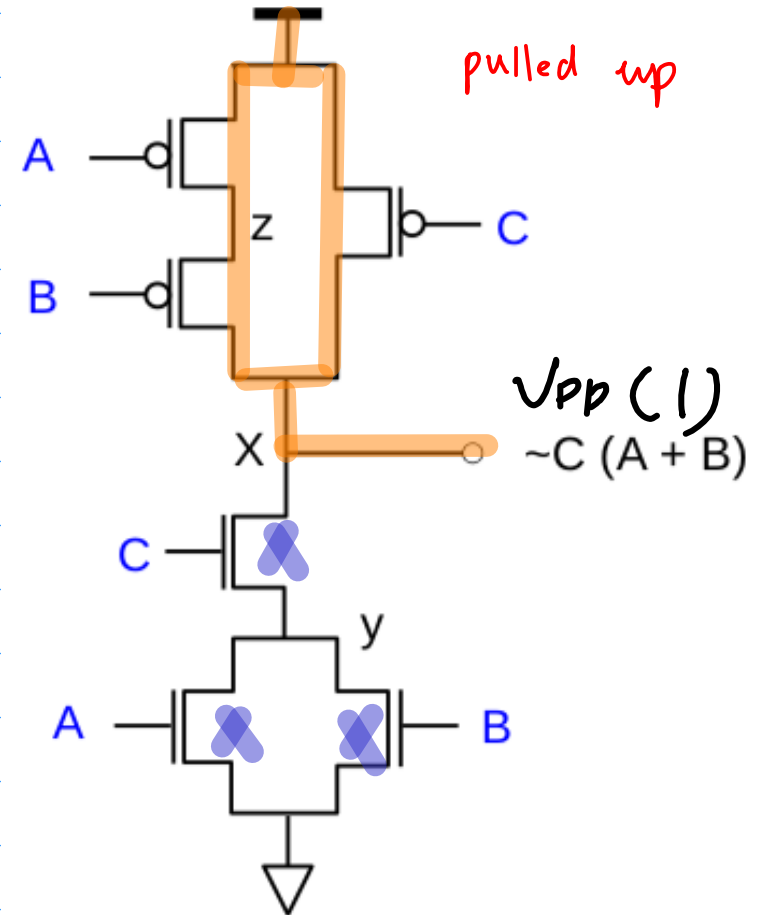


0 \rightarrow 0V - L - GND

1 \rightarrow 5V - H - V_{DD}

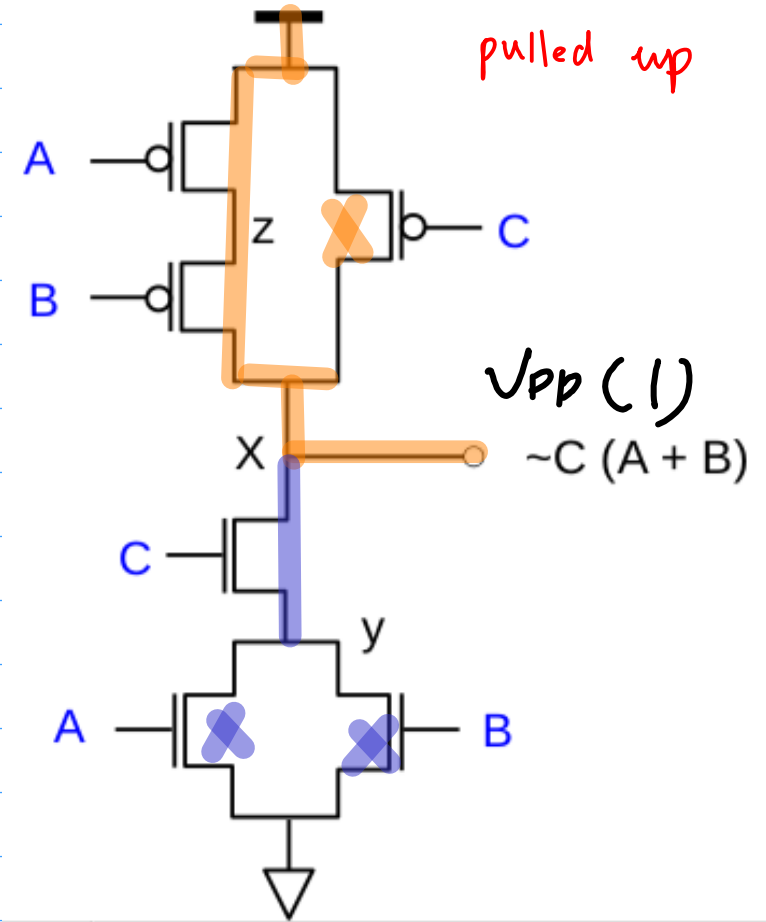
⑥

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



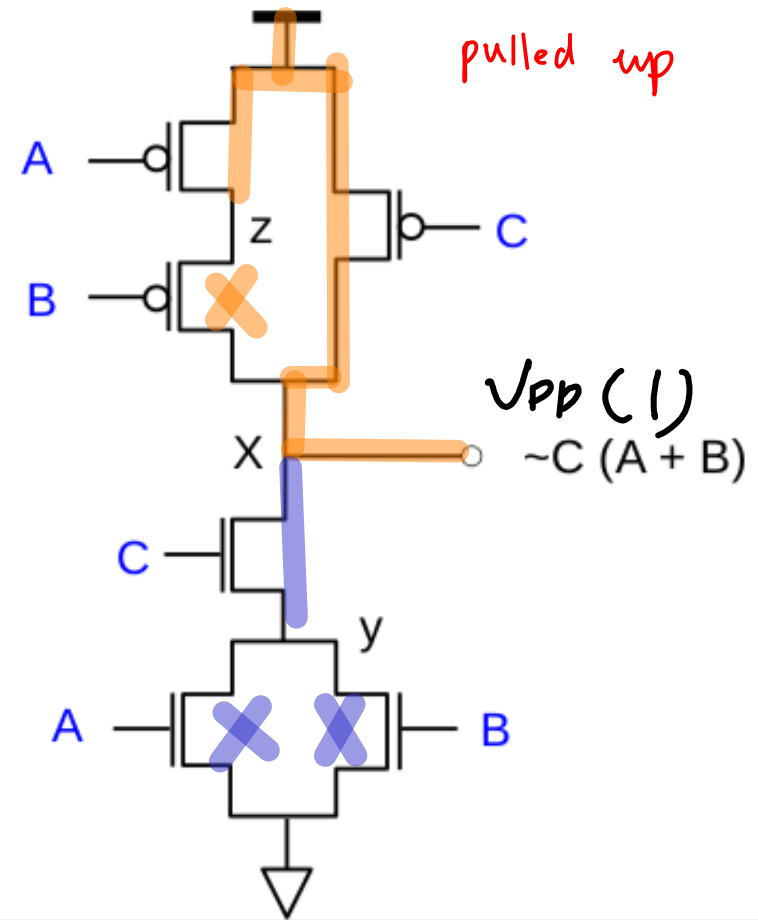
①

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



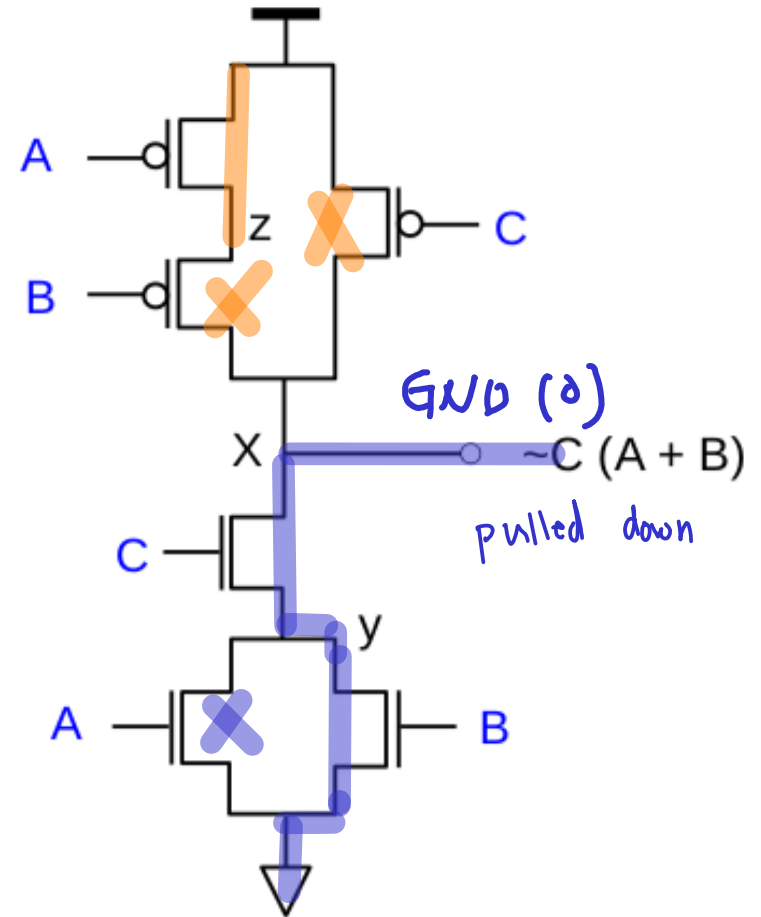
2

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



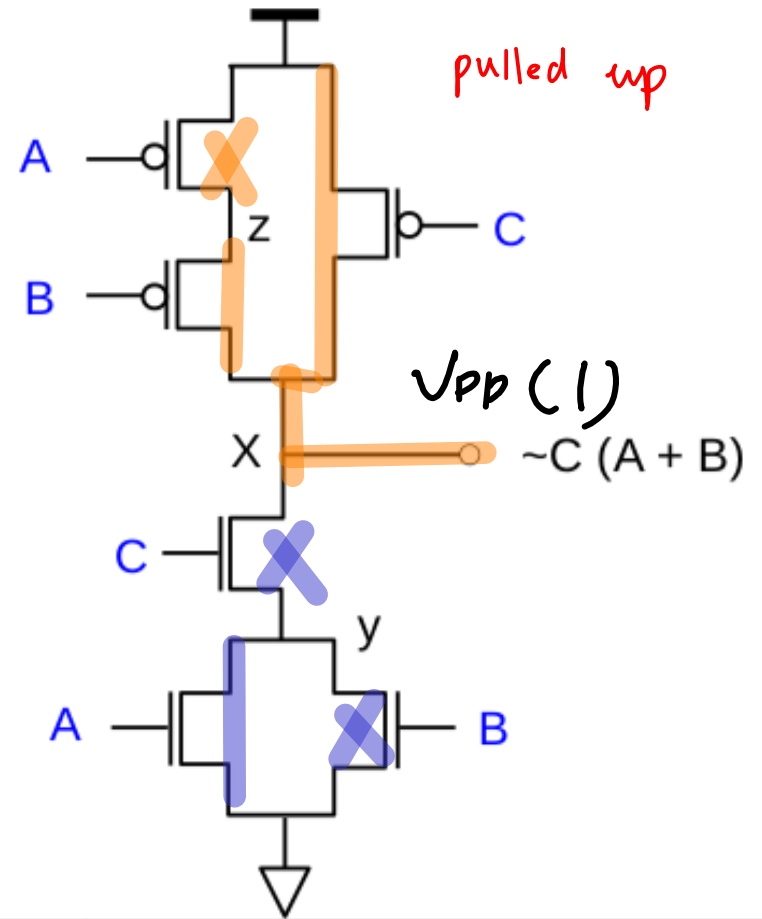
3

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



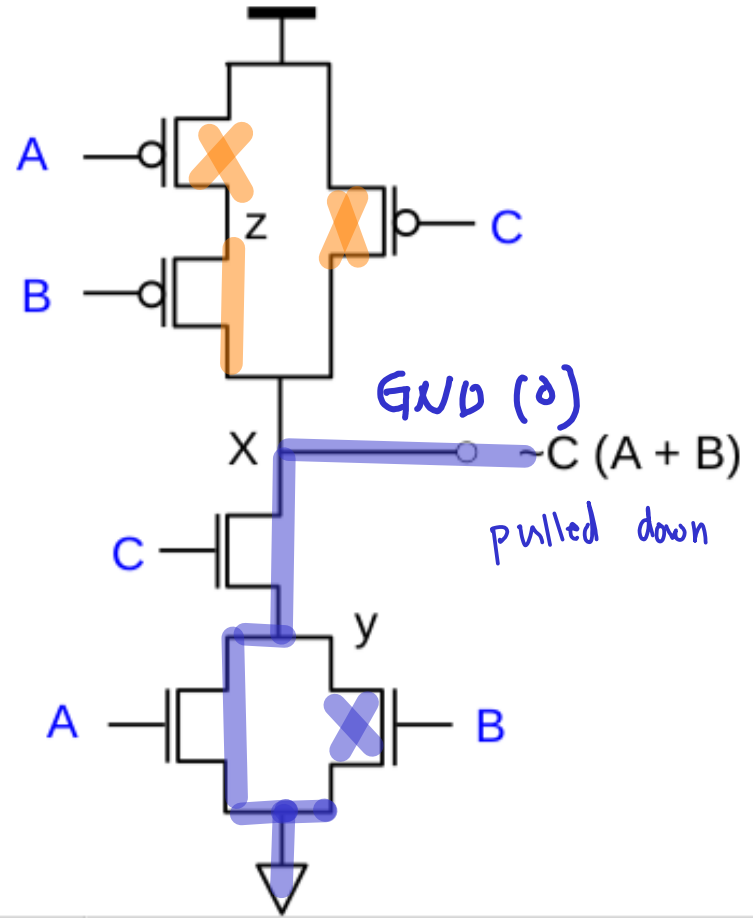
④

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



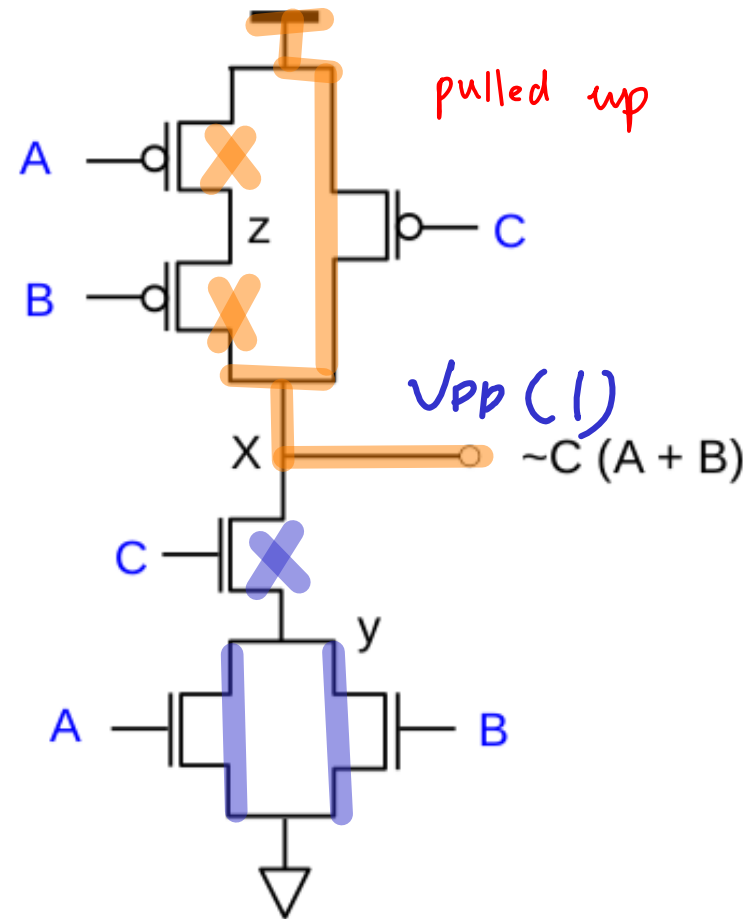
5

A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0



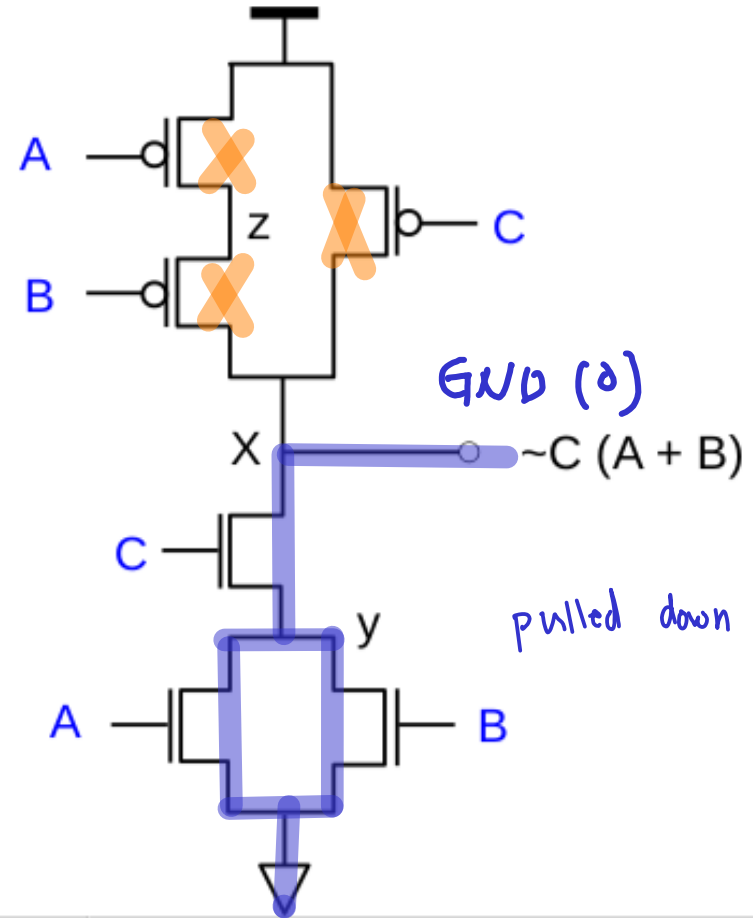
6

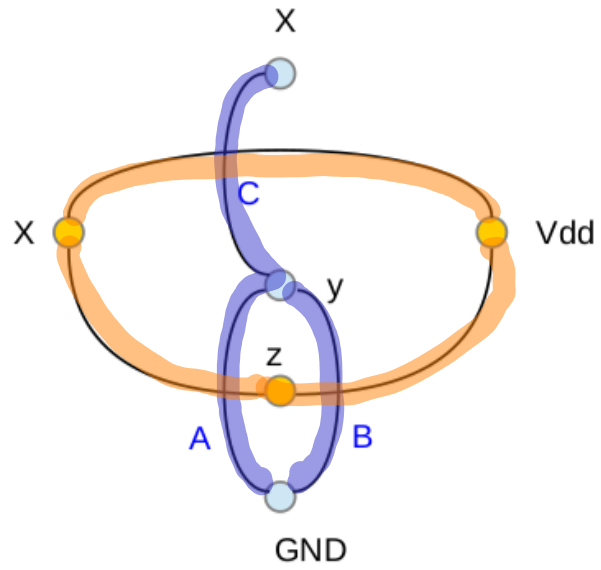
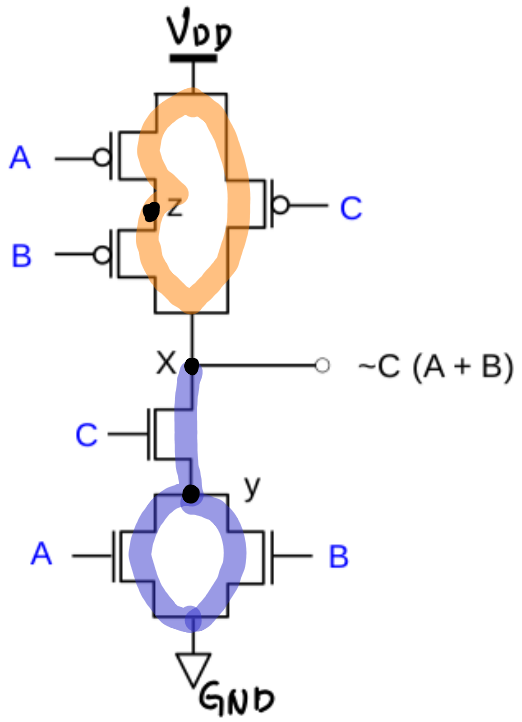
A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0

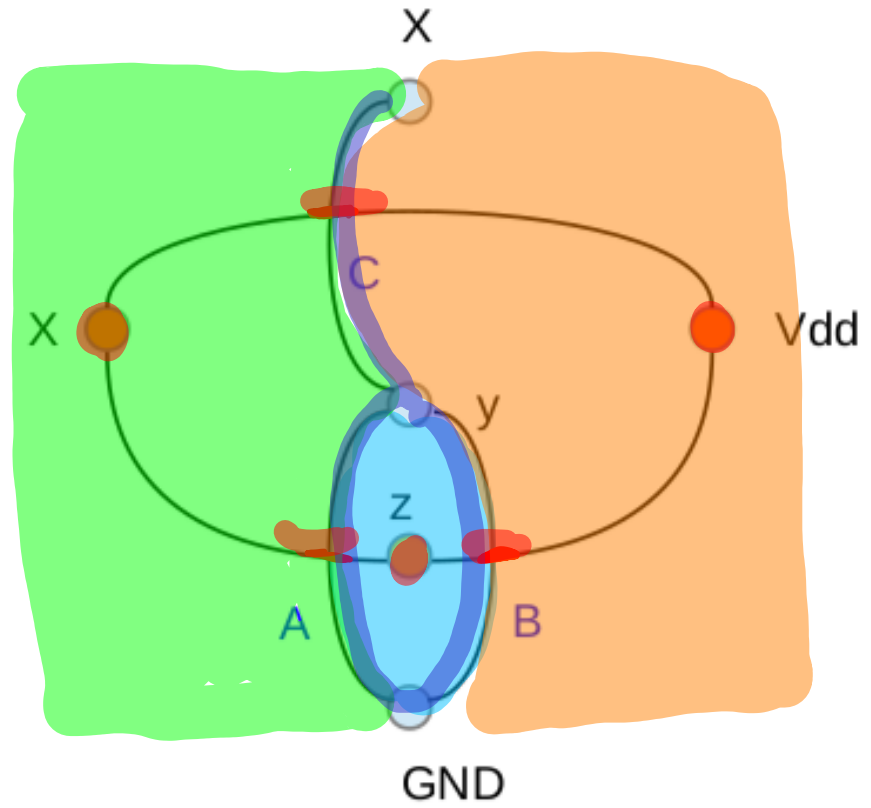
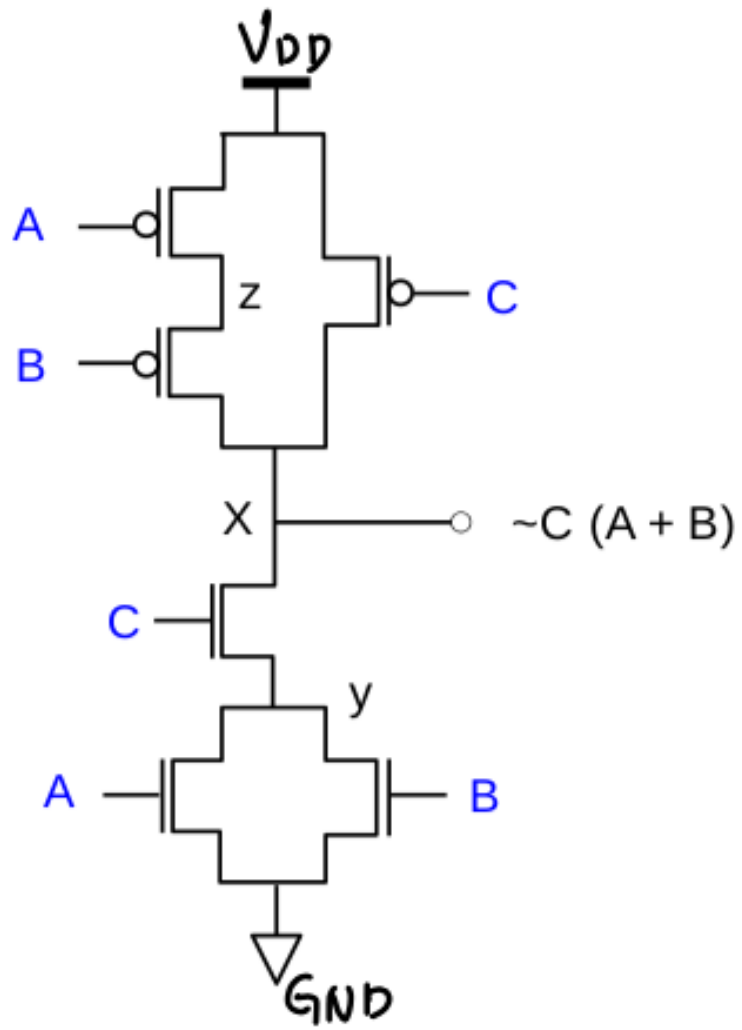


②

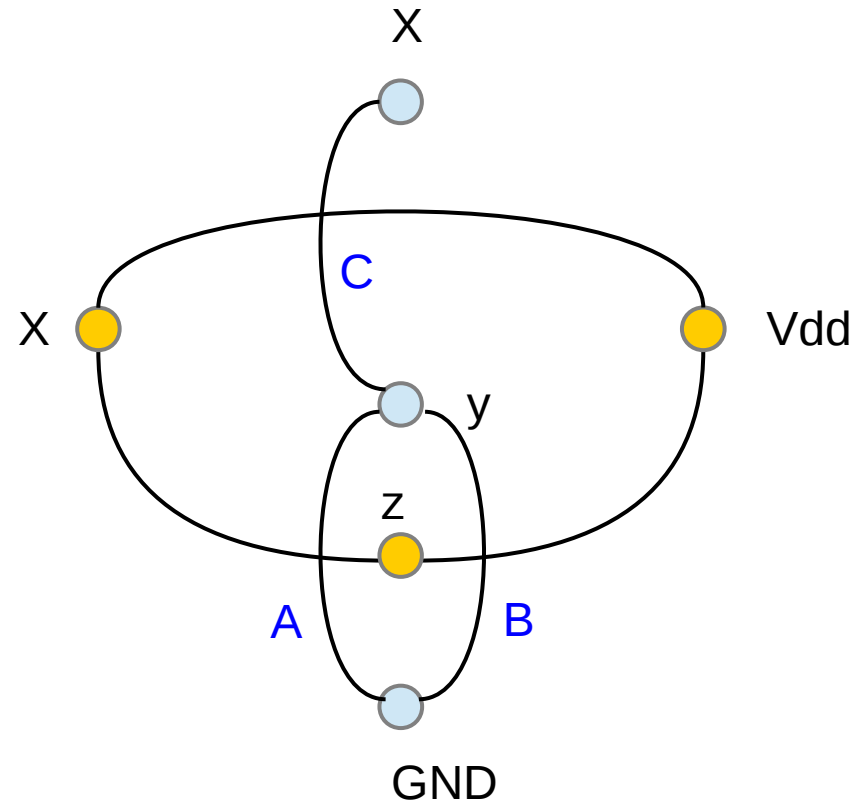
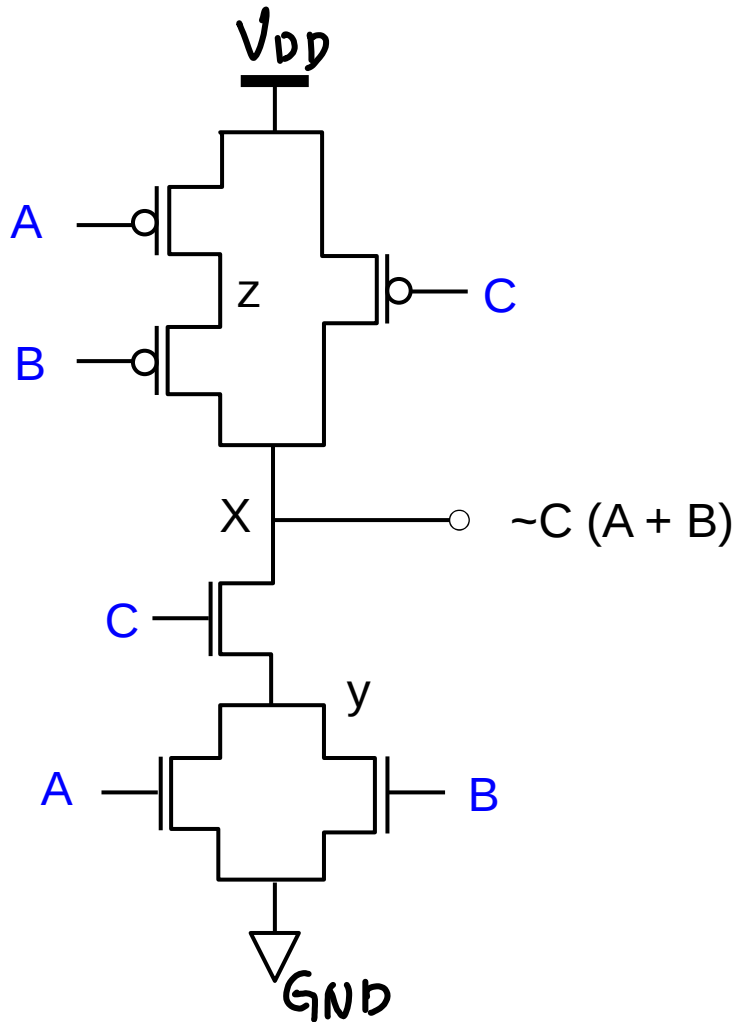
A	B	C	A+B	C(A+B)	$\sim C(A+B)$
0	0	0	0	0	1
0	0	1	0	0	1
0	1	0	1	0	1
0	1	1	1	1	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	0	1
1	1	1	1	1	0







Dual Graph



https://en.wikipedia.org/wiki/Hamiltonian_path

References

- [1] <http://en.wikipedia.org/>
- [2]

Minimum Spanning Tree (5A)

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Please send corrections (or suggestions) to youngwlim@hotmail.com.

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Minimum Spanning Tree

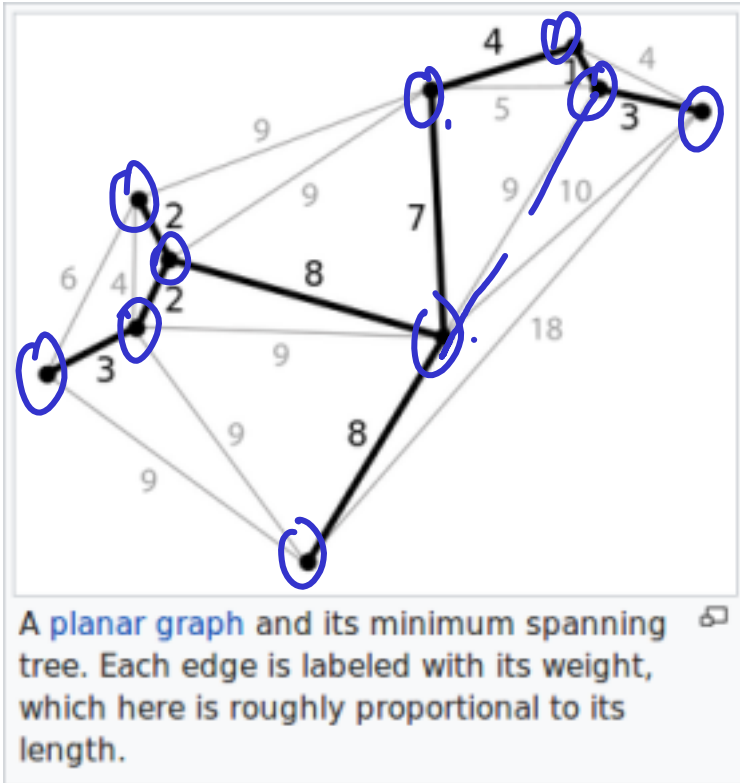
a **subset** of the **edges** of a connected, edge-weighted (un)directed graph that connects **all** the **vertices** together, without any **cycles** and with the **minimum** possible total edge **weight**.

a spanning tree whose sum of edge weights is as small as possible.

More generally, any edge-weighted undirected graph (not necessarily connected) has a minimum spanning **forest**, which is a **union** of the minimum spanning **trees** for its connected components.

https://en.wikipedia.org/wiki/Minimum_spanning_tree

Types of Shortest Path Problems



tree

loop X

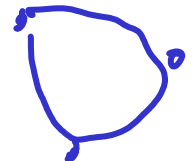


cycle X



10 vertices

$$3 + 2 + 2 + 8 + 7 + 8 + 4 + 1 + 5$$



https://en.wikipedia.org/wiki/Minimum_spanning_tree

Properties (1)

Possible multiplicity

If there are **n vertices** in the graph, then each spanning tree has **n-1 edges**.

Uniqueness

If each edge has a distinct weight then there will be only one, unique minimum spanning tree. this is true in many realistic situations

Minimum-cost subgraph

If the weights are positive, then a minimum spanning tree is in fact a minimum-cost subgraph connecting **all vertices**, since subgraphs containing cycles necessarily have more total weight.

https://en.wikipedia.org/wiki/Minimum_spanning_tree

Properties (2)

Cycle Property

For any **cycle C** in the graph, if the weight of an **edge e** of **C** is larger than the individual weights of all other edges of **C**, then this edge cannot belong to a MST.

Cut property

For any **cut C** of the graph, if the weight of an **edge e** in the **cut-set** of **C** is strictly smaller than the weights of all other edges of the **cut-set** of **C**, then this edge belongs to all MSTs of the graph.

https://en.wikipedia.org/wiki/Minimum_spanning_tree

Properties (3)

Minimum-cost edge

If the minimum cost **edge** e of a graph is unique, then this edge is included in any MST.

Contraction

If T is a **tree** of **MST edges**, then we can contract T into a single vertex while maintaining the invariant that the MST of the contracted graph plus T gives the MST for the graph before contraction.

https://en.wikipedia.org/wiki/Minimum_spanning_tree

Borůvka's algorithm

Input: A graph G whose edges have distinct weights
Initialize a forest F to be a set of one-vertex trees,
one for each vertex of the graph.

While F has more than one component:

Find the connected components of F and
label each vertex of G by its component

Initialize the cheapest edge for each component to "None"

For each edge uv of G :

If u and v have different component labels:

If uv is cheaper than the cheapest edge
for the component of u :

Set uv as the cheapest edge for the component of u

If uv is cheaper than the cheapest edge
for the component of v :

Set uv as the cheapest edge for the component of v

For each component whose cheapest edge
is not "None":

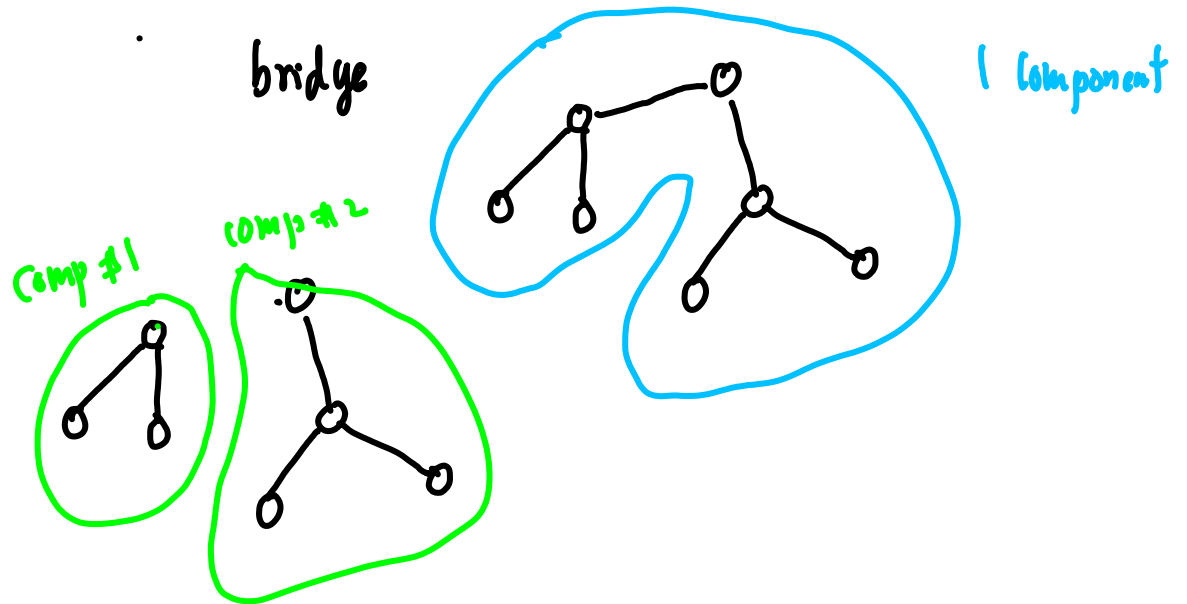
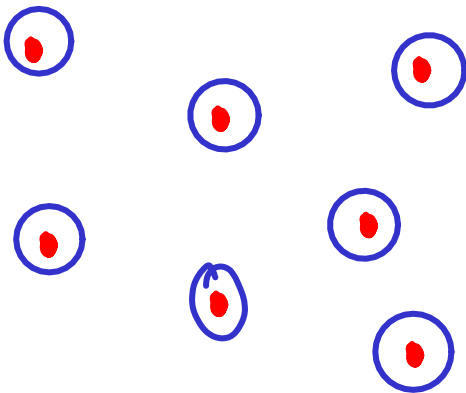
Add its cheapest edge to F

Output: F is the minimum spanning forest of G .

https://en.wikipedia.org/wiki/Bor%C5%AFvka%27s_algorithm

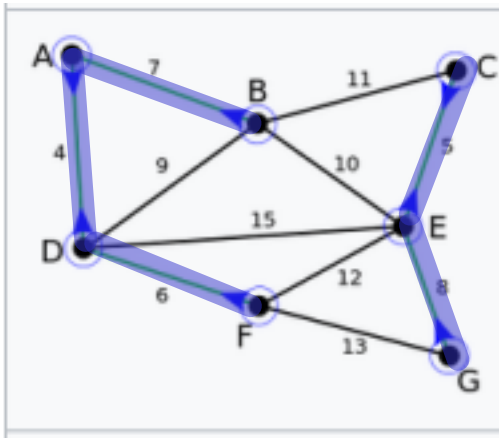
Borůvka's algorithm examples (1)

Image	components	Description
	{A} {B} {C} {D} {E} {F} {G}	This is our original weighted graph. The <u>numbers</u> near the edges indicate their <u>weight</u> . Initially, every <u>vertex</u> by itself is a <u>component</u> (blue circles).



https://en.wikipedia.org/wiki/Bor%C5%AFvka%27s_algorithm

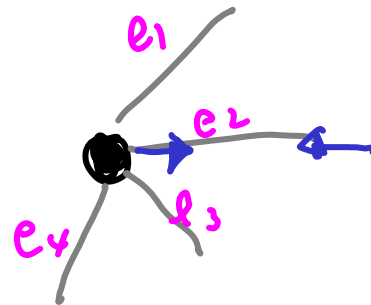
Borůvka's algorithm examples (2)



②
connected
components

{A,B,D,F}
{C,E,G}

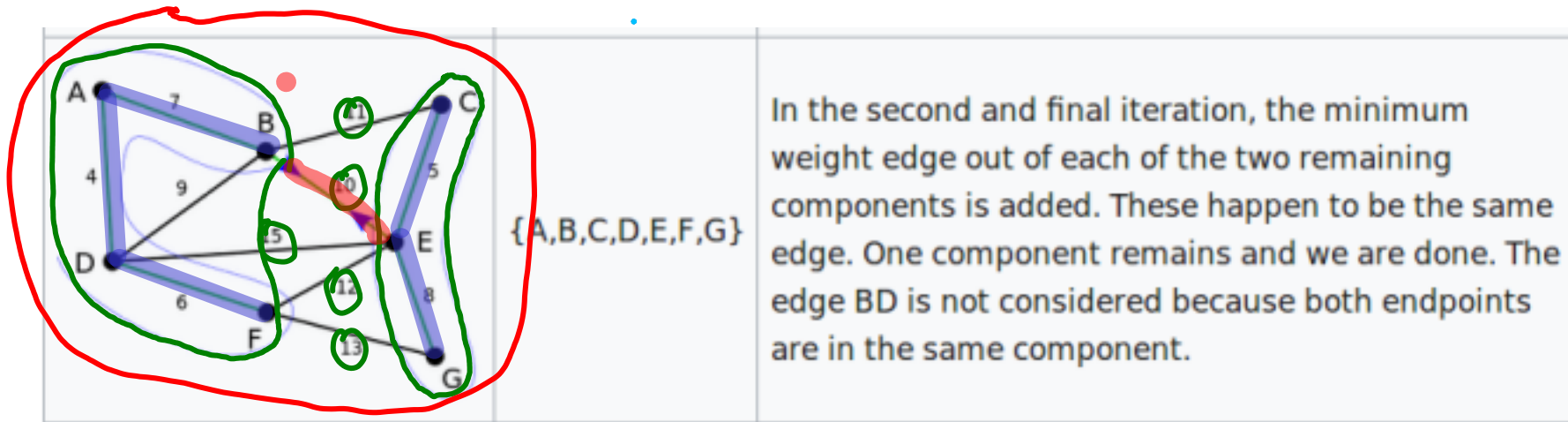
In the first iteration of the outer loop, the minimum weight edge out of every component is added. Some edges are selected twice (AD, CE). Two components remain.



$$\min\{e_1, e_2, e_3, e_4\}$$

https://en.wikipedia.org/wiki/Bor%C5%AFvka%27s_algorithm

Borůvka's algorithm examples (3)



tree no cycle

Spanning ... A, B, C, D, E, F, G

minimum ... $6 + 4 + 7 + 10 + 5 + 8 =$

https://en.wikipedia.org/wiki/Bor%C5%AFvka%27s_algorithm

Kruskal's algorithm

KRUSKAL(G):

1 $A = \emptyset$

2 **foreach** $v \in G.V$:

3 MAKE-SET(v)

4 **foreach** (u, v) in $G.E$ ordered by $\text{weight}(u, v)$, increasing:

5 if FIND-SET(u) \neq FIND-SET(v):

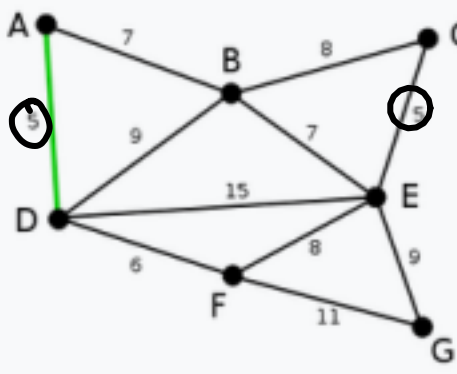
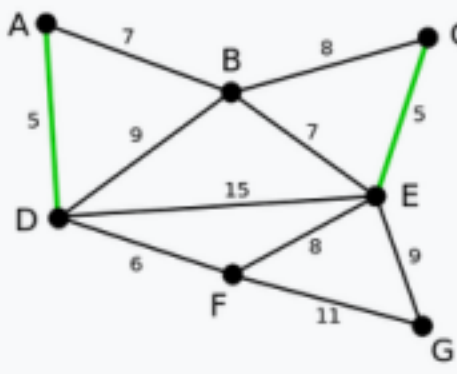
6 $A = A \cup \{(u, v)\}$

7 UNION(u, v)

8 **return** A

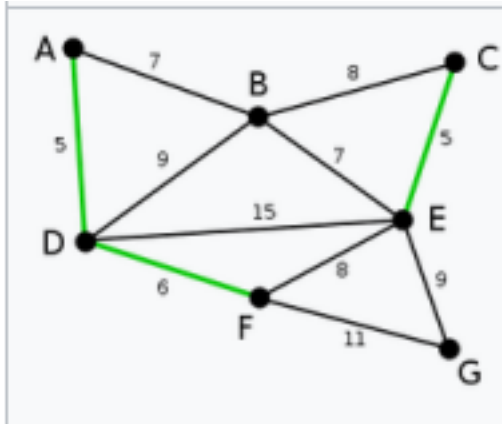
https://en.wikipedia.org/wiki/Kruskal%27s_algorithm

Kruskal's algorithm examples (1)

	<p>$5, 5, 6, 7, 7, 8, 8, 9, 9, 11, 15$</p> <p>AD and CE are the shortest edges, with length 5, and AD has been arbitrarily chosen, so it is highlighted.</p>
	<p>$5, 5, 6, 7, 7, 8, 8, 9, 9, 11, 15$</p> <p>CE is now the shortest edge that does <u>not form a cycle</u>, with length 5, so it is highlighted as the second edge.</p>

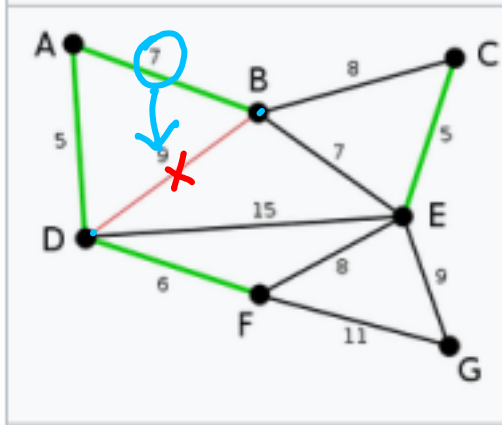
https://en.wikipedia.org/wiki/Kruskal%27s_algorithm

Kruskal's algorithm examples (2)



5, 5, 6, 7, 7, 8, 8, 9, 9, 11, 15

The next edge, **DF** with length 6, is highlighted using much the same method.

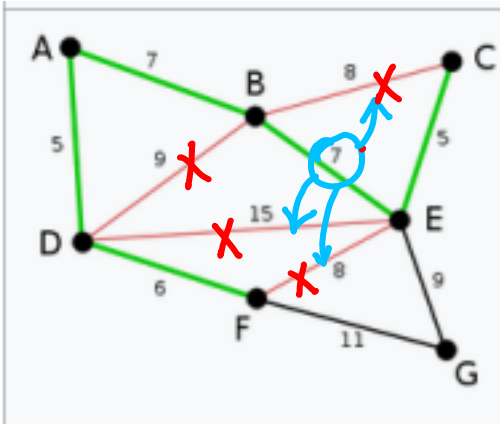


5, 5, 6, 7, 7, ~~8~~, 8, 9, 9, 11, 15

The next-shortest edges are **AB** and **BE**, both with length 7. **AB** is chosen arbitrarily, and is highlighted. The edge **BD** has been highlighted in red, because there already exists a path (in green) between **B** and **D**, so it would form a cycle (**ABD**) if it were chosen.

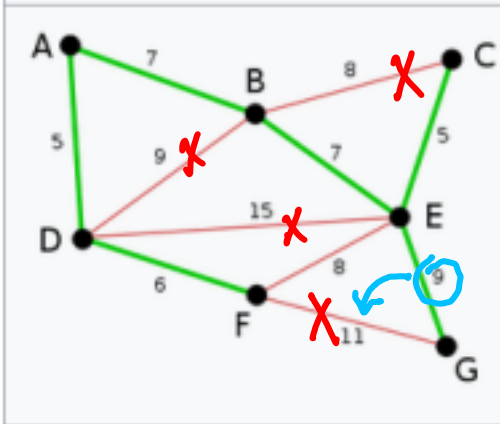
https://en.wikipedia.org/wiki/Kruskal%27s_algorithm

Kruskal's algorithm examples (3)



5, 5, 6, 7, 7, 8, 8, 9, 9, 11, 15

The process continues to highlight the next-smallest edge, **BE** with length 7. Many more edges are highlighted in red at this stage: **BC** because it would form the loop **BCE**, **DE** because it would form the loop **DEBA**, and **FE** because it would form **FEBAD**.



5, 5, 6, 7, 7, 8, 8, 9, 11, 15

Finally, the process finishes with the edge **EG** of length 9, and the minimum spanning tree is found.

https://en.wikipedia.org/wiki/Kruskal%27s_algorithm

Prim's algorithm

a greedy algorithm that finds a minimum spanning tree for a weighted undirected graph.

operates by building this tree one vertex at a time, from an arbitrary starting vertex, at each step adding the cheapest possible connection from the tree to another vertex.

1. Initialize a tree with a single vertex, chosen arbitrarily from the graph.
2. Grow the tree by one edge: of the edges that connect the tree to vertices not yet in the tree, find the minimum-weight edge, and transfer it to the tree.
3. Repeat step 2 (until all vertices are in the tree).

https://en.wikipedia.org/wiki/Prim%27s_algorithm

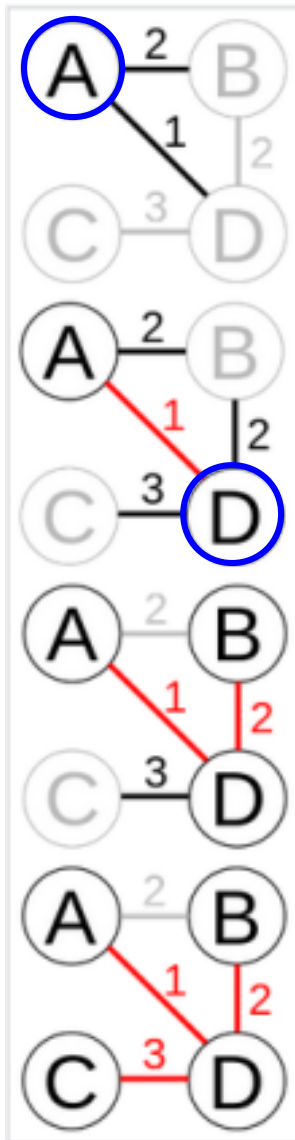
Prim's algorithm

1. Associate with each vertex v of the graph a number $C[v]$ (the cheapest cost of a connection to v) and an edge $E[v]$ (the cheapest edge).
Initial values: $C[v] = +\infty$, $E[v] = \text{flag for no connection}$
2. Initialize an empty **forest** F and a **set** Q of **vertices** that have not yet been included in F
3. Repeat the following steps until Q is empty:
 - a. Find and remove a vertex v from Q having the minimum possible value of $C[v]$
 - b. Add v to F and, if $E[v]$ is not the special flag value, also add $E[v]$ to F
 - c. Loop over the edges vw connecting v to other vertices w . For each such edge, if w still belongs to Q and vw has smaller weight than $C[w]$, perform the following steps:
 - I) Set $C[w]$ to the cost of edge vw
 - II) Set $E[w]$ to point to edge vw .

Return F

https://en.wikipedia.org/wiki/Prim%27s_algorithm

Prim's algorithm



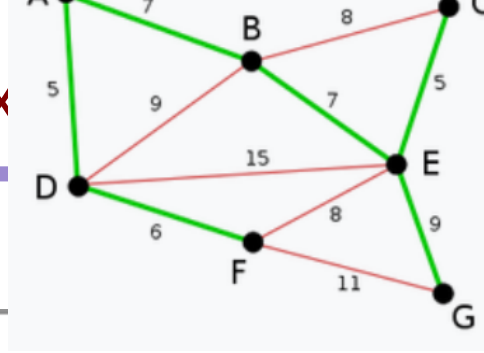
Prim's algorithm starting at vertex A.

In the third step, edges BD and AB both have weight 2, so BD is chosen arbitrarily.

After that step, AB is no longer a candidate for addition to the tree because it links two nodes that are already in the tree.

https://en.wikipedia.org/wiki/Kruskal%27s_algorithm

Prim's algorithm ex



	<p>This is the initial weighted graph. It is not a tree, since to be a tree it is required that there are no cycles, and in this case there is. The numbers near the edges indicate the weight. None of the edges is marked, and vertex D has been chosen arbitrarily as the starting point.</p>	C, G	A, B, E, F	D
	<p>The second vertex is closest to D : A is 5 away, B is 9, E is 15, and F is 6. Of these, 5 is the smallest value, so we mark the DA edge.</p> <p>(5) 9, 15, 6</p>	C, G	B, E, F	A, D

https://es.wikipedia.org/wiki/Algoritmo_de_Prim

Prim's algorithm examples (2)

	<p>⑤ 9, 15, ⑥</p> <p>The next vertex to choose is the closest to D or A. B is 9 away from D and 7 away from A, E is at 15, and F is at 6. 6 is the smallest value, so we mark the vertex F and the edge DF.</p>	C	B, E, G	A, D, F
	<p>The algorithm continues. The vertex B, which is at a distance of 7 from A, is the next one marked. At this point the edge DB is marked in red because its two ends are already in the tree and therefore can not be used.</p>	null	C, E, G	A, D, F, B

https://es.wikipedia.org/wiki/Algoritmo_de_Prim

Prim's algorithm examples (3)

	<p>Here you have to choose between C , E and G. C is 8 away from B , E is 7 away from B , and G is 11 away from F. E is closer, so we mark the vertex E and the edge EB . Two other edges were marked in red because both vertices that join were added to the tree.</p>	<p>null</p>	<p>C, G</p>	<p>A, D, F, B, E</p>
	<p>Only C and G are available. C is 5 away from E , and G is 9 away from E. Choose C , and mark with the arc EC . The BC arc is also marked with red.</p>	<p>null</p>	<p>G</p>	<p>A, D, F, B, E, C</p>
	<p>G is the only outstanding vertex, and it is closer to E than to F , so EG is added to the tree. All vertices are already marked, the minimum expansion tree is shown in green. In this case with a weight of 39.</p>	<p>null</p>	<p>null</p>	<p>A, D, F, B, E, C, G</p>

https://es.wikipedia.org/wiki/Algoritmo_de_Prim

References

- [1] <http://en.wikipedia.org/>
- [2]