

# Day11 A

Young W. Lim

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- 1 Based on
- 2 Arrays (2) - and Functions
  - Arrays and Functions
  - Multidimensional Arrays
  - Size
  - Array Applications

## "C How to Program", Paul Deitel and Harvey Deitel

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# Passing an array to functions

- to pass an array argument to a function
  - the name of an array without brackets
  - the size of an array
- always to pass by reference
  - the start address of an array is passed by reference
  - the called function can modify the elements of the caller's array
  - use `const`, if the prevention of this modification is desired

# Receiving an array through a function call

- in the parameter list of a function definition
  - specify the array name with empty brackets
    - the number inside the brackets represents the array size
    - the array size is ignored, for 1-d dimensional arrays
    - therefore, any non-negative number is ok
    - or just empty brackets
  - specify the size of an array as a separate parameter

# Passing an individual element of an array

- like an ordinary variable, an individual array element can
  - passed by value : `a[1]`, `a[i]`
  - passed by reference : `&a[1]`, `&a[i]`, `(a+1)`, `(a+i)`
- such simple pieces of data are called scalars
- use the subscripted name of the array element as an argument

# Receiving an individual element of an array

- like an ordinary variable, an individual array element can be
  - received by value : `int a1, int ai`
  - received by reference : `int *p1, int *pi`
- do not need the subscripted name in the parameter list

## 2-dimensional arrays

- representing tables of values arranged in rows and columns
- to identify an element of a table two subscripts are needed (row subscript, col subscript)
- double scripted arrays



## 2-dimensional array initialization

- the initializer values are grouped by row in braces `{ }`
- when not enough initializers for a given row the remaining elements of that row are initialized with zero

```
{ row_0, row_1, ..., row_m }
```

```
{ {a_00, a_01, ..., a_0n},  
  {a_10, a_11, ..., a_1n},  
  {a_00, a_01, ..., a_0n},  
  {a_m0, a_m1, ..., a_mn} } (m+1)x(n+1)
```

## 2-dimensional array initialization examples

```
#include <stdio.h>
```

```
int main(void) {  
    int a[3][4] = { {1, 2, 3, 4},  
                   {5, 6, 7, 8},  
                   {9,10,11,12} };  
  
    int i, j;  
  
    for (i=0; i<3; ++i) {  
        for (j=0; j<4; ++j)  
            printf("%3d ", a[i][j]);  
        printf("\n");  
    }  
}
```

```
-----  
  1   2   3   4  
  5   6   7   8  
  9  10  11  12
```

```
#include <stdio.h>
```

```
int main(void) {  
  
    int b[3][4] = { {1, 2, 3, 4},  
                   {5, 6} };  
  
    int i, j;  
  
    for (i=0; i<3; ++i) {  
        for (j=0; j<4; ++j)  
            printf("%3d ", b[i][j]);  
        printf("\n");  
    }  
}
```

```
-----  
  1   2   3   4  
  5   6   0   0  
  0   0   0   0
```

# Row major order

- all array elements are stored consecutively in memory regardless of the number of subscripts
- 2-dimensional array,  
the first row is stored in memory  
then the second row follows the first row in memory

# Passing a multi-dimensional array

- a multi-dimensional array in a **parameter** list
  - each script represents the size of a corresponding dimension
  - the first subscript size is not required
  - all subsequent subscript sizes are required
  - to identify a memory location of an element  
the size informations for each dimension are necessary  
except for the 1st dimension
  - `a[] [M] [N]` in a parameter list

# Accessing a multi-dimensional array

- $a[] [M] [N]$  in a parameter list
- $a[i] [j] [k] = *a( ( i*M+j)*N + k )$  in accessing an element
- each row can be viewed as a 2-dimensional array  
 $p = a[ i ];$

$a[ i ]$	$a[ i ][ j ][ k ]$
$p$	$p[ j ][ k ]$

# The type `size_t`

- unsigned integral type
  - `unsigned int` for one computer
  - `unsigned long` for another computer
- translation may be required
  - the code for one computer
  - the code for another computer
  - `size_t` provides portability of a code
- defined in `<stddef.h>`  
which is often included by `<stdio.h>`
- `size_t` is recommended for any variable that represents an array's size or an array's subscripts

# sizeof Operator

- unary operator sizeof determines the size in bytes of a variable or a type at compile time
- When applied to the name of an array, sizeof returns the total number of bytes in the array
- The type `size_t` is an integral type
  - unsigned int
  - unsigned long int
  - returned by operator sizeof
  - defined in `<stddef.h>`
- Operator sizeof can be applied to any variable name, type, or value
- The parenthesis used with sizeof required if a type name is supplied as its operand

# Sorting algorithm

- placing the data into a particular order
  - ascending order
  - descending order
- various sorting algorithms
  - bubble sort



# Bubble sorting algorithm

- the smaller values gradually "bubble" their way upward to the top
- the larger values gradually sink down to the bottom
- several passes over the array
- on each pass, successive pairs of elements are compared
  - if a pair is in non-decreasing order, no action
  - otherwise, swap the elements of the pair
  - a small value can be moved up by only one position
  - a large value can be moved down by many positions

# Search algorithm

- the processing of finding a particular element in an array
- such a particular element to be found : a **search key**
- find the location (subsript) of a search key in the searched array
  
- linear search algorithm
- binary search algorithm

# Linear search algorithm

- 1 when the given array is unsorted
  - only linear search can be applied
  - on average, the program will have to compare the search key with the half the elements
- 1 when the given array is sorted
  - linear search still can be used for a small size array
  - binary search is more efficient for a large size array

# Binary search algorithm (1)

- eliminates from consideration one-half of the elements in the sorted array whenever comparison is made
- comparison is made only with the middle element of the sorted array
- recursively reduce the given problem by half
- repeat until
  - the search key is equal to the middle element
  - or the reduced problem contains only one element which is not equal to the search key

## Binary search algorithm (2)

- locates the middle element of the sorted array (increasing order)
- compare this middle element with the search key
  - if equal, the search key is found
  - if not equal, the problem is reduced to search only the half
    - when the search key is less than the middle element search only the first half of the array
    - when the search key is greater than the middle element search only the second half of the array